

Timed pushdown automata and branching vector addition systems

Lorenzo Clemente¹, Sławomir Lasota¹, Ranko Lazić², and
Filip Mazowiecki³

¹University of Warsaw

²University of Warwick

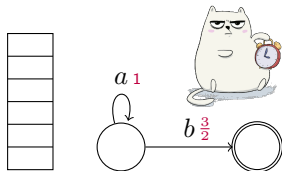
³University of Oxford

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Outline

1. Three models

trPDA



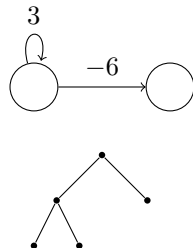
time registers x, y, z

Systems of equations

$$X_i \subseteq \mathbb{Z}$$

$$\left\{ \begin{array}{l} X_1 \supseteq X_2 \cup X_3 \\ X_2 \supseteq X_1 + X_3 \\ X_3 \supseteq \{-1, 1\} \\ \vdots \end{array} \right.$$

1BVASS



2. Reductions between models

3. Decidability

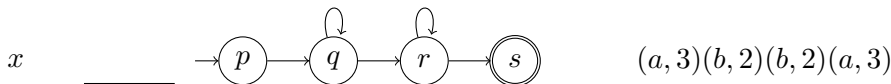
What is time?

$(\mathbb{Q}, \leq, +1)$ or $(\mathbb{Z}, \leq, +1)$

Input $A \times \mathbb{Z}$, $A = \{a, b\}$ (finite in general)

Example

$L = \text{"Palindromes such that } \#_a(w) = \#_b(w)\text{"}$



Strictly subsumes other models:

- Non-monotonic time
- Only one register (or orbit-finiteness)
- [Bouajjani, Echahed, Robbana]
- [Abdulla, Atig, Stenman]

trPDA state of the art

Input: trPDA \mathcal{A}

Problem: non-emptiness of $L(\mathcal{A})$

(universality, equivalence, etc. undecidable)

Unrestricted – undecidable [Bojańczyk and Lasota, 2012]

(no stack, 3 registers)

Restrict to orbit-finite/one register

Timeless stack – EXPTIME -complete

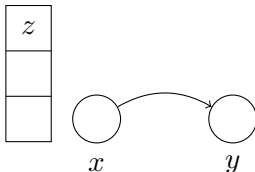
Orbit-finite time stack – in NEXPTIME [Clemente and Lasota, 2015]

Time stack – this paper

Transitions in trPDA

- Push and pop
- Only ϵ -transitions (no input to test non-emptiness)

3 time variables:



Example constraint:

$$(x = y + 1) \wedge (y \leq z + 1 + 1 + 1) \wedge (z \leq y + 1) \wedge (x \leq z)$$

Diagram illustrating the constraints derived from the example constraint:

- $(x = y + 1) \implies x - y \in [1, 1]$
- $(y \leq z + 1 + 1 + 1) \implies y - z \in [1, 3]$
- $(z \leq y + 1) \implies y - z \in [1, 3]$
- $(x \leq z) \implies x - z \in (-\infty, 0]$

Transition: 3 intervals

Systems of equations over \mathbb{Z}

$$X_1 \dots X_n \subseteq \mathbb{Z}$$

Systems of equations \mathcal{S} using: $\cup, \cap, +$ and $\{1\}, \{-1\}$

$$\left\{ \begin{array}{l} X_0 \supseteq t_0 \\ \vdots \\ X_n \supseteq t_n \end{array} \right.$$

solution $\mu(X_i) \rightarrow \mathcal{P}(\mathbb{Z}), \quad \mu(X_i) \supseteq \mu(t_i)$

goal: minimal solution of \mathcal{S}

Example: $X_0 \dots X_k$

$$X_0 \supseteq \{1\} + \{-1\}$$

$$X_{2m} \supseteq X_m + X_m$$

$$X_{2m+1} \supseteq X_m + X_m + \{1\}$$

$$X_0 \supseteq X_0 + X_k$$

minimal solution: $\mu(X_i) = \{i\}$

$$\mu(X_0) = k\mathbb{N}$$

Systems of equations state of the art

Input: system \mathcal{S} , variable X

Problem: non-emptiness of $\mu(X)$

Unrestricted: undecidable [Jež and Okhotin, 2010]

Restricting \cap

No intersections – in PTIME

Intersections with $\{0\}$ – NPTIME-complete [Clemente and Lasota, 2015]
(or any bounded intervals)

Intersections with \mathbb{N} and $(-\mathbb{N})$ – this paper
(or any intervals)

trPDA to systems of equations

Non-emptiness: trPDA $\mathcal{A} \rightarrow$ system (\mathcal{S}, X)

Previously: [Clemente and Lasota, 2015]

- \mathcal{A} with timeless stack $\rightarrow (\mathcal{S}, X)$ with no \cap
- \mathcal{A} with orbit-finite stack $\rightarrow (\mathcal{S}, X)$ with $\cap \{0\}$

This paper:

- \mathcal{A} with stack $\rightarrow (\mathcal{S}, X)$ with $\cap \mathbb{N}, \cap (-\mathbb{N})$

trPDA to systems of equations

trPDA \mathcal{A} with states Q , empty stack acceptance

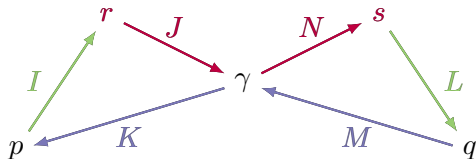
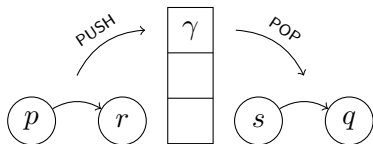
Variables:

$X_{p,q}$ for every $p, q \in Q$

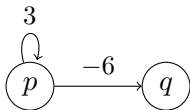
$t \in X_{p,q}$: “reach q from p (the same stack) changing time by t ”

Inclusions:

- $X_{p,p} \supseteq \{0\}$, for every p
- $X_{p,q} \supseteq X_{p,r} + X_{r,q}$, for all p, q, r
- $X_{p,q} \supseteq (I + (X_{r,s} \cap (J + N)) + L) \cap -(K + M)$



Recall 1-VASS



Computations are words: $(p, 0) \xrightarrow{3} (p, 3) \xrightarrow{3} (p, 6) \xrightarrow{-6} (q, 0)$

States Q , transitions $T \subseteq Q \times \mathbb{Z} \times Q$, configurations $Q \times \mathbb{N}$

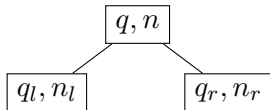
1-BVASS $^\pm$: states Q , transitions $T \subseteq Q^3$, configurations $Q \times \mathbb{N}$

Computations are binary trees:

- leaves $(q_0, 1)$

- inner nodes

$(q, q_l, q_r) \in T$



1-BVASS

$n = n_l + n_r$ if $q \in Q^+$

$n = n_l - n_r$ if $q \in Q^-$

BVASS state of the art

Input: BVASS \mathcal{B} , configuration (q, n)

Problem: reachability of (q, n)

1-BVASS (no subtraction):

Unary encoding – PTIME-complete [Göller et al., 2016]

Binary encoding – PSPACE-complete [Figueira et al., 2017]

In higher dimensions – open

1-BVASS $^{\pm}$ unary/binary – this paper

In higher dimensions – undecidable ($d \geq 6$) [Lazić, 2010]

Decidability BVASS

1-BVASS[±] \mathcal{B} , configuration (q, n)

Lemma

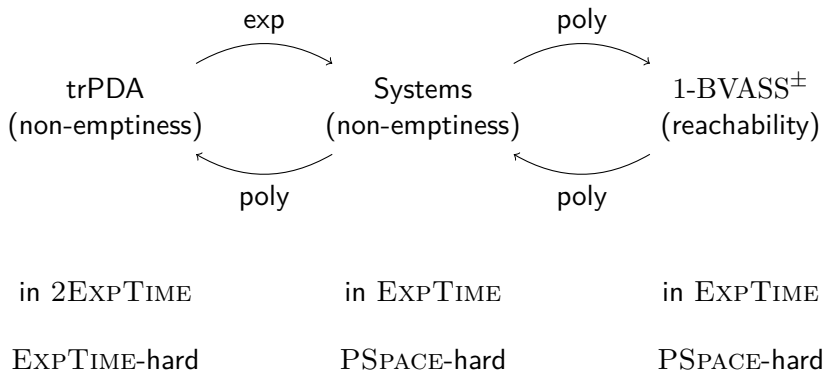
If (q, n) is reachable then there is a computation with all values bounded by $N = \text{poly}(n) \cdot \exp(|B|)$.

Non-emptiness of tree-automaton, states $Q \times \{0 \dots N\}$.

So in EXPTIME

Results summary

Three models/problems



Conclusions

- Complexity gaps
- Reachability of BVASS?
- Reachability of n -BVASS $^{\pm}$ for $n < 6$