Design and Analysis of Algorithms

Approximation Algorithms - Part 3

Pan Peng

School of Computer Science and Technology University of Science and Technology of China



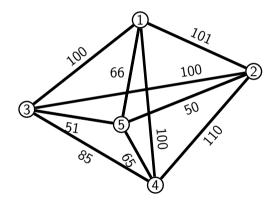
Outline

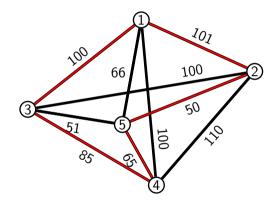
- Approximation algorithms for
 - TSP
 - Max 2-SAT

Travelling salesman problem: a 2-approximation algorithm

Travelling salesman problem (TSP)

- \blacksquare A salesman must travel between n cities
- Each city is connected to other cities with different distances
- The salesman wants to start and finish at a city after having visited each other city exactly once with minimum total distance





Travelling salesman problem (TSP)

Input: a complete weighted undirected graph G=(V,E,w) with non-negative edge weights w(e)'s

Objective: find a cycle that visits each vertex exactly once and has the minimum total weight.

• The total weight (or value) of a cycle is the sum of the weights associated with the edges in the cycle.

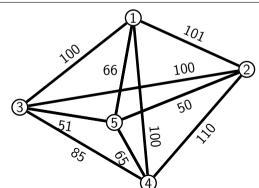
We assume that the edge weights satisfy triangle inequality:

- \blacksquare for any three vertices u,v,x in G , $w(u,v) \leq w(u,x) + w(x,v)$
- TSP with triangle inequality is known as metric TSP
- Mertic TSP is NP-hard.

Tools: Minimum spanning tree (MST)

■ An MST T of a weighted graph G is a subset of the edges that connects all the vertices together, without any cycles and with the minimum possible total edge weight, i.e., $\sum_{e \in T} w(e)$ is minimum.

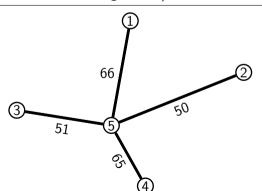
Fact: An MST of a weighted graph G can be found in polynomial time (e.g. by Boruvka's algorithm, Prim's algorithm or Kruskal's algorithm,).



Tools: Minimum spanning tree (MST)

■ An MST T of a weighted graph G is a subset of the edges that connects all the vertices together, without any cycles and with the minimum possible total edge weight, i.e., $\sum_{e \in T} w(e)$ is minimum.

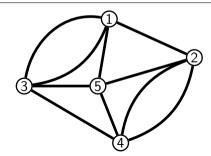
Fact: An MST of a weighted graph G can be found in polynomial time (e.g. by Boruvka's algorithm, Prim's algorithm or Kruskal's algorithm,).



Tools: Eulerian tour (or cycle)

- lacktriangle an Eulerian trail of a (multi-)graph G is a trail that visits every edge exactly once (allowing for revisiting vertices).
- lacksquare an Eulerian tour (or cycle) of a (multi-)graph G is an Eulerian trail that starts and ends on the same vertex.

Fact: A connected graph has an Eulerian tour iff it has no vertices of odd degree; If exist, it can be found in linear time.



TSP: an algorithm

FIND TOUR.

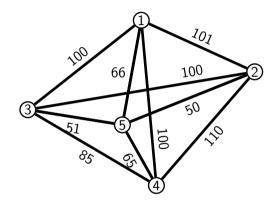
- 1. Compute an MST T
- 2. Construct a graph H in which all edges of T are duplicated
- 3. Find an Eulerian tour C in H (each edge is traversed exactly once).
- 4. Convert to TSP: if a vertex v is visited twice, create a shortcut from the vertex before v in the tour to the one after v.

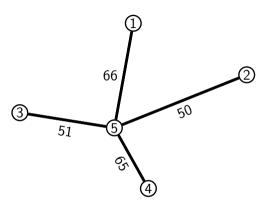
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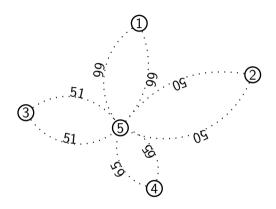
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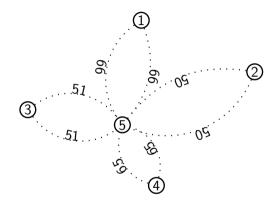
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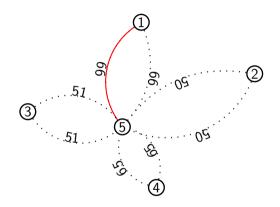
note: the starting vertex in the Eulerian tour can be arbitrary

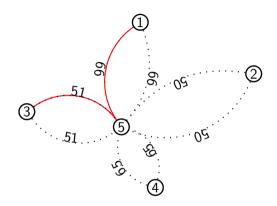


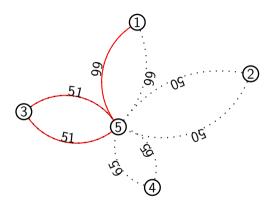


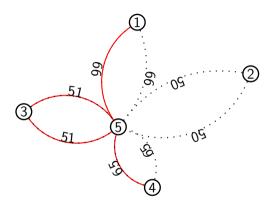


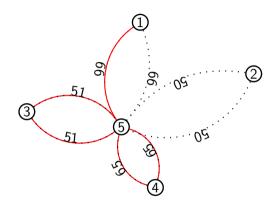


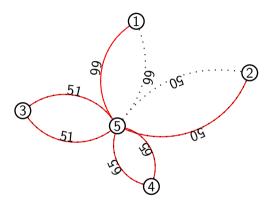


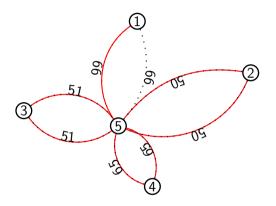


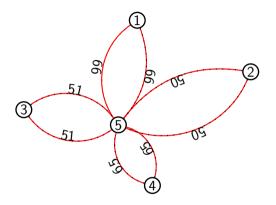




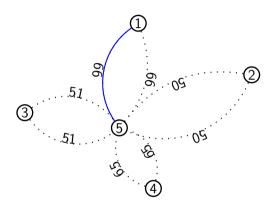




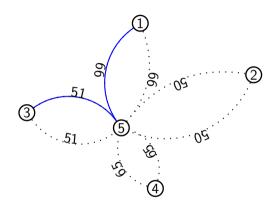




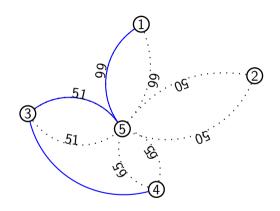
Eulerian tour: $1,5,3,5,4,5,2,5,1\,$



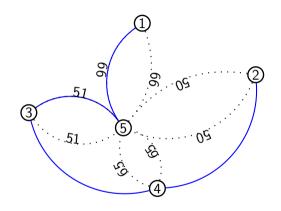
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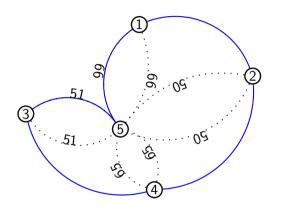
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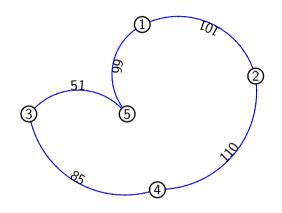
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TSP: analysis of the algorithm

Theorem: FINDTOUR is a 2-approximation algorithm of the Metric TSP problem.

Proof

Runs in polynomial time: by the definition of the algorithm Correctness

- Let C^* be the cost of an optimal tour
- The cost of MST $\leq C^*$ as removing an arbitrary edge from the optimal tour results in a spanning tree, whose weight is at least the cost of MST
- Cost of the Eulerian tour $\leq 2C^*$ as the cost of the Eulerian tour $= 2 \times$ the cost of MST
- Cost of the final output ≤ Cost of the Eulerian tour (by triangle inequality)
- Thus, FINDTOUR is a 2-approximation algorithm

Travelling salesman problem: a 1.5-approximation algorithm

TSP: Christofides-Serdyukov algorithm

FINDTOUR-2

- 1. Compute an MST T
- 2. Compute a minimum cost perfect matching M on the set of odd-degree vertices of MST T; Add M to T to obtain an Eulerian graph H
- 3. Find an Eulerian tour C in H (each edge is traversed exactly once).
- 4. Convert to TSP: go through the vertices in the same order of T, skipping vertices that were already visited. More precisely, if a vertex v is visited twice, create a shortcut from the vertex before v in the tour to the one after v.

Analysis of FINDTOUR-2

Claim

Let $V' \subseteq V$ be a set such that |V'| is even. Let M be a minimum cost perfect matching on V'. Then $cost(M) \leq C^*/2$, where C^* is the cost of an optimal TSP tour.

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■ Consider an optimal TSP tour with cost C^* . Let \mathcal{T}' be the tour on V' by shortcutting vertices in $V \setminus V'$.

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- By triangle inequality,

$$cost(\mathcal{T}') \le C^*$$

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- Note \mathcal{T}' is the union of two perfect matchings on V', each consisting of alternate edges on \mathcal{T}' .
- Since M is a minimum cost perfect matching, we have $2cost(M) \leq cost(T') \leq C^*$.

Analysis FINDTOUR-2

Theorem: FINDTOUR-2 is a 1.5-approximation algorithm of the Metric TSP problem.

Proof

Runs in polynomial time: by the definition of the algorithm Correctness

- Let C^* be the cost of an optimal tour
- The cost of MST $\leq C^*$ (see before)
- Cost of perfect matching $\leq \frac{1}{2}C^*$
- Cost of final output $\leq 1.5C^*$
- Thus, FINDTOUR-2 is a 1.5-approximation algorithm

Further discussion

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- since 1976. Christofides-Serdyukov algorithm remained the method with the best approximation ratio until 2020
- \blacksquare recently, the approximation ratio is improved to 1.5ε , where $\varepsilon > 10^{-36}$ (see a paper published at [STOC 2021])

A (Slightly) Improved Approximation Algorithm for Metric TSP

Anna R. Karlin karlin@cs.washington.edu University of Washington TICA

Nathan Klein nwklein@cs.washington.edu University of Washington USA

Shayan Oveis Gharan shavan@cs.washington.edu University of Washington A STT

ABSTRACT

For some $\epsilon > 10^{-36}$ we give a randomized $3/2 - \epsilon$ approximation algorithm for metric TSP

In contrast, there have been major improvements to this algorithm for a number of special cases of TSP. For example, polynomialtime approximation schemes (PTAS) have been found for Euclidean [3, 36], planar [4, 25, 35], and low-genus metric [17] instances. In ad-

Max 2-SAT

Maximum 2-satisfiability problem (MAX 2-SAT)

Input: Boolean variables x_1, \ldots, x_n and clauses C_1, \ldots, C_m in conjunctive normal form.

■ each clause consists of two distinct literals t_1, t_2 out of x_1, \ldots, x_n and $\neg x_1, \ldots, \neg x_n$ and contains at most one x_i or $\neg x_i$.

Objective: find a 0-1-assignment of the variables such that a maximum number of clauses is satisfied.

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Example instance:

$$(x_1 \vee \neg x_3) \wedge (\neg x_2 \vee x_3) \wedge (x_2 \vee \neg x_4).$$

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• Max 2-SAT is NP-hard

RANDOMASSIGN

- 1. Assign $x_i = 0$ or $x_i = 1$ with probability $\frac{1}{2}$ independently for each i.
- 2. output the values x_i , $1 \le i \le n$.

Theorem: The expected number of satisfied clauses given by RANDOMASSIGN is at least $\frac{3}{4}OPT$.

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- Let Y_i be an indicator random variable for clause C_i .
 - i.e., $Y_i = 1$ if C_i is satisfied; and 0 otherwise

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- $\Pr[Y_i = 0] = \left(\frac{1}{2}\right)^2 = \frac{1}{4}; \Pr[Y_i = 1] = 1 \frac{1}{4} = \frac{3}{4}.$
 - ullet eg., $C_i=x_1\vee \neg x_3$, then $Y_i=0$, i.e., C_i is not satisfied if and only if $x_1=0$ and $x_3=1$.

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$$\Pr[Y_i = 0] = \left(\frac{1}{2}\right)^2 = \frac{1}{4}$$
; $\Pr[Y_i = 1] = 1 - \frac{1}{4} = \frac{3}{4}$.

■ Thus, $\mathrm{E}[Y_i] = 0 \cdot \frac{1}{4} + 1 \cdot \frac{3}{4} = \frac{3}{4}$ and for $Y = \sum_{i=1}^m Y_i$ we have

$$\mathrm{E}[Y] = \mathrm{E}[\sum_{i=1}^m Y_i] = \sum_{i=1}^m \mathrm{E}[Y_i]$$
 (by linearity of expectation)
$$= \sum_{i=1}^m \frac{3}{4} = \frac{3}{4} \cdot m$$

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■ Trivially $OPT \le m$ which ends the proof.