# An Introduction to Decidability of Higher-Order Matching

Colin Stirling cps@inf.ed.ac.uk

LFCS School of Informatics University of Edinburgh

GALOP, London, 18th July 2013

- ▶ Types  $A := \mathbf{0} \mid A \rightarrow A$ 
  - ▶ **0** single base type (for simplicity)
  - ▶  $A \rightarrow B$  type of functions from A to B

- ▶ Types  $A := \mathbf{0} \mid A \rightarrow A$ 
  - ▶ 0 single base type (for simplicity)
  - ▶  $A \rightarrow B$  type of functions from A to B
- ▶ If  $A \neq \mathbf{0}$  then A has form  $A_1 \rightarrow \ldots \rightarrow A_n \rightarrow \mathbf{0}$  abbreviated to  $(A_1, \ldots, A_n, \mathbf{0})$

- ▶ Types  $A ::= \mathbf{0} \mid A \rightarrow A$ 
  - ▶ 0 single base type (for simplicity)
  - ▶  $A \rightarrow B$  type of functions from A to B
- ▶ If  $A \neq \mathbf{0}$  then A has form  $A_1 \rightarrow \ldots \rightarrow A_n \rightarrow \mathbf{0}$  abbreviated to  $(A_1, \ldots, A_n, \mathbf{0})$
- ▶ Order of **0** is 1

- ▶ Types  $A ::= \mathbf{0} \mid A \rightarrow A$ 
  - ▶ 0 single base type (for simplicity)
  - ▶  $A \rightarrow B$  type of functions from A to B
- ▶ If  $A \neq \mathbf{0}$  then A has form  $A_1 \rightarrow \ldots \rightarrow A_n \rightarrow \mathbf{0}$  abbreviated to  $(A_1, \ldots, A_n, \mathbf{0})$
- ▶ Order of **0** is 1
- ▶ Order of  $(A_1, ..., A_n, \mathbf{0})$  is k + 1 where k is maximum of orders of  $A_i$ s

# Terms of simply type $\lambda$ -calculus

Variables and constants each have a unique type (Church style)

### Terms of simply type $\lambda$ -calculus

#### Variables and constants each have a unique type (Church style)

- 1. if x(f) has type A then x : A(f : A)
- 2. if t: B and x: A then  $\lambda x.t: A \rightarrow B$
- 3. if  $t: A \rightarrow B$  and u: A then (tu): B

# Terms of simply type $\lambda$ -calculus

#### Variables and constants each have a unique type (Church style)

- 1. if x(f) has type A then x : A(f : A)
- 2. if t: B and x: A then  $\lambda x.t: A \rightarrow B$
- 3. if  $t: A \rightarrow B$  and u: A then (tu): B
- order of t : A is order A
- closed t : A no free variables
- ightharpoonup t, t': A are  $\alpha$ -equivalent renamings of each other

#### Dynamics: reduction

$$\begin{array}{lll} (\beta) & (\lambda x.t)v \to_{\beta} t\{v/x\} & \{\cdot/\cdot\} \text{ Substitution} \\ (\eta) & \lambda x.(tx) \to_{\eta} t & x \text{ not free in } t \end{array}$$

#### Dynamics: reduction

(
$$\beta$$
)  $(\lambda x.t)v \rightarrow_{\beta} t\{v/x\}$  {·/·} Substitution ( $\eta$ )  $\lambda x.(tx) \rightarrow_{\eta} t$   $x$  not free in  $t$ 

#### ► Facts

Strong normalisation and confluence (of  $\rightarrow_{\beta}$ ,  $\rightarrow_{\eta}$ ,  $\rightarrow_{\beta\eta}$ )

### Dynamics: reduction

$$\begin{array}{lll} (\beta) & (\lambda x.t)v \to_{\beta} t\{v/x\} & \{\cdot/\cdot\} \text{ Substitution} \\ (\eta) & \lambda x.(tx) \to_{\eta} t & x \text{ not free in } t \end{array}$$

- ► Facts
  Strong normalisation and confluence (of  $\rightarrow_{\beta}$ ,  $\rightarrow_{\eta}$ ,  $\rightarrow_{\beta\eta}$ )
- ▶ Equivalence:  $t =_{\beta\eta} t'$  if there are s, s'

lacktriangleright t in eta-normal form if no t' such that  $t 
ightarrow_eta t'$ 

- ▶ t in  $\beta$ -normal form if no t' such that  $t \rightarrow_{\beta} t'$
- ▶ t in  $\eta$ -long  $\beta$ -normal form if t is in  $\beta$ -normal form and there is no t' such that  $t' \to_{\eta} t$

- ▶ t in  $\beta$ -normal form if no t' such that  $t \rightarrow_{\beta} t'$
- ▶ t in  $\eta$ -long  $\beta$ -normal form if t is in  $\beta$ -normal form and there is no t' such that  $t' \to_{\eta} t$
- ▶  $lnf = \eta$ -long  $\beta$ -normal form
- ▶ If t, v are in lnf and  $tv \to_{\beta}^* s$  in  $\beta$ -normal form then s is in lnf No  $\eta$ -reductions when terms in lnf

- ▶ t in  $\beta$ -normal form if no t' such that  $t \rightarrow_{\beta} t'$
- ▶ t in  $\eta$ -long  $\beta$ -normal form if t is in  $\beta$ -normal form and there is no t' such that  $t' \to_{\eta} t$
- ▶  $lnf = \eta$ -long  $\beta$ -normal form
- ▶ If t, v are in Inf and  $tv \to_{\beta}^* s$  in  $\beta$ -normal form then s is in Inf No  $\eta$ -reductions when terms in Inf
- ▶  $T_A(C)$  is the set of closed Inf terms of type A whose constants belong to C.

# Example

ightharpoonup x : (0,0) λx.x : ((0,0),0,0) in β-normal form not Inf

#### Example

- $\triangleright$   $x:(\mathbf{0},\mathbf{0})$   $\lambda x.x:((\mathbf{0},\mathbf{0}),\mathbf{0},\mathbf{0})$  in  $\beta$ -normal form not lnf
- ▶  $z: \mathbf{0}$  then  $\lambda z.xz: (\mathbf{0}, \mathbf{0})$  and  $\lambda xz.xz: ((\mathbf{0}, \mathbf{0}), \mathbf{0}, \mathbf{0})$  are in Inf
- ▶ Notation:  $\lambda x_1 \dots x_k \cdot t$  abbreviates  $\lambda x_1 \dots \lambda x_k \cdot t$

#### Example

- ightharpoonup x : (0,0) λx.x : ((0,0),0,0) in β-normal form not Inf
- ▶  $z : \mathbf{0}$  then  $\lambda z.xz : (\mathbf{0}, \mathbf{0})$  and  $\lambda xz.xz : ((\mathbf{0}, \mathbf{0}), \mathbf{0}, \mathbf{0})$  are in Inf
- ▶ Notation:  $\lambda x_1 \dots x_k \cdot t$  abbreviates  $\lambda x_1 \dots \lambda x_k \cdot t$
- Monster type M = ((((0,0),0),0),0,0) has order 5
- ▶  $\lambda xy.x(\lambda z_1.x(\lambda z_2.z_1y)) \in T_M(\emptyset)$ when  $x:(((\mathbf{0},\mathbf{0}),\mathbf{0}),\mathbf{0}),z_i:(\mathbf{0},\mathbf{0})$  and  $y:\mathbf{0}$ .

#### Decision questions

- ► Higher-order unification
- v = u contains free variables  $x_1, \dots, x_n$
- ► Solution  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  such that  $v\theta =_{\beta\eta} u\theta$ Simultaneous substitution

#### Decision questions

- ► Higher-order unification
- v = u contains free variables  $x_1, \ldots, x_n$
- ► Solution  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  such that  $v\theta =_{\beta\eta} u\theta$ Simultaneous substitution
- ▶ Decision question: given v = u, does it have a solution ?
- Order is max order of the x<sub>i</sub>s

### Decision questions

- Higher-order unification
- v = u contains free variables  $x_1, \ldots, x_n$
- ► Solution  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  such that  $v\theta =_{\beta\eta} u\theta$ Simultaneous substitution
- ▶ Decision question: given v = u, does it have a solution ?
- Order is max order of the x<sub>i</sub>s
- ▶ Undecidable (even at order 2) [Huet 1972;Goldfarb 1981]

- Higher-order matching
- v = u contains free variables  $x_1, \dots, x_n$  BUT u closed
- ► Solution  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  such that  $v\theta =_{\beta\eta} u$  W.l.o.g assume  $v, u : \mathbf{0}$

- Higher-order matching
- v = u contains free variables  $x_1, \dots, x_n$  BUT u closed
- ► Solution  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  such that  $v\theta =_{\beta\eta} u$  W.l.o.g assume  $v, u : \mathbf{0}$
- ▶ Decision question: given v = u, does it have a solution?
- ▶ Order is max order of the  $x_i$ s

- Higher-order matching
- v = u contains free variables  $x_1, \dots, x_n$  BUT u closed
- ► Solution  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  such that  $v\theta =_{\beta\eta} u$  W.l.o.g assume  $v, u : \mathbf{0}$
- ▶ Decision question: given v = u, does it have a solution ?
- Order is max order of the x<sub>i</sub>s
- ► Huet conjecture decidable [Huet 1976]
- ▶ Up to order 4 decidable + special cases [Huet 1976, Dowek 1993, Padovani 2000, ...]

- Higher-order matching
- v = u contains free variables  $x_1, \dots, x_n$  BUT u closed
- ► Solution  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  such that  $v\theta =_{\beta\eta} u$  W.l.o.g assume  $v, u : \mathbf{0}$
- ▶ Decision question: given v = u, does it have a solution ?
- Order is max order of the x<sub>i</sub>s
- ► Huet conjecture decidable [Huet 1976]
- ▶ Up to order 4 decidable + special cases [Huet 1976, Dowek 1993, Padovani 2000, ...]
- ▶ Undecidable for  $=_{\beta}$  [Loader 2003]

- Higher-order matching
- v = u contains free variables  $x_1, \dots, x_n$  BUT u closed
- ► Solution  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  such that  $v\theta =_{\beta\eta} u$  W.l.o.g assume  $v, u : \mathbf{0}$
- ▶ Decision question: given v = u, does it have a solution ?
- Order is max order of the x<sub>i</sub>s
- ► Huet conjecture decidable [Huet 1976]
- ▶ Up to order 4 decidable + special cases [Huet 1976, Dowek 1993, Padovani 2000, ...]
- ▶ Undecidable for  $=_{\beta}$  [Loader 2003]
- ▶ Decidable for all orders [Stirling 2006; 2009; 2012]

- Given v = u with  $x_1 : A_1, \dots, x_n : A_n$  in v
- ▶ there is the matching problem  $x(\lambda x_1 ... x_n.v) = u$  where  $x : ((A_1, ..., A_n, 0), 0)$

- Given v = u with  $x_1 : A_1, \ldots, x_n : A_n$  in v
- ▶ there is the matching problem  $x(\lambda x_1 ... x_n.v) = u$  where  $x : ((A_1, ..., A_n, \mathbf{0}), \mathbf{0})$
- ► Conceptually simpler problem: just one free variable
- ► Called "interpolation":  $x w_1 ... w_k = u$  where  $x : (B_1, ..., B_k, \mathbf{0}), w_i : B_i, u : \mathbf{0}$  in Inf.
- Solution t in Inf such that  $tw_1 \dots w_k \to_{\beta}^* u$

- Given v = u with  $x_1 : A_1, \ldots, x_n : A_n$  in v
- ▶ there is the matching problem  $x(\lambda x_1 ... x_n.v) = u$  where  $x : ((A_1, ..., A_n, \mathbf{0}), \mathbf{0})$

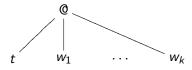
Canonical solution  $\lambda z.z \ t_1 \dots t_n$  where  $t_i$ s are closed Consequently  $v\{t_1/x_1, \dots, t_n/x_n\} \to_{\beta}^* u$ So,  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  solves v = uReduces matching to interpolation

- Given v = u with  $x_1 : A_1, \dots, x_n : A_n$  in v
- ► there is the matching problem  $x(\lambda x_1 ... x_n.v) = u$  where  $x : ((A_1, ..., A_n, \mathbf{0}), \mathbf{0})$

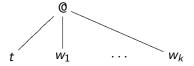
- Canonical solution  $\lambda z.z \ t_1 \dots t_n$  where  $t_i$ s are closed Consequently  $v\{t_1/x_1, \dots, t_n/x_n\} \to_{\beta}^* u$ So,  $\theta = \{t_1/x_1, \dots, t_n/x_n\}$  solves v = uReduces matching to interpolation
- ▶ Restrict constants in solution terms to be those in *u* plus fresh*b* : **0** Restricts to finitely many constants



- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 \dots w_k = u$  (Assume u does not have bound variables)
- ▶ Interpolation tree

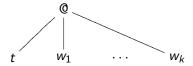


- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 \dots w_k = u$  (Assume u does not have bound variables)
- ▶ Interpolation tree



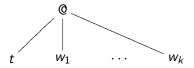
▶ Goal: understand the reduction of  $tw_1 \dots w_k$  to normal form by only examining the interpolation tree. Three ways of doing this

- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 \dots w_k = u$  (Assume u does not have bound variables)
- ▶ Interpolation tree



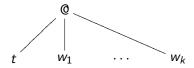
- ▶ Goal: understand the reduction of  $tw_1 ldots w_k$  to normal form by only examining the interpolation tree. Three ways of doing this
  - 1. Typing with intersection types

- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 \dots w_k = u$  (Assume u does not have bound variables)
- ▶ Interpolation tree



- ▶ Goal: understand the reduction of  $tw_1 ldots w_k$  to normal form by only examining the interpolation tree. Three ways of doing this
  - 1. Typing with intersection types
  - 2. Tree automata

- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 \dots w_k = u$  (Assume u does not have bound variables)
- ▶ Interpolation tree

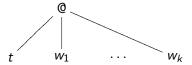


- ▶ Goal: understand the reduction of  $tw_1 \dots w_k$  to normal form by only examining the interpolation tree. Three ways of doing this
  - 1. Typing with intersection types
  - 2. Tree automata
  - 3. Games/(Nonstandard) Automata



#### Intersection types

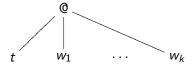
- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 \dots w_k = u$  (Assume u does not have bound variables)
- ▶ Interpolation tree



▶ Goal: understand the reduction of  $tw_1 ldots w_k$  to normal form by only examining the interpolation tree

#### Intersection types

- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 \dots w_k = u$  (Assume u does not have bound variables)
- ▶ Interpolation tree



- ▶ Goal: understand the reduction of  $tw_1 ldots w_k$  to normal form by only examining the interpolation tree
- Based on [Kobayashi 2009, Kobayashi and Ong 2009]; use intersection types

$$\begin{array}{lll} \theta & := & r \mid \tau \to \theta & r \text{ subterm } u \\ \tau & := & \bigwedge_{i_1 \in I_1} \theta_{i_1} \wedge \ldots \wedge \bigwedge_{i_m \in I_m} \theta_{i_m} & I_j \text{ finite} \end{array}$$

#### Typing rules

$$\begin{aligned} \Gamma \vdash a : a & \Gamma, x : \bigwedge_{i \in I} \theta_i \vdash x : \theta_j & j \in I \\ & \frac{\Gamma \vdash t_1 : r_1 & \Gamma \vdash t_m : r_m}{\Gamma \vdash f \ t_1 \dots t_m : fr_1 \dots r_m} \end{aligned}$$

$$\frac{\Gamma \vdash t : \bigwedge_{i_1 \in I_1} \theta_{i_1} \wedge \ldots \wedge \bigwedge_{i_m \in I_m} \theta_{i_m} \rightarrow r \quad \Gamma \vdash v_j : \theta_{i_j} \text{ for all } i_j \in I_j}{\Gamma \vdash t v_1 \ldots v_m : r}$$

$$\frac{\Gamma, x_1 : \bigwedge_{i_1 \in I_1} \theta_{i_1}, \dots, x_m : \bigwedge_{i_m \in I_m} \theta_{i_m} \vdash t : r}{\Gamma \vdash \lambda x_1 \dots x_m . t : \bigwedge_{i_1 \in J_1} \theta_{i_1} \wedge \dots \wedge \bigwedge_{i_m \in J_m} \theta_{i_m} \to r} J_i \subseteq I_i$$

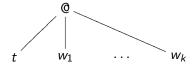
▶ Assume  $\Gamma \vdash w_j : \theta_i$  for all  $i \in I_j$ 

- ▶ Assume  $\Gamma \vdash w_j : \theta_i$  for all  $i \in I_j$
- ▶ So,  $xw_1 \dots w_k = u$  has canonical solution iff

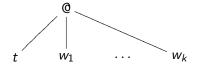
- ▶ Assume  $\Gamma \vdash w_j : \theta_i$  for all  $i \in I_j$
- ▶ So,  $xw_1 \dots w_k = u$  has canonical solution iff
- ▶ some canonical term t has type  $\bigwedge_{i \in I_1} \theta_i \wedge \ldots \wedge \bigwedge_{i \in I_k} \theta_i \rightarrow u$

- ▶ Assume  $\Gamma \vdash w_j : \theta_i$  for all  $i \in I_j$
- ▶ So,  $xw_1 \dots w_k = u$  has canonical solution iff
- ▶ some canonical term t has type  $\bigwedge_{i \in I_1} \theta_i \wedge \ldots \wedge \bigwedge_{i \in I_k} \theta_i \rightarrow u$
- Reduces matching to inhabitation problem for intersection types

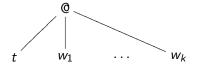
- ▶ Assume  $\Gamma \vdash w_j : \theta_i$  for all  $i \in I_j$
- ▶ So,  $xw_1 \dots w_k = u$  has canonical solution iff
- ▶ some canonical term t has type  $\bigwedge_{i \in I_1} \theta_i \wedge \ldots \wedge \bigwedge_{i \in I_k} \theta_i \rightarrow u$
- Reduces matching to inhabitation problem for intersection types
- ▶ BUT, inhabitation is undecidable [Urzyczyn 1999]



► Are solutions recognisable by an automaton ?

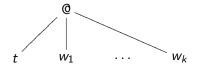


- Are solutions recognisable by an automaton ?
- ► Tree automaton Finite sets: states Q, alphabet  $\Sigma$ , final states  $F \subseteq Q$ , transitions  $\Delta$  of form  $sq_1 \dots q_k \Rightarrow q$ ,  $k \geq 0$ ,  $s \in \Sigma$ , arity(s) = k and  $q, q_i \in Q$



- Are solutions recognisable by an automaton ?
- ► Tree automaton Finite sets: states Q, alphabet  $\Sigma$ , final states  $F \subseteq Q$ , transitions  $\Delta$  of form  $sq_1 \dots q_k \Rightarrow q$ ,  $k \geq 0$ ,  $s \in \Sigma$ , arity(s) = k and  $q, q_i \in Q$
- ► Using transitions label tree bottom-up with states

  Automaton accepts tree iff root can be labelled with a final state



- Are solutions recognisable by an automaton ?
- ► Tree automaton Finite sets: states Q, alphabet  $\Sigma$ , final states  $F \subseteq Q$ , transitions  $\Delta$  of form  $sq_1 \dots q_k \Rightarrow q$ ,  $k \geq 0$ ,  $s \in \Sigma$ , arity(s) = k and  $q, q_i \in Q$
- Using transitions label tree bottom-up with states
   Automaton accepts tree iff root can be labelled with a final state
- ▶ Non-emptiness decidable; sets recognised are regular

- ▶ 4th-order  $xw_1 \dots w_k = u$  and C constants in u plus b
- For finite alphabet  $\Sigma$  consider a potential solution term  $t = \lambda x_1 \dots x_k . s$

$$s ::= z_j^n \mid x_i v_1 \dots v_m \mid f s_1 \dots s_m \quad f \in C, \ m \ge 0$$
  
 $v ::= s \mid \lambda z_1^n \dots z_m^n.s \quad m \ge 0 \quad \text{NOTE: } z_i^n : \mathbf{0}$ 

- ▶ 4th-order  $xw_1 \dots w_k = u$  and C constants in u plus b
- ► For finite alphabet  $\Sigma$  consider a potential solution term  $t = \lambda x_1 \dots x_k.s$

$$s ::= z_j^n \mid x_i v_1 \dots v_m \mid f s_1 \dots s_m \quad f \in C, \ m \ge 0$$
  
 $v ::= s \mid \lambda z_1^n \dots z_m^n.s \quad m \ge 0 \quad \text{NOTE: } z_i^n : \mathbf{0}$ 

Node n of t is labelled with a variable/constant; let t<sup>n</sup> be subterm rooted at n

- ▶ 4th-order  $xw_1 \dots w_k = u$  and C constants in u plus b
- ► For finite alphabet  $\Sigma$  consider a potential solution term  $t = \lambda x_1 \dots x_k . s$

$$s ::= z_j^n \mid x_i v_1 \dots v_m \mid f s_1 \dots s_m \quad f \in C, \ m \ge 0$$
  
 $v ::= s \mid \lambda z_1^n \dots z_m^n.s \quad m \ge 0 \quad \text{NOTE: } z_i^n : \mathbf{0}$ 

- Node n of t is labelled with a variable/constant; let t<sup>n</sup> be subterm rooted at n
- n is inaccessible
   if it does not contribute to normal form of tw<sub>1</sub>...w<sub>k</sub>
   (Therefore, can replace t<sup>n</sup> with b: 0; preserve normal form)

- ▶ 4th-order  $xw_1 \dots w_k = u$  and C constants in u plus b
- ► For finite alphabet  $\Sigma$  consider a potential solution term  $t = \lambda x_1 \dots x_k.s$

$$s ::= z_j^n \mid x_i v_1 \dots v_m \mid f s_1 \dots s_m \quad f \in C, \ m \ge 0$$
  
 $v ::= s \mid \lambda z_1^n \dots z_m^n.s \quad m \ge 0 \quad \text{NOTE: } z_i^n : \mathbf{0}$ 

- Node n of t is labelled with a variable/constant; let t<sup>n</sup> be subterm rooted at n
- ▶ n is inaccessible if it does not contribute to normal form of  $tw_1 \dots w_k$ (Therefore, can replace  $t^n$  with b:0; preserve normal form)
- n is accessible; look at evaluation of t<sup>n</sup>
   which is normal form of t<sup>n</sup>{w<sub>1</sub>/x<sub>1</sub>,..., w<sub>k</sub>/x<sub>k</sub>}
   this is a subterm of u when its subterms can be replaced by leaf variables z<sup>i</sup>.

- ▶ 4th-order  $xw_1 \dots w_k = u$  and C constants in u plus b
- ► For finite alphabet  $\Sigma$  consider a potential solution term  $t = \lambda x_1 \dots x_k . s$

$$s ::= z_j^n \mid x_i v_1 \dots v_m \mid f s_1 \dots s_m \quad f \in C, \ m \ge 0$$
  
 $v ::= s \mid \lambda z_1^n \dots z_m^n.s \quad m \ge 0 \quad \text{NOTE: } z_i^n : \mathbf{0}$ 

- Node n of t is labelled with a variable/constant; let t<sup>n</sup> be subterm rooted at n
- ▶ n is inaccessible if it does not contribute to normal form of  $tw_1 \dots w_k$ (Therefore, can replace  $t^n$  with b:0; preserve normal form)
- n is accessible; look at evaluation of t<sup>n</sup>
   which is normal form of t<sup>n</sup>{w<sub>1</sub>/x<sub>1</sub>,..., w<sub>k</sub>/x<sub>k</sub>}
   this is a subterm of u when its subterms can be replaced by leaf variables z<sub>i</sub><sup>i</sup>
- ► Guarantees finite alphabet for accessible nodes: reuse variables



► Finite states:

inaccessible nodes: — for "doesn't matter" accessible nodes: U is subterms of u closed under replacement of subterms with leaves labelled with finitely many different variables  $z_j^i$ :  $\mathbf{0}$ 

$$\{[e], [\lambda z_1^n \dots z_m^n.e], [\lambda x_1 \dots x_k.u] \mid e \in U \cup \{-\}\}$$

► Finite states:

inaccessible nodes: — for "doesn't matter" accessible nodes: U is subterms of u closed under replacement of subterms with leaves labelled with finitely many different variables  $z_j^i$ :  $\mathbf{0}$ 

$$\{[e],[\lambda z_1^n\dots z_m^n.e],[\lambda x_1\dots x_k.u]\ |\ e\in U\cup\{-\}\}$$

▶ Final states  $\{[\lambda x_1 \dots x_k.u]\}$ 

► Finite states: inaccessible nodes: — for "doesn't matter" accessible nodes: U is subterms of u closed under replacement of subterms with leaves labelled with finitely many different

$$\{[e], [\lambda z_1^n \dots z_m^n . e], [\lambda x_1 \dots x_k . u] \mid e \in U \cup \{-\}\}$$

- ▶ Final states  $\{[\lambda x_1 \dots x_k.u]\}$
- ► Finite transitions: such as

variables  $z_i^i$ : **0** 

$$z \Rightarrow [z]$$
  $z \Rightarrow [-]$   $a \Rightarrow [a]$   $c \Rightarrow [-]$   
 $\lambda x_1[ga] \Rightarrow [\lambda x_1.ga]$   $x_1[-][gz] \Rightarrow [gz]$   
...

► Finite states: inaccessible nodes: — for "doesn't matter" accessible nodes: U is subterms of u closed under replacement of subterms with leaves labelled with finitely many different variables z<sup>i</sup><sub>i</sub>: 0

$$\{[e], [\lambda z_1^n \dots z_m^n.e], [\lambda x_1 \dots x_k.u] \mid e \in U \cup \{-\}\}$$

- ▶ Final states  $\{[\lambda x_1 ... x_k.u]\}$
- Finite transitions: such as

$$z \Rightarrow [z]$$
  $z \Rightarrow [-]$   $a \Rightarrow [a]$   $c \Rightarrow [-]$   
 $\lambda x_1[ga] \Rightarrow [\lambda x_1.ga]$   $x_1[-][gz] \Rightarrow [gz]$   
...

► Theorem The tree automaton associated with a 4th-order  $xw_1 \dots w_k = u$  accepts t iff t solves  $xw_1 \dots w_k = u$ 

#### Tree automata for 5th-order: PROBLEMS

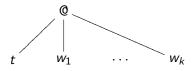
Finite alphabet ? can stack 2nd-order variables  $\frac{\lambda xy.x(\lambda z_1.x(\lambda z_2...(\lambda z_n.z_n(z_{n-1}(...z_1(y))...)))}{\text{Need an infinite alphabet}}$ 

#### Tree automata for 5th-order: PROBLEMS

- Finite alphabet ? can stack 2nd-order variables  $\frac{\lambda xy.x(\lambda z_1.x(\lambda z_2...(\lambda z_n.z_n(z_{n-1}(...z_1(y))...)))}{\text{Need an infinite alphabet}}$
- Finite number of states? stack same 2nd-order variable  $\frac{z_n(z_n(\dots(z_na)\dots))}{\text{Number of evaluations can be infinite}}$

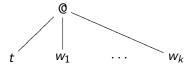
#### Interpolation trees

- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 \dots w_k = u$  (Assume u does not have bound variables)
- ▶ Interpolation tree



#### Interpolation trees

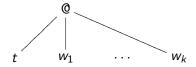
- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 ... w_k = u$  (Assume u does not have bound variables)
- ▶ Interpolation tree



Special representation of term trees

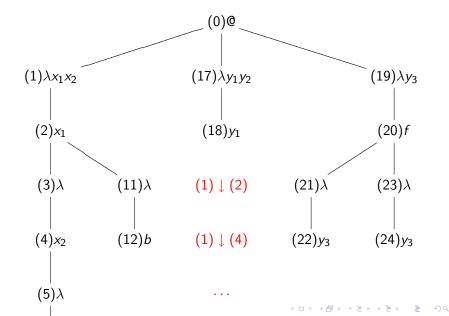
#### Interpolation trees

- ▶ t (of the right type and in lnf) a potential solution to  $xw_1 \dots w_k = u$  (Assume u does not have bound variables)
- ► Interpolation tree



- Special representation of term trees
- ▶  $t, w_1, ..., w_k$  binding trees with dummy lambdas and binding relation  $\downarrow$  between nodes
- ▶  $n \downarrow m$  if n labelled  $\lambda \overline{y}$  binds  $y_i$ , label at m

# Example: $x(\lambda y_1y_2.y_1)(\lambda y_3.fy_3y_3) = faa$



#### Tree automata for 5th-order

- Finite alphabet ? can stack 2nd-order variables  $\lambda xy.x(\lambda z_1.x(\lambda z_2...(\lambda z_n.z_n(z_{n-1}(...z_1(y))...)))$ Need an infinite alphabet
- Finite number of states ? stack same 2nd-order variable  $z_n(z_n(\ldots(z_na)\ldots))$ Number of evaluations can be infinite

#### Tree automata for 5th-order

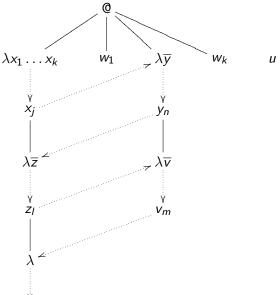
- Finite alphabet ? can stack 2nd-order variables  $\lambda xy.x(\lambda z_1.x(\lambda z_2...(\lambda z_n.z_n(z_{n-1}(...z_1(y))...)))$ Need an infinite alphabet
- Finite number of states ? stack same 2nd-order variable  $z_n(z_n(\ldots(z_na)\ldots))$ Number of evaluations can be infinite
- ▶ Overcome the first problem: employ binding trees  $\lambda xy.x(\lambda z.x(\lambda z...x(\lambda z.z(\lambda.z(...\lambda.z(\lambda.y))...)))$  ↓ from the first node labelled  $\lambda z$  to the last node labelled z, and so on

Fact For all A and finite C, there is a finite  $\Sigma$  such that every  $t \in T_A(C)$  up to  $\alpha$ -equivalence is a binding  $\Sigma$ -tree.

#### Tree automata for 5th-order

- Finite alphabet ? can stack 2nd-order variables  $\lambda xy.x(\lambda z_1.x(\lambda z_2...(\lambda z_n.z_n(z_{n-1}(...z_1(y))...)))$ Need an infinite alphabet
- Finite number of states ? stack same 2nd-order variable  $z_n(z_n(\ldots(z_na)\ldots))$ Number of evaluations can be infinite
- ▶ Overcome the first problem: employ binding trees  $\lambda xy.x(\lambda z.x(\lambda z...x(\lambda z.z(\lambda.z(...\lambda.z(\lambda.y))...)))$  ↓ from the first node labelled  $\lambda z$  to the last node labelled z, and so on
  - Fact For all A and finite C, there is a finite  $\Sigma$  such that every  $t \in T_A(C)$  up to  $\alpha$ -equivalence is a binding  $\Sigma$ -tree.
- ► Second problem ? need finer analysis than evaluation of an accessible node

#### Games: automaton moving around interpolation tree



- ▶ Play: sequence  $n_1q_1\theta_1, \ldots, n_lq_l\theta_l$ 
  - $ightharpoonup n_i$  is a node of the interpolation tree,
  - $ightharpoonup q_i$  is a state [u'] where u' subterm of u or final
  - $\bullet$   $\theta_i$  is look-up table: tells where to jump when at a variable

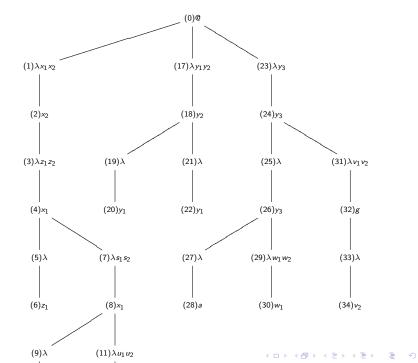
- ▶ Play: sequence  $n_1q_1\theta_1, \ldots, n_lq_l\theta_l$ 
  - $ightharpoonup n_i$  is a node of the interpolation tree,
  - $ightharpoonup q_i$  is a state [u'] where u' subterm of u or final
  - $ightharpoonup heta_i$  is look-up table: tells where to jump when at a variable
- ▶ Initial position at @,  $q_1 = [u]$  and  $\theta_1$  is empty
- ▶  $\forall$  loses the play if the final state  $q_l = [\exists]$

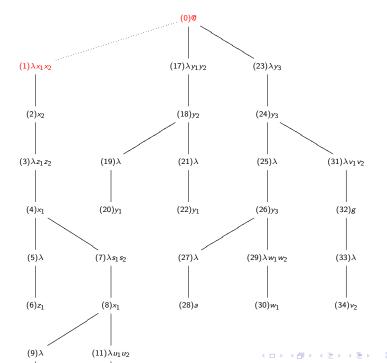
- ▶ Play: sequence  $n_1q_1\theta_1, \ldots, n_lq_l\theta_l$ 
  - $ightharpoonup n_i$  is a node of the interpolation tree,
  - $ightharpoonup q_i$  is a state [u'] where u' subterm of u or final
  - $\blacktriangleright$   $\theta_i$  is look-up table: tells where to jump when at a variable
- ▶ Initial position at @,  $q_1 = [u]$  and  $\theta_1$  is empty
- ▶  $\forall$  loses the play if the final state  $q_I = [\exists]$
- ▶ Current position is  $n[r]\theta$ ; next position
  - @ then  $n1[r]\theta'$  where  $\theta' = \theta\{((n2, ..., n(k+1)), \theta)/n1\}$
  - ▶  $\lambda \overline{y}$  then  $n1[r]\theta$

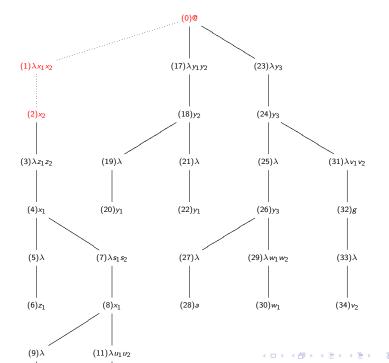
- ▶ Play: sequence  $n_1q_1\theta_1, \ldots, n_lq_l\theta_l$ 
  - $ightharpoonup n_i$  is a node of the interpolation tree,
  - $ightharpoonup q_i$  is a state [u'] where u' subterm of u or final
  - $\blacktriangleright$   $\theta_i$  is look-up table: tells where to jump when at a variable
- ▶ Initial position at @,  $q_1 = [u]$  and  $\theta_1$  is empty
- ▶  $\forall$  loses the play if the final state  $q_I = [\exists]$
- ▶ Current position is  $n[r]\theta$ ; next position
  - @ then  $n1[r]\theta'$  where  $\theta' = \theta\{((n2, ..., n(k+1)), \theta)/n1\}$
  - ▶  $\lambda \overline{y}$  then  $n1[r]\theta$
  - ▶  $a : \mathbf{0}$  if r = a then  $n[\exists]\theta$  else  $n[\forall]\theta$
  - ▶  $f: (B_1, ..., B_p, \mathbf{0})$  if  $r = fr_1 ... r_p$  then  $\forall$  chooses  $j \in \{1, ..., p\}$  and  $nj [r_j]\theta$  else  $n[\forall]\theta$

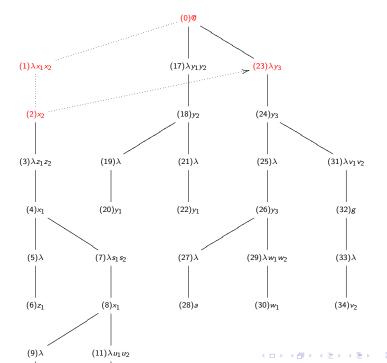
- ▶ Play: sequence  $n_1q_1\theta_1, \ldots, n_lq_l\theta_l$ 
  - $ightharpoonup n_i$  is a node of the interpolation tree,
  - $ightharpoonup q_i$  is a state [u'] where u' subterm of u or final
  - $\blacktriangleright$   $\theta_i$  is look-up table: tells where to jump when at a variable
- ▶ Initial position at 0,  $q_1 = [u]$  and  $\theta_1$  is empty
- ▶  $\forall$  loses the play if the final state  $q_I = [\exists]$
- ► Current position is  $n[r]\theta$ ; next position
  - @ then  $n1[r]\theta'$  where  $\theta' = \theta\{((n2, ..., n(k+1)), \theta)/n1\}$
  - ▶  $\lambda \overline{y}$  then  $n1[r]\theta$
  - ▶  $a : \mathbf{0}$  if r = a then  $n[\exists]\theta$  else  $n[\forall]\theta$
  - ►  $f: (B_1, ..., B_p, \mathbf{0})$  if  $r = fr_1 ... r_p$  then  $\forall$  chooses  $j \in \{1, ..., p\}$  and  $nj [r_i]\theta$  else  $n[\forall]\theta$
  - ▶  $y_j : \mathbf{0}$  if  $m \downarrow n$  and  $\theta(m) = ((m_1, \dots, m_l), \theta')$  then  $m_j[r]\theta'$
  - ▶  $y_j : (B_1, ..., B_p, \mathbf{0})$  if  $m \downarrow n$  and  $\theta(m) = ((m_1, ..., m_l), \theta')$  then  $m_i [r]\theta''$  where  $\theta'' = \theta' \{((n1, ..., np), \theta)/m_i\}$

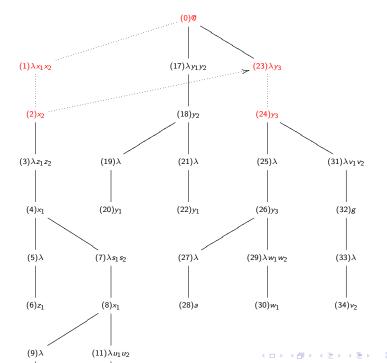
- ▶ Play: sequence  $n_1q_1\theta_1, \ldots, n_lq_l\theta_l$ 
  - $ightharpoonup n_i$  is a node of the interpolation tree,
  - $ightharpoonup q_i$  is a state [u'] where u' subterm of u or final
  - lacktriangledown  $heta_i$  is look-up table: tells where to jump when at a variable
- ▶ Initial position at @,  $q_1 = [u]$  and  $\theta_1$  is empty
- ▶  $\forall$  loses the play if the final state  $q_l = [\exists]$
- ▶ Current position is  $n[r]\theta$ ; next position
  - ▶ @ then  $n1[r]\theta'$  where  $\theta' = \theta\{((n2, ..., n(k+1)), \theta)/n1\}$
  - ▶  $\lambda \overline{y}$  then  $n1[r]\theta$
  - ▶  $a: \mathbf{0}$  if r = a then  $n[\exists]\theta$  else  $n[\forall]\theta$
  - ▶  $f: (B_1, ..., B_p, \mathbf{0})$  if  $r = fr_1 ... r_p$  then  $\forall$  chooses  $j \in \{1, ..., p\}$  and  $nj [r_i]\theta$  else  $n[\forall]\theta$
  - ▶  $y_j : \mathbf{0}$  if  $m \downarrow n$  and  $\theta(m) = ((m_1, \dots, m_l), \theta')$  then  $m_j[r]\theta'$
  - ▶  $y_j : (B_1, ..., B_p, \mathbf{0})$  if  $m \downarrow n$  and  $\theta(m) = ((m_1, ..., m_l), \theta')$  then  $m_j [r]\theta''$  where  $\theta'' = \theta'\{((n1, ..., np), \theta)/m_j\}$
- ▶ Player  $\forall$  loses every play in G(t, E) iff t solves E

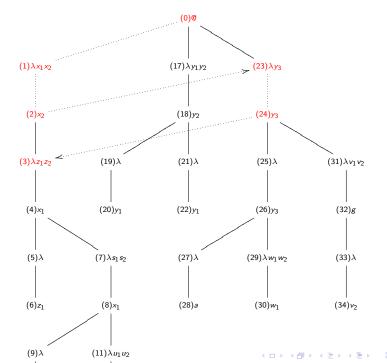


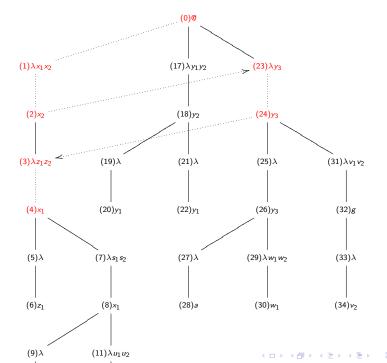


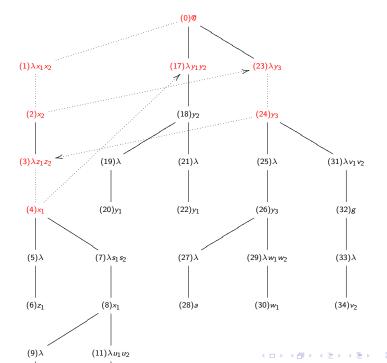


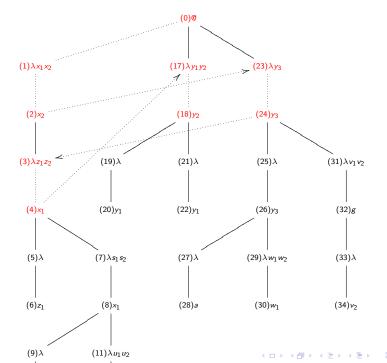


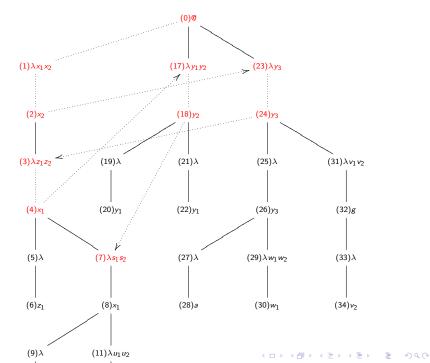


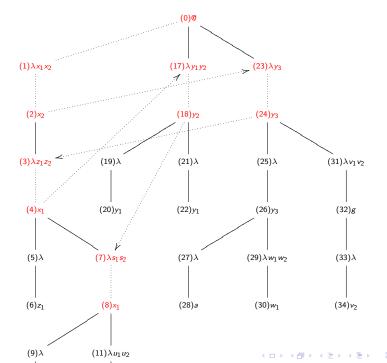


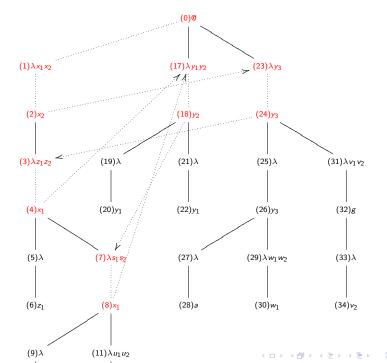


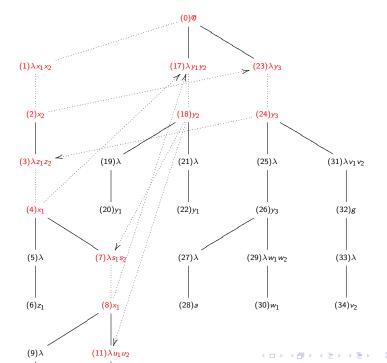












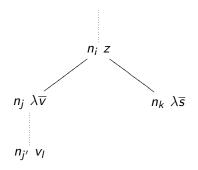
- ▶ Let *E* be interpolation equation of arbitrary order
- Two problems extending Comon and Jurski's result
  - 1. Ensuring finitely many states in automaton
  - 2. Ensuring finite alphabet in automaton

- ▶ Let *E* be interpolation equation of arbitrary order
- ▶ Two problems extending Comon and Jurski's result
  - 1. Ensuring finitely many states in automaton
  - 2. Ensuring finite alphabet in automaton
- Instead of using evaluation of a node for states use (version of) variable profiles from [Ong 2006]
- ▶ Variable profile: abstraction from sequences of positions from a node  $\{(x_2, ga, \{(y_3, ga, \{(z_2, ga, \{(v_2, a, \emptyset)\})\})\})\})$

- ▶ Let *E* be interpolation equation of arbitrary order
- ▶ Two problems extending Comon and Jurski's result
  - 1. Ensuring finitely many states in automaton
  - 2. Ensuring finite alphabet in automaton
- Instead of using evaluation of a node for states use (version of) variable profiles from [Ong 2006]
- ▶ Variable profile: abstraction from sequences of positions from a node  $\{(x_2, ga, \{(y_3, ga, \{(z_2, ga, \{(v_2, a, \emptyset)\})\})\})\})$
- ► Theorem The set of solutions of *E* built out of a fixed finite alphabet of variables is recognised by a tree automaton [Stirling 2007]

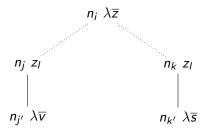
- ▶ Let *E* be interpolation equation of arbitrary order
- ▶ Two problems extending Comon and Jurski's result
  - 1. Ensuring finitely many states in automaton
  - 2. Ensuring finite alphabet in automaton
- Instead of using evaluation of a node for states use (version of) variable profiles from [Ong 2006]
- ▶ Variable profile: abstraction from sequences of positions from a node  $\{(x_2, ga, \{(y_3, ga, \{(z_2, ga, \{(v_2, a, \emptyset)\})\})\})\})$
- ► Theorem The set of solutions of *E* built out of a fixed finite alphabet of variables is recognised by a tree automaton [Stirling 2007]
- ▶ Theorem The set of solutions of *E* is recognised by a special alternating binding tree automaton BUT non-emptiness of such automata undecidable [Stirling 2009; Ong, Tzevelekos 2009]

## Uniformity properties of game playing I



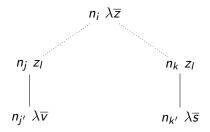
▶ If play is at  $n_i$  then at  $n_j$  and then later at  $n_k$  then inbetween there must have been a position at an  $n_{j'}$  bound by  $n_j$ 

### Uniformity properties of game playing II



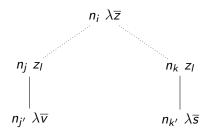
▶ If play is at  $n_i$  then at  $n_j$  and then later at  $n_{j'}$ ; then at  $n_k$  then there must be a corresponding sequence to that between  $n_j$  and  $n_{j'}$  between  $n_k$  and  $n_{k'}$  unless there is a different  $\forall$  choice

### Uniformity properties of game playing II



- ▶ If play is at  $n_i$  then at  $n_j$  and then later at  $n_{j'}$ ; then at  $n_k$  then there must be a corresponding sequence to that between  $n_j$  and  $n_{j'}$  between  $n_k$  and  $n_{k'}$  unless there is a different  $\forall$  choice
- ▶ Especially relevant if  $n_k$  is somewhere below  $n_j$  ("embedded")

### Uniformity properties of game playing II



- ▶ If play is at  $n_i$  then at  $n_j$  and then later at  $n_{j'}$ ; then at  $n_k$  then there must be a corresponding sequence to that between  $n_j$  and  $n_{i'}$  between  $n_k$  and  $n_{k'}$  unless there is a different  $\forall$  choice
- ▶ Especially relevant if  $n_k$  is somewhere below  $n_j$  ("embedded")
- Property not enforced in a tree automaton

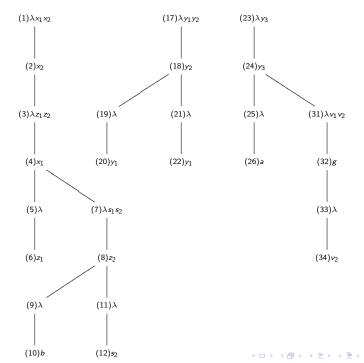
► Combinatorial argument based on uniformities of play

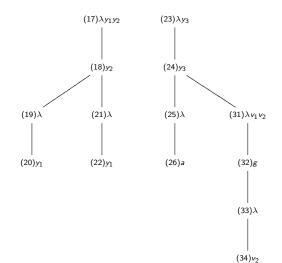
- Combinatorial argument based on uniformities of play
- Two steps in proof assuming an arbitrary solution term

- Combinatorial argument based on uniformities of play
- ▶ Two steps in proof assuming an arbitrary solution term
  - 1. partition each play

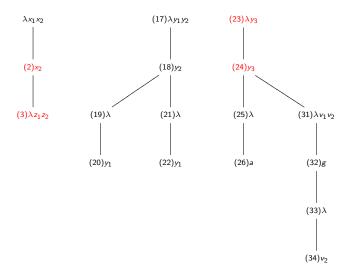
- Combinatorial argument based on uniformities of play
- ► Two steps in proof assuming an arbitrary solution term
  - 1. partition each play
- 5th-order example

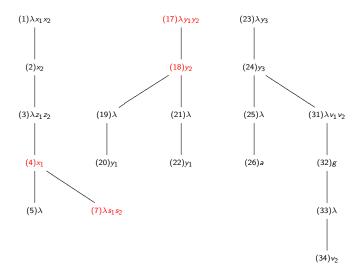
$$x(\lambda y_1y_2.y_2y_1y_1)(\lambda y_3.y_3a(\lambda v_1v_2.gv_2)) = ga$$

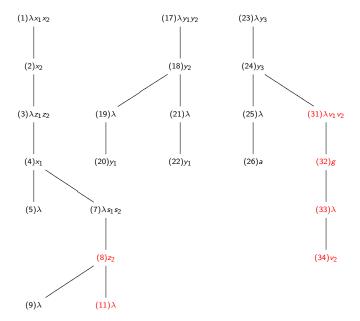


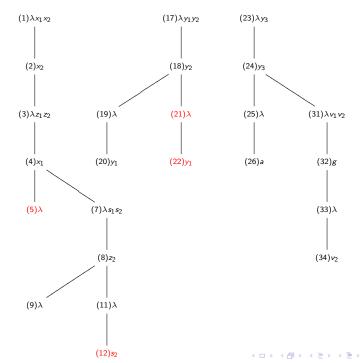


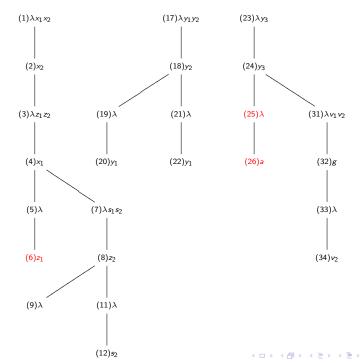
 $(1)\lambda x_1x_2$ 











- Combinatorial argument based on uniformities of play.
- ► Two steps in proof assuming an arbitrary solution term

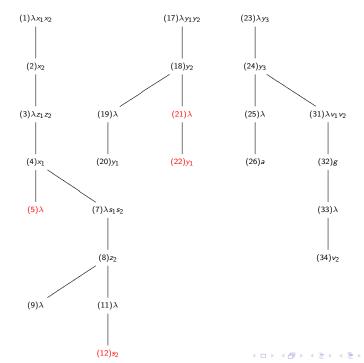
  1. partition each play

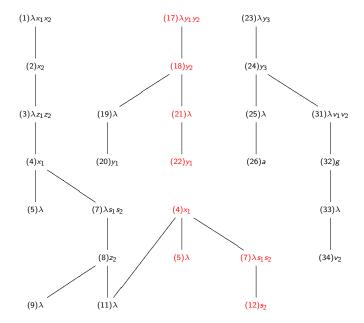
▶ 5th-order example

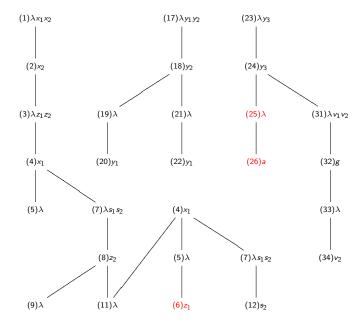
$$x(\lambda y_1 y_2.y_2 y_1 y_1)(\lambda y_3.y_3 a(\lambda v_1 v_2.g v_2)) = ga$$

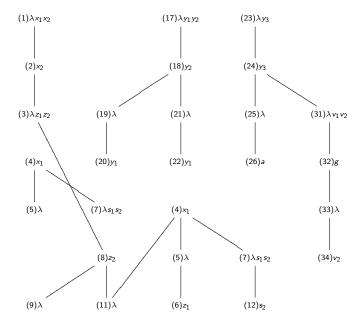
- Combinatorial argument based on uniformities of play.
- ▶ Two steps in proof assuming an arbitrary solution term
  - 1. partition each play
  - 2. unfold into a small solution (by adding prefixes) and then removing redundant parts of term
- ▶ 5th-order example

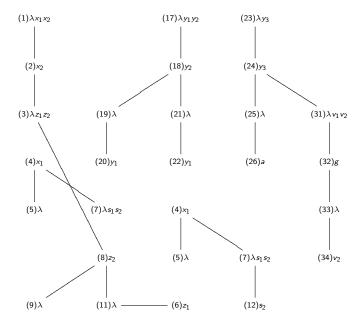
$$x(\lambda y_1 y_2.y_2 y_1 y_1)(\lambda y_3.y_3 a(\lambda v_1 v_2.g v_2)) = ga$$

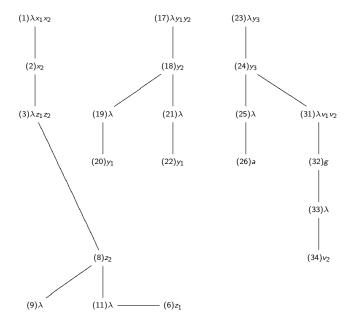












# Application of games to decidability of matching

- Combinatorial argument based on uniformities of play.
- ▶ Two steps in proof assuming an arbitrary solution term
  - 1. partition each play
  - 2. unfold into a small solution (by adding prefixes) and then remove redundant parts of term

# Application of games to decidability of matching

- Combinatorial argument based on uniformities of play.
- ▶ Two steps in proof assuming an arbitrary solution term
  - 1. partition each play
  - 2. unfold into a small solution (by adding prefixes) and then remove redundant parts of term
- Small term property

# Application of games to decidability of matching

- Combinatorial argument based on uniformities of play.
- ► Two steps in proof assuming an arbitrary solution term
  - 1. partition each play
  - 2. unfold into a small solution (by adding prefixes) and then remove redundant parts of term
- ► Small term property
- ▶ Theorem If x : A and A has order 2p + 2 or 2p + 3 and arity q then  $xw_1 ... w_k = u$  has a (canonical) solution iff it has a (canonical) solution of depth at most  $O(p^2q^{2p}|u|)$

Type A is a retract of B, if there are  $t:A\to B$  and  $s:B\to A$  such that  $s(tx)=_{\beta\eta}x$ 

Type A is a retract of B, if there are  $t:A\to B$  and  $s:B\to A$  such that  $s(tx)=_{\beta\eta}x$ 

DECISION PROBLEM: given A, B, is A a retract of B?

▶ Bruce and Longo [STOC 85] solve problem for  $=_{\beta}$  by providing a simple proof system. Much harder for  $=_{\beta\eta}$ 

Type A is a retract of B, if there are  $t:A\to B$  and  $s:B\to A$  such that  $s(tx)=_{\beta\eta}x$ 

- ▶ Bruce and Longo [STOC 85] solve problem for  $=_{\beta}$  by providing a simple proof system. Much harder for  $=_{\beta\eta}$
- ▶ De Liguro, Piperno and Statman [LICS 92] solve affine case for  $=_{\beta\eta}$  when single base type by providing a proof system
- Generalised by Regnier and Urzyczyn [2002] to arbitrary base types: proof system for affine case provides NP decision procedure

Type A is a retract of B, if there are  $t:A\to B$  and  $s:B\to A$  such that  $s(tx)=_{\beta\eta}x$ 

- ▶ Bruce and Longo [STOC 85] solve problem for  $=_{\beta}$  by providing a simple proof system. Much harder for  $=_{\beta\eta}$
- ▶ De Liguro, Piperno and Statman [LICS 92] solve affine case for  $=_{\beta\eta}$  when single base type by providing a proof system
- Generalised by Regnier and Urzyczyn [2002] to arbitrary base types: proof system for affine case provides NP decision procedure
- ► Padovani [TLCA 01] shows decidability for general case when single base type (no complexity bound)

Type A is a retract of B, if there are  $t:A\to B$  and  $s:B\to A$  such that  $s(tx)=_{\beta\eta}x$ 

- ▶ Bruce and Longo [STOC 85] solve problem for  $=_{\beta}$  by providing a simple proof system. Much harder for  $=_{\beta\eta}$
- ▶ De Liguro, Piperno and Statman [LICS 92] solve affine case for  $=_{\beta\eta}$  when single base type by providing a proof system
- Generalised by Regnier and Urzyczyn [2002] to arbitrary base types: proof system for affine case provides NP decision procedure
- ▶ Padovani [TLCA 01] shows decidability for general case when single base type (no complexity bound)
- ► Decidability of general case follows from decidability of higher-order matching; non-elementary complexity bound

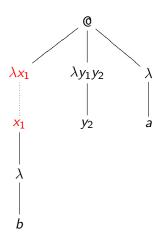
Type A is a retract of B, if there are  $t:A\to B$  and  $s:B\to A$  such that  $s(tx)=_{\beta\eta}x$ 

- ▶ Bruce and Longo [STOC 85] solve problem for  $=_{\beta}$  by providing a simple proof system. Much harder for  $=_{\beta\eta}$
- ▶ De Liguro, Piperno and Statman [LICS 92] solve affine case for  $=_{\beta\eta}$  when single base type by providing a proof system
- Generalised by Regnier and Urzyczyn [2002] to arbitrary base types: proof system for affine case provides NP decision procedure
- ▶ Padovani [TLCA 01] shows decidability for general case when single base type (no complexity bound)
- Decidability of general case follows from decidability of higher-order matching; non-elementary complexity bound
- ▶ Proof system for general case with EXPSPACE upper bound; soundness and completeness uses games [ICALP 13]



# Games only work for long normal forms

•  $x : ((0,0,0),0,0) \ \beta$ -interpolation problem  $x(\lambda y_1 y_2.y_2)a = a$ 



- ▶ No natural game?

