# Your first neural network

In this project, you'll build your first neural network and use it to predict daily bike rental ridership. We've provided some of the code, but left the implementation of the neural network up to you (for the most part). After you've submitted this project, feel free to explore the data and the model more.

#### In [1]:

```
%matplotlib inline
%load_ext autoreload
%autoreload 2
%config InlineBackend.figure_format = 'retina'

import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
```

# Load and prepare the data

A critical step in working with neural networks is preparing the data correctly. Variables on different scales make it difficult for the network to efficiently learn the correct weights. Below, we've written the code to load and prepare the data. You'll learn more about this soon!

#### In [2]:

```
data_path = 'Bike-Sharing-Dataset/hour.csv'
rides = pd.read_csv(data_path)
```

#### In [3]:

```
rides.head()
```

## Out[3]:

	instant	dteday	season	yr	mnth	hr	holiday	weekday	workingday	weathersit	temp	ŧ
0	1	2011- 01-01	1	0	1	0	0	6	0	1	0.24	(
1	2	2011- 01-01	1	0	1	1	0	6	0	1	0.22	(
2	3	2011- 01-01	1	0	1	2	0	6	0	1	0.22	(
3	4	2011- 01-01	1	0	1	3	0	6	0	1	0.24	(
4	5	2011- 01-01	1	0	1	4	0	6	0	1	0.24	(

# Checking out the data

This dataset has the number of riders for each hour of each day from January 1 2011 to December 31 2012. The number of riders is split between casual and registered, summed up in the cnt column. You can see the first few rows of the data above.

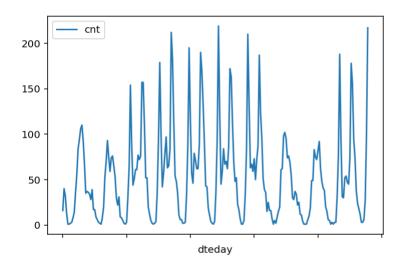
Below is a plot showing the number of bike riders over the first 10 days or so in the data set. (Some days don't have exactly 24 entries in the data set, so it's not exactly 10 days.) You can see the hourly rentals here. This data is pretty complicated! The weekends have lower over all ridership and there are spikes when people are biking to and from work during the week. Looking at the data above, we also have information about temperature, humidity, and windspeed, all of these likely affecting the number of riders. You'll be trying to capture all this with your model.

#### In [4]:

```
rides[:24*10].plot(x='dteday', y='cnt')
```

#### Out[4]:

<matplotlib.axes. subplots.AxesSubplot at 0x7f63f5695da0>



## **Dummy variables**

Here we have some categorical variables like season, weather, month. To include these in our model, we'll need to make binary dummy variables. This is simple to do with Pandas thanks to <code>get\_dummies()</code>.

#### In [5]:

```
dummy fields = ['season', 'weathersit', 'mnth', 'hr', 'weekday']
for each in dummy fields:
   dummies = pd.get dummies(rides[each], prefix=each, drop first=False)
   rides = pd.concat([rides, dummies], axis=1)
data = rides.drop(fields to drop, axis=1)
data.head()
```

#### Out[5]:

	yr	holiday	temp	hum	windspeed	casual	registered	cnt	season_1	season_2	 hr_2
0	0	0	0.24	0.81	0.0	3	13	16	1	0	
1	0	0	0.22	0.80	0.0	8	32	40	1	0	
2	0	0	0.22	0.80	0.0	5	27	32	1	0	
3	0	0	0.24	0.75	0.0	3	10	13	1	0	
4	0	0	0.24	0.75	0.0	0	1	1	1	0	

5 rows × 59 columns

## Scaling target variables

To make training the network easier, we'll standardize each of the continuous variables. That is, we'll shift and scale the variables such that they have zero mean and a standard deviation of 1.

The scaling factors are saved so we can go backwards when we use the network for predictions.

#### In [6]:

```
quant features = ['casual', 'registered', 'cnt', 'temp', 'hum', 'windspeed']
# Store scalings in a dictionary so we can convert back later
scaled features = {}
for each in quant features:
   mean, std = data[each].mean(), data[each].std()
   scaled features[each] = [mean, std]
   data.loc[:, each] = (data[each] - mean)/std
```

## Splitting the data into training, testing, and validation sets

We'll save the data for the last approximately 21 days to use as a test set after we've trained the network. We'll use this set to make predictions and compare them with the actual number of riders.

#### In [7]:

```
# Save data for approximately the last 21 days
test data = data[-21*24:]
# Now remove the test data from the data set
data = data[:-21*24]
# Separate the data into features and targets
target_fields = ['cnt', 'casual', 'registered']
features, targets = data.drop(target fields, axis=1), data[target fields]
test features, test targets = test data.drop(target fields, axis=1), test data[t
arget fields]
```

We'll split the data into two sets, one for training and one for validating as the network is being trained. Since this is time series data, we'll train on historical data, then try to predict on future data (the validation set).

#### In [8]:

```
# Hold out the last 60 days or so of the remaining data as a validation set
train features, train targets = features[:-60*24], targets[:-60*24]
val features, val targets = features[-60*24:], targets[-60*24:]
```

## Time to build the network

Below you'll build your network. We've built out the structure. You'll implement both the forward pass and backwards pass through the network. You'll also set the hyperparameters: the learning rate, the number of hidden units, and the number of training passes.



The network has two layers, a hidden layer and an output layer. The hidden layer will use the sigmoid function for activations. The output layer has only one node and is used for the regression, the output of the node is the same as the input of the node. That is, the activation function is f(x)=x. A function that takes the input signal and generates an output signal, but takes into account the threshold, is called an activation function. We work through each layer of our network calculating the outputs for each neuron. All of the outputs from one layer become inputs to the neurons on the next layer. This process is called *forward propagation*.

We use the weights to propagate signals forward from the input to the output layers in a neural network. We use the weights to also propagate error backwards from the output back into the network to update our weights. This is called *backpropagation*.

**Hint:** You'll need the derivative of the output activation function (f(x) = x) for the backpropagation implementation. If you aren't familiar with calculus, this function is equivalent to the equation y = x. What is the slope of that equation? That is the derivative of f(x).

Below, you have these tasks:

- 1. Implement the sigmoid function to use as the activation function. Set self.activation\_function in \_\_init\_\_ to your sigmoid function.
- 2. Implement the forward pass in the train method.
- 3. Implement the backpropagation algorithm in the train method, including calculating the output error.
- 4. Implement the forward pass in the run method.

# **Unit tests**

def MSE(y, Y):

**return** np.mean((y-Y)\*\*2)

Run these unit tests to check the correctness of your network implementation. This will help you be sure your network was implemented correctly befor you starting trying to train it. These tests must all be successful to pass the project.

#### In [75]:

```
import unittest
inputs = np.array([[0.5, -0.2, 0.1]])
targets = np.array([[0.4]])
test w i h = np.array([[0.1, -0.2],
                       [0.4, 0.5],
                       [-0.3, 0.211)
test w h o = np.array([[0.3],
                       [-0.1])
class TestMethods(unittest.TestCase):
    ##########
    # Unit tests for data loading
    ##########
    def test data path(self):
        # Test that file path to dataset has been unaltered
        self.assertTrue(data path.lower() == 'bike-sharing-dataset/hour.csv')
    def test data loaded(self):
        # Test that data frame loaded
        self.assertTrue(isinstance(rides, pd.DataFrame))
    ##########
    # Unit tests for network functionality
    ##########
    def test activation(self):
        network = NeuralNetwork(3, 2, 1, 0.5)
        # Test that the activation function is a sigmoid
        self.assertTrue(np.all(network.activation function(0.5) == 1/(1+np.exp(-
0.5))))
    def test train(self):
        # Test that weights are updated correctly on training
        network = NeuralNetwork(3, 2, 1, 0.5)
        network.weights_input_to_hidden = test_w_i_h.copy()
        network.weights hidden to output = test w h o.copy()
        network.train(inputs, targets)
        self.assertTrue(np.allclose(network.weights_hidden_to_output,
                                    np.array([[ 0.37275328],
                                              [-0.03172939]])))
        self.assertTrue(np.allclose(network.weights input to hidden,
                                    np.array([[ 0.10562014, -0.20185996],
                                              [0.39775194, 0.50074398],
                                              [-0.29887597, 0.19962801]])))
    def test run(self):
        # Test correctness of run method
        network = NeuralNetwork(3, 2, 1, 0.5)
        network.weights_input_to_hidden = test_w_i_h.copy()
        network.weights hidden to output = test w h o.copy()
        self.assertTrue(np.allclose(network.run(inputs), 0.09998924))
```

```
suite = unittest.TestLoader().loadTestsFromModule(TestMethods())
unittest.TextTestRunner().run(suite)
Ran 5 tests in 0.012s
OK
Out[75]:
<unittest.runner.TextTestResult run=5 errors=0 failures=0>
```

# Training the network

Here you'll set the hyperparameters for the network. The strategy here is to find hyperparameters such that the error on the training set is low, but you're not overfitting to the data. If you train the network too long or have too many hidden nodes, it can become overly specific to the training set and will fail to generalize to the validation set. That is, the loss on the validation set will start increasing as the training set loss drops.

You'll also be using a method know as Stochastic Gradient Descent (SGD) to train the network. The idea is that for each training pass, you grab a random sample of the data instead of using the whole data set. You use many more training passes than with normal gradient descent, but each pass is much faster. This ends up training the network more efficiently. You'll learn more about SGD later.

## Choose the number of iterations

This is the number of batches of samples from the training data we'll use to train the network. The more iterations you use, the better the model will fit the data. However, this process can have sharply diminishing returns and can waste computational resources if you use too many iterations. You want to find a number here where the network has a low training loss, and the validation loss is at a minimum. The ideal number of iterations would be a level that stops shortly after the validation loss is no longer decreasing.

## Choose the learning rate

This scales the size of weight updates. If this is too big, the weights tend to explode and the network fails to fit the data. Normally a good choice to start at is 0.1; however, if you effectively divide the learning rate by n records, try starting out with a learning rate of 1. In either case, if the network has problems fitting the data, try reducing the learning rate. Note that the lower the learning rate, the smaller the steps are in the weight updates and the longer it takes for the neural network to converge.

#### Choose the number of hidden nodes

In a model where all the weights are optimized, the more hidden nodes you have, the more accurate the predictions of the model will be. (A fully optimized model could have weights of zero, after all.) However, the more hidden nodes you have, the harder it will be to optimize the weights of the model, and the more likely it will be that suboptimal weights will lead to overfitting. With overfitting, the model will memorize the training data instead of learning the true pattern, and won't generalize well to unseen data.

Try a few different numbers and see how it affects the performance. You can look at the losses dictionary for a metric of the network performance. If the number of hidden units is too low, then the model won't have enough space to learn and if it is too high there are too many options for the direction that the learning can take. The trick here is to find the right balance in number of hidden units you choose. You'll generally find that the best number of hidden nodes to use ends up being between the number of input and output nodes.

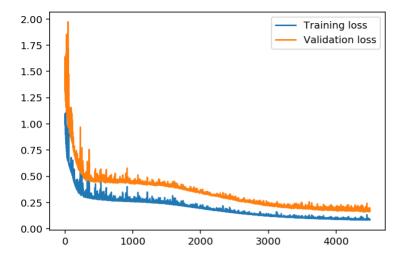
#### In [76]:

```
import sys
######################
### Set the hyperparameters in you myanswers.py file ###
####################
from my answers import iterations, learning rate, hidden nodes, output nodes
N i = train features.shape[1]
network = NeuralNetwork(N i, hidden nodes, output nodes, learning rate)
losses = {'train':[], 'validation':[]}
for ii in range(iterations):
    # Go through a random batch of 128 records from the training data set
    batch = np.random.choice(train features.index, size=128)
    X, y = train features.ix[batch].values, train targets.ix[batch]['cnt']
    network.train(X, y)
    # Printing out the training progress
    train loss = MSE(network.run(train features).T, train targets['cnt'].values)
    val loss = MSE(network.run(val features).T, val targets['cnt'].values)
    sys.stdout.write("\rProgress: {:2.1f}".format(100 * ii/float(iterations)) \
                     + "% ... Training loss: " + str(train loss)[:5] \
                     + " ... Validation loss: " + str(val_loss)[:5])
    sys.stdout.flush()
    losses['train'].append(train loss)
    losses['validation'].append(val loss)
Progress: 0.1% ... Training loss: 0.932 ... Validation loss: 1.388
/opt/conda/lib/python3.6/site-packages/ipykernel launcher.py:17: Dep
recationWarning:
.ix is deprecated. Please use
.loc for label based indexing or
.iloc for positional indexing
See the documentation here:
http://pandas.pydata.org/pandas-docs/stable/indexing.html#ix-indexer
-is-deprecated
```

Progress: 100.0% ... Training loss: 0.086 ... Validation loss: 0.176

```
In [77]:
```

```
plt.plot(losses['train'], label='Training loss')
plt.plot(losses['validation'], label='Validation loss')
plt.legend()
_ = plt.ylim()
```



# **Check out your predictions**

Here, use the test data to view how well your network is modeling the data. If something is completely wrong here, make sure each step in your network is implemented correctly.

#### In [78]:

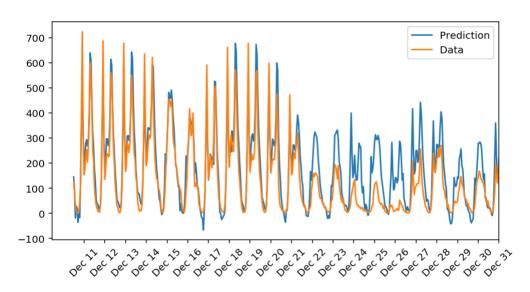
/opt/conda/lib/python3.6/site-packages/ipykernel\_launcher.py:10: Dep
recationWarning:

- .ix is deprecated. Please use
- .loc for label based indexing or
- .iloc for positional indexing

See the documentation here:

http://pandas.pydata.org/pandas-docs/stable/indexing.html#ix-indexer
-is-deprecated

# Remove the CWD from sys.path while we load stuff.



# OPTIONAL: Thinking about your results(this question will not be evaluated in the rubric).

Answer these questions about your results. How well does the model predict the data? Where does it fail? Why does it fail where it does?

**Note:** You can edit the text in this cell by double clicking on it. When you want to render the text, press control + enter

#### Your answer below

The prediction failed where number of bikes required is too low.

# **Submitting:**

Open up the 'jwt' file in the first-neural-network directory (which also contains this notebook) for submission instructions

In [3]:

```
import os
import tarfile
def recursive_files(dir_name='.', ignore=None):
    for dir name, subdirs, files in os.walk(dir name):
        if ignore and os.path.basename(dir name) in ignore:
            continue
        for file name in files:
            if ignore and file name in ignore:
                continue
            yield os.path.join(dir name, file name)
def make tar file(dir name='.', target file name='workspace archive.tar', ignore
=None):
    tar = tarfile.open(target file name, 'w')
    for file name in recursive files(dir name, ignore):
        tar.add(file name)
    tar.close()
dir name = '.'
target file name = 'workspace archive.tar'
# List of files/directories to ignore
ignore = {'.ipynb_checkpoints', '__pycache__', target_file_name}
make tar file(dir name, target file name, ignore)
```

```
In [ ]:
```