

# An Introduction to Synthetic Differential Geometry

Lázaro Alberto Larrauri Borroto


June 23, 2019

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# What is Synthetic Differential Geometry?

Given two different points there exists only one line incident to both of them.

Through a point not in a line, only one parallel line to the given one can be drawn.




Euklid.jpg

But what are points and lines?

# What is Synthetic Differential Geometry?

It is an axiomatic theory that deals with space forms in terms of their structure.

It allows for rigorous reasoning with nilpotent infinitesimals.



Lie.jpg

# Where does it take place?

We work in an ambient category  $\mathcal{E}$  composed of “smooth spaces and morphisms”.

Synthetic differential geometry has no models in the category of sets. It has to be interpreted over a **topos**.

Cartesian closed category with sub-object classifier.

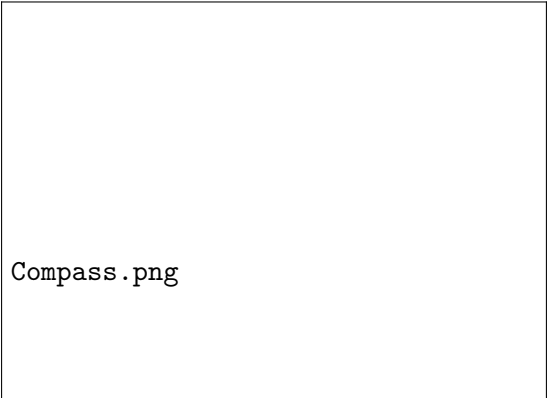
$A \times B$ ,  $A^B$ ,  $A \cup B$ ,  $A \cap B$ ,  $P(A)$  ...

# Basic structure of the geometric line.

The geometric line  $R$  satisfies:

Axiom

$R$  is a non-trivial  $\mathbb{Q}$ -algebra.



Compass.png

# The Kock-Lawvere axiom.

$$f(x) \simeq f(0) + f'(0)x$$

Is there any  $x$  such that we can substitute  $\simeq$  with  $=$  for all  $f$ 's?

No, we would need  $x$  “so small” that  $x^2 = 0$ .

# The Kock-Lawvere axiom.

Let

$$D := \{ d \in R \mid d^2 = 0 \}$$

Axiom (Kock-Lawvere axiom)

*For any  $f : D \rightarrow R$  there exists a unique  $b \in R$  such that*

$$\forall d \in D : \quad f(d) = f(0) + db.$$



## Wait, are we safe?

Intuitionistically speaking, yes.

Under classical assumptions, not so much.

## Wait, are we safe?

The Kock-Lawvere axiom is not consistent with the Principle of the Excluded Middle:

$$P \vee \neg P$$

We must use “intuitionistic” logic.

# Derivatives and Taylor series.

Derivatives are defined in a natural way.

## Definition

Let  $f \in R^R$ . The derivative of  $f$  at the point  $x \in R$  is the unique constant  $f'(x) \in R$  such that

$$\forall d \in D : \quad f(x + d) = f(x) + f'(x)d.$$

And functions “locally” coincide with their linear approximations.

# Derivatives and Taylor series.

$D$  is not an ideal.

What can we say about

$$D_2 := \{ d \in R \mid d^3 = 0 \}?$$

# Derivatives and Taylor series.

Not much. We need an additional axiom:

## Axiom

*For any  $f \in R^{D_2}$  there exist unique  $c_1, c_2 \in R$  such that*

$$\forall d \in D_2 : \quad f(d) = f(0) + c_1 d + c_2 d^2$$

# Derivatives and Taylor series.

This way we have:

## Theorem

For any  $f \in R^R$

$$\forall d \in D_2, \forall x \in R : \quad f(x + d) = f(0) + f'(x)d + \frac{f''(x)}{2}d^2.$$

# Derivatives and Taylor series.

Similarly, we would need an additional axiom for any of

$$D_k := \{ d \in R \mid d^{k+1} = 0 \} \text{ for } k = 1, 2, \dots$$

We can state them all together:

## Axiom

*Let  $f \in R^{D_k}$  for some  $k \in \mathbb{N}$ . Then there exists a unique  $k$ -tuple of constants  $c_1, \dots, c_k \in R$  such that*

$$\forall d \in D_k : \quad f(d) = f(0) + \sum_{i=1}^k c_i d^i$$

# Derivatives and Taylor series.

If we define  $D_\infty = \bigcup_{i=0}^\infty D_i$  it follows

## Theorem (Taylor series)

*For all  $f \in R^R$  and  $x \in R$  there exists a unique formal power series  $\Phi(X)$  such that*

$$\forall d \in D_\infty : \quad f(x + d) = \Phi(d).$$

*Namely,*

$$\Phi(X) = \sum_{i=0}^{\infty} \frac{f^{(i)}(x)}{i!} X^i.$$



# Don't let the axiom-party stop.

There are still families of infinitesimals we cannot deal with.

$$D(2) := \{ (d_1, d_2) \in D^2 \mid d_1 d_2 = 0 \}$$

Our current axioms state that

$$W_k := R[X]/\langle X^{k+1} \rangle \simeq R^{D_k}, \text{ where } "D_k = \text{Spec}_R(W_k)"$$

# Don't let the axiom-party stop.

In general, if  $W = R[X_1, \dots, X_n]$  satisfies some technical condition (it is a **Weil algebra**) we can state:

Axiom

$$W \simeq R^{\text{Spec}_R(W)}$$

# Tangent Vectors

## Definition

A **tangent vector** to  $M$  at the point  $p \in M$  is a map  $t \in M^D$  such that  $t(0) = p$ .

Thus,  $M^D$  is the tangent bundle of  $M$ .

To give  $(M^D)_p$  a tangent space structure we need  $M$  to be “infinitesimally linear”.

# Tangent Vectors

## Definition

An object  $M$  is said to be **infinitesimally linear** if for any  $p \in M$  and any  $n$ -tuple of maps  $t_1, \dots, t_n \in (M^D)_p$  there is a unique map  $l \in M^{D(n)}$  satisfying  $l \circ \text{incl}_i = t_i$  for all  $i = 1, \dots, n$ .

# Differentials

## Theorem

*Let  $M$  and  $N$  be infinitesimally linear, and  $f \in N^M$ . Then, for any  $p \in M$  the map  $f^D(t) = f \circ t$  restricts to a linear map from  $(M^D)_p$  to  $(N^D)_{f(p)}$ .*

# Vector Fields

## Definition

A vector field  $X$  over  $M$  is any of the following:

A “section of the tangent bundle”,  $\hat{X} : M \rightarrow M^D$ .

An “infinitesimal flow of the additive group  $R$ ”  $X : M \times D \rightarrow M$

An “infinitesimal deformation of the identity map”  $\check{X} : D \rightarrow M^M$ .

# Directional Derivatives

## Definition

The directional derivative of  $f$  in the direction of  $X$  is the unique map  $X(f) \in M^R$  such that, for any  $p \in M$

$$\forall d \in D: \quad f(X(p, d)) = f(p) + dX(f)(p).$$

Under some additional hypotheses on  $M$  we can define:

### Definition

Let  $X, Y \in \text{Vect}(M)$ . The **Lie bracket**  $[X, Y]$  is the unique vector field such that

$$\forall d_1, d_2 \in D: \quad [X, Y]^\vee(d_1 d_2) = \check{Y}(-d_2) \circ \check{X}(-d_1) \circ \check{Y}(d_2) \circ \check{X}(d_1)$$

And it is satisfied

$$[X, Y](f) = X(f) - Y(f)$$



# Questions?

Let them be easy please