

# Machine Learning and Artificial Intelligence

Lab 04 – Principal Component Analysis

30/03/2021

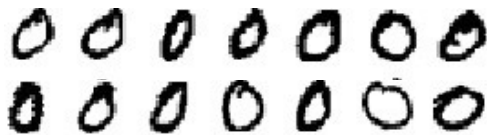
# A typical problem

We want to recognise and classify images of handwritten figures

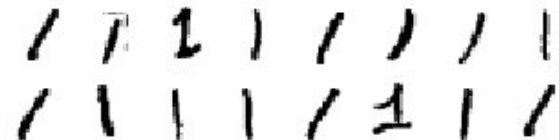
[https://en.wikipedia.org/wiki/MNIST\\_database](https://en.wikipedia.org/wiki/MNIST_database)

For this lesson, let us consider only images of “0” and “1” → the training set size is reduced to about 12000 images

«0»



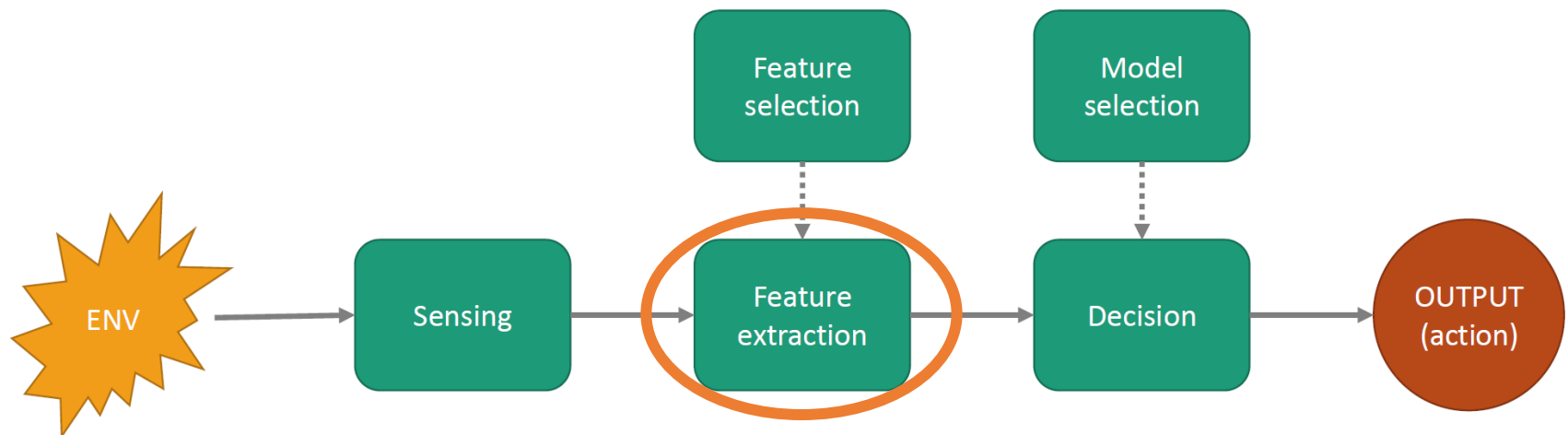
«1»



# Feature Extraction

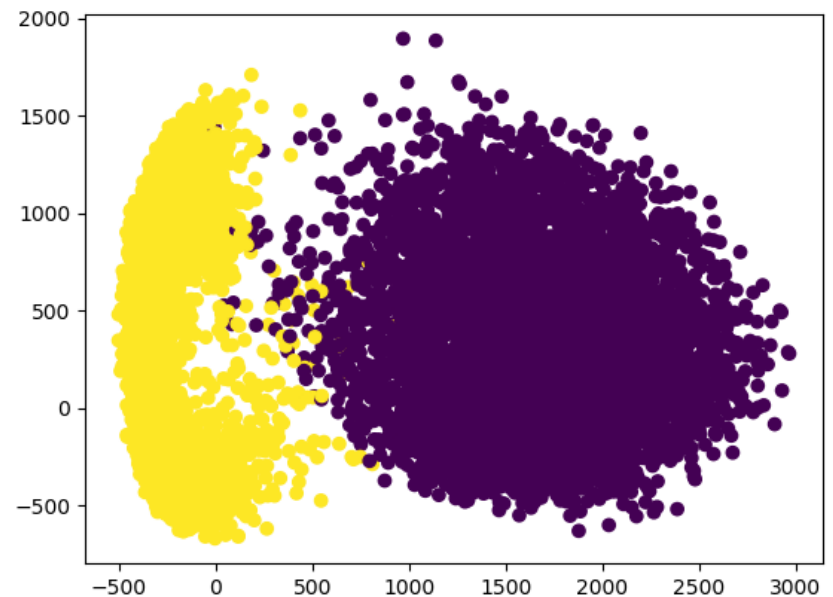
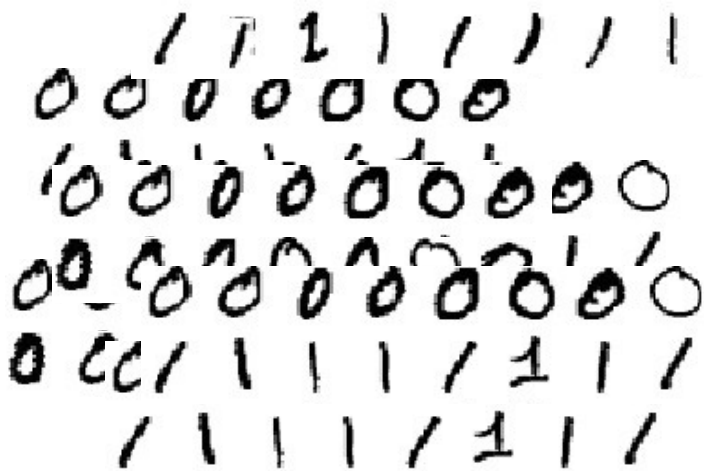
**Input:** each image is a 28x28 matrix.

**Features:** How do we describe the points of the training set? Is it necessary to use all the features?

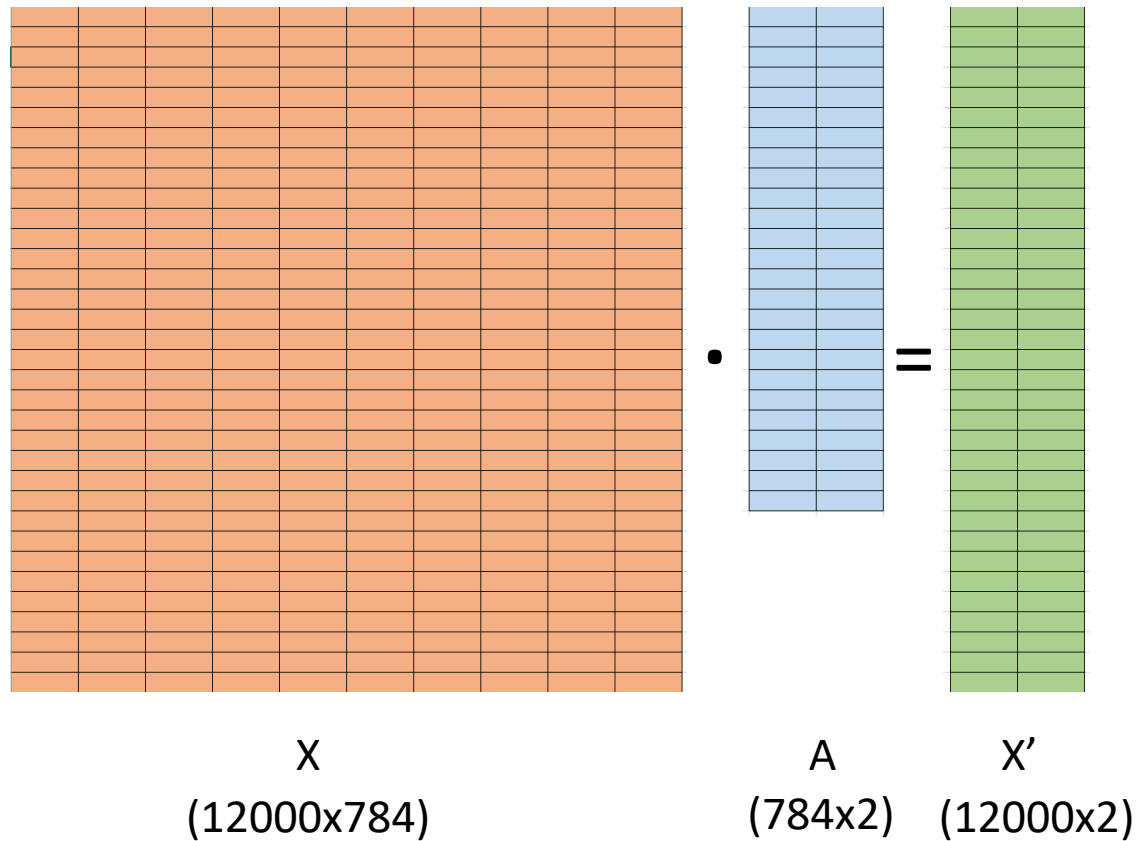


# Idea

We could reduce the dimensionality of the space, while *retaining* as much information as possible.

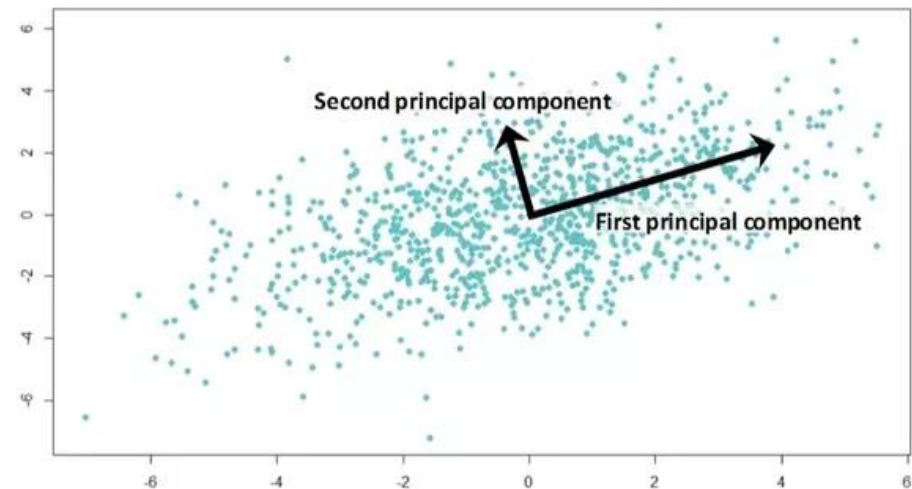


# Dimensionality reduction



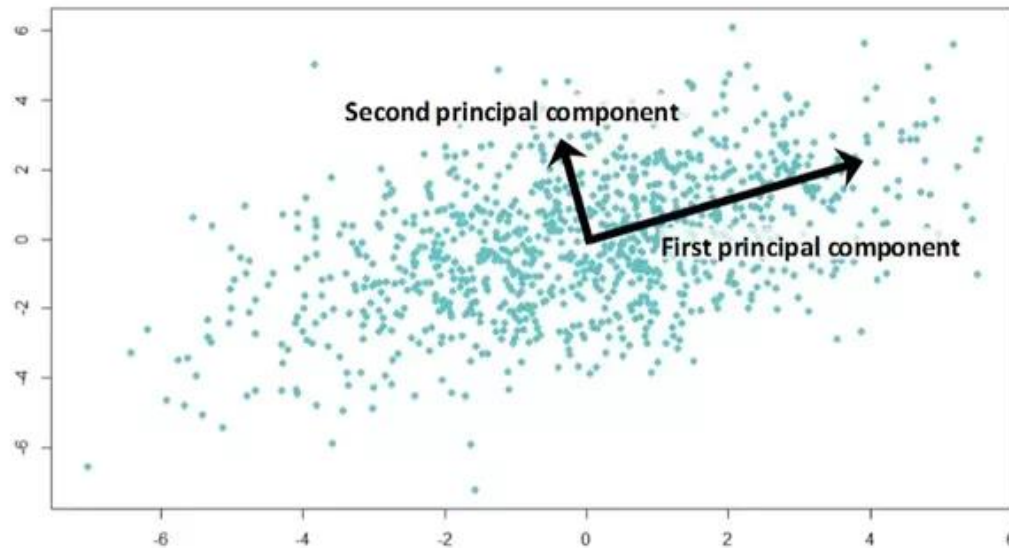
# Principal Component Analysis

- Project the data into a space such that:
  - The first direction (coordinate) is the direction of maximum information.
  - The second direction (coordinate) is the one of second most maximum variance, orthogonal to the first one.
  - And so on....
- *Information = Variance*



# Principal Component Analysis

- The eigenvectors of the covariance matrix encode the principal directions or components.
- The largest eigenvalues occur in the directions of maximum dispersion of the data.



# Principal Component Analysis

An algorithmic overview:

1. Subtract from each  $x^k, k = 1 \dots M$ , the mean  $m = \frac{1}{M} \sum_{k=1}^M x^k$ , obtaining in this way the centered data  $\{x_c^k\}$
2. Calculate the covariance matrix  $C$  from the centered data.
3. Calculate the eigenvalues and eigenvectors of the covariance matrix.

```
>> D,V = np.linalg.eigh(C)  
>> # D vector of eigenvalues, V matrix with eigenvectors in its columns
```

<https://docs.scipy.org/doc/numpy/reference/generated/numpy.linalg.eigh.html>



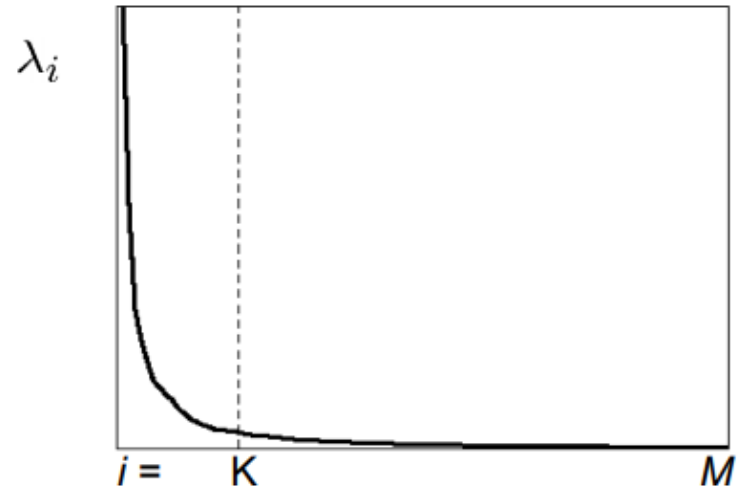
# Principal Component Analysis

An algorithmic overview (2):

4. Sort the eigenvalues from largest to smallest (the eigenvectors corresponding to the largest eigenvalues encode the main directions).
5. The transformation matrix  $T$ , that is used to reduce the data into  $N$  dimensions, is made of the first  $N$  eigenvectors (columns of  $V$ ), corresponding to the  $N$  largest eigenvalues.
6. Compute  $\omega^k$ , i.e., the data projected into the desired dimensions by multiplying  $x_c^k, k = 1 \dots M$  by  $T$ . Each  $\omega^k$  is composed of single components  $a_i^k, i = 1 \dots N$  (the new features).

# How many eigenvectors to use?

- Each eigenvector “carries” a certain variance, which can be seen as the amount of information with respect to the data.
- “Good” data, i.e., tractable, have low dimensions and high variance.

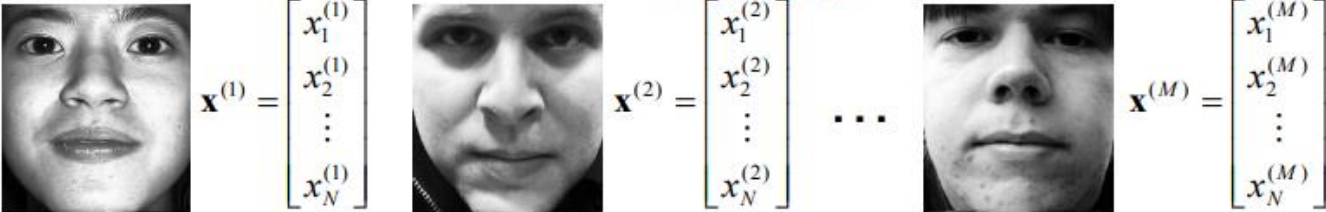


# Exercises

# Practical problem

- Appearance-based recognition of faces.
- Consider each point  $x^k, k = 1 \dots M$  as the image of a face.
- We can use PCA as a recognition tool as well.

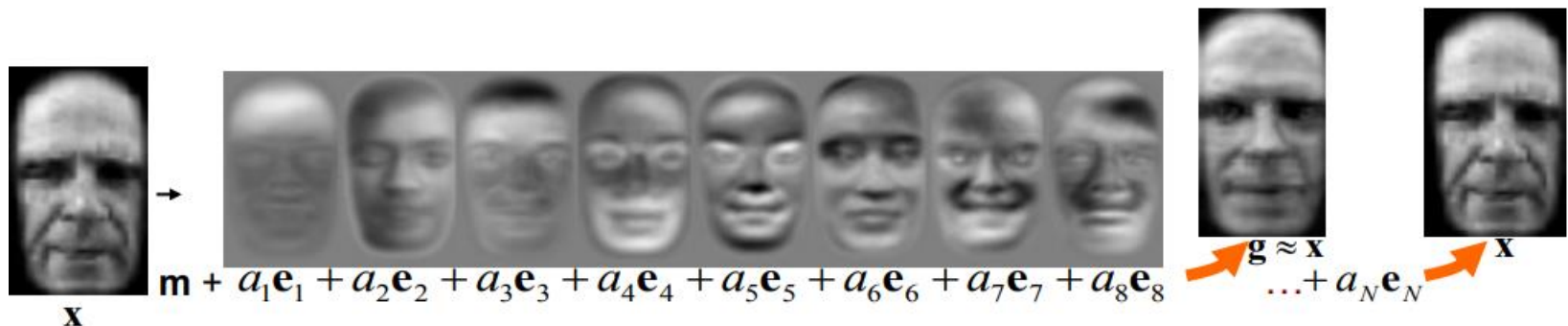
Gray levels


$$\mathbf{x}^{(1)} = \begin{bmatrix} x_1^{(1)} \\ x_2^{(1)} \\ \vdots \\ x_N^{(1)} \end{bmatrix} \quad \mathbf{x}^{(2)} = \begin{bmatrix} x_1^{(2)} \\ x_2^{(2)} \\ \vdots \\ x_N^{(2)} \end{bmatrix} \quad \dots \quad \mathbf{x}^{(M)} = \begin{bmatrix} x_1^{(M)} \\ x_2^{(M)} \\ \vdots \\ x_N^{(M)} \end{bmatrix}$$

Usually,  
 $M \ll N$

# EigenFaces

- The image of a face  $x$  can be projected in the same way in a new space obtaining  $\omega^k = [a_1^k, a_2^k, \dots a_N^k]$ .
- The reconstruction  $g$  is given from the sum of the multiplications of the components  $a_i^k$  of the image  $x$ , with the corresponding eigenfaces  $e_i, i = 1 \dots N$ , used for the projection.



# Recognition with eigenfaces

TRAINING

## 1. Data analysis

- a) Apply PCA, obtaining the eigenfaces  $e_i, i = 1 \dots N \equiv V$  and the components  $a_i^k, i = 1 \dots N$  for each image.
- b) Calculate the threshold

$$\Theta = \max \left\{ \left\| \omega^j - \omega^k \right\|_2 \right\} \text{ for } j, k = 1, \dots, M$$

TESTING

## 2. Given a new image to recognise $x^{te}$

- a) Subtract the mean of the training dataset  $m$ , obtaining  $x_c^{te}$
- b) Project  $x_c^{te}$  into the new space and obtain  $\omega^{te} = [a_1, a_2, \dots, a_N]$
- c) Calculate the set of distances

$$(\epsilon^k) = \left\| \omega^{te} - \omega^k \right\|_2 \text{ for } k = 1, \dots, M$$

# Recognition with eigenfaces

3. Reconstruct the face using eigenfaces and components

$$g = \sum_{i=1}^K a_i e_i \quad \text{or} \quad g = V \omega^{te}$$

TESTING

4. Calculate the distance between the “unknown” starting face and the reconstructed face.

$$\xi = \|g - x_c^{te}\|_2$$

5. If
- $\xi \geq \Theta \rightarrow$  it's not a face
  - $\xi < \Theta$  and  $\epsilon^k \geq \Theta, (k = 1, \dots, M) \rightarrow$  it's a new face
  - $\xi < \Theta$  and  $\min\{\epsilon^k\} < \Theta$  it's a known face, more precisely the  $k_{best} - th$ , where:

$$k_{best} = \operatorname{argmin}_k \{\epsilon^k\}$$

# Exercises