

Event-B conventions

Event-B mathematical basis: predicate calculus

- partition is a shorthand definition of a set that can be partitioned into separate, disjoint parts (subsets)
- If the parts (subsets) are singleton sets, e.g., of the form {element}, such a definition defines of an enumerated set
- For instance, $\text{partition}(\text{Set}, \{\text{element1}\}, \{\text{element2}\}, \{\text{element3}\})$ is a shorthand for the axioms
 - element1 ∈ Set,
 - element2 ∈ Set,
 - element3 ∈ Set,
 - element1 ≠ element2,
 - element1 ≠ element3,
 - element2 ≠ element3,
 - Set = {element1, element2, element3}.
- In general, any disjoint subsets instead of {element}, e.g.,
 $\text{partition}(ITEM, Available, Sold)$

Relations (cont.)

- A relation R between sets S and T can be represented as a set of pairs (s, t) representing those elements of S and T that are related
- A pair is syntactically represented in Event-B as $(s \mapsto t)$ or (s, t) in ascii
- Mathematically, a relation between sets S and T is a member of $\mathbb{P}(S \times T)$, i.e., a subset of $S \times T$
- Reminder: $S \times T$ – all possible pairs from S and T
- Shorthand notation: $S \leftrightarrow T = \mathbb{P}(S \times T)$
- In other words, $R \in S \leftrightarrow T$ is equivalent to
 $R \in \mathbb{P}(S \times T)$ or $R \subseteq S \times T$

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Some set constants and operations

Graphical notation, followed by the equivalent ascii notation:

\emptyset	{}	empty set
$\{e_1, e_2, \dots, e_n\}$	{e ₁ , e ₂ , ..., e _n }	enumerated set
$n_1..n_2$	n _{1..n₂}	interval set between numbers n ₁ and n ₂
$e \in S$	e ∈ S	set membership
$e \notin S$	e ∉ S	“e does not belong to S”, i.e.
$S \subseteq T$	S ⊆ T	set inclusion
$S \not\subseteq T$	S ⊈ T	“S is not included in T”
$S \subsetneq T$	S ⊂ T	set union
$S \cup T$	S ∪ T	set intersection
$S \cap T$	S ∩ T	set difference (subtraction)
$S \setminus T$	S \ T	

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Some other set expressions

- The domain of a relation $R \in S \leftrightarrow T$ is the subset of elements of S that are related to something in T
- Relation domain (denoted as $\text{dom}(R)$) is defined by
 $\{x \mid x \in S \wedge \exists y. (y \in T \wedge (x, y) \in R)\}$
- Example: $\text{dom}(\text{owns_camera}) = \{\text{Jonas, Vaidas, Vaiva, Sandra}\}$
- The range of a relation $R \in S \leftrightarrow T$ is the subset of elements of T that are related to something in S
- Relation range (denoted as $\text{ran}(R)$) is defined by
 $\{y \mid y \in T \wedge \exists x. (x \in S \wedge (x, y) \in R)\}$
- Example: $\text{ran}(\text{owns_camera}) = \{\text{Canon, Nikon, Sony, Pentax}\}$

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Relation domain and range

- The subset of R such that P^*
Set comprehension:
‘the subset of R such that P^* ’
- cartesian product
 $S \times T = \{(x, y) \mid x \in S \wedge y \in T\}$
- cardinality: the number of set elements
- power set: the set of all subsets of S
- all non-empty subsets of S

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More operations on relations (cont.)

- Relational composition R_1, R_2 .
- Composition of relations $R_1 \in S \leftrightarrow T$ and $R_2 \in T \leftrightarrow U$ is relation $\{(s \mapsto u) \mid \exists t. (s \mapsto t) \in R_1 \wedge (t \mapsto u) \in R_2\}$
- Example: Suppose we are given a relation between cameras and their brands $cmodels \in CMODEL \leftrightarrow CAMERA$, for instance,

$cmodels = \{350 \mapsto Canon, 60D \mapsto Canon, D5200 \mapsto Nikon, \dots\}$

Then the previously defined `owns_camera` can be built as a result of a composition of the relations $owns_cmodel \in PERSON \leftrightarrow CMODEL$ and $cmodels \in CMODEL \leftrightarrow CAMERA$, i.e.,

`owns_camera = owns_cmodel ; cmodels`

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More operations on relations (cont.)

- Relational overriding $R_1 \Leftarrow R_2$ (ascii $R_1 <+ R_2$).

Updating the relation R_1 by R_2 :

$R_1 \Leftarrow R_2 = (\text{dom}(R_2) \Leftarrow R_1) \cup R_2$

- Example:

`owns_camera $\Leftarrow \{Jonas \mapsto Nikon\}$`

Two pairs $Jonas \mapsto Canon$ and $Jonas \mapsto Sony$ are removed, one pair $Jonas \mapsto Nikon$ is added

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Basic operations with relations

- Initialising (for $R \in S \leftrightarrow T$):
 $R := \{s_1 \mapsto t_1, s_2 \mapsto t_2, \dots\}$ or $R := S \times \{t_0\}$
 where $s_i \mapsto t_j$ are constructed pairs from $S \leftrightarrow T$
- Adding, merging elements (using set operations):
 $R := R \cup \{s \mapsto t\}$ or $R := R \cup Q$
 where Q is a relation of the same type, i.e., $Q \in S \leftrightarrow T$
- Checking membership or inclusion:
 $s \mapsto t \in R$ or $R \subseteq Q$

- Removing elements (filtering on the relation domain):
 $R := \{s_1, s_2, \dots\} \triangleleft R$ or $R := \{s_1, s_2, \dots\} \triangleleft R$
- Removing elements (filtering on the relation range):
 $R := R \triangleright \{t_1, t_2, \dots\}$ or $R := R \triangleright \{t_1, t_2, \dots\}$

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More operations on relations (cont.)

- Identity relation: $id \in S \leftrightarrow S$

The relation contains pairs $(s \mapsto s)$ for all $s \in S$ (each element is only related to itself)

- Example: suppose we have the relation
`connected $\in CITY \leftrightarrow CITY$`
 containing all the road connections between cities
 (encoding a graph representation of roads between cities)

Then the requirements "Roads can only be between different cities" can be formulated as

`connected $\cap id = \emptyset$`

More operations on relations

- Inverse relation R^{-1} (ascii R^{\sim}).
 Includes all such $(x \mapsto y)$ that $(y \mapsto x) \in R$
- Example: for the relation
`owns_camera = \{Jonas \mapsto Canon, Vaidas \mapsto Nikon, Vaiva \mapsto Sony, Jonas \mapsto Sony, Sandra \mapsto Pentax\}`
 its inverse is
`owns_camera^{-1} = \{Canon \mapsto Jonas, Vaidas \mapsto Vaidas, Sony \mapsto Vaiva, Sony \mapsto Jonas, Pentax \mapsto Sandra\}`
- Relational image $R[S]$. Returns a subset of the relation range related to any element from the given set S
- Example: for the relation `owns_camera` defined above
`owns_camera[\{Jonas, Vaidas\}] = \{Canon, Sony\}`

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Functional (array) assignment

- The notation used to describe machine actions (i.e., assignments in the machine events) allows us to directly assign values to indexed elements of arrays:

$$a(i) := E$$

- This is just syntactic sugar for the following assignment:

$$a := a \Leftrightarrow \{(i \mapsto E)\}$$

- The assignment also works if a is modelled as a partial function.

However, if we want to check/read values from such an array, we have to ensure/prove (by using the event guards and/or machine invariants) that the used index belongs to the function domain, i.e., $i \in \text{dom}(a)$

- $\text{reserved}(r) := \text{FALSE}$
- $n\text{items}(j) := n\text{items}(i) + 1$ **OK!**
only if $i \in \text{dom}(n\text{items})$

Varieties of functions

Suppose we have a function f (from the source X to the target Y). Then it is called

Total function	\rightarrow	\rightarrow	if $\text{dom}(f) = X$, $\text{ran}(f) \subseteq Y$
Partial function	\rightarrowtail	\rightarrowtail	if $\text{dom}(f) \subseteq X$, $\text{ran}(f) \subseteq Y$
Total injection	\rightarrowtail	\rightarrowtail	if $\text{dom}(f) = X$, $\text{ran}(f) \subseteq Y$ and one-to-one function
Partial injection	\rightarrowtail	\rightarrowtail	if $\text{dom}(f) \subseteq X$, $\text{ran}(f) \subseteq Y$ and one-to-one function
Total surjection	\rightarrowtail	\rightarrowtail	if $\text{dom}(f) = X$, $\text{ran}(f) = Y$
Partial surjection	\rightarrowtail	\rightarrowtail	if $\text{dom}(f) \subseteq X$, $\text{ran}(f) = Y$
(Total) Bijection	\rightarrowtail	\rightarrowtail	if $\text{dom}(f) = X$, $\text{ran}(f) = Y$ and one-to-one function

Total and partial functions

- Functions are called *total* if their domain is the whole source set
Syntax: $f \in S \rightarrow T$ (or ascii $f : S \rightarrow T$)
where $\text{dom}(f) = S$ and $\text{ran}(f) \subseteq T$
- Example: the camera model relation is actually a total function
 $\text{cmodels} \in \text{CMODEL} \rightarrow \text{CAMERA}$
(any camera model identifier is uniquely associated with its brand)
- Functions are called *partial* if their domain is a subset of the source set
Syntax: $f \in S \rightarrowtail T$ (or ascii $f : S \rightarrowtail T$)
where $\text{dom}(f) \subseteq S$ and $\text{ran}(f) \subseteq T$
- Example: room reservation relation is actually a partial function
 $\text{reserved} \in \text{ROOM} \rightarrowtail \text{CUSTOMER}$
(each reserved room has the unique customer that served it, however, not all rooms must be reserved)

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Functions

- The machine events) allows us to directly assign values to indexed elements of arrays:
- Functions form a special class of relations that satisfy additional requirement: any element of the source set can be related to no more than 1 element of the target

- Functionality requirement mathematically:

$$\forall x, y, z. (x \mapsto y) \in R \wedge (x \mapsto z) \in R \Rightarrow y = z$$

- Any operation applicable to a relation or a set is also applicable to a function. For example, we can talk about the domain and the range of a function or a function as a set of pairs
- If f is a function, then $f(x)$ is the result of the function f for the argument x

- $a(i) := E$

- This is just syntactic sugar for the following assignment:

$$a := a \Leftrightarrow \{(i \mapsto E)\}$$

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Arrays

- An array is a named, indexed collection of values of a given type.
- The array values can be accessed (read and updated) by using appropriate indexes.
- If we use $1..n$ (for some $n \in \mathbb{N}$) as our index set, then an array (containing elements of type S) can be modelled as a function from $1..n$ to S .
- In fact, any set can be used as the index set for arrays. Therefore, arrays can be usually modelled as total functions from S (index set) to T (the type of array values).

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