

1. Locality-Sensitive Hashing (LSH)	3. Mutual Information Loss and Generalized JS Divergence	5. LSH Schemes for f -Divergences
<p>\mathcal{M}: the universal set of items (the database), endowed with a distance function D.</p> <p>Intuition of LSH: For any p and q in \mathcal{M},</p> <ul style="list-style-type: none"> ► If they are close, they are more likely to have the same hash value; ► If they are far apart, they are more likely to have different hash values. <p>(r_1, r_2, p_1, p_2)-sensitive LSH: Let $\mathcal{H} = \{h : \mathcal{M} \rightarrow U\}$ be a family of hash functions, where U is the set of possible hash values. Assume that there is a distribution $h \sim \mathcal{H}$ over the family of functions. This family \mathcal{H} is called (r_1, r_2, p_1, p_2)-sensitive ($r_1 < r_2$ and $p_1 > p_2$) for D, if for $\forall p, q \in \mathcal{M}$ the following statements hold:</p> <ul style="list-style-type: none"> ► If $D(p, q) \leq r_1$, then $\Pr_{h \sim \mathcal{H}}[h(p) = h(q)] \geq p_1$; ► If $D(p, q) > r_2$, then $\Pr_{h \sim \mathcal{H}}[h(p) = h(q)] \leq p_2$. 	<p>Suppose that two random variables X and C obeys a joint distribution $p(X, C)$. This joint distribution can model a dataset where X denotes the feature value of a data point and C denotes its label [2]. Let \mathcal{X} and \mathcal{C} denote the support of X and C (i.e., the universal set of all possible feature values and labels), respectively. Consider clustering two feature values into a new combined value. This operation can be represented by the following map</p> $\pi_{x,y} : \mathcal{X} \rightarrow \mathcal{X} \setminus \{x, y\} \cup \{z\} \quad \text{such that} \quad \pi_{x,y}(t) = \begin{cases} t, & t \in \mathcal{X} \setminus \{x, y\} \\ z, & t = x, y \end{cases},$ <p>where x and y are the two feature values to be clustered and $z \notin \mathcal{X}$ is the new combined feature value. To make the dataset after applying the map $\pi_{x,y}$ preserve as much information of the original dataset as possible, one has to select two feature values x and y such that the mutual information loss incurred by the clustering operation $\text{mil}(x, y) = I(X; C) - I(\pi_{x,y}(X); C)$ is minimized, where $I(\cdot; \cdot)$ is the mutual information between two random variables [4]. Note that the <i>mutual information loss (MIL) divergence</i> $\text{mil} : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is symmetric in both arguments and always non-negative due to the data processing inequality [4]. Next, we motivate the generalized Jensen-Shannon divergence. If we let P and Q be the conditional distribution of C given $X = x$ and $X = y$, respectively, such that $P(c) = p(C = c X = x)$ and $Q(c) = p(C = c X = y)$, the mutual information loss can be re-written as</p> $\lambda D_{\text{KL}}(P \parallel M_\lambda) + (1 - \lambda) D_{\text{KL}}(Q \parallel M_\lambda), \quad (3)$ <p>where $\lambda = \frac{p(x)}{p(x) + p(y)}$ and the distribution $M_\lambda = \lambda P + (1 - \lambda)Q$. Note that (3) is a generalized version of (2). Therefore, we define the <i>generalized Jensen-Shannon (GJS) divergence</i> between P and Q [10, 1, 8] by $D_{\text{GJS}}^\lambda(P \parallel Q) = \lambda D_{\text{KL}}(P \parallel M_\lambda) + (1 - \lambda) D_{\text{KL}}(Q \parallel M_\lambda)$, where $\lambda \in [0, 1]$ and $M_\lambda = \lambda P + (1 - \lambda)Q$. We immediately have $D_{\text{GJS}}^{1/2}(P \parallel Q) = D_{\text{JS}}(P \parallel Q)$, which indicates that the JS divergence is indeed a special case of the GJS divergence when $\lambda = 1/2$. The GJS divergence has another equivalent definition $D_{\text{GJS}}^\lambda(P \parallel Q) = H(M_\lambda) - \lambda H(P) - (1 - \lambda)H(Q)$, where $H(\cdot)$ denotes the Shannon entropy [4]. In contrast to the MIL divergence, the GJS $D_{\text{GJS}}^\lambda(\cdot \parallel \cdot)$ is not symmetric in general as the weight $\lambda \in [0, 1]$ is fixed and not necessarily equal to $1/2$.</p>	<p>We build LSH schemes for f-divergences based on approximation via another f-divergence if the latter admits an LSH family. If D_f and D_g are two divergences associated with convex functions f and g as defined by (1), the approximation ratio of $D_f(P \parallel Q)$ to $D_g(P \parallel Q)$ is determined by the ratio of the functions f and g, as well as the ratio of P to Q (to be precise, $\inf_{i \in \Omega} \frac{P(i)}{Q(i)}$) [12].</p> <p>Proposition 1[Proof in ??] Let $\beta_0 \in (0, 1)$, $L, U > 0$ and let f and g be two convex functions $(0, \infty) \rightarrow \mathbb{R}$ that obey $f(1) = 0$, $g(1) = 0$, and $f(t), g(t) > 0$ for every $t \neq 1$. Let \mathcal{P} be a set of probability measures on a finite sample space Ω such that for every $i \in \Omega$ and $P, Q \in \mathcal{P}$, $0 < \beta_0 \leq \frac{P(i)}{Q(i)} \leq \beta_0^{-1}$. Assume that for every $\beta \in (\beta_0, 1) \cup (1, \beta_0^{-1})$, it holds that $0 < L \leq \frac{f(\beta)}{g(\beta)} \leq U < \infty$. If \mathcal{H} forms an (r_1, r_2, p_1, p_2)-sensitive family for g-divergence on \mathcal{P}, then it is also an (Lr_1, Ur_2, p_1, p_2)-sensitive family for f-divergence on \mathcal{P}.</p> <p>?? provides a general strategy of constructing LSH families for f-divergences. The performance of such LSH families depends on the tightness of the approximation. In ?? and ??, as instances of the general strategy, we derive concrete results for the generalized Jensen-Shannon divergence and triangular discrimination, respectively.</p> <p>Generalized Jensen-Shannon Divergence First, ?? shows that the GJS divergence is indeed an instance of f-divergence. lemma Define $m_\lambda(t) = \lambda t \ln t - (\lambda t + 1 - \lambda) \ln(\lambda t + 1 - \lambda)$. For any $\lambda \in [0, 1]$, $m_\lambda(t)$ is convex on $(0, \infty)$ and $m_\lambda(1) = 0$. Furthermore, m_λ-divergence yields the GJS divergence with parameter λ. We choose to approximate it via the squared Hellinger distance, which plays a central role in the construction of the hash family with desired properties. The approximation guarantee is established in theorem 1. We show that the ratio of $D_{\text{GJS}}^\lambda(P \parallel Q)$ to $H^2(P, Q)$ is upper bounded by the function $U(\lambda)$ and lower bounded by the function $L(\lambda)$. Furthermore, theorem 1 shows that $U(\lambda) \leq 1$, which implies that the squared Hellinger distance is an upper bound of the GJS divergence.</p>
2. f -Divergence	4. Positive Definite Kernel and Kreĭn Kernel	Theorem (Proof in ??)
<ul style="list-style-type: none"> ► f-divergence from P to Q [5] is defined by is defined by $D_f(P \parallel Q) = \sum_{i \in \Omega} Q(i) f\left(\frac{P(i)}{Q(i)}\right), \quad (1)$ <p>where $f : (0, \infty) \rightarrow \mathbb{R}$ be convex s.t. $f(1) = 0$. It is not symmetric in general: $D_f(P \parallel Q) \neq D_f(Q \parallel P)$.</p> <ul style="list-style-type: none"> ► KL-Divergence $D_{\text{KL}}(P \parallel Q)$ is the f_{KL}-divergence [4], where $f_{\text{KL}}(t) = t \ln t + (1 - t)$. We have $D_{\text{KL}}(P \parallel Q) = \sum_{i \in \Omega} P(i) \ln \frac{P(i)}{Q(i)}$. ► Squared Hellinger Distance $H^2(P, Q)$ is the hel-divergence [6], where $\text{hel}(t) = \frac{1}{2}(\sqrt{t} - 1)^2$. We have $H^2(P, Q) = \frac{1}{2} \int_\Omega (\sqrt{dP} - \sqrt{dQ})^2$. ► Triangular Discrimination: If $\delta(t) = \frac{(t-1)^2}{t+1}$, the δ-divergence is the <i>triangular discrimination</i> (also known as Vincze-Le Cam distance) [9, 14]. If the sample space is finite, the triangular discrimination between P and Q is given by $\Delta(P \parallel Q) = \sum_{i \in \Omega} \frac{(P(i) - Q(i))^2}{P(i) + Q(i)}$. ► Jensen-Shannon (JS) Divergence is a symmetrized version of the KL divergence. If $P \ll Q$, $Q \ll P$ and $M = (P + Q)/2$, it is defined by $D_{\text{JS}}(P \parallel Q) = \frac{1}{2} D_{\text{KL}}(P \parallel M) + \frac{1}{2} D_{\text{KL}}(Q \parallel M). \quad (2)$	<p>Positive definite kernel [13] Let \mathcal{X} be a non-empty set. A symmetric, real-valued map $k : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is a positive definite kernel on \mathcal{X} if for all positive integer n, real numbers $a_1, \dots, a_n \in \mathbb{R}$, and $x, \dots, x_n \in \mathcal{X}$, it holds that $\sum_{i=1}^n \sum_{j=1}^n a_i a_j k(x_i, x_j) \geq 0$. A kernel is said to be a <i>Kreĭn kernel</i> if it can be represented as the difference of two positive definite kernels.</p> <p>Kreĭn kernel [11] Let \mathcal{X} be a non-empty set. A symmetric, real-valued map $k : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ is a Kreĭn kernel on \mathcal{X} if there exists two positive definite kernels k_1 and k_2 on \mathcal{X} such that $k(x, y) = k_1(x, y) - k_2(x, y)$ holds for all $x, y \in \mathcal{X}$.</p>	<p>We assume that the sample space Ω is finite. Let P and Q be two different distributions on Ω. For every $t > 0$ and $\lambda \in (0, 1)$, we have</p> $L(\lambda) H^2(P, Q) \leq D_{\text{GJS}}^\lambda(P \parallel Q) \leq U(\lambda) H^2(P, Q) \leq H^2(P, Q),$ <p>where $L(\lambda) = 2 \min\{\eta(\lambda), \eta(1 - \lambda)\}$, $\eta(\lambda) = -\lambda \ln \lambda$ and $U(\lambda) = \frac{2\lambda(1-\lambda)}{1-2\lambda} \ln \frac{1-\lambda}{\lambda}$.</p> <p>We show theorem 1 by showing a two-sided approximation result regarding m_λ and hel. This result might be of independent interest for other machine learning tasks, say, approximate information-theoretic clustering [3].</p>
		Lemma (Proof in ??)
		<p>Define $\kappa_\lambda(t) = \frac{m_\lambda(t)}{\text{hel}(t)}$. For every $t > 0$ and $\lambda \in (0, 1)$, we have $\kappa_\lambda(t) = \kappa_{1-\lambda}(1/t)$ and $\kappa_\lambda(t) \in [L(\lambda), U(\lambda)]$.</p>