

The Theory of NP-Completeness

Tractable and intractable problems
NP-complete problems

The theory of NP-completeness

- Tractable and intractable problems
- NP-complete problems

Classifying problems

- Classify problems as tractable or intractable.
- Problem is *tractable* if there **exists at least one** polynomial bound algorithm that solves it.
- An algorithm is *polynomial bound* if its worst case growth rate can be bound by a polynomial $p(n)$ in the size n of the problem

$$p(n) = a_n n^k + \dots + a_1 n + a_0 \text{ where } k \text{ is a constant}$$

Intractable problems

- Problem is *intractable* if it is not tractable.
- **All** algorithms that solve the problem are not polynomial bound.
- It has a worst case growth rate $f(n)$ which cannot be bound by a polynomial $p(n)$ in the size n of the problem.
- For intractable problems the bounds are:

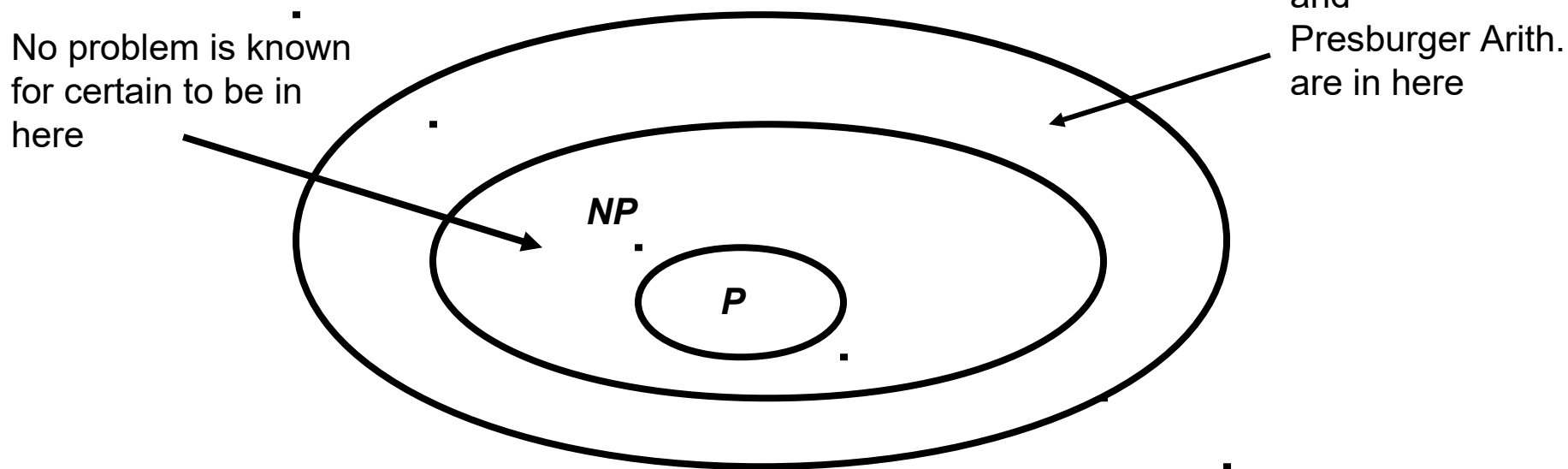
$$f(n) = c^n, \text{ or } n^{\log n}, \text{ etc.}$$

Why is this classification useful?

- If problem is intractable, no point in trying to find an efficient algorithm
- All algorithms will be too slow for **large inputs**.

Intractable problems

- Turing showed some problems are so hard that no algorithm can solve them (undecidable)
- Other researchers showed some decidable problems from automata, mathematical logic, etc. are intractable:
Presburger Arithmetic



Hard practical problems

- There are many practical problems for which no one has yet found a polynomial bound algorithm.
- Examples: traveling salesperson, 0/1 knapsack, graph coloring, bin packing etc.
- Most design automation problems such as testing and routing.
- Many networks, database and graph problems.

How are they solved?

- A variety of algorithms based on backtracking, branch and bound, dynamic programming, etc.
- None can be shown to be polynomial bound

The theory of NP completeness

- The theory of NP-completeness enables showing that these problems are at least as hard as *NP-complete* problems
- Practical implication of knowing problem is NP-complete is that it is **probably** intractable (whether it is or not has not been proved yet)
- So any algorithm that solves it will probably be very slow for large inputs

We will need to discuss

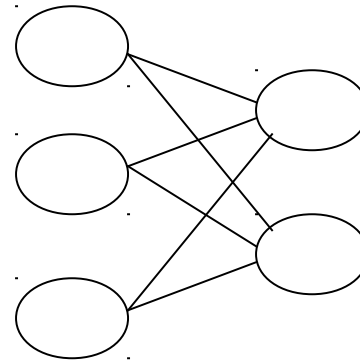
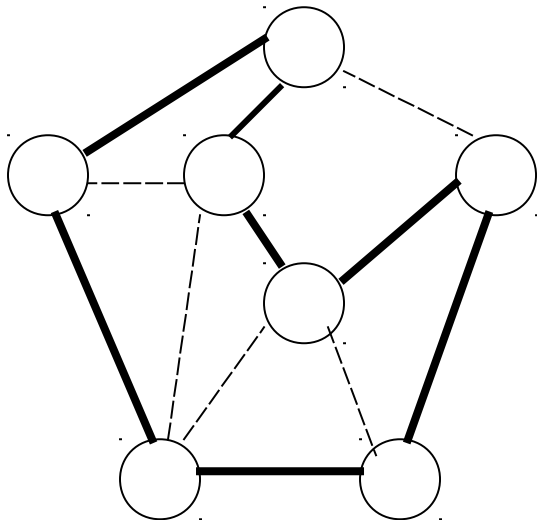
- Decision problems
- Converting optimization problems into decision problems
- The relationship between an optimization problem and its decision version
- The class P
- Verification algorithms
- The class NP
- The concept of polynomial transformations
- The class of NP-complete problems

Decision Problems

- A *decision* problem answers *yes or no* for a given input
- Examples:
 - Given a graph G Is there a path from s to t of length at most k ?
 - Does graph G contain a Hamiltonian cycle?
 - Given a graph G is it bipartite?

A decision problem: HAMILTONIAN-CYCLE

- A *Hamiltonian cycle* of a graph G is a cycle that includes each vertex of the graph exactly once.
- Problem: Given a graph G , does G have a Hamiltonian cycle?



Converting to decision problems

- Optimization problems can be converted to decision problems (typically) by adding a bound B on the value to optimize, and asking the question:
 - Is there a solution whose value is at most B ? (for a minimization problem)
 - Is there a solution whose value is at least B ? (for a maximization problem)

An optimization problem: traveling salesman

- Given:
 - A finite set $C=\{c_1,\dots,c_m\}$ of cities,
 - A distance function $d(c_i, c_j)$ of nonnegative numbers.
- Find the length of the **minimum** distance tour which includes every city exactly once

A decision problem for traveling salesman (TS)

- Given a finite set $C=\{c_1,\dots,c_m\}$ of cities, a distance function $d(c_i, c_j)$ of nonnegative numbers and a bound B
- Is there a tour of all the cities (in which each city is visited exactly once) with total length **at most B** ?
- There is no known polynomial bound algorithm for TS.

The relation between

- If we have a solution to the optimization problem we can compare the solution to the bound and answer “yes” or “no”.
- Therefore if the optimization problem is tractable so is the decision problem
- If the decision problem is “hard” the optimization problems are also “hard”
 - If the optimization was easy then the decision problem is easy.

The class P

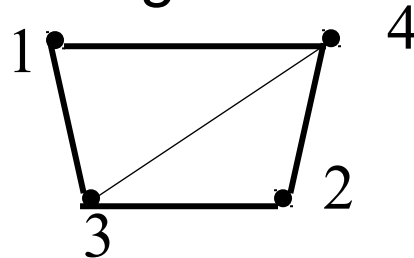
- P is the class of decision problems that are polynomial bounded
- Is the following problem in P?
 - Given a weighted graph G , is there a spanning tree of weight at most B ?
- The decision versions of problems such as shortest distance, and minimum spanning tree belong to P

The goal of verification algorithms

- The goal of a verification algorithm is to verify a “yes” answer to a decision problem’s input (i.e., if the answer is “yes” the verification algorithm verify this answer)
- The inputs to the verification algorithm are:
 - the original input (problem instance) and
 - a *certificate* (possible solution)

Verification Algorithms

- A *verification algorithm*, takes a problem instance x and answers “yes”, if there **exists** a certificate y such that the answer for x with certificate y is “yes”
- Consider HAMILTONIAN-CYCLE
- A problem *instance* x lists the vertices and edges of G : $(\{1,2,3,4\}, \{(3,2), (2,4), (3,4), (4,1), (1, 3)\})$
- There **exists** a certificate $y = (3, 2, 4, 1, 3)$ for which the verification algorithm answers “yes”



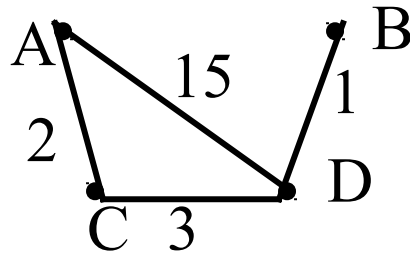
Polynomial bound verification algorithms

- Given a decision problem d .
- A verification algorithm for d is *polynomial bound* if given an input x to d , there exists a certificate y , such that $|y| = O(|x|^c)$ where c is a constant, and a polynomial bound algorithm $A(x, y)$ that verifies an answer “yes” for d with input x

Note: $|y|$ is the size of the certificate, $|x|$ is the size of the input

The problem PATH

- PATH denotes the decision problem version of shortest path.
- PATH: Given a graph G , a start vertex u , and an end vertex v . Does there exist a path in G , from u to v of length at most k ?
- The instance is: $G=(\{A, B, C, D\}, \{(A, C, 2), (A, D, 15), (C, D, 3), (D, B, 1)\})$ $k=6$
- A certificate $y=(A, C, D, B)$



A verification algorithm for PATH

- Verification algorithm:
 - Given the problem instance x and a certificate y
 - Check that y is indeed a path from u to v .
 - Verify that the length of y is at most k
- Is the verification algorithm for PATH polynomial bound?
- Is the size of y polynomial in the size of x ?
- Is the verification algorithm polynomial bound?

Example: A verification algorithm for TS

- Given a problem instance x for TS and a certificate y
 - Check that y is indeed a cycle that includes every vertex exactly once
 - Verify that the length of the cycle is at most B
- Is the size of y polynomial in the size of x ?
- Is the verification algorithm polynomial?

The class NP

- NP is the class of decision problems for which there is a polynomial bounded verification algorithm
- It can be shown that:
 - all decision problems in P, and
 - decision problems such as traveling salesman, knapsack, bin pack, are also in NP

The relation between P and NP

- $P \subseteq NP$
- If a problem is solvable in polynomial time, a polynomial time verification algorithm can easily be designed that *ignores the certificate* and answers “yes” for all inputs with the answer “yes”.

The relation between P and NP

- It is not known whether $P = NP$.
- Problems in P can be *solved* “quickly”
- Problems in NP can be *verified* “quickly”.
- It is easier to verify a solution than to solve a problem.
- Some researchers believe that P and NP are not the same class.

Polynomial reductions

- **Motivation:** The definition of NP-completeness uses the notion of *polynomial reductions* of one problem A to another problem B, written as

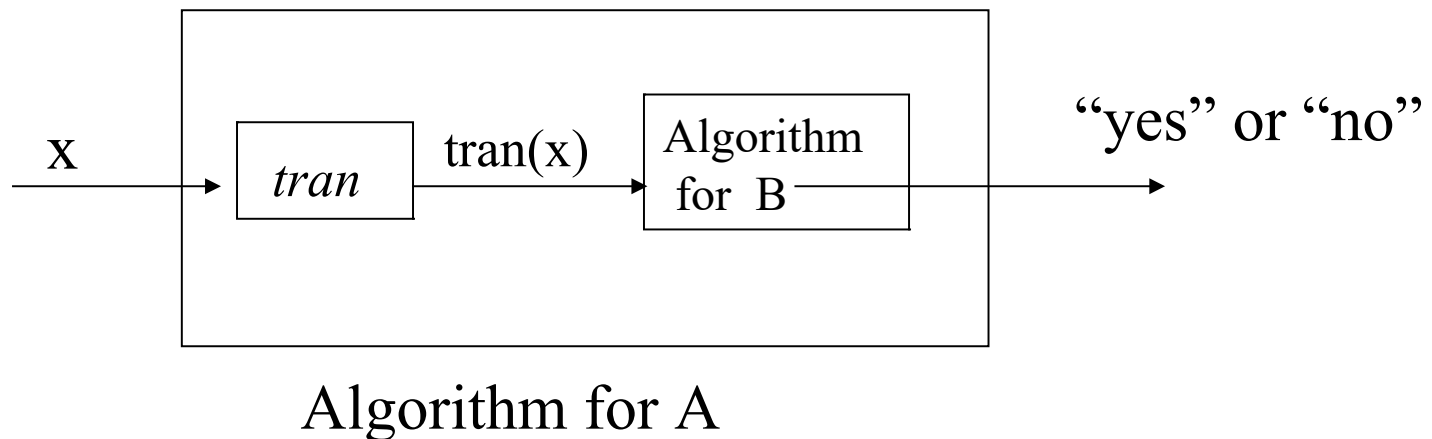
$$A \propto B$$

- Let *tran* be a function that converts any input x for decision problem A into input tran(x) for decision problem B

Polynomial reductions

tran is a *polynomial reduction* from *A* to *B* if:

1. *tran* can be computed in polynomial bounded time
2. The answer to *A* for input *x* is yes if and only if the answer to *B* for input *tran*(*x*) is yes.



Two simple problems

- A: Given n Boolean variables with values x_1, \dots, x_n , does at least one variable have the value True?
- B: Given n integers i_1, \dots, i_n is $\max\{i_1, \dots, i_n\} > 0$?

Algorithm for B :

Check the integers one after the other.

If one is positive stop and answer “yes”,
otherwise (if none is positive) stop and answer “no”.

Example:

$n=4$.

Given integers: -1, 0, 3, and 20.

Algorithm for B answers “yes”.

Given integers: -1, 0, 0, and 0.

Algorithm for B answers “no”.

Is there a transformation?

- Can we transform an instance of A into an instance of B?
- Yes.

```
tran(x)
for (j=1; j ≤ n; j++)
    if (xj == true)
        ij = 1
    else // xj = false
        ij = 0
```

$T(\text{false}, \text{false}, \text{true}, \text{false}) = 0, 0, 1, 0$

- Is this transformation polynomial bounded? yes

Does it satisfy all the requirements?

- Can we show that when the answer for an instance x_1, \dots, x_n of A is “yes” the answer for the transformed instance $tran(x_1, \dots, x_n) = i_1, \dots, i_n$ of B is also “yes”?
- If the answer for the given instance x_1, \dots, x_n of A is “yes”, there is some $x_j = \text{true}$.
- The transformation assigns $i_j = 1$.
- Therefore the answer for problem B is also “yes” (the maximum is positive)

The other direction

- Can we also show that when the answer for problem B with input $tran(x_1, \dots, x_n) = i_1, \dots, i_n$ is “yes”, the answer for the instance x_1, \dots, x_n of A is also “yes”?
- If the answer for problem B is “yes”, it means that there is an $i_j > 0$ in the transformed instance.
- i_j is either 0 or 1 in the transformed instance. So $i_j = 1$, and therefore $x_j = \text{true}$.
- So the answer for A is also “yes”

Polynomial reductions

Theorem:

If $A \leq B$ and B is in P , then A is in P

If A is not in P then B is also not in P

NP-complete problems

- A problem A is *NP-complete* if
 1. It is in NP and
 2. For every other problem A' in NP, $A' \leq A$
- A problem A is *NP-hard* if
For every other problem A' in NP, $A' \leq A$

Examples of NP-Complete problems

- Cook's theorem
 - Satisfiability is NP-complete
- This was the first problem shown to be NP-complete
- Other problems
 - the decision version of knapsack,
 - the decision version of traveling salesman

Coping with NP- Complete Problems

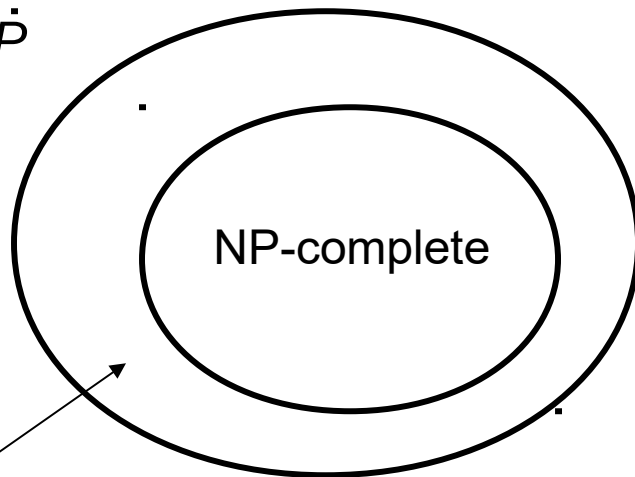
- To solve use approximations, heuristics, etc.
- Sometimes we need to solve only a restricted version of the problem.
- If restricted problem tractable design an algorithm for restricted problem

NP-complete problems: Theorem

If any NP-complete problem is in P, then $P = NP$.

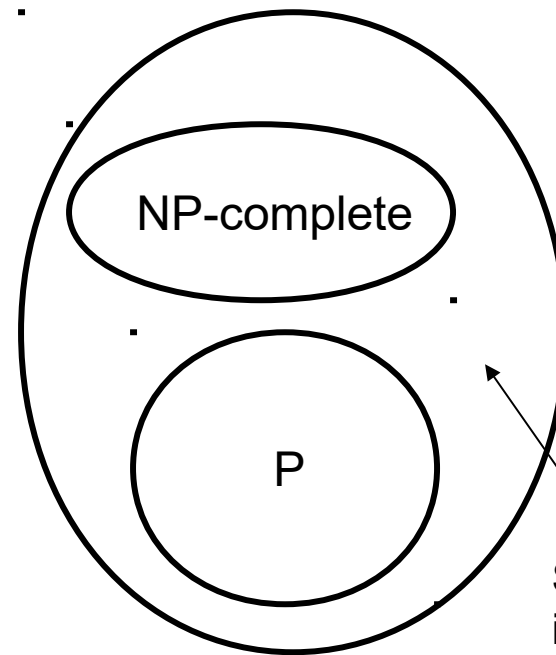
If any NP-complete problem is not polynomial bound, then all NP-Complete problems are not polynomial bound.

$P = NP$



The trivial decision problem that always answers "yes" in here

$NP \neq P$



Some Problem is definitely in here

NP-completeness and Reducibility

- The existence of NP-complete problems leads us to suspect that $P \neq NP$.
- If HAMILTONIAN CYCLE could be solved in polynomial time, every problem in NP can be solved in polynomial time.
- If HAMILTONIAN CYCLE could not be solved in polynomial time, every NP-complete problem cannot be solved in polynomial time.

The Satisfiability problem

- First, Conjunctive Normal Form (CNF) will be defined
- Then, the Satisfiability problem will be defined
- Finally, we will show a polynomial bounded verification algorithm for the problem

Conjunctive Normal Form (CNF)

- A *logical (Boolean) variable* is a variable that may be assigned the value *true* or *false* (p , q , r and s are Boolean variables)
- A *literal* is a logical variable or the negation of a logical variable (p and $\neg q$ are literals)
- A *clause* is a disjunction of literals
($(p \vee q \vee s)$ and $(\neg q \vee r)$ are clauses)

Conjunctive Normal Form (CNF)

- A logical (Boolean) expression is in Conjunctive Normal Form if it is a conjunction of *clauses*.
- The following expression is in conjunctive normal form:

$$(p \vee q \vee s) \wedge (\neg q \vee r) \wedge (\neg p \vee r) \wedge (\neg r \vee s) \wedge (\neg p \vee \neg s \vee \neg q)$$

The Satisfiability problem

- Is there a truth assignment to the n variables of a logical expression in Conjunctive Normal Form which makes the value of the expression true?
- For the answer to be “yes”, all clauses must evaluate to true
- Otherwise the answer is “no”

The Satisfiability problem

- $p=T, q=F, r=T$ and $s=T$ is a truth assignment for:
 $(p \vee q \vee s) \wedge (\neg q \vee r) \wedge (\neg p \vee r) \wedge (\neg r \vee s) \wedge (\neg p \vee \neg s \vee \neg q)$
- Note that if $q=F$ then $\neg q=T$
- Each clause evaluates to true

A verification algorithm for Satisfiability

1. Check that the certificate s is a string of exactly n characters which are T or F.
2. **while** (there are unchecked clauses) {
 select next clause
 if (clause evaluates to false) **return**(“no”) }
3. **return** (“yes”)

- Is verification algorithm polynomial bound?
- Satisfiability is in NP since there exists a polynomial bound verification algorithm for it