

A Near-Minimal Axiomatisation of ZX-Calculus for Pure Qubit Quantum Mechanics

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Abstract—Recent developments in the ZX-Calculus have resulted in complete axiomatisations first for an approximately universal restriction of the language, and then for the whole language. The main drawbacks were that the axioms that were added to achieve completeness were numerous, tedious to manipulate and lacking a physical interpretation.

We present in this paper two complete axiomatisations for the general ZX-Calculus, that we believe are optimal, in that all their equations are necessary and moreover have a nice physical interpretation. To do so, we introduce the singular-value decomposition of a ZX-diagram, and use it to show that all the rules of the former axiomatisation are provable with the new one.

I. INTRODUCTION

The ZX-Calculus is a powerful graphical language for quantum computing and reasoning [6]. The objects manipulated are open graphs, also called diagrams, that represent quantum evolutions through the standard interpretation. One of the most important features of the language is that the graphs can be considered unoriented, that is, any two isomorphic graphs will yield the same linear map. Isomorphisms between diagrams are not the only transformations that preserve the interpretation though, so the ZX-Calculus comes equipped with a set of axioms: transformations between diagrams that, when applied locally, preserve the interpretation.

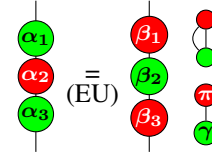
The language is universal: any $2^n \times 2^m$ matrix can be represented by a ZX-diagram with respect to the standard interpretation. Hence, it has already been used in numerous applications [7], ranging from measurement-based quantum computing [11], [16], [22] and quantum codes [10], [5], [13], [14], to protocols [20] and foundations [4], [12]. The language itself can be manipulated through tools such as Quantomatic [26], [28] or PYZX [27].

A broader use of the ZX-Calculus was limited though, because of a question that remained open for a while: completeness. The language would be complete if, for any two diagrams that represent the same quantum evolution, they could be transformed into one another by mere application of the axioms. The question has been answered for gradually more expressive restrictions of the language. In 2014, complete axiomatisations were provided for the stabiliser [2] and the real stabiliser [17], then for the one-qubit Clifford+T case [3]. However, none of these restrictions are approximately universal. The first complete axiomatisation for an approximately universal restriction – many-qubit Clifford+T – was recently provided

[23], and soon followed two complete axiomatisations for the general – universal – ZX-Calculus [19], [24].

Up to the one-qubit Clifford+T case, all the axioms provided were natural and had a relevant interpretation, however, the axiomatisations for (approximately) universal ZX-Calculus introduced rules that are hard to manipulate, mainly because of their size, and that moreover can not be naturally justified.

We give in this paper a simpler axiomatisation of the general ZX-Calculus, and prove that it is complete for pure qubit quantum mechanics. It is basically composed of the axioms that make the Clifford – or stabiliser – fragment complete, and of an additional axiom, denoted (EU):



with a side condition that links the angles on the right to those on the left. In ZX-Calculus, the green node with angle α represents a rotation of angle α around the Z axis (denoted $R_Z(\alpha)$), and the red one a rotation around the orthogonal axis, X (denoted $R_X(\alpha)$). This axiom, which is an application of the Euler angles, essentially gives a normal form for one-qubit unitaries, as a sequences of rotations around the axes X, Z and X again. This equality between diagrams has been used in [30] to prove that the then existing version of ZX-Calculus was not complete, and is part of the axiomatisation of [9].

To prove that the new axiomatisation is complete, we simply derive the rules of the former axiomatisation [24]. However, since all the power of “beyond-Clifford” is contained in the rule (EU), we will end up using it a lot, which would cause a lot of side computation, for the angles on one side of the rule are not defined from the others in a linear fashion. So to avoid having to go through this tedious process, we use a new kind of normal form for ZX-diagrams, which is the graphical version of the singular-value decomposition of a matrix. Hence, instead of showing that a sound equation is derivable, we will show that we can transform the diagrams on both sides into a particular form, which is essentially unique.

We also provide a second axiomatisation, which is not very far from the other. Indeed, in the first, we may notice a rule (HD) that we call *the Euler decomposition of Hadamard*, which essentially gives the unitary normal form

of the Hadamard gate. The second axiomatisation replaces the rules (HD) and (EU) by a single rule that unifies them.

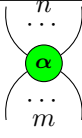







In Section II, we formally introduce the language ZX-Calculus, as well as the two aforementioned axiomatisations, and we discuss their minimality. In Section III, we recover a known complete axiomatisation for the Clifford fragment, hence directly giving us access to already proven lemmas from it. In Section IV, we introduce the singular-value decompositions of cycle-free $0 \rightarrow 1$ and $1 \rightarrow 1$ ZX-diagrams, and show they are essentially unique. Finally, in Section V, we use these decompositions to show the completeness of the axiomatisations for the Clifford+T and for the unrestricted ZX-Calculus. The proofs can be found at arXiv:1812.09114

II. ZX-CALCULUS

In this section, we introduce the ZX-diagrams together with a new simple axiomatisation that we prove complete in the following sections. The definition of the ZX-diagrams and their interpretation is standard.

A. Diagrams and standard interpretation

A ZX-diagram $D : k \rightarrow l$ with k inputs and l outputs is generated by:

$R_Z^{(n,m)}(\alpha) : n \rightarrow m$		$H : 1 \rightarrow 1$	
$R_X^{(n,m)}(\alpha) : n \rightarrow m$		$e : 0 \rightarrow 0$	
$\mathbb{I} : 1 \rightarrow 1$		$\sigma : 2 \rightarrow 2$	
$\epsilon : 2 \rightarrow 0$		$\eta : 0 \rightarrow 2$	

where $n, m \in \mathbb{N}$, $\alpha \in \mathbb{R}$, and the generator e is the empty diagram.

and the two compositions:

- Spatial Composition: for any $D_1 : a \rightarrow b$ and $D_2 : c \rightarrow d$, $D_1 \otimes D_2 : a + c \rightarrow b + d$ consists in placing D_1 and D_2 side by side, D_2 on the right of D_1 .
- Sequential Composition: for any $D_1 : a \rightarrow b$ and $D_2 : b \rightarrow c$, $D_2 \circ D_1 : a \rightarrow c$ consists in placing D_1 on the top of D_2 , connecting the outputs of D_1 to the inputs of D_2 .

The standard interpretation of the ZX-diagrams associates to any diagram $D : n \rightarrow m$ a linear map $\llbracket D \rrbracket : \mathbb{C}^{2^n} \rightarrow \mathbb{C}^{2^m}$ inductively defined as follows:

$$\begin{aligned} \llbracket D_1 \otimes D_2 \rrbracket &:= \llbracket D_1 \rrbracket \otimes \llbracket D_2 \rrbracket & \llbracket D_2 \circ D_1 \rrbracket &:= \llbracket D_2 \rrbracket \circ \llbracket D_1 \rrbracket \\ \llbracket \begin{array}{|c|} \hline \square \\ \hline \end{array} \rrbracket &:= (1) & \llbracket \begin{array}{|c|} \hline | \\ \hline \end{array} \rrbracket &:= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \end{aligned}$$

$$\llbracket \begin{array}{|c|} \hline \square \\ \hline \end{array} \rrbracket := \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \quad \llbracket \begin{array}{|c|} \hline \cup \\ \hline \end{array} \rrbracket := \begin{pmatrix} 1 & 0 & 0 & 1 \end{pmatrix}$$

$$\llbracket \begin{array}{|c|} \hline \times \\ \hline \end{array} \rrbracket := \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \llbracket \begin{array}{|c|} \hline \cap \\ \hline \end{array} \rrbracket := \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\llbracket \begin{array}{|c|} \hline \bullet \\ \hline \end{array} \rrbracket := (1 + e^{i\alpha})$$

$$\llbracket \begin{array}{|c|} \hline n \\ \vdots \\ \bullet \\ \vdots \\ m \\ \hline \end{array} \rrbracket := 2^m \begin{pmatrix} 1 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 & 0 \\ 0 & 0 & \cdots & 0 & e^{i\alpha} \end{pmatrix}$$

For any $n, m \geq 0$ and $\alpha \in \mathbb{R}$:

$$\llbracket \begin{array}{|c|} \hline n \\ \vdots \\ \bullet \\ \vdots \\ m \\ \hline \end{array} \rrbracket = \llbracket \begin{array}{|c|} \hline \square \\ \hline \end{array} \rrbracket^{\otimes m} \circ \llbracket \begin{array}{|c|} \hline n \\ \vdots \\ \bullet \\ \vdots \\ m \\ \hline \end{array} \rrbracket \circ \llbracket \begin{array}{|c|} \hline \square \\ \hline \end{array} \rrbracket^{\otimes n}$$

(where $M^{\otimes 0} = (1)$ and $M^{\otimes k} = M \otimes M^{\otimes k-1}$ for $k \in \mathbb{N}^*$).

To simplify, the red and green nodes will be represented empty when holding a 0 angle:

$$\begin{pmatrix} \vdots \\ \bullet \\ \vdots \end{pmatrix} := \begin{pmatrix} \vdots \\ 0 \\ \vdots \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} \vdots \\ \bullet \\ \vdots \end{pmatrix} := \begin{pmatrix} \vdots \\ 0 \\ \vdots \end{pmatrix}$$

We call a *scalar* any $0 \rightarrow 0$ ZX-diagram. Indeed the standard interpretation of such a diagram is a 1×1 matrix, equivalent to a scalar. We call a $0 \rightarrow n$ ZX-diagram a *state on n qubits*, since its underlying matrix is a column vector.

ZX-Diagrams are universal [6]

$$\forall A \in \mathbb{C}^{2^n} \times \mathbb{C}^{2^m}, \quad \exists D : n \rightarrow m, \quad \llbracket D \rrbracket = A$$

However, it is customary to restrict the language to a countable or finite set of angles. Some of these restrictions, or fragments, correspond to well-known restrictions of quantum computing: The $\frac{\pi}{2}$ -fragment – the restriction where all the angles are multiples of $\frac{\pi}{2}$ – corresponds to Clifford; while the $\frac{\pi}{4}$ -fragment corresponds to Clifford+T. In the following, we may refer to the $\frac{\pi}{2}$ -fragment using the term Clifford, and similarly for the $\frac{\pi}{4}$ -fragment.

B. Calculus

The diagrammatic representation of a matrix is not unique in the ZX-Calculus. As a consequence the language comes with a set of axioms. Additionally to the axioms of the language described in Figure 1, one can:

- bend any wire of a ZX-diagram at will, without changing its semantics. These transformations fall under the

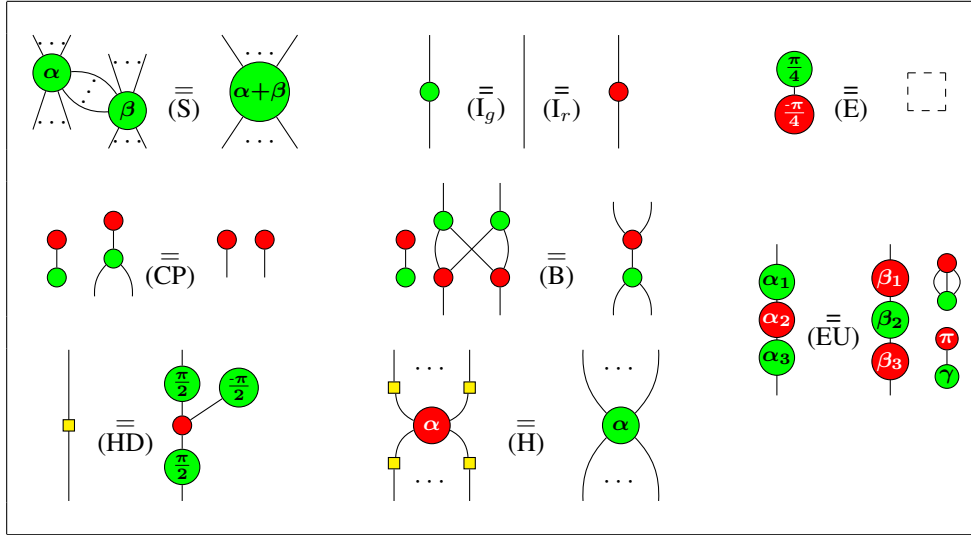
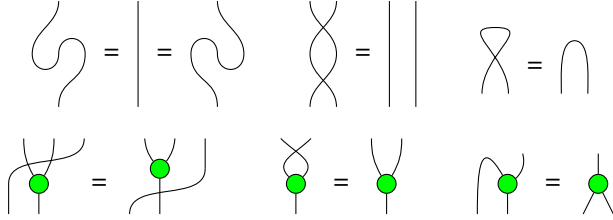


Fig. 1. Set of rules ZX for the ZX-Calculus with scalars. The right-hand side of (E) is an empty diagram. (...) denote zero or more wires, while (...) denote one or more wires. In rule (EU), $\beta_1, \beta_2, \beta_3$ and γ can be determined as follows: $x^+ := \frac{\alpha_1 + \alpha_3}{2}$, $x^- := x^+ - \alpha_3$, $z := \cos(\frac{\alpha_2}{2}) \cos(x^+) + i \sin(\frac{\alpha_2}{2}) \cos(x^-)$ and $z' := \cos(\frac{\alpha_2}{2}) \sin(x^+) - i \sin(\frac{\alpha_2}{2}) \sin(x^-)$, then $\beta_1 = \arg z + \arg z'$, $\beta_2 = 2 \arg(i + \frac{z}{z'})$, $\beta_3 = \arg z - \arg z'$, $\gamma = x^+ - \arg(z) + \frac{\alpha_2 - \beta_2}{2}$ where by convention $\arg(0) := 0$ and $z' = 0 \implies \beta_2 = 0$.

paradigm **Only Connectivity Matters**, some of which are:

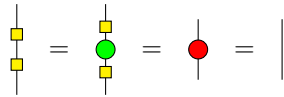


- apply the axioms to sub-diagrams. If $ZX \vdash D_1 = D_2$ then, for any diagram D with the appropriate number of inputs and outputs:

- $ZX \vdash D_1 \circ D = D_2 \circ D$
- $ZX \vdash D \circ D_1 = D \circ D_2$
- $ZX \vdash D_1 \otimes D = D_2 \otimes D$
- $ZX \vdash D \otimes D_1 = D \otimes D_2$

where $ZX \vdash D_1 = D_2$ means that D_1 can be transformed into D_2 using the axioms of the ZX-Calculus.

- colour-swap equalities. Indeed, thanks to (H), and since



it is fairly easy to see that if an equation is derivable, its colour-swapped version also is.

All the axioms of Figure 1, but (EU), are standard in the ZX-calculus. Roughly speaking: (S) and (I) correspond to the axiomatisation of an orthonormal basis [8], each color being associated with an orthonormal basis; (CP) and (B) capture the fact that the two bases are strongly complementary [6]; (H) means that Hadamard can be used to exchange the colours and (HD) means that Hadamard can be decomposed using

$\frac{\pi}{2}$ -rotations [15]; (E) states that some particular scalars (ZX-diagram with no input/output) can vanish, which means that their interpretation is one [25]. In the following we investigate the properties of (EU).

C. The Euler Angles

The rule (EU) is really all about unitaries. Indeed, we have the following result:

Proposition 1. *Any one-qubit unitary can be decomposed as $e^{i\gamma} R_Z(\alpha_3) R_X(\alpha_2) R_Z(\alpha_1)$, which can be represented as a ZX-diagram as:*



If the unitary is not diagonal or anti-diagonal (i.e. if $\alpha_2 \neq 0 \pmod{\pi}$), then this decomposition can be made unique if we impose $\alpha_1 \in [0, \pi)$

In 1775, Euler proved what is now called Euler's rotation theorem [18], stating that there are several ways to decompose a rotation into several rotations around elementary axes. In quantum mechanics, a consequence is that any unitary operator on one qubit can be seen as either a composition of rotations around Z, X, Z; or around X, Z, X. On the one hand, the rule (HD) says – in a distorted, ZX-style way – that the Hadamard gate can be decomposed as a series of rotations, while on the other hand, the rule (EU) gives the equality between two




Diagram illustrating a vertical stack of three circles labeled α_1 , α_2 , and α_3 . The top and bottom circles are green, and the middle circle is red. To the right of the stack is the label $(\overline{\text{EU}})$.

can be replaced by

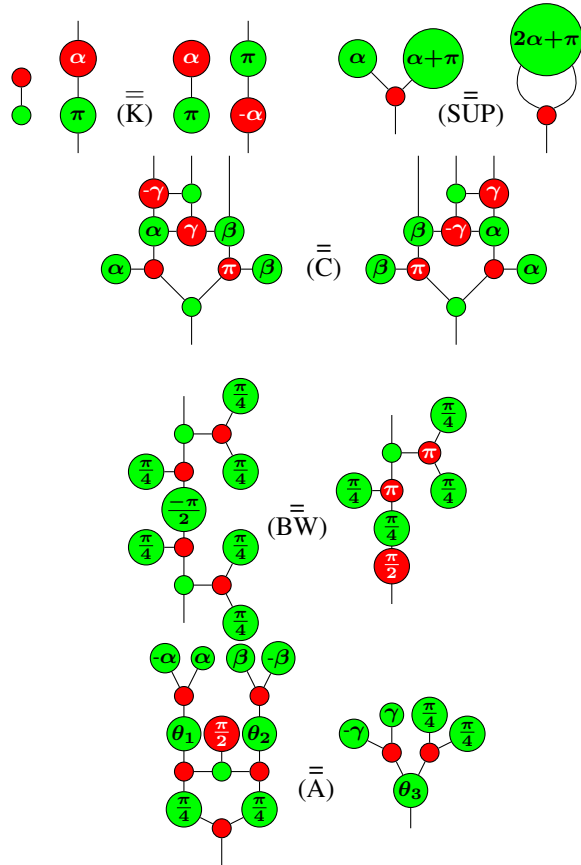
$$\text{where } \begin{cases} x^+ := \frac{\alpha_1 + \alpha_2}{2} & x^- := x^+ - \alpha_2 \\ z := -\sin(x^+) + i \cos(x^+) \\ z' := \cos(x^+) - i \sin(x^+) \\ \beta_1 = \arg z + \arg z \\ \beta_2 = 2 \arg(i + \frac{z}{z'}) \\ \beta_3 = \arg z - \arg z' \\ \gamma = x^+ - \arg(z) + \frac{\pi - \beta_2}{2} \end{cases}$$

As a consequence, the axiomatisation given in Figure 2 is complete for universal quantum mechanics.

On the one hand, this new axiomatisation is one axiom shorter, and (EU') and (IV) (Figure 2) can be considered simpler than (EU) and (E) (Figure 1). On the other hand, the axiomatisation in Figure 1 has the nice property that it suffices to remove (EU) and (E) to get a complete axiomatisation for the scalar-free Clifford fragment. Moreover, (EU) is arguably more natural, and has already been given for instance in [9].

The following of the paper is dedicated to the proof of Theorem 2. Since [19], [24] provided us with two complete axiomatisations for the general ZX-Calculus, all we have to do is prove all the equations used as axioms in either one of these two axiomatisations. As the axiomatisation in [19] requires additional generators and more axioms, we will use the axiomatisation of [24] as a reference. It consists of all the axioms of Figure 1 but (EU), together with the following axioms, that we call obsolete, as we are proving in the following that they can be derived using the rule (EU):

Obsolete ZX-rules



$$2e^{i\theta_3} \cos(\gamma) = e^{i\theta_1} \cos(\alpha) + e^{i\theta_2} \cos(\beta)$$

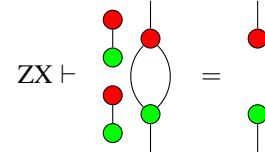


Remark 4. The last two equations, (ZO) and (IV'), are actually derivable from (K), (SUP) and the Clifford axiomatisation [25]. However, they are given here, because together with (S), (I), (CP), (B), (HD) and (H), they make the Clifford fragment complete, which will be our first milestone.

III. CLIFFORD

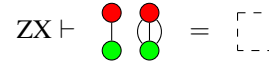
As we just said, a first and easy step to do is to show that we can recover the rules that are known to make the language complete for Clifford [1]. This will allow us to freely use in the following all the equations of the $\frac{\pi}{2}$ -fragment that are sound. We already have most of these rules that make the ZX-calculus complete for Clifford. We only lack two: the *zero* (ZO) and the *inverse* (IV') rules. A first very well known lemma we will use for both proofs is the Hopf law:

Lemma 5 (Hopf Law).



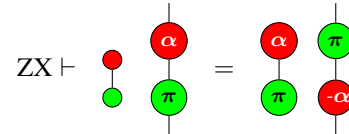
From there, it is fairly easy to recover the inverse rule:

Proposition 6. The inverse rule is derivable:



To prove the zero rule, we will use another well known equation, called π -commutation, which is also one of the now obsolete rules.

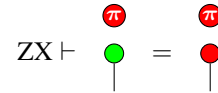
Proposition 7. The π -commutation is derivable:



Remark 8. This is one of the few applications of (EU) that still preserves linearity.

Now, with some effort, the rule (ZO), which only deals with null diagrams, can be recovered:

Proposition 9. The zero rule is derivable:



As a result:

Theorem 10. For any diagrams D_1, D_2 of the $\frac{\pi}{2}$ -fragment:

$$\llbracket D_1 \rrbracket = \llbracket D_2 \rrbracket \iff \text{ZX} \vdash D_1 = D_2$$

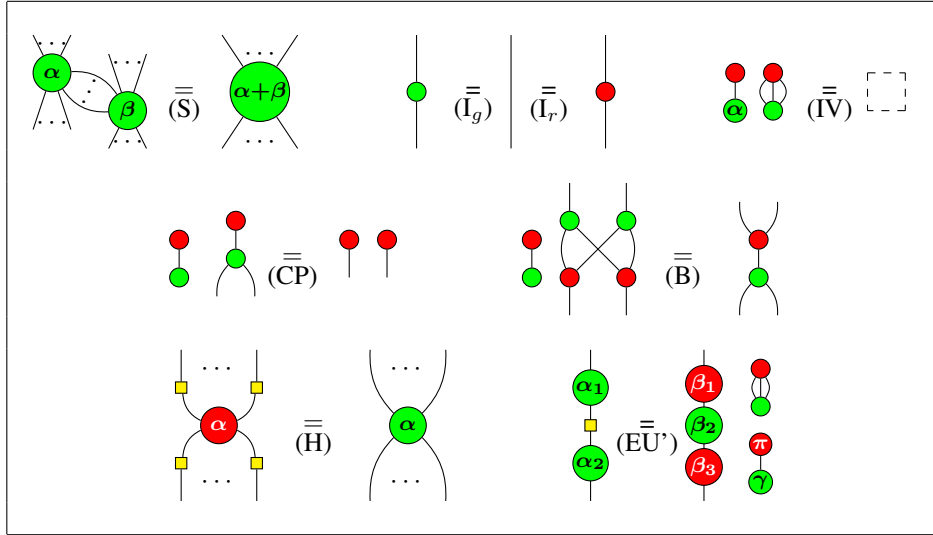
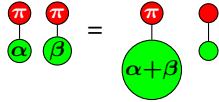


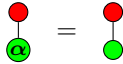
Fig. 2. Set of rules ZX' for the ZX-Calculus with scalars. The right-hand side of (E) is an empty diagram. (...) denote zero or more wires, while (· ·) denote one or more wires. In rule (EU'), $\beta_1, \beta_2, \beta_3$ and γ can be determined as follows: $x^+ := \frac{\alpha_1 + \alpha_2}{2}$, $x^- := x^+ - \alpha_2$, $z := -\sin(x^+) + i \cos(x^-)$ and $z' := \cos(x^+) - i \sin(x^-)$, then $\beta_1 = \arg z + \arg z'$, $\beta_2 = 2 \arg(i + \frac{z}{z'})$, $\beta_3 = \arg z - \arg z'$, $\gamma = x^+ - \arg(z) + \frac{\pi - \beta_2}{2}$ where by convention $\arg(0) := 0$ and $z' = 0 \implies \beta_2 = 0$.

From this first milestone, we get all the sound equations in Clifford, but actually also a bit more. For instance, the following lemmas are known to be derivable from the Clifford axiomatisation (see Appendix):

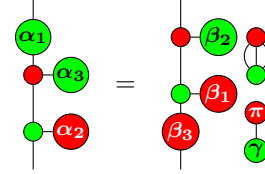
Lemma 11.



Lemma 12.



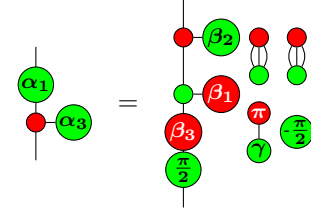
Lemma 13.



where $\beta_1, \beta_2, \beta_3, \gamma$ can be determined as in rule (EU).

In a particular case, it implies:

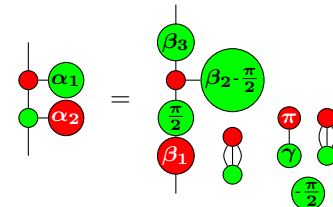
Corollary 14.



where $\beta_1, \beta_2, \beta_3, \gamma$ can be determined as in rule (EU) with $\alpha_2 \leftarrow \frac{\pi}{2}$.

We can also derive a kind of inverse operation:

Lemma 15.



where $\beta_1, \beta_2, \beta_3, \gamma$ can be determined as in rule (EU) applied with the angles $\alpha_2 \leftarrow \alpha_2 + \frac{\pi}{2}$ and $\alpha_3 \leftarrow \frac{\pi}{2}$.

IV. SINGULAR VALUE DECOMPOSITIONS

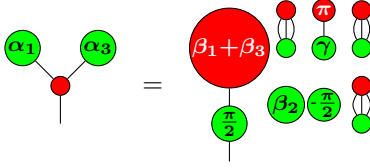
The next step is logically to get the completeness for Clifford+T quantum mechanics, i.e. the completeness of the $\frac{\pi}{4}$ -fragment of the ZX-calculus. Now that we are seeking to prove equations that are out of Clifford, we will begin to use (EU) to its full potential. However, we would like, as much as possible, to avoid computing the angles, because, since we work on the problem of completeness, we need to *formally* prove the equality between two diagrams, and hence to formally write what the angles resulting from (EU) are, which becomes tedious after a few number of application of the rule.

To simplify this task, instead of showing directly that two diagrams can be turned into one another, we will define a normal form for them, show that it is unique, and show that there is an algorithm to turn them in this normal form.

First, we show another version of the rule (EU) with dangling branches:

Then, we show that any diagram in the form of the left hand side of (SUP)– but with arbitrary angles – can be transformed in a state with no branching:

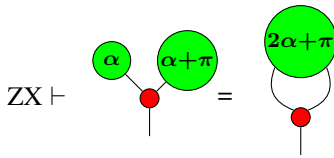
Lemma 16.



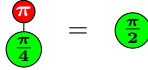
where $\beta_1, \beta_2, \beta_3, \gamma$ can be determined as in rule (EU) with $\alpha_2 \leftarrow \frac{\pi}{2}$.

Now, by specialising the angles to α and $\alpha + \pi$, we shall recover (SUP):

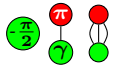

Proposition 17. *The supplementarity is derivable:*



Remark 18. *The supplementarity allows us to prove:*



which, coupled with Lemma 11 and Proposition 6, implies

that  can be replaced by  in the last three lemmas.

So far, we have proven all the obsolete equations that do not really need a unique normal form. For the rest, we present the singular-value decomposition of a matrix, and introduce it to ZX-diagrams.

Definition 19. *We call a singular value decomposition (SVD) of a matrix a decomposition of the form*

$$M = U\Sigma V^\dagger$$

where U and V are unitary, and Σ is diagonal. Notice that M needs not be square (in this case Σ has the same dimensions as M).

To justify the use of SVDs, we give some of their interesting properties [21]:





Proposition 20. *The SVD $M = U\Sigma V^\dagger$ of a matrix M has the following properties:*

- It exists for all M
- Σ can be made unique if we require that its diagonal entries are decreasing non-negative real numbers
- U and V are not unique in general, though:
- If M is square with distinct and non-zero singular values, then U and V are essentially unique:

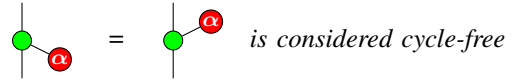
$$U\Sigma V^\dagger = U'\Sigma V'^\dagger \iff (\exists d, (U' = Ud) \wedge (V' = Vd))$$

where d is diagonal with diagonal entries some roots of unity.

Even though the singular-value decomposition is relevant for any diagram, we are only going to give its derivation for a particular family of diagrams:

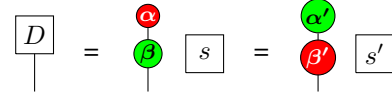
Definition 21. *We call a cycle-free diagram a diagram composed only of , , ,  where $n \in \mathbb{N}$ and $\alpha \in \mathbb{R}$.*

Remark 22. *Some diagrams that do not strictly follow the conditions of the previous definition will still be considered cycle-free if they are equal to a cycle-free diagram by mere application of the “only connectivity matters” paradigm, i.e. if they are isomorphic to a cycle-free diagram. E.g.:*



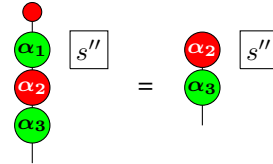
We can now easily give a normal form for one-qubit states, using the SVD of the underlying matrix.

Proposition 23 (SVD of a One-Qubit State). *Any cycle-free state $D : 0 \rightarrow 1$ can be put in the following forms:*



where $\beta, \beta' \in [0, \pi)$, and where s and s' are $0 \rightarrow 0$ diagrams, i.e. scalars. We call these two forms respectively SVD_g and SVD_r .

To understand where it comes from, notice that if $M \in \mathbb{C}^2 \times \mathbb{C}$, with $U\Sigma V^\dagger$ its SVD, then U is a 2×2 unitary, and V^\dagger is a 1×1 unitary. A 2×2 unitary can be expressed as in Proposition 1, while a 1×1 unitary is merely a global phase i.e. a root of unity. Σ is of the form $\begin{pmatrix} s \\ 0 \end{pmatrix} = s' \begin{pmatrix} \sqrt{2} \\ 0 \end{pmatrix}$ (where $s = 0$ if $M = 0$). Hence one of its representations is:



thanks to some rules of ZX, and where s'' is the aggregation of the scalars produced by U , Σ and V^\dagger .

Proposition 24 (SVDs of states are essentially unique). *If*

$D_1 = \begin{array}{c} \text{red circle } \alpha_1 \\ \text{green circle } \beta_1 \end{array} \boxed{s_1}$ and $D_2 = \begin{array}{c} \text{red circle } \alpha_2 \\ \text{green circle } \beta_2 \end{array} \boxed{s_2}$ are in SVD, and if $\llbracket D_1 \rrbracket = \llbracket D_2 \rrbracket \neq 0$, then either:

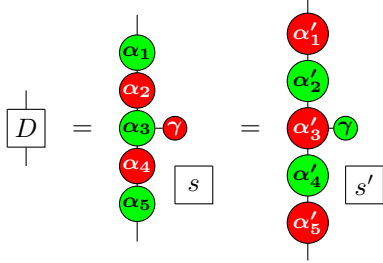
- $\alpha_1 = \alpha_2 \bmod 2\pi$ and $\alpha_i = 0 \bmod \pi$
- $\alpha_1 = \alpha_2$ and $\beta_1 = \beta_2$

Notice that in the first \bullet , β_1 and β_2 are unconstrained. Indeed, in this case, the SVD decomposition is not unique, but


it can be reduced to a form where the angles β_i are absent, making them unique. Except for these singular values of α_i , the SVD form is unique.

We can have basically the same results for $1 \rightarrow 1$ operators:

Proposition 25 (SVD of a $1 \rightarrow 1$ diagram). *Any cycle-free diagram $D : 1 \rightarrow 1$ can be written in the forms:*

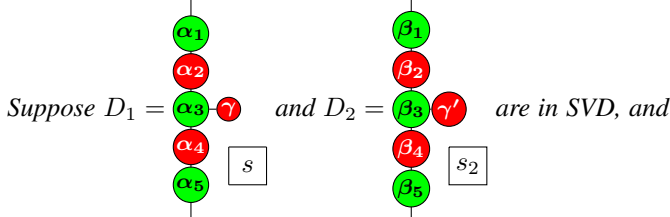


where $\gamma \in [0, \frac{\pi}{2}]$, and $\alpha_1, \alpha_5, \alpha'_1, \alpha'_5 \in [0, \pi)$. We denote the two forms respectively SVD_g and SVD_r .

Indeed, the diagram  has interpretation (up to a scalar) $\begin{pmatrix} 1 & 0 \\ 0 & \tan(\frac{\gamma}{2}) \end{pmatrix}$, and hence can be used to represent Σ in the SVD of $\llbracket D \rrbracket$. U and V^\dagger here are 2×2 unitaries, and so can be represented as in Proposition 1. Using (S) to merge the green nodes gives the above form.

Remark 26. We gave two conventions for the SVDs of $0 \rightarrow 1$ and $1 \rightarrow 1$ diagrams. These two depend on the basis in which we consider the decomposition. SVD_g corresponds to the computational basis, while SVG_r corresponds to the diagonal basis. If $M = U\Sigma V^\dagger$ with Σ diagonal in the computational basis, $M = (UH) \cdot H\Sigma H \cdot (VH)^\dagger$.

Proposition 27 ($1 \rightarrow 1$ SVDs are essentially unique).



that $\llbracket D_1 \rrbracket = \llbracket D_2 \rrbracket \neq 0$. Then, either:

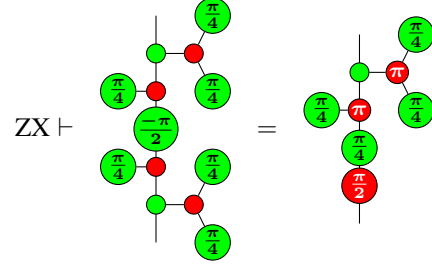
- $\gamma = \gamma' = 0$
- $\gamma = \gamma' = \frac{\pi}{2}$
- $\alpha_i = \beta_i$ and $\gamma = \gamma'$

Again, the SVD form can be not unique, but only for singular values of γ and γ' .

V. CLIFFORD+T AND BEYOND

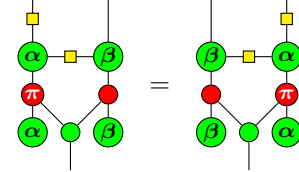
The point now is to exploit the SVD of ZX-diagrams and their uniqueness. A rule that can directly use these results is (BW), because the diagrams on both sides of the equation are cycle-free:

Proposition 28.



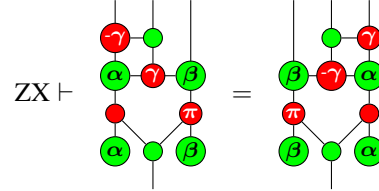
The results on SVDs can not be directly used to prove the equation (C) though, for its diagrams have 4 inputs/outputs, and have a cycle. However, the SVDs can be used to prove a first intermediary result:

Lemma 29.



From which we can deduce the equation (C) itself:

Proposition 30.



Remark 31. (C) can be derived using only Lemma 29 and the Clifford rules. However, the provided proof requires using half angles. Hence, whenever the considered fragment contains all its half angles, the equation in Lemma 29 should be preferred to (C).

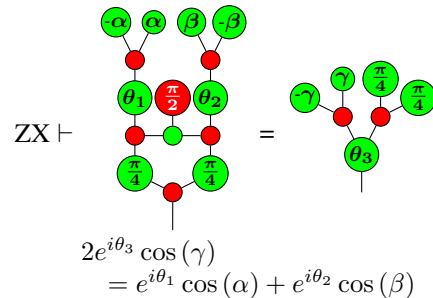
We have derived all the rules necessary for the completeness of the Clifford+T fragment of the ZX-Calculus, which means:

Theorem 32. For any diagrams D_1, D_2 of the $\frac{\pi}{4}$ -fragment:

$$\llbracket D_1 \rrbracket = \llbracket D_2 \rrbracket \iff \text{ZX} \vdash D_1 = D_2$$

Finally, it remains to derive the equation (A). Notice that the diagram on the left hand side contains a cycle, which implies we can not use the results on SVDs. However, the cycle can be easily removed, and we are able to prove:

Proposition 33.



This last proposition ends the proof of Theorem 2. ■

VI. DISCUSSION AND FURTHER WORK

We have provided two simple but complete axiomatisations of the ZX-Calculus for universal quantum mechanics. By doing so, we have restored intuitiveness – one of its the first aims – to the language (at least on the structural level, computing the angles in (EU) remains tedious if done formally). This step forward should simplify axiom-related problems such as verification or compilation. Indeed, the simplified axiomatisation allows for simplified derivations (using (EU) is arguably easier than using (A)). This should also simplify the search for strategies of rewriting.

To simplify the task of proving the derivability of equations, we introduced singular-value decomposition of $0 \rightarrow 1$ and $1 \rightarrow 1$ diagrams, and proved that there exists an algorithm to turn any $0 \rightarrow 1$ and $1 \rightarrow 1$ cycle-free diagram into its SVD form. We did not need the SVD form for diagrams *with* cycle, and leave as a further development the extension of the algorithm to arbitrary $0 \rightarrow 1$ and $1 \rightarrow 1$ diagrams, which should be possible by completeness and universality.

We did not need to define the SVD form for larger diagrams either. A problem would arise in ZX, for instance for a diagram with 3 inputs/outputs: do we decompose the diagram as a $0 \rightarrow 3$, or a $1 \rightarrow 2$ diagram and then use the map/state duality? This would result in two completely different decompositions. Still, defining SVDs for diagrams of any arity could prove interesting.

Concerning the result itself, we have proven that, in ZX-Calculus:

$$\begin{array}{c} \text{many-qubit Clifford completeness} \\ + \\ \text{completeness for 1-qubit unitaries} \\ \hline = \\ \text{many-qubit completeness} \end{array}$$

This formulation is a bit excessive, since we actually have several rules that operate beyond the Clifford fragment, namely (S) and (H), where the angles can take any value in \mathbb{R} – and this feature is actually needed for the completeness. Still, since it is not absurd to imagine we can always find similar rules for the considered language, this raises two questions:

- Is it true for fragments of the ZX-Calculus?
The answer in general is no. Indeed, in the case of Clifford+T, the axiomatisation for Clifford is enough to get the 1-qubit completeness [3]. However, it has been proven that rules (SUP) and (E) are necessary [25], [29]. Hence, the previous statement does not stand for Clifford+T.
- How far from this statement are we in other languages?
For instance, we know a complete presentation for the many-qubit Clifford fragment of quantum circuits [31]. Moreover, there is a strong link between circuits and ZX (it is easy to transform a circuit into an equivalent ZX-diagram, although the other way round is not always

possible), and the rule (EU) has an obvious equivalent in circuits, and is the only needed axiom for 1-qubit completeness. So what do we lack to get universal completeness?

ACKNOWLEDGEMENTS

The author would like to thank Emmanuel Jeandel, Simon Perdrix and Titouan Carette for fruitful discussions and feedback. The author acknowledges support from the projects ANR-17-CE25-0009 SoftQPro, ANR-17-CE24-0035 VanQuTe, PIA-GDN/Quantex, and STIC-AmSud 16-STIC-05 FoQCoSS. All diagrams were written with the help of TikZit.

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