

① $TSP-tour(G, c) // G$ is graph, c is cost function
 $T = MST-Prim(G, c, r) // r$ is root vertex, arbitrary.
 $H = preorder(T, r) // H$ is list of vertices
 return $hamiltonian(H) //$ complete cycle
 $//$ returning to root

$MST-Prim(G, c, r)$

for each $v \in G.V //$ for each vertex

$v.key = \infty$

$v.\pi = NIL$

$H = \emptyset; r.key = 0$

$Q = G.V //$ Priority Q initialized to all vertices

while $Q \neq \emptyset$

$u = Extract-Min(Q)$

for each $v \in G.Adj[u] //$ for each vertex
 $//$ adj. to u .

if $v \in Q$ and $c(u, v) < v.key$

$v.\pi = u$

$v.key = c(u, v)$

$A = A \cup \{u, v\} // A$ is MST

If the cost function satisfies the triangle inequality,
 $c(u, w) \leq c(u, v) + c(v, w)$, the tour T (returned) by
 $TSP-tour$ is less than w with $w = 2H^*$ where H^*
 is cost of optimal tour.

$c(T) \leq c(H^*)$ since T can be obtained by deleting an
 edge from H^* . A full walk, w , traverses every edge of T
 twice so $c(w) = 2c(T) \leq 2c(H^*)$. By the triangle inequality
 we can delete any vertex from w and the cost does
 not increase, which can generate a tour from a walk
 visiting a vertex more than once. Call this H which must
 be $\leq w$ thus $c(H) \leq c(w) \leq 2c(H^*)$

② makeChange(d, v) // d is array containing possible denominations. v is input bill

table = [d.length][v]

for i = 1 to v

table[0][i] = ∞

for i = 1 to d.length

for j = 1 to v

if (j - d[i] >= 0)

amount = table[i][j - d[i]]

else

amount = ∞

table[i][j] = min(table[i-1][j], amount)

for i = 1 to d.length

for j = 1 to v

if table[i][j] ≠ ∞

return true

③ a) $W(i, j) = \max(W(i+1, j), W(i, j+1)) + W(i, j)$

return cost

if we are at the end of the array

return 0

return cost

if we are at the end of the array

return 0

return cost

if we are at the end of the array

return 0


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b) w(i, j)
    if i == n and j == n {
        return max(weight[i-1][j], weight[i][j-1]
            + weight[i][j])
    }
    right = table[i+1][j]
    down = table[i][j+1]
    if right and down >= 0
        if right > down
            w(i+1, j) ← return
        else
            w(i, j+1) ← return
    if right >= 0
        table[i+1][j] = weight[i][j] + weight[i+1][j]
        w(i+1, j)
    else
        table[i][j+1] = weight[i][j] + weight[i][j+1]
        w(i, j+1)

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