The Complexity of Admissibility in ω -Regular Games

R. Brenguier J.-F. Raskin M. Sassolas



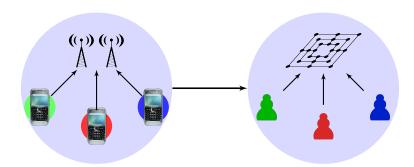


Highlights 2013 September, 19-21

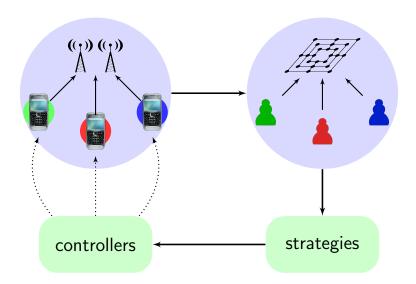
Controller synthesis



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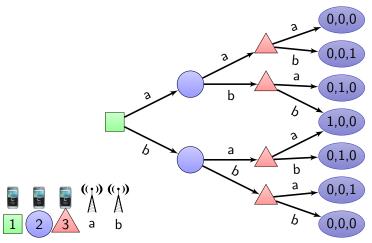
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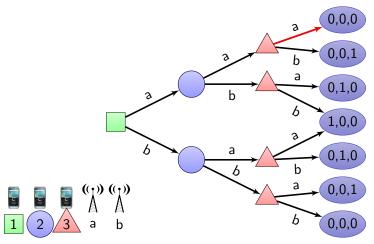
Models of rationality

- Nash equilibria → no player has interest in deviating.
- Elimination of dominated strategies \(\simp \) players eliminate "bad" strategies
- \hookrightarrow In all cases it is assumed everybody knows and uses the model of rationality.

- What is a "bad" strategy? σ is strictly dominated by σ' if
 - for all profiles of the other players, if σ wins, so does σ' .
 - for some profile of the other players, σ loses while σ' wins.

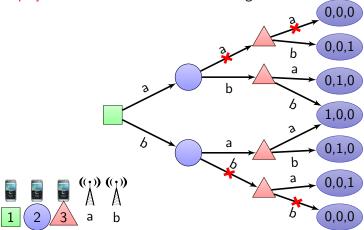


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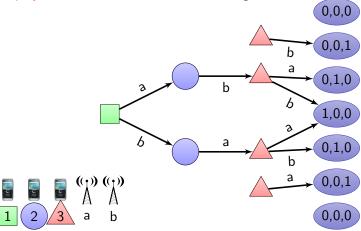
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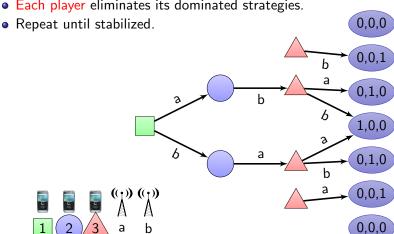
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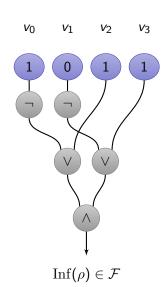


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- Objective of player i: $W_{IN_i} \subseteq V^{\omega}$.
- Muller objectives: $\rho \in W_{IN_i}$ iff $Inf(\rho) \in \mathcal{F}$.
- → Generalizes Büchi and parity conditions.
 - Weak Muller objectives: $\rho \in Win_i$ iff $Occ(\rho) \in \mathcal{F}$.
- Generalizes safety and reachability conditions.



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- Dominance: $\sigma'_i \succ_{S^n} \sigma_i$ if σ'_i strictly dominates σ_i w.r.t S^n .
- Iterative admissibility: $S_i^0 = S_i$ and $S_i^{n+1} := S_i^n \setminus \{\sigma_i \mid \exists \sigma_i' \in S_i^n, \sigma_i' \succ_{S^n} \sigma_i \}$.
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 \mathcal{S}^* is well defined and is reached after a finite number of iterations. "Admissibility in Infinite Games" [Berwanger, STACS'07]

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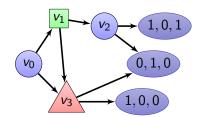
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Decision problems on \mathcal{S}^*

The winning coalition problem: Given $W, L \subseteq P$, does there exists $\sigma_P \in \mathcal{S}^*$ such that all players of W win the game, and all players of L lose. The model-checking under admissibility problem: Given φ an LTL formula, is it the case that for any profile $\sigma_P \in \mathcal{S}^*$, $Out(\sigma_P) \models \varphi$?

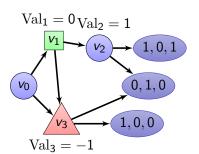
Introduced in [Berwanger, STACS'07]

- If there is a winning strategy
- admissible strategies are the winning ones.
 - It is impossible to win
- → all strategies are admissible.



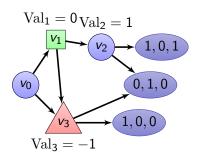
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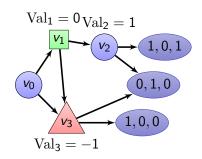
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- If there is a winning strategy: value 1.
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Remark

- A player should never decrease its own value.
- The value depends on S^n .
- \hookrightarrow How to compute those values?

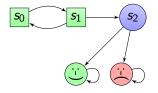


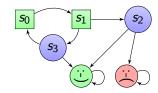
Safety objectives: a local notion of dominance

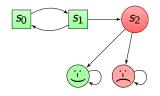
- Objective: avoid Bad states
- Existence of a winning strategy depends only on:
 - the current state
 - Bad states visited
 - wifold the graph to keep this information
 - \rightsquigarrow size: $|V| \times 2^{|P|}$.
- In unfolded safety games the rule to never decrease one's own value is sufficient for admissibility.
- The structure of the unfolding avoid explosion in complexity.

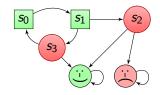
Theorem

The winning coalition problem is PSPACE-complete for safety.

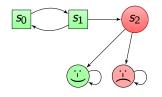


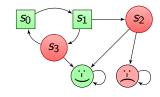




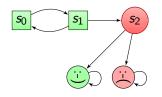


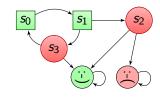
- In case the value is 0, need to allow other players to help.
- "Help!"-state for i: a state where $j \neq i$ has several choices with value ≥ 0 for i, while not changing the value for j.
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 - ullet In turn, \mathcal{A}_n is used to compute the values at the next step.

Complexity for Objectives defined by Circuits

Theorem (Winning coalition problem)

- The winning coalition problem PSPACE-complete for circuits.
- The winning coalition problem with Büchi objectives is in PNP
- The winning coalition problem for weak circuit is PSPACE-complete.

Theorem (Model-checking under admissibility problem)

The model-checking under admissibility problem is PSPACE-complete for games where the winning condition of each player is given by a circuit condition.

Summary

- Automata representing all outcomes of admissible strategies.
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- Application to model-checking of LTL assuming all players follow rationality.

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Thank you

