

# Verification of *Open* Interactive Markov Chains

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Highlights, Paris  
September 19, 2013

# Our contribution

The first **assume-guarantee reasoning**  
for systems with **stochastic continuous time**

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The first **assume-guarantee reasoning**  
for systems with **stochastic continuous time**

- given a system  $S$ ,  
we compute guarantees on  $S \parallel ?$
- we give a **specification formalism** to express assumptions
- given a system  $S$  and assumptions  $\varphi$  on its environment,  
we compute guarantees on  $S \parallel \varphi$



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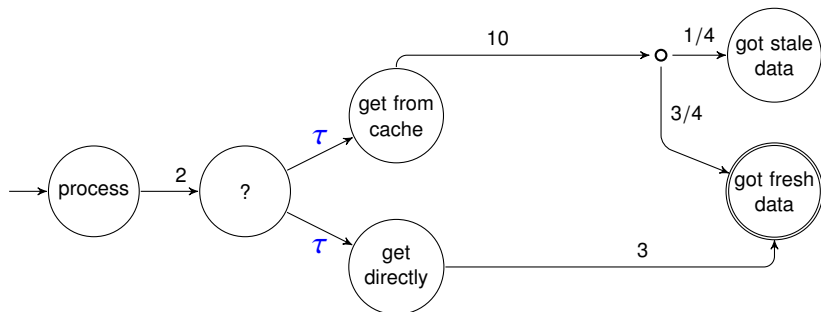
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# Guarantees in continuous-time stochastic systems

Synthesize optimal scheduler  $\sigma$  of system  $S$

$$\sup_{\sigma} Pr_S^{\sigma} [Reach \leq 1.5] = ?$$



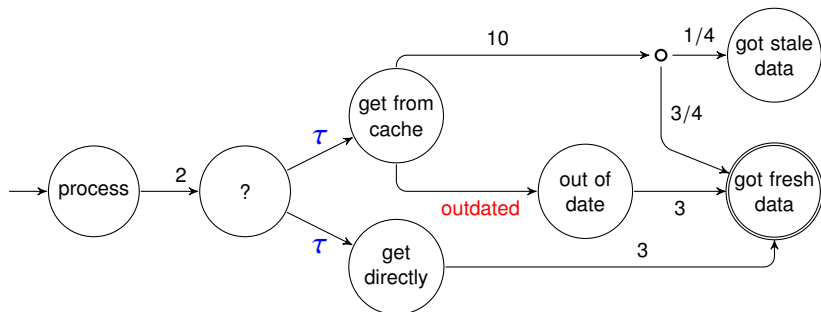
Interactive Markov chains

- similar to continuous-time Markov decision processes
- *compositional* process-algebraic framework

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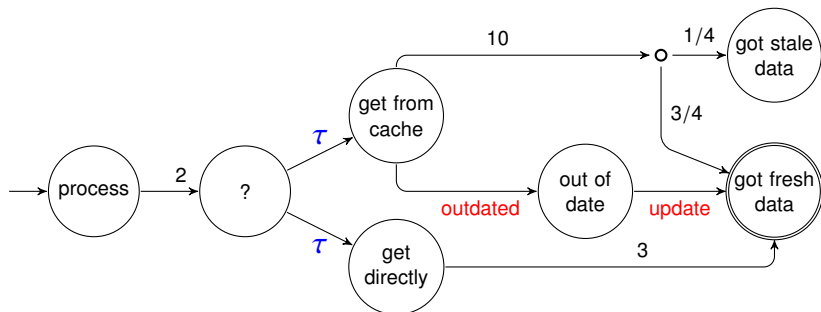
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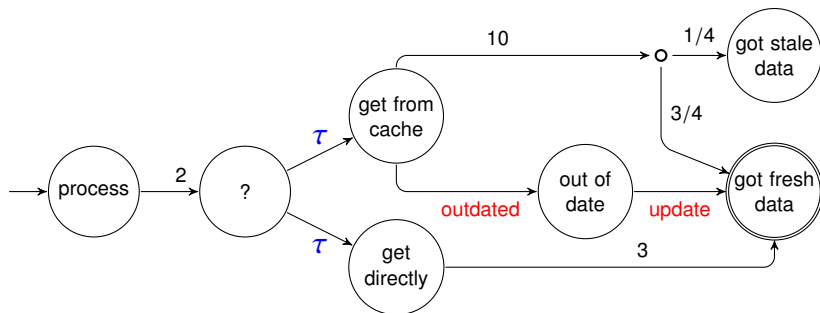
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# Guarantees in continuous-time stochastic systems

Synthesize optimal scheduler  $\sigma$  of system  $S$

$$\sup_{\sigma} \inf_{E \models \varphi} Pr_{S \parallel E}^{\sigma} [Reach \leq 1.5] = ?$$



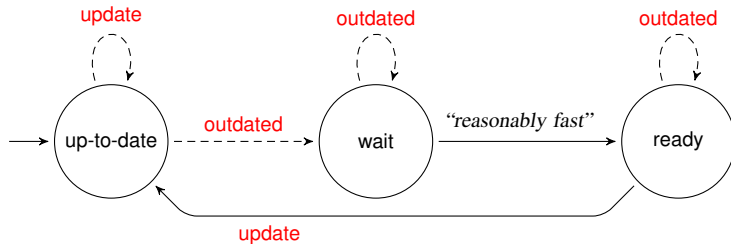


# Specification formalism

We introduce **modal continuous-time automata** (MCA)

- **may/must** transitions as in modal transition systems [Larsen&Thomsen'88]

**Example:** after each **outdated** an **update** is ready *reasonably fast*



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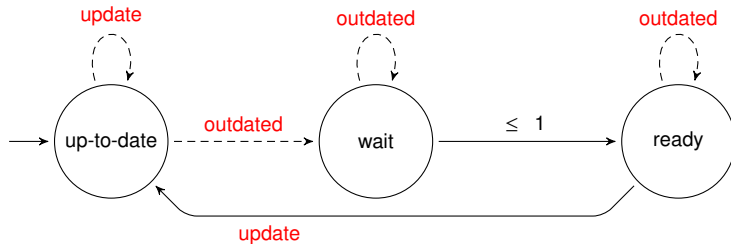
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extending timed automata

[Alur,Courcoubetis&Dill'91]

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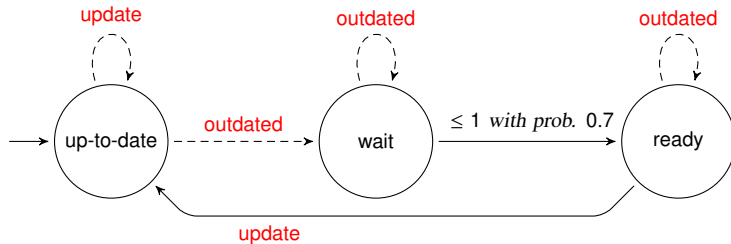
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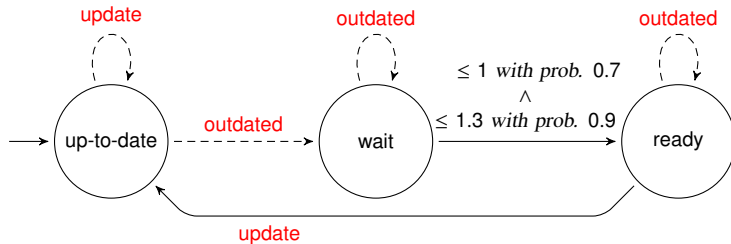
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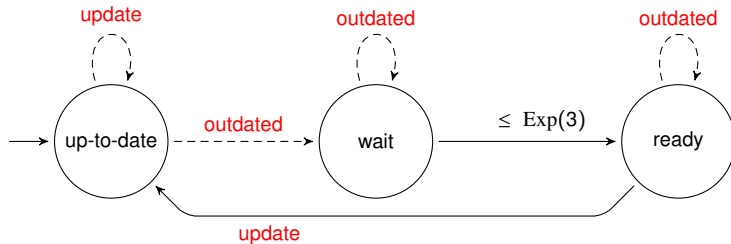
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**Example:** after each **outdated** an **update** is ready within time  $\sim \text{Exp}(3)$

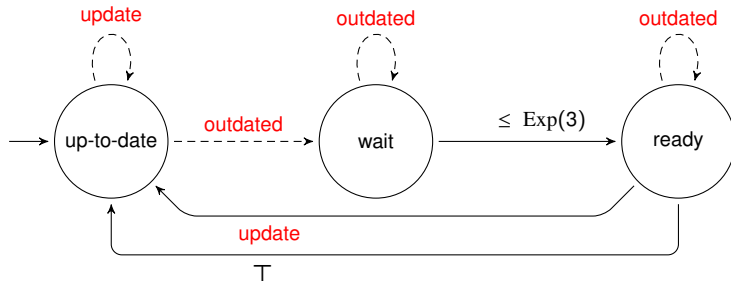


# Specification formalism

We introduce **modal continuous-time automata** (MCA)

- **may/must** transitions as in modal transition systems [Larsen&Thomsen'88]
- **continuous time constraints** extending timed automata [Alur,Courcoubetis&Dill'91]

**Example:** after each **outdated** an **update** is ready within time  $\sim \text{Exp}(3)$



# Main results

## Theorem

For IMC  $S$  without *internal* and *external* edges enabled at once, the guarantee  $\sup_{\sigma} \inf_E Pr_{S||E}^{\sigma} [\text{Reach} \leq T]$  can be  $\varepsilon$ -approximated in polynomial time.

## Theorem

For IMC  $S$  and a modal continuous-time automaton  $\varphi$ , the guarantee  $\sup_{\sigma} \inf_{E \models \varphi} Pr_{S||E}^{\sigma} [\text{Reach} \leq T]$  can be  $\varepsilon$ -approximated in exponential time.

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**Idea:** games with stochastic and non-deterministic time  
*more on Saturday 16:45 (the very last talk!)*

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**Idea:** reduce to  $\sup_{\sigma} \inf_E Pr_{(S \times \varphi)||E}^{\sigma} [\text{Reach} \leq T]$   
games with partial information



# Summary and conclusions

- The first assume-guarantee reasoning on stochastic continuous-time systems
- Specification language **modal continuous-time automata** with *continuous time constraints*

For IMC  $S$  without **internal** and **external** edges enabled at once, the guarantee  $\sup_{\sigma} \inf_E Pr_{S||E}^{\sigma} [Reach \leq T]$  can be  $\varepsilon$ -approximated in polynomial time.

For IMC  $S$  and a modal continuous-time automaton  $\varphi$ , the guarantee  $\sup_{\sigma} \inf_{E \models \varphi} Pr_{S||E}^{\sigma} [Reach \leq T]$  can be  $\varepsilon$ -approximated in exponential time.

## Future work

- lowering the theoretical/practical complexity
- logical specification language