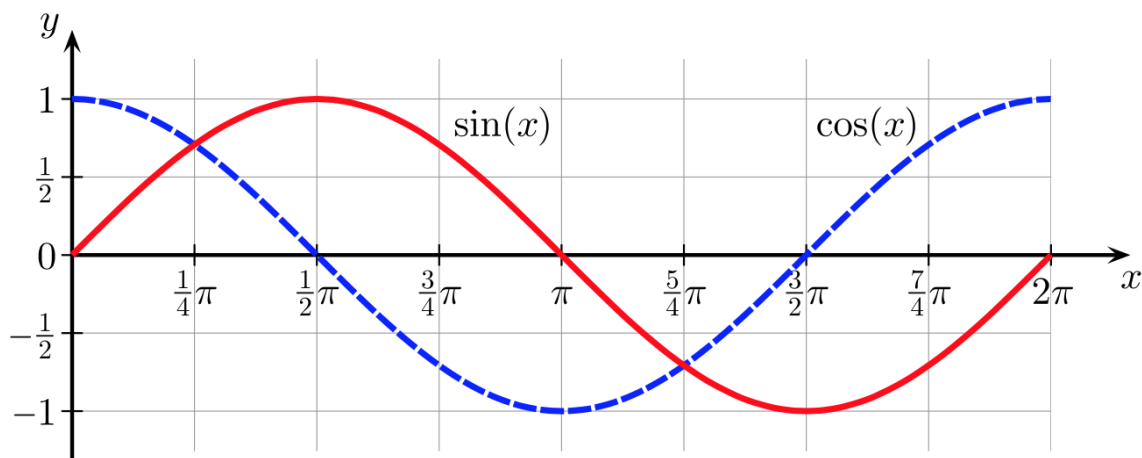


1 Allgemein

1.1 Trigonometrie



| | | | | | | | | | |
|----------|----|----------------------|----------------------|----------------------|-----------------|----------------------|-----------------------|-----------------------|-------|
| Bogenmaß | 0 | $\frac{\pi}{6}$ | $\frac{\pi}{4}$ | $\frac{\pi}{3}$ | $\frac{\pi}{2}$ | $\frac{2\pi}{3}$ | $\frac{3\pi}{4}$ | $\frac{5\pi}{6}$ | π |
| Winkel | 0° | 30° | 45° | 60° | 90° | 120° | 135° | 150° | 180° |
| $\sin x$ | 0 | $\frac{1}{2}$ | $\frac{\sqrt{2}}{2}$ | $\frac{\sqrt{3}}{2}$ | 1 | $\frac{\sqrt{3}}{2}$ | $\frac{\sqrt{2}}{2}$ | $\frac{1}{2}$ | 0 |
| $\cos x$ | 1 | $\frac{\sqrt{3}}{2}$ | $\frac{\sqrt{2}}{2}$ | $\frac{1}{2}$ | 0 | $-\frac{1}{2}$ | $-\frac{\sqrt{2}}{2}$ | $-\frac{\sqrt{3}}{2}$ | -1 |

$$\tan(x) = \frac{\sin(x)}{\cos(x)}$$

$$\sin(2x) = 2 \sin(x) \cos(x)$$

$$\sin(\alpha + \beta) = \sin(\alpha) \cos(\beta) + \cos(\alpha) \sin(\beta)$$

$$\cos(\alpha + \beta) = \cos(\alpha) \cos(\beta) - \sin(\alpha) \sin(\beta)$$

$$\cos^2(x) = \frac{1 + \cos(2x)}{2}$$

$$\sin^2(x) + \cos^2(x) = 1$$

1.2 Potenzgesetze

$$a^0 = 1$$

$$a^1 = a$$

$$a^m \cdot a^n = a^{m+n}$$

$$(a^n)^m = a^{nm}$$

$$\frac{a^n}{a^m} = a^{n-m}$$

$$a^{-n} = \frac{1}{a^n}$$

$$a^{\frac{b}{n}} = \sqrt[n]{a^b}$$

1.3 Logarithmus

$$\log(0) = \text{undef.}$$

$$\log(1) = 0$$

$$x \log_a(y) \Leftrightarrow a^x = y$$

$$-\log(x) = \log\left(\frac{1}{x}\right)$$

$$\log(x) - \log(y) = \log\left(\frac{x}{y}\right)$$

$$\frac{\log(x)}{\log(a)} = \log_a(x)$$

2 Integration

2.1 Elementare Integrale

| $f'(x)$ | $f(x)$ | $F(x)$ |
|---|-------------------------------------|---|
| $\frac{f'(x)g(x)-f(x)g'(x)}{g(x)^2}$ | $\frac{f(x)}{g(x)}$ | |
| 0 | c | cx |
| $r \cdot x^{r-1}$ | x^r | $\frac{x^{r+1}}{r+1}$ |
| $-\frac{1}{x^2} = -x^{-2}$ | $\frac{1}{x} = x^{-1}$ | $\ln x $ |
| $\frac{1}{2\sqrt{x}} = \frac{1}{2}x^{-\frac{1}{2}}$ | $\sqrt{x} = x^{\frac{1}{2}}$ | $\frac{2}{3}x^{\frac{3}{2}}$ |
| $\cos(x)$ | $\sin(x)$ | $-\cos(x)$ |
| $-\sin(x)$ | $\cos(x)$ | $\sin(x)$ |
| $1 + \tan^2(x) = \frac{1}{\cos^2(x)}$ | $\tan(x)$ | $-\ln \cos(x) $ |
| e^x | e^x | e^x |
| $c \cdot e^{cx}$ | e^{cx} | $\frac{1}{c} \cdot e^{cx}$ |
| $\ln(c) \cdot c^x$ | c^x | $\frac{c^x}{\ln(c)}$ |
| $\frac{1}{x}$ | $\ln x $ | $x(\ln x - 1)$ |
| $\frac{1}{\ln(a) \cdot x}$ | $\log_a x $ | $\frac{x}{\ln(a)}(\ln x - 1)$ |
| $\frac{1}{\sqrt{1-x^2}}$ | $\arcsin(x)$ | $x \cdot \arcsin(x) + \sqrt{1-x^2}$ |
| $-\frac{1}{\sqrt{1-x^2}}$ | $\arccos(x)$ | $x \cdot \arccos(x) - \sqrt{1-x^2}$ |
| $\frac{1}{1+x^2}$ | $\arctan(x)$ | $x \cdot \arctan(x) - \frac{1}{2} \ln(1+x^2)$ |
| $\cosh(x)$ | $\sinh(x) = \frac{e^x - e^{-x}}{2}$ | $\cosh(x)$ |
| $\sinh(x)$ | $\cosh(x) = \frac{e^x + e^{-x}}{2}$ | $\sinh(x)$ |
| $\frac{1}{\cosh^2(x)}$ | $\tanh(x)$ | $\log(\cosh(x))$ |

2.2 Regeln

Direkter Integral $\int f(g(x))g'(x) dx = F(g(x))$

Partielle Integration $\int f' \cdot g dx = f \cdot g - \int f \cdot g' dx$

mit Polynomen $\int \frac{p(x)}{q(x)} dx \Rightarrow$ Partialbruchzerlegung

Substitution $\int_a^b f(\varphi(t))\varphi'(t) dt = \int_{\varphi(a)}^{\varphi(b)} f(x) dx$ mit $x = \varphi(t)$

2.3 Tipps

$$\begin{aligned} \int \tan x dx &= \int \frac{\sin x}{\cos x} dx = -\log|\cos(x)| \\ \int \frac{1}{x-\alpha} dx &= \log(x-\alpha) \\ \int \frac{\frac{1}{\alpha}}{1+(\frac{x}{\alpha})^2} dx &= \arctan(x) \\ \int \sin^2(x) dx &= \frac{1}{2}(x - \sin(x)\cos(x)) + C \\ \int \cos^2(x) dx &= \frac{1}{2}(x + \sin(x)\cos(x)) + C \\ \int \sqrt{x^2+1} dx &= \sinh(x) + C \end{aligned}$$

3 Vektorfelder

3.1 Differenzial (für $f: \mathbb{R}^n \mapsto \mathbb{R}^m$)

$$df = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}$$

3.2 Gradient (für $f: \mathbb{R}^n \mapsto \mathbb{R}$)

$$\text{grad}(f) = \nabla f = \begin{pmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{pmatrix}$$

Der Gradient zeigt in die Richtung der maximalen Zuwachsrates von f und seine Länge ist gleich der maximalen Änderung von f .

3.3 Hessematrix (für $f: \mathbb{R}^n \mapsto \mathbb{R}$)

$$\text{Hess}(f) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{pmatrix}$$

3.4 Rotation (für $f: \mathbb{R}^3 \mapsto \mathbb{R}^3$ oder $f: \mathbb{R}^2 \mapsto \mathbb{R}^2$)

$$\text{In } \mathbb{R}^3: \text{rot}(\vec{v}) = \nabla \times \vec{v} = \begin{pmatrix} \frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \\ \frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} \\ \frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \end{pmatrix}, \text{ in } \mathbb{R}^2: \text{rot}(\vec{v}) = \frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y}$$

Bemerkung: Falls $\text{rot}(\vec{v}) = 0$, dann ist \vec{v} konservativ (Potenzialfeld).

3.5 Divergenz (für $f: \mathbb{R}^n \mapsto \mathbb{R}^n$)

$$\text{div}(v) = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \dots$$

3.6 Potenzialfeld

Ein Potenzialfeld ist konservativ. Das Potenzial Φ eines Potenzialfeldes ist gleich:

$$\nabla \Phi = \vec{v}$$

Für ein Potenzialfeld gilt $\text{rot}(\vec{v}) = 0$ und es erfüllt die **Integrabilitätsbedingungen**:

$$\frac{\partial v_i}{\partial x_j} = \frac{\partial v_j}{\partial x_i}, \forall i \neq j$$

Berechnung eines Potenzials

$$\text{gegeben: } \vec{v} = \begin{pmatrix} e^{xy}(1+xy) \\ e^{xy}x^2 \end{pmatrix}$$

$$\text{Nach } y \text{ integrieren: } \frac{\partial \Phi}{\partial y} = e^{xy}x^2 \Rightarrow \Phi = \int e^{xy}x^2 dy = xe^{xy} + C(x)$$

$$\text{Nach } x \text{ ableiten: } \frac{\partial \Phi}{\partial x} = e^{xy} + xye^{xy} + C' \stackrel{!}{=} e^{xy} + xye^{xy} \Rightarrow C' = 0 \Rightarrow C = \text{konst.}$$

$$\text{Potenzial: } \Phi = xe^{xy} + \text{konst.}$$

3.7 Koordinatentransformationen

3.7.1 Polarkoordinaten (\mathbb{R}^2)

Variablen: $x = r \cos(\phi)$
 $y = r \sin(\phi)$ **Volumenelement:** $\iint dxdy = \int_0^{2\pi} d\phi \int_0^R \textcolor{red}{r} dr$

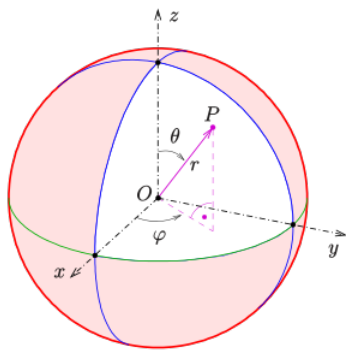
3.7.2 Elliptische Koordinaten (\mathbb{R}^2)

Variablen: $x = ra \cos(\phi)$
 $y = rb \sin(\phi)$ **Volumenelement:** $\iint dxdy = \textcolor{red}{a}\textcolor{red}{b} \int_0^{2\pi} d\phi \int_0^R \textcolor{red}{r} dr$

3.7.3 Zylinderkoordinaten (\mathbb{R}^3)

Variablen: $x = r \cos(\phi)$
 $y = r \sin(\phi)$
 $z = z$ **Volumenelement:** $\iiint dxdydz = \int_{-Z}^Z dz \int_0^{2\pi} d\phi \int_0^R \textcolor{red}{r} dr$

3.7.4 Kugelkoordinaten (\mathbb{R}^3)



Variablen: $x = r \sin(\theta) \cos(\varphi)$
 $y = r \sin(\theta) \sin(\varphi)$
 $z = r \cos(\theta)$ **Volumenelement:** $\iiint dxdydz = \int_0^{2\pi} d\varphi \int_0^\pi \textcolor{red}{\sin}(\theta) d\theta \int_0^R \textcolor{red}{r}^2 dr$