

UPPAAL 4.0

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Abstract—UPPAAL 4.0 is the result of over two and a half years of development and contains many new features, additions to the modeling language, performance improvements, enhancements and polish to the easy to use graphical user interface, and is accompanied by several open source libraries. The tool and libraries are available free of charge for academic, educational and evaluation purposes from <http://www.uppaal.com/>. We describe three of the new features: User defined functions, priorities and symmetry reduction.

I. INTRODUCTION

UPPAAL is a verification tool for timed automata. Its focus on speed and usability has made the tool popular both as a teaching tool in academia, as a gentle introduction to the world of model checking, and as a tool for doing serious case studies as witnessed by the large number of publications in which UPPAAL was used. Version 4.0 was released in May 2006 and introduces many new features that increase the applicability and the performance of the tool. This paper describes three major features of the new release. Many more are worth describing (such as a typical reduction in memory usage of a factor 3 to 5, new abstraction techniques resulting in large performance increases [1], or our implementation of the generalised sweep line method), however lack of space forces us to focus on the most visible changes.

II. USER DEFINED FUNCTIONS

Many problems require non-trivial computations with complex control-flow to be embedded in the model. In a graphical language like the one used by UPPAAL, this tends to clutter the model and makes the model hard to read and maintain. Often, including such computations in the model enlarges the state space by introducing intermediate states and irrelevant interleaving. In the past, this has led to the addition of committed locations in UPPAAL to build atomic sequences.

In UPPAAL 4.0 we have extended the modeling language with user defined functions. These are fully integrated into the modeling language, and can access and modify all state variables. The syntax follows the style of C/C++/Java, and most control-flow constructs of C are supported. Functions are evaluated atomically and must be deterministic, whereby intermediate states are avoided (similar to the `d_step` construction in SPIN, which marks a sequence of statements as atomic and deterministic). The only limitations are that recursive calls are

not allowed and functions must eventually return. The second requirement is currently not enforced by UPPAAL, and model-checking will not terminate if a user defined function enters an infinite loop (this is a technicality and the language was designed such that future versions of UPPAAL can be extended to analyze the model for such problems).

User defined functions are compiled to byte-code, and executed at verification time on a small embedded stack machine. We have decided not to use an external compiler like `gcc`, even though this would result in faster evaluation of complicated functions. The dependence on an external compiler would complicate the installation procedure of UPPAAL considerably.

The extension has proven to be extremely useful in almost all UPPAAL models. Typical uses include that of naming or hiding complicated expressions from the graphical language, performing updates on data structures like routing tables, queues, and stacks (although, the size of such data structures must always be bounded), and performing computations that require loops and complex control-flow. One of the more ingenious uses we have seen, is to implement an interpreter for live sequence charts, which when embedded in a UPPAAL model can be used to check conformance.

III. PRIORITIES

In the implementation of real-time systems, priorities are often associated with processes (or tasks) to structure and control the usage of shared resources such as the CPU or memory. As a consequence, programming languages and scheduling policies used in real-time operating systems are often based on a notion of priorities on tasks. In lower levels, priorities are often associated with interrupts to hardware devices and access to e.g., shared communication buses.

In UPPAAL 4.0 we have extended the modelling language with priorities on channels and automata [2]. The priority orders defined in the model are translated into a priority order on internal and synchronizing transitions. At a given time-point, an enabled transition will *block* (disable) another if it has a higher priority.

The example below specifies that channel *a* has a lower priority than channels *b* and *c*, and that the automaton *P* has a lower priority than automata *Q* and *R*. In such a model, with priorities on both automata and channels, we resolve

priorities by comparing priorities on channels first. If they are the same, the automata priorities are compared. For efficient model-checking the priority orders are total orders.

```
chan priority a < b, c;
system P < Q, R;
```

UPPAAL uses difference bound matrices (DBMs) [3] to represent convex constraints on clock variables. The efficient implementation of priorities is made possible by the introduction of a optimised subtraction operation in the DBM library. However, the result of the subtraction is not necessarily a convex zone, but rather a set of zones. The algorithm we use for subtraction generates a disjoint set of DBMs, and uses a heuristic to minimise the number of DBMs in the result. The library even supports merging zones back together.

IV. SYMMETRY REDUCTION

Symmetry reduction is a well-known technique to alleviate the state-space explosion problem and has recently been added to UPPAAL. This technique can be applied to models that contain multiple equivalently behaving processes [4]. Consider, for instance, Fischer's mutual exclusion algorithm. It consists of a set of processes that only differ in their "identity". A process writes its identity in a global variable and checks after a while whether this global variable still contains its identity. If so, it can enter the critical section.

In order to provide convenient and safe usage of symmetry reduction, the modeling language of UPPAAL has been extended with the *scalar* datatype. It can be used to define *scalarsets* which can be regarded as unordered integer subranges. As a result, the only operations allowed on scalars are (i) equivalency testing with a scalar of the same type and (ii) assignment with a scalar of the same type. Furthermore, scalars can be used to index arrays if the dimension of the array has the same type as the indexing scalar. In the model for Fischer's mutex algorithm, the process identity is a scalar and therefore there is a single scalarset.

Symmetry reduction can – in theory – be very beneficial: its savings w.r.t. the size of the reachable state space can (for a model with one scalarset of size n) approach a factor $n!$. This super-exponential gain is, unfortunately, not always observed due to a fundamental technical issue. Fig. 1 shows the effect of symmetry reduction for Fischer's mutex algorithm.

An important application area of symmetry reduction is the area of distributed algorithms since models of instances of such algorithms often consist of a number of symmetric processes. For instance, symmetry reduction in UPPAAL has been successfully applied to the leader election algorithm in [5], a consensus algorithm [6] and the Zeroconf protocol [7]¹.

V. DEVELOPING WITH UPPAAL

A number of libraries for third party developers have been released with UPPAAL 4.0: The DBM library mentioned above is released under the GPL and contains language bindings for

¹The work in [6] does not use automatic symmetry reduction, but recent experiments show that this can be done with a significant gain.

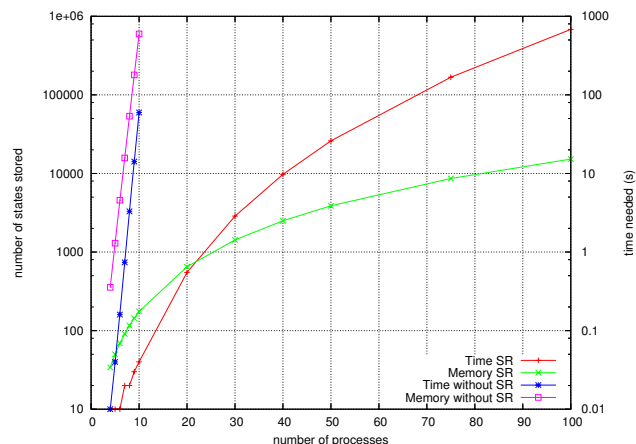


Fig. 1. The effects of symmetry reduction on the time and memory consumption of UPPAAL 4.0 for Fischer's mutual exclusion algorithm.

C, C++ and Ruby. The parser library is released under the LGPL and is ideal for implementing model transformation tools or analysis tools. Java parsers and client stubs for the verification backend are distributed with UPPAAL and may be used by, e.g., domain specific tools (the documentation can be found at our web site). Finally, UPPAAL can be used as a compiler for UPPAAL models, translating the model to a byte-code representation.

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