## 暨大資工系 線性代數 期末考 112.6.14

#### Theorem 1

### 4.6 Change of Basis

Change of Basis Problem: If we change the basis for a vector space  $\nabla$  from some old basis B to some new basis B', how is the old coordinate matrix  $[v]_B$  of a vector v related to the new coordinate matrix  $[v]_B$ ?  $\therefore v = k \cdot u + k_2 u_2$ 

sol: Let 
$$B = \{u_1, u_2\}$$
 &  $B' = \{u'_1, u'_2\}$  
$$= k_1 u_1 + k_2 u_2$$

$$= k_1 (au_1 + bu_2) + k_2 (cu_1 + du_2)$$

$$= (k_1 a + k_2 c) u_1 + (k_1 b + k_2 d) u_2$$
i.e.  $u'_1 = au_1 + bu_2$ ;  $u'_2 = cu_1 + du_2$ 
i.e.  $[v]_B = \begin{bmatrix} k_1 a + k_2 c \\ k_1 b + k_2 d \end{bmatrix} = \begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} k_1 \\ k_2 \end{bmatrix}$ 

$$= P[v]_{B'}$$

Solution of the change of Basis Problem: If we change the basis for a vector space  $\nabla$  from some old basis  $B=\{u_1,u_2,\ldots,u_n\}$  to some new basis  $B'=\{u_1',u_2',\ldots,u_n'\}$ , then the old coordinate matrix  $[v]_B$  of a vector v related to the new coordinate matrix  $[v]_B$  of the same vector v by the equation  $[v]_B$   $P[v]_B$ , where the column of P are the coordinate matrices of the new basis vectors relative to the old basis.

i.e. 
$$P = \left[ \left[ u_1 \right]_B \middle| \left[ u_2 \right]_B \middle| \cdots \middle| \left[ u_n \right]_B \right]$$
 P is called the transition matrix from B' to B

2022/4/8 Yuh-Ming Huang, CSIE NCNU Chapter 4 60

Theorem 2 If  $S = \{v_1, v_2, ..., v_n\}$  is an orthonormal basis for an inner product space  $\nabla$ , and u is any vector in  $\nabla$ , then  $u = \langle u, v_1 \rangle v_1 + \langle u, v_2 \rangle v_2 + ... + \langle u, v_n \rangle v_n$ 

Theorem 3. Let  $\varpi$  be a finite-dimensional subspace of an inner product space  $\nabla$ .

- (a) If  $\{v_1, v_2, ..., v_r\}$  is an orthonormal basis for  $\varpi$ , and u is any vector in  $\nabla$ , then  $proj_{\varpi}u = \langle u, v_1 \rangle v_1 + \langle u, v_2 \rangle v_2 + \cdots + \langle u, v_r \rangle v_r$
- (b) If  $\{v_1, v_2, ..., v_n\}$  is an orthogonal basis for  $\varpi$ , and u is any vector in  $\nabla$ , then  $proj_{\varpi}u = \frac{\langle u, v_1 \rangle}{\|v_1\|^2} v_1 + \frac{\langle u, v_2 \rangle}{\|v_2\|^2} v_2 + \cdots + \frac{\langle u, v_n \rangle}{\|v_n\|^2} v_n$

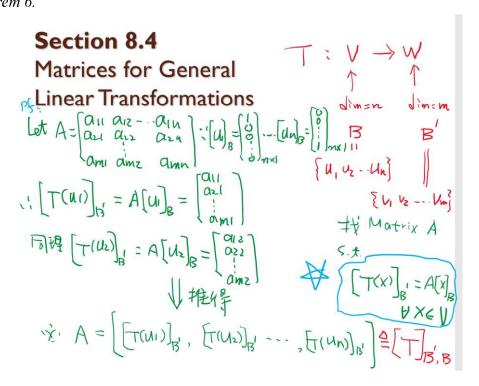
Theorem 4: A least squares solution of Ax=b must satisfy the equality  $A^TAx=A^Tb$  (i.e.  $x=(A^TA)^{-1}A^Tb$ ) [it is called the *normal system* associated with Ax=b].

If A is an  $m \times n$  matrix with linearly independent column vectors, then for every  $n \times 1$  matrix b, the linear system Ax = b has a <u>unique least squares solution</u>. This solution is given by  $x = (A^T A)^{-1} A^T b$ . Moreover, if  $\varpi$  is the column space of A, then the orthogonal projection of b on  $\varpi$  is  $proj_{\varpi}b = Ax = A(A^T A)^{-1}A^T b$ 

Theorem 5.

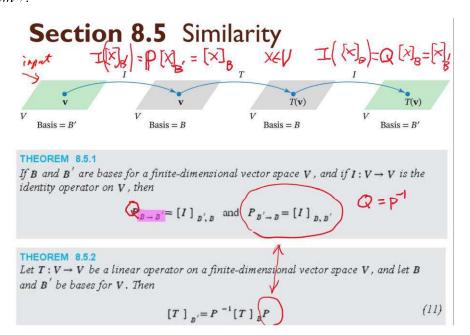
If  $T: \mathbb{R}^n \to \mathbb{R}^n$  is a linear transformation, and  $e_1, e_2, \dots, e_n$  are the standard basic vectors for  $\mathbb{R}^n$ , then the standard matrix for T is  $[T] = [T(e_1)|T(e_2)|\cdots|T(e_n)]$ 

Theorem 6.



Theorem 6-1

## Theorem 7.



## Theorem 8.

### THEOREM 2.3.6 Inverse of a Matrix Using Its Adjoint

If A is an invertible matrix, then

$$A^{-1} = \frac{1}{\det(A)} \operatorname{adj}(A)$$

## Theorem 9. Fourier Series

$$f(x) = \frac{a_0}{2} + \sum_{k=1}^{\infty} (a_k \cos kx + b_k \sin kx)$$

$$\| \| \|_{2}^{2} = \int_{0}^{2\pi} |dx| = 2\pi$$

$$\| \cos kx \|_{2}^{2} = \int_{0}^{2\pi} |dx| = 2\pi$$

$$\| \sin kx \|_{2}^{2} = \int_{0}^{2\pi} |\sin^{2}kx| dx = \int_{0}^{2\pi} \frac{|+\omega R_{2}kx|}{2} dx = \pi$$

$$\| \sin kx \|_{2}^{2} = \int_{0}^{2\pi} |\sin^{2}kx| dx = \int_{0}^{2\pi} \frac{|+\omega R_{2}kx|}{2} dx = \pi$$

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$$\frac{a_0}{2} = \frac{|+\omega R_{2}kx|}{||x||^{2}} = \frac{1}{2\pi} \int_{0}^{2\pi} |x| dx$$

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- 1. (10%) Find a  $3\times3$  matrix A that has eigenvalues 1, 2, and 3, and for which (0,1,0), (-1,2,2), and (-1,1,1) are their corresponding eigenvectors.
- 2. (30%) Let W be the plane with equation 5x 3y + z = 0.
  - (a) (10%) Find an orthonormal basis for W.
  - (b) (10%) Find the standard matrix for the orthogonal projection onto W.
  - (c) (10%) Find all of the points in  $\mathbb{R}^3$ , such that all of them are orthogonally projected to the same vector (1, 1, -2) which is on the plane W.
- 3. (10%) Let W be the line in  $R^3$  with parametric equations x = 2t, y=-t, z=4t (- $\infty < t < \infty$ ). Find an equation for  $W^{\perp}$ .
- 4. (15%) Let  $T: M_{22} \rightarrow M_{22}$  be a linear operator and defined by

$$T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} 2c & a+c \\ b-2c & d \end{bmatrix}$$

- (a) (10%) Find a basis B of  $M_{22}$ , then the standard matrix  $[T]_B$  of T with respect to the basis B is a diagonal matrix.
- (b) (5%) Find  $[T]_B^{100}$ .
- 5. (10%) Find a curve of the form a+(b/x) that best fits the data points (1, 7), (3, 3), (6, 1) by making the substitution X = 1/x.
- **6.** (10%) Find the Fourier series of f(x) = 1,  $0 \le x < \pi$  and f(x) = 0,  $\pi \le x \le 2\pi$  over the interval  $[0, 2\pi]$ .
- **7.** (15%)

## ► EXAMPLE 3 Matrix for a Linear Transformation

Let  $T: \mathbb{R}^2 \to \mathbb{R}^3$  be the linear transformation defined by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_2 \\ -5x_1 + 13x_2 \\ -7x_1 + 16x_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -5 & 13 \\ -7 & 16 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Find the matrix for the transformation T with respect to the bases  $B = \{ \mathbf{u}_1, \mathbf{u}_2 \}$  for  $R^2$  and  $B' = \{ \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3 \}$  for  $R^3$ , where

$$\mathbf{u}_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} 5 \\ 2 \end{bmatrix}; \quad \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$$

1. (10%) Find a  $3\times3$  matrix A that has eigenvalues 1, 2, and 3, and for which (0,1,0), (-1,2,2), and (-1,1,1) are their corresponding eigenvectors.

Solution [= 
$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{bmatrix} 0 \\ 0 \end{pmatrix} = \begin{bmatrix} 0 \\ 0 \end{pmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix} =$$

$$A \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$A \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 4 \\ 4 \end{bmatrix}$$

$$A \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix}$$

$$A \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix}$$

$$A \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 3 \\ 3 \end{bmatrix}$$

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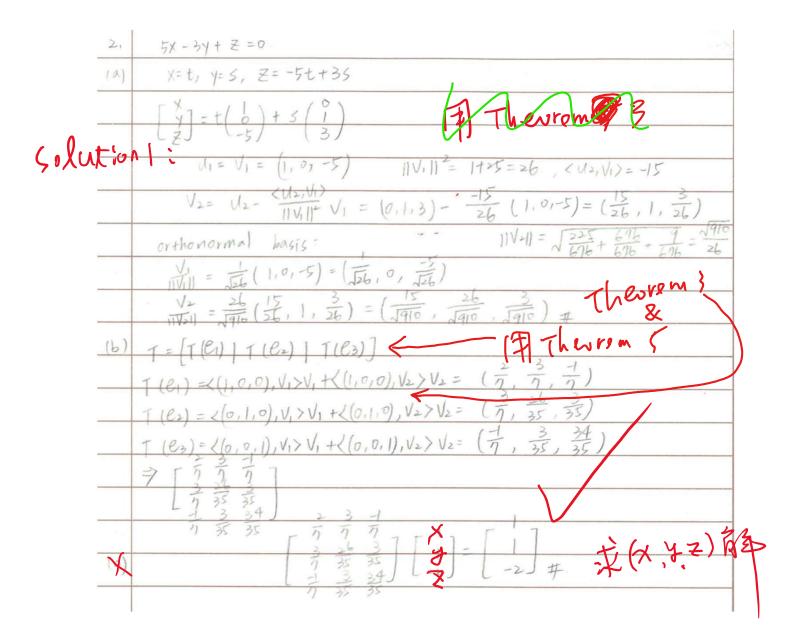
$$A \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 3 \end{bmatrix}$$

$$A \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\$$

solution 2

$P = \begin{bmatrix} 0 & -1 & -1 \\ 1 & 2 & 1 \end{bmatrix}$ $adj(P)^T = \begin{bmatrix} 0 & -1 & 2 \\ -1 & 0 & 0 \end{bmatrix}$ $def(P) = -2 + 1 = -1$
$P^{-1} = \begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \end{bmatrix}$
$P^{-1}AP = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 &$
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= [ 4 0 1 ] -2 1 0   -2 0 1 ] #

- 2. (30%) Let W be the plane with equation 5x 3y + z = 0.
  - (a) (10%) Find an orthonormal basis for W.
  - (b) (10%) Find the standard matrix for the orthogonal projection onto W.
  - (c) (10%) Find all of the points in  $\mathbb{R}^3$ , such that all of them are orthogonally projected to the same vector (1, 1, -2) which is on the plane  $\mathbb{W}$ .



- (a) If x=s and y=t, then a point on the plane is (s,t,-5s+3t)=s(1,0,-5)+t(0,1,3).
- Solution  $Z = \underbrace{w_1 = (1,0,-5) \text{ and } w_2 = (0,1,3) \text{ form a basis for } W \text{ (they are linearly independent since neither of them is a scalar multiple of the other).}$ 
  - **(b)** Letting  $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -5 & 3 \end{bmatrix}$ , Formula (11) yields

$$P = A(A^{T}A)^{-1}A^{T} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -5 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 3 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 3 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 3 \end{bmatrix}$$

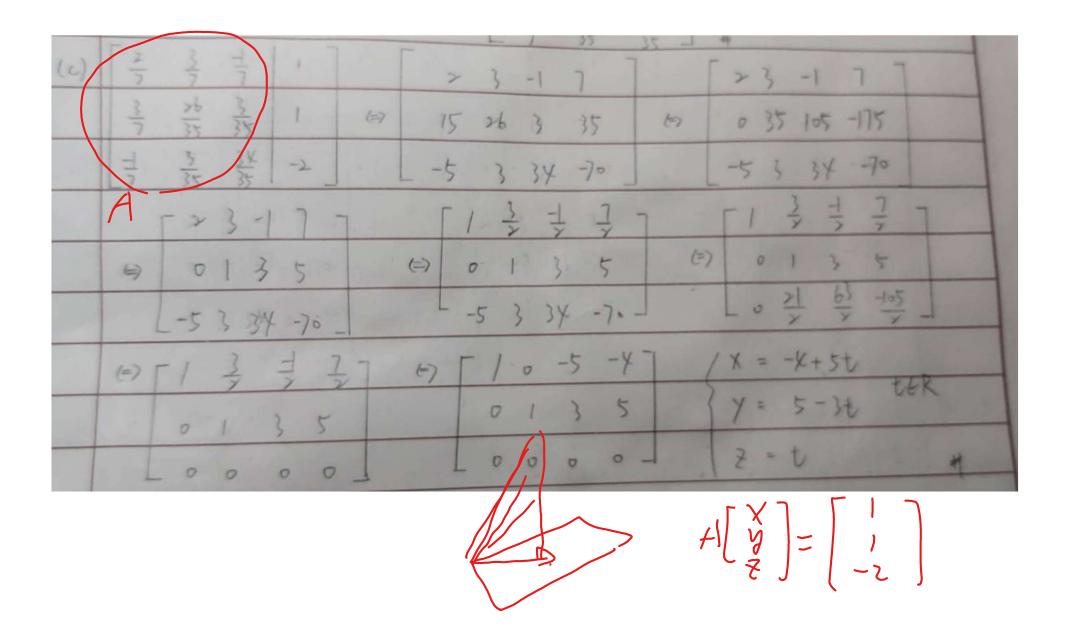
$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -5 & 3 \end{bmatrix} \begin{bmatrix} 26 & -15 \\ -15 & 10 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -5 & 3 \end{bmatrix} \begin{bmatrix} 10 & 15 \\ 15 & 26 \end{bmatrix} \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 3 \end{bmatrix}$$

$$= \frac{1}{35} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -5 & 3 \end{bmatrix} \begin{bmatrix} 10 & 15 \\ 15 & 26 \end{bmatrix} \begin{bmatrix} 1 & 0 & -5 \\ 0 & 1 & 3 \end{bmatrix} = \frac{1}{35} \begin{bmatrix} 10 & 15 \\ 15 & 26 & 3 \\ -5 & 3 & 34 \end{bmatrix}. = \begin{bmatrix} 2 & 3 & 3 \\ 35 & 35 & 35 \\ 15 & 35 & 35 & 35 \end{bmatrix}$$

Golution3

Y . DV	
(A)	5x-3y+7=0
	3 = -5x + 3y [x7 [17 [07
	X=3
	y=t [2] [-5] [3]
	let v, = (0,1,3)   v   = 10
	$V_2 = (1,0,-5) - \frac{\langle (0,1,3), (1,0,-5) \rangle}{10} (0.1.3)$
	$= (1,0,-5) - \frac{-3}{70.2} (0,1,3)$
	$=(1,\frac{3}{2},\frac{1}{2}) \Leftrightarrow (2,3,-1)   V_2   = 1/4$
	orthonormal basis = { (0, \frac{1}{10}, \frac{3}{10}), \left(\frac{1}{174}, \frac{1}{174}) \}

(6)	A = \[ \frac{7}{\tau_{\text{Ty}}} \] Proj_w = A(A^TA)^TA^T \[ \frac{1}{\tau_{\text{Ty}}} \] Theorem \[ \frac{1}{\text{Ty}} \] = A\[ \frac{1}{A}^T \]
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3. (10%) Let W be the line in  $R^3$  with parametric equations x = 2t, y=-t, z=4t (- $\infty < t < \infty$ ). Find an equation for  $W^{\perp}$ .

$$50\%$$
:  $(x,y,z)\cdot(z,-1,4)=0$   
 $\Rightarrow 2 \times y + 4 \times z = 0$ 

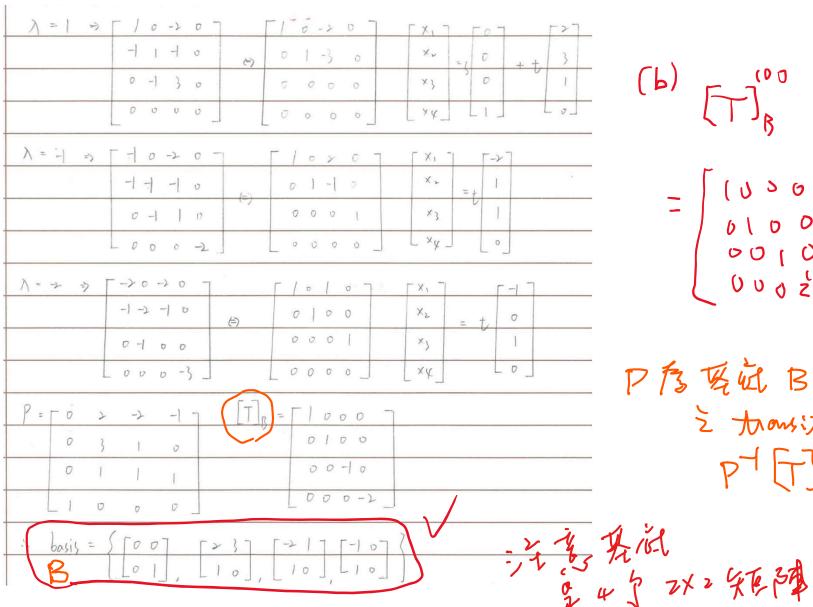
4. (15%) Let  $T: M_{22} \rightarrow M_{22}$  be a linear operator and defined by

$$T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} 2c & a+c \\ b-2c & d \end{bmatrix}$$

- (a) (10%) Find a basis B of  $M_{22}$ , then the standard matrix  $[T]_B$  of T with respect to the basis B is a diagonal matrix.
- (b) (5%) Find  $[T]_B^{100}$ .

(F) Theorem 6 & Theorem 6-1 Theorem 1

[a] [xc]	$T(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$	Bo=\{(0)\{0\}\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	ן [טי
-   b   = a+L	$T\left[\begin{bmatrix}0 & 1 & 1\end{bmatrix}\right] = \begin{bmatrix}0 & 1 & 1\\ & & & \end{bmatrix}$		
C 6->C	T ([0 0]) = [=	横军及成	
	T([0,0]) = [0,0]	7]	
[00 > 0 7 = [T]	B [ ) 0 -2 0 7	$(\lambda-1)(\lambda,(\lambda+\tau)-\tau-\gamma)$	
1010	-1 7 -1 0	$= (\lambda - 1) (\lambda^3 + 2\lambda^2 - \lambda - 2)$	
0 1 -2 0	0 -1 1+20	$= (\lambda - 1)^{2} (\lambda^{2} + 3\lambda + 2)$	
	[ 0 0 0 \lambda -1 ]	= (7-1) = (7+1) (7+2)	
i. N-1,-1,-2	,	1	



P含感说 B至易 2 transition matrix PT[T]BOP = [T]B

- 5. (10%) Find a curve of the form a+(b/x) that best fits the data points (1, 7), (3, 3), (6, 1) by making the substitution X = 1/x.
- With the substitution  $X = \frac{1}{x}$ , the problem becomes to find a line of the form  $y = a + b \cdot X$  that best fits the data points  $(1, 7), (\frac{1}{3}, 3), (\frac{1}{6}, 1)$ .

We have 
$$M = \begin{bmatrix} 1 & 1 \\ 1 & \frac{1}{3} \\ 1 & \frac{1}{6} \end{bmatrix}$$
,  $M^{T}M = \begin{bmatrix} 3 & \frac{3}{2} \\ \frac{3}{2} & \frac{41}{36} \end{bmatrix}$ ,  $(M^{T}M)^{-1} = \frac{1}{42} \begin{bmatrix} 41 & -54 \\ -54 & 108 \end{bmatrix}$ , and  $M^{T}M = \begin{bmatrix} 3 & \frac{3}{2} \\ \frac{3}{2} & \frac{41}{36} \end{bmatrix}$ 

$$\mathbf{v}^* = \begin{pmatrix} M^T M \end{pmatrix}^{-1} M^T \mathbf{y} = \frac{1}{42} \begin{bmatrix} 41 & -54 \\ -54 & 108 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & \frac{1}{3} & \frac{1}{6} \end{bmatrix} \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{5}{21} \\ \frac{48}{7} \end{bmatrix}. \text{ The line in terms of } X \text{ is } y = \frac{5}{21} + \frac{48}{7} X, \text{ so the}$$

required curve is  $y = \frac{5}{21} + \frac{48}{7x}$ .

**6.** (10%) Find the Fourier series of f(x) = 1,  $0 \le x < \pi$  and f(x) = 0,  $\pi \le x \le 2\pi$  over the interval  $[0, 2\pi]$ .

50Q :

(7) Theorem 9

Let 
$$f(x) = \begin{cases} 1, & 0 < x < \pi \\ 0, & \pi \le x \le 2\pi \end{cases}$$
.  

$$a_0 = \frac{1}{\pi} \int_0^{2\pi} f(x) \, dx = \frac{1}{\pi} \int_0^{\pi} dx = 1$$

$$a_k = \frac{1}{\pi} \int_0^{2\pi} f(x) \cos kx \, dx = \frac{1}{\pi} \int_0^{\pi} \cos kx \, dx = 0$$

$$b_k = \frac{1}{\pi} \int_0^{2\pi} f(x) \sin kx \, dx = \frac{1}{\pi} \int_0^{\pi} \sin kx \, dx = \frac{1}{k\pi} (1 - (-1)^k)$$

So the Fourier series is  $\frac{1}{2} + \sum_{k=1}^{\infty} \frac{1}{k\pi} (1 - (-1)^k) \sin kx$ .

# **7.** (15%)

## EXAMPLE 3 Matrix for a Linear Transformation

Let  $T: \mathbb{R}^2 \to \mathbb{R}^3$  be the linear transformation defined by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} x_2 \\ -5x_1 + 13x_2 \\ -7x_1 + 16x_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -5 & 13 \\ -7 & 16 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Find the matrix for the transformation T with respect to the bases  $B = \{ \mathbf{u}_1, \mathbf{u}_2 \}$  for  $R^2$  and  $B' = \{ \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3 \}$  for  $R^3$ , where

$$\mathbf{u}_1 = \begin{bmatrix} 3 \\ 1 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} 5 \\ 2 \end{bmatrix}; \quad \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$$

## Solution

From the formula for T,

$$T(\mathbf{u}_1) = \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix}$$
.  $T(\mathbf{u}_2) = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$   $\Rightarrow$  Theorem 6

Expressing these vectors as linear combinations of  $v_1$ ,  $v_2$ , and  $v_3$ , we obtain (verify)

$$T(\mathbf{u}_1) = \mathbf{v}_1 - 2\mathbf{v}_3, \quad T(\mathbf{u}_2) = 3\mathbf{v}_1 + \mathbf{v}_2 - \mathbf{v}_3$$

Thus,

$$\begin{bmatrix} T(\mathbf{u}_1) \end{bmatrix}_{B'} = \begin{bmatrix} 1\\0\\-2 \end{bmatrix}, \quad \begin{bmatrix} T(\mathbf{u}_2) \end{bmatrix}_{B'} = \begin{bmatrix} 3\\1\\-1 \end{bmatrix}$$

SO

$$[T]_{B',B} = [[T(\mathbf{u}_1)]_{B'} | [T(\mathbf{u}_2)]_{B'}] = \begin{bmatrix} 1 & 3\\ 0 & 1\\ -2 & -1 \end{bmatrix}$$