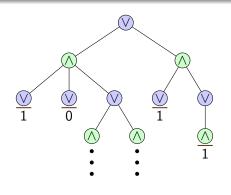
# Efficient Analysis of Probabilistic Programs with an Unbounded Counter CAV 2011

Tomáš Brázdil<sup>1</sup> <u>Stefan Kiefer</u><sup>2</sup> Antonín Kučera<sup>1</sup>

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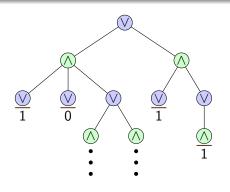
<sup>2</sup>University of Oxford, UK



```
procedure AND(node)
if node is a leaf
   return node.value
else
   for each successor s of node
      if OR(s) = 0 then return 0
   return 1

procedure OR(node) ...
```

(evaluate only when necessary)



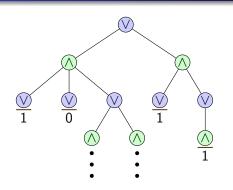
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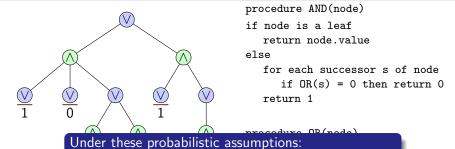
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- cannot tell: program may not even terminate
- ⇒ probabilistic assumptions:

What is the average runtime?

- AND node has 3 kids in average (geom. distribution)
- OR node has 2 kids in average
- a branch has length 4 in average
- Pr(leaf evaluates to 0) = Pr(leaf evaluates to 1) =  $\frac{1}{2}$



(arv

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- ⇒ probabilistic assumptions:
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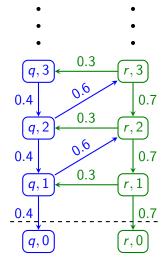
Approximate efficiently the expected runtime

- OR node has 2 kids in average
- a branch has length 4 in average
- $Pr(leaf \ evaluates \ to \ 0) = Pr(leaf \ evaluates \ to \ 1) = \frac{1}{2}$

## **Probabilistic Counter Machines**

#### Probabilistic Counter Machines induce infinite Markov chains:

$$q \stackrel{0.6}{\longleftrightarrow} r(+1)$$
  $r \stackrel{0.3}{\longleftrightarrow} q(\pm 0)$   
 $q \stackrel{0.4}{\longleftrightarrow} q(-1)$   $r \stackrel{0.7}{\longleftrightarrow} r(-1)$ 



# Modeling a Program as Prob. Counter Machine

```
and \stackrel{\ell \cdot z}{\longleftrightarrow} and 0(-1)
                                                        and \stackrel{\ell \cdot (1-z)}{\longleftrightarrow} and 1(-1)
procedure AND(node)
                                                        otherwise, call OR:
if node is a leaf
                                                        and \stackrel{1-\ell}{\longleftrightarrow} or (+1)
    return node.value
else
                                                        if OR returns 0, return 0 immediately:
    for each successor s of node
         if OR(s) = 0 then return 0
                                                        or0 \stackrel{1}{\hookrightarrow} and0(-1)
    return 1
                                                        otherwise, maybe call another OR:
                                                        or1 \stackrel{\times}{\hookrightarrow} or(+1)
                                                        or1 \stackrel{1-x}{\longleftrightarrow} and1(-1)
```

if leaf, return 0 or 1:

# Applications of Probabilistic Counter Machines

PCMs model infinite-state probabilistic programs

- recursion
- unbounded data structures

PCMs = discrete-time Quasi-Birth-Death processes

- well established stochastic model
- studied since the late 60s
- ⇒ queueing theory, performance evaluation, . . .

Recently: Games over (Probabilistic) Counter Machines

- energy games [Chatterjee, Doyen et al.]
- ⇒ optimizing resource consumption in portable devices

# Related Model: Probabilistic Pushdown System

Probabilistic Pushdown Systems modify a stack:

$$q(X) \stackrel{0.3}{\longleftrightarrow} r(YY)$$

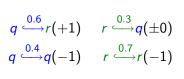
$$q(X) \stackrel{0.5}{\longleftrightarrow} r(X) \qquad q(Y) \hookrightarrow \dots \quad r(X) \hookrightarrow \dots \quad r(Y) \hookrightarrow \dots$$

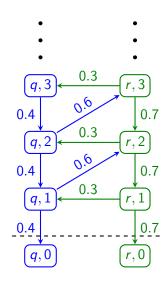
$$q(X) \stackrel{0.2}{\longleftrightarrow} q(\varepsilon)$$

Prob. Pushdown Systems (equivalently, Recursive Markov Chains) are more general, but more expensive to analyze.

PCMs are Prob. Pushdown Systems with a single stack symbol.

# **Probabilistic Counter Machines**





Runtime T := number of steps from (q, 1) to (\*, 0) We want to efficiently approximate  $\mathbb{E} T$ .

Trend t:= "average increase of the counter per step" Assume t < 0. Intuition: The more negative the trend t, the smaller T.

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# Proposition (from martingale theory: Azuma's inequality)

Let  $m^{(0)}, m^{(1)}, m^{(2)}, \ldots$  be random variables with  $m^{(0)} = 1$ . Let t < 0.

Assume  $\mathbb{E}(m^{(k+1)} \mid m^{(k)}) = m^{(k)} + t$  for all k. Then for all k:  $\Pr(m^{(k)} \ge 1) \le a^k$ , where  $a = e^{-t^2/2} < 1$ .

 $m^{(0)}=1$ 

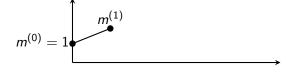
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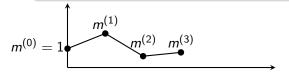
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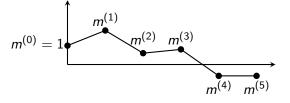
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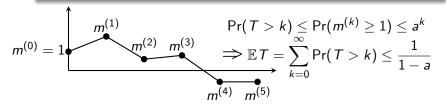
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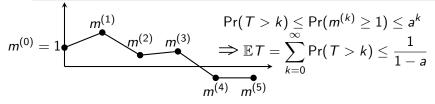
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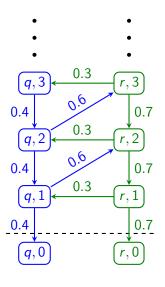
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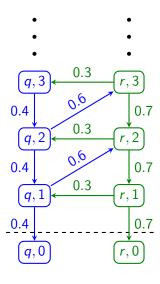
Then for all k:  $Pr(m^{(k)} > 1) < a^k$ , where  $a = e^{-t^2/2} < 1$ .





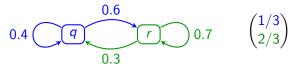
Average counter increase depends on state:

$$\binom{0.4 \cdot (-1) + 0.6 \cdot (+1)}{0.3 \cdot 0 + 0.7 \cdot (-1)} = \binom{0.2}{-0.7}$$

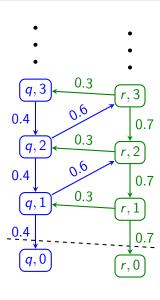


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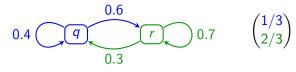


trend 
$$t = \left\langle \begin{pmatrix} 0.2 \\ -0.7 \end{pmatrix}, \begin{pmatrix} 1/3 \\ 2/3 \end{pmatrix} \right\rangle = -0.4$$

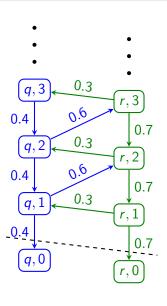


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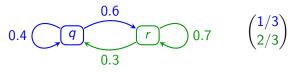


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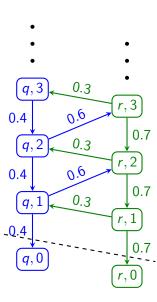


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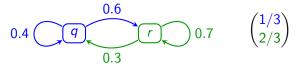


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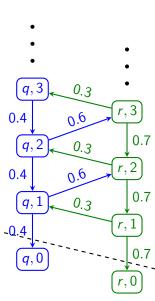


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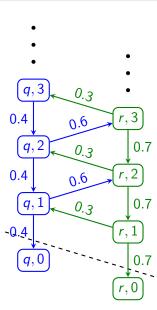


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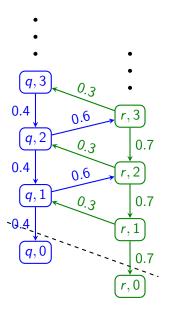


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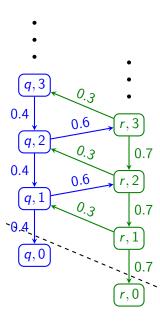


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Average counter increase depends on state:

$$\begin{pmatrix} 0.4 \cdot (-1) + 0.6 \cdot (+1) \\ 0.3 \cdot 0 + 0.7 \cdot (-1) \end{pmatrix} = \begin{pmatrix} 0.2 \\ -0.7 \end{pmatrix}$$

$$0.4$$
  $q$   $r$   $0.7$   $0.7$   $0.7$   $0.7$   $0.7$ 

trend 
$$t = \left\langle \begin{pmatrix} 0.2 \\ -0.7 \end{pmatrix}, \begin{pmatrix} 1/3 \\ 2/3 \end{pmatrix} \right\rangle = -0.4$$

$$q,3$$
 $0.4$ 
 $q,2$ 
 $0.6$ 
 $q,2$ 
 $0.6$ 
 $q,3$ 
 $0.7$ 
 $0.4$ 
 $0.6$ 
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Weight this by the stationary distribution of the counterless system:

$$0.6$$

$$0.4$$

$$q$$

$$r$$

$$0.7$$

trend 
$$t = \left\langle \begin{pmatrix} 0.2 \\ -0.7 \end{pmatrix}, \begin{pmatrix} 1/3 \\ 2/3 \end{pmatrix} \right\rangle = -0.4$$

0.3

$$q, 3$$
 $0.4$ 
 $q, 2$ 
 $0.6$ 
 $r, 3$ 
 $0.7$ 
 $q, 1$ 
 $0.6$ 
 $r, 2$ 
 $0.7$ 
 $q, 0.7$ 
 $0.7$ 
 $0.7$ 
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 $0.7$ 

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0.3

$$q,3$$
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 $q,2$ 
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Weight this by the stationary distribution of the counterless system:

$$0.6$$

$$0.4$$

$$q$$

$$r$$

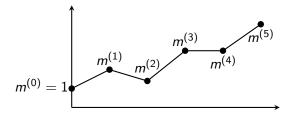
$$0.7$$

trend 
$$t = \left\langle \begin{pmatrix} 0.2 \\ -0.7 \end{pmatrix}, \begin{pmatrix} 1/3 \\ 2/3 \end{pmatrix} \right\rangle = -0.4$$

$$\Rightarrow$$
 expected height increase:  $t = -0.4$ . independent of control state :-)

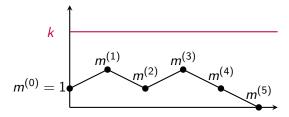
0.3

# Positive Trend



If t > 0, then  $\Pr(T = \infty) > 0$ .  $\mathbb{E}(T \mid \text{finite})$  can be bounded as before.

#### Zero Trend



#### Proposition (from martingale theory: Optional stopping theorem)

Let  $m^{(0)}, m^{(1)}, m^{(2)}, ...$  be random variables with  $m^{(0)} = 1$ .

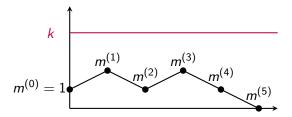
Assume  $\mathbb{E}(m^{(i+1)} \mid m^{(i)}) = m^{(i)}$  for all i.

Let  $k \in \mathbb{N}$ .

Let  $\tau$  be the first time with  $m^{(\tau)} \notin (0, k)$ .

Then  $\mathbb{E}m^{(\tau)}=1$ .

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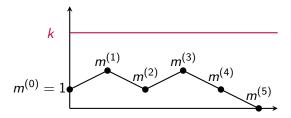
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Assuming all jumps are  $+1,\pm 0,-1$ , we must have  $m^{(\tau)}=\mathbf{k}$   $m^{(\tau)}=0$ 

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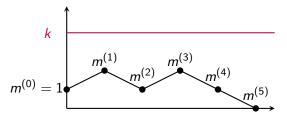
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$$\Rightarrow$$
  $\Pr(T \ge k) \ge \Pr(m^{(\tau)} = k) = 1/k$  and hence  $\mathbb{E}T = \infty$ 

# Finiteness of Expected Time

We condition on runs  $q \downarrow r$ : from (q, 1) reach (r, 0) (e.g., consider  $[and \downarrow and 0]$ ,  $[and \downarrow and 1]$ )

#### Theorem

Either some easy case holds or one of the following:

- If trend  $t \neq 0$ , then  $\mathbb{E}(T \mid q \downarrow r) \leq 85000 \cdot \frac{|Q|^6}{x_{\min}^{5|Q|+|Q|^3} \cdot t^4}$ .
- If trend t = 0, then  $\mathbb{E}(T \mid q \downarrow r)$  is infinite.

### Corollary

Whether  $\mathbb{E}(T \mid q \downarrow r)$  is finite can be decided in polynomial time.

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# Corollary

Whether  $\mathbb{E}(T \mid q \downarrow r)$  is finite can be decided in polynomial time.

But we want an approximation of  $\mathbb{E}(T \mid q \downarrow r)$ .

# Return Probabilities

```
"return probabilities": [q \downarrow r] := \Pr (from (q, 1) reach (r, 0))
```

### Proposition (from [EWY'08])

- If  $[q \downarrow r] > 0$ , then  $[q \downarrow r] \ge x_{\min}^{|Q|^3}$ .
- $[q \downarrow r]$  can be approximated within any error  $\varepsilon > 0$  in time  $poly(|\mathcal{S}|, \log(1/\varepsilon))$  in unit-cost arithmetic.

(does not hold for pushdown systems)

# Approximating Expected Runtime

#### Theorem

The value  $\mathbb{E}(T \mid q \downarrow r)$  can be approximated within any error  $\varepsilon > 0$  in time poly( $|\mathcal{S}|$ ,  $\log(1/\varepsilon)$ ) in unit-cost arithmetic.

Use the following procedure:

- Set up an equation system  $A\mathbf{x} = \mathbf{1}$ . (system already known) Solution vector contains  $\mathbb{E}(T \mid q \downarrow r)$  for all  $q, r \in Q$ . The matrix A contains return probabilities.
- Approximate A by approximating the return probabilities.
- Solve the approximated equation system.

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#### $\mathsf{Theorem}$

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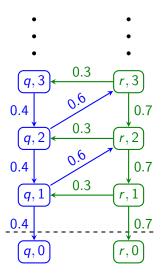
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- Approximate A by approximating the return probabilities.
- Solve the approximated equation system.

Precision of this method depends on the condition number of *A*. The condition number is good enough as:

- the return probabilities cannot be too small
- the solution cannot be too large (by our bound on  $\mathbb{E}T$ )

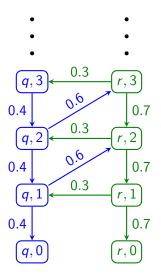
## Rules for Zero Counter



Now allow rules for zero counter (not -1)

⇒ all runs are infinite

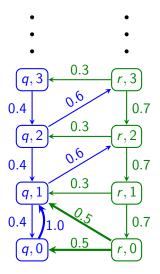
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 $\omega$ -regular Specifications

#### Theorem

Given an  $\omega$ -regular specification in terms of a Rabin automaton  $\mathcal{R}$ , the probability of a run satisfying the specification can be approximated within any error  $\varepsilon > 0$  in time  $\operatorname{poly}(|\mathcal{S}|, |\mathcal{R}|, \log(1/\varepsilon))$  in unit-cost arithmetic.

Proof uses again "trend"-based martingale arguments.

# Summary

- Probabilistic Counter Machines model infinite-state systems with a regular "counter-like" structure.
- Expected runtime and other quantities can be efficiently approximated (cf. prob. pushdown systems).
- Martingale techniques play a key role for the analysis.

