

# Advanced Automata Minimization

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# Computationally Hard Automata Problems

- Nondeterministic Büchi Automata
- NFA: Nondeterministic finite-word automata

PSPACE-complete problems.

**Minimization:** Given an automaton  $A$ . What is the minimal size of an automaton  $A'$  s.t.  $\mathcal{L}(A) = \mathcal{L}(A')$  ?  
(The minimal-size automaton for a given language is not unique, in general.)

**In practice:** Find a smaller  $A'$ , not necessarily the smallest.

**Inclusion:** Given two automata  $A, B$ . Is  $\mathcal{L}(A) \subseteq \mathcal{L}(B)$  ?  
Related problems: Equivalence, Universality

PSPACE-completeness is no reason to despair.  
Think of NP-complete problems and SAT-solvers.

# Automata Minimization

- Given an automaton  $A$ . Find a **smaller** automaton  $A'$  s.t.  $\mathcal{L}(A) = \mathcal{L}(A')$ . (Not necessarily the smallest.)
- Algorithmic tradeoff between minimization effort and time for subsequent computations.
- Extensive minimization only worthwhile if hard questions are to be solved, e.g., inclusion, equivalence, universality, LTL model-checking.

# Minimization Techniques

- **Removing dead states.** Remove states that cannot be reached, and states that cannot reach any accepting loop. (Trivial.)
- **Quotienting.** Find an equivalence relation  $\equiv$  on the set of states. Merge equivalence classes into single states, inheriting transitions, and obtain a smaller automaton  $A/\equiv$ .  
If  $\mathcal{L}(A/\equiv) = \mathcal{L}(A)$  then  $\equiv$  is called **good for quotienting (GFQ)**.
- **Transition pruning.** Some transitions can be removed without changing the language. This yields new dead states that can be removed.

But how to find these superfluous transitions, without trial and error?

Idea: Find a suitable relation  $R$  to compare transitions.

Remove all transitions that are  $R$ -smaller than some other transition.

If this preserves the language then  $R$  is called **good for pruning (GFP)**.

**Problem:** Relation  $R$  might be hard to compute. Removing transitions might change  $R$ . Need to remove transitions in parallel.

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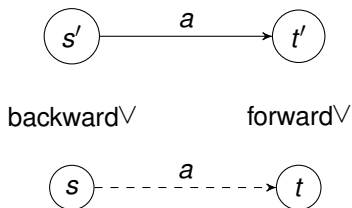
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# Transition Pruning with Semantic Preorders

Compare transitions  $s \xrightarrow{a} t$  and  $s' \xrightarrow{a} t'$  by comparing their source and target.



If  $s'$  is backward-bigger than  $s$ , and  $t'$  is forward-bigger than  $t$  then consider  $s' \xrightarrow{a} t'$  as bigger than  $s \xrightarrow{a} t$  and remove the superfluous transition  $s \xrightarrow{a} t$ .

But does this preserve the language?

Which semantic relations are suitable for backward-bigger and forward-bigger?

# Comparing States of Automata

**Simulation:**  $s \sqsubseteq t$  iff  $t$  can match the computation of  $s$  stepwise.

Simulation game: Spoiler moves  $s \xrightarrow{a} s'$ .

Duplicator replies  $t \xrightarrow{a} t'$ .

Next round of the game starts from  $s', t'$ .

Simulation preorder is **polynomial**.

**Trace inclusion:**  $s \subseteq t$  iff  $t$  has at least the same traces as  $s$ .

Trace game: Spoiler chooses a trace  $s \xrightarrow{a_1} s_1 \xrightarrow{a_2} s_2 \dots$

Duplicator replies with a trace  $t \xrightarrow{a_1} t_1 \xrightarrow{a_2} t_2 \dots$

Trace inclusion is **PSPACE-complete**.

Trace inclusion is generally **much larger** than simulation, but **hard to compute**.

Backward simulation/traces defined similarly with backward steps.

# Acceptance Conditions

**Direct:** If Spoiler accepts then Duplicator must accept **immediately**.

**Delayed:** If Spoiler accepts then Duplicator must accept **eventually** (i.e., within finitely many steps in the future, but there is no fixed bound).

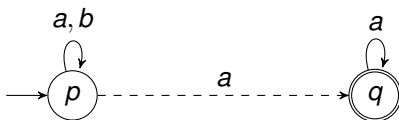
**Fair:** If Spoiler accepts **infinitely often** then Duplicator must accept **infinitely often**.

(This is a weaker condition than delayed. If Spoiler accepts only finitely often then Duplicator has no obligations.)

This yields semantic preorders of direct/delayed/fair simulation and trace inclusion.

Preorders induce equivalences by considering both directions.

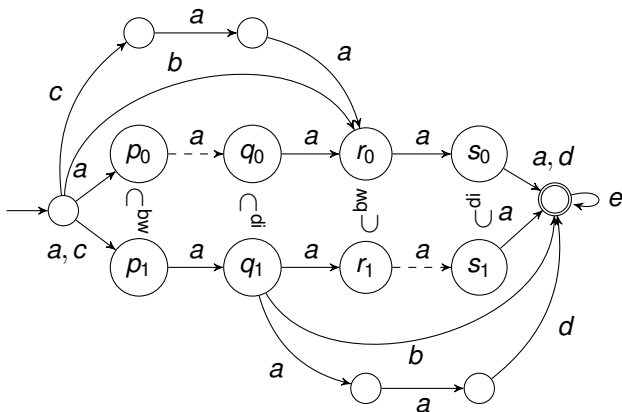
## Delayed/Fair Simulation is **not** Good-for-Pruning



$q \sqsubseteq^{\text{de}} p$ , so the transition  $p \xrightarrow{a} p$  looks larger than  $p \xrightarrow{a} q$ .

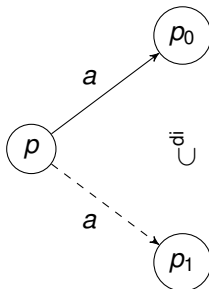
However, removing the dashed transition  $p \xrightarrow{a} q$  makes the language empty.

# Pruning with Direct Forward **and** Backward Trace Inclusion is Incorrect



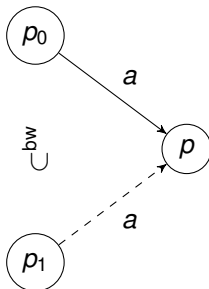
If the ‘smaller’ dashed transitions are removed then the word  $aaaaae^\omega$  is no longer accepted.

# Pruning w.r.t. Direct Forward Trace Inclusion



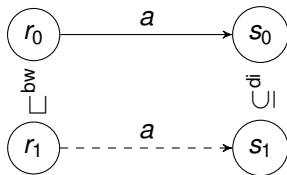
This generalizes [Bustan, Grumberg] who use direct forward simulation.

# Pruning w.r.t. Direct Backward Trace Inclusion



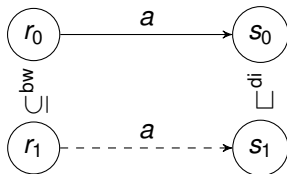
This generalizes [Bustan, Grumberg] who use direct backward simulation.

# Pruning w.r.t. Direct Backward Simulation and Forward Trace Inclusion





# Pruning w.r.t. Direct Backward Trace Inclusion and Forward Simulation



One can have backward simulation and forward trace-inclusion, or vice-versa, but **not both trace-inclusions**.

# Quotienting

- Forward/backward **direct** simulation/trace-equivalence is **good for quotienting (GFQ)**.
- **Fair** simulation/trace-equivalence is **not GFQ**.
- **Delayed simulation** is **GFQ**, but **delayed trace inclusion** is **not GFQ**.
- Delayed multipebble simulation [Etesami, Wilke, Schuller] allows Duplicator to hedge his bets in the simulation game, yielding a larger relation. **GFQ**, but **hard to compute** (exponential in the number of pebbles).

# Computing Semantic Preorders

One would like to use

- Direct backward/forward trace inclusion for pruning (and quotienting).
- Multi-pebble delayed simulation for quotienting.

But these are **hard to compute** (PSPACE-complete membership problem).

**Idea:** Compute good under-approximations of these relations.

**$k$ -Lookahead-simulations:**

- Play a simulation game where Duplicator has information about Spoiler's next  $k$  moves.
- Higher lookahead  $k$  yields larger relations, but is harder to compute.
- Many possible ways of defining lookahead. Most are very bad.
- **Idea:** Degree of lookahead is dynamically under the control of Duplicator, i.e., use only as much as needed (up-to  $k$ ).  
Efficient computation **and** large relations.

# Benchmarks

**GOAL:** Best effort of previous methods. Quotienting/pruning w.r.t. backward/forward simulation. Delayed simulation quotienting. Fair simulation minimization of [Gurumurthy, Bloem, Somenzi].

**Heavy-12:** Our transition pruning and quotienting methods with lookahead simulations of lookahead 12. Much faster than GOAL.

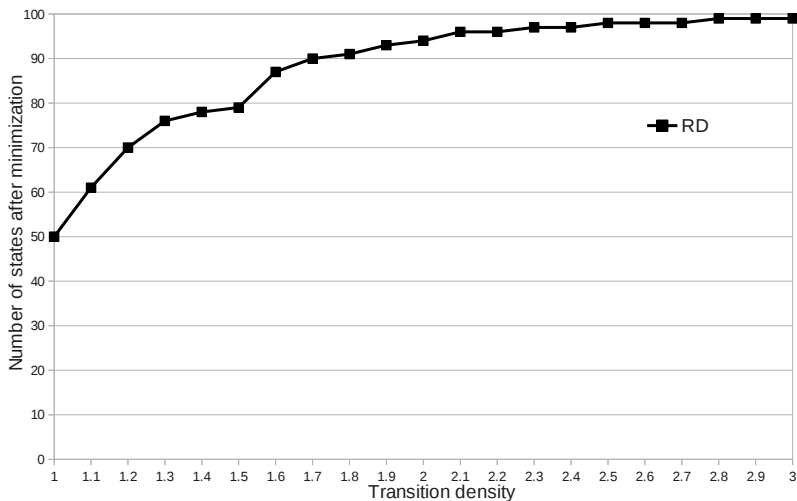
## Test cases.

**Protocols:** Automata derived from protocols like Peterson, Fischer, Phils, Bakery, Mcs. Heavy-12 minimizes better and faster than GOAL; see table in paper.

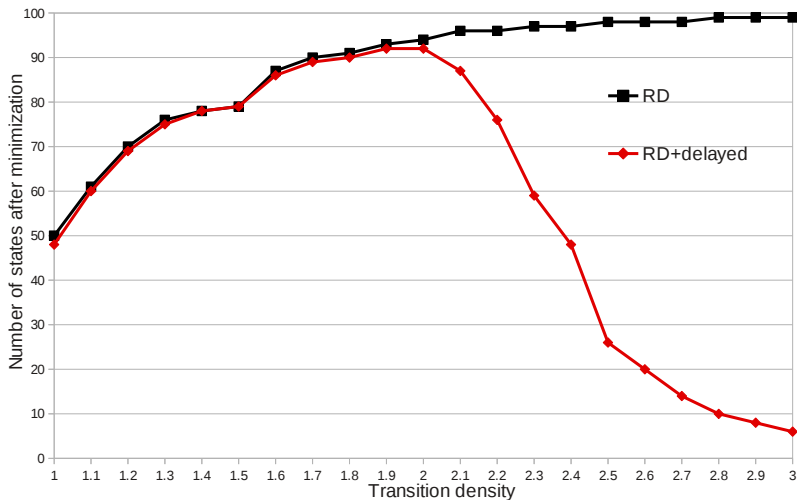
**LTL formulae:** Consider large (size 70) LTL-formulae, transformed into Büchi automata by LTL2BA and minimized by GOAL.  
82% can be minimized further by Heavy-12.  
Average reduction ratio 0.76 for states and 0.68 for transitions.

**Tabakov-Vardi random automata:** Binary alphabet.  
Transition density =  $\frac{\text{\#transitions}}{\text{\# states} * \text{\# symbols}}$ .  
Acceptance density 0.5 (does not matter much).

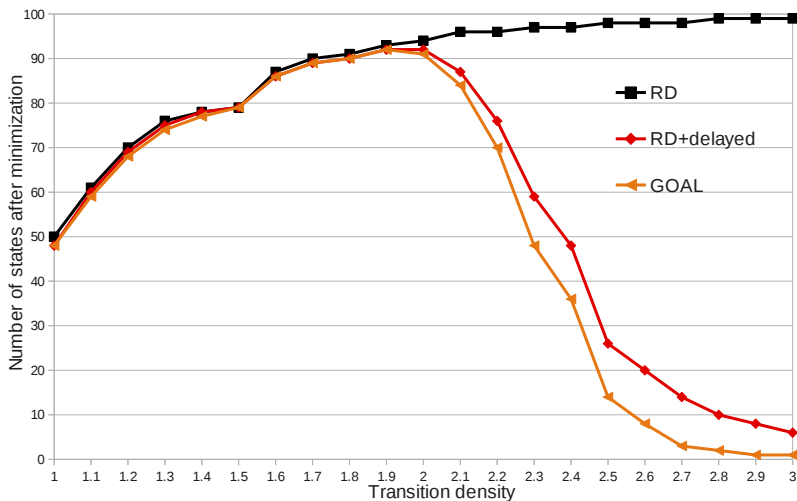
# Benchmark: Remove dead states



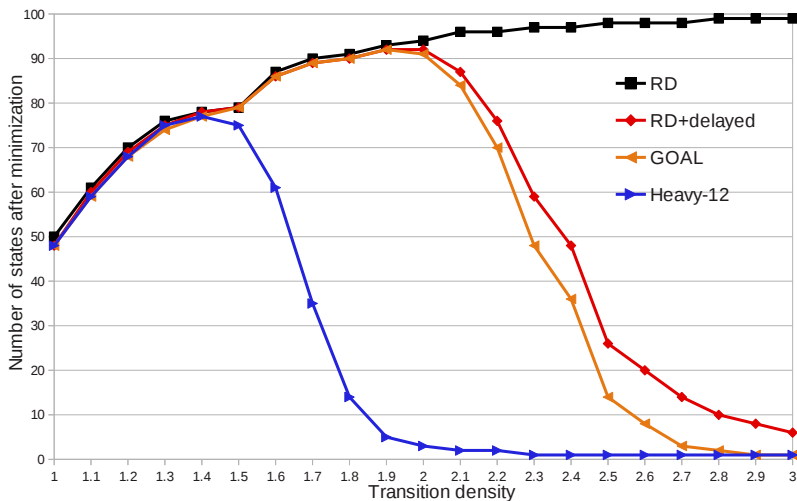
# Benchmark: Remove dead + quotient with delayed sim



# Benchmark: Best effort of GOAL

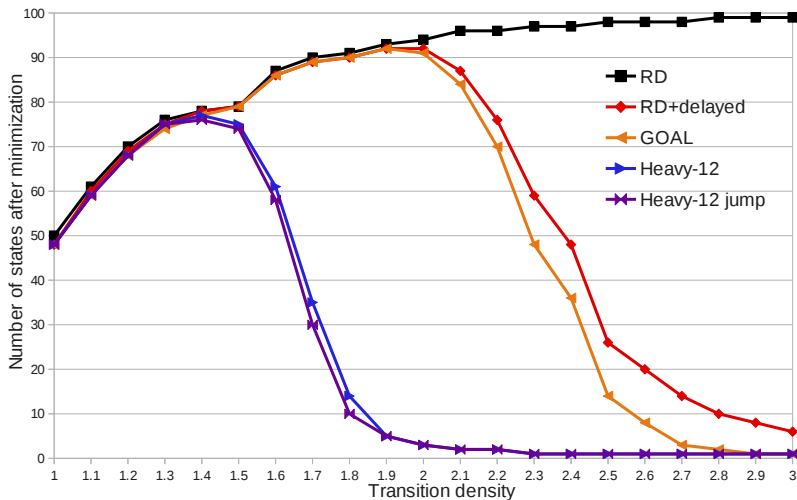


# Benchmark: Heavy-12

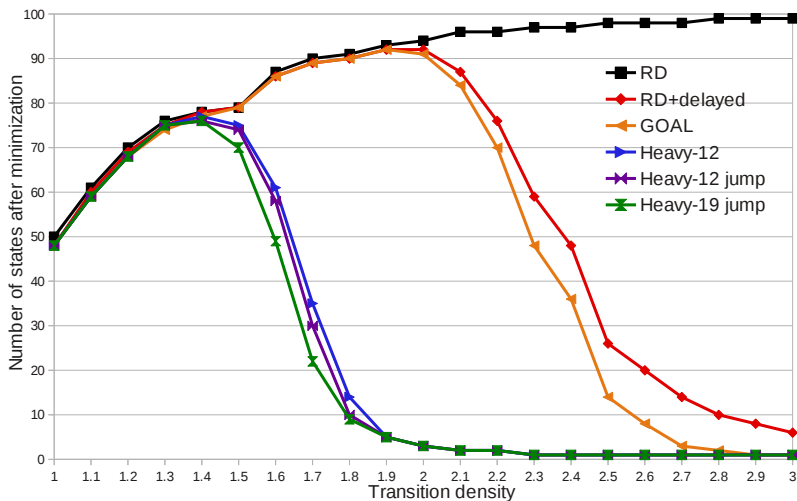




# Benchmark: Heavy-12 plus jumping simulation



# Benchmark: Best. Lookahead 19 plus jumping simulation



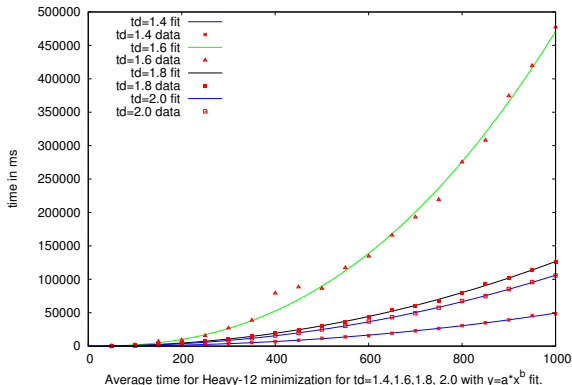
# Scalability: Almost quadratic

Minimize Tabakov-Vardi automata with transition density 1.4, 1.6, 1.8, 2.0.

The size increases from  $n = 50$  to  $n = 1000$  states.

Plot the time and compute the best fit of the function  $time = a * n^b$ .

This yields exponents  $b$  between 2.05 and 2.39. Almost quadratic average-case complexity.



# Language Inclusion Checking

Checking language inclusion  $\mathcal{L}(A) \subseteq \mathcal{L}(B)$  of Büchi automata.

- Minimize  $A$  and  $B$  together.
- (Generalized) simulations can witness inclusion already at this stage (if inclusion holds). This happens very often.
- Additional pruning techniques and witnessing inclusion by jumping lookahead fair simulation.
- If inclusion was not proven yet, then use a complete technique on the now smaller instance  $A', B'$ .

Can check inclusion of Tabakov-Vardi Büchi automata with 1000 states.

Success rate 98% – 100%, depending on density. Much better than previous techniques.

# Conclusion

- Minimize automata with **transition pruning**, not only quotienting.
- Compute good approximations of trace-inclusion and multipebble-simulation by **lookahead-simulations**.
- Much better automata minimization.
- Can check inclusion for much larger Büchi automata.
- Techniques carry over to NFA, but
  - ▶ Good NFA minimization.
  - ▶ NFA inclusion/equivalence checking: Since NFA are simpler, computing global relations like simulation is not always worth the effort.  
→ Talk by Bonchi and Pous.
- Links and tools available at **[www.languageinclusion.org](http://www.languageinclusion.org)**