The Homogeneous Self-Dual Method

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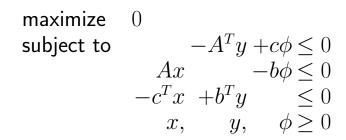
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The Homogeneous Self-Dual Problem

Primal-Dual Pair

$$\begin{array}{ll} \text{minimize} & b^T y \\ \text{subject to} & A^T y \geq c \\ & y \geq 0 \end{array}$$

Homogeneous Self-Dual Problem





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In Matrix Notation

$$\begin{array}{ll} \text{maximize} & 0 \\ \text{subject to} & \begin{bmatrix} 0 & -A^T & c \\ A & 0 & -b \\ -c^T & b^T & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ \phi \end{bmatrix} \leq \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\ x,y,\phi \geq 0. \end{array}$$

HSD is self-dual (constraint matrix is skew symmetric).

HSD is feasible
$$(x = 0, y = 0, \phi = 0)$$
.

HSD is homogeneous—i.e., multiplying a feasible solution by a positive constant yields a new feasible solution.

Any feasible solution is optimal.

If ϕ is a null variable, then either primal or dual is infeasible (see text).



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Theorem. Let (x, y, ϕ) be a solution to HSD. If $\phi > 0$, then

- \bullet $x^* = x/\phi$ is optimal for primal, and
- $y^* = y/\phi$ is optimal for dual.



 x^* is primal feasible—obvious.

 y^* is dual feasible—obvious.

Weak duality theorem implies that $c^T x^* \leq b^T y^*$.

3rd HSD constraint implies reverse inequality.

Primal feasibility, plus dual feasibility, plus no gap implies optimality.



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Change of Notation

$$\begin{vmatrix} 0 & -A^T & c \\ A & 0 & -b \\ -c^T & b^T & 0 \end{vmatrix} \longrightarrow A \qquad \begin{vmatrix} x \\ y \\ \phi \end{vmatrix} \longrightarrow x \qquad n+m+1 \longrightarrow n$$

$$\begin{bmatrix} x \\ y \\ \phi \end{bmatrix} \longrightarrow x$$

$$n+m+1 \longrightarrow m$$



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In New Notation:

maximize 0 subject to Ax + z = 0x, z > 0

More Notation

Infeasibility:
$$\rho(x,z) = Ax + z$$

Complementarity: $\mu(x,z) = \frac{1}{n}x^Tz$

Nonlinear System

$$\begin{array}{rcl} A(x+\Delta x) + (z+\Delta z) & = & \delta(Ax+z) \\ (X+\Delta X)(Z+\Delta Z)e & = & \delta\mu(x,z)e \end{array}$$

Linearized System

$$A\Delta x + \Delta z = -(1 - \delta)\rho(x, z)$$

$$Z\Delta x + X\Delta z = \delta\mu(x, z)e - XZe$$



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Algorithm

Solve linearized system for $(\Delta x, \Delta z)$.

Pick step length θ .

Step to a new point:

$$\bar{x} = x + \theta \Delta x, \qquad \bar{z} = z + \theta \Delta z.$$

Even More Notation

$$\bar{\rho} = \rho(\bar{x}, \bar{z}), \qquad \bar{\mu} = \mu(\bar{x}, \bar{z})$$



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Theorem 2

- 1. $\Delta z^T \Delta x = 0$.
- 2. $\bar{\rho} = (1 \theta + \theta \delta) \rho$.
- 3. $\bar{\mu} = (1 \theta + \theta \delta)\mu$.
- 4. $\bar{X}\bar{Z}e \bar{\mu}e = (1-\theta)(XZe \mu e) + \theta^2 \Delta X \Delta Ze$.

Proof.

- 1. Tedious but not hard (see text).
- 2.

$$\bar{\rho} = A(x + \theta \Delta x) + (z + \theta \Delta z)$$

$$= Ax + z + \theta (A\Delta x + \Delta z)$$

$$= \rho - \theta (1 - \delta)\rho$$

$$= (1 - \theta + \theta \delta)\rho.$$



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$$\bar{x}^T \bar{z} = (x + \theta \Delta x)^T (z + \theta \Delta z)$$

$$= x^T z + \theta (z^T \Delta x + x^T \Delta z) + \theta^2 \Delta x^T \Delta z$$

$$= x^T z + \theta e^T (\delta \mu e - X Z e)$$

$$= (1 - \theta + \theta \delta) x^T z.$$

Now, just divide by n.

4.

$$\begin{split} \bar{X}\bar{Z}e - \bar{\mu}e &= (X + \theta\Delta X)(Z + \theta\Delta Z)e - (1 - \theta + \theta\delta)\mu e \\ &= XZe - \mu e + \theta(X\Delta z + Z\Delta x + (1 - \delta)\mu e) + \theta^2\Delta X\Delta Z_{\text{EACK}} \\ &= (1 - \theta)(XZe - \mu e) + \theta^2\Delta X\Delta Ze. \end{split}$$



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Neighborhoods of
$$\{(x,z) > 0 : x_1z_1 = x_2z_2 = \cdots = x_nz_n\}$$

$$\mathcal{N}(\beta) = \{(x, z) > 0 : ||XZe - \mu(x, z)e|| \le \beta \mu(x, z)\}$$

Note: $\beta < \beta'$ implies $\mathcal{N}(\beta) \subset \mathcal{N}(\beta')$.

Predictor-Corrector Algorithm

Odd Iterations-Predictor Step

Assume $(x, z) \in \mathcal{N}(1/4)$.

Compute $(\Delta x, \Delta z)$ using $\delta = 0$.

Compute θ so that $(\bar{x}, \bar{z}) \in \mathcal{N}(1/2)$.

Even Iterations—Corrector Step

Assume $(x, z) \in \mathcal{N}(1/2)$.

Compute $(\Delta x, \Delta z)$ using $\delta = 1$.

Put $\theta = 1$.



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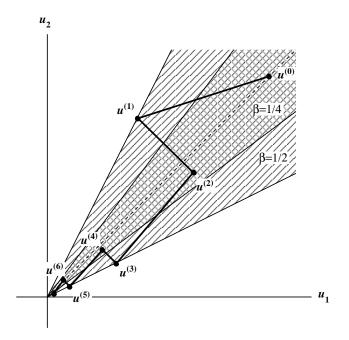
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Predictor-Corrector Algorithm

In Complementarity Space

Let

$$u_j = x_j z_j \qquad j = 1, 2, \dots, n.$$





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Well-Definedness of Algorithm



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Must check that preconditions for each iteration are met.

Technical Lemma.

- 1. If $\delta = 0$, then $\|\Delta X \Delta Z e\| \leq \frac{n}{2}\mu$.
- 2. If $\delta = 1$ and $(x, z) \in \mathcal{N}(\beta)$, then $\|\Delta X \Delta Z e\| \leq \frac{\beta^2}{1-\beta} \mu/2$.

Proof. Tedious and tricky. See text.

Theorem.

- 1. After a predictor step, $(\bar{x}, \bar{z}) \in \mathcal{N}(1/2)$ and $\bar{\mu} = (1 \theta)\mu$.
- 2. After a corrector step, $(\bar{x}, \bar{z}) \in \mathcal{N}(1/4)$ and $\bar{\mu} = \mu$.

Proof.

1. $(\bar{x}, \bar{z}) \in \mathcal{N}(1/2)$ by definition of θ .

$$\bar{\mu} = (1 - \theta)\mu$$
 since $\delta = 0$.

2. $\theta = 1$ and $\beta = 1/2$. Therefore,

$$\|\bar{X}\bar{Z}e - \bar{\mu}e\| = \|\Delta X\Delta Ze\| \le \mu/4.$$

Need to show also that $(\bar{x}, \bar{z}) > 0$. Intuitively clear (see earlier picture) but proof is tedious. See text.



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Complexity Analysis

Progress toward optimality is controlled by the stepsize θ .

Theorem. In predictor steps, $\theta \ge \frac{1}{2\sqrt{n}}$.

Proof.

Consider taking a step with step length $t \le 1/2\sqrt{n}$:

$$x(t) = x + t\Delta x,$$
 $z(t) = z + t\Delta z.$

From earlier theorems and lemmas,

$$\begin{split} \|X(t)Z(t)e - \mu(t)e\| & \leq (1-t)\|XZe - \mu e\| + t^2 \|\Delta X \Delta Ze\| \\ & \leq (1-t)\frac{\mu}{4} + t^2 \frac{n\mu}{2} \\ & \leq (1-t)\frac{\mu}{4} + \frac{\mu}{8} \\ & \leq (1-t)\frac{\mu}{4} + (1-t)\frac{\mu}{4} \\ & = \frac{\mu(t)}{2}. \end{split}$$

Therefore $(x(t), z(t)) \in \mathcal{N}(1/2)$ which implies that $\theta \geq 1/2\sqrt{n}$.



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 $\mu^{(2k)} = (1 - \theta^{(2k-1)})(1 - \theta^{(2k-3)}) \cdots (1 - \theta^{(1)})\mu^{(0)}$ and $\mu^{(0)} = 1$, we see from the previous theorem that

$$\mu^{(2k)} \le \left(1 - \frac{1}{2\sqrt{n}}\right)^k.$$

$$\mu^{(2k)} \leq \left(1-\frac{1}{2\sqrt{n}}\right) \ .$$
 Hence, to get a small number, say 2^{-L} , as an upper bound for $\mu^{(2k)}$

Since

it suffices to pick k so that:

$$\left(1 - \frac{1}{2\sqrt{n}}\right)^k \le 2^{-L}.$$

This inequality is implied by the following simpler one:

 $k > 2\log(2)L\sqrt{n}$.

Since the number of iterations is
$$2k$$
, we see that $4\log(2)L\sqrt{n}$ iterations will suffice to make the final value of μ be less than 2^{-L} .

Of course,

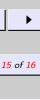
$$\rho^{(k)} = \mu^{(k)} \rho^{(0)}$$

so the same bounds guarantee that the final infeasibility is small too.















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Back to Original Primal-Dual Setting

Just a final remark: If primal and dual problems are feasible, then algorithm will produce a solution to HSD with $\phi>0$ from which a solution to original problem can be extracted. See text for details.

