CMSC 25025 Problem 54 3

1. Classification

11d Suppose P(Y:1) = P(Y=0) = = =

XIY=0~N(0,1) A XIY=1~=N1-5,1)+=N65,1) (Assuming iid N)

> XIY=0~N(0,1) A XIY=1~ N(-5, 1) + N(5, 4)

=> XIX =0 NN(0,1) A XIX=1~ N(0, 1)

We show the Bayes Charlier as:

Y(x)= { 1 . { x-no, < (x-40) + 500 (1-1) + 1.2 (100) |

=> TI = P(Y=1) = = , MI = Q=MO, 00=1, 0== 7

So, ue have:

The Bayes risk can be described as P(L')=P(L"(x) + Y) = /P(L'(x)=1, Y=0) + P(L'(x)=0, Y=1) = P(L*[x)=1|Y=0) P(Y=0) + IP(L*[x)=0 | Y=1) IP(Y=1) = P(x fx | Y=0, |x| < J | P(Y=0) + P(x fx | Y=1, x > J | P(Y=1)

= 0.949523

There is no traditional linear classifier that minimites the risk, since the decision boundary Exex: 8. (x) = 8, (x) 3 15 trac for an xex. This rosalts from the fact that XIV=1~ N(0,1) and XIV=0~ N(0,1) both have mean Q. So, our linear classifier

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15 L(x)= 1 for XX.
         So, there is a Bayes Risk of 0.5
          since we will be wrong 50% of the time.
1.2 Suppose that P(Y=1)= P(Y=-1)= = and x1Y=-1~ U(-10,5)
       and XIV=1~4(-5,10)
   a) We define the Bayes Classifier as:
        |\vec{r}(x)| = \left( \frac{1}{|\vec{r}|} \right) \frac{P(x|Y=1)}{P(x|Y=1)} > \frac{1-\pi_1}{\pi_1}
|\vec{r}(x)| = \frac{1}{|\vec{r}|} \frac{P(x|Y=1)}{|\vec{r}|} = \frac{\pi_1}{|\vec{r}|}
    = 1.1(x) = { 1.1 5< x< 100
       Where the decision boundary corresponds to -55x55
     The Bayes Risk corresponds to:
P(Y+ k(x)) = P(Y=1, k(x)=-1) + P(Y=-1, k(k)=1)
                       = P(Y=1, [1x)=-1) + 0
                     = P(1-(x)=-1 | Y=1) P(Y=1)
                       = P(-55x<5 | V=1) P(Y=1) + P( x=5 | Y=1)
                      = \left( \int_{-16}^{6} \frac{1x}{16} \right) \frac{1}{2} = \left( \frac{2}{3} \right) \frac{1}{2} = \frac{1}{3}
    b) h_5(x) = \begin{cases} 1 & \text{if } sgn(x-5) > 0 \\ -1 & \text{if } sgn(x-5) \leq 0 \end{cases}
       This essentially the same classifier
       as part (a), so the Bayes Risk
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C) We wish to compute the Hinge Risk
RD(B)= #(1-YBX)+ = 213
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2. Cognetic Regionson

We define the log-likelihood function to be

P(Bo, P) =
$$\frac{1}{2}$$
 [$y: \{Pot \times_i^T P\} - \{rg(1 + e^{to^T x_i^T P})\}$

Lie has simplification:

 $x: \leftarrow (1, x_i^T)^T$ for $\{Pot \times_i^T P\} - \{rg(1 + e^{to^T x_i^T P})\}$

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Also, recall $\Pi_i(x_i, p^0) = \frac{e^{x_i^T P}}{1 + e^{x_i^T P}}$

Lie hove to the $\{Pot \times_i^T P\} - \{rg(1 + e^{x_i^T P})\}$

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 $P(x_i, p^0t) = P(x_i^T P) = P(x_i^T P) = P(x_i^T P) = P(x_i^T P)$

Lie has from our closs roter that

 $P(x_i, p^0t) = P(x_i^T P) = P(x_i$

This giver us recrutively remoghed least squares.

superable then the maximum conditional log-likelihood dece not exist for the log-regression model. If the data are perfectly separable then No can find a linear decision boundary which portatly classifies the data. since it classifies portatly 109 TT, or 109 1-TT, would not converge So, there is no unique solution to this problem. Also, the IRLS algorithm would divorg 6. Since, if y=1 or y=0, TT=1 or T=1, respulsively, we would see Wil = T (X; B(A)) (1-T (X; B(A))) -> 0. So, the algorithm would not converge. c) We wish to give a derivation of Novton's Algorithm for Ridge Losistic Regression 45ing 1/18/12. Recall the Ridge Lostic Reglession equationi B. B= argmin {- 5 4: (Bo+xTB) -1-5 (1+ exp(Bo+xTB)) + 1 11B113} Using the same notation as before (\$2, \$) TOB and (X!,1) TO X; Again w. want to derive: β*+1 € β* - [3 217)] - 32(β) So, 32(B) == = X; X: - exit X:] + 21B = -XT[Y-H:]+21B And $\frac{32g(\beta)}{3\beta\beta\beta^{T}} = -\frac{8}{8} \times \frac{7}{1} \left(\frac{e^{x^{T}\beta}}{(1+e^{x^{T}\beta})(1+e^{x^{T}\beta})} \right) \times \frac{1}{1} + 2AT = x^{T}Wx + 2AT$

similar to (a)

50, β(+1) = β(κ) - () (β(κ)) -1) (β(κ))

= β(κ) + [χ^TWX ^T 2 / I] ^T [X^T (Y - π₁) - 2 / β^(κ)]

= [x^TWX + 2 / I] ⁻¹ [X^TWX + 2 / I] β^(κ)

+ [x^TWX + 2 / I] ⁻¹ X^T (Y - π₁) · [X^TWX + 2 / I] ^T Z / β^(κ)

β^(κ+1)

= [x^TWX + 2 / I] ⁻¹ X^TW [x β^(κ) + W⁻¹ (Y - π^(κ))]

From this stop we have dorived the North algorithm

For Ridge logistic Regrossion.

The stop is almost exactly the same as

in the derivation of the IRLS algorithm, except

the inverse form includes the ponalty.