

# Microcontroller

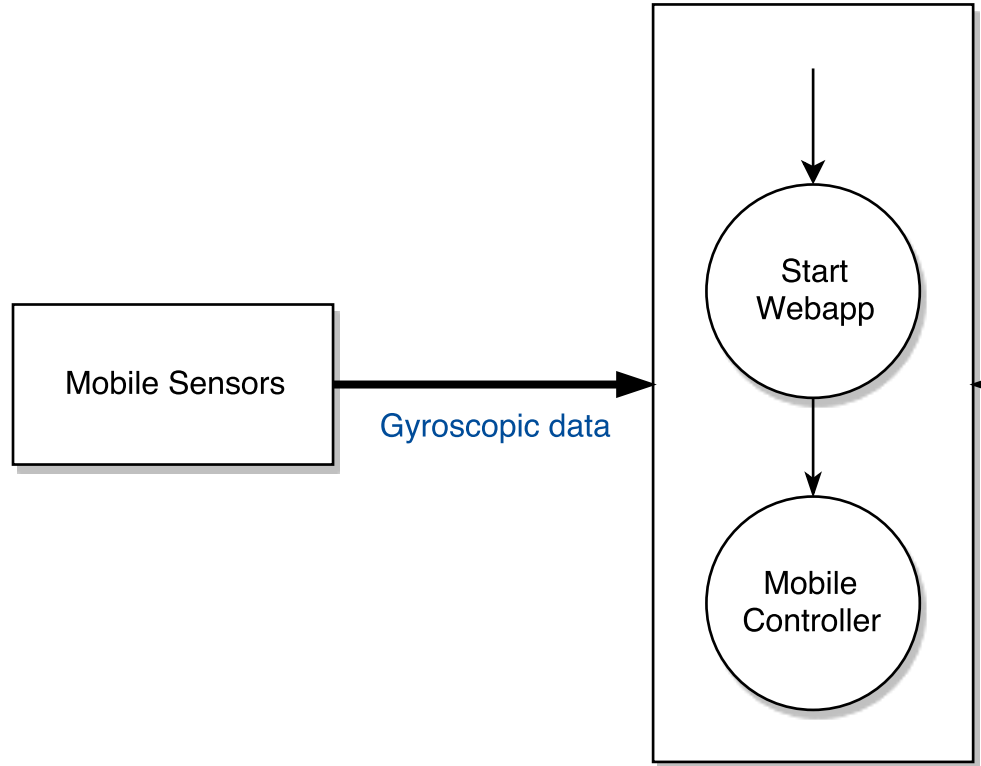
Takes care of all the real time control including PID output and position sensing

# Electro-Mechanical

Abstracted feedback device

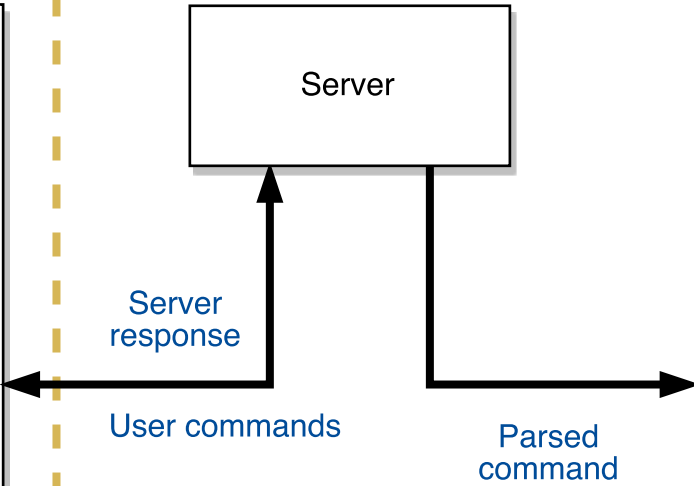
## Mobile Controller

Master control devices connected to server via socket



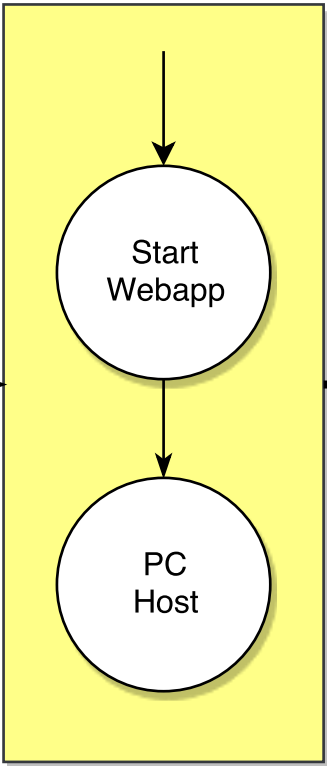
## Node Server

Server that is handling mobile control and Serial interface runs locally on the host PC



## Host PC

Host connected to the socket server that also communicates with microcontroller via Serial



## Shape Vertex Memory

Holds all the desired locations of each vertex of the shape to be drawn

