Bounds for D-finite Substitution



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f(x) is called algebraic if it satisfies a polynomial equation with polynomial coefficients:

$$p_0(x) + p_1(x)f(x) + \cdots + p_r(x)f(x)^r = 0.$$

Examples:
$$x^5 - 1$$
, $\sqrt{1 - x}$, $\sqrt[3]{x^2 + 2x - 1} - \sqrt{1 + x^9}$, ...

f(x) is called D-finite if it satisfies a linear differential equation with polynomial coefficients:

$$p_1(x)f(x) + p_2(x)f'(x) + \cdots + p_r(x)f^{(r)}(x) = 0.$$

Examples:
$$\log(x)$$
, e^x , $\sqrt{1-x}$, $\log(1-\sqrt{1-x})$, ...

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Abel's theorem:

$$algebraic \Rightarrow D-finite$$

More generally:

$$f(x)$$
 D-finite \wedge $g(x)$ algebraic \Rightarrow $f(g(x))$ D-finite

Example:

$$\begin{array}{ll} f(x) = \log(1-x) & f'(x) + (x-1)f''(x) = 0 & \leftarrow \text{short} \\ g(x) = \sqrt{1-x} & (1-x) - g(x)^2 = 0 & \leftarrow \text{short} \\ h(x) = f(g(x)) & 3h'(x) + (7x-4)h''(x) + (2x^2 - 2x)h'''(x) = 0 \\ \hline & \text{longer} \end{array}$$

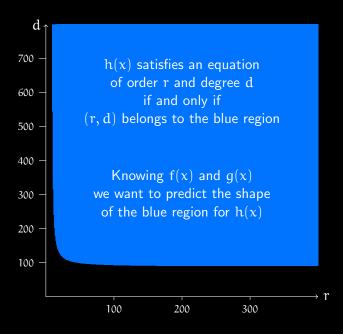
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Main Question:

How big is the equation for h(x) in terms of the sizes of equations for f(x) and g(x)?

Subquestion A: how to measure the size of an equation?

Subquestion B: the equation of h(x) is not unique; which equation is the smallest?



Similar questions have already been addressed for other operations:

- f(x) algebraic $\Rightarrow f(x)$ D-finite [Bostan, Chyzak, Salvy, Lecerf, Schost, 2007]
- f(x,y) hyperexponential $\Rightarrow \int_x f(x,y)$ D-finite [Chen, Kauers, 2012]
- f(x), g(x) D-finite $\Rightarrow f(x) + g(x)$ and f(x)g(x) D-finite [Kauers, 2014]

In all these cases, it is not too hard to get a bound on the order. Also for substitution, this is not too hard.

- If f satisfies a differential equation of order 4, then every higher order derivative of f can be rewritten as a C(x)-linear combination of f, f', f", f".
- If g satisfies a polynomial equation of degree 3, then every higher power of g can be rewritten as a C(x)-linear combination of $1, g, g^2$.
- ullet Moreover, also the derivative g' can be written in this form.

$$\begin{split} h^{(8)}(x) &= \cdots \\ &= (\bigcirc + \bigcirc g(x) + \bigcirc g(x)^2) f(g(x)) \\ &+ (\bigcirc + \bigcirc g(x) + \bigcirc g(x)^2) f'(g(x)) \\ &+ (\bigcirc + \bigcirc g(x) + \bigcirc g(x)^2) f''(g(x)) \\ &+ (\bigcirc + \bigcirc g(x) + \bigcirc g(x)^2) f'''(g(x)) \end{split}$$

 h, h', h'', \ldots all live in a C(x)-vector space of dimension $4 \times 3 = 12$. Therefore, $h, h', \ldots, h^{(12)}$ are linearly dependent over C(x).

Therefore, h satisfies a linear differential equation of order 12.

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More generally:

$$\underbrace{\frac{f(x) \text{ D-finite}}{\text{order } r_f} \land \underbrace{g(x) \text{ algebraic}}_{\text{degree } r_g} \Rightarrow \underbrace{\frac{f(g(x)) \text{ D-finite}}{\text{order} \leq r_f r_g}}$$

There can be equations of order $< r_f r_g$, but generically there aren't.

What about the degrees?

To bound the degrees, equate coefficients with respect to C rather than with respect to C(x) and balance variables and equations.

This requires a more precise understanding of the clouds on the previous slide, which can be obtained by a lengthy calculation.

Theorem [Kauers, Pogudin, 2017]:

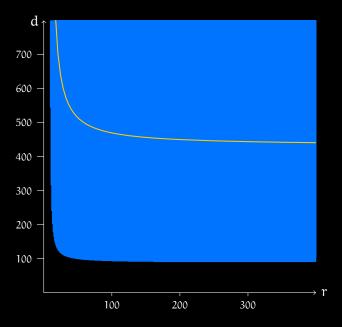
$$\begin{array}{c|c} \underline{f(x) \ D\text{-finite}} \land \underline{g(x) \ algebraic} \Rightarrow \underline{f(g(x)) \ D\text{-finite}} \\ \text{order } r_f & g\text{-degree } r_g & \text{order } \underline{r} \geq r_f r_g \\ x\text{-degree } d_f & x\text{-degree } d_g & x\text{-degree } d \text{ s.t.} \\ d \geqslant \frac{r(3r_g + d_f - 1)d_g r_g r_f}{r + 1 - r_f r_g} \\ \end{array}$$

The bound for the degree d depends rationally on the order r.

We get a hyperbolic curve.



How accurate is it?



Main Question:

Can we do better?

Subquestion A: Can we improve the left part of the curve?

Subquestion B: Can we improve the right part of the curve?

A Degree bounds for the operator of minimal order

• Setting $r = r_f r_a$ into our formula for the curve yields

$$\frac{d}{\leq}(3r_g+d_f-1)d_gr_g^2r_f^2=\mathrm{O}((r_g+d_f)d_gr_g^2r_f^2)$$

• Generalizing a theorem of [Bostan, Chyzak, Salvy, Lecerf, Schost, 2007], we can show that when $r \leq r_g r_f$ is the minimal order and d is the corresponding degree, then

$$\begin{split} \frac{d}{d} & \leq 2r^2d_g - \frac{1}{2}r(r-1) + rd_gr_f(2r_g + d_f - 1) - \frac{1}{2}d_gr_fr_g(r_g - 1) \\ & = \mathrm{O}((r_g + d_f)d_gr_gr_f^2). \end{split}$$

We conjecture that generically the degree is

$$\begin{split} & \frac{d}{d} = r_f^2 (2r_g(r_g-1)+1)d_g + r_f r_g (d_g(d_f+1)+1) + d_f d_g - r_f^2 r_g^2 - r_f d_f d_g \\ & = \mathrm{O}((r_g r_f + d_f) d_g r_g r_f). \end{split}$$

B Order-Degree Curve via Desingularization

- The order-degree curve is uniquely determined by the minimal order operator L ∈ C[x][∂], because all other operators are C(x)[∂]-left multiples of L.
- Left multiples of L may have lower degree than L, for example:

$$(\frac{1}{x}\partial^{2}) \underbrace{((x-1)x\partial + (2-x))}_{\text{order 1}} = \underbrace{(x-1)\partial^{3} + 3\partial^{2}}_{\text{order 3}}$$

$$\underset{\text{degree 2}}{\text{order 1}}$$

 Whether such a degree reduction is possible depends on the removable factors of L. A polynomial p ∈ C[x] is called removable at cost c (from L) if

$$\exists P \in C(x)[\partial] : \deg_{\partial}(c) = P, PL \in C[x][\partial], lc(PL) = lc(L)/p.$$

B Order-Degree Curve via Desingularization

Lemma [Chen, Jaroschek, Kauers, Singer, 2013] Let $L \in C[x][\mathfrak{d}]$, and let p be removable from L at cost c. Let $r \geq \deg_{\mathfrak{d}}(L)$ and

$$\frac{d}{} \geq \deg_x(L) - \left(1 - \frac{c}{r - \deg_{\hat{\sigma}}(L) + 1}\right) \deg_x(p).$$

Then there is a $C(x)[\partial]$ -left multiple of L of order r and degree d.

Theorem [Kauers, Pogudin, 2017]: Generically, h(x) = f(g(x)) satisfies a recurrence of order r and degree $\operatorname{\mathbf{d}}$ if $r \geq r_f r_g$ and

$$\mathbf{d} \geq (d_g(4r_fr_g - 2r_f + d_f) - \delta)\left(1 - \frac{1}{r - r_fr_g + 1}\right) + \delta.$$

Here, δ is a degree bound for the minimal order operator.

