

# Higher-Order Probabilistic Programming

A Tutorial at POPL 2019

## Part II

*Ugo Dal Lago*

(Based on joint work with *Flavien Breuvert*, *Raphaëlle Crubillé*, *Charles Grellois*, *Davide Sangiorgi*, . . . )



ALMA MATER STUDIORUM  
UNIVERSITÀ DI BOLOGNA



POPL 2019, Lisbon, January 14th

# A Foundation for Higher-Order Probabilistic Programming

- ▶ We are interested in a better understanding of some crucial questions about higher-order probabilistic programs, e.g.:
  - ▶ How could we *formalise* and *prove* programs to have certain desirable **properties**, like being terminating or consuming a bounded amount of resources?
  - ▶ How could we prove programs to be **equivalent**, or more generally to be in a certain relation?

# A Foundation for Higher-Order Probabilistic Programming

- ▶ We are interested in a better understanding of some crucial questions about higher-order probabilistic programs, e.g.:
  - ▶ How could we *formalise* and *prove* programs to have certain desirable **properties**, like being terminating or consuming a bounded amount of resources?
  - ▶ How could we prove programs to be **equivalent**, or more generally to be in a certain relation?
- ▶ We could in principle answer these questions directly in a programming language like OCAML.

# A Foundation for Higher-Order Probabilistic Programming

- ▶ We are interested in a better understanding of some crucial questions about higher-order probabilistic programs, e.g.:
  - ▶ How could we *formalise* and *prove* programs to have certain desirable **properties**, like being terminating or consuming a bounded amount of resources?
  - ▶ How could we prove programs to be **equivalent**, or more generally to be in a certain relation?
- ▶ We could in principle answer these questions directly in a programming language like OCAML.
- ▶ It is methodologically much better to distill some paradigmatic calculi which expose all the essential features, but which are somehow agnostic to many unimportant details.
- ▶ We will introduce and study two such calculi:
  - ▶  $\text{PCF}_{\oplus}$ , a calculus for randomized higher-order programming.
  - ▶  $\text{PCF}_{\text{sample, score}}$ , a calculus for bayesian programming.

## PCF<sub>⊕</sub>: Types, Terms, Values

**Types**      $\tau, \rho ::= \text{UNIT} \mid \text{NUM} \mid \tau \rightarrow \rho$

**Terms**     $M, N ::= V \mid V W \mid \text{let } M = x \text{ in } N \mid M \oplus N$   
                   $\mid \text{if } V \text{ then } M \text{ else } N \mid f_n(V_1, \dots, V_n)$

**Values**     $V, W ::= \star \mid x \mid r \mid \lambda x. M \mid \text{fix } x. V$

# PCF<sub>⊕</sub>: Type Assignment Rules

## Value Typing Rules

$$\begin{array}{c} \overline{\Gamma \vdash \star : \text{UNIT}} \text{ S} \quad \overline{\Gamma, x : \tau \vdash x : \tau} \text{ V} \quad \overline{\Gamma \vdash r : \text{NUM}} \text{ R} \\[1em] \frac{\Gamma, x : \tau \vdash M : \rho}{\Gamma \vdash \lambda x.M : \tau \rightarrow \rho} \lambda \quad \frac{\Gamma, x : \tau \rightarrow \rho \vdash M : \tau \rightarrow \rho}{\Gamma \vdash \text{fix } x.M : \tau \rightarrow \rho} \times \end{array}$$

## Term Typing Rules

$$\begin{array}{c} \frac{\Gamma \vdash V : \tau \rightarrow \rho \quad \Gamma \vdash W : \tau}{\Gamma \vdash V W : \rho} @ \quad \frac{\Gamma \vdash M : \tau \quad \Gamma, x : \tau \vdash N : \rho}{\Gamma \vdash \text{let } M = x \text{ in } N : \rho} \text{ L} \quad \frac{\Gamma \vdash M : \tau \quad \Gamma \vdash N : \tau}{\Gamma \vdash M \oplus N : \tau} \oplus \\[1em] \frac{\Gamma \vdash V : \text{NUM} \quad \Gamma \vdash M : \tau \quad \Gamma \vdash N : \tau}{\Gamma \vdash \text{if } V \text{ then } M \text{ else } N : \tau} \text{ I} \quad \frac{\Gamma \vdash V_1 : \text{NUM} \quad \dots \quad \Gamma \vdash V_n : \text{NUM}}{\Gamma \vdash f_n(V_1, \dots, V_n) : \text{NUM}} \text{ F} \end{array}$$

# PCF<sub>⊕</sub>: Type Assignment Rules

## Value Typing Rules

$$\begin{array}{c} \overline{\Gamma \vdash \star : \text{UNIT}} \text{ S} \quad \overline{\Gamma, x : \tau \vdash x : \tau} \text{ V} \quad \overline{\Gamma \vdash r : \text{NUM}} \text{ R} \\[1em] \frac{\Gamma, x : \tau \vdash M : \rho}{\Gamma \vdash \lambda x.M : \tau \rightarrow \rho} \lambda \quad \frac{\Gamma, x : \tau \rightarrow \rho \vdash M : \tau \rightarrow \rho}{\Gamma \vdash \text{fix } x.M : \tau \rightarrow \rho} \times \end{array}$$

## Term Typing Rules

$$\begin{array}{c} \frac{\Gamma \vdash V : \tau \rightarrow \rho \quad \Gamma \vdash W : \tau}{\Gamma \vdash V W : \rho} @ \quad \frac{\Gamma \vdash M : \tau \quad \Gamma, x : \tau \vdash N : \rho}{\Gamma \vdash \text{let } M = x \text{ in } N : \rho} \text{ L} \quad \frac{\Gamma \vdash M : \tau \quad \Gamma \vdash N : \tau}{\Gamma \vdash M \oplus N : \tau} \oplus \\[1em] \frac{\Gamma \vdash V : \text{NUM} \quad \Gamma \vdash M : \tau \quad \Gamma \vdash N : \tau}{\Gamma \vdash \text{if } V \text{ then } M \text{ else } N : \tau} \text{ I} \quad \frac{\Gamma \vdash V_1 : \text{NUM} \quad \dots \quad \Gamma \vdash V_n : \text{NUM}}{\Gamma \vdash f_n(V_1, \dots, V_n) : \text{NUM}} \text{ F} \end{array}$$

- ▶ The closed terms of type  $\tau$  forms a set  $\mathbb{CT}_\tau$ .
- ▶ Similarly for values and  $\mathbb{CV}_\tau$ .

# Distributions

- ▶ Given any set  $X$ , a *distribution* on  $X$  is a function  $\mathcal{D} : X \rightarrow \mathbb{R}_{[0,1]}$  such that  $\mathcal{D}(x) > 0$  only for denumerably many elements of  $X$  and that  $\sum_{x \in X} \mathcal{D}(x) \leq 1$ .



# Distributions

- ▶ Given any set  $X$ , a *distribution* on  $X$  is a function  $\mathcal{D} : X \rightarrow \mathbb{R}_{[0,1]}$  such that  $\mathcal{D}(x) > 0$  only for denumerably many elements of  $X$  and that  $\sum_{x \in X} \mathcal{D}(x) \leq 1$ .
- ▶ The *support* of a distribution  $\mathcal{D}$  on  $X$  is the subset  $\text{SUPP}(\mathcal{D})$  of  $X$  defined as

$$\text{SUPP}(\mathcal{D}) := \{x \in X \mid \mathcal{D}(x) > 0\}$$

# Distributions

- ▶ Given any set  $X$ , a *distribution* on  $X$  is a function  $\mathcal{D} : X \rightarrow \mathbb{R}_{[0,1]}$  such that  $\mathcal{D}(x) > 0$  only for denumerably many elements of  $X$  and that  $\sum_{x \in X} \mathcal{D}(x) \leq 1$ .
- ▶ The *support* of a distribution  $\mathcal{D}$  on  $X$  is the subset  $\text{SUPP}(\mathcal{D})$  of  $X$  defined as

$$\text{SUPP}(\mathcal{D}) := \{x \in X \mid \mathcal{D}(x) > 0\}$$

- ▶ The set of all distributions over  $X$  is indicated as  $\mathbf{D}(X)$ .

# Distributions

- ▶ Given any set  $X$ , a *distribution* on  $X$  is a function  $\mathcal{D} : X \rightarrow \mathbb{R}_{[0,1]}$  such that  $\mathcal{D}(x) > 0$  only for denumerably many elements of  $X$  and that  $\sum_{x \in X} \mathcal{D}(x) \leq 1$ .
- ▶ The *support* of a distribution  $\mathcal{D}$  on  $X$  is the subset  $\text{SUPP}(\mathcal{D})$  of  $X$  defined as

$$\text{SUPP}(\mathcal{D}) := \{x \in X \mid \mathcal{D}(x) > 0\}$$

- ▶ The set of all distributions over  $X$  is indicated as  $\mathbf{D}(X)$ .
- ▶ We indicate the distribution assigning probability 1 to the element  $x \in X$  and 0 to any other element of  $X$  as  $\delta(x)$ .

# Distributions

- ▶ Given any set  $X$ , a *distribution* on  $X$  is a function  $\mathcal{D} : X \rightarrow \mathbb{R}_{[0,1]}$  such that  $\mathcal{D}(x) > 0$  only for denumerably many elements of  $X$  and that  $\sum_{x \in X} \mathcal{D}(x) \leq 1$ .
- ▶ The *support* of a distribution  $\mathcal{D}$  on  $X$  is the subset  $\text{SUPP}(\mathcal{D})$  of  $X$  defined as

$$\text{SUPP}(\mathcal{D}) := \{x \in X \mid \mathcal{D}(x) > 0\}$$

- ▶ The set of all distributions over  $X$  is indicated as  $\mathbf{D}(X)$ .
- ▶ We indicate the distribution assigning probability 1 to the element  $x \in X$  and 0 to any other element of  $X$  as  $\delta(x)$ .
- ▶ Given a distribution  $\mathcal{D}$  on  $X$ , its *sum*  $\sum \mathcal{D}$  is simply  $\sum_{x \in X} \mathcal{D}(x)$ .

## One-Step Reduction

$$(\lambda x.M)V \rightarrow \delta(M[V/x])$$

$$\text{let } V = x \text{ in } M \rightarrow \delta(M[V/x])$$

$$\text{if } 0 \text{ then } M \text{ else } N \rightarrow \delta(M)$$

$$\text{if } r \text{ then } M \text{ else } N \rightarrow \delta(N) \text{ if } r \neq 0$$

$$M \oplus N \rightarrow \left\{ M : \frac{1}{2}, N : \frac{1}{2} \right\}$$

$$f(r_1, \dots, r_n) \rightarrow \delta(f^*(r_1 \dots, r_n))$$

$$\frac{M \rightarrow \{L_i : p_i\}_{i \in I}}{\text{let } M = x \text{ in } N \rightarrow \{\text{let } L_i = x \text{ in } N : p_i\}_{i \in I}}$$

## Step-Indexed Reduction

$$\overline{M \Rightarrow_0 \emptyset} \quad \overline{V \Rightarrow_1 \delta(V)} \quad \overline{V \Rightarrow_{n+1} \emptyset} \quad \frac{M \rightarrow \mathcal{D} \quad \forall N \in \text{SUPP}(\mathcal{D}). N \Rightarrow_n \mathcal{E}_N}{M \Rightarrow_{n+1} \sum_{N \in \text{SUPP}(\mathcal{D})} \mathcal{D}(N) \cdot \mathcal{E}_N}$$

## PCF<sub>⊕</sub>: Some Easy Meta-Theorems

### Lemma

*If  $M \Rightarrow_n \mathcal{D}$ , then  $\text{SUPP}(\mathcal{D})$  is a finite set.*

## PCF<sub>⊕</sub>: Some Easy Meta-Theorems

### Lemma

*If  $M \Rightarrow_n \mathcal{D}$ , then  $\text{SUPP}(\mathcal{D})$  is a finite set.*

### Proposition (Progress)

*For every  $M \in \mathbb{CT}_\tau$ , either  $M$  is a value or there is  $\mathcal{D}$  with  $M \rightarrow \mathcal{D}$*



## PCF<sub>⊕</sub>: Some Easy Meta-Theorems

### Lemma

*If  $M \Rightarrow_n \mathcal{D}$ , then  $\text{SUPP}(\mathcal{D})$  is a finite set.*

### Proposition (Progress)

*For every  $M \in \mathbb{CT}_\tau$ , either  $M$  is a value or there is  $\mathcal{D}$  with  $M \rightarrow \mathcal{D}$*

### Proposition (Subject Reduction)

*For every  $M \in \mathbb{CT}_\tau$  and for every  $n \in \mathbb{N}$ , if  $M \rightarrow \mathcal{D}$  and  $M \Rightarrow_n \mathcal{E}$ , then  $\mathcal{D} \in \mathbf{D}(\mathbb{CT}_\tau)$  and  $\mathcal{E} \in \mathbf{D}(\mathbb{CV}_\tau)$ .*

## PCF<sub>⊕</sub>: Some Easy Meta-Theorems

### Lemma

*If  $M \Rightarrow_n \mathcal{D}$ , then  $\text{SUPP}(\mathcal{D})$  is a finite set.*

### Proposition (Progress)

*For every  $M \in \mathbb{CT}_\tau$ , either  $M$  is a value or there is  $\mathcal{D}$  with  $M \rightarrow \mathcal{D}$*

### Proposition (Subject Reduction)

*For every  $M \in \mathbb{CT}_\tau$  and for every  $n \in \mathbb{N}$ , if  $M \rightarrow \mathcal{D}$  and  $M \Rightarrow_n \mathcal{E}$ , then  $\mathcal{D} \in \mathbf{D}(\mathbb{CT}_\tau)$  and  $\mathcal{E} \in \mathbf{D}(\mathbb{CV}_\tau)$ .*

### Corollary

*For every  $M \in \mathbb{CT}_\tau$  and for every  $n \in \mathbb{N}$ , there is exactly one distribution  $\mathcal{D}_n$  such that  $M \Rightarrow_n \mathcal{D}_n$ . We will write  $\langle M \rangle_n$  for such a distribution.*

## PCF<sub>⊕</sub>: The Operational Semantics of a Term

- ▶ Given two distributions  $\mathcal{D}, \mathcal{E} \in \mathbf{D}(X)$ , we write  $\mathcal{D} \leq \mathcal{E}$  iff  $\mathcal{D}(x) \leq \mathcal{E}(x)$  for every  $x \in X$ . This relation endows  $\mathbf{D}(X)$  with the structure of a partial order, which is actually an  $\omega\mathbf{CPO}$ :
- ▶ Given a closed term  $M \in \mathbb{CT}_\tau$ , the *operational semantics* of  $M$  is defined to be the distribution  $\langle M \rangle \in \mathbb{CV}_\tau$  defined as  $\sum_{n \in \mathbb{N}} \langle M \rangle_n$ .

## PCF<sub>⊕</sub>: The Operational Semantics of a Term

- ▶ Given two distributions  $\mathcal{D}, \mathcal{E} \in \mathbf{D}(X)$ , we write  $\mathcal{D} \leq \mathcal{E}$  iff  $\mathcal{D}(x) \leq \mathcal{E}(x)$  for every  $x \in X$ . This relation endows  $\mathbf{D}(X)$  with the structure of a partial order, which is actually an  $\omega\mathbf{CPO}$ :
- ▶ Given a closed term  $M \in \mathbb{CT}_\tau$ , the *operational semantics* of  $M$  is defined to be the distribution  $\langle M \rangle \in \mathbb{CV}_\tau$  defined as  $\sum_{n \in \mathbb{N}} \langle M \rangle_n$ .

$$\begin{array}{ll} \textbf{Term Contexts} & C_{\mathsf{T}}, D_{\mathsf{T}} ::= C_{\mathsf{V}} \mid [\cdot] \mid C_{\mathsf{V}} V \mid V C_{\mathsf{V}} \\ & \mid \text{let } C_{\mathsf{T}} = x \text{ in } N \mid \text{let } M = x \text{ in } C_{\mathsf{T}} \mid C_{\mathsf{T}} \oplus D_{\mathsf{T}} \\ & \mid \text{if } V \text{ then } C_{\mathsf{T}} \text{ else } D_{\mathsf{T}} \\ \textbf{Value Contexts} & C_{\mathsf{V}}, D_{\mathsf{V}} ::= \lambda x. C_{\mathsf{T}} \mid \text{fix } x. C_{\mathsf{V}} \end{array}$$

## PCF<sub>⊕</sub>: The Operational Semantics of a Term

- ▶ Given two distributions  $\mathcal{D}, \mathcal{E} \in \mathbf{D}(X)$ , we write  $\mathcal{D} \leq \mathcal{E}$  iff  $\mathcal{D}(x) \leq \mathcal{E}(x)$  for every  $x \in X$ . This relation endows  $\mathbf{D}(X)$  with the structure of a partial order, which is actually an  $\omega\mathbf{CPO}$ :
- ▶ Given a closed term  $M \in \mathbb{CT}_\tau$ , the *operational semantics* of  $M$  is defined to be the distribution  $\langle M \rangle \in \mathbb{CV}_\tau$  defined as  $\sum_{n \in \mathbb{N}} \langle M \rangle_n$ .

$$\begin{array}{lcl} \textbf{Term Contexts} & C_{\mathbb{T}}, D_{\mathbb{T}} ::= & C_{\mathbb{V}} \mid [\cdot] \mid C_{\mathbb{V}} V \mid V C_{\mathbb{V}} \\ & & \mid \text{let } C_{\mathbb{T}} = x \text{ in } N \mid \text{let } M = x \text{ in } C_{\mathbb{T}} \mid C_{\mathbb{T}} \oplus D_{\mathbb{T}} \\ & & \mid \text{if } V \text{ then } C_{\mathbb{T}} \text{ else } D_{\mathbb{T}} \end{array}$$

$$\begin{array}{lcl} \textbf{Value Contexts} & C_{\mathbb{V}}, D_{\mathbb{V}} ::= & \lambda x. C_{\mathbb{T}} \mid \text{fix } x. C_{\mathbb{V}} \end{array}$$

- ▶ Given two terms  $M, N$  such that  $\Gamma \vdash M : \tau$  and  $\Gamma \vdash N : \tau$ , we say that  $M$  and  $N$  are  $(\Gamma, \tau)$ -*equivalent*, and we write  $M \equiv_{\Gamma}^{\tau} N$  iff whenever  $\emptyset \vdash C[\Gamma \vdash \cdot : \tau] : \text{UNIT}$ , it holds that  $\sum \langle C[M] \rangle = \sum \langle C[N] \rangle$ .

## PCF<sub>⊕</sub>: from Equivalences to Metrics?

- ▶ The definition of contextual equivalence asks that  $\sum \langle C[M] \rangle = \sum \langle C[N] \rangle$  for every context  $C$ .
- ▶ But what if  $\sum \langle C[M] \rangle$  and  $\sum \langle C[N] \rangle$  are very close, without being really equal to each other?
- ▶ It makes sense to generalize contextual equivalence to a notion of **distance**:

$$\delta^{\Gamma, \tau}(M, N) = \sup_{\emptyset \vdash C[\Gamma \vdash \cdot : \tau] : \mathbf{UNIT}} \left| \sum \langle C[M] \rangle - \sum \langle C[N] \rangle \right|.$$

- ▶ For every  $\Gamma, \tau$ ,  $\delta^{\Gamma, \tau}$  is indeed a *pseudo-metric*:

$$\delta^{\Gamma, \tau}(M, M) = 0$$

$$\delta^{\Gamma, \tau}(M, N) = \delta^{\Gamma, \tau}(N, M)$$

$$\delta^{\Gamma, \tau}(M, L) \leq \delta^{\Gamma, \tau}(M, N) + \delta^{\Gamma, \tau}(N, L)$$

## Termination in a Probabilistic Setting

- ▶ Let  $M$  be any closed term. We say that  $M$  is **almost surely terminating** if  $\sum \langle M \rangle = 1$ , namely if its probability of convergence is 1.

## Termination in a Probabilistic Setting

- ▶ Let  $M$  be any closed term. We say that  $M$  is **almost surely terminating** if  $\sum \langle M \rangle = 1$ , namely if its probability of convergence is 1.
- ▶ **Example:**

$$GEO := (\mathbf{fix} \ f.\lambda x.x \oplus (\mathbf{let} \ succ_1(x) = y \ \mathbf{in} \ f \ y))0$$



## Termination in a Probabilistic Setting

- ▶ Let  $M$  be any closed term. We say that  $M$  is **almost surely terminating** if  $\sum \langle M \rangle = 1$ , namely if its probability of convergence is 1.
- ▶ **Example:**

$$GEO := (\text{fix } f.\lambda x.x \oplus (\text{let } succ_1(x) = y \text{ in } f \ y))0$$

- ▶ The **expected evaluation length** of any closed term as follows:

$$ExLen(M) := \sum_{m=0}^{\infty} \left( 1 - \sum_{n=0}^m \sum \langle M \rangle_n \right)$$

Let  $M$  be any closed term. We say that  $M$  is **positively almost surely terminating** if  $ExLen(M) < +\infty$ .

## Termination in a Probabilistic Setting

- ▶ Let  $M$  be any closed term. We say that  $M$  is **almost surely terminating** if  $\sum \langle M \rangle = 1$ , namely if its probability of convergence is 1.
- ▶ **Example:**

$$GEO := (\text{fix } f.\lambda x.x \oplus (\text{let } succ_1(x) = y \text{ in } f \ y))0$$

- ▶ The **expected evaluation length** of any closed term as follows:

$$ExLen(M) := \sum_{m=0}^{\infty} \left( 1 - \sum_{n=0}^m \sum \langle M \rangle_n \right)$$

Let  $M$  be any closed term. We say that  $M$  is **positively almost surely terminating** if  $ExLen(M) < +\infty$ .

### Lemma

*Every positively almost-surely terminating term is almost-surely terminating.*

## Variations on $\text{PCF}_{\oplus}$

- ▶ **Free, Untyped** rather than applied, typed.
  - ▶ **Terms:**  $M ::= x \mid \lambda M. \mid MM \mid M \oplus M$ ;
  - ▶ **Values:**  $V ::= \lambda M.$ ;
  - ▶ **One-Step Reduction:**

$$(\lambda x.M)V \rightarrow \delta(M[V/x]) \qquad M \oplus N \rightarrow \left\{ M : \frac{1}{2}, N : \frac{1}{2} \right\}$$

$$\frac{M \rightarrow \{L_i : p_i\}_{i \in I}}{MN \rightarrow \{L_i N : p_i\}_{i \in I}} \qquad \frac{M \rightarrow \{L_i : p_i\}_{i \in I}}{VM \rightarrow \{V L_i : p_i\}_{i \in I}}$$

- ▶ The obtained calculus will be referred to as  $\Lambda_{\oplus}$ .

## Variations on $\text{PCF}_\oplus$

- ▶ **Free, Untyped** rather than applied, typed.
  - ▶ **Terms:**  $M ::= x \mid \lambda M. \mid MM \mid M \oplus M;$
  - ▶ **Values:**  $V ::= \lambda M.;$
  - ▶ **One-Step Reduction:**

$$(\lambda x.M)V \rightarrow \delta(M[V/x]) \qquad M \oplus N \rightarrow \left\{ M : \frac{1}{2}, N : \frac{1}{2} \right\}$$

$$\frac{M \rightarrow \{L_i : p_i\}_{i \in I}}{MN \rightarrow \{L_i N : p_i\}_{i \in I}} \qquad \frac{M \rightarrow \{L_i : p_i\}_{i \in I}}{VM \rightarrow \{V L_i : p_i\}_{i \in I}}$$

- ▶ The obtained calculus will be referred to as  $\Lambda_\oplus$ .
- ▶ **CBN** rather than CBV.
  - ▶ **One-Step Reduction:**

$$(\lambda x.M)N \rightarrow \delta(M[N/x]) \qquad M \oplus N \rightarrow \left\{ M : \frac{1}{2}, N : \frac{1}{2} \right\}$$

$$\frac{M \rightarrow \{L_i : p_i\}_{i \in I}}{MN \rightarrow \{L_i N : p_i\}_{i \in I}}$$

# From Randomised Algorithms to Bayesian Programming

- ▶ Binary probabilistic choice is perfectly adequate to model randomised computation.

# From Randomised Algorithms to Bayesian Programming

- ▶ Binary probabilistic choice is perfectly adequate to model randomised computation.

## Theorem

*The class of computable probabilistic functions coincides with the class of probabilistic functions computable by  $\text{PCF}_{\oplus}^{\mathbb{N}}$ .*

# From Randomised Algorithms to Bayesian Programming

- ▶ Binary probabilistic choice is perfectly adequate to model randomised computation.

## Theorem

*The class of computable probabilistic functions coincides with the class of probabilistic functions computable by  $\text{PCF}_{\oplus}^{\mathbb{N}}$ .*

- ▶ In recent years, starting from the pioneering works on languages like CHURCH, ANGLICAN, or HANSEI, functional programs have been also employed as means to represent probabilistic *models* rather than *algorithms*.
- ▶ The languages above can be modeled [Staton2017] as  $\lambda$ -calculi endowed with two new operators:
  - ▶ **sample**, modeling sampling from the uniform distribution on  $[0, 1]$ .
  - ▶ **score**, which takes a positive real number  $r$  as a parameter, and modify the *weight* of the current probabilistic branch by multiplying it by  $r$ .

## PCF<sub>sample,score</sub>: Terms, Typing Rules, and Reduction

**Terms**             $M, N ::= \text{sample} \mid \text{score}(V).$



## PCF<sub>sample,score</sub>: Terms, Typing Rules, and Reduction

**Terms**  $M, N ::= \text{sample} \mid \text{score}(V).$

**Typing Rules**  $\frac{}{\Gamma \vdash \text{sample} : \text{NUM}} \text{A} \quad \frac{\Gamma \vdash V : \text{NUM}}{\Gamma \vdash \text{score}(V) : \text{UNIT}} \text{C}$

## PCF<sub>sample,score</sub>: Terms, Typing Rules, and Reduction

**Terms**  $M, N ::= \text{sample} \mid \text{score}(V).$

**Typing Rules** 
$$\frac{}{\Gamma \vdash \text{sample} : \text{NUM}} \text{A} \qquad \frac{\Gamma \vdash V : \text{NUM}}{\Gamma \vdash \text{score}(V) : \text{UNIT}} \text{C}$$

- ▶ One needs to switch from distributions to *measures*, and assume the underlying set, namely  $\mathbb{R}$  to have the structure of a measurable space
- ▶ Adapting the rule for **let**-terms naturally leads to

$$\frac{M \rightarrow \mu}{\text{let } M = x \text{ in } N \rightarrow \text{let } \mu = x \text{ in } N}$$

where **let**  $\mu = x$  **in**  $N$  should itself be a measure.

- ▶ The key rule in step-indexed reduction needs to be adapted:

$$\frac{M \rightarrow \mu \quad \forall N \in \text{SUPP}(\mu). N \Rightarrow_n \sigma_N}{M \Rightarrow_{n+1} A \mapsto \int \sigma_N(A) \mu(dN)}$$

# The Operational Meaning of Bayesian Terms

- ▶ It can well be that  $\langle M \rangle = \mu$ , where  $\mu$  sums to something *strictly higher* than 1.

# The Operational Meaning of Bayesian Terms

- ▶ It can well be that  $\langle M \rangle = \mu$ , where  $\mu$  sums to something *strictly higher* than 1.
- ▶ How should we interpret  $\mu(A)$  for a measurable set of terms  $A$ ?
- ▶ We need to *normalize*  $\mu$ !

# The Operational Meaning of Bayesian Terms

- ▶ It can well be that  $\langle M \rangle = \mu$ , where  $\mu$  sums to something *strictly higher* than 1.
- ▶ How should we interpret  $\mu(A)$  for a measurable set of terms  $A$ ?
- ▶ We need to *normalize*  $\mu$ !
- ▶ Explicitly building a normalized version of  $\mu$  (if it exists) is the goal of so-called *inference algorithms*.

# The Operational Meaning of Bayesian Terms

- ▶ It can well be that  $\langle M \rangle = \mu$ , where  $\mu$  sums to something *strictly higher* than 1.
- ▶ How should we interpret  $\mu(A)$  for a measurable set of terms  $A$ ?
- ▶ We need to *normalize*  $\mu$ !
- ▶ Explicitly building a normalized version of  $\mu$  (if it exists) is the goal of so-called *inference algorithms*.
- ▶ The operational semantics we have just introduced, called **distribution-based** is thus just an *idealized* form of semantics.
- ▶ An *executable* semantics can be given in the form of **sampling-based semantics**.

## Sampling-Based Semantics (1)

$$\langle (\lambda x.M)V, s \rangle \xrightarrow{1} \langle M[V/x], s \rangle$$

$$\langle \text{let } V = x \text{ in } M, s \rangle \xrightarrow{1} \langle M[V/x], s \rangle$$

$$\langle \text{if } 0 \text{ then } M \text{ else } N, s \rangle \xrightarrow{1} \langle M, s \rangle$$

$$\langle \text{if } r \text{ then } M \text{ else } N, s \rangle \xrightarrow{1} \langle N, s \rangle \text{ if } r \neq 0$$

$$\langle \text{sample}, r :: s \rangle \xrightarrow{1} \langle r, s \rangle$$

$$\langle \text{score}(r), s \rangle \xrightarrow{r} \langle \star, s \rangle$$

$$\langle f(r_1, \dots, r_n), s \rangle \xrightarrow{1} \langle f^*(r_1 \dots, r_n), s \rangle$$

$$\frac{\langle M, s \rangle \xrightarrow{r} \langle L, t \rangle}{\langle \text{let } M = x \text{ in } N, s \rangle \xrightarrow{r} \langle \text{let } L = x \text{ in } N, s \rangle}$$

## Sampling-Based Semantics (2)

$$\frac{}{\langle V, s \rangle \stackrel{1}{\Rightarrow} \langle V, s \rangle} \quad \frac{\langle M, s \rangle \stackrel{r}{\rightarrow} \langle N, t \rangle \quad \langle N, t \rangle \stackrel{s}{\Rightarrow} \langle L, u \rangle}{\langle M, s \rangle \stackrel{r \cdot s}{\Rightarrow} \langle L, u \rangle}$$



Thank You!

Questions?