

ORF 522

Linear Optimization

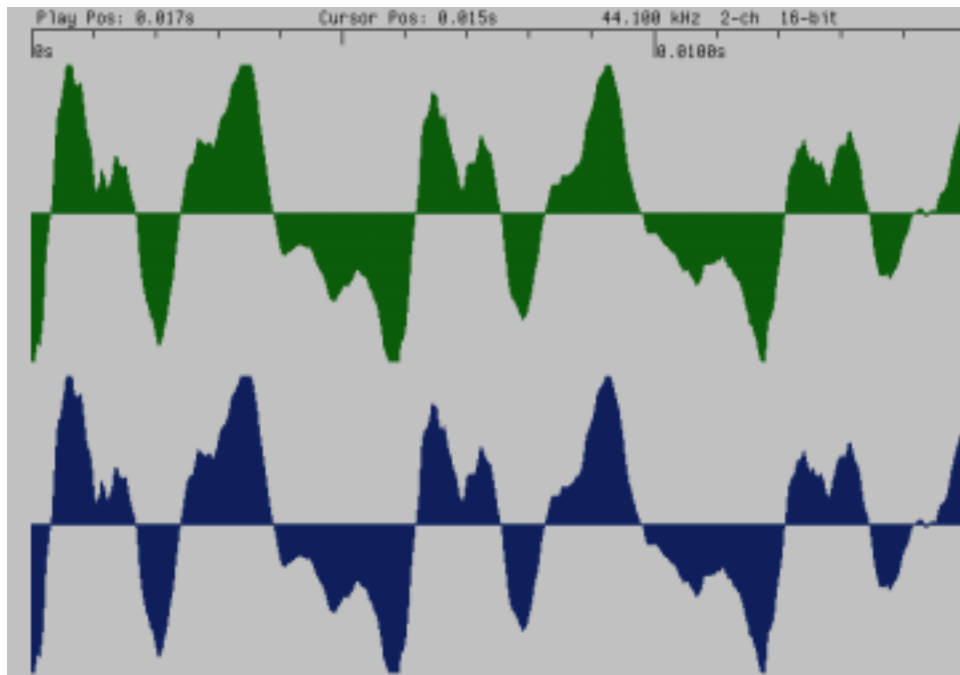
Lecture 19

Applications in Electrical Engineering

Digital Signal Processing¹

¹J.O. Coleman, [A Systematic Approach to the Constrained Quadratic Optimization of Embedded FIR Filters](#)

An Audio Signal



Digitization

44,100 samples/sec-channel

Each sample is a 2 byte (16 bit) integer
(i.e., between -32768 and 32767).

Stereo needs 176 kBytes/sec = 634 MBytes/hour.

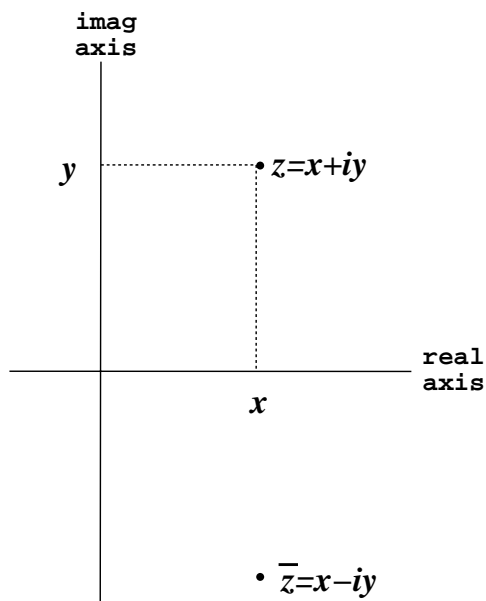
A Glimpse at the Data

0	-32768	20	23519	40	16975	60	12719
1	-32768	21	25247	41	16191	61	12223
2	-32768	22	27535	42	14799	62	11055
3	-30753	23	29471	43	12367	63	10479
4	-28865	24	31919	44	8607	64	10367
5	-29105	25	32767	45	5599	65	9951
6	-29201	26	32767	46	4927	66	10399
7	-26513	27	32767	47	5599	67	10255
8	-23681	28	32767	48	6799	68	8591
9	-18449	29	32031	49	9135	69	6671
10	-11025	30	29759	50	9839	70	5199
11	-6913	31	28399	51	8575	71	3823
12	-4337	32	28095	52	7615	72	2783
13	-1329	33	28399	53	5983	73	1567
14	1743	34	28751	54	5343	74	-785
15	6223	35	28751	55	6287	75	-4433
16	12111	36	26911	56	7183	76	-8737
17	17311	37	24063	57	8687	77	-12001
18	21311	38	21247	58	10927	78	-14369
19	23055	39	18415	59	12479	79	-16305

Complex Variables—A Brief Tutorial

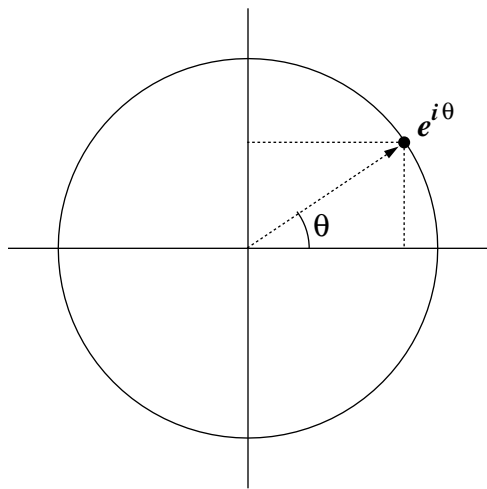
Complex Number: $z = x + iy$, where $i = \sqrt{-1}$

Complex Conjugate: $\bar{z} = x - iy$



Magnitude: $|z|^2 = z\bar{z} = x^2 + y^2$

The Unit Circle: $e^{i\theta} = \cos \theta + i \sin \theta$, $|e^{i\theta}|^2 = \cos^2 \theta + \sin^2 \theta = 1$



Input

Complex random sequence:

$$\dots, u_{-2}, u_{-1}, u_0, u_1, u_2, \dots$$

Assume:

$$\mathbf{E}u_k = 0$$

Autocorrelation:

$$s_k = \mathbf{E}u_j \bar{u}_{j+k}$$

Assumption: independent of j (random sequence is called **stationarity**).

Spectral Density = Fourier Transform:

$$\begin{aligned} S(\omega) &= \int_{-\infty}^{\infty} s_t e^{i\omega t} dt \\ &= \sum_k s_k e^{ik\omega} \end{aligned}$$

Power:

$$\mathbf{E}|u_0|^2 = s_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} S(\omega) d\omega$$

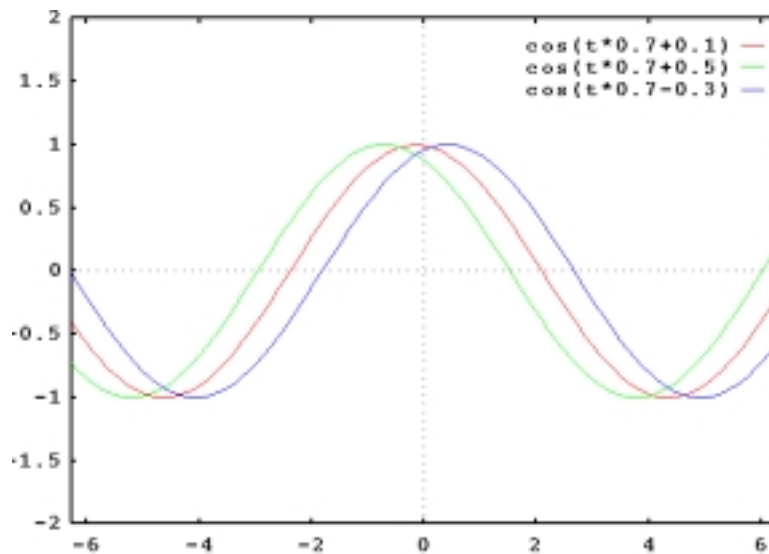
Example

A sine/cosine wave with frequency ω_0 but undetermined phase:

$$\begin{aligned} u_k &= e^{i(k\omega_0 + \theta)} \\ &= \cos(k\omega_0 + \theta) + i \sin(k\omega_0 + \theta) \end{aligned}$$

where

$$\theta = \text{Uniform}(-\pi, \pi)$$



$$\mathbf{E}u_k = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{i(k\omega_0+\theta)} d\theta = \frac{1}{2\pi} e^{ik\omega_0} \int_{-\pi}^{\pi} e^{i\theta} d\theta = 0$$

$$s_k = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{i(j\omega_0+\theta)} e^{-i((j+k)\omega_0+\theta)} d\theta = e^{-ik\omega_0}$$

The spectral density is a **delta function** at ω_0 :

$$S(\omega) = \cdots = 2\pi \delta_{\omega_0}(\omega)$$

Power:

$$P = \frac{1}{2\pi} \int_{-\pi}^{\pi} S(\omega) d\omega = 1$$

Finite Impulse Response (FIR) Filter

Finite Impulse Response

$$h_{-n+1}, \dots, h_{-1}, h_0, h_1, \dots, h_{n-1}$$

Assumption: $h_{-k} = h_k$ (called **linear phase filter**)

Autocorrelation

$$g_k = \sum_j h_j h_{j+k}$$

Fourier Transform of $\{h_k\}$

$$\begin{aligned} H(\omega) &= \sum_k h_k e^{ik\omega} \\ &= h_0 + 2 \sum_{k=1}^{n-1} h_k \cos(k\omega) \end{aligned}$$

Fourier Transform of $\{g_k\}$

$$\begin{aligned} G(\omega) &= \sum_k g_k e^{ik\omega} \\ &\vdots \\ &= |H(\omega)|^2 \end{aligned}$$

Output

At time k , the output includes the input from time $k - j$ multiplied by the impulse response h_j :

$$y_k = \sum_j h_j u_{k-j}.$$

The output is a **convolution** of the input and the filter.

Autocorrelation:

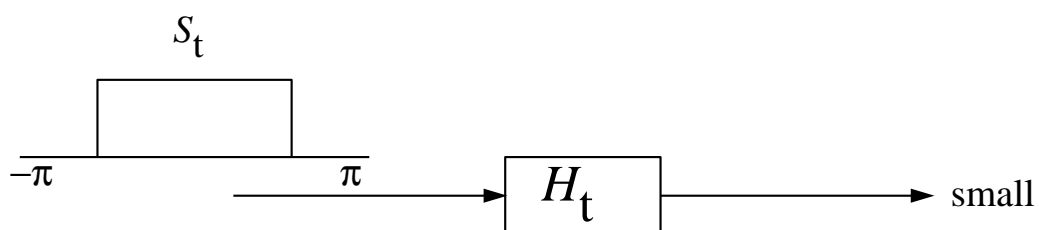
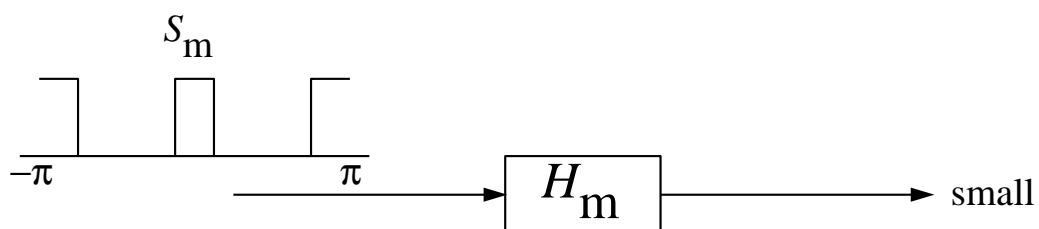
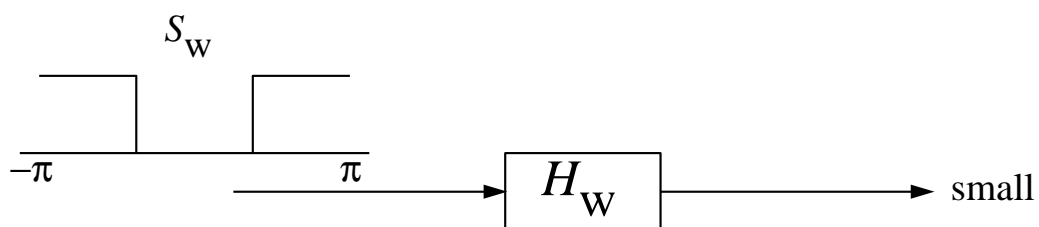
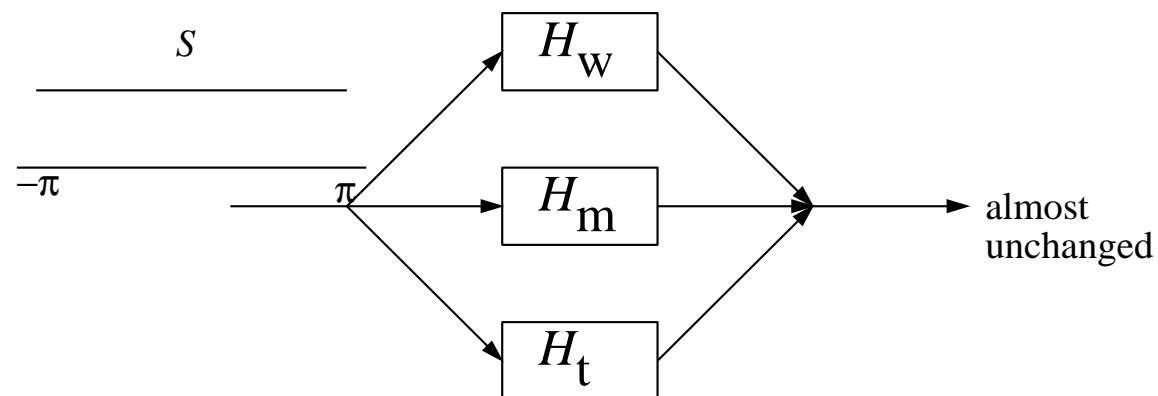
$$\begin{aligned} r_k &= \mathbf{E} y_j \bar{y}_{j+k} \\ &\vdots \\ &= \sum_j g_j s_{k-j}. \end{aligned}$$

Again, just a convolution.

Spectral Density:

$$\begin{aligned} R(\omega) &= \sum_k r_k e^{ik\omega} \\ &\vdots \\ &= G(\omega) S(\omega) \end{aligned}$$

A Design Specification



A Convex Optimization Problem

minimize:

$$\rho$$

subject to:

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} (H_{\mathbf{w}}(\omega) + H_{\mathbf{m}}(\omega) + H_{\mathbf{t}}(\omega) - 1)^2 d\omega \leq \epsilon$$

$$\left(\frac{1}{2\pi} \int_{-\pi}^{\pi} H_{\mathbf{w}}^2(\omega) S_{\mathbf{w}}(\omega) d\omega \right)^{1/2} \leq \rho$$

$$\left(\frac{1}{2\pi} \int_{-\pi}^{\pi} H_{\mathbf{m}}^2(\omega) S_{\mathbf{m}}(\omega) d\omega \right)^{1/2} \leq \rho$$

$$\left(\frac{1}{2\pi} \int_{-\pi}^{\pi} H_{\mathbf{t}}^2(\omega) S_{\mathbf{t}}(\omega) d\omega \right)^{1/2} \leq \rho$$

where

$$H_{\mathbf{s}}(\omega) = h_0^{\mathbf{s}} + 2 \sum_{k=1}^{n-1} h_k^{\mathbf{s}} \cos(k\omega), \quad \mathbf{s} = \mathbf{w}, \mathbf{m}, \mathbf{t}$$

Note: The integrals can be approximated by sums. They can also be integrated explicitly.

The ampl Model

```
# length 27 (-13,...,13) linear phase FIR filter

param n := 14;
param N := 1000;
param pi := 4*atan(1);
param eps := 1.0e-4;

set OMEGA := setof {j in -N..N} pi*j/N;

param Sw {omega in OMEGA} := (if abs(omega) > 0.4*pi then 1 else 0)
param Sm {omega in OMEGA} := (if abs(omega) < 0.2*pi
    || abs(omega) > 0.8*pi then 1 else 0);
param St {omega in OMEGA} := (if abs(omega) < 0.6*pi then 1 else 0)

var rho >= 0;
var hw {0..n-1};
var hm {0..n-1};
var ht {0..n-1};

var Hw {omega in OMEGA} =
    hw[0] + 2* sum {k in 1..n-1} (hw[k]*cos(k*omega));

var Hm {omega in OMEGA} =
    hm[0] + 2* sum {k in 1..n-1} (hm[k]*cos(k*omega));

var Ht {omega in OMEGA} =
    ht[0] + 2* sum {k in 1..n-1} (ht[k]*cos(k*omega));

minimize power_bnd: rho;

subject to passband:
    sqrt(sum {omega in OMEGA} (Hw[omega]+Hm[omega]+Ht[omega]-1)^2)
    <= sqrt(N)*sqrt(2*pi*eps);

subject to wooferband:
    sqrt(sum {omega in OMEGA} Hw[omega]^2 * Sw[omega])
    <= sqrt(N)*rho;

subject to midrangeband:
    sqrt(sum {omega in OMEGA} Hm[omega]^2 * Sm[omega])
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    <= sqrt(N)*rho;

subject to tweeterband:
    sqrt(sum {omega in OMEGA} Ht[omega]^2 * St[omega])
    <= sqrt(N)*rho;

let hw[0] := 2;
let hm[0] := 2;
let ht[0] := 2;

solve;

printf {omega in OMEGA}: "%7.4f %10.3e \n",
    omega, 20*log10(abs(Hw[omega])) > 3w.out;

printf {omega in OMEGA}: "%7.4f %10.3e \n",
    omega, 20*log10(abs(Hm[omega])) > 3m.out;

printf {omega in OMEGA}: "%7.4f %10.3e \n",
    omega, 20*log10(abs(Ht[omega])) > 3t.out;

```

The Iteration Log

LOQO 4.01: verbose=2

timing=1

variables: non-neg 1, free 42, bdd 0, total 43
 constraints: eq 0, ineq 4, ranged 0, total 4
 nonzeros: A 87, Q 1764

Iter	Primal		Dual		Sig Fig	Status	P	M
	Obj Value	Infeas	Obj Value	Infeas				
1	0.0000000e+00	5.47e+00	-4.5048766e+01	8.20e+01				
nonzeros: L 990, arith_ops 31041								
2	8.1566802e-02	2.67e+00	-2.2246490e+01	3.11e+01				
3	4.2789358e-02	9.91e-01	-8.2537485e+00	1.14e+01				
4	1.3387496e-01	2.06e-01	-1.6740002e+00	2.32e+00				
5	1.6865099e-02	1.16e-01	1.0434433e-01	1.86e-01	1			
6	1.3181610e-03	1.40e-01	-8.0805850e-03	1.50e-02	2			
7	7.5265116e-05	1.44e-01	4.5425492e-04	9.05e-04	3			
8	5.9279466e-06	1.39e-01	-3.6288050e-05	6.97e-05	4			
9	3.1343416e-06	7.84e-02	1.8886582e-05	3.31e-05	5			1
10	2.6317200e-07	6.24e-02	-1.6970215e-06	1.62e-05	6			
11	6.9794369e-08	6.42e-02	3.1953216e-07	5.72e-06	7			
12	1.5662519e-08	1.32e+00	-4.2603108e-10	2.60e-06	8			
13	1.0162506e-08	2.59e-01	3.9640273e-08	7.34e-07	8	DF		
14	7.3901217e-09	2.07e-01	4.5719497e-08	4.30e-07	7	DF		
15	6.8298003e-09	1.83e-01	8.6045607e-08	2.07e-07	7	DF		
.								
.								
.								
28	2.3814666e-07	1.78e-01	1.6399637e-03	4.01e-07	3	DF		
29	9.4878775e-04	2.17e-01	3.3674241e-04	9.48e-03	3			
30	1.4551883e-03	1.01e-01	9.6862590e-04	6.88e-03	3			
31	1.7563445e-03	4.66e-02	1.3613840e-03	4.52e-03	3			
32	2.0179127e-03	1.25e-02	1.6853065e-03	2.00e-03	3			
33	2.1373955e-03	1.72e-03	1.9841897e-03	3.99e-04	4			
34	2.1589812e-03	1.17e-04	2.1435636e-03	2.86e-05	5			
35	2.1603608e-03	6.05e-06	2.1595563e-03	1.48e-06	6			
36	2.1604314e-03	3.03e-07	2.1603910e-03	7.43e-08	7	PF	DF	
37	2.1604349e-03	1.52e-08	2.1604329e-03	3.72e-09	9	PF	DF	

 OPTIMAL SOLUTION FOUND

The Output

