

How to be both rich and happy:
**Combining quantitative and qualitative
strategic reasoning in multi-player games**

Valentin Goranko

Technical University of Denmark
and

Nils Bulling

Clausthal University of Technology, Germany

Highlights'2013

Paris, September 21, 2013

Introduction:

strategic abilities of agents in multi-player games

Two traditions:

Introduction:

strategic abilities of agents in multi-player games

Two traditions:

Quantitative: study of the abilities of rational players achieve
quantitative objectives: optimizing payoffs or, more generally,
preferences on outcomes.

Introduction:

strategic abilities of agents in multi-player games

Two traditions:

Quantitative: study of the abilities of rational players achieve
quantitative objectives: optimizing payoffs or, more generally,
preferences on outcomes.

Typical models:

normal form games, repeated games, extensive games.

Introduction:

strategic abilities of agents in multi-player games

Two traditions:

Quantitative: study of the abilities of rational players achieve
quantitative objectives: optimizing payoffs or, more generally,
preferences on outcomes.

Typical models:

normal form games, repeated games, extensive games.

Qualitative: study of strategic abilities of players for achieving
qualitative objectives: reaching or maintaining outcome states with
desired properties, e.g., winning states, or safe states, etc.

Introduction:

strategic abilities of agents in multi-player games

Two traditions:

Quantitative: study of the abilities of rational players achieve
quantitative objectives: optimizing payoffs or, more generally,
preferences on outcomes.

Typical models:

normal form games, repeated games, extensive games.

Qualitative: study of strategic abilities of players for achieving
qualitative objectives: reaching or maintaining outcome states with
desired properties, e.g., winning states, or safe states, etc.

Typical models:

multi-agent transition systems, a.k.a. concurrent game models.

Introduction:

strategic abilities of agents in multi-player games

Two traditions:

Quantitative: study of the abilities of rational players achieve
quantitative objectives: optimizing payoffs or, more generally,
preferences on outcomes.

Typical models:

normal form games, repeated games, extensive games.

Qualitative: study of strategic abilities of players for achieving
qualitative objectives: reaching or maintaining outcome states with
desired properties, e.g., winning states, or safe states, etc.

Typical models:

multi-agent transition systems, a.k.a. concurrent game models.

We develop a logical framework combining both traditions.

Introduction:

strategic abilities of agents in multi-player games

Two traditions:

Quantitative: study of the abilities of rational players achieve
quantitative objectives: optimizing payoffs or, more generally, preferences on outcomes.

Typical models:

normal form games, repeated games, extensive games.

Qualitative: study of strategic abilities of players for achieving
qualitative objectives: reaching or maintaining outcome states with desired properties, e.g., winning states, or safe states, etc.

Typical models:

multi-agent transition systems, a.k.a. concurrent game models.

We develop a logical framework combining both traditions.

Builds on several existing types of models and logics.

Towards quantitative reasoning:
Concurrent game models with payoffs and guards

Towards quantitative reasoning:

Concurrent game models with payoffs and guards

Concurrent game model with payoffs and guards (GGMPG):

extend concurrent game models by associating with every state a strategic game with payoffs. Thus:

Towards quantitative reasoning:

Concurrent game models with payoffs and guards

Concurrent game model with payoffs and guards (GGMPG):

extend concurrent game models by associating with every state a strategic game with payoffs. Thus:

- at every state each player chooses an **action**; all actions are applied simultaneously and determine transition to **successor state**;

Towards quantitative reasoning:

Concurrent game models with payoffs and guards

Concurrent game model with payoffs and guards (GGMPG):

extend concurrent game models by associating with every state a strategic game with payoffs. Thus:

- at every state each player chooses an **action**; all actions are applied simultaneously and determine transition to **successor state**;
- the collective action also determines each player's **payoff**;

Towards quantitative reasoning: Concurrent game models with payoffs and guards

Concurrent game model with payoffs and guards (GGMPG):

extend concurrent game models by associating with every state a strategic game with payoffs. Thus:

- at every state each player chooses an **action**; all actions are applied simultaneously and determine transition to **successor state**;
- the collective action also determines each player's **payoff**;
- same happens at the successor state, etc., thus eventually generating an infinite play;

Towards quantitative reasoning: Concurrent game models with payoffs and guards

Concurrent game model with payoffs and guards (GGMPG):

extend concurrent game models by associating with every state a strategic game with payoffs. Thus:

- at every state each player chooses an **action**; all actions are applied simultaneously and determine transition to **successor state**;
- the collective action also determines each player's **payoff**;
- same happens at the successor state, etc., thus eventually generating an infinite play;

So, players **accumulate utilities** in the course of the play;

Towards quantitative reasoning: Concurrent game models with payoffs and guards

Concurrent game model with payoffs and guards (GGMPG):

extend concurrent game models by associating with every state a strategic game with payoffs. Thus:

- at every state each player chooses an **action**; all actions are applied simultaneously and determine transition to **successor state**;
- the collective action also determines each player's **payoff**;
- same happens at the successor state, etc., thus eventually generating an infinite play;

So, players **accumulate utilities** in the course of the play;

The players' current utility values determine their available actions at the current state, by means of **guards** – arithmetical constraints over the current utilities.

Towards quantitative reasoning: Concurrent game models with payoffs and guards

Concurrent game model with payoffs and guards (GGMPG):

extend concurrent game models by associating with every state a strategic game with payoffs. Thus:

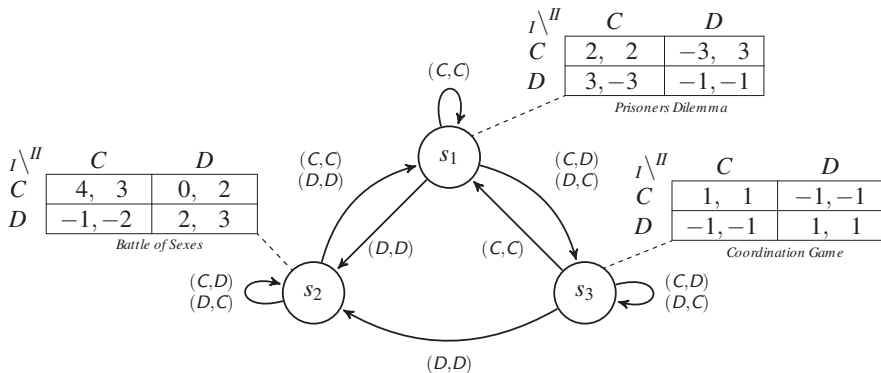
- at every state each player chooses an **action**; all actions are applied simultaneously and determine transition to **successor state**;
- the collective action also determines each player's **payoff**;
- same happens at the successor state, etc., thus eventually generating an infinite play;

So, players **accumulate utilities** in the course of the play;

The players' current utility values determine their available actions at the current state, by means of **guards** – arithmetical constraints over the current utilities.

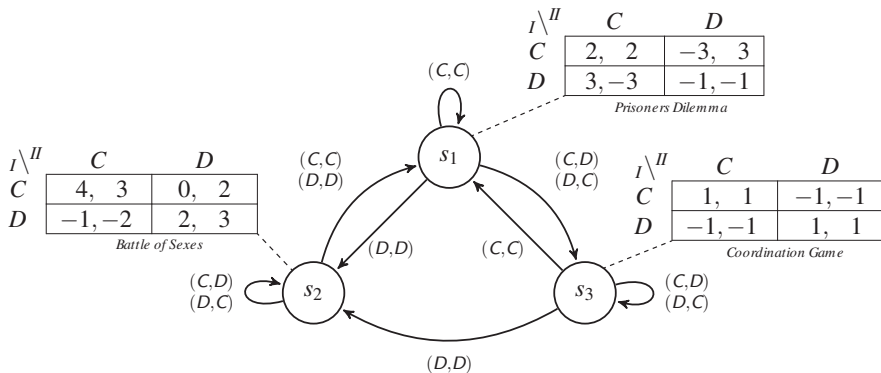
CGMPGs: games with qualitative and quantitative objectives.

Guarded concurrent game model with payoffs: example



The guards for both players are defined at each state so that the player may:

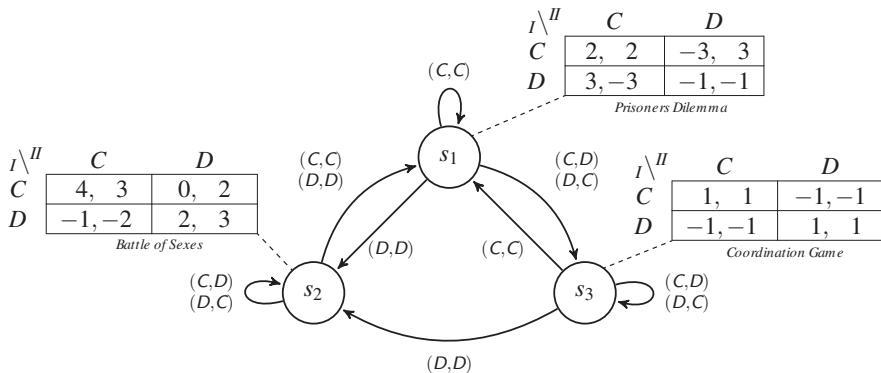
Guarded concurrent game model with payoffs: example



The guards for both players are defined at each state so that the player may:

- apply any action if she has a positive current accumulated utility,

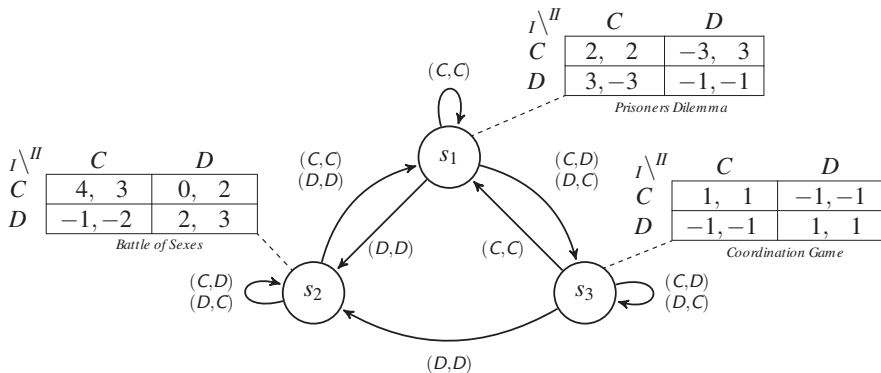
Guarded concurrent game model with payoffs: example



The guards for both players are defined at each state so that the player may:

- apply any action if she has a positive current accumulated utility,
- only apply action C if she has accumulated utility 0,

Guarded concurrent game model with payoffs: example



The guards for both players are defined at each state so that the player may:

- apply any action if she has a positive current accumulated utility,
- only apply action C if she has accumulated utility 0,
- must play an action maximizing her minimum payoff in the current game if she has a negative accumulated utility.

Configurations, plays and histories in a GCGMP

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:
a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:
a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.
The set of possible configurations: $\text{Con}(\mathfrak{M}) = \mathcal{S} \times D^{|\mathbb{A}|}$.

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:
a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.

The set of possible configurations: $\text{Con}(\mathfrak{M}) = \mathcal{S} \times D^{|\mathbb{A}|}$.

Partial configuration transition function:

$$\widehat{\text{out}} : \text{Con}(\mathfrak{M}) \times \text{Act}_{\mathbb{A}} \dashrightarrow \text{Con}(\mathfrak{M})$$

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:
a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.

The set of possible configurations: $\text{Con}(\mathfrak{M}) = \mathcal{S} \times D^{|\mathbb{A}|}$.

Partial configuration transition function:

$$\widehat{\text{out}} : \text{Con}(\mathfrak{M}) \times \text{Act}_{\mathbb{A}} \dashrightarrow \text{Con}(\mathfrak{M})$$

where $\widehat{\text{out}}((s, \vec{u}), \vec{\alpha}) = (s', \vec{u}')$ iff:

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:
a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.

The set of possible configurations: $\text{Con}(\mathfrak{M}) = \mathcal{S} \times D^{|\mathbb{A}|}$.

Partial configuration transition function:

$$\widehat{\text{out}} : \text{Con}(\mathfrak{M}) \times \text{Act}_{\mathbb{A}} \dashrightarrow \text{Con}(\mathfrak{M})$$

where $\widehat{\text{out}}((s, \vec{u}), \vec{\alpha}) = (s', \vec{u}')$ iff:

(i) $\text{out}(s, \vec{\alpha}) = s'$

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:

a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.

The set of possible configurations: $\text{Con}(\mathfrak{M}) = \mathcal{S} \times D^{|\mathbb{A}|}$.

Partial configuration transition function:

$$\widehat{\text{out}} : \text{Con}(\mathfrak{M}) \times \text{Act}_{\mathbb{A}} \dashrightarrow \text{Con}(\mathfrak{M})$$

where $\widehat{\text{out}}((s, \vec{u}), \vec{\alpha}) = (s', \vec{u}')$ iff:

- (i) $\text{out}(s, \vec{\alpha}) = s'$
- (ii) the value u_a assigned to v_a satisfies $g_a(s, \alpha_a)$ for each $a \in \mathbb{A}$

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:

a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.

The set of possible configurations: $\text{Con}(\mathfrak{M}) = \mathcal{S} \times D^{|\mathbb{A}|}$.

Partial configuration transition function:

$$\widehat{\text{out}} : \text{Con}(\mathfrak{M}) \times \text{Act}_{\mathbb{A}} \dashrightarrow \text{Con}(\mathfrak{M})$$

where $\widehat{\text{out}}((s, \vec{u}), \vec{\alpha}) = (s', \vec{u}')$ iff:

- (i) $\text{out}(s, \vec{\alpha}) = s'$
- (ii) the value u_a assigned to v_a satisfies $g_a(s, \alpha_a)$ for each $a \in \mathbb{A}$
- (iii) $u'_a = u_a + \text{payoff}_a(s, \vec{\alpha})$ for each $a \in \mathbb{A}$

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:

a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.

The set of possible configurations: $\text{Con}(\mathfrak{M}) = \mathcal{S} \times D^{|\mathbb{A}|}$.

Partial configuration transition function:

$$\widehat{\text{out}} : \text{Con}(\mathfrak{M}) \times \text{Act}_{\mathbb{A}} \dashrightarrow \text{Con}(\mathfrak{M})$$

where $\widehat{\text{out}}((s, \vec{u}), \vec{\alpha}) = (s', \vec{u}')$ iff:

- (i) $\text{out}(s, \vec{\alpha}) = s'$
- (ii) the value u_a assigned to v_a satisfies $g_a(s, \alpha_a)$ for each $a \in \mathbb{A}$
- (iii) $u'_a = u_a + \text{payoff}_a(s, \vec{\alpha})$ for each $a \in \mathbb{A}$

The **configuration graph on \mathfrak{M} with an initial configuration (s_0, \vec{u}_0)** consists of all configurations in \mathfrak{M} reachable from (s_0, \vec{u}_0) by $\widehat{\text{out}}$.

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:

a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.

The set of possible configurations: $\text{Con}(\mathfrak{M}) = \mathcal{S} \times D^{|\mathbb{A}|}$.

Partial configuration transition function:

$$\widehat{\text{out}} : \text{Con}(\mathfrak{M}) \times \text{Act}_{\mathbb{A}} \dashrightarrow \text{Con}(\mathfrak{M})$$

where $\widehat{\text{out}}((s, \vec{u}), \vec{\alpha}) = (s', \vec{u}')$ iff:

- (i) $\text{out}(s, \vec{\alpha}) = s'$
- (ii) the value u_a assigned to v_a satisfies $g_a(s, \alpha_a)$ for each $a \in \mathbb{A}$
- (iii) $u'_a = u_a + \text{payoff}_a(s, \vec{\alpha})$ for each $a \in \mathbb{A}$

The **configuration graph on \mathfrak{M} with an initial configuration (s_0, \vec{u}_0)** consists of all configurations in \mathfrak{M} reachable from (s_0, \vec{u}_0) by $\widehat{\text{out}}$.

A **play** in \mathfrak{M} : an infinite sequence $\pi = c_0 \vec{\alpha}_0, c_1 \vec{\alpha}_1, \dots$ from $(\text{Con}(\mathfrak{M}) \times \text{Act})^\omega$ such that $c_n \in \widehat{\text{out}}(c_{n-1}, \vec{\alpha}_{n-1})$ for all $n > 0$.

Configurations, plays and histories in a GCGMP

Configuration in $\mathfrak{M} = (\mathcal{S}, \text{payoff}, \{g_a\}_{a \in \mathbb{A}}, \{d_a\}_{a \in \mathbb{A}})$:

a pair (s, \vec{u}) of a state s and a vector $\vec{u} = (u_1, \dots, u_k)$ of currently accumulated utilities of the agents at that state.

The set of possible configurations: $\text{Con}(\mathfrak{M}) = \mathcal{S} \times D^{|\mathbb{A}|}$.

Partial configuration transition function:

$$\widehat{\text{out}} : \text{Con}(\mathfrak{M}) \times \text{Act}_{\mathbb{A}} \dashrightarrow \text{Con}(\mathfrak{M})$$

where $\widehat{\text{out}}((s, \vec{u}), \vec{\alpha}) = (s', \vec{u}')$ iff:

- (i) $\text{out}(s, \vec{\alpha}) = s'$
- (ii) the value u_a assigned to v_a satisfies $g_a(s, \alpha_a)$ for each $a \in \mathbb{A}$
- (iii) $u'_a = u_a + \text{payoff}_a(s, \vec{\alpha})$ for each $a \in \mathbb{A}$

The **configuration graph on \mathfrak{M} with an initial configuration (s_0, \vec{u}_0)** consists of all configurations in \mathfrak{M} reachable from (s_0, \vec{u}_0) by $\widehat{\text{out}}$.

A **play** in \mathfrak{M} : an infinite sequence $\pi = c_0 \vec{\alpha}_0, c_1 \vec{\alpha}_1, \dots$ from $(\text{Con}(\mathfrak{M}) \times \text{Act})^\omega$ such that $c_n \in \widehat{\text{out}}(c_{n-1}, \vec{\alpha}_{n-1})$ for all $n > 0$.

A **history**: any finite initial sequence of a play in $\text{Plays}_{\mathfrak{M}}$.

Strategies

Strategies

A **strategy** of a player \mathbf{a} is a function $s_{\mathbf{a}} : \text{Hist} \rightarrow \text{Act}$ that respects the guards, i.e., if $s_{\mathbf{a}}(h) = \alpha$ then $h^u[\text{last}]_{\mathbf{a}} \models g_{\mathbf{a}}(h^s[\text{last}], \alpha)$.

Strategies

A **strategy** of a player \mathbf{a} is a function $s_{\mathbf{a}} : \text{Hist} \rightarrow \text{Act}$ that respects the guards, i.e., if $s_{\mathbf{a}}(h) = \alpha$ then $h^u[\text{last}]_{\mathbf{a}} \models g_{\mathbf{a}}(h^s[\text{last}], \alpha)$.

NB: strategies are based on **histories of configurations and actions**.

Strategies

A **strategy** of a player \mathbf{a} is a function $s_{\mathbf{a}} : \text{Hist} \rightarrow \text{Act}$ that respects the guards, i.e., if $s_{\mathbf{a}}(h) = \alpha$ then $h^u[\text{last}]_{\mathbf{a}} \models g_{\mathbf{a}}(h^s[\text{last}], \alpha)$.

NB: strategies are based on **histories of configurations and actions**.

Some natural restrictions: **state-**, **action-**, or **configuration-based**; **memoryless**, **bounded memory**, of **perfect recall** strategies.

Strategies

A **strategy** of a player \mathbf{a} is a function $s_{\mathbf{a}} : \text{Hist} \rightarrow \text{Act}$ that respects the guards, i.e., if $s_{\mathbf{a}}(h) = \alpha$ then $h^u[\text{last}]_{\mathbf{a}} \models g_{\mathbf{a}}(h^s[\text{last}], \alpha)$.

NB: strategies are based on **histories of configurations and actions**.

Some natural restrictions: **state-**, **action-**, or **configuration-based**; **memoryless**, **bounded memory**, of **perfect recall** strategies.

We assume that two classes of strategies \mathcal{S}^p and \mathcal{S}^o are fixed as parameters, resp. for the proponents and opponents to select from.

Strategies

A **strategy** of a player \mathbf{a} is a function $s_{\mathbf{a}} : \text{Hist} \rightarrow \text{Act}$ that respects the guards, i.e., if $s_{\mathbf{a}}(h) = \alpha$ then $h^u[\text{last}]_{\mathbf{a}} \models g_{\mathbf{a}}(h^s[\text{last}], \alpha)$.

NB: strategies are based on **histories of configurations and actions**.

Some natural restrictions: **state-**, **action-**, or **configuration-based**; **memoryless**, **bounded memory**, of **perfect recall** strategies.

We assume that two classes of strategies \mathcal{S}^p and \mathcal{S}^o are fixed as parameters, resp. for the proponents and opponents to select from.

A unique **outcome_play** $_{\mathfrak{M}}(c, (s_A, s_{\mathbb{A} \setminus A}))$ emerges from the execution of any strategy profile $(s_A, s_{\mathbb{A} \setminus A})$ from configuration c .

Strategies

A **strategy** of a player \mathbf{a} is a function $s_{\mathbf{a}} : \text{Hist} \rightarrow \text{Act}$ that respects the guards, i.e., if $s_{\mathbf{a}}(h) = \alpha$ then $h^u[\text{last}]_{\mathbf{a}} \models g_{\mathbf{a}}(h^s[\text{last}], \alpha)$.

NB: strategies are based on **histories of configurations and actions**.

Some natural restrictions: **state-**, **action-**, or **configuration-based**; **memoryless**, **bounded memory**, of **perfect recall** strategies.

We assume that two classes of strategies \mathcal{S}^p and \mathcal{S}^o are fixed as parameters, resp. for the proponents and opponents to select from.

A unique **outcome_play** $_{\mathfrak{M}}(c, (s_A, s_{\mathbb{A} \setminus A}))$ emerges from the execution of any strategy profile $(s_A, s_{\mathbb{A} \setminus A})$ from configuration c .

Effective strategies: bounded memory strategies determined by transducers with transitions and outputs defined by arithmetical constraints on the current configurations.

QATL*: Quantitative extension of ATL*

QATL*: Quantitative extension of ATL*

Language **AC** of arithmetic formulae over accumulated utilities:
Boolean combinations of equalities and inequalities between terms
built by applying addition over a set of variables $V_{\mathbb{A}} = \{v_{\mathbf{a}} \mid \mathbf{a} \in \mathbb{A}\}$
for the accumulated utilities and a fixed set X of constants.

QATL*: Quantitative extension of ATL*

Language **AC** of arithmetic formulae over accumulated utilities:
Boolean combinations of equalities and inequalities between terms
built by applying addition over a set of variables $V_{\mathbb{A}} = \{v_{\mathbf{a}} \mid \mathbf{a} \in \mathbb{A}\}$
for the accumulated utilities and a fixed set X of constants.

Language of QATL*. Extends ATL* with formulae from AC:

QATL*: Quantitative extension of ATL*

Language **AC** of arithmetic formulae over accumulated utilities:
Boolean combinations of equalities and inequalities between terms
built by applying addition over a set of variables $V_{\mathbb{A}} = \{v_{\mathbf{a}} \mid \mathbf{a} \in \mathbb{A}\}$
for the accumulated utilities and a fixed set X of constants.

Language of QATL*. Extends ATL* with formulae from AC:

State formulae $\varphi ::= p \mid \mathbf{ac} \mid \neg\varphi \mid \varphi \wedge \varphi \mid \langle\langle A \rangle\rangle\gamma$

QATL*: Quantitative extension of ATL*

Language **AC** of arithmetic formulae over accumulated utilities:
Boolean combinations of equalities and inequalities between terms
built by applying addition over a set of variables $V_{\mathbb{A}} = \{v_{\mathbf{a}} \mid \mathbf{a} \in \mathbb{A}\}$
for the accumulated utilities and a fixed set X of constants.

Language of QATL*. Extends ATL* with formulae from AC:

State formulae $\varphi ::= p \mid \mathbf{ac} \mid \neg\varphi \mid \varphi \wedge \varphi \mid \langle\langle A \rangle\rangle\gamma$

Path formulae: $\gamma ::= \varphi \mid \neg\gamma \mid \gamma \wedge \gamma \mid \mathcal{X}\gamma \mid \mathcal{G}\gamma \mid \gamma\mathcal{U}\gamma$

QATL*: Quantitative extension of ATL*

Language **AC** of arithmetic formulae over accumulated utilities:
Boolean combinations of equalities and inequalities between terms
built by applying addition over a set of variables $V_{\mathbb{A}} = \{v_{\mathbf{a}} \mid \mathbf{a} \in \mathbb{A}\}$
for the accumulated utilities and a fixed set X of constants.

Language of QATL*. Extends ATL* with formulae from AC:

State formulae $\varphi ::= p \mid \mathbf{ac} \mid \neg\varphi \mid \varphi \wedge \varphi \mid \langle\langle A \rangle\rangle\gamma$

Path formulae: $\gamma ::= \varphi \mid \neg\gamma \mid \gamma \wedge \gamma \mid \mathcal{X}\gamma \mid \mathcal{G}\gamma \mid \gamma\mathcal{U}\gamma$

where $A \subseteq \mathbb{A}$, $\mathbf{ac} \in \text{AC}$ and $p \in \text{Prop}$.

QATL*: Quantitative extension of ATL*

Language **AC** of arithmetic formulae over accumulated utilities:
Boolean combinations of equalities and inequalities between terms
built by applying addition over a set of variables $V_{\mathbb{A}} = \{v_{\mathbf{a}} \mid \mathbf{a} \in \mathbb{A}\}$
for the accumulated utilities and a fixed set X of constants.

Language of QATL*. Extends ATL* with formulae from AC:

State formulae $\varphi ::= p \mid \mathbf{ac} \mid \neg\varphi \mid \varphi \wedge \varphi \mid \langle\langle A \rangle\rangle\gamma$

Path formulae: $\gamma ::= \varphi \mid \neg\gamma \mid \gamma \wedge \gamma \mid \mathcal{X}\gamma \mid \mathcal{G}\gamma \mid \gamma\mathcal{U}\gamma$

where $A \subseteq \mathbb{A}$, $\mathbf{ac} \in \mathbf{AC}$ and $p \in \mathbf{Prop}$.

An extension: with arithmetic formulae over entire plays. Requires adding discounting factors on payoffs. Will not be discussed here.

Semantics of QATL*

Semantics of QATL*

Given: \mathfrak{M} be a GCGMP, c a configuration, φ state formula,
 $\gamma, \gamma_1, \gamma_2$ path formulae, \mathcal{S}^p and \mathcal{S}^o two classes of strategies.

Semantics of QATL*

Given: \mathfrak{M} be a GCGMP, c a configuration, φ state formula,
 $\gamma, \gamma_1, \gamma_2$ path formulae, \mathcal{S}^p and \mathcal{S}^o two classes of strategies.

$\mathfrak{M}, c \models p$ iff $p \in L(c^s)$;

Semantics of QATL*

Given: \mathfrak{M} be a GCGMP, c a configuration, φ state formula,
 $\gamma, \gamma_1, \gamma_2$ path formulae, \mathcal{S}^p and \mathcal{S}^o two classes of strategies.

$\mathfrak{M}, c \models p$ iff $p \in L(c^s)$;

$\mathfrak{M}, c \models \text{ac}$ iff $c^u \models \text{ac}$,

Semantics of QATL*

Given: \mathfrak{M} be a GCGMP, c a configuration, φ state formula, $\gamma, \gamma_1, \gamma_2$ path formulae, \mathcal{S}^p and \mathcal{S}^o two classes of strategies.

$\mathfrak{M}, c \models p$ iff $p \in L(c^s)$;

$\mathfrak{M}, c \models ac$ iff $c^u \models ac$,

$\mathfrak{M}, c \models \langle\langle A \rangle\rangle \gamma$ iff there is a \mathcal{S}^p -strategy s_A such that for all \mathcal{S}^o -strategies $s_{A \setminus A}$: $\mathfrak{M}, \text{outcome_play}^{\mathfrak{M}}(c, (s_A, s_{A \setminus A})) \models \gamma$.

Semantics of QATL*

Given: \mathfrak{M} be a GCGMP, c a configuration, φ state formula, $\gamma, \gamma_1, \gamma_2$ path formulae, \mathcal{S}^p and \mathcal{S}^o two classes of strategies.

$\mathfrak{M}, c \models p$ iff $p \in L(c^s)$;

$\mathfrak{M}, c \models ac$ iff $c^u \models ac$,

$\mathfrak{M}, c \models \langle\langle A \rangle\rangle \gamma$ iff there is a \mathcal{S}^p -strategy s_A such that for all \mathcal{S}^o -strategies $s_{A \setminus A}$: $\mathfrak{M}, \text{outcome_play}^{\mathfrak{M}}(c, (s_A, s_{A \setminus A})) \models \gamma$.

$\mathfrak{M}, \pi \models \varphi$ iff $\mathfrak{M}, \pi[0] \models \varphi$,

Semantics of QATL*

Given: \mathfrak{M} be a GCGMP, c a configuration, φ state formula, $\gamma, \gamma_1, \gamma_2$ path formulae, \mathcal{S}^p and \mathcal{S}^o two classes of strategies.

$\mathfrak{M}, c \models p$ iff $p \in L(c^s)$;

$\mathfrak{M}, c \models ac$ iff $c^u \models ac$,

$\mathfrak{M}, c \models \langle\langle A \rangle\rangle \gamma$ iff there is a \mathcal{S}^p -strategy s_A such that for all \mathcal{S}^o -strategies $s_{\mathbb{A} \setminus A}$: $\mathfrak{M}, \text{outcome_play}^{\mathfrak{M}}(c, (s_A, s_{\mathbb{A} \setminus A})) \models \gamma$.

$\mathfrak{M}, \pi \models \varphi$ iff $\mathfrak{M}, \pi[0] \models \varphi$,

$\mathfrak{M}, \pi \models \mathcal{X}\gamma$ iff $\mathfrak{M}, \pi[1] \models \gamma$,

Semantics of QATL*

Given: \mathfrak{M} be a GCGMP, c a configuration, φ state formula, $\gamma, \gamma_1, \gamma_2$ path formulae, \mathcal{S}^p and \mathcal{S}^o two classes of strategies.

$\mathfrak{M}, c \models p$ iff $p \in L(c^s)$;

$\mathfrak{M}, c \models ac$ iff $c^u \models ac$,

$\mathfrak{M}, c \models \langle\langle A \rangle\rangle \gamma$ iff there is a \mathcal{S}^p -strategy s_A such that for all \mathcal{S}^o -strategies $s_{\mathbb{A} \setminus A}$: $\mathfrak{M}, \text{outcome_play}^{\mathfrak{M}}(c, (s_A, s_{\mathbb{A} \setminus A})) \models \gamma$.

$\mathfrak{M}, \pi \models \varphi$ iff $\mathfrak{M}, \pi[0] \models \varphi$,

$\mathfrak{M}, \pi \models \mathcal{X}\gamma$ iff $\mathfrak{M}, \pi[1] \models \gamma$,

$\mathfrak{M}, \pi \models \mathcal{G}\gamma$ iff $\mathfrak{M}, \pi[i] \models \gamma$ for all $i \in \mathbb{N}$,

Semantics of QATL*

Given: \mathfrak{M} be a GCGMP, c a configuration, φ state formula, $\gamma, \gamma_1, \gamma_2$ path formulae, \mathcal{S}^p and \mathcal{S}^o two classes of strategies.

$\mathfrak{M}, c \models p$ iff $p \in L(c^s)$;

$\mathfrak{M}, c \models ac$ iff $c^u \models ac$,

$\mathfrak{M}, c \models \langle\langle A \rangle\rangle \gamma$ iff there is a \mathcal{S}^p -strategy s_A such that for all \mathcal{S}^o -strategies $s_{A \setminus A}$: $\mathfrak{M}, \text{outcome_play}^{\mathfrak{M}}(c, (s_A, s_{A \setminus A})) \models \gamma$.

$\mathfrak{M}, \pi \models \varphi$ iff $\mathfrak{M}, \pi[0] \models \varphi$,

$\mathfrak{M}, \pi \models \mathcal{X}\gamma$ iff $\mathfrak{M}, \pi[1] \models \gamma$,

$\mathfrak{M}, \pi \models \mathcal{G}\gamma$ iff $\mathfrak{M}, \pi[i] \models \gamma$ for all $i \in \mathbb{N}$,

$\mathfrak{M}, \pi \models \gamma_1 \mathcal{U} \gamma_2$ iff there is $j \in \mathbb{N}_0$ such that $\mathfrak{M}, \pi[j] \models \gamma_2$ and $\mathfrak{M}, \pi[i] \models \gamma_1$ for all $0 \leq i < j$.

Semantics of QATL*

Given: \mathfrak{M} be a GCGMP, c a configuration, φ state formula, $\gamma, \gamma_1, \gamma_2$ path formulae, \mathcal{S}^p and \mathcal{S}^o two classes of strategies.

$\mathfrak{M}, c \models p$ iff $p \in L(c^s)$;

$\mathfrak{M}, c \models ac$ iff $c^u \models ac$,

$\mathfrak{M}, c \models \langle\langle A \rangle\rangle \gamma$ iff there is a \mathcal{S}^p -strategy s_A such that for all \mathcal{S}^o -strategies $s_{A \setminus A}$: $\mathfrak{M}, \text{outcome_play}^{\mathfrak{M}}(c, (s_A, s_{A \setminus A})) \models \gamma$.

$\mathfrak{M}, \pi \models \varphi$ iff $\mathfrak{M}, \pi[0] \models \varphi$,

$\mathfrak{M}, \pi \models \mathcal{X}\gamma$ iff $\mathfrak{M}, \pi[1] \models \gamma$,

$\mathfrak{M}, \pi \models \mathcal{G}\gamma$ iff $\mathfrak{M}, \pi[i] \models \gamma$ for all $i \in \mathbb{N}$,

$\mathfrak{M}, \pi \models \gamma_1 \mathcal{U} \gamma_2$ iff there is $j \in \mathbb{N}_0$ such that $\mathfrak{M}, \pi[j] \models \gamma_2$ and $\mathfrak{M}, \pi[i] \models \gamma_1$ for all $0 \leq i < j$.

Ultimately, we define $\mathfrak{M}, c \models \varphi$ iff $\mathfrak{M}, c, 0 \models \varphi$.

Expressing properties in QATL*

Expressing properties in QATL*

- ▷ QATL* extends ATL*, so it can express all purely qualitative ATL* properties,

Expressing properties in QATL*

- ▷ QATL* extends ATL*, so it can express all purely qualitative ATL* properties, like

$$\langle\langle A \rangle\rangle(\mathcal{G}p \wedge q\mathcal{U}r)$$

Expressing properties in QATL*

- ▷ QATL* extends ATL*, so it can express all purely qualitative ATL* properties, like

$$\langle\langle A \rangle\rangle(\mathcal{G}p \wedge q\mathcal{U}r)$$

- ▷ QATL* can also express quantitative properties,

Expressing properties in QATL*

- ▷ QATL* extends ATL*, so it can express all purely qualitative ATL* properties, like

$$\langle\langle A \rangle\rangle(\mathcal{G}p \wedge q\mathcal{U}r)$$

- ▷ QATL* can also express quantitative properties, e.g.:

$$\langle\langle \{a\} \rangle\rangle \mathcal{G}(v_a > 0)$$

*“Player **a** has a strategy to maintain his accumulated utility positive”* ,

Expressing properties in QATL*

- ▷ QATL* extends ATL*, so it can express all purely qualitative ATL* properties, like

$$\langle\langle A \rangle\rangle(\mathcal{G}p \wedge q\mathcal{U}r)$$

- ▷ QATL* can also express quantitative properties, e.g.:

$$\langle\langle \{a\} \rangle\rangle \mathcal{G}(v_a > 0)$$

“Player a has a strategy to maintain his accumulated utility positive” ,

- ▷ Moreover, QATL* can naturally express combined qualitative and quantitative properties,

Expressing properties in QATL*

- ▷ QATL* extends ATL*, so it can express all purely qualitative ATL* properties, like

$$\langle\langle A \rangle\rangle(\mathcal{G}p \wedge q\mathcal{U}r)$$

- ▷ QATL* can also express quantitative properties, e.g.:

$$\langle\langle \{a\} \rangle\rangle \mathcal{G}(v_a > 0)$$

“Player a has a strategy to maintain his accumulated utility positive” ,

- ▷ Moreover, QATL* can naturally express combined qualitative and quantitative properties, e.g.

$$\langle\langle \{a\} \rangle\rangle ((a \text{ is happy}) \mathcal{U} (v_a \geq 10^6))$$

Expressing properties in QATL*

- ▷ QATL* extends ATL*, so it can express all purely qualitative ATL* properties, like

$$\langle\langle A \rangle\rangle(\mathcal{G}p \wedge \mathcal{Q}Ur)$$

- ▷ QATL* can also express quantitative properties, e.g.:

$$\langle\langle \{a\} \rangle\rangle \mathcal{G}(v_a > 0)$$

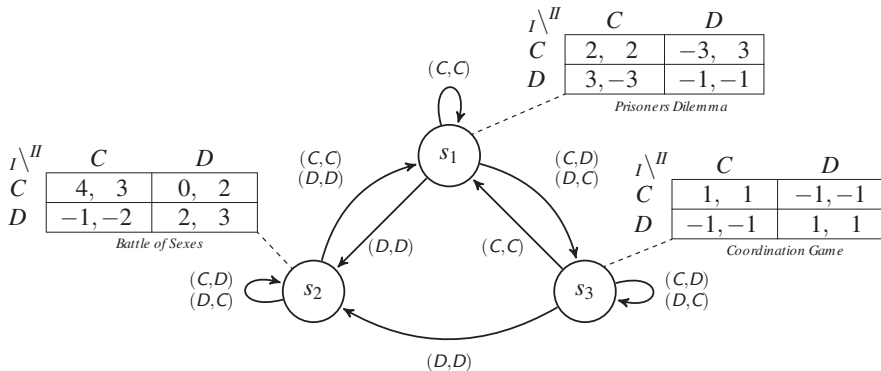
“Player a has a strategy to maintain his accumulated utility positive” ,

- ▷ Moreover, QATL* can naturally express combined qualitative and quantitative properties, e.g.

$$\langle\langle \{a\} \rangle\rangle ((a \text{ is happy}) \mathcal{U} (v_a \geq 10^6))$$

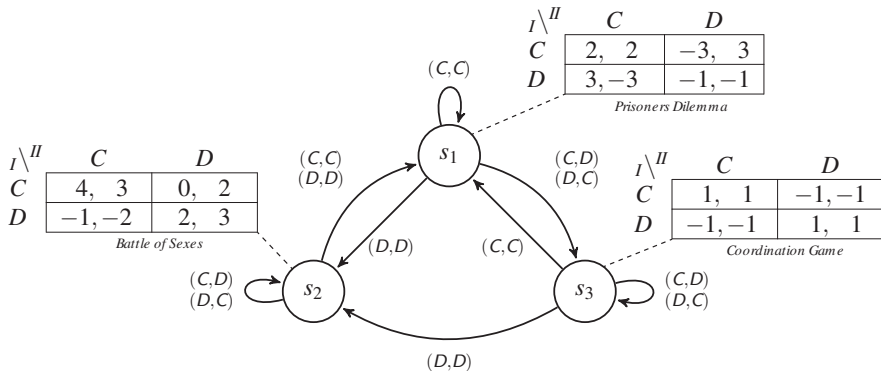
“Player a has a strategy to reach accumulated utility of one million and meanwhile stay in “happy” states.”

Expressing properties in QATL*: more examples



In the examples below p_i is true only at s_i , for each $i = 1, 2, 3$.

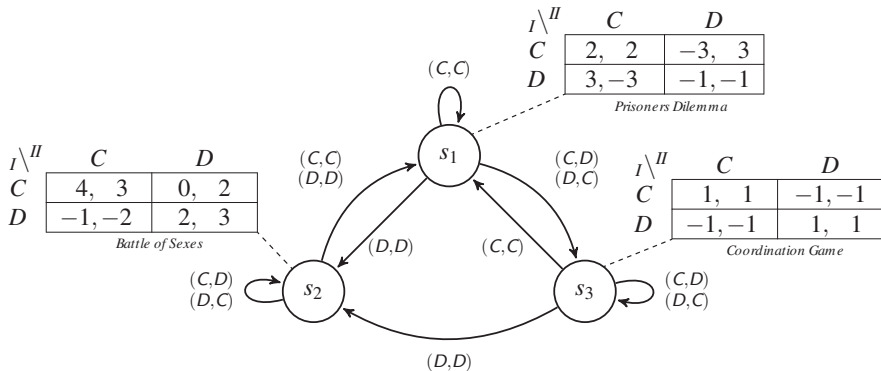
Expressing properties in QATL*: more examples



In the examples below p_i is true only at s_i , for each $i = 1, 2, 3$.

1. $\langle\langle\{I, II\}\rangle\rangle \mathcal{F}(p_1 \wedge v_I > 100 \wedge v_{II} > 100)$

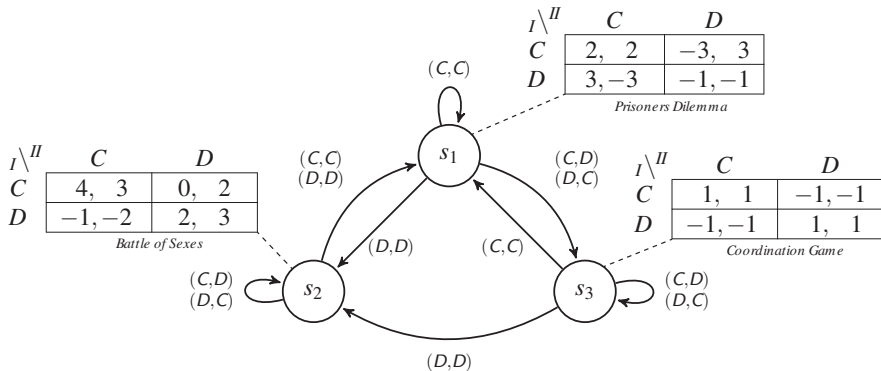
Expressing properties in QATL*: more examples



In the examples below p_i is true only at s_i , for each $i = 1, 2, 3$.

1. $\langle\langle\{I, II\}\rangle\rangle \mathcal{F}(p_1 \wedge v_I > 100 \wedge v_{II} > 100)$
2. $\langle\langle\{I, II\}\rangle\rangle \mathcal{X}\mathcal{X}\langle\langle\{II\}\rangle\rangle (\mathcal{G}(p_2 \wedge v_I = 0) \wedge \mathcal{F} v_{II} > 100).$

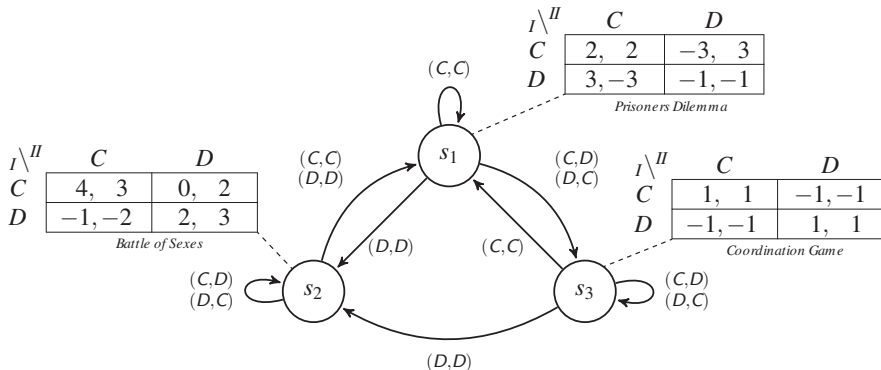
Expressing properties in QATL*: more examples



In the examples below p_i is true only at s_i , for each $i = 1, 2, 3$.

1. $\langle\langle\{I, II\}\rangle\rangle \mathcal{F}(p_1 \wedge v_I > 100 \wedge v_{II} > 100)$
2. $\langle\langle\{I, II\}\rangle\rangle \mathcal{X} \mathcal{X} \langle\langle\{II\}\rangle\rangle (\mathcal{G}(p_2 \wedge v_I = 0) \wedge \mathcal{F} v_{II} > 100).$
3. $\neg \langle\langle\{I\}\rangle\rangle \mathcal{G}(p_1 \vee v_I > 0)$

Expressing properties in QATL*: more examples



In the examples below p_i is true only at s_i , for each $i = 1, 2, 3$.

1. $\langle\langle\{I, II\}\rangle\rangle \mathcal{F}(p_1 \wedge v_I > 100 \wedge v_{II} > 100)$
2. $\langle\langle\{I, II\}\rangle\rangle \mathcal{X} \mathcal{X} \langle\langle\{II\}\rangle\rangle (\mathcal{G}(p_2 \wedge v_I = 0) \wedge \mathcal{F} v_{II} > 100).$
3. $\neg \langle\langle\{I\}\rangle\rangle \mathcal{G}(p_1 \vee v_I > 0)$
4. $\neg \langle\langle\{I, II\}\rangle\rangle \mathcal{F}(p_3 \wedge \mathcal{G}(p_3 \wedge v_I + v_{II} > 0)).$

Some undecidability results about QATL*

Some undecidability results about QATL*

The framework is very general and easily leads to undecidable MC.

Some undecidability results about QATL*

The framework is very general and easily leads to undecidable MC.

Lemma (Reduction from the Halting problem for Minsky machines)

For any Minsky machine (2-counter automaton) A a finite 2-player GCGMP \mathfrak{M}^A using a proposition `halt` can be constructed so that:

A halts on empty input iff

there is a play π in \mathfrak{M}^A which reaches a `halt`-state.

Some undecidability results about QATL*

The framework is very general and easily leads to undecidable MC.

Lemma (Reduction from the Halting problem for Minsky machines)

For any Minsky machine (2-counter automaton) A a finite 2-player GCGMP \mathfrak{M}^A using a proposition `halt` can be constructed so that:

A halts on empty input iff

there is a play π in \mathfrak{M}^A which reaches a `halt`-state.

Thm Model checking in the logic QATL* is undecidable, even for the fragment with no nested cooperation modalities, where $\mathcal{S}^p = \mathcal{S}^{mem}$ and $\mathcal{S}^o = \mathcal{S}^{pos}$, in each of the following cases:

Some undecidability results about QATL*

The framework is very general and easily leads to undecidable MC.

Lemma (Reduction from the Halting problem for Minsky machines)

For any Minsky machine (2-counter automaton) A a finite 2-player GCGMP \mathfrak{M}^A using a proposition `halt` can be constructed so that:

A halts on empty input iff

there is a play π in \mathfrak{M}^A which reaches a `halt`-state.

Thm Model checking in the logic QATL* is undecidable, even for the fragment with no nested cooperation modalities, where $\mathcal{S}^p = \mathcal{S}^{mem}$ and $\mathcal{S}^o = \mathcal{S}^{pos}$, in each of the following cases:

1. Two players, no arithmetic constraints in the formula.

Some undecidability results about QATL*

The framework is very general and easily leads to undecidable MC.

Lemma (Reduction from the Halting problem for Minsky machines)

For any Minsky machine (2-counter automaton) A a finite 2-player GCGMP \mathfrak{M}^A using a proposition `halt` can be constructed so that:

A halts on empty input iff

there is a play π in \mathfrak{M}^A which reaches a `halt`-state.

Thm Model checking in the logic QATL* is undecidable, even for the fragment with no nested cooperation modalities, where $\mathcal{S}^p = \mathcal{S}^{mem}$ and $\mathcal{S}^o = \mathcal{S}^{pos}$, in each of the following cases:

1. Two players, no arithmetic constraints in the formula.
2. Two players, state-based guards.

Some undecidability results about QATL*

The framework is very general and easily leads to undecidable MC.

Lemma (Reduction from the Halting problem for Minsky machines)

For any Minsky machine (2-counter automaton) A a finite 2-player GCGMP \mathfrak{M}^A using a proposition `halt` can be constructed so that:

A halts on empty input iff

there is a play π in \mathfrak{M}^A which reaches a halt-state.

Thm Model checking in the logic QATL* is undecidable, even for the fragment with no nested cooperation modalities, where $\mathcal{S}^p = \mathcal{S}^{mem}$ and $\mathcal{S}^o = \mathcal{S}^{pos}$, in each of the following cases:

1. Two players, no arithmetic constraints in the formula.
2. Two players, state-based guards.
3. Three players, no guards, non-negative payoffs only.

Some decidability results and conjectures about QATL*

Some decidability results and conjectures about QATL*

Thm: MC in the logic QATL* is decidable in the following cases:

Some decidability results and conjectures about QATL*

Thm: MC in the logic QATL* is decidable in the following cases:

1. Many players, all executing bounded memory effective strategies.

Some decidability results and conjectures about QATL*

Thm: MC in the logic QATL* is decidable in the following cases:

1. Many players, all executing bounded memory effective strategies.
2. Two-player turn-based GCGMPs, for the fragment with formulae involving only player 1's accumulated utility.

Some decidability results and conjectures about QATL*

Thm: MC in the logic QATL* is decidable in the following cases:

1. Many players, all executing bounded memory effective strategies.
2. Two-player turn-based GCGMPs, for the fragment with formulae involving only player 1's accumulated utility.

Conjectures: Model checking in the logic QATL* is decidable in each of the following cases:

Some decidability results and conjectures about QATL*

Thm: MC in the logic QATL* is decidable in the following cases:

1. Many players, all executing bounded memory effective strategies.
2. Two-player turn-based GCGMPs, for the fragment with formulae involving only player 1's accumulated utility.

Conjectures: Model checking in the logic QATL* is decidable in each of the following cases:

1. Two players and non-negative payoffs.

Some decidability results and conjectures about QATL*

Thm: MC in the logic QATL* is decidable in the following cases:

1. Many players, all executing bounded memory effective strategies.
2. Two-player turn-based GCGMPs, for the fragment with formulae involving only player 1's accumulated utility.

Conjectures: Model checking in the logic QATL* is decidable in each of the following cases:

1. Two players and non-negative payoffs.
2. Many players, no guards, restriction to the quantitative atomic formulae to only allow comparisons between players' payoffs and constants, i.e. of the type $v_i \circ c$ but not $v_i \circ v_j$, where $\circ \in \{>, =, <\}$.

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

▷ Three perspectives of research agenda:

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

▷ Three perspectives of research agenda:

- **Logic:** Expressiveness, formal reasoning, deduction.

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

▷ Three perspectives of research agenda:

- **Logic:** Expressiveness, formal reasoning, deduction.
- **Computation:** decidability, algorithms and complexity for model checking and synthesis.

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

▷ Three perspectives of research agenda:

- **Logic:** Expressiveness, formal reasoning, deduction.
- **Computation:** decidability, algorithms and complexity for model checking and synthesis.
- **Game theory:** solution concepts, equilibria, extending results from repeated games (e.g., folk theorems), etc.

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

▷ Three perspectives of research agenda:

- **Logic:** Expressiveness, formal reasoning, deduction.
- **Computation:** decidability, algorithms and complexity for model checking and synthesis.
- **Game theory:** solution concepts, equilibria, extending results from repeated games (e.g., folk theorems), etc.

▷ Many still unexplored directions, including:

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

▷ Three perspectives of research agenda:

- **Logic:** Expressiveness, formal reasoning, deduction.
- **Computation:** decidability, algorithms and complexity for model checking and synthesis.
- **Game theory:** solution concepts, equilibria, extending results from repeated games (e.g., folk theorems), etc.

▷ Many still unexplored directions, including:

- games with imperfect information,

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

▷ Three perspectives of research agenda:

- **Logic:** Expressiveness, formal reasoning, deduction.
- **Computation:** decidability, algorithms and complexity for model checking and synthesis.
- **Game theory:** solution concepts, equilibria, extending results from repeated games (e.g., folk theorems), etc.

▷ Many still unexplored directions, including:

- games with imperfect information,
- satisfiability testing and model synthesis,

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

▷ Three perspectives of research agenda:

- **Logic:** Expressiveness, formal reasoning, deduction.
- **Computation:** decidability, algorithms and complexity for model checking and synthesis.
- **Game theory:** solution concepts, equilibria, extending results from repeated games (e.g., folk theorems), etc.

▷ Many still unexplored directions, including:

- games with imperfect information,
- satisfiability testing and model synthesis,
- stochastic games with probabilistic strategies, etc.

Concluding remarks

We have proposed a logical framework combining qualitative with quantitative reasoning in multi-payer games.

▷ Three perspectives of research agenda:

- **Logic:** Expressiveness, formal reasoning, deduction.
- **Computation:** decidability, algorithms and complexity for model checking and synthesis.
- **Game theory:** solution concepts, equilibria, extending results from repeated games (e.g., folk theorems), etc.

▷ Many still unexplored directions, including:

- games with imperfect information,
- satisfiability testing and model synthesis,
- stochastic games with probabilistic strategies, etc.

The End