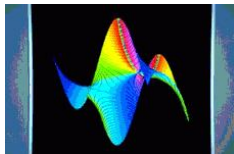


Differential Equations for Algebraic Functions

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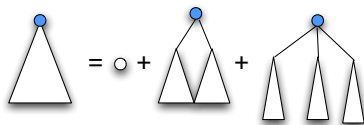
Algorithms Project, Inria



Joint work with A. Bostan, F. Chyzak, G. Lecerf & É. Schost

I Introduction

Example: Binary-Ternary Trees



c_N = number of trees with N nodes

Generating series:

$$\alpha = 1 + 2z + 10z^2 + 66z^3 + \cdots + c_N z^N + \cdots$$

$$\alpha = 1 + z\alpha^2 + z\alpha^3.$$

More generally, context-free languages:

- their enumeration;
- their random generation.

Aim

c_0, \dots, c_N for large N .

Computations for Binary-Ternary Trees

$$\alpha = 1 + z\alpha^2 + z\alpha^3.$$

1 Non-linear recurrence

$$c_N = \sum_{i+j=N-1} c_i c_j + \sum_{i+j+k=N-1} c_i c_j c_k, \quad N \geq 1.$$

Complexity: $O(N^3)$ ops

Computations for Binary-Ternary Trees

$$\alpha = 1 + z\alpha^2 + z\alpha^3.$$

① Non-linear recurrence $O(N^3)$

② Iterate $\alpha_{k+1} = 1 + z\alpha_k + z\alpha_k^3$

$$\alpha_0 = 1$$

$$\alpha_1 = 1 + 2z$$

$$\alpha_2 = 1 + 2z + 10z^2 + 16z^3 + 8z^4$$

$$\alpha_3 = 1 + 2z + 10z^2 + 66z^3 + 248z^4 + \dots$$

$$\alpha_4 = 1 + 2z + 10z^2 + 66z^3 + 488z^4 + \dots$$

Complexity: $O(NM(N))$ ($M(N)$ for series product)

Computations for Binary-Ternary Trees

$$\alpha = 1 + z\alpha^2 + z\alpha^3.$$

- 1 Non-linear recurrence $O(N^3)$
- 2 Iterate $O(NM(N))$

Fast Multiplication

- **Balanced** input: $\text{degree}N \times \text{degree}N$
 - Naïve: $M(N) = O(N^2)$
 - Karatsuba (1963): $M(N) = O(N^{1.59})$
 - Fast Fourier Transform: $M(N) = O(N \log N) =: \tilde{O}(N)$
[Schönhage-Strassen71]
- Many applications via **Newton** iteration, including division.

Computations for Binary-Ternary Trees

$$\alpha = 1 + z\alpha^2 + z\alpha^3.$$



- ❶ Non-linear recurrence $O(N^3)$
- ❷ Iterate $O(NM(N))$
- ❸ Newton iteration [Kung & Traub 78]

$$\alpha_{k+1} = \alpha_k - \frac{\alpha_k - (1 + z\alpha_k^2 + z\alpha_k^3)}{1 - 2z\alpha_k - 3z\alpha_k^2}$$

$$\alpha_0 = 1$$

$$\alpha_1 = 1 + 2z + 10z^2 + 50z^3 + \dots$$

$$\alpha_2 = 1 + 2z + 10z^2 + 66z^3 + 498z^4 + 4066z^5 + 34970z^6 + 311042z^7 + \dots$$

Complexity: $O(M(N))$ ($M(N)$ for series product)

Computations for Binary-Ternary Trees

$$\alpha = 1 + z\alpha^2 + z\alpha^3.$$

- ① Non-linear recurrence $O(N^3)$
- ② Iterate $O(NM(N))$
- ③ Newton iteration [Kung & Traub 78] $O(M(N))$
- ④ Linear recurrence [Comtet 64, Chudnovsky² 86]
 - ① linear differential equation [Abel 1827, Cockle 1861]

$$2z(z-2)(z^2+11z-1)\alpha'' + (3z^3 + 12z^2 - 89z + 6)\alpha' - 3(z+3)\alpha = z+3,$$

- ② translate

$$(2n+6)(2n+7)c_{n+3} = (46n^2 + 227n + 279)c_{n+2} \\ - 3(6n^2 + 10n + 3)c_{n+1} - n(2n+1)c_n.$$

Complexity: $O(N)$.

Computations for Binary-Ternary Trees

$$\alpha = 1 + z\alpha^2 + z\alpha^3.$$

- ① Non-linear recurrence $O(N^3)$
- ② Iterate $O(NM(N))$
- ③ Newton iteration [Kung & Traub 78] $O(M(N))$
- ④ Linear recurrence [Comtet 64, Chudnovsky² 86] $O(N)$

Series \leftrightarrow Coefficients: orders differ

$$z^i \alpha^{(j)} = z^i \partial_z^j \cdot \alpha = \sum_n (n - i + 1) \cdots (n - i + j) c_{n+j-i} z^n$$

$$(z \partial_z)^k z^{-i} \cdot \alpha = \sum_n c_{n+i} n^k z^n.$$

Computations for Binary-Ternary Trees

$$\alpha = 1 + z\alpha^2 + z\alpha^3.$$

- ① Non-linear recurrence $O(N^3)$
- ② Iterate $O(NM(N))$
- ③ Newton iteration [Kung & Traub 78] $O(M(N))$
- ④ Linear recurrence [Comtet 64, Chudnovsky² 86] $O(N)$

Our Result

Even faster! (wrt degree)

Algorithms and Complexities

$$P(z, \alpha) = 0, \quad \deg P = D$$

- ① Non-linear recurrence $O(N^D)$
- ② Iterate if $\alpha = P(z, \alpha)$: $O(\sqrt{D}NM(N))$ (baby steps/giant steps)
- ③ Newton iteration $O(\sqrt{D}M(N))$
- ④ Linear recurrence $O(D^?N)$.

Theorem (BoChLeSaSc07)

- ① *the recurrence computed through Cockle's differential equation leads to $O(D^2M(D)N)$ ops;*
- ② *there exist other recurrences leading to $O(DM(D)N)$ ops.*

Also, results in terms of D_z and D_y separately.

Nicer Recurrence on our Example

$$\alpha = 1 + z\alpha^2 + z\alpha^3$$



- Classical way:

- 1 Linear differential equation [Abel 1827, Cockle 1861]

$$2z(z-2)(z^2+11z-1)\alpha'' + (3z^3+12z^2-89z+6)\alpha' - 3(z+3)\alpha = z+3,$$

- 2 translate

$$(2n+6)(2n+7)c_{n+3} = (46n^2 + 227n + 279)c_{n+2} \\ - 3(6n^2 + 10n + 3)c_{n+1} - n(2n+1)c_n.$$

- Shorter recurrence:

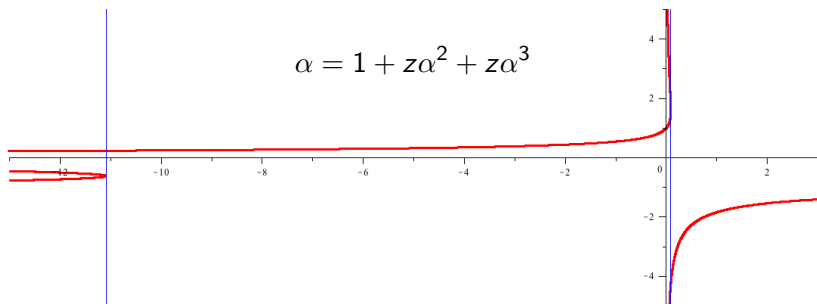
$$(n+2)(2n+5)(5n+3)c_{n+2} = (110n^3+396n^2+445n+150)c_{n+1} \\ + n(2n+1)(5n+8)c_n.$$

Questions

Minimal order for differential equation? for recurrence?

Minimal “size”? Efficiency?

Apparent Singularities Pollution



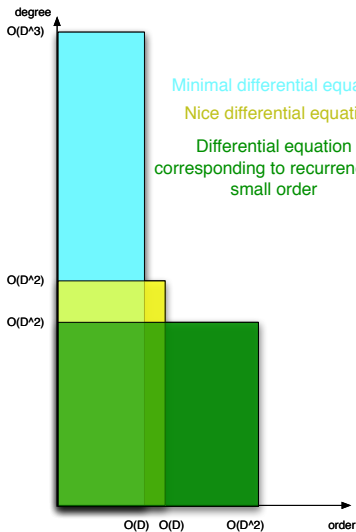
- Cockle's differential equation:

$$2z(z-2)(z^2+11z-1)\alpha'' + (3z^3+12z^2-89z+6)\alpha' - 3(z+3)\alpha = z+3,$$

- differential equation associated to shorter recurrence:

$$10z(z^2+11z-1)\alpha''' - (2z^3-33z^2-442z+25)\alpha'' + \dots = 0.$$

Our Results



Computation

$\tilde{O}(D^{\omega+4})$

$\tilde{O}(D^{\omega+3})$

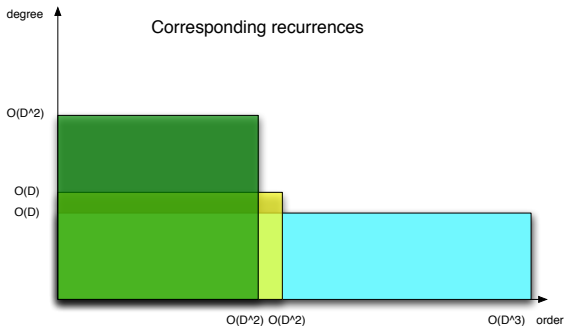
$\tilde{O}(D^{2\omega+3})$

Unrolling the recurrence

$\tilde{O}(D^2 M(D) N)$

$\tilde{O}(D M(D) N)$

$\tilde{O}(M(D^3) N)$



History

- Abel (1827): Existence of linear differential equation;
- Cockle (1861–1862): Algorithm for linear differential equation of minimal order;
- Harley (1862): Name “Differential resolvent”;
- Tannery (1875): Rediscovery of Cockle’s method;
- Comtet (1964): Application to series expansion (by hand);
- Chudnovsky² (1986): Complexity point of view;
- Cormier, Singer, Trager, Ulmer (2002): \rightsquigarrow Degree bound in $O(D^5)$ for the differential resolvent;
- Nahay (2003–2004): Deg. bound in $O(D^3)$ for α^λ with $\lambda \notin \bar{\mathbb{Q}}$;
- Tsai (2000): Weyl closure \rightsquigarrow removal of apparent singularities.

II Algorithms

Recurrence Unrolling

Problem

Given initial conditions and $p_k(n)u_{n+k} + \dots + p_0(n)u_n = 0$, with p_i 's of degree d , compute u_0, \dots, u_N efficiently for N large.

Direct: $O(Nkd)$ ops; Better: $O(NkM(d)/d)$.

→ The degree of the coefficients does not matter (much).

Algorithm: Fast Evaluation of $P(x)$ on $0, \dots, N$ [Bostan *et alii* 07]

Idea: expand generating series $\mathcal{P}(z) = \sum_{k \geq 0} P(k)z^k = \frac{Q(z)}{(1-z)^{d+1}}$.

① Compute $S(z) := (1-z)^{-d-1} \bmod z^d$;

② Compute N/d times

$$\frac{A(z)}{(1-z)^{d+1}} = \underbrace{b_0 + \dots + b_{d-1}z^{d-1}}_{B(z)} + \frac{z^d C(z)}{(1-z)^{d+1}}$$

$$\text{by } B := AS \bmod z^d; z^d C := A - B(1-z)^{d+1}.$$

Cockle's Algorithm — Example

$$\alpha(z) - (1 + z\alpha^2(z) + z\alpha^3(z)) =: P(z, \alpha) = 0$$

$$\rightarrow \begin{cases} P_y(z, \alpha)\alpha'(z) + P_z(z, \alpha) = 0 \\ A(z, y)P(z, y) + B(z, y)P_y(z, y) = 1. \end{cases} \quad (\text{Bézout})$$

$$\alpha' = -BP_z \bmod P =: u_1\alpha^2 + v_1\alpha + w_1\mathbf{1},$$

Vector space of dimension 3

$$\alpha'' = (u'_1\alpha^2 + v'_1\alpha + w'_1) + (2u_1\alpha + v_1)\alpha' =: u_2\alpha^2 + v_2\alpha + w_2\mathbf{1},$$

$$\alpha''' = (u'_2\alpha^2 + v'_2\alpha + w'_2) + (2u_2\alpha + v_2)\alpha' =: u_3\alpha^2 + v_3\alpha + w_3\mathbf{1}.$$

$$(\alpha \quad \alpha' \quad \alpha'' \quad \alpha''') = (\alpha^2 \quad \alpha \quad 1) \underbrace{\begin{pmatrix} 0 & u_1 & u_2 & u_3 \\ 1 & v_1 & v_2 & v_3 \\ 0 & w_1 & w_2 & w_3 \end{pmatrix}}_A$$

$V \in \ker A$ has for coordinates the coefficients of a differential equation.

Cockle's Algorithm — General Case

$P(z, \alpha) = 0$, $P_z(z, \alpha) + P_y(z, \alpha)\alpha' = 0$, so that

$$\alpha^{(k)} = \frac{W_k(z, \alpha)}{P_y(z, \alpha)^{2k-1}} = V_k(z, \alpha), \quad \deg_y V_k < D_y, \quad k \geq 1.$$

Algorithm

- ① Compute $V_1 := -P_z P_y^{-1} \bmod P$ (Euclidean algorithm);
- ② For $k = 2, 3, \dots$, $V_k := \partial_z \cdot V_{k-1} + (\partial_y \cdot V_{k-1}) V_1 \bmod P$;
- ③ Stop the loop when k is the first integer $r \leq D_y$ for which V_0, \dots, V_r are linearly dependent over $\mathbb{Q}(z)$;
- ④ **Output** r and the operator $\partial_z^r - A_{r-1} \partial_z^{r-1} - \dots - A_1 \partial_z - A_0$ such that $V_r = A_{r-1} V_{r-1} + \dots + A_1 V_1 + A_0 V_0$.

Implemented in gfun and in Magma's DifferentialOperator.

Padé and Padé-Hermite approximants

Definition (Padé-Hermite Approximant)

The vector of polynomials (P_1, \dots, P_k) with $\deg P_i \leq d_i$ is a **Padé-Hermite approximant** of type (d_1, \dots, d_k) for a vector of power series (f_1, \dots, f_k) when

$$P_1 f_1 + \dots + P_k f_k = O(x^{d_1 + \dots + d_k + k - 1}).$$

Special cases: (given one series y)

- $k = 2$, $f_1 = -1$, $f_2 = y$: Padé-approximant;
- $f_i = y^{i-1}$, $i = 1, \dots, k$: algebraic approximants;
- $f_i = y^{(i-1)}$, $i = 1, \dots, k$: differential approximants.

Algorithms and complexity ($D = d_1 + \dots + d_k$):

- Linear algebra: $O(D^\omega)$ ops;
- minimal basis in $O(k^\omega M(D))$ ops [Beckermann-Labahn94];
- genset in $O(k^\omega M(D/k))$ ops [Storjohann06].

Cockle's Algorithm via Truncated Series

Algorithm, non-degenerate case

- ① Compute $\alpha^{(k)} = u_{k,1}\mathbf{1} + u_{k,2}\alpha + \cdots + u_{k,D}\alpha^{D-1}$ with **power series** coefficients $u_{k,i}$, for $k = 1, \dots, D$;
- ② find linear relation (diff. eqn) with power series coefficients (Newton!);
- ③ compute Padé approximants to recover rational coefficients.

[Chudnovsky² 86, Cormier-Singer-Trager-Ulmer 02]

Complexity: $O(r^\omega M(\eta))$, η bound on degree coeffs.

Good bound \rightarrow good algorithm

Timings

Cockle's algorithm over $F = \text{GF}_{9973}$ for random dense polynomials with $D_z = D_y = N$:

N	ser.	rat.	η	\deg_z
1	.002	.002	2	2
2	.003	.004	17	10
3	.02	.03	69	36
4	.10	.16	182	92
5	.47	.98	380	190
6	1.86	4.56	687	342
7	5.80	16.5	1127	560
8	15.5	49.9	1724	856
9	38.0	138	2502	1242
10	72.7	340	3485	1730

- Always faster than Magma's built-in routine (rat.).
- Bound η off by a factor 2?

Differential Equation by Padé-Hermite Approximants

Algorithm

Input: P irreducible, order r and degree bound d ;

- ① $\sigma := ?$;
- ② Compute a series expansion for α at precision σ (Newton);
- ③ Compute a Padé-Hermite approximant (P_0, \dots, P_r) of type (d, \dots, d) for $(\alpha, \dots, \alpha^{(r)})$;
- ④ return $L \cdot y = P_0 y + \dots + P_r y^{(r)}$.

Good bounds \rightarrow good algorithm

Lemma (Truncated Series \rightarrow Full Series)

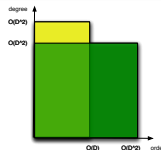
$P(x, \alpha) = 0, L \cdot \alpha = O(x^\sigma), \sigma \geq D(4Dr + d - r) \Rightarrow L \cdot \alpha = 0$.

- ① $\alpha^{(k)} = W_k / P_y^{2k-1} \rightarrow$ a polynomial $Q(z, y)$ such that $L \cdot \alpha = 0$ iff $Q(z, \alpha) = 0$, together with degree bounds on Q .
- ② The resultant $R(z)$ of P and Q w.r.t. y has degree $< \sigma$.
- ③ $R = O(x^\sigma) \Rightarrow R = 0 \Rightarrow P|Q$ (P irreducible).

III Bounds

Bounds by Creative Telescoping

$$\alpha(z) = \frac{1}{2\pi i} \oint \underbrace{\frac{yP_y(z, y)}{P(z, y)}}_{F(z, y)} dy.$$



Creative telescoping: an algorithm for differentiation under \int and integration by parts.

- ① Find $\Lambda = A(z, \partial_z) + \partial_y B(z, \partial_z, y, \partial_y)$ s.t. $\Lambda \cdot F = 0$;
- ② return A .

Bounds by counting dimensions (cf. [Lipshitz 88] for diagonals)

$$z^i \partial_z^j \partial_y^k \cdot F = \frac{Q}{p_{j+k+1}}, \quad \deg Q \leq i + (j + k + 1)D.$$

Taking $i \leq N_z$, $j + k \leq N_\partial$, $N_z = 4D^2$, $N_\partial = 4D$,

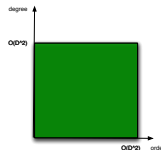
$$\dim(\text{lhs}) = (N_z + 1) \binom{N_\partial + 2}{2}, \quad > \dim(\text{rhs}) = \binom{(N_\partial + 1)D + N_z + 2}{2}.$$

\rightarrow Recurrence of order $\leq 4(D^2 + D)$, coeffs of deg $\leq 4D$.

Better Bound on Order Using y

Aim

$F = yP_y/P$, we want: $A(z, \partial_z) \cdot F = \partial_y \cdot G$, $A \neq 0$.



- ① Decompose $P =: \tilde{P} + R$, with $\deg \tilde{P} = D$, $\deg R < D$;
- ② Populate $V_d := \{Q/P^{d+1} \mid \deg Q \leq Dd + D + d\}$ with
 - $F_d := \text{Vect}(\{z^i(z\partial_z)^j \cdot F \mid i, j \leq d\})$;
 - $H_d := \partial_y \cdot \text{Vect}(\{\frac{cz^{d+1}\tilde{P}^d + H}{P^d} \mid \deg H \leq dD + d\})$.
- ③ Count dimensions:

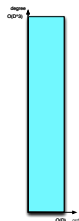
$$\dim F_d = (d+1)^2; \quad \dim H_d = \binom{dD + d + 2}{2} + 1 - \underbrace{(d+1)}_{\text{kernel}}$$

$$\dim V_d = \binom{Dd + D + d + 2}{2}.$$
- ④ Conclude: $d \geq D^2 + D \Rightarrow \dim F_d + \dim H_d > \dim V_d$.
 \rightarrow Recurrence of order $\leq D^2 + D$.

Degree bounds for the differential resolvent

$$\text{Wr}(\alpha_1, \dots, \alpha_r, \alpha) =$$

$$\begin{vmatrix} \alpha_1 & \dots & \alpha_r & \alpha \\ \frac{W_1(z, \alpha_1)}{P_Y(z, \alpha_1)} & \dots & \frac{W_1(z, \alpha_r)}{P_Y(z, \alpha_r)} & \alpha' \\ \vdots & & \vdots & \vdots \\ \frac{W_r(z, \alpha_1)}{P_Y(z, \alpha_1)^{2r-1}} & \dots & \frac{W_r(z, \alpha_r)}{P_Y(z, \alpha_r)^{2r-1}} & \alpha^{(r)} \end{vmatrix} = 0.$$



Degree bounds for the differential resolvent

$$L := \frac{1}{\prod_{1 \leq i < j \leq r} (\alpha_i - \alpha_j)} \text{Wr}(\alpha_1, \dots, \alpha_r, \alpha) \prod_i P_y(z, \alpha_i)^{2r-1} = \frac{1}{\prod_{1 \leq i < j \leq r} (\alpha_i - \alpha_j)} \times$$

$$\begin{vmatrix} P_y(z, \alpha_1)^{2r-1} \alpha_1 & \dots & P_y(z, \alpha_r)^{2r-1} \alpha_r & \alpha \\ W_1(z, \alpha_1) P_y(z, \alpha_1)^{2r-2} & \dots & W_1(z, \alpha_r) P_y(z, \alpha_r)^{2r-2} & \alpha' \\ \vdots & & \vdots & \vdots \\ W_r(z, \alpha_1) & \dots & W_r(z, \alpha_r) & \alpha^{(r)} \end{vmatrix} = 0.$$

- L is **polynomial** and **symmetric** in $\alpha_1, \dots, \alpha_r$;
- $\deg_z(\text{kth row}) = O(D^2)$, $\deg_{\alpha_i}(\text{ith col}) = O(D^2)$;
- \Rightarrow if $r = D_y$, $\deg_z L = O(D^3)$;
- if $r < D_y$, symmetrize first wrt $\alpha_1, \dots, \alpha_{D_y}$.

Precise bounds (rather than $O()$) available, and necessary in algorithm

IV Conclusion

Conclusion

- **Summary:** Good bounds + Newton + Padé or Padé-Hermite approximants = good algorithms;
- **Also in the paper:**
 - 1 Bounds in terms of D, D_x, D_y simultaneously;
 - 2 Fast heuristic algorithms using these bounds;
 - 3 Experiments and conjectures on bounds in generic cases;
 - 4 Lower bounds;
 - 5 Degenerate cases;
 - 6 Handling of algebraic extensions.
- **Future:**
 - 1 Other cases of creative telescoping (smaller certificates? better efficiency?);
 - 2 Bit complexity;
 - 3 Positive characteristic.