# Design and Analysis of Algorithms Approximation Algorithms – Part 5

#### Pan Peng

School of Computer Science and Technology University of Science and Technology of China

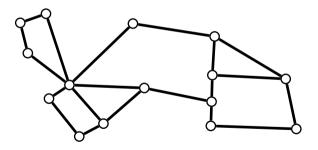


### Outline

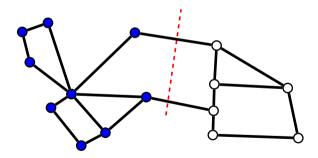
- Approximation algorithms for
  - max cut
  - correlation clustering

### Max cut

Input: an undirected weighted graph G=(V,E,w) such that  $w_{ij}\geq 0$  for edges  $(i,j)\in E$ 

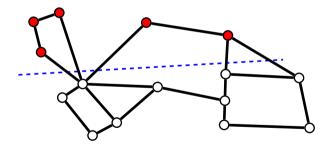


Input: an undirected weighted graph G=(V,E,w) such that  $w_{ij}\geq 0$  for edges  $(i,j)\in E$ 



unweighted graph: a cut of size 2

Input: an undirected weighted graph G=(V,E,w) such that  $w_{ij}\geq 0$  for edges  $(i,j)\in E$ 



unweighted graph: a cut of size 5

Input: an undirected weighted graph G=(V,E,w) such that  $w_{ij}\geq 0$  for edges  $(i,j)\in E$ 

- The max cut problem is **NP**-hard
- There are several algorithms achieving  $\frac{1}{2}$ -approximation, e.g., local search, randomized assignment
- $lue{}$  In the following, we present an SDP based algorithm achieving 0.878-approximation ratio, by Goemans and Williamson 1996.

# A Tool: Semidefinite Programming (SDP)

### Positive semidefinite (PSD) matrix

 $X: n \times n \text{ real symmetric matrix}$ 

### Positive semidefinite (PSD) matrix

 $X: n \times n$  real symmetric matrix

X is called a positive semidefinite (PSD) matrix, denoted  $X \succeq 0$ , if

 $v^T X v \ge 0$  for all  $v \in \mathbb{R}^n$ .

### Positive semidefinite (PSD) matrix

 $X: n \times n$  real symmetric matrix

X is called a positive semidefinite (PSD) matrix, denoted  $X \succeq 0$ , if

 $v^T X v \ge 0$  for all  $v \in \mathbb{R}^n$ .

Recall: the following are equivalent:

- $X \succeq 0$  (i.e., X is PSD)
- all eigenvalues of X are non-negative ( $\lambda \in \mathbb{R}$  is an eigenvalue of X if there is some  $v \in \mathbb{R}^n$  with  $Xv = \lambda v$ )
- $lacksquare X = U^T U$  for some matrix  $U \in \mathbb{R}^{k \times n}$ , where  $k \leq n$

# Semidefinite program (SDP)

SDPs: a class of convex programs; many of them solvable in polynomial time (e.g., by ellipsoid algorithm)

Two equivalent definitions of SDP:

#### Def 1:

$$\max \quad \sum_{i,j} w_{ij} \cdot x_{ij}$$
 s.t. 
$$\sum_{i,j} a_{ij}^r \cdot x_{ij} \ge b_r \quad \forall \, r \in I$$
 
$$X \succ 0$$

where  $w_{ij}, a^r_{ij}, b_r$  are given numbers and  $X = (x_{ij})_{1 \leq i,j \leq n}$  denote the variables. Note that the objective and the first set of constraints are linear in the variables

### Semidefinite program (SDP)

Since X is PSD, we can write  $X=U^TU$  for some  $k\times n$  matrix U. If  $u_1,\ldots,u_n\in\mathbb{R}^k$  denote the columns of U, then  $x_{ij}=\langle u_i,u_j\rangle$ . (here  $\langle u,v\rangle$  denotes the inner product of vectors.) As  $k\leq n$ , we can write the previous SDP as

#### Def 2:

$$\max \sum_{i,j} w_{ij} \cdot \langle u_i, u_j \rangle$$
s.t. 
$$\sum_{i,j} a_{ij}^r \cdot \langle u_i, u_j \rangle \ge b_r \quad \forall r \in I$$

$$u_i \in \mathbb{R}^n \qquad \forall i \in [n]$$

Remark: note that if k < n, then a vector  $u \in \mathbb{R}^k$  can be naturally extended to an n-dimensional vector  $u' \in \mathbb{R}^n$  by adding some zero entries.

Input: an undirected weighted graph G=(V,E,w) such that  $w_{ij}\geq 0$  for edges  $(i,j)\in E$ 

Input: an undirected weighted graph G=(V,E,w) such that  $w_{ij}\geq 0$  for edges  $(i,j)\in E$ 

- use variable  $v_i$  for each  $i \in V$
- ideally, want the solution to only have two directions, either  $v_i = e$  (corresponding to  $i \in S$ ), or  $v_i = -e$  (corresponding to  $i \notin S$ ), where e is a fixed unit vector
- We set up the SDP as

$$\max \sum_{(i,j)\in E} \frac{1}{2} w_{ij} \cdot (1 - \langle v_i, v_j \rangle)$$
s.t.  $\langle v_i, v_i \rangle = 1$   $\forall i \in V$ 

$$v_i \in \mathbb{R}^n \qquad \forall i \in V$$

- lacktriangleright note the optimal solution of SDP has objective  $OPT_{SDP}$  that is at least OPT, the value of the optimal solution of the Max Cut problem.
- we need to round the optimal SDP solution

### SDP based algorithm for Max Cut

#### Algorithm SDP-MAXCUT

- 1. solve the SDP for Max Cut to obtain the optimum solution  $v_i, \forall i \in V$
- 2. choose a uniformly random unit vector  $r \in \mathbb{R}^n$  ("unit" means  $\|r\|_2 = 1$ )
- 3. output  $S := \{i \in V \mid \langle r, v_i \rangle \geq 0\}$

### SDP based algorithm for Max Cut

#### Algorithm SDP-MAXCUT

- 1. solve the SDP for Max Cut to obtain the optimum solution  $v_i, \forall i \in V$
- 2. choose a uniformly random unit vector  $r \in \mathbb{R}^n$  ("unit" means  $\|r\|_2 = 1$ )
- 3. output  $S := \{i \in V \mid \langle r, v_i \rangle \ge 0\}$

#### Remark: Implementation of Step 2:

■ generate n Gaussian random variables  $x_1, x_2, ..., x_n \in \mathcal{N}(0,1)$  (i.e., Gaussian distribution with expectation 0 and variance 1) independently at random, and let

$$r = \frac{1}{\sqrt{x_1^2 + \dots + x_n^2}} (x_1, \dots, x_n)^T$$

### Analysis of SDP-MaxCut

Lemma: For each  $i, j \in V$ ,

$$\Pr[i,j \text{ separated by } S] = \Pr[|\{i,j\} \cap S| = 1] \geq 0.878 \cdot \frac{1 - \langle v_i, v_j \rangle}{2}$$

### Analysis of SDP-MAXCUT

Lemma: For each  $i, j \in V$ ,

$$\Pr[i, j \text{ separated by } S] = \Pr[|\{i, j\} \cap S| = 1] \ge 0.878 \cdot \frac{1 - \langle v_i, v_j \rangle}{2}$$

#### Proof:

■ Since only two vectors  $v_i, v_j$  are involved, consider the 2-dimensional plane H where  $v_i \in H, v_j \in H$ .

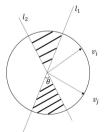


Figure:  $v_i, v_j$  in 2-dimensional plane

lacksquare let  $\bar{r}$  be the projection of r on H

- lacksquare let  $\bar{r}$  be the projection of r on H
- lacksquare note that the normalization  $rac{ar{r}}{\|ar{r}\|}$  is a uniform unit vector in  $\mathbb{R}^d$

- lacksquare let  $\bar{r}$  be the projection of r on H
- lacksquare note that the normalization  $rac{ar{r}}{\|ar{r}\|}$  is a uniform unit vector in  $\mathbb{R}^d$
- lacksquare note that  $\langle r, v_i \rangle = \langle \bar{r}, v_i \rangle$

- $\blacksquare$  let  $\bar{r}$  be the projection of r on H
- $\blacksquare$  note that the normalization  $\frac{\bar{r}}{||\bar{r}||}$  is a uniform unit vector in  $\mathbb{R}^d$
- $\blacksquare$  note that  $\langle r, v_i \rangle = \langle \bar{r}, v_i \rangle$
- Then

 $\Pr[i,j \text{ separated by } S] = \Pr[\langle \overline{r},v_i \rangle \text{ and } \langle \overline{r},v_j \rangle \text{ have opposite sign}]$ 

- $\blacksquare$  let  $\bar{r}$  be the projection of r on H
- lacksquare note that the normalization  $rac{ar{r}}{\|ar{r}\|}$  is a uniform unit vector in  $\mathbb{R}^d$
- lacksquare note that  $\langle r, v_i \rangle = \langle \bar{r}, v_i \rangle$
- Then

$$\Pr[i,j \text{ separated by } S] = \Pr[\langle ar{r}, v_i 
angle \text{ and } \langle ar{r}, v_j 
angle \text{ have opposite sign}]$$

■ If  $\bar{r}$  falls into the shadow area in the above Figure,  $\langle \bar{r}, v_i \rangle$  and  $\langle \bar{r}, v_j \rangle$  have opposite sign.

- $\blacksquare$  let  $\bar{r}$  be the projection of r on H
- lacksquare note that the normalization  $rac{ar{r}}{\|ar{r}\|}$  is a uniform unit vector in  $\mathbb{R}^d$
- note that  $\langle r, v_i \rangle = \langle \bar{r}, v_i \rangle$
- Then

$$\Pr[i,j \text{ separated by } S] = \Pr[\langle \bar{r},v_i \rangle \text{ and } \langle \bar{r},v_j \rangle \text{ have opposite sign}]$$

- If  $\bar{r}$  falls into the shadow area in the above Figure,  $\langle \bar{r}, v_i \rangle$  and  $\langle \bar{r}, v_j \rangle$  have opposite sign.
- Thus

$$\begin{split} \Pr[i,j \text{ separated by } S] &= \frac{2\theta}{2\pi} = \frac{1}{\pi} \arccos\langle v_i,v_j\rangle \\ &= \frac{1 - \langle v_i,v_j\rangle}{\pi} \cdot \frac{\arccos\langle v_i,v_j\rangle}{1 - \langle v_i,v_j\rangle} \\ &\geq \frac{1 - \langle v_i,v_j\rangle}{2} \cdot \frac{2}{\pi} \left( \min_{x \in [-1,1]} \frac{\arccos x}{1-x} \right) \\ &\geq 0.878 \cdot \frac{1 - \langle v_i,v_j\rangle}{2} \end{split}$$

### Performance guarantee of SDP-MAXCUT

By taking the weighted sum over all pairs  $i, j \in V$  and linearity of expectation, and noting that the algorithm SDP-MAXCUT runs in polynomial time, it follows that:

Theorem: The expected value of the solution S of SDP-MaxCut is at least  $0.878 \cdot OPT_{SDP} \geq 0.878 \cdot OPT$ . Thus, SDP-MaxCut is a 0.878-approximation algorithm for the Max Cut problem.

Approximation in expectation:  $E[\frac{\text{result}}{OPT}] \leq \alpha$ .

• We have a bound on the expected approximation factor.

```
Approximation in expectation: E[\frac{\text{result}}{OPT}] \leq \alpha.
```

- We have a bound on the expected approximation factor.
- The algorithm may return worse results *most of the time*.

```
Approximation in expectation: E[\frac{\text{result}}{\text{OPT}}] \leq \alpha.
```

- We have a bound on the expected approximation factor.
- The algorithm may return worse results *most of the time*.
- Example: the above algorithm.

### Approximation in expectation: $E[\frac{\text{result}}{\text{OPT}}] \leq \alpha$ .

- We have a bound on the expected approximation factor.
- The algorithm may return worse results *most of the time*.
- Example: the above algorithm.
- Remark: the above algorithm can be *derandomized*; deterministic algorithm with 0.878-approximation.

### Approximation in expectation: $E[\frac{\text{result}}{\text{OPT}}] \leq \alpha$ .

- We have a bound on the expected approximation factor.
- The algorithm may return worse results *most of the time*.
- Example: the above algorithm.
- Remark: the above algorithm can be *derandomized*; deterministic algorithm with 0.878-approximation.

### Approximation in expectation: $E[\frac{\text{result}}{\text{OPT}}] \leq \alpha$ .

- We have a bound on the expected approximation factor.
- The algorithm may return worse results *most of the time*.
- Example: the above algorithm.
- Remark: the above algorithm can be *derandomized*; deterministic algorithm with 0.878-approximation.

# Approximation with high probability: $\Pr[\frac{\text{result}}{\text{OPT}} \leq \alpha] > 1 - \varepsilon$

■ The approximation factor is bounded with high probability.

### Approximation in expectation: $E[\frac{\text{result}}{OPT}] \leq \alpha$ .

- We have a bound on the expected approximation factor.
- The algorithm may return worse results *most of the time*.
- Example: the above algorithm.
- Remark: the above algorithm can be *derandomized*; deterministic algorithm with 0.878-approximation.

# Approximation with high probability: $\Pr[\frac{\text{result}}{\text{OPT}} \leq \alpha] > 1 - \varepsilon$

- The approximation factor is bounded with high probability.
- The algorithm may return worse results *occasionally*.

### Approximation in expectation: $E[\frac{\text{result}}{OPT}] \leq \alpha$ .

- We have a bound on the expected approximation factor.
- The algorithm may return worse results *most of the time*.
- Example: the above algorithm.
- Remark: the above algorithm can be *derandomized*; deterministic algorithm with 0.878-approximation.

# Approximation with high probability: $\Pr[\frac{\text{result}}{\text{OPT}} \leq \alpha] > 1 - \varepsilon$

- The approximation factor is bounded with high probability.
- The algorithm may return worse results *occasionally*.

## Randomized Approximation Algorithms

## Approximation in expectation: $E[\frac{\text{result}}{\text{OPT}}] \leq \alpha$ .

- We have a bound on the expected approximation factor.
- The algorithm may return worse results *most of the time*.
- Example: the above algorithm.
- Remark: the above algorithm can be *derandomized*; deterministic algorithm with 0.878-approximation.

# Approximation with high probability: $\Pr[\frac{\text{result}}{\text{OPT}} \leq \alpha] > 1 - \varepsilon$

- The approximation factor is bounded with high probability.
- The algorithm may return worse results *occasionally*.

## Approximation in expected running time: $\frac{\text{result}}{\text{OPT}} \leq \alpha$

■ The approximation factor satisfies the bound at all times.

## Randomized Approximation Algorithms

## Approximation in expectation: $E[\frac{\text{result}}{\text{OPT}}] \leq \alpha$ .

- We have a bound on the expected approximation factor.
- The algorithm may return worse results *most of the time*.
- Example: the above algorithm.
- Remark: the above algorithm can be *derandomized*; deterministic algorithm with 0.878-approximation.

# Approximation with high probability: $\Pr[\frac{\text{result}}{\text{OPT}} \leq \alpha] > 1 - \varepsilon$

- The approximation factor is bounded with high probability.
- The algorithm may return worse results *occasionally*.

## Approximation in expected running time: $\frac{\text{result}}{\text{OPT}} \leq \alpha$

- The approximation factor satisfies the bound at all times.
- Occasionally the running time might be bad.

# Correlation clustering - version 1

Input: Given a complete graph G = (V, E) on n vertices. Each edge is labeled + or -.

Goal: find a partition of vertices so that the agreement is maximized.

• for a partition  $\mathcal{P} = \{P_1, \dots, P_t\}$  of V, the agreement of  $\mathcal{P}$  is the number of positive edges within a cluster (i.e. some part  $P_i$ ) plus the number of negative edges between clusters

Input: Given a complete graph G = (V, E) on n vertices. Each edge is labeled + or -.

Goal: find a partition of vertices so that the agreement is maximized.

• for a partition  $\mathcal{P} = \{P_1, \dots, P_t\}$  of V, the agreement of  $\mathcal{P}$  is the number of positive edges within a cluster (i.e. some part  $P_i$ ) plus the number of negative edges between clusters

Remark: a clustering problem without any assumption on the number of clusters

Input: Given a complete graph G = (V, E) on n vertices. Each edge is labeled + or -.

Goal: find a partition of vertices so that the agreement is maximized.

• for a partition  $\mathcal{P} = \{P_1, \dots, P_t\}$  of V, the agreement of  $\mathcal{P}$  is the number of positive edges within a cluster (i.e. some part  $P_i$ ) plus the number of negative edges between clusters

Remark: a clustering problem without any assumption on the number of clusters

#### Intuition

Partition a set of objects such that "similar" objects are grouped together and "dissimilar" objects are set apart.

For an edge  $(i,j) \in E$ , let  $\operatorname{sgn}(ij) = 1$  if (i,j) is labeled +, and  $\operatorname{sgn}(ij) = -1$  otherwise.

For an edge  $(i,j) \in E$ , let  $\mathrm{sgn}(ij) = 1$  if (i,j) is labeled +, and  $\mathrm{sgn}(ij) = -1$  otherwise. For  $1 \le k \le n$ , let  $e_k \in \{0,1\}^n$  be the k-th unit vector, i.e.,  $e_k(t) = 1$  if t = k and 0 otherwise.

For an edge  $(i,j) \in E$ , let  $\mathrm{sgn}(ij) = 1$  if (i,j) is labeled +, and  $\mathrm{sgn}(ij) = -1$  otherwise. For  $1 \le k \le n$ , let  $e_k \in \{0,1\}^n$  be the k-th unit vector, i.e.,  $e_k(t) = 1$  if t = k and 0 otherwise.

$$\max \sum_{i < j: \operatorname{sgn}(ij) = 1} x_i^T x_j + \sum_{i < j: \operatorname{sgn}(ij) = -1} (1 - x_i^T x_j)$$
s.t.  $x_i \in \{e_1, \dots, e_n\} \quad \forall i \in V$ 

(Intuition: in the optimal solution, vertices v in the k-th cluster are assigned vector  $e_k$ )

For an edge  $(i,j) \in E$ , let  $\mathrm{sgn}(ij) = 1$  if (i,j) is labeled +, and  $\mathrm{sgn}(ij) = -1$  otherwise. For  $1 \le k \le n$ , let  $e_k \in \{0,1\}^n$  be the k-th unit vector, i.e.,  $e_k(t) = 1$  if t = k and 0 otherwise.

$$\max \sum_{i < j: \operatorname{sgn}(ij) = 1} x_i^T x_j + \sum_{i < j: \operatorname{sgn}(ij) = -1} (1 - x_i^T x_j)$$
s.t.  $x_i \in \{e_1, \dots, e_n\} \quad \forall i \in V$ 

(Intuition: in the optimal solution, vertices v in the k-th cluster are assigned vector  $e_k$ ) SDP relaxation of the correlation clustering problem

$$\max \sum_{i < j: \operatorname{sgn}(ij) = 1} x_i^T x_j + \sum_{i < j: \operatorname{sgn}(ij) = -1} (1 - x_i^T x_j)$$
s.t. 
$$x_i^T x_i = 1 \quad \forall i \in V$$

$$x_i^T x_j \ge 0 \quad \forall i, j \in V$$

$$x_i \in \mathbb{R}^n \quad \forall i \in V$$

### Rounding of the SDP

#### Main ideas:

- Follow the Max-Cut approach, and choose two hyperplanes
- We always obtain at most four clusters

## Rounding of the SDP

#### Main ideas:

- Follow the Max-Cut approach, and choose two hyperplanes
- We always obtain at most four clusters

#### Algorithm SDP-CC

- 1. solve the SDP for the correlation clustering problem to obtain the optimum solution  $v_i, \forall i \in V$
- 2. choose two uniformly random unit vectors  $r_1, r_2 \in \mathbb{R}^n$
- 3. output
  - $R_1 := \{i \in V \mid \langle r_1, v_i \rangle \ge 0 \text{ and } \langle r_2, v_i \rangle \ge 0\}$
  - $R_2 := \{i \in V \mid \langle r_1, v_i \rangle \ge 0 \text{ and } \langle r_2, v_i \rangle < 0\}$
  - $R_3 := \{i \in V \mid \langle r_1, v_i \rangle < 0 \text{ and } \langle r_2, v_i \rangle \ge 0\}$
  - $R_4 := \{i \in V \mid \langle r_1, v_i \rangle < 0 \text{ and } \langle r_2, v_i \rangle < 0\}$

• for  $(i,j) \in E$ , let  $q_{ij}$  be the probability that  $v_i, v_j$  are on the same side of both hyperplanes, and the expected cost of our rounding algorithm is

$$\sum_{i < j: \text{sgn}(ij) = 1} q_{ij} + \sum_{i < j: \text{sgn}(ij) = -1} (1 - q_{ij})$$

• for  $(i,j) \in E$ , let  $q_{ij}$  be the probability that  $v_i, v_j$  are on the same side of both hyperplanes, and the expected cost of our rounding algorithm is

$$\sum_{i < j: \operatorname{sgn}(ij) = 1} q_{ij} + \sum_{i < j: \operatorname{sgn}(ij) = -1} (1 - q_{ij})$$

 $\blacksquare$  moreover,  $q_{ij} = (1 - \frac{\arccos v_i^T v_j}{\pi})^2$ 

• for  $(i,j) \in E$ , let  $q_{ij}$  be the probability that  $v_i, v_j$  are on the same side of both hyperplanes, and the expected cost of our rounding algorithm is

$$\sum_{i < j: \text{sgn}(ij) = 1} q_{ij} + \sum_{i < j: \text{sgn}(ij) = -1} (1 - q_{ij})$$

- $\blacksquare$  moreover,  $q_{ij} = (1 \frac{\arccos v_i^T v_j}{\pi})^2$
- if we let

$$\alpha_1 = \min_{0 \le z \le 1} \left(1 - \frac{\arccos z}{\pi}\right)^2 / z, \ \alpha_2 = \min_{0 \le z \le 1} \left(1 - \left(1 - \frac{\arccos z}{\pi}\right)^2\right) / (1 - z),$$

then  $\alpha^* = \min\{\alpha_1, \alpha_2\} \ge 0.75$  (see the book "The Design of Approximation Algorithms Chapter 6")

• for  $(i,j) \in E$ , let  $q_{ij}$  be the probability that  $v_i, v_j$  are on the same side of both hyperplanes, and the expected cost of our rounding algorithm is

$$\sum_{i < j: \text{sgn}(ij) = 1} q_{ij} + \sum_{i < j: \text{sgn}(ij) = -1} (1 - q_{ij})$$

- $\blacksquare$  moreover,  $q_{ij} = (1 \frac{\arccos v_i^T v_j}{\pi})^2$
- if we let

$$\alpha_1 = \min_{0 \le z \le 1} \left(1 - \frac{\arccos z}{\pi}\right)^2 / z, \ \alpha_2 = \min_{0 \le z \le 1} \left(1 - \left(1 - \frac{\arccos z}{\pi}\right)^2\right) / (1 - z),$$

then  $\alpha^* = \min\{\alpha_1, \alpha_2\} \ge 0.75$  (see the book "The Design of Approximation Algorithms Chapter 6")

■ Then the expected cost is at least

$$\alpha^* \cdot \left(\sum_{i < j: \operatorname{sgn}(ij) = 1} v_i^T v_j + \sum_{i < j: \operatorname{sgn}(ij) = -1} (1 - v_i^T v_j)\right) \ge \alpha^* \cdot \operatorname{OPT}$$

Theorem: The algorithm  $\overline{SDP\text{-}CC}$  is a 0.75-approximation for the agreement maximization version of the correlation clustering problem.

Theorem: The algorithm  $\overline{SDP\text{-}CC}$  is a 0.75-approximation for the agreement maximization version of the correlation clustering problem.

Remark: There exists a  $(1-\varepsilon)$ -approximation algorithm for the above problem, for any constant  $\varepsilon>0$ .

# Correlation clustering - version 2

Input: Given a complete graph G = (V, E) on n vertices. Each edge is labeled + or -.

Goal: find a partition of vertices so that the disagreement is minimized.

• for a partition  $\mathcal{P} = \{P_1, \dots, P_t\}$  of V, the disagreement of  $\mathcal{P}$  is the number of negative edges within a cluster plus the number of positive edges between clusters

Input: Given a complete graph G = (V, E) on n vertices. Each edge is labeled + or -.

Goal: find a partition of vertices so that the disagreement is minimized.

• for a partition  $\mathcal{P} = \{P_1, \dots, P_t\}$  of V, the disagreement of  $\mathcal{P}$  is the number of negative edges within a cluster plus the number of positive edges between clusters

#### Remark:

- The best known approximation algorithm for the above problem achieves approximation ratio  $1.994 + \varepsilon$  for any constant  $\varepsilon > 0$ .
- Here we present a simple greedy algorithm.

### A greed algorithm

Let G = (V, E) be the input graph such that each edge is labeled + or -.

## A greed algorithm

Let G = (V, E) be the input graph such that each edge is labeled + or -.

#### Algorithm PIVOT-CC

- 1.  $E^+ \leftarrow$  the set of all + edges
- 2. while  $V \neq \emptyset$  do
  - 2.1  $i \leftarrow$  uniformly random node from V
  - 2.2 create cluster  $C_i = \{i\} \cup E^+(i)$  ( $E^+(i)$ : set of + neighbors of i)
  - 2.3  $V \leftarrow V \setminus C_i$
  - 2.4  $E^+ \leftarrow E^+ \cap (V \times V)$
- 3. output all the clusters  $C_i$ 's

### Performance guarantee of PIVOT-CC

Theorem: Algorithm PIVOT-CC is a randomized expected 3-approximation algorithm for the disagreement minimization version of the correlation clustering problem.

### Performance guarantee of PIVOT-CC

Theorem: Algorithm PIVOT-CC is a randomized expected 3-approximation algorithm for the disagreement minimization version of the correlation clustering problem.

Note: for the proof, see the paper "Aggregating inconsistent information: ranking and clustering", Ailon, Charikar and Newman, STOC 05