

## Lecture 2: Two-Player Zero-Sum Finite Matrix Games with Mixed Strategies

### Last Lecture Recap

Two-player zero-sum (2PZS) finite game with **pure strategies**.

**2PZS:**  $J_1 + J_2 = 0 \Rightarrow$  use single cost function  $J = J_1 = -J_2$

**Player 1's objective:**  $\min_{\mathbf{u}_1} J(\mathbf{u}_1, \mathbf{u}_2)$

Action Set:  $|\Omega_1| = m_1, M_1 = \{1, \dots, m_1\}$

$$\text{Action: } \mathbf{u}_1 = \mathbf{e}_{1j} = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \quad (\text{j-th component})$$

**Player 2's objective:**  $\max_{\mathbf{u}_2} J(\mathbf{u}_1, \mathbf{u}_2)$

Action Set:  $|\Omega_2| = m_2, M_2 = \{1, \dots, m_2\}$

$$\text{Action: } \mathbf{u}_2 = \mathbf{e}_{2k} = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} \quad (\text{k-th component})$$

**Cost for finite actions:**  $(j, k) \in M_1 \times M_2 \Rightarrow J(\mathbf{e}_{1j}, \mathbf{e}_{2k}) = a_{jk} = \mathbf{e}_{1j}^T A \mathbf{e}_{2k} \in \mathbb{R}$

- $P_1$ 's security strategy:

$$j^* \in \arg \min_j \max_k a_{jk} \Rightarrow J_U \neq J_L \text{ in general}$$

- Minimax solution: both use security strategies  $\Rightarrow (j^*, k^*)$  ("no-regret" not necessarily hold)
- Saddle point:

$$\underbrace{a_{j^*k} \leq a_{j^*k^*}}_{\text{no regret for } P_2} \quad \underbrace{a_{j^*k^*} \leq a_{jk^*}}_{\text{no regret for } P_1} \quad \forall k \in M_2 \quad \forall j \in M_1$$

### Game Elements in This Lecture

**Players** Two players  $\mathcal{N} = \{1, 2\}$  (denoted  $P_1, P_2$ )

**Strategy** Mixed strategies  $\mathbf{x}_i \in \Delta_i$  (probability simplex)

**Cost** Expected cost:  $\bar{J}(\mathbf{x}, \mathbf{y}) = \mathbf{x}^T A \mathbf{y}$

**Why This Change?** Pure strategy saddle-point may not exist  $\Rightarrow$  need randomization.

**Key Result:** Minimax Theorem guarantees mixed strategy saddle-point *always* exists.

### 2.1 Mixed-Strategy Extension

When no pure-strategy equilibrium exists, we introduce **randomization** over actions by replacing one-hot pure action vectors with **probability distributions** over the action sets.

**Example: Matching Pennies (MP).**

$$A = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}$$

$P_1$ : both rows are security strategies

$P_2$ : both columns are security strategies

$$\begin{aligned} j^* &\in \arg \min_j \max_k a_{jk} \\ &= \arg \min_j \max_k \{1, 1\} = \{1, 2\} \end{aligned}$$

$$\begin{aligned} k^* &\in \arg \max_k \min_j a_{jk} \\ &= \arg \max_k \min_j \{-1, -1\} = \{1, 2\} \end{aligned}$$

Security strategy solutions (minimax pairs):  $(1, 1), (1, 2), (2, 1), (2, 2)$

**Question:** Which one is saddle point (no regret property)?

Check  $(j^*, k^*) = (1, 2)$ :

- $P_1$  regrets: Given  $P_2$  plays  $k = 2$ ,  $P_1$  checks column 2:

$$a_{12} = 1 > a_{22} = -1$$

$P_1$  could reduce cost by switching to row 2.

- $P_2$  no regret: Given  $P_1$  plays  $j = 1$ ,  $P_2$  checks row 1:

$$a_{11} = -1 < a_{12} = 1$$

$P_2$  already maximizes  $P_1$ 's cost.

$\Rightarrow (j^*, k^*) = (1, 2)$  is not a saddle point solution.

**Problem:** Checking all minimax pairs, we found that **no pure-strategy saddle point exists**.

**Solution:** Introduce randomization in selection of actions. Extend the game from

$$\mathcal{G}(\mathcal{N}, \underbrace{\Omega}_{\text{deterministic actions}}, J) \rightarrow \mathcal{G}(\mathcal{N}, \underbrace{\Delta_X}_{\text{probability distributions}}, \bar{J})$$

### Notation 1: Mixed strategy.

- $x_j$  = probability of  $P_1$  selects  $j$ -th action

$$\Rightarrow P_1 \text{'s mixed strategy : } \mathbf{x} = [x_1, \dots, x_j, \dots, x_{m_1}]^T \in \mathbb{R}^{m_1}$$

- $y_k$  = probability of  $P_2$  selects  $k$ -th action

$$\Rightarrow P_2 \text{'s mixed strategy : } \mathbf{y} = [y_1, \dots, y_k, \dots, y_{m_2}]^T \in \mathbb{R}^{m_2}$$

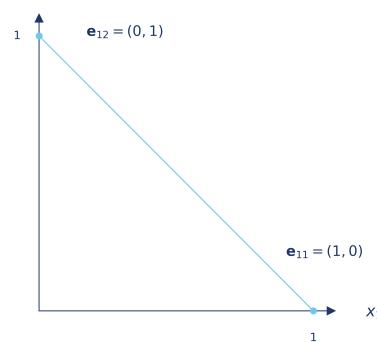
Require  $\begin{cases} 0 \leq x_j \leq 1, & \sum_{j=1}^{m_1} x_j = 1 \\ 0 \leq y_k \leq 1, & \sum_{k=1}^{m_2} y_k = 1 \end{cases}$  for  $\mathbf{x}, \mathbf{y}$  to be probability distributions.

If  $P_1$  selects  $j$ -th action with 100% probability, then  $\mathbf{x} = \mathbf{e}_j = [0, \dots, \underbrace{1}_{j\text{-th}}, \dots, 0]^T$

2D example: 2 actions to choose from

$$\Delta_1 := \left\{ \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{R}^2 \mid 0 \leq x_1, x_2 \leq 1, \mathbf{1}^T \mathbf{x} = 1 \right\}$$

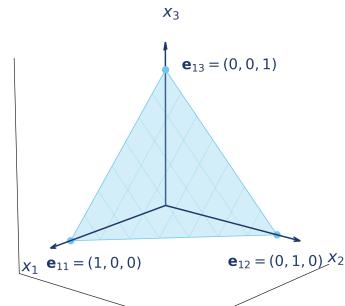
$\Delta_1$ : 1D line segment



3D example: 3 actions to choose from

$$\Delta_1 := \left\{ \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in \mathbb{R}^3 \mid 0 \leq x_j \leq 1 \forall j, \mathbf{1}^T \mathbf{x} = 1 \right\}$$

$\Delta_1$ : 2D triangular region



## Notation 2: Expected cost.

$P_1$  plays action  $j$  with probability  $x_j$

$$\mathbb{P}(\chi_1 = \mathbf{e}_{1j}) = \begin{bmatrix} x_1 & \cdots & x_{m_1} \end{bmatrix} \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} = x_j$$

$P_2$  plays action  $k$  with probability  $y_k$

$$\mathbb{P}(\chi_2 = \mathbf{e}_{2k}) = \begin{bmatrix} y_1 & \cdots & y_{m_2} \end{bmatrix} \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix} = y_k$$

**Assume** players randomize independently

$$\begin{aligned} \bar{J}(\mathbf{x}, \mathbf{y}) &= \mathbb{E}[J] \\ &= \sum_{j=1}^{m_1} \sum_{k=1}^{m_2} \underbrace{a_{jk}}_{\text{cost}} \cdot \underbrace{x_j \cdot y_k}_{\Pr(\text{outcome } (j,k))} \\ &= \sum_{j=1}^{m_1} x_j \left( \sum_{k=1}^{m_2} a_{jk} \cdot y_k \right) \\ &= \mathbf{x}^T A \mathbf{y} \end{aligned}$$

$P_1$  aims to minimize the expected cost:

$$\min_{\mathbf{x} \in \Delta_1} \bar{J}(\mathbf{x}, \mathbf{y})$$

$P_2$  aims to maximize the expected cost:

$$\max_{\mathbf{y} \in \Delta_2} \bar{J}(\mathbf{x}, \mathbf{y})$$

## 2.2 Mixed Security Strategies

### Def. 2.6 Security Mixed Strategy.

$P_1$  has security mixed strategy  $\mathbf{x}^* \in \Delta_1$  if

$$\mathbf{x}^* = \arg \min_{\mathbf{x} \in \Delta_1} \max_{\mathbf{y} \in \Delta_2} \mathbf{x}^T A \mathbf{y}$$

$$\Rightarrow \bar{J}_U = \min_{\mathbf{x} \in \Delta_1} \max_{\mathbf{y} \in \Delta_2} \mathbf{x}^T A \mathbf{y}$$

$P_2$  has security mixed strategy  $\mathbf{y}^* \in \Delta_2$  if

$$\mathbf{y}^* = \arg \max_{\mathbf{y} \in \Delta_2} \min_{\mathbf{x} \in \Delta_1} \mathbf{x}^T A \mathbf{y}$$

$$\Rightarrow \bar{J}_L = \max_{\mathbf{y} \in \Delta_2} \min_{\mathbf{x} \in \Delta_1} \mathbf{x}^T A \mathbf{y}$$

The expected cost  $\bar{J}_U$  is called the **upper value**.

The expected cost  $\bar{J}_L$  is called the **lower value**

**Note.** Allowing mixed strategies enlarges each player's feasible set:

$$J_L \leq \bar{J}_L \leq \bar{J}_U \leq J_U$$

Minimax Theorem shows that the interval  $[J_L, J_U]$  collapses to:  $\bar{J}_L = \bar{J}_U$  in finite zero-sum games,

## 2.3 Mixed-Strategy Saddle-Point Equilibrium

**Def 2.8 Mixed-Strategy Saddle-Point Equilibrium.** saddle-point equilibrium is  $(\mathbf{x}^*, \mathbf{y}^*) \in \Delta_1 \times \Delta_2$  such that

$$\mathbf{x}^{*\top} A \mathbf{y} \leq \mathbf{x}^{*\top} A \mathbf{y}^* \leq \mathbf{x}^T A \mathbf{y}^* \quad \forall \mathbf{x} \in \Delta_1, \forall \mathbf{y} \in \Delta_2$$

The common value  $\bar{J} := \mathbf{x}^{*\top} A \mathbf{y}^*$  is called the **value of the game**.

**Note.** At saddle-point equilibrium, neither player can unilaterally improve outcome (no-regret)

$$\bar{J} = \bar{J}_U = \bar{J}_L \Leftrightarrow (\mathbf{x}^*, \mathbf{y}^*)$$

## 2.4 Minimax Theorem (von Neumann)

**Thm 2.10 Minimax Theorem.** In any two-player zero-sum matrix (2PZSM) game with cost matrix  $A$ , where  $A$  is an  $m \times n$  matrix, or  $\mathcal{G}(\mathcal{N}, \Delta_X, \bar{J})$  with  $\bar{J}(\mathbf{x}, \mathbf{y}) = \mathbf{x}^\top A \mathbf{y}$ , we have

$$\min_{\mathbf{x} \in \Delta_1} \max_{\mathbf{y} \in \Delta_2} \bar{J}(\mathbf{x}, \mathbf{y}) = \max_{\mathbf{y} \in \Delta_2} \min_{\mathbf{x} \in \Delta_1} \bar{J}(\mathbf{x}, \mathbf{y}),$$

or equivalently

$$\min_{\mathbf{x} \in \Delta_1} \max_{\mathbf{y} \in \Delta_2} \mathbf{x}^\top A \mathbf{y} = \max_{\mathbf{y} \in \Delta_2} \min_{\mathbf{x} \in \Delta_1} \mathbf{x}^\top A \mathbf{y}.$$

where  $\Delta_1$  and  $\Delta_2$  denote the simplices of appropriate dimensions:

$$\Delta_1 = \{\mathbf{x} \in \mathbb{R}^m \mid \mathbf{1}_m^\top \mathbf{x} - 1 = 0, x_j \geq 0, \forall j\}, \quad \Delta_2 = \{\mathbf{y} \in \mathbb{R}^n \mid \mathbf{1}_n^\top \mathbf{y} - 1 = 0, y_k \geq 0, \forall k\}.$$

**Proof. Goal.** Show the mixed lower and upper values coincide:

$$\bar{J}_L := \max_{\mathbf{y} \in \Delta_2} \min_{\mathbf{x} \in \Delta_1} \mathbf{x}^\top A \mathbf{y}, \quad \bar{J}_U := \min_{\mathbf{x} \in \Delta_1} \max_{\mathbf{y} \in \Delta_2} \mathbf{x}^\top A \mathbf{y}, \quad \Rightarrow \quad \bar{J}_L = \bar{J}_U.$$

**Lemma 2.9 Separating Hyperplane.** Let  $Q \in \mathbb{R}^{m \times n}$  be arbitrary. Exactly one of the following holds:

- (i)  $\exists \mathbf{y}_0 \in \Delta_2$  such that  $\mathbf{x}^\top Q \mathbf{y}_0 \leq 0, \forall \mathbf{x} \in \Delta_1$ ,
- (ii)  $\exists \mathbf{x}_0 \in \Delta_1$  such that  $\mathbf{x}_0^\top Q \mathbf{y} \geq 0, \forall \mathbf{y} \in \Delta_2$ .

Interpretation: either  $P_2$  has a mixed strategy  $\mathbf{y}_0$  making  $P_1$ 's payoff non-positive for all  $\mathbf{x}$ , or  $P_1$  has a mixed strategy  $\mathbf{x}_0$  making the payoff non-negative for all  $\mathbf{y}$ , but not both.

**Step 1: Relate lemma to the game.** Fix a scalar  $c \in \mathbb{R}$  and define a shifted matrix

$$Q := -A + c \mathbf{1}_{m \times n}.$$

**Case (i).** Suppose there exists  $\mathbf{y}_0 \in \Delta_2$  such that  $\mathbf{x}^\top Q \mathbf{y}_0 \leq 0$  for all  $\mathbf{x} \in \Delta_1$ . Then

$$0 \geq \mathbf{x}^\top Q \mathbf{y}_0 = \mathbf{x}^\top (-A + c \mathbf{1}) \mathbf{y}_0 = -\mathbf{x}^\top A \mathbf{y}_0 + c \quad \Rightarrow \quad \mathbf{x}^\top A \mathbf{y}_0 \geq c, \forall \mathbf{x}.$$

Taking  $\min_{\mathbf{x}}$  and then  $\max_{\mathbf{y}}$ ,

$$\bar{J}_L = \max_{\mathbf{y} \in \Delta_2} \min_{\mathbf{x} \in \Delta_1} \mathbf{x}^\top A \mathbf{y} \geq c. \tag{1}$$

**Case (ii).** Suppose instead there exists  $\mathbf{x}_0 \in \Delta_1$  such that  $\mathbf{x}_0^\top Q \mathbf{y} \geq 0$  for all  $\mathbf{y} \in \Delta_2$ . Then

$$0 \leq \mathbf{x}_0^\top Q \mathbf{y} = \mathbf{x}_0^\top (-A + c \mathbf{1}) \mathbf{y} = -\mathbf{x}_0^\top A \mathbf{y} + c \quad \Rightarrow \quad \mathbf{x}_0^\top A \mathbf{y} \leq c, \forall \mathbf{y}.$$

Taking  $\max_{\mathbf{y}}$  and then  $\min_{\mathbf{x}}$ ,

$$\bar{J}_U = \min_{\mathbf{x} \in \Delta_1} \max_{\mathbf{y} \in \Delta_2} \mathbf{x}^\top A \mathbf{y} \leq c. \tag{2}$$

**Step 2: Eliminate the gap by contradiction.** Assume for contradiction, that there is a positive gap:

$$\bar{J}_U > \bar{J}_L \quad \Rightarrow \quad k := \bar{J}_U - \bar{J}_L > 0.$$

Choose the midpoint

$$c := \frac{\bar{J}_L + \bar{J}_U}{2} = \bar{J}_L + \frac{k}{2} = \bar{J}_U - \frac{k}{2}.$$

Apply Lemma 2.9 to  $Q = -A + c\mathbf{1}_{m \times n}$ :

- If case (i) holds, then by (1)

$$\bar{J}_L \geq c = \bar{J}_L + \frac{k}{2},$$

which implies  $0 \geq \frac{k}{2} > 0$ , a contradiction.

- If case (ii) holds, then by (2)

$$\bar{J}_U \leq c = \bar{J}_U - \frac{k}{2},$$

which implies  $0 \leq -\frac{k}{2} < 0$ , also a contradiction.

In both cases we obtain a contradiction, so the assumption  $\bar{J}_U > \bar{J}_L$  is false. Therefore

$$\bar{J}_L = \bar{J}_U$$

and hence

$$\min_{\mathbf{x} \in \Delta_1} \max_{\mathbf{y} \in \Delta_2} \mathbf{x}^\top A \mathbf{y} = \max_{\mathbf{y} \in \Delta_2} \min_{\mathbf{x} \in \Delta_1} \mathbf{x}^\top A \mathbf{y}.$$

## 2.5 Computing Mixed Saddle-Point

### 2.5.1 Dominated Strategies

#### Def. Dominated Strategies.

Row  $j$  dominates row  $r$  if

$$\begin{aligned} a_{jk} &\leq a_{rk}, \quad \forall k, \\ a_{jk} &< a_{rk}, \quad \text{for at least one } k. \end{aligned}$$

Column  $k$  dominates column  $c$  if

$$\begin{aligned} a_{jk} &\geq a_{jc}, \quad \forall j, \\ a_{jk} &> a_{jc}, \quad \text{for at least one } j. \end{aligned}$$

Dominated strategies can be eliminated since they will never be chosen in any optimal strategy.

**Prop. 2.13 Elimination of Dominated Strategies.** If rows  $j_1, \dots, j_l$  are dominated, then  $P_1$  has an optimal strategy with  $x_{j_1} = \dots = x_{j_l} = 0$ . Any optimal strategy for the reduced game (after removing dominated strategies) is optimal for the original game.

#### Example 2.14 Iterative Elimination.

$$A = \begin{bmatrix} 2 & 1 & 4 \\ 0 & 2 & 1 \\ 1 & 5 & 3 \\ 4 & 3 & 2 \end{bmatrix}$$

**Step 1:** Remove Row 4, which is dominated by Row 2 (compare:  $0 \leq 4, 2 \leq 3, 1 < 2$ ).

$$\begin{bmatrix} 2 & 1 & 4 \\ 0 & 2 & 1 \\ 1 & 5 & 3 \end{bmatrix}$$

**Step 2:** Remove Column 1, which is dominated by Column 3 (compare:  $4 \geq 2, 1 \geq 0, 3 > 1$ ).

$$\begin{bmatrix} 1 & 4 \\ 2 & 1 \\ 5 & 3 \end{bmatrix}$$

**Step 3:** Remove Row 3, which is dominated by Row 2 (compare:  $2 \leq 5, 1 < 3$ ).

$$A' = \begin{bmatrix} 1 & 4 \\ 2 & 1 \end{bmatrix}$$

## 2.5.2 Graphical Solution

**Graphical Solution for  $2 \times n$  Games.** Suppose  $P_1$  has two actions ( $m_1 = 2$ ), and  $P_2$  has  $m_2$  actions.

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1m_2} \\ a_{21} & a_{22} & \cdots & a_{2m_2} \end{bmatrix}.$$

Mixed strategies:

$$\Delta_1 = \left\{ x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \in \mathbb{R}^2 \mid 0 \leq x_j \leq 1, x_1 + x_2 = 1 \right\}, \quad \Delta_2 = \left\{ y = \begin{bmatrix} y_1 \\ \vdots \\ y_{m_2} \end{bmatrix} \in \mathbb{R}^{m_2} \mid 0 \leq y_k \leq 1, \sum_{k=1}^{m_2} y_k = 1 \right\}.$$

$P_1$ 's security strategy. By definition,

$$\mathbf{x}^* \in \arg \min_{\mathbf{x} \in \Delta_1} \max_{\mathbf{y} \in \Delta_2} \mathbf{x}^\top A \mathbf{y}.$$

For fixed  $\mathbf{x}$ ,  $\mathbf{x}^\top A \mathbf{y}$  is linear in  $\mathbf{y}$ , hence its maximum is attained at a vertex  $\mathbf{e}_{2k}$ :

$$\begin{aligned} \mathbf{x}^* &= \arg \min_{\mathbf{x} \in \Delta_1} \max_{k \in M_2} \mathbf{x}^\top A \mathbf{e}_{2k} \\ &= \arg \min_{\mathbf{x} \in \Delta_1} \max_{k \in M_2} \left\{ \mathbf{x}^\top \begin{bmatrix} a_{11} \\ a_{21} \end{bmatrix}, \dots, \mathbf{x}^\top \begin{bmatrix} a_{1k} \\ a_{2k} \end{bmatrix}, \dots, \mathbf{x}^\top \begin{bmatrix} a_{1m_2} \\ a_{2m_2} \end{bmatrix} \right\}, \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ 1 - x_1 \end{bmatrix}, \quad x_1 \in [0, 1]. \\ &= \underbrace{\arg \min_{x_1 \in [0, 1]} \max_{k \in M_2} \left\{ \underbrace{(a_{11} - a_{21})x_1 + a_{21}}_{\text{best response function } R_1(x_1)}, \dots, \underbrace{(a_{1k} - a_{2k})x_1 + a_{2k}}_{R_k(x_1)}, \dots, \underbrace{(a_{1m_2} - a_{2m_2})x_1 + a_{2m_2}}_{R_{m_2}(x_1)} \right\}}_{\text{worst-case expected loss } V_1(x_1)} \end{aligned}$$

**Example: Matching Pennies (MP).**

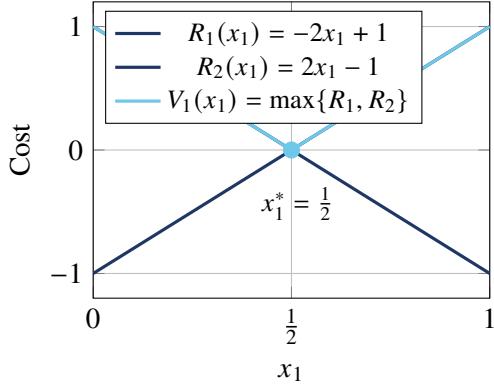
$$A = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}.$$

from graphical solution, we obtain

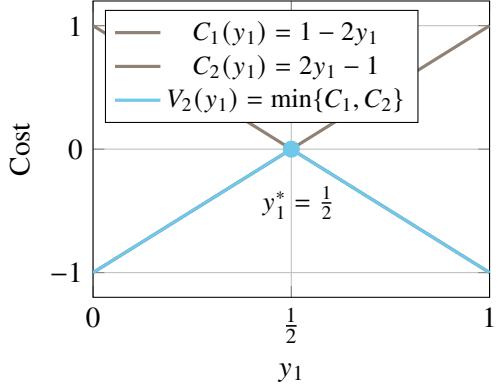
$$R_k(x_1) = (a_{1k} - a_{2k})x_1 + a_{2k} \Rightarrow \begin{cases} R_1(x_1) = (-1 - 1)x_1 + 1 = -2x_1 + 1, \\ R_2(x_1) = (1 - (-1))x_1 - 1 = 2x_1 - 1. \end{cases}$$

Player 1 minimizes

$$V_1(x_1) = \max\{R_1(x_1), R_2(x_1)\}, \quad x_1 \in [0, 1].$$



Graphical method:  $P_1$ 's mixed security strategy



Graphical method:  $P_2$ 's mixed security strategy

The optimal  $x_1^*$  occurs at the intersection of  $R_1$  and  $R_2$ :

$$R_1(x_1) = R_2(x_1) \Rightarrow -2x_1^* + 1 = 2x_1^* - 1 \Rightarrow \begin{cases} x_1^* = \frac{1}{2} \\ x_2^* = 1 - x_1^* = \frac{1}{2}. \end{cases}$$

Thus

$$x^* = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix}, \quad V_1(x_1^*) = R_1\left(\frac{1}{2}\right) = R_2\left(\frac{1}{2}\right) = 0.$$

By symmetry, Player 2's optimal mixed strategy is

$$y^* = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix},$$

and the saddle-point value (expected cost) is  $\bar{J}^* = 0$ .