

$$w_{\text{new}} = w_{\text{old}} - \eta \frac{\partial L}{\partial w_{\text{old}}}$$

- weight weigh update

$$\frac{\partial L}{\partial w_{\text{old}}} = \frac{\partial \text{O}1P}{\partial w_{\text{old}}} \times \frac{\partial L}{\partial \text{O}1P} + \frac{\partial \text{O}2P}{\partial w_{\text{old}}} \times \frac{\partial L}{\partial \text{O}2P}$$

* here there are 2 roots that you can basically see.

- ① loss is dependent on $\text{O}3_1$, $\text{O}3_1$ is dependent on $\text{O}2_1$
 $\text{O}2_1 \rightarrow \text{O}1_1$, $\text{O}1_1 \rightarrow w_1$
- ② loss is dependent on $\text{O}3_1$, $\text{O}3_1$ is dependent on $\text{O}2_2$
 $\text{O}2_2 \rightarrow \text{O}1_1$ & $\text{O}1_1 \rightarrow w_1$

now

$$\frac{\partial L}{\partial w_{\text{old}}} = \left[\frac{\partial L}{\partial \text{O}3_1} \times \frac{\partial \text{O}3_1}{\partial \text{O}2_1} \times \frac{\partial \text{O}2_1}{\partial \text{O}1_1} \times \frac{\partial \text{O}1_1}{\partial w_{\text{old}}} \right]$$

$$\left[\frac{\partial L}{\partial \text{O}3_1} \times \frac{\partial \text{O}3_1}{\partial \text{O}2_2} \times \frac{\partial \text{O}2_2}{\partial \text{O}1_1} \times \frac{\partial \text{O}1_1}{\partial w_{\text{old}}} \right]$$

so we do this to propagate from one node to another two bits of you out account at a math engine and then if

③ Vanishing gradient problem

let say I have a very deep neural net

$$\text{loss} = \text{mean squared error}$$

$$= \frac{1}{n} (y - \hat{y})^2$$

Initially we discussed about sigmoid activation σ^n

to update w_1

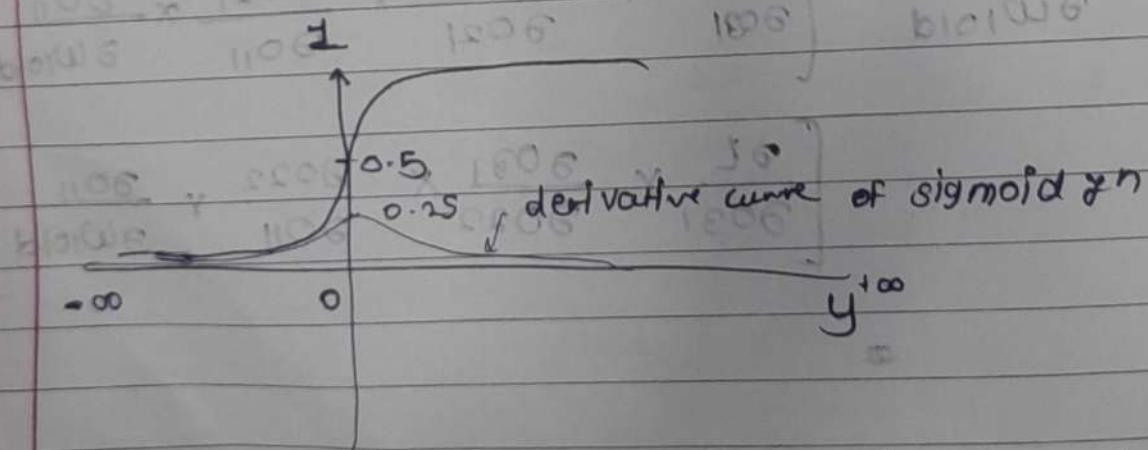
$$w_{\text{new}} = w_{\text{old}} - \frac{\partial L}{\partial w_{\text{old}}}$$

$$\frac{\partial L}{\partial w_{\text{old}}} = \frac{\partial L}{\partial o_5} \times \frac{\partial o_5}{\partial o_4} \times \frac{\partial o_4}{\partial o_3} \times \frac{\partial o_3}{\partial o_2} \times \frac{\partial o_2}{\partial w_{\text{old}}}$$

we are using here sigmoid activation $\sigma^n = 0$

$$\sigma(y) = \frac{1}{1 + e^{-x}}$$

$$\sigma'(y) = \sigma(0.5) = 0.5$$



- The imp property of sigmoid σ^n whenever we try to find out derivative of sigmoid it will be ranging from 0 to 0.25

$$0 \leq o(y) \leq 0.25$$

- bcoz of this what will happen is
- In each and every value sigmoid is getting used.
- e.g. $0.5 = o[(0.4 \times w_4) + b]$
- on top of it we applying an activation fn.
- So in backpropagation when I'm finding the derivative of the value will always be ranging b/w 0 to 0.25

e.g. in eqn ② we will be getting

$$\frac{\partial L}{\partial w_{new}} = 0.25 \times 0.15 \times 0.10 \times 0.05 \times 0.02$$

- ~~if we~~ the values will keep on decreasing bcoz as we are going to this chain rule, as we going to calculate derivative it is always going to reduce until we go the end of the chain.
- now what will happen bcoz of this since we are multiplying with smaller values we will be getting very small value.
now bcoz of this small no.
- $w_{new} = w_{old} - \eta (\text{small no}) \rightarrow \text{no change}$
in weights.
- at one point of time $w_{new} \approx w_{old}$
it will hardly change and if it is hardly changing then weights are not getting updated & this situation where weights are not getting updated or it's just getting updated with small value. this problem is basically caused as a vanishing gradient problem

then use another activation fn that is why we came up with another activation fn that we are going to learn.

- ① sigmoid
- ② Tanh
- ③ ReLU
- ④ Leaky ReLU
- ⑤ pre-relu.

① Sigmoid, frequently used in the beginning of DL.

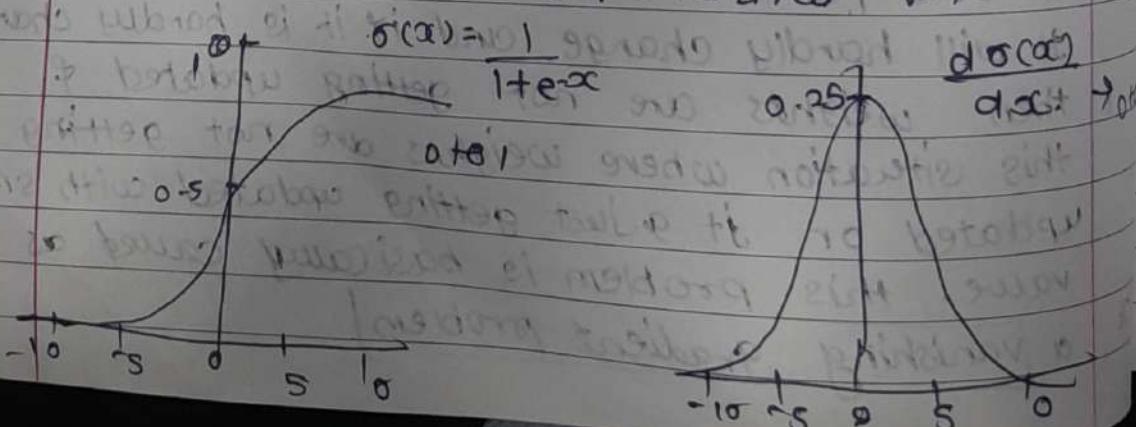
→ frequently used in the beginning of DL.

advantages

- ① smooth gradient, preventing "jumps" in o/p value.
- ② o/p value bounded between 0 & 1, normalizing the o/p of each neuron at price of loss of gradient information.
- ③ clear predictions, i.e. very close to 0 or 1.

disadvantages

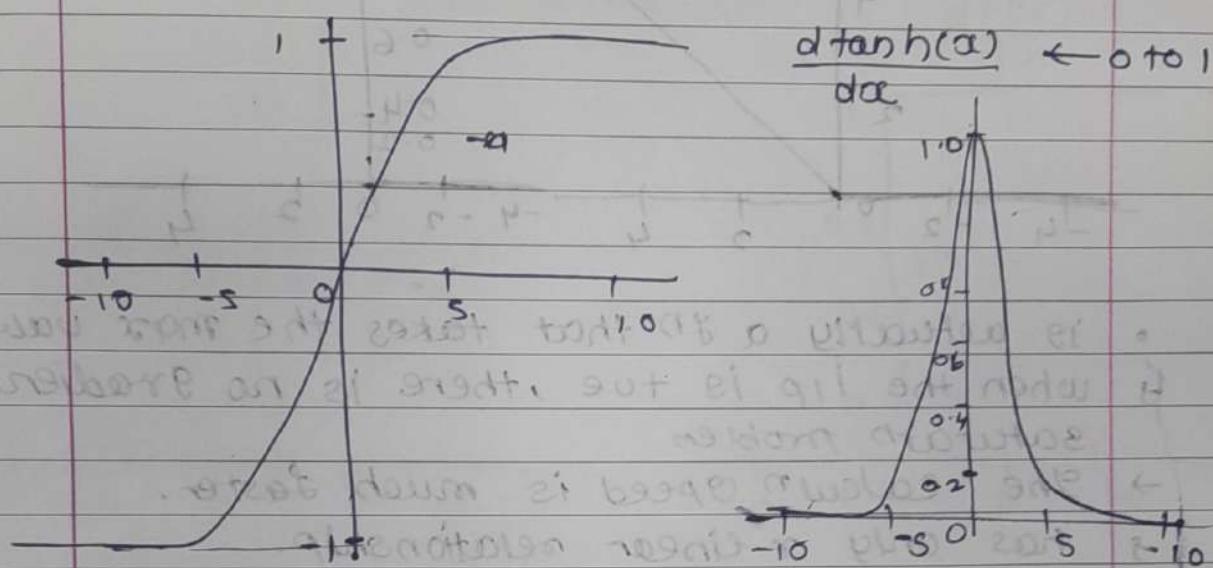
- ① prone to gradient vanishing
- ② f'n o/p is not zero-centered
- ③ power operations are relatively time consuming since there is an exponential



② \tanh y^n (hyperbolic tangent y^n)

$$\tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}} \quad -1 \text{ to } +1$$

value ranges from -1 to +1



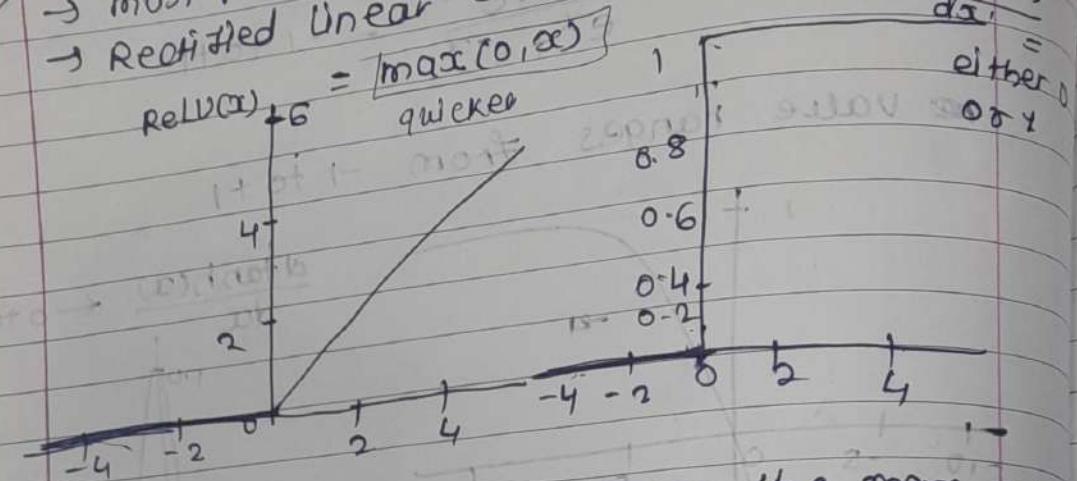
- does this prevent vanishing gradient problem?.
- still there will a issue if we go on constructing a deep neural nw or deep deep neural nw at one point of time there may be chances that vanishing G. P. still exist bcoz of that we also not using tanh activation

③ the opt interval of tanh is [-1, 1] the whole y^n is 0-centered which is better than sigmoid

In general binary classif. problem, the tanh y^n is used for the hidden layer & sigmoid y^n is used for output layer

binary classif. problem illus this is not good to change sign of output & mod. sign of output

- ⑧ ReLU fn
 → most popular using activation fn
 → Rectified Linear unit



$$\frac{d \text{ReLU}(x)}{dx}$$

either 0 or 1

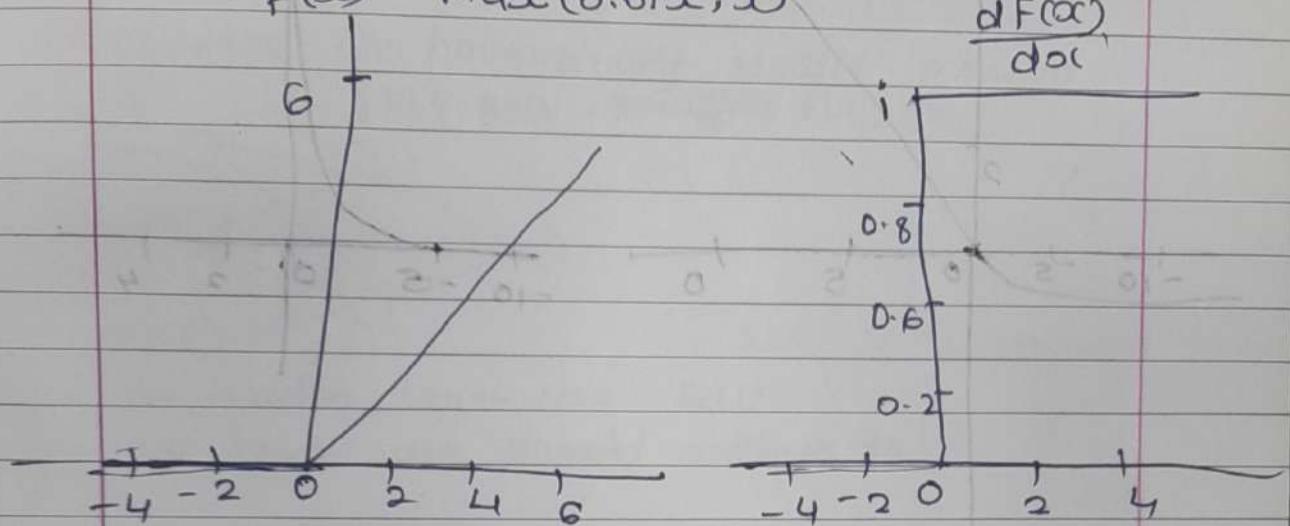
- is actually a fn that takes the max value
- when the input is +ve, there is no gradient saturation problem
- calculation speed is much faster.
- has only a linear relationship.
whether it is forward or backward.
- it is much faster than sigmoid & tanh.
(sigmoid & tanh need to calculate the exponent, which will be slower)

- when the input is -ve, ReLU is completely inactive, which means that once a -ve number is entered, ReLU will die.
In this way, in forward propagation, it is not a problem. Some areas are sensitive.
Some are insensitive.
- But in the B.P., if we enter a -ve number, the gradient will completely zero, which has the same problem as the sigmoid & tanh fn.

- we find that the dip of the ReLU γ_h is either 0 or a +ve number, which means that the ReLU γ_h is not a 0 centered γ_h

(4) Leaky ReLU γ_h

$$f(x) = \max(0.01x, x)$$

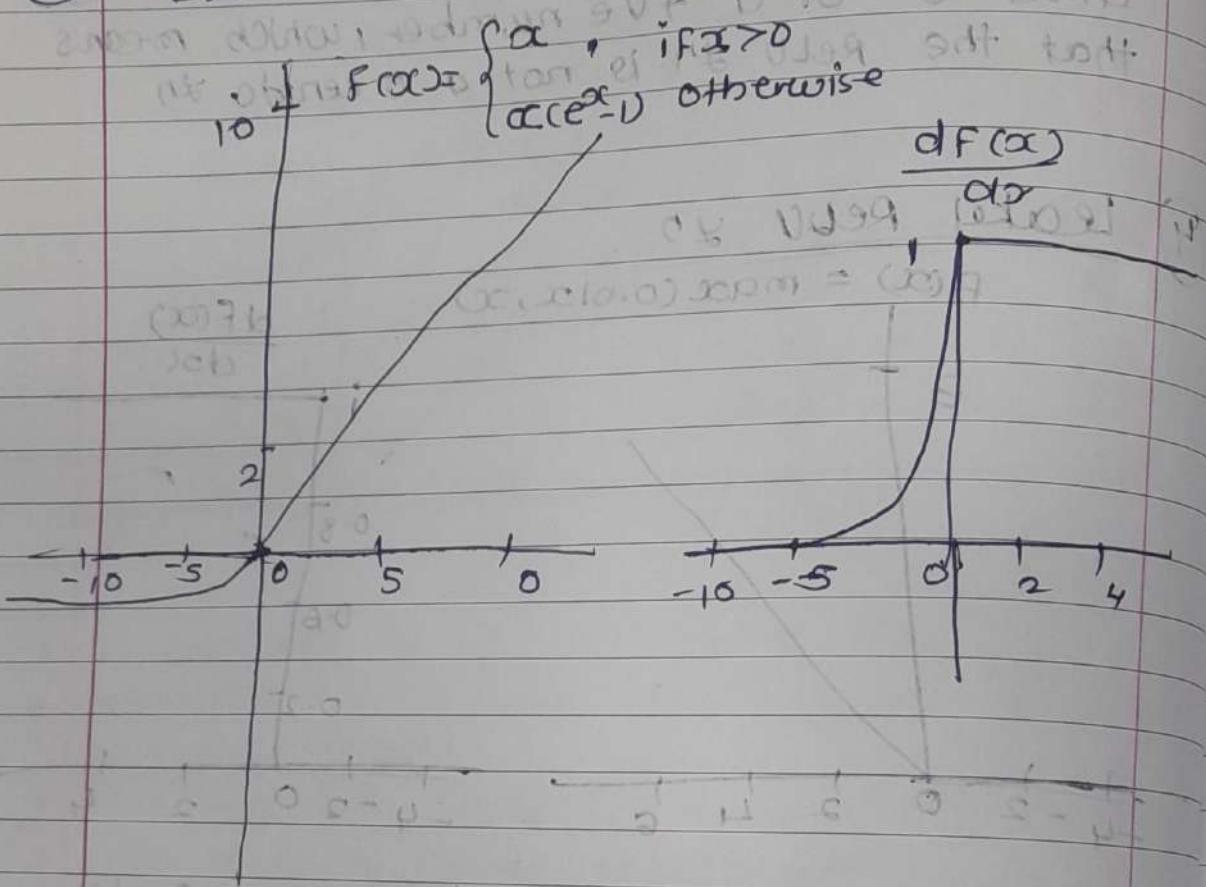


- In order to solve the dead ReLU problem, people proposed to set the first half of ReLU $0.01x$ instead 0.

Another intuitive idea is a parameter-based method.
 Parameteric ReLU: $F(x) = \max(-\alpha x, x)$
 which alpha can be learned from B.P.
 In theory, Leaky ReLU has all the advantages of ReLU. Plus there will be no problems with dead ReLU, but in actual it has not been fully proved that Leaky ReLU is always better than ReLU.

(3)

ELU (Exponential Linear Units) Function



ELU is also proposed to solve the problems of RELU, obviously, ELU has all the advantages of RELU &

- NO Dead ReLU issues
- The mean of the SLP is close to zero, centered.
- One small problem is that it is slightly more computationally intensive, similar to leak RELU although theoretically better than RELU.
- Good evidence in practice that ELU is always better than RELU.

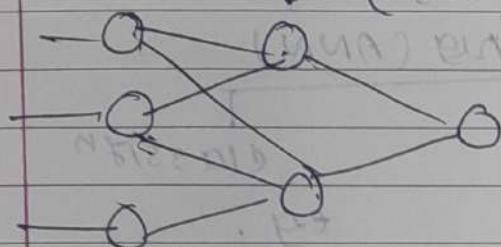
⑥ preReLU

$$f(y_i) = \begin{cases} y_i & \text{if } y_i > 0 \\ a_i y_i & \text{if } y_i \leq 0 \end{cases}$$

* Technique which Activation fn we should used?

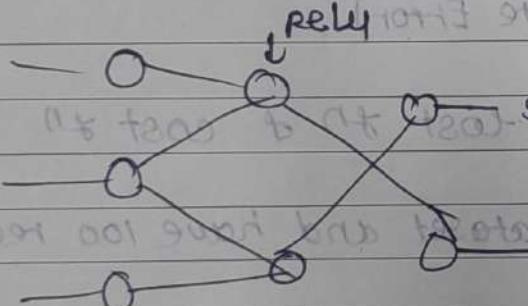
* Suppose we have binary classifer problem

→ HL (ReLU, preReLU, ELU)



* In hidden layer use ReLU
O/P layer use sigmoid activatin fn

~~multilayer class classifer~~ use softmax activatin fn in the O/P layer.



* In the case of regression problem.

