ON TIME-SPACE CLASSES AND THEIR RELATION TO THE THEORY OF REAL ADDITION*

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ABSTRACT: A new lower bound on the computational complexity of the theory of real addition and several related theories is established: any decision procedure for these theories requires either space $2^{\epsilon n}$ or nondeterministic time $2^{\epsilon n^2}$ for some constant $\epsilon > 0$ and infinitely many n.

The proof is based on the families of languages TISP(T(n),S(n)) which can be recognized simultaneously in time T(n) and space S(n) and the conditions under which they form a hierarchy.

I. INTRODUCTION

We consider the computational complexity of the theory of real addition $(\text{Th} < R,+ >)$ and several related theories. Previous results provide the following bounds on the complexity of $\text{Th} < R,+ >$:

1. Lower bound [FiR74]. Any decision procedure for $\text{Th} < R,+ >$ requires nondeterministic time $2^{0(n)}$ for infinitely many n.
2. Upper bound [FeR73]. $\text{Th} < R,+ >$ is decidable within space $2^{0(n)}$.

Because the precise relation between computation time and space remains unknown, there is an exponential discrepancy when upper and lower bounds are both expressed in terms of time or space alone. That is, the exponential lower bound (1) for time is only known to imply a linear space lower bound; the exponential upper bound (2) for space is only known to imply a double exponential upper bound for time.

In this paper we improve the lower bound, showing in particular

Main Theorem: There is an $\epsilon > 0$ such that any decision procedure for $\text{Th} < R,+ >$ requires either more than space $2^{\epsilon n}$ or more than nondeterministic time $2^{\epsilon n^2}$ for infinitely many n.

Let (N)TISP(T(n),S(n)) be the family of languages recognizable by a (non)deterministic Turing machine which runs in time T(n) and space S(n) simultaneously for almost all n. The Main Theorem is equivalent to the assertion that $\text{Th} < R,+ >$ is not a member of $\text{NTISP}(2^{\epsilon n^2},2^{\epsilon n})$ for some $\epsilon > 0$.

We do not interpret the Main Theorem as suggesting the likelihood of an inherent time-space tradeoff among decision algorithms for $\text{Th} < R,+ >$. The Theorem merely leaves open the possibility of such a tradeoff.

The Main Theorem applies to other theories such as monadic predicate calculus and exponentially bounded concatenation theory, all of which can be shown to be log-lin equivalent [SM73, STO74]. Recently Berman has observed that $\text{Th} < R,+ >$ is an example of a language complete under polynomial time reduction in what is essentially the class $\text{Alt}(2^n,n)$ of languages recognizable by alternating machines using time 2^n and n alternations [BER77, CSTO76, KO76]. Our results imply that $\text{NTISP}(2^{n^2},2^n) \subset \text{Alt}(2^{0(n)},0(n))$, an observation which we interpret as supporting the conjecture that Berman's alternating machine complexity classes properly contain the languages recognizable in nondeterministic exponential time.

II. TIME-SPACE CLASSES

The basic computational model used is a deterministic or nondeterministic multitape Turing machine (DTM or NTM). It has a finite number of worktapes, each with a single read-write head which can move in both directions and a single input tape with a two-way read-only head. An accepting computation of a Turing machine M on input x is a computation of M which starts with the word x written on the input tape and the rest of the tapes blank, and terminates in an accepting state. The time of a computation is the number of steps in it; its space is the number of worktape squares visited during the computation (input tape squares not counted). By the linear speed-up theorem [HU69] it suffices to specify time and space bounds only to within a constant factor (e.g., it is unnecessary to specify the base of a logarithm). All time and space bounds are assumed to be positive valued functions on the positive integers.

Definition 1: Let T and S be functions from the positive integers to the positive integers. Then a (n)tisp(T,S)-machine is a (non)deterministic multitape Turing machine which on every input of length n computes for time at most T(n) and space at most S(n).

Remark: Both time and space bounds have to be observed by a single computation.

* Supported by NSF grant 77-19754MCS.

Definition 2: Let Σ be a finite alphabet. Then (N)TISP(T(n),S(n)) is the set of languages $A \subseteq \Sigma^*$ for which there exists a (n)tisp(T,S)-machine M such that for all $x \in \Sigma^*$ (where n denotes the length of x)

i) if $x \in A$ then there is an accepting computation of M on x,

ii) if $x \notin A$ then there is no accepting computation of M on x.

We will show that under some familiar "honesty" conditions [GLI71, SFM73] upon T and S, TISP(NTISP) defines a hierarchy in the following sense: for small increases in the growth rate of T and S new languages can be accepted which could not be accepted before.

Definition 3: [SFM73] A function S(n) is fully constructible if there is a DTM M such that for each input of length n M halts in precisely space S(n) with the string $\#b^{S(n)-2}\#$ on one of its work tapes.

Definition 4: [SFM73] A function T(n) is a running time if there is a DTM M such that for each input of length n, the computation of M has precisely T(n) steps.

Definition 5: Two functions T(n) and S(n) are compatible if each of them is computable by a tisp(T,S)-machine.

Remark: If two functions T and S are compatible then T is a running time and S is fully constructible. It is a major open problem for which pairs of functions the converse holds.

Theorem 1: Let T_1 and S_1 and T_2 and S_2 be compatible functions respectively.

If

i) $T_1(n)\log(T_1(n)) = o(T_2(n))$ and

ii) $S_1(n) = o(S_2(n))$,

then

$$TISP(T_1(n),S_1(n)) \subsetneq TISP(T_2(n),S_2(n)).$$

Proof: It is a well-known result that condition (i) suffices to show that $DTIME(T_1(n))$ (i.e., the class of languages recognized by a DTM within time $T_1(n)$) is properly contained in $DTIME(T_2(n))$. Likewise condition (ii) suffices to obtain a similar result for deterministic space [HU69]. It is straightforward to combine these proofs to obtain the separation result for TISP. We omit the details. □

Theorem 2: Let $S_2(n) > \log(n)$ and let T_1 and S_1 and T_2 and S_2 be compatible respectively.

If

i) $T_1(n+1) = o(T_2(n))$ and

ii) $S_1(n+1) = o(S_2(n))$,

then

$$NTISP(T_1(n), S_1(n)) \subsetneq NTISP(T_2(n), S_2(n)).$$

Proof: Condition (i) suffices to obtain a separation result for nondeterministic time classes whereas condition (ii) is adequate to get a similar result for nondeterministic space classes [SFM73]. We will sketch how to combine the proofs of these results - assuming familiarity with the notation of [SFM73] - to obtain a proof of Theorem 2. The conditions for the program code (Appendix I) are the same as for the time and space theorem (Theorem 1 and Theorem 2). The universal simulator first lays off $S_2(n)$ squares and then behaves like the clocked version. Only in the case when $k \geq T(|x|)$ and $\log(k) \geq S(|x|)$ does the machine M' behave like the machine M. In all other cases it behaves like U_1. □

Basic for proving the Main Theorem is the notion of log-linear reducibility defined in [STO77].

Lemma 1: Let $A \leq_{\text{log-lin}} B$, T(n) and S(n) be monotone nondecreasing functions. Then there is some polynomial p and some constant $c > 0$ such that

i)
$$A \notin \begin{cases} DTIME(T(n) + p(n)) \\ DSPACE(S(n) + \log(n)) \\ NTIME(T(n) + p(n)) \\ NSPACE(S(n) + \log(n)) \end{cases} \Rightarrow B \notin \begin{cases} DTIME(T(cn)) \\ DSPACE(S(cn)) \\ NTIME(T(cn)) \\ NSPACE(S(cn)) \end{cases}$$

ii)
$$A \notin \begin{cases} TISP(T(n)p(n),S(n) + \log(n)) \\ NTISP(T(n)p(n),S(n) + \log(n)) \end{cases} \Rightarrow B \notin \begin{cases} TISP(T(cn),S(cn)) \\ NTISP(T(cn),S(cn)). \end{cases}$$

For a proof of part (i) of this Lemma see [STO74]. Part (ii) can be shown in an analogous way.

III. THE THEORY OF REAL ADDITION

Let $\mathcal{R} = \langle R, + \rangle$ be the structure consisting of the set of all real numbers with the operation of addition. Let $Th(\mathcal{R})$ be the first order theory of $\mathcal{R}$, i.e., the set of all first order sentences true in $\mathcal{R}$.

As a technical tool for the proof of the Main Theorem as stated in the introduction we will use the first order theory of string concatenation and what we call t-bounded concatenation theory. Meyer [FMS76B] has shown that 2^n-bounded concatenation theory is log-lin reducible to $Th(\mathcal{R})$. We will show that $NTISP(2^{n^2}, 2^n)$ is log-lin reducible to 2^n-bounded concatenation theory. The Main Theorem then follows immediately from Lemma 1, Theorem 2 and the transitivity of log-lin reducibility.

Definition 6: Let Σ be a finite set and let $L(\Sigma)$ be the first order language with equality, with constants $\underline{\sigma}$ for each $\sigma \in \Sigma$, and whose only atomic formulae (other than equalities) are of the form $\underline{cat}(x,y,z)$. The elementary theory of concatenation, $CT(\Sigma)$, is the set of true sentences in $L(\Sigma)$ under the following interpretation: Σ^* is the underlying domain, the constant symbols denote the elements $\sigma \in \Sigma$, and for $a,b,c \in \Sigma^*$, $\underline{cat}(a,b,c)$ is true iff a is the concatenation of b and c.

We assume that one of the standard formats is used for writing well formed formulae in $CT(\Sigma)$ which are built up with propositional connectives and quantifiers as usual. The length of a formula is the number of symbols in the formula where subscripts are written in binary.

By bounding the length of strings in $CT(\Sigma)$ (in a sense made precise in the following definition), we obtain bounded concatenation theory.

Definition 7: Let Σ be a finite set and let $L(\Sigma)$ be the first order language with equality, with constants $\underline{\sigma}$ for each $\sigma \in \Sigma$, and whose only atomic formulae (other than equalities) are of the form $\underline{bcat}(x,y,z,\underline{n})$. Then for any function $t:N \to N$, we define t-bounded concatenation theory (t-$BCT(\Sigma)$) as the set of true sentences in $L(\Sigma)$ under the following interpretation: Σ^* is the underlying domain, the constant symbols denote the elements $\sigma \in \Sigma$, and for $a,b,c \in \Sigma^*$, $\underline{bcat}(a,b,c,\underline{n})$ is true iff a is the concatenation of b and c and the length of a is smaller than or equal to $t(n)$, where $\underline{n}$ is the unary numeral for the non-negative integer n.

Remark: As $\underline{n}$ is written in unary the length of the atomic formula $\underline{bcat}(a,b,c,\underline{n})$ is proportional to n plus the size of the variables a,b and c.

In reducing NTISP to bounded concatenation theory it is convenient to restrict the underlying computational model to be a "simple" one-tape Turing machine (STM) [STO77]. This can be done without loss of generality because an STM can simulate a multitape Turing machine with only a quadratic time loss and no space loss [HU69]. Furthermore, we assume that any move which shifts the head off the left end of the tape causes the STM to halt and reject the input.

In the reduction we will describe the computation of an STM with short formulae in 2^{3n}-$BCT(\Sigma)$. Let M be an STM, let Q denote the set of its states and S its tape alphabet. An instantaneous description (i.d.) of M is any word in S^*QS^*. As in [STO77] we define the function $Next_M$: $S^*QS^* \to 2^{S^*QS^*}$, where $Next_M(d)$ is the set of i.d.'s that can occur one step after i.d. d. We remark here that $Next_M$ is length preserving. It suffices to make "local checks" within i.d. d_1 and i.d. d_2 to decide if $d_2 \in Next_M(d_1)$. The reason for this is that in one step only a few symbols around the state symbol can change.

Lemma 2: [STO77] Let M be an STM, $\$ \notin S \cup Q$, and $\Sigma = S \cup Q \cup \{\$\}$. There is a function N_M: $\Sigma^3 \to 2^{\Sigma^3}$ with the following properties:

Let d_1 be any i.d. of M, let k be the length of d_1 and suppose

$\$d_1\$ = d_{10}d_{11}d_{12}\cdots\cdots d_{1k}d_{1,k+1}$ where $d_{1j} \in \Sigma$ for $0 \le j \le k+1$ and

$\$d_2\$ = d_{20}d_{21}d_{22}\cdots\cdots d_{2k}d_{2,k+1}$ where $d_{2j} \in \Sigma$ for $0 \le j \le k+1$

then

$d_2 \in Next_M(d_1)$ iff $d_{2,j-1}d_{2,j}d_{2,j+1} \in N_M(d_{1,j-1}d_{1,j}d_{1,j+1})$ for all $1 \le j \le k$.

For a proof of Lemma 2 see [STO74]. Informally N_M specifies all possibilities of how the symbols of one i.d. can change in one step.

The classes 1-TISP and 1-NTISP are defined for STM's in the same way that TISP and NTISP were given in Definition 2 for (n)tisp(T,S)-machines. Then the main lemma can be stated as following:

Lemma 3: $(\forall A \in 1\text{-}NTISP(2^{n^2}, 2^n))(\exists \Sigma)(A \le_{\text{log-lin}} 2^{3n}\text{-}BCT(\Sigma))$.

Proof: Let M be a nondeterministic STM recognizing $A \subseteq \Theta^*$ simultaneously within time 2^{n^2} and space 2^n. Let Σ be the alphabet for M given in Lemma 2. For each $x \in \Theta^*$ we will describe a sentence S_x in 2^{3n}-$BCT(\Sigma)$ which asserts that there is an accepting computation of M on input x. Thus $x \in A$ iff S_x is true in 2^{3n}-$BCT(\Sigma)$. We will then observe that the function mapping x to S_x is computable in deterministic logspace and is linear bounded, viz., the length of S_x is at most proportional to the length of x. This will then complete the proof.

Let $n = |x|$. The computation to be described is 2^{n^2} steps long, thus a word consisting of a

representation of the whole computation would be of length $2^{0(n^2)}$ and therefore too long to be expressed in the language of 2^{3n}-BCT(Σ). Instead we shall define the formula S_x based on the construction of the formula $P_{k,n}(z)$ which, for all integers k,n and for all $z \in \Sigma^*$, is true iff

1) z is a string of the form $\$z_1\$z_2\$\ldots\$z_{2^n}\$$,

2) z_j represents an i.d., $1 \le j \le 2^n$,

3) $|z_j| = 2^n+1$, $1 \le j \le 2^n$,

4) in some computation of M which is started in i.d. z_j the i.d. z_{j+1} can be reached in at most 2^{kn} steps using space at most 2^n, $1 \le j \le 2^n$.

The formulae $P_{k,n}(z)$ will be defined inductively. First we will write them in CT(Σ) to clarify the idea underlying the construction of the appropriate formulae in 2^{3n}-BCT(Σ).

As a notational convenience we will introduce some abbreviations for formulae in concatenation theory. Let $\Delta = \{\sigma_1,\sigma_2,..,\sigma_k\}$, where $\sigma_i \in \Sigma$ for $1 \le i \le k$.

Abbreviation	Formula
$p = qr$	$cat(p,q,r)$
$p = qrs$	$(\exists x)(p = qx \wedge x = rs)$
$p \in \Delta$	$(p = \sigma_1) \vee \ldots \vee (p = \sigma_k)$
$p \in \Delta^*$	$(\forall x,y,z)(p = xyz \wedge y \in \Sigma \rightarrow y \in \Delta)$
$p \subset q$	$(\exists x,y)(q = xpy)$

We also define for each $k \in N$ a formula $\ell_k(x)$ of concatenation theory which is true iff the length of x is equal to k. We define $\ell_k(x)$ inductively in such a way that the length of the formula itself is proportional to log(k) plus the length of the variable x.

$\ell_1(x) := x \in \Sigma$

$\ell_{2k}(x) := (\exists y,z)(x = yz \wedge (\forall w)((w = y \vee w = z) \rightarrow \ell_k(w)))$

$\ell_{2k+1}(x) := (\exists y,z)(x = yz \wedge \ell_{2k}(y) \wedge \ell_1(z))$

Furthermore we note that the new variables introduced in constructing ℓ_{2k} from ℓ_k need only be distinct from each other and from the free variables of ℓ_k. Thus only a constant number of different variables is needed to construct ℓ_k.

The formula Form(z) will assert conditions 1) - 3) above. We use the convention that in every i.d. the state symbol q is positioned immediately to the left of the symbol being scanned.

$$Form(z) := (\exists w)(z = \$w\$) \wedge \ell_{2^{n(2n+2)}+1}(z) \wedge (\forall z_1)[(\$z_1\$ \subset z \wedge \$ \notin z_1) \rightarrow [\ell_{2n+1}(z_1) \wedge (\exists w_1,w_2,q)(w_1,w_2 \in S^* \wedge q \in Q \wedge w_2 \neq \in \wedge z_1 = w_1qw_2)]] \quad (1)$$

As the induction base we will construct the formula $P_{0,n}(z)$ which satisfies the conditions 1)-3) above and the condition that each of the successive i.d.'s are either identical or follow in one step.

$$P_{0,n}(z) := Form(z) \wedge (\forall z_1,z_2)[(\$z_1\$z_2\$ \subset z \wedge \$ \notin z_1 \wedge \$ \notin z_2) \rightarrow (\exists w_1,s_1,q,s_2,w_2,u)(s_1,s_2 \in S \cup \{\$\} \wedge q \in Q \wedge \$z_1\$ = w_1s_1qs_2w_2 \wedge z_2 = w_1uw_2 \wedge u \in N_M(s_1qs_2))] \quad (2)$$

For the induction step we will write a formula $P_{k+1,n}(z)$ using $P_{k,n}(z)$ as a subformula. The basic idea is that i.d. z_{j+1} can be reached in $2^{(k+1)n}$ steps from i.d. z_j iff there is a string w which has z_j as a prefix, z_{j+1} as a suffix and for which $P_{k,n}(w)$ holds. Thus $P_{k+1,n}(z)$ can be written as:

$$P_{k+1,n}(z) := Form(z) \wedge (\forall z_1,z_2)[(\$z_1\$z_2\$ \subset z \wedge \$ \notin z_1 \wedge \$ \notin z_2) \rightarrow (\exists w_1)(P_{k,n}(\$z_1\$w_1\$z_2\$))]. \quad (3)$$

This completes the inductive construction of $P_{k,n}(z)$.

We remark here that the length of $P_{k+1,n}$ is equal to a constant plus the length of $P_{k,n}$ and the length of the formula Form.

The formula Form is of length O(n). Hence $P_{n,n}$ is of length $O(n^2)$ primarily because of the n occurrences of Form. However, there is a standard "abbreviation trick" [RA75, FeR78] which allows n occurrences of subformulae which are the same - except for the names of the variables - to be replaced by single occurrences of n distinct variables and one occurrence of the subformula. Applying this abbreviation trick to $P_{n,n}$ would yield an equivalent formula $P'_{n,n}$ of length O(nlog(n)).

We wish now to construct a short formula b-$P_{n,n}(z)$ in the language of 2^{3n}-BCT(Σ) which is true iff

conditions 1)-4) as above hold. The straightforward way to obtain such a b-$P_{n,n}$ is to first rewrite $P'_{n,n}$ so that the formula bcat replaces each occurrence of cat. Since there are only proportional to n occurrences of cat in $P'_{n,n}$ and the length of bcat is $0(n)$, one could next apply the standard abbreviation trick on the multiple occurrences of bcat to obtain a formula b-$P_{n,n}$ which is also of length $0(n\log(n))$. This would be enough to prove a version of our Main Theorem with $2^{0(n^2/\log^2(n))}$ in place of $2^{0(n^2)}$ and $2^{0(n/\log(n))}$ in place of $2^{0(n)}$. In the paragraphs below we will give a slightly more complicated construction yielding a formula b-$P_{n,n}$ which is actually of length $0(n)$.

The idea of the construction is as follows: the formula $S_{k,n}(a,b,c,d,e,z)$ will mean the same as bcat(a,b,c,n) and $\ell_{2^n+1}(d)$ and $\ell_{2^n(2^n+2)+1}(e)$ and $P_{k,n}(z)$. Thus the formula $S_{k+1,n}(a,b,c,d,e,z)$ will be equivalent to

$$(\exists f,g,u)S_{k,n}(a,b,c,f,g,u) \wedge (\exists u)S_{k,n}(\in,\in,\in,d,e,u) \wedge P_{k+1,n}(z),$$

(where $\in$ denotes the empty string).

Now note that as in (3) $P_{k+1,n}(z)$ is equivalent to

$$\text{Form}(z) \wedge (\forall z_1,z_2)[(\$z_1\$z_2\$ \subset z \wedge \$ \not\subset z_1 \wedge \$ \not\subset z_2) \rightarrow (\exists w_1,f,g)(S_{k,n}(\in,\in,\in,f,g,\$z_1\$w_1\$z_2\$)]. \qquad (4)$$

Similarly the formula Form(z) as in (1) is equivalent to

$$(\exists w)(z = \$w\$) \wedge (\exists f,u)S_{k,n}(\in,\in,\in,f,z,u) \wedge (\forall z_1)[(\$z_1\$ \subset z \wedge \$ \not\subset z_1) \rightarrow [(\exists g,u)S_{k,n}(\in,\in,\in,z_1,g,u) \wedge (\exists w_1,w_2,q)(w_1,w_2 \in S^* \wedge q \in Q \wedge w_2 \neq \in \wedge z_1 = w_1qw_2)]]. \qquad (5)$$

We observe now that the meaning of formulae equivalent to (4) and (5) does not change if each occurrence of the formula cat is replaced by the formula bcat as the length of all strings in (4) and (5) is bounded by 2^{3n}. Thus (4) and (5) can equivalently be written by replacing each occurrence of cat(p,q,r) by $(\exists f,g,u)S_{k,n}(p,q,r,f,g,u)$. So we can conclude that a formula $S'_{k+1,n}$ equivalent to $S_{k+1,n}$ can be written using a fixed number (independent of k and n) of copies of $S_{k,n}$ plus a fixed number of additional quantifiers, variables and logical connectives. We assume now that the reader is familiar with the technical details of the abbreviation trick and we merely summarize its application to $S'_{k+1,n}$. Applying the abbreviation trick to $S'_{k+1,n}$ yields the formula $S_{k+1,n}$ which has only one copy of $S_{k,n}$ as a subformula and a fixed number of quantifiers, variables and logical connectives. Again we note that no difficulty arises if the new variables introduced in constructing $S_{k+1,n}$ coincide with variables bound inside $S_{k,n}$ Thus only a constant number of additional variables are needed to construct $S_{k+1,n}$ from $S_{0,n}$. Therefore the length of $S_{k+1,n}$ is $0(k+1)$ plus the length of $S_{0,n}$.

We will proceed now in constructing a formula $S_{0,n}(a,b,c,d,e,z)$ whose meaning is the same as bcat(a,b,c,n) and $\ell_{2^n+1}(d)$ and $\ell_{2^n(2^n+2)+1}(e)$ and $P_{0,n}(z)$. As we want the length of $S_{0,n}$ to be proportional to n, we shall require a formula b-$\ell_{m,n}(a,b,c,d)$ written in the language of 2^{3n}-BCT(Σ) whose length is $0(n)$ plus $0(\log(m))$ plus the length of a,b,c and d and which means that bcat(a,b,c,n) holds and that the length of d is m, where m is any integer $\leq 2^{3n}$. The construction of b-$\ell_{m,n}(a,b,c,d)$ is similar to the one for $\ell_m(d)$.

We henceforth use the same notational abbreviations as were introduced for formulae in CT(Σ) except that p = qr is an abbreviation for the formula bcat(p,q,r,n).

$$\text{b-}\ell_{1,n}(a,b,c,d) \quad := \text{bcat}(a,b,c,\underline{n}) \wedge d \in \Sigma.$$

$$\text{b-}\ell_{2m,n}(a,b,c,d) \quad := (\exists e,f)(\forall p,q,r,s)[(< p,q,r,s > = < d,e,f,e > \vee < p,q,r,s > = < a,b,c,f >) \rightarrow \text{b-}\ell_{m,n}(p,q,r,s)]$$

$$\text{b-}\ell_{2m+1,n}(a,b,c,d) := (\exists e,f)(\text{b-}\ell_{2m,n}(d,e,f,e) \wedge \text{b-}\ell_{1,n}(a,b,c,f)).$$

By carefully reusing bound variables in the construction above, only a fixed number of distinct variables is needed. Thus the length of b-$\ell_{m,n}(a,b,c,d)$ is $0(n)$ plus $0(\log(m))$, plus the length of a,b,c and d. Note that therefore the lengths of the formulae b-$\ell_{2^n+1,n}(a,b,c,d)$ and b-$\ell_{2^n(2^n+2)+1,n}(a,b,c,d)$ are both proportional to n plus the length of a,b,c and d.

Now let b-$P_{0,n}(z)$ be the formula obtained from $P_{0,n}(z)$ as given in (2) by first replacing each occurrence of $\ell_m(d)$ by b-$\ell_{m,n}(\in,\in,\in,d)$ and then by substituting the formula bcat(p,q,r,n) for each occurrence of

the formula cat(p,q,r). As only a fixed number (independent of n) of copies of the formulae $\underline{\text{b-}\ell}_{2n+1,n}$, $\underline{\text{b-}\ell}_{2n(2n+2)+1,n}$ and bcat (not including the bcat's inside $\underline{\text{b-}\ell}_{m,n}$) are needed to write the formula $\text{b-P}_{0,n}$, the length of $\text{b-P}_{0,n}(z)$ is proportional to n. Finally, we take $S_{0,n}(a,b,c,d,e,z)$ to be

$$\text{b-}\ell_{2n+1,n}(a,b,c,d) \wedge \text{b-}\ell_{2n(2n+2)+1,n}(\in,\in,\in,e) \wedge \text{b-P}_{0,n}(z).$$

Therefore the length of $S_{0,n}(a,b,c,d,e,z)$ is O(n).

Thus we have shown how to construct a formula $S_{n,n}(a,b,c,d,e,z)$ in the language of 2^{3n}-BCT(Σ) whose meaning is the same as the conjunction of $\text{b-}\ell_{2n+1,n}(a,b,c,d)$, $\text{b-}\ell_{2n(2n+2)+1,n}(\in,\in,\in,e)$ and $\text{b-P}_{n,n}(z)$ and whose length is proportional to n.

Now to complete the construction of S_x we will need, in addition to $S_{n,n}$, a formula $IN_{x,n}(w)$ which is true iff w is the string x. Let $x_1,x_2,\ldots,x_n$ be the successive symbols in x. Then the straightforward way to write the formula $IN_{x,n}(w)$ uses n different variables and therefore its length would be nlog(n). Instead we will define a formula $I_{x,n}(a,b,c,w)$ whose meaning is the same as the conjunction of $IN_{x,n}(w)$ and bcat(a,b,c,$\underline{n}$), such that the length of $I_{x,n}$ is O(n).

$$I_{\in,n}(a,b,c,w) := \text{bcat}(a,b,c,\underline{n}) \wedge w = \in.$$

For $u \in \Sigma^*$, $\sigma \in \Sigma$, we define

$$I_{u\sigma,n}(a,b,c,w) := (\exists w_1)(\forall p,q,r,s)[(\langle p,q,r,s\rangle = \langle w,w_1,\sigma,w_1\rangle \vee \langle p,q,r,s\rangle = \langle a,b,c,w_1\rangle) \rightarrow I_{u,n}(p,q,r,s)].$$

Again we note that $I_{x,n}$ can be constructed using a fixed number of distinct variables.

Finally let S_x be the following formula where q_0 denotes the initial state, q_a the accepting state and $\not b$ the blank tape symbol.

$$S_x := (\exists w,b,z,u)[I_{x,n}(\in,\in,\in,w) \wedge b \in \{\not b\}^* \wedge \$q_0wb\$q_au\$ \subset z \wedge S_{n,n}(\in,\in,\in,q_au,z,z)]$$

Clearly $x \in A$ iff S_x is (true) in 2^{3n}-BCT(Σ). We have already shown that the function mapping x to S_x is linear bounded. The results of [SM73,LIN74] may be used to show that the computation of S_x can be carried out within deterministic logspace; we leave the verification of this final claim to the reader. Hence the transformation of x to S_x implies that $A \leq_{\text{log-lin}} 2^{3n}$-BCT($\Sigma$). □

Remark: For any $c > 1$ and any alphabet Σ there exists an alphabet Θ such that 2^{cn}-BCT(Σ) is log-lin reducible to 2^n-BCT(Θ)

Lemma 3 and the preceding remark, together with the reduction of 2^n-BCT(Σ) to Th$\langle \mathbb{R},+\rangle$ completes the proof of the Main Theorem.

IV. OPEN PROBLEMS

In this paper we classified logical theories with respect to both computation time and space. The basic open question remaining is to characterize the complexity of Th$\langle \mathbb{R},+\rangle$ (or equivalently Alt(2^n,n)) more precisely in terms of time and space. Note that the claims that Alt(2^n,n) is equivalent to NTIME(2^n) or equivalent to SPACE(2^n), or both for that matter, remain consistent with our Main Theorem.

A second related open problem is to improve the known lower bounds on the complexity of Presburger Arithmetic. Such improvements do not follow directly by the same method used to bound Th$\langle \mathbb{R},+\rangle$, as can easily be seen by parameterizing our main result. We have shown that for $f(n) = 2^n$ the class NTISP($f(n)^n$,f(n)) reduces to Th$\langle \mathbb{R},+\rangle$. The same proof shows only that NTISP($g(n)^n$,g(n)) reduces to Presburger Arithmetic where $g(n) = 2^{2^n}$, a result which degenerates to the known result [FiR74] that NTIME(2^{2^n}) reduces to Presburger Arithmetic.

We hope that the framework we have set up leads to a better understanding of the relation between the computational resources time and space.

ACKNOWLEDGEMENTS

We wish to thank Jeanne Ferrante and Karl Winklmann for their careful reading and helpful comments concerning this paper.

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