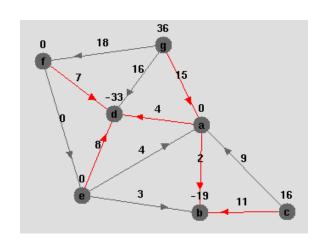
# Linear Programming: Chapter 13 Network Flows: Theory

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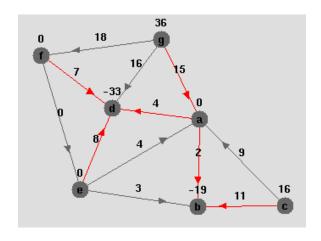
## Networks



#### Basic elements:

- $\mathcal{N}$  Nodes (let m denote number of them).
- A Directed Arcs
  - subset of all possible arcs:  $\{(i,j): i,j \in \mathcal{N}, i \neq j\}$ .
  - arcs are *directed*:  $(i, j) \neq (j, i)$ .

## Network Flow Data



- $b_i$ ,  $i \in \mathcal{N}$ , supply at node i
- $c_{ij}$ ,  $(i,j) \in \mathcal{A}$ , cost of shipping 1 unit along arc (i,j).

Note: demands are recorded as negative supplies.

## **Network Flow Problem**

#### **Decision Variables:**

•  $x_{ij}$ ,  $(i, j) \in \mathcal{A}$ , quantity to ship along arc (i, j).

### Objective:

minimize 
$$\sum_{(i,j)\in\mathcal{A}} c_{ij} x_{ij}$$

## Network Flow Problem-Cont.

#### **Constraints:**

• Mass conservation (aka flow balance):

$$\begin{split} \inf & \mathsf{low}(k) - \mathsf{outflow}(k) = \, \mathsf{demand}(k) \, = -\mathsf{supply}(k), \qquad k \in \mathcal{N} \\ & \qquad \qquad \updownarrow \\ & \sum_{\substack{i \, : \\ (i,k) \, \in \, \mathcal{A}}} x_{ik} - \sum_{\substack{j \, : \\ (k,j) \, \in \, \mathcal{A}}} x_{kj} & = & -b_k, \qquad k \in \mathcal{N} \end{split}$$

Nonnegativity:

$$x_{ij} \ge 0, \qquad (i,j) \in \mathcal{A}$$

# **Matrix Notation**

$$\begin{array}{ll} \text{minimize} & c^T x \\ \text{subject to} & Ax = -b \\ & x \geq 0 \end{array}$$

where

$$\begin{bmatrix} -1 & -1 & 1 & 1 & 1 & \end{bmatrix}$$

 $c^T = \begin{bmatrix} 2 & 4 & 9 & 11 & 4 & 3 & 8 & 7 & 0 & 15 & 16 & 18 \end{bmatrix}$ 

## Notes

- A is called *node-arc incidence matrix*.
- A is large and sparse.

## **Dual Problem**

#### In network notation:

$$\begin{array}{ll} \text{maximize} & -\sum_{i \in \mathcal{N}} b_i y_i \\ \text{subject to} & y_j - y_i + z_{ij} = c_{ij} & (i,j) \in \mathcal{A} \\ & z_{ij} \geq 0 & (i,j) \in \mathcal{A} \end{array}$$

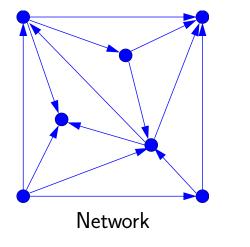
# Complementarity Relations

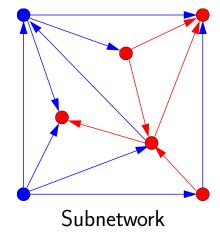
- The primal variables must be nonnegative.
- Therefore the associated dual constraints are inequalities.
- The dual slack variables are complementary to the primal variables:

$$x_{ij}z_{ij}=0, \qquad (i,j)\in\mathcal{A}$$

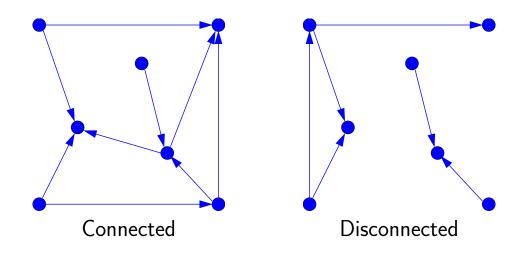
- The primal constraints are equalities.
- Therefore they have no slack variables.
- $\bullet$  The corresponding dual variables, the  $y_i$ 's, are free variables.
- No complementarity conditions apply to them.

# Definition: Subnetwork

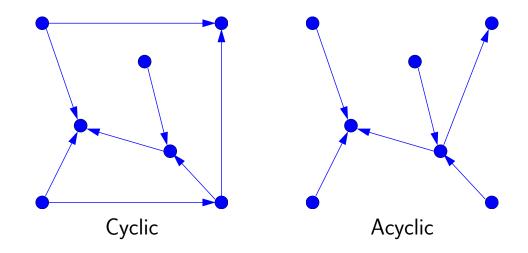




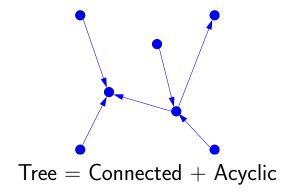
# Connected vs. Disconnected

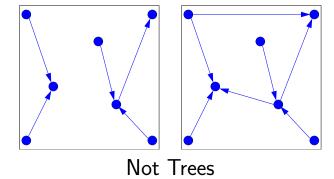


# Cyclic vs. Acyclic

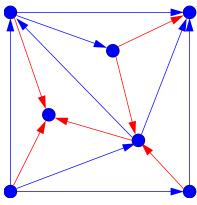


# **Trees**





# **Spanning Trees**



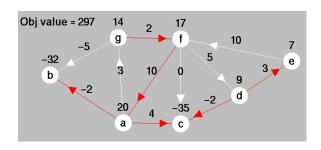
Spanning Tree-A tree touching every node

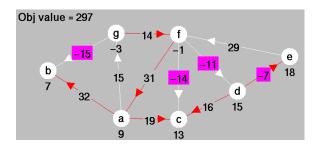
#### Tree Solution

$$x_{ij} = 0$$
 for  $(i, j) \not\in \mathsf{Tree} \; \mathsf{Arcs}$ 

Note: Tree solutions are easy to compute—start at the leaves and work inward...

# Online Pivot Tool–Notations





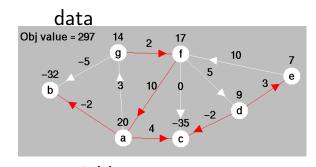
#### Data:

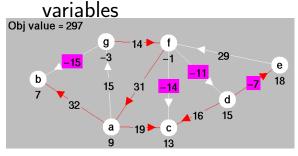
- *Costs* on arcs shown above arcs.
- Supplies at nodes shown above nodes.

#### Variables:

- *Primal flows* shown on tree arcs.
- *Dual slacks* shown on nontree arcs.
- Dual variables shown below nodes.

# Tree Solutions-An Example





- Fix a root node, say a.
- Primal flows on tree arcs calculated recursively from leaves inward.
- Dual variables at nodes calculated recursively from root node outward along tree arcs using:

$$y_j - y_i = c_{ij}$$

• *Dual slacks* on nontree arcs calculated using:

$$z_{ij} = y_i - y_j + c_{ij}.$$