(Fragments)

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Outline (of the fragments)

This work addresses, and proposes a solution to, the problem of ε -transition removal in weighted automata.

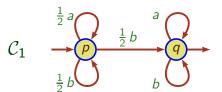
The problem lies in effectivity.

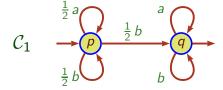
The solution is based on a new, and more constrained, definition of the validity of weighted automata.

The definition insures that algorithms are successful on valid automata.

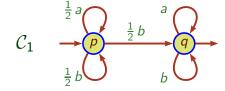
In some (interesting) cases, we are able to establish that success of algorithms implies validity of automata.

This solution provides a sound theoretical framework for the algorithms implemented in VAUCANSON.





- ▶ Weight of a path *c*: *product* of the weights of transitions in *c*
- ▶ Weight of a word *w*: *sum* of the weights of paths with label *w*



- ▶ Weight of a path c: product of the weights of transitions in c
- ▶ Weight of a word w: sum of the weights of paths with label w

$$\frac{1}{\longrightarrow} p \xrightarrow{\frac{1}{2}b} p \xrightarrow{\frac{1}{2}a} p \xrightarrow{\frac{1}{2}b} q \xrightarrow{1}$$

$$\frac{1}{\longrightarrow} p \xrightarrow{\frac{1}{2}b} q \xrightarrow{a} q \xrightarrow{b} q \xrightarrow{1}$$

$$C_1 \xrightarrow{\frac{1}{2}a} P \xrightarrow{\frac{1}{2}b} P \xrightarrow{\frac{1}{2}b} |C_1| \in \mathbb{Q}\langle\langle A^* \rangle\rangle$$

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$$bab \longmapsto \frac{1}{2} + \frac{1}{8} = \frac{5}{8} = \langle 0.101 \rangle_2 \qquad |\mathcal{C}_1|: A^* \longrightarrow \mathbb{Q}$$

$$C_1 \xrightarrow{\frac{1}{2}a} \xrightarrow{\frac{1}{2}b} \xrightarrow{a} \qquad |C_1| \in \mathbb{Q}\langle\langle A^* \rangle\rangle$$

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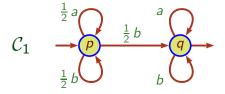
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$$|\mathcal{C}_1| = \frac{1}{2}b + \frac{1}{4}ab + \frac{1}{2}ba + \frac{3}{4}bb + \frac{1}{8}aab + \frac{1}{4}aba + \frac{3}{8}abb + \frac{1}{2}baa + \dots$$

$$C_1 \xrightarrow{\frac{1}{2}a} P \xrightarrow{\frac{1}{2}b} Q$$

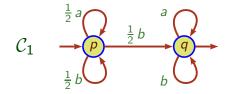
$$\mathcal{C}_1 = \left\langle I_1, \underline{E_1}, T_1 \right\rangle = \left\langle \begin{pmatrix} 1 & 0 \end{pmatrix}, \begin{pmatrix} \frac{1}{2}a + \frac{1}{2}b & \frac{1}{2}b \\ 0 & a+b \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right
angle$$



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$$|\mathcal{C}_1| = I_1 \cdot E_1^* \cdot T_1$$

Every \mathbb{K} -automaton defines a series in $\mathbb{K}\langle\langle A^* \rangle\rangle$ whose coefficients are effectively computable



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Where is the problem?

We want to deal with automata whose transitions may be labelled by the empty word $\,arepsilon\,$

A basic result in (classical) automata theory

Theorem

Every ε -NFA is equivalent to an NFA

A basic result in (classical) automata theory

Theorem

Every ε -NFA is equivalent to an NFA

Usefulness of ε -transitions:

Preliminary step for many constructions on NFA's:

- Product and star of position automata
- ► Thompson construction
- Construction of the universal automaton
- Computation of the image of a transducer
- **...**

May correspond to the structure of the computations

Removal of ε -transitions is implemented in all automata software

A basic question in weighted automata theory

Question

Is every ε -WFA is equivalent to a WFA?

A basic question in weighted automata theory

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Is every ε -WFA is equivalent to a WFA?

certainly not!

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Is every ε -WFA is equivalent to a WFA?

certainly not!

New questions

Which ε -WFAs have a well-defined behaviour?

How to compute the behaviour of an ε -WFA (when it is *well-defined*)?

How to decide if the behaviour of an ε -WFA is well-defined?

Infinite sums are given a meaning via a topology on \mathbb{K} Topology on \mathbb{K} defines a topology on $\mathbb{K}\langle\!\langle A^*\rangle\!\rangle$ Topology allows to define summable families in $\mathbb{K}\langle\!\langle A^*\rangle\!\rangle$

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$$\mathcal{A} = \langle \, \mathbb{K}, Q, A, E, I, T \, \rangle \qquad \text{possibly with ε-transitions}$$

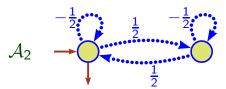
$$\mathsf{P}_{\mathcal{A}} \qquad \qquad \text{set of all paths in } \mathcal{A}$$

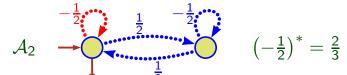
$$|\mathcal{A}| \text{ well-defined} \iff \forall p,q \in Q \quad \mathbf{WL}(\mathsf{P}_{\mathcal{A}}(p,q)) \text{ summable}$$

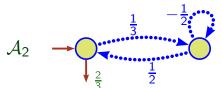
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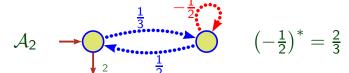
Definition taken in previous works (Lombardy, S. 03 –)

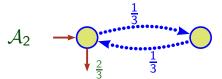
- Yields a consistent theory
- Two pitfalls for effectivity
 - effective computation of a summable family may not be possible
 - effective computation may give values to non summable families

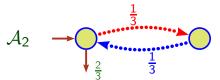


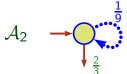




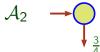












$$A_2 \rightarrow \bigcap_{\frac{3}{4}}$$

$$\mathcal{A}_2 = \left\langle I_2, \underline{E_2}, T_2 \right\rangle = \left\langle (1 \quad 0), \begin{pmatrix} -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\rangle$$

$$\left| \mathcal{A}_2 \right| = I_2 \cdot \underline{E_2}^* \cdot T_2$$

$$\underline{E_2}^3 = \underline{E_2} \quad \Longrightarrow \quad \underline{E_2}^* \quad \text{undefined} \quad \Longrightarrow \quad \left| \mathcal{A}_2 \right| \quad \text{undefined}$$

A chicken and egg problem

automaton

algorithm

 \mathcal{A}

4

valid?

d? success?

A chicken and egg problem

automaton		algorithm
${\cal A}$		A
valid ?		success ?
valid	\Longrightarrow	success

A chicken and egg problem

automaton		algorithm
${\cal A}$		A
valid ?		success ?
valid	\Longrightarrow	success
valid	?	success

$$\mathcal{A}=\langle\,\mathbb{K},Q,A,E,I,T\,
angle$$
 possibly with $arepsilon$ -transitions
$$E^* \qquad \qquad \textit{free monoid} \ \text{generated by} \ E$$
 $\mathsf{P}_{\mathcal{A}} \qquad \textit{set of paths} \ \text{in} \ \mathcal{A} \qquad \text{(local) rational subset of} \ E^*$

Definition

R rational family of paths of A $R \in RatE^* \land R \subseteq P_A$

$$\mathsf{R} \in \mathsf{RatE}^* \, \wedge \, \mathit{R} \subseteq \mathsf{P}_{\!\mathcal{A}}$$

Definition

A is valid iff

 $\forall R$ rational family of paths of \mathcal{A} , $\mathbf{WL}(R)$ is summable

Validity of weighted automata Validity implies well-definition of behaviour

Validity implies well-definition of behaviour

Remark

If every (rational) subfamily of a summable family in \mathbb{K} is summable then validity is equivalent to well-definition of behaviour

Eg. \mathbb{R} , \mathbb{Q} .

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Theorem

 ${\cal A}$ is valid iff the behaviour of every covering of ${\cal A}$ is well-defined

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If ${\mathcal A}$ is valid, then 'every' removal algorithm on ${\mathcal A}$ is successful

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Reminder

We do not know yet how to decide whether

a \mathbb{Q} - or an \mathbb{R} -automaton is valid.

Deciding validity

Definition

K topological, ordered, positive, star-domain downward closed

$$\mathbb{N}$$
, \mathcal{N} , \mathbb{Q}_+ , \mathbb{R}_+ , \mathbb{Z} min, $\operatorname{Rat} A^*$,... \mathbb{N}_{∞} , (binary) positive decimals,...

are TOPS SDC are not TOPS SDC

Theorem

 \mathbb{K} topological, ordered, positive, star-domain downward closed A \mathbb{K} -automaton is valid if, and only if,

the ε -removal algorithm succeeds

Deciding validity

Definition

If $\mathcal A$ is a $\mathbb Q$ - or $\mathbb R$ -automaton, then $\mathsf{abs}(\mathcal A)$ is a $\mathbb Q_+$ - or $\mathbb R_+$ -automaton

Theorem

 $A \mathbb{Q}$ - or \mathbb{R} -automaton A is valid if and only if abs(A) is valid.

Conclusion

- Semiring structure is weak, topology does not help so much.
- This weakness imposes a restricted definition of validity, in order to guarantee success of validity algorithms.
- Axiomatic approach does not allow to deal wit most common numerical semirings: Zmin, Q
- On 'usual' semirings,
 the new definition of validity coincides with the former one.

Conclusion (2)

- Apart the trivial cases, and the TOPS SCD case, decision of validity is never granted, and is to be established.
- On 'usual' semirings, validity is decidable.
- The new definition of validity fills the 'effectivity gap' left open by the former one.
- lacktriangleright The algorithms implemented in Vaucanson are given a theoretical framework

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All's well, that ends well!

Hidden parts

- ► The removal algorithm itself:
 - Termination issues (weighted versus Boolean cases)
 - Complexity issues
- Automata and expressions validity
- ▶ 'Infinitary' axioms : strong, star-strong semirings
- Links with the 'axiomatic' approach (Bloom-Ésik-Kuich)
- ▶ References to previous work (on removal algorithm):
 - ► locally closed srgs (Ésik–Kuich), k-closed srgs (Mohri)
 - links with other algorithms: shortest-distance algorithm (Mohri), state-elimination method (Hanneforth-Higueira)