

# Synchronization in MDPs

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Laurent Doyen



Thierry Massart



Highlight 2013, September 19th, Paris

# Spy and factory

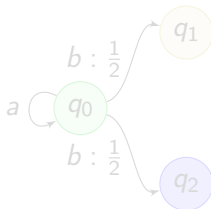
1



factory



thief



# Spy and factory

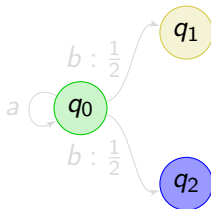
1



factory



thief



# Spy and factory

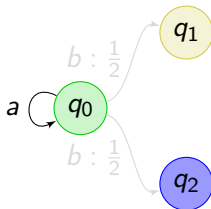
1



factory



thief

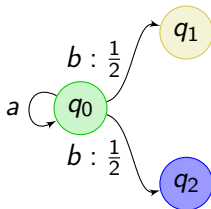




factory



thief



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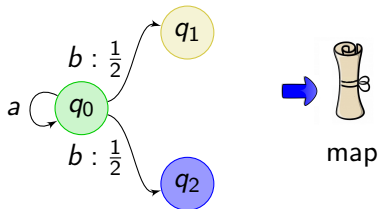
1



factory



thief



# Spy and factory

1



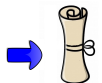
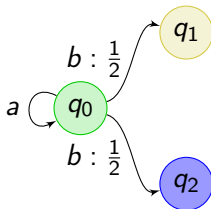
factory



impenetrable  
wall



thief



map

# Spy and factory

1



factory

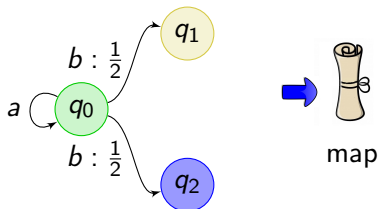


request/reply



thief

clients send physical requests,  
and fix a "time" to pick it up





# Spy and factory

1



factory

thief sends a request as a honest client with a hidden spy robot, plus the “time”



thief

the factory responds exactly at that “time”

It means that

⇒ when robot gets into the factory, it has to accomplish a “mission” at

that exact “time” fixed by thief

nomatter how the random behavior of factory responses

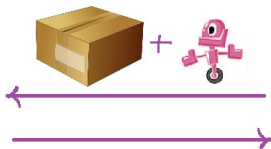
# Spy and factory

1



factory

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thief

the factory responds exactly at that “time”

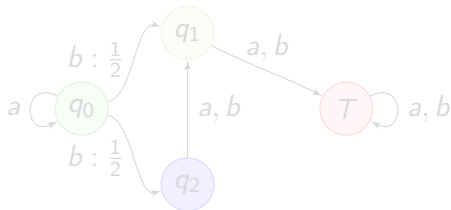
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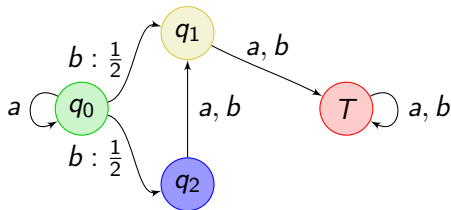
no matter how the random behavior of factory responses

⚡ mission could be arriving in a **target set**  $T$



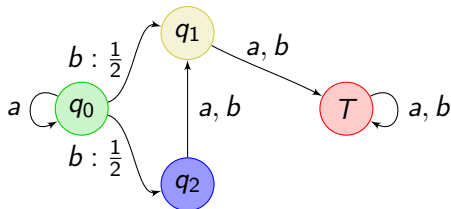
thief



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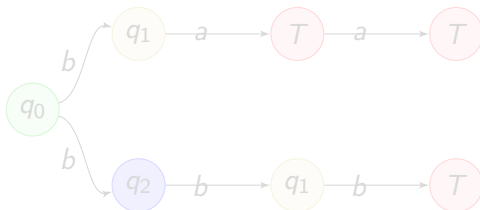


thief

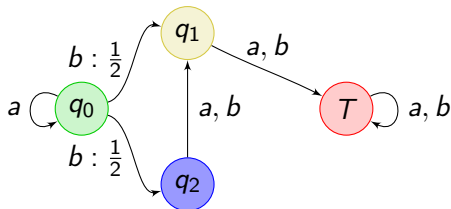
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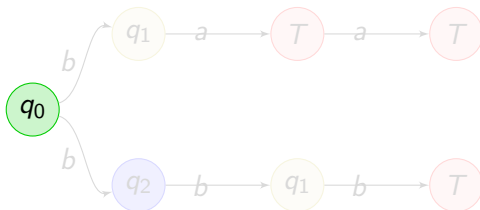
thief  can look  
at the map  and  
see that



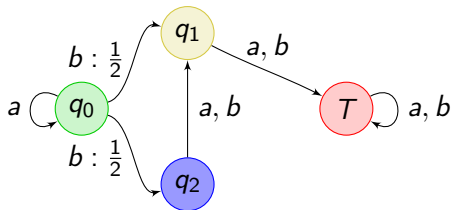
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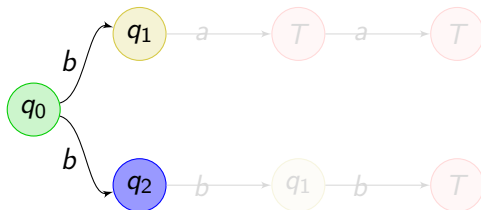
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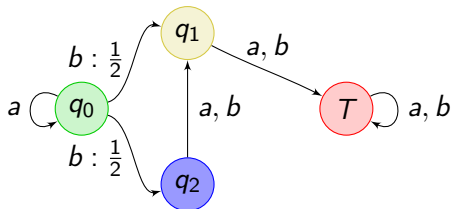
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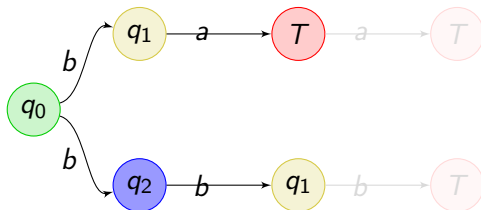
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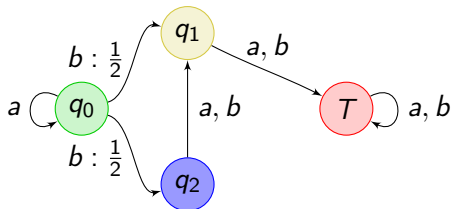




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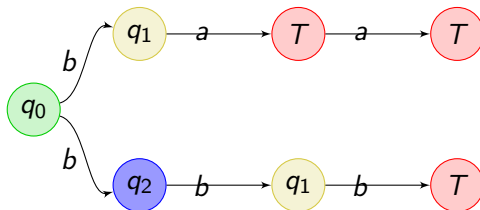




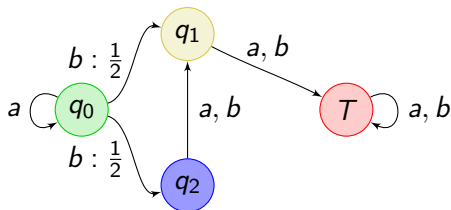
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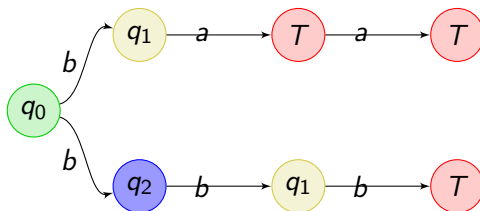
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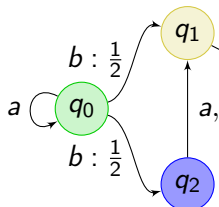




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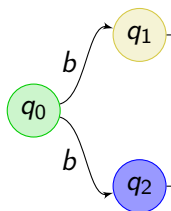



so, he codes the  to send it to factory, and declare **time 3** to pick up

⚡ mission could be arriving in a target synchronization



thief  can look at the map  and see that



The code for the spy robot  is a strategy

$$\alpha : Q^* \rightarrow A$$

MDP is synchronizing in  $T$ , under strategy  $\alpha$  at the step 3:

$$Pr_{\alpha,3}(T) = 1$$

so, he codes the  to send it to factory, and declare time 3 to pick up

# Synchronization vs. Reachability.

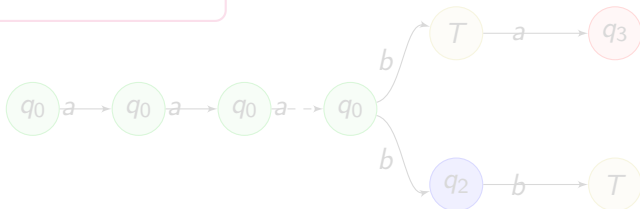
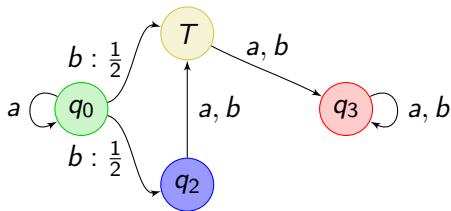
3

⚡ Different from classical reachability!

change the target set

😊 MDP can always reach  $T$

😞 MDP is not synchronizing in  $T$



# Synchronization vs. Reachability.

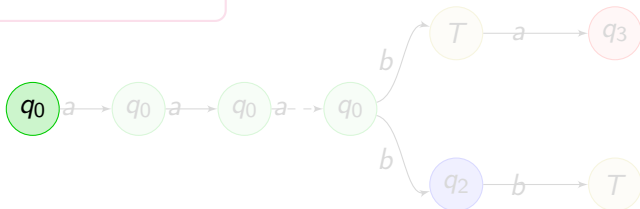
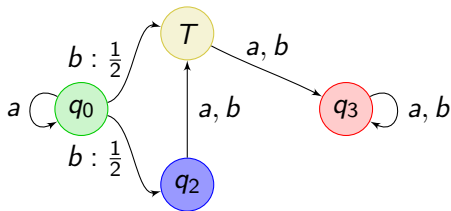
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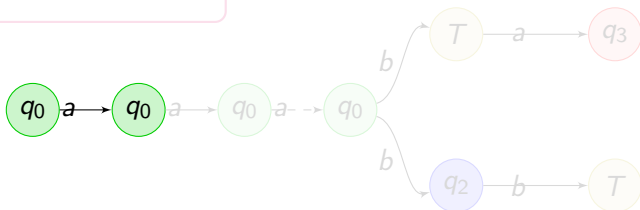
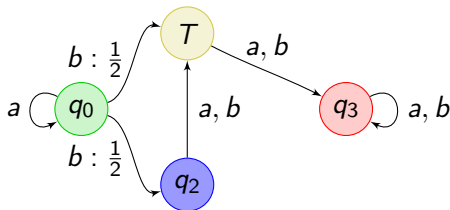
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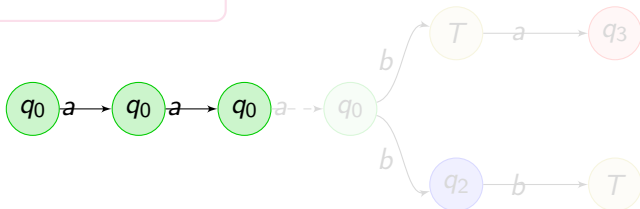
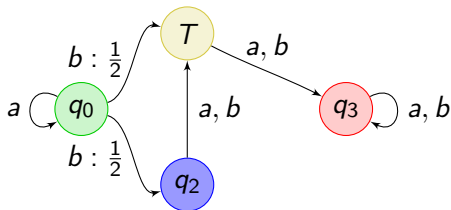
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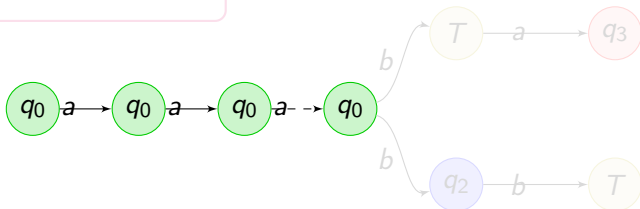
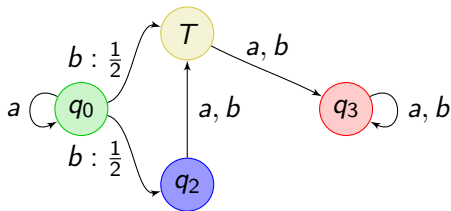
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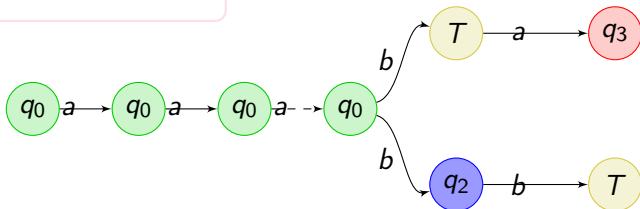
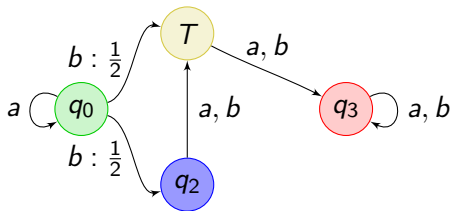
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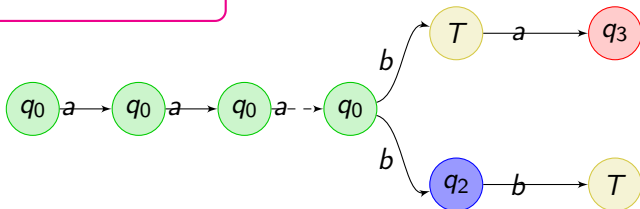
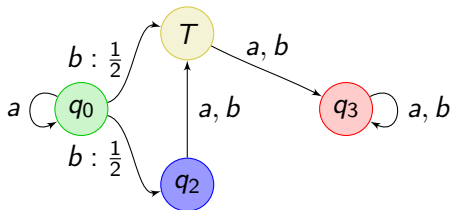
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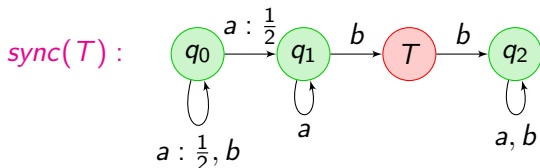
For a target set  $T$ ,  
we say an MDP is **synchronizing** for the winning mode

	sure	almost-sure	limit-sure
Definition	there exists a strategy $\alpha$ and a certain step $n$  $Pr_{\alpha,n}(T) = 1$	there exists a strategy $\alpha$  $\sup_n Pr_{\alpha,n}(T) = 1$	  $\sup_{\alpha,n} Pr_{\alpha,n}(T) = 1$
Complexity	PSPACE-C	PSPACE-C	PSPACE-C
Memory	exponential	infinite	unbounded

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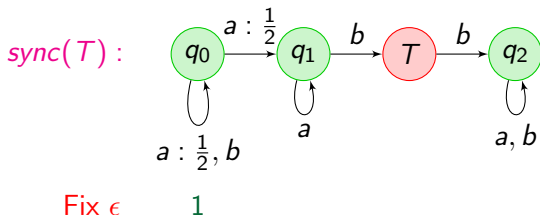
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⚡ Limit-sure synchronization requires unbounded memory!  
(dependent on how close to 1:  $\epsilon$ )

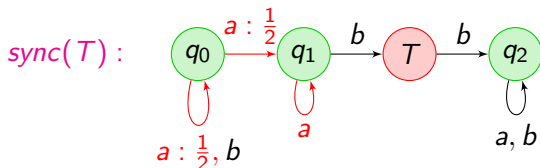


Fix  $\epsilon$       1

⚡ Limit-sure synchronization requires unbounded memory!  
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Fix  $\epsilon$

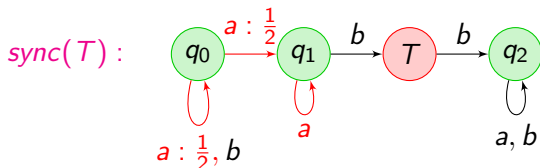
	1	
playing a:	$\frac{1}{2}$	$\frac{1}{2}$

playing a:	$\frac{1}{4}$	$\frac{3}{4}$
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too many times

playing a:	$\epsilon$	$1 - \epsilon$
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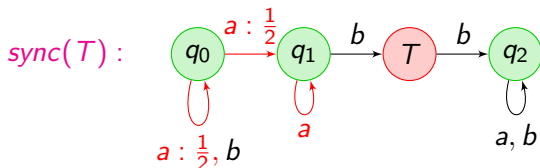
Fix $\epsilon$	1	
playing a:	$\frac{1}{2}$	$\frac{1}{2}$
playing a:	$\frac{1}{4}$	$\frac{3}{4}$
playing a:	$\epsilon$	$1 - \epsilon$

too many times



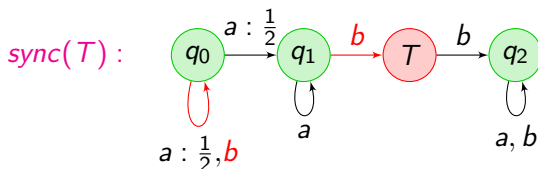


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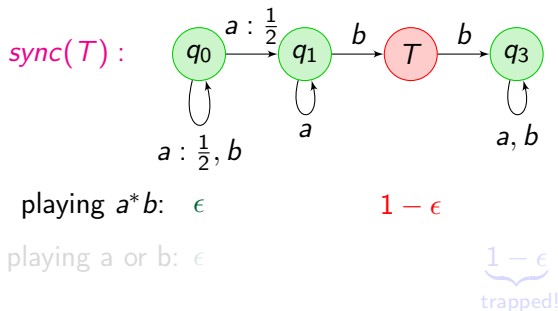


	Fix $\epsilon$	1	
	playing a:	$\frac{1}{2}$	$\frac{1}{2}$
	playing a:	$\frac{1}{4}$	$\frac{3}{4}$
too many times	playing a:	$\epsilon$	$1 - \epsilon$
	playing b:	$\epsilon$	$1 - \epsilon$

# Almost-sure vs. Limit-sure synchronization

6

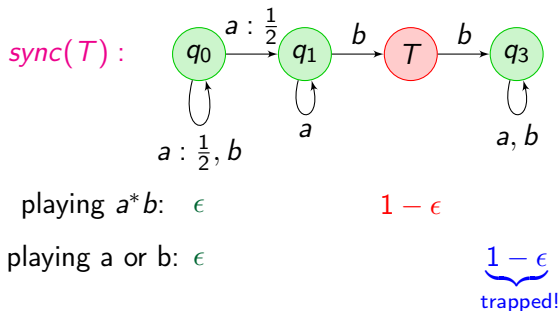
⚡ Almost-sure and limit-sure synchronization are different!



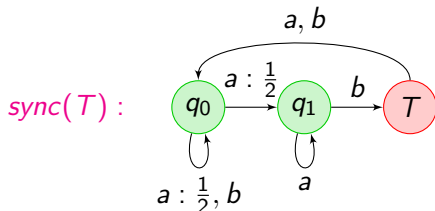
# Almost-sure vs. Limit-sure synchronization

6

⚡ Almost-sure and limit-sure synchronization are different!



⚡ Almost-sure synchronization requires infinite memory strategies!



1

Fix  $\epsilon$  (by  $a^n b$ ):

$\epsilon$

$1 - \epsilon$

Playing b:

1

reset!!

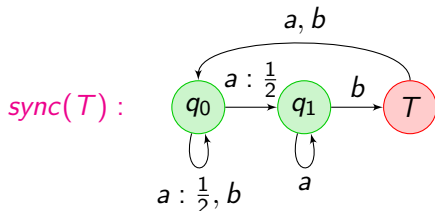
Fix  $\epsilon' < \epsilon$  ( $a^{n+m} b$ ):

$\epsilon'$

$1 - \epsilon'$

Repeating this template forever  $\Rightarrow$  almost-sure

⚡ Almost-sure synchronization requires infinite memory strategies!



1

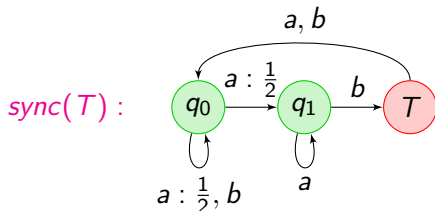
Fix  $\epsilon$  (by  $a^n b$ ):  $\epsilon$   $1 - \epsilon$

Playing b: 1 reset!!

Fix  $\epsilon' < \epsilon$  ( $a^{n+m} b$ ):  $\epsilon'$   $1 - \epsilon'$

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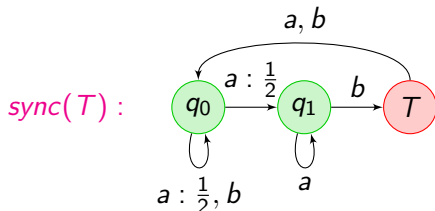
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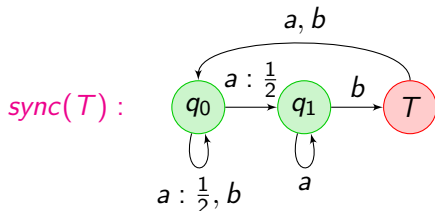
Fix  $\epsilon' < \epsilon$  ( $a^{n+m} b$ ):  $\epsilon'$

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Repeating this template forever  $\Rightarrow$  almost-sure



⚡ Almost-sure synchronization requires infinite memory strategies!



1

Fix  $\epsilon$  (by  $a^n b$ ):

$\epsilon$

$1 - \epsilon$

Playing b:

1

reset!!

Fix  $\epsilon' < \epsilon$  ( $a^{n+m} b$ ):

$\epsilon'$

$1 - \epsilon'$

Repeating this template forever  $\Rightarrow$  almost-sure

# Contributions.

⚡ For a target set  $T$ , to decide whether an MDP is

synchronizing

for the winning mode

	sure	almost-sure	limit-sure
Complexity	PSPACE-C	PSPACE-C	PSPACE-C
Memory	exponential	infinite	unbounded

Questions! ☹ and Comments! ☺