Introduction to Mixture of Experts (MoEs)

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Large Language Models: Introduction and Recent Advances

IBM Research, India Conversational-Al



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Sonam Mishra



Dinesh Khandelwal



Gaurav Pandey



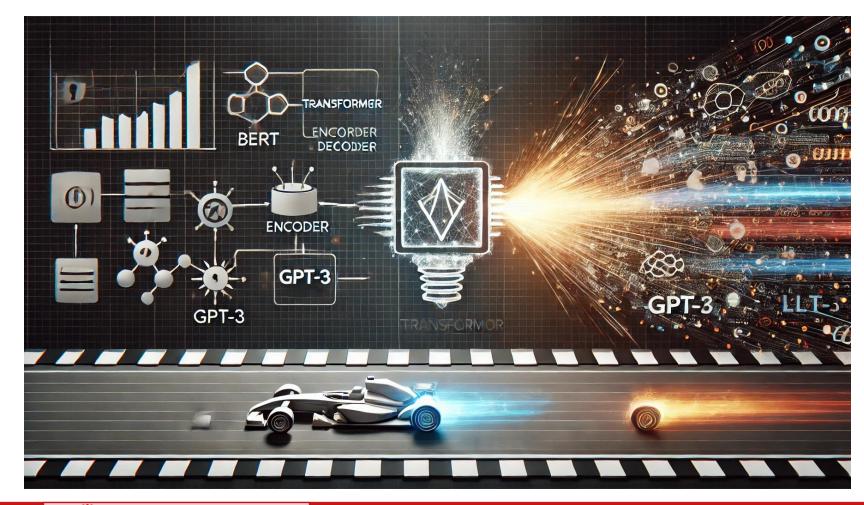
Vineet Kumar



Dinesh Raghu

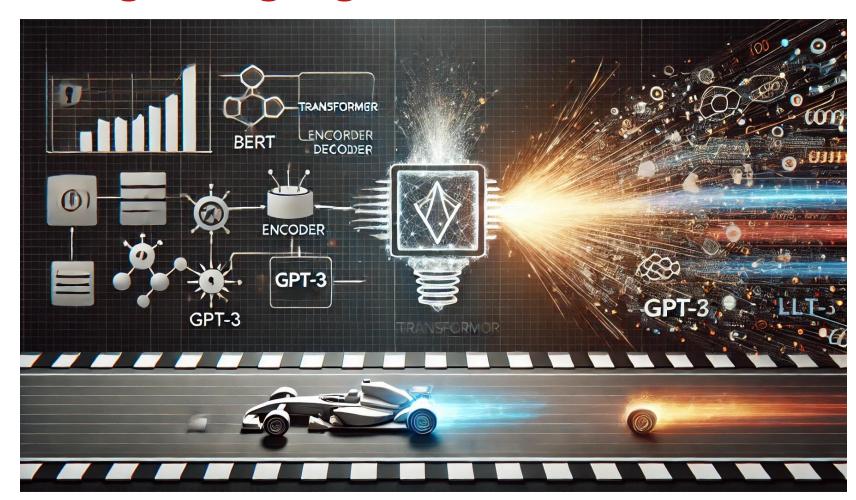


Sachindra Joshi









Pretraining

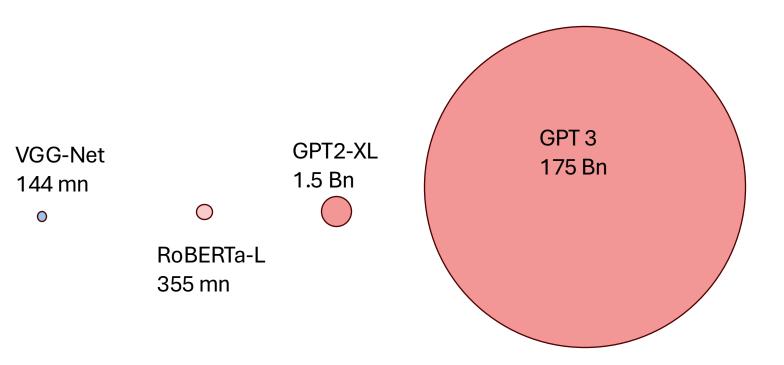
 Pretrain the model on a large dataset.

Finetuning

 Fine-tune of a specific task using a small dataset

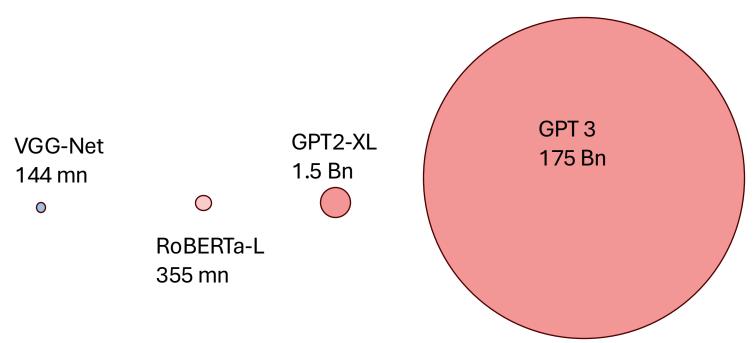










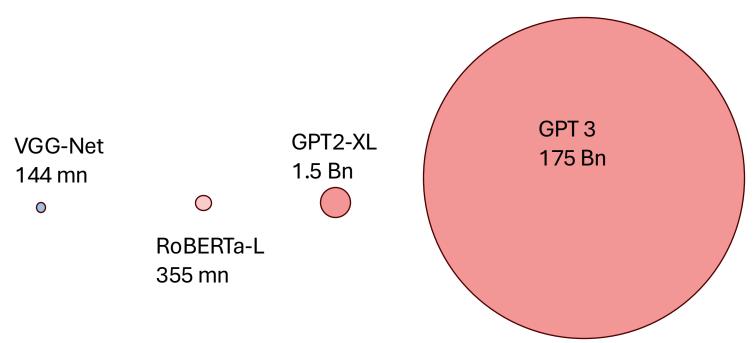


	Approx. Training
Size	Time
255 Mn	410 A100-days
333 1411	(410 A100s on 1 day)
175 Bn	60k A100-days
	(2k A100 on 30 days)
	355 Mn









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Switch Transformer 1.6 Trillion

VGG-Net 144 mn

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RoBERTa-L 355 mn GPT2-XL 1.5 Bn









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RoBERTa-L 355 mn GPT 3 175 Bn

Model	Size	Approx. Training Time
RoBERTa-L	L 355 Mn	410 A100-days
NODEINIA E		(410 A100s on 1 day)
GPT-3	175 Bn	60k A100-days
GP1-3		(2k A100 in 1 Month)
	1.6T	540k A100-days
		(2k A100 in 9 Months!)





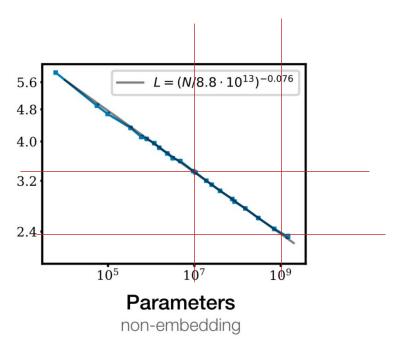
Why care about model size?





Neural Scaling Laws

• Performance improve smoothly as we increase the compute, dataset size, or the model size



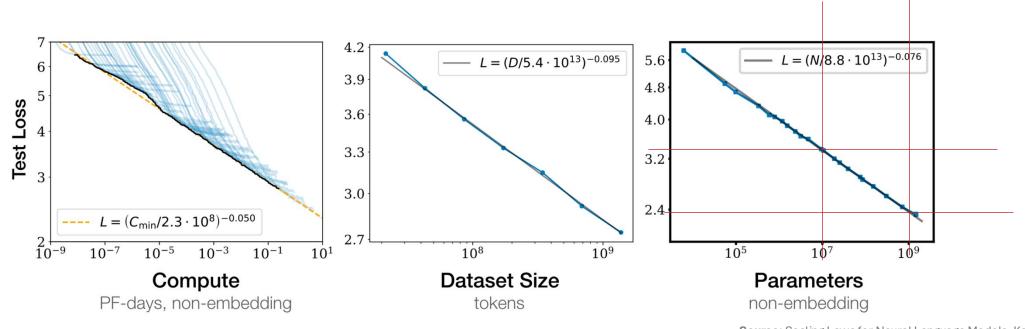
Source: Scaling Laws for Neural Language Models, Kaplan et al. 2020, Open Al





Neural Scaling Laws

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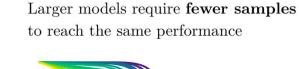


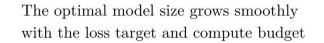


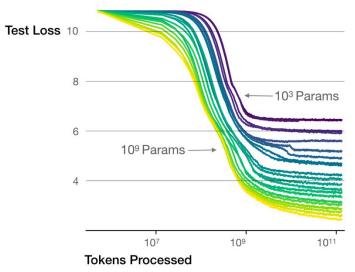


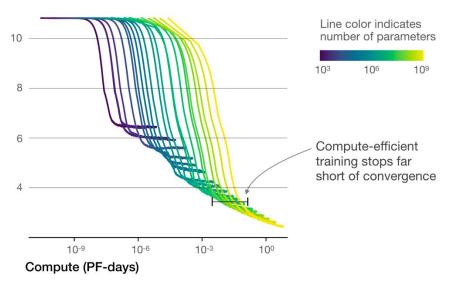
Neural Scaling Laws

- Performance improve smoothly as we increase the compute, dataset size, or the model size
- Large models are more sample efficient -- given a fixed computing budget, training a larger model for fewer steps is better than training a smaller model for more steps.









Source: Scaling Laws for Neural Language Models, Kaplan et al. 2020, Open Al



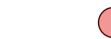


How to efficiently increase model size?

Switch Transformer
1.6 Trillion



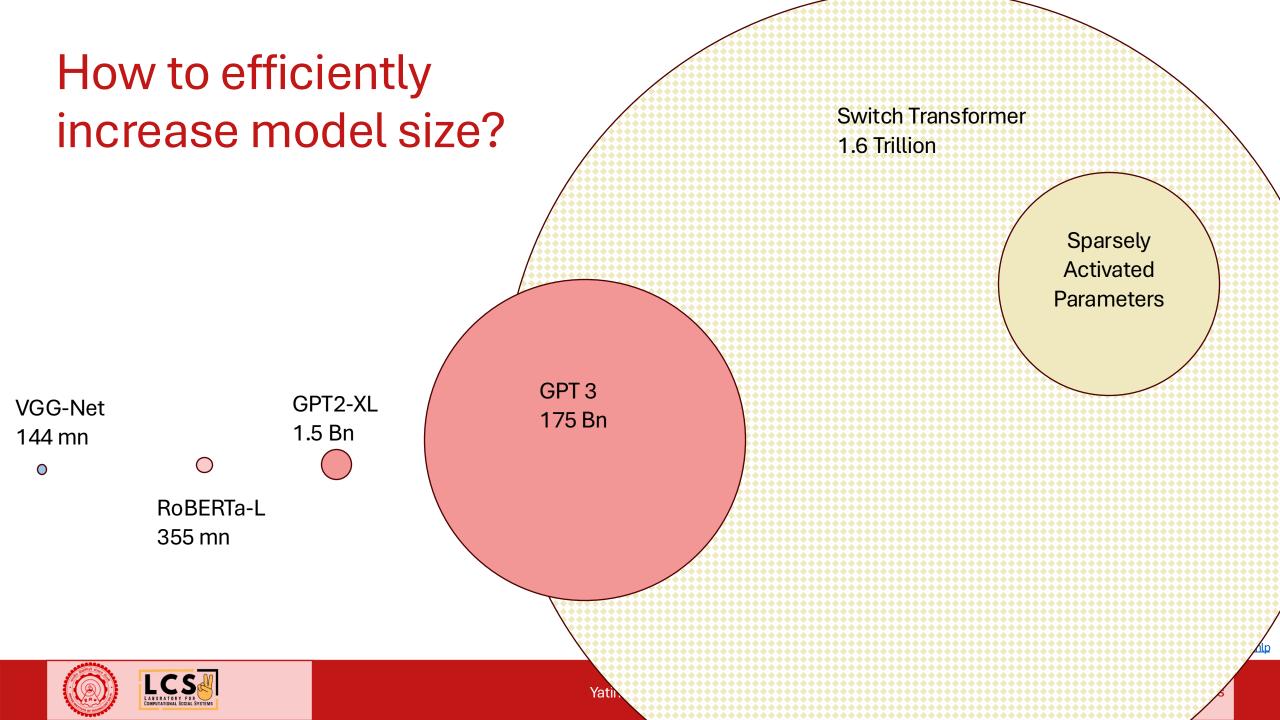
GPT2-XL 1.5 Bn



RoBERTa-L 355 mn XL GPT 3 175 Bn







Adaptive Mixtures of Local Experts

Robert A. Jacobs Michael I. Jordan

Department of Brain and Cognitive Sciences, Massachusetts Institute of Technology, Cambridge, MA 02139 USA

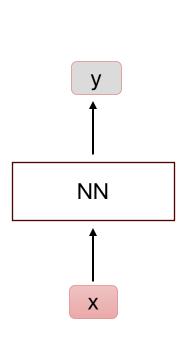
Steven J. Nowlan Geoffrey E. Hinton

Department of Computer Science, University of Toronto, Toronto, Canada M5S 1A4

We present a new supervised learning procedure for systems composed of many separate networks, each of which learns to handle a subset of the complete set of training cases. The new procedure can be viewed either as a modular version of a multilayer supervised network, or as an associative version of competitive learning. It therefore provides a new link between these two apparently different approaches. We demonstrate that the learning procedure divides up a vowel discrimination task into appropriate subtasks, each of which can be solved by a very simple expert network.

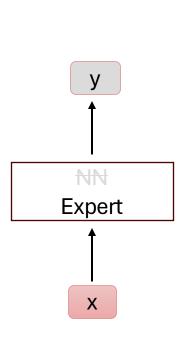






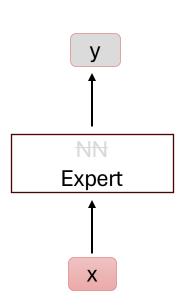






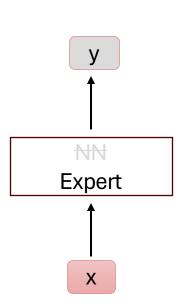






Expert 1 Expert 2 Expert n -1 Expert n

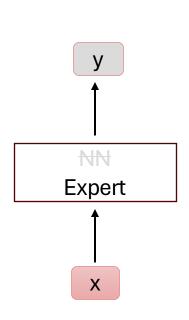




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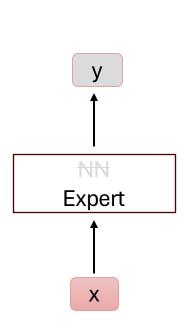


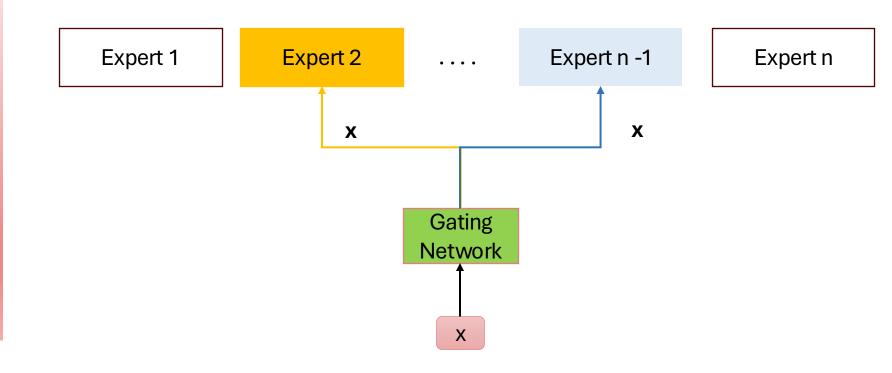


Expert 1 Expert 2 Expert n -1 Expert n Gating Network Χ



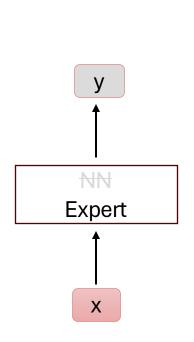


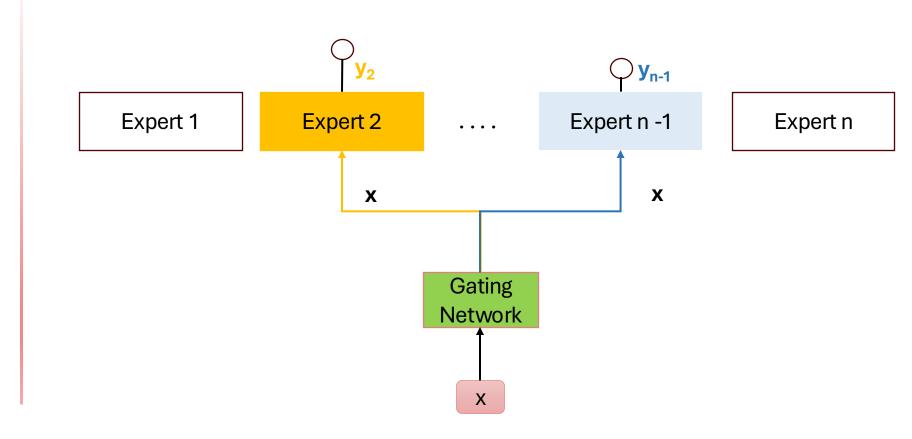






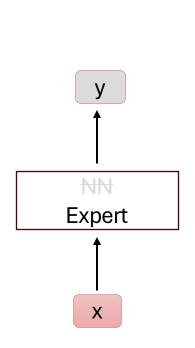


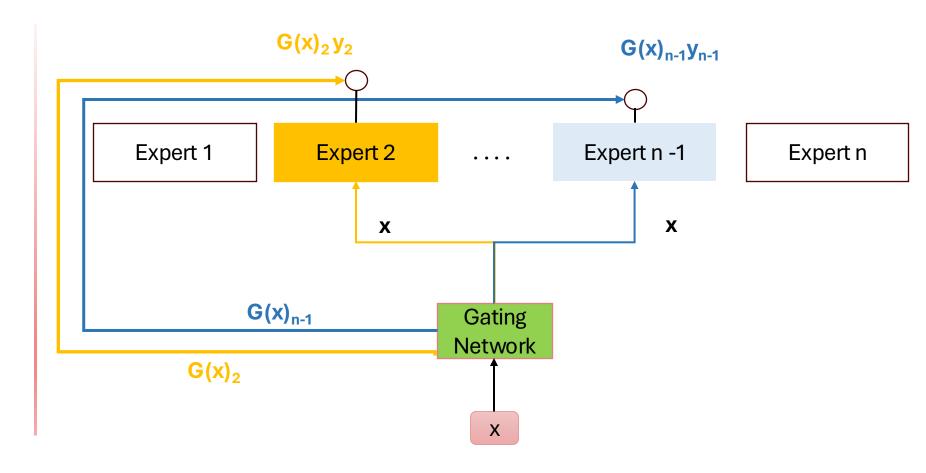






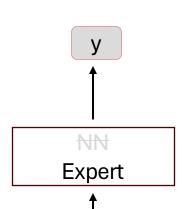




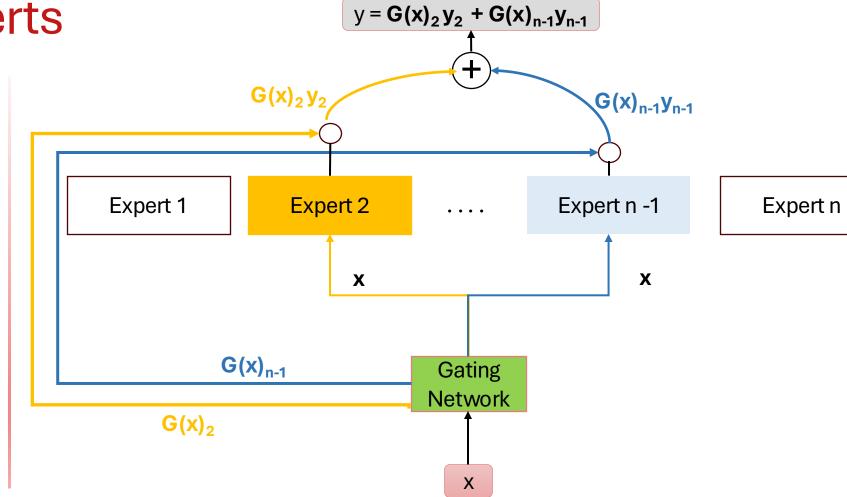








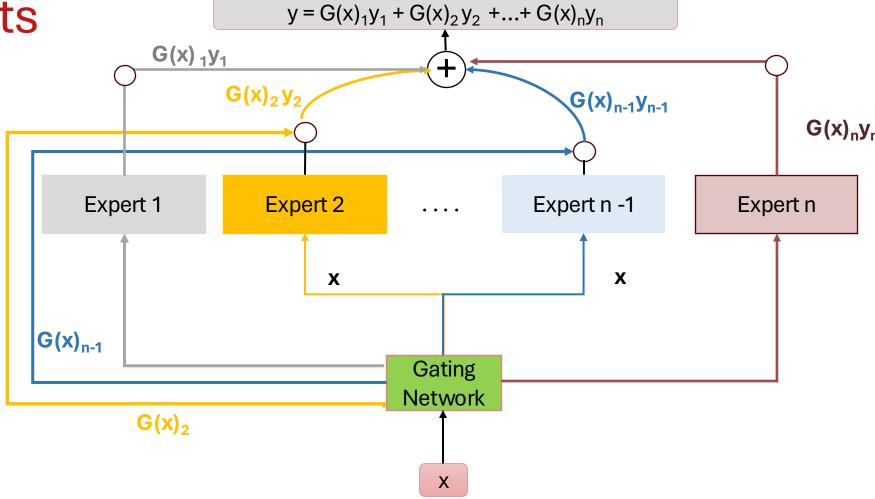
Χ







$$G_{\sigma}(x) = \operatorname{Softmax}(x \cdot W_g)$$

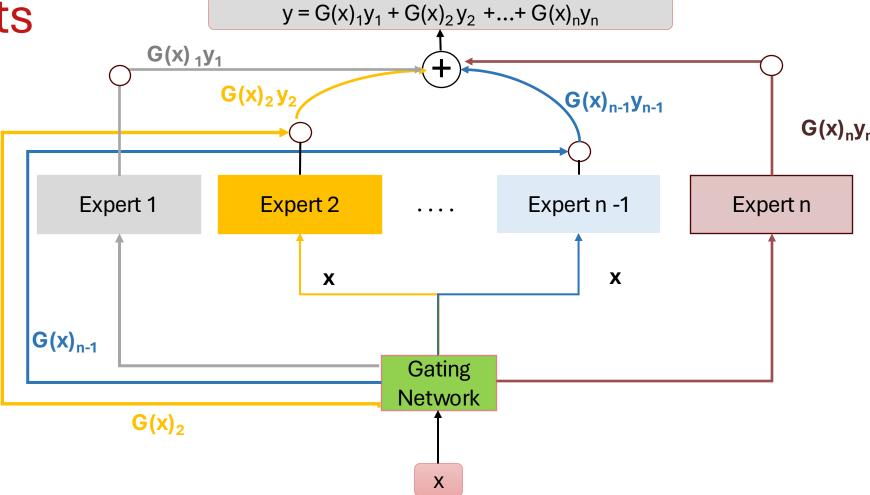






$$G_{\sigma}(x) = \operatorname{Softmax}(x \cdot W_q)$$

$$y = \sum_{i=1}^n G(x)_i E_i(x)$$







➤ Mixture of Experts Model [Jacobs et al., 1991; Jordan and Jacobs, 1994; Jordan et al., 1997; Tresp, 2001; Collobert et al., 2002;]





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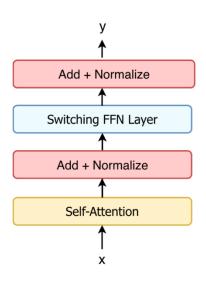


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- ➤ MoE layer in Transformer based LLMs [Fedus et al., 2021; Du, Nan, et al., 2021]
- ➤ Mixtral-8x7B [Jiang et al. 2024] Apache 2.0 license; surpasses GPT-3.5 Turbo, Claude-2.1, Gemini Pro, and Llama 2 70B chat model on human benchmarks

Content credits: https://www.youtube.com/watch?v=TwHPxUAuqy4

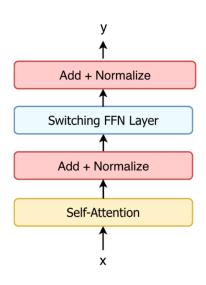


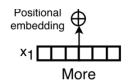


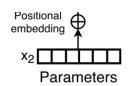






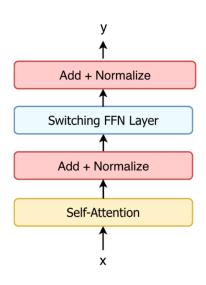


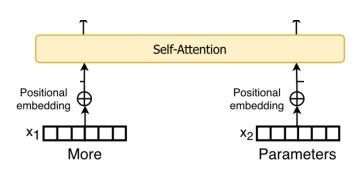






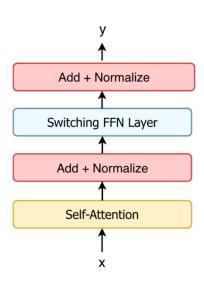


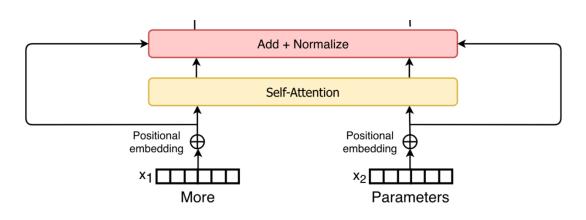






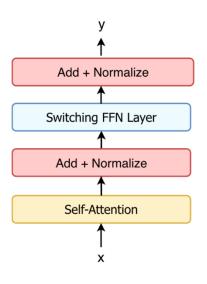


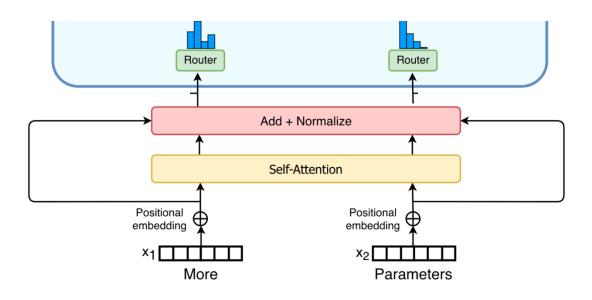








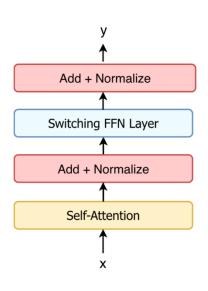


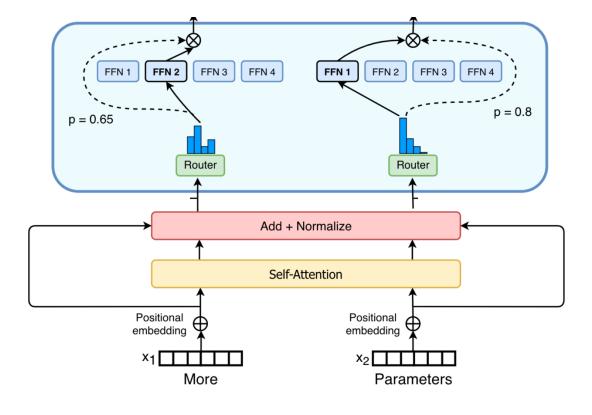






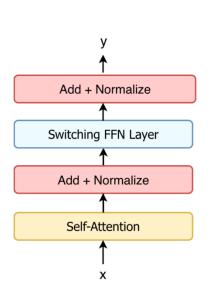
Mixture of Experts as a Layer

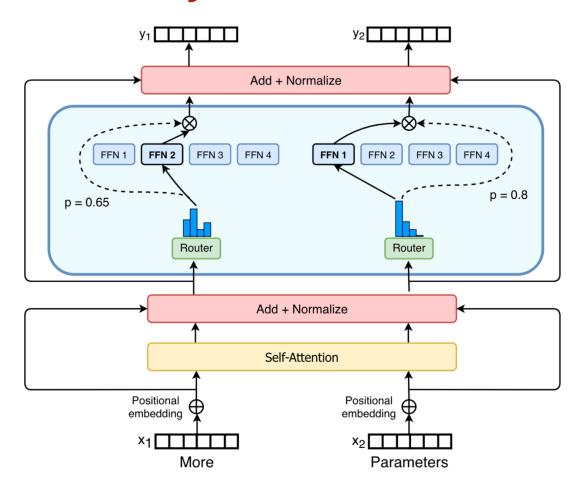






Mixture of Experts as a Layer

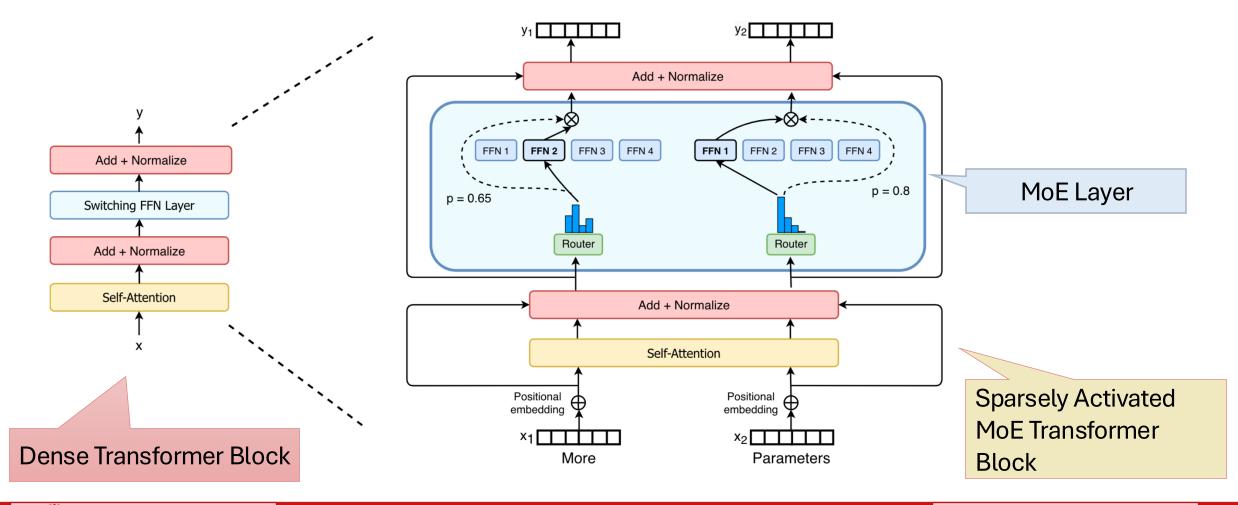






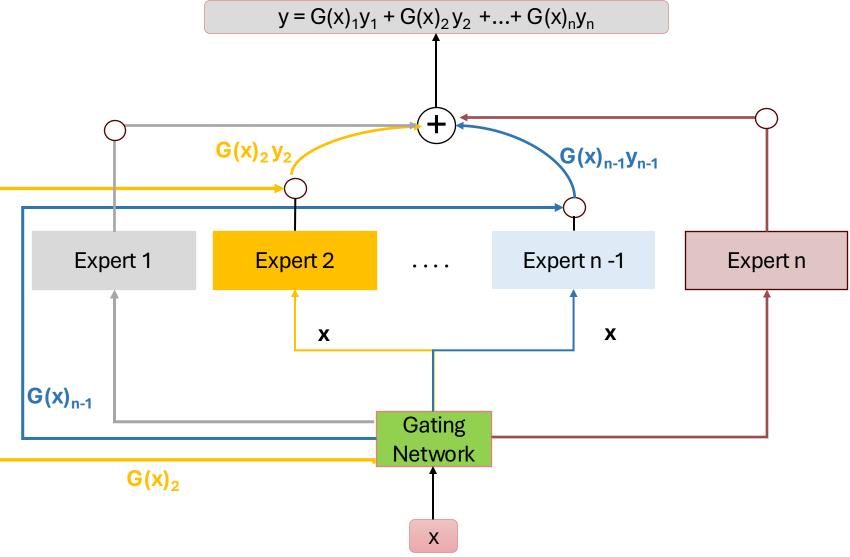


Mixture of Experts as a Layer



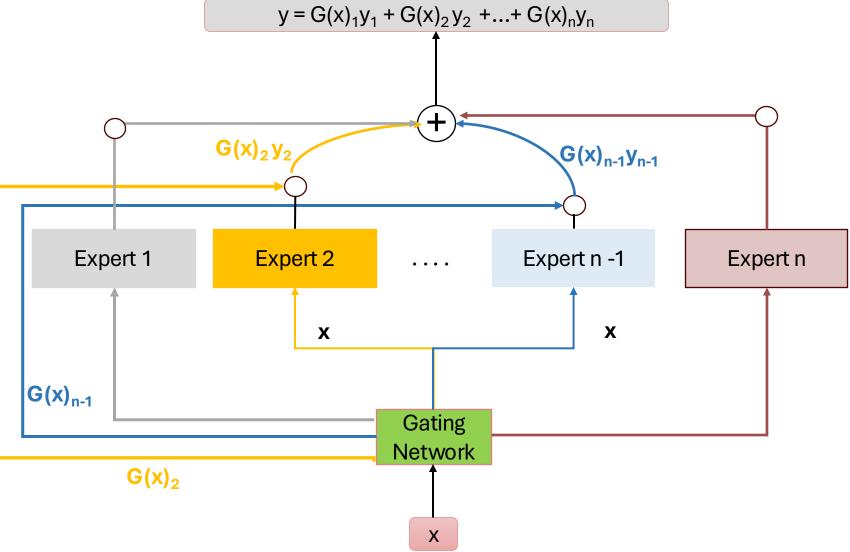








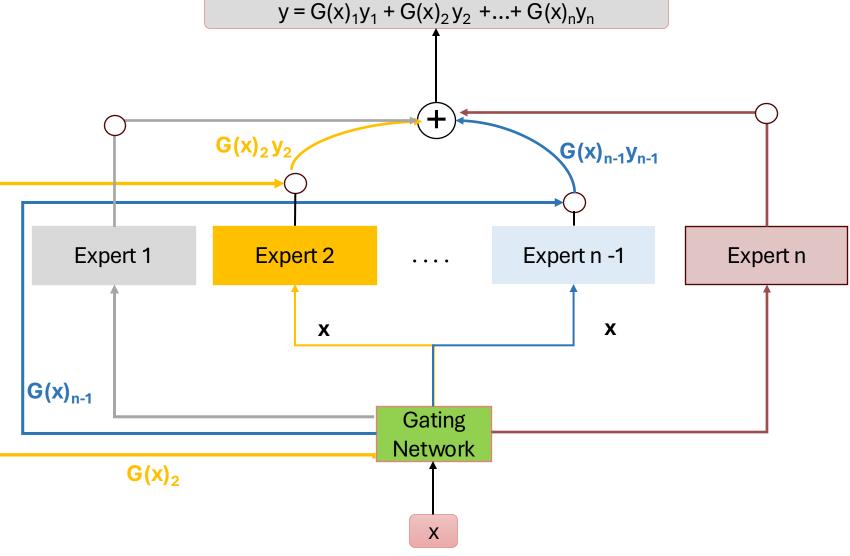
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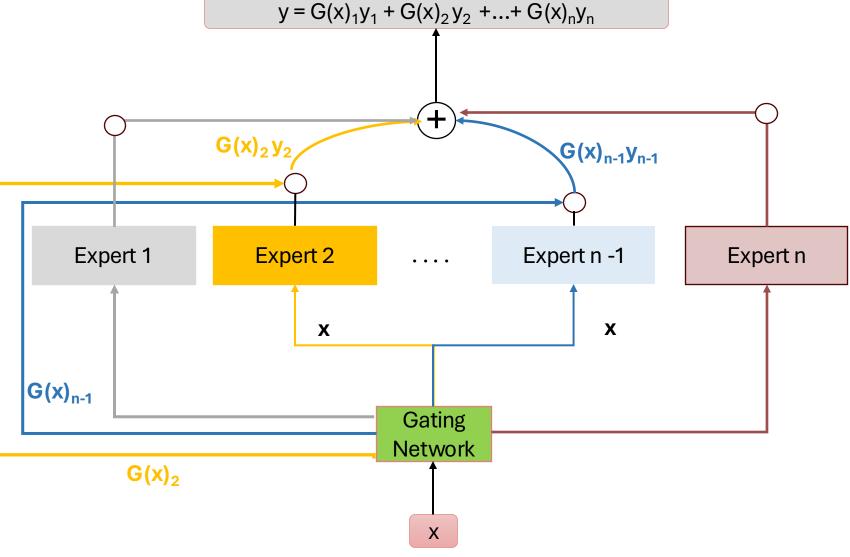
$$y=\sum_{i=1}^n G(x)_i E_i(x)$$





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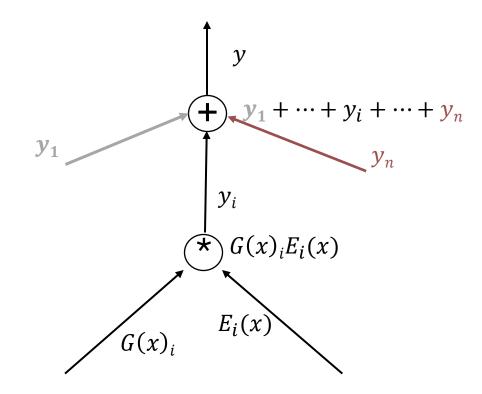
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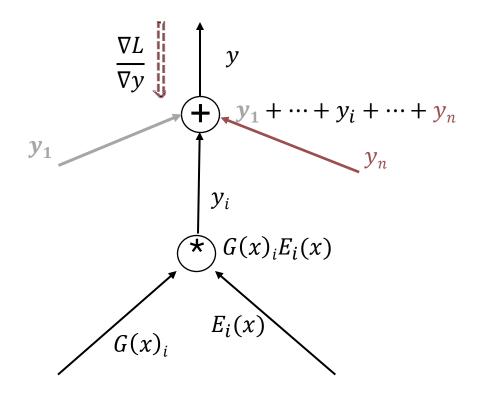
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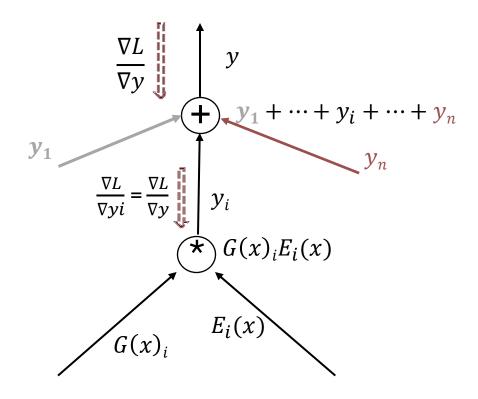
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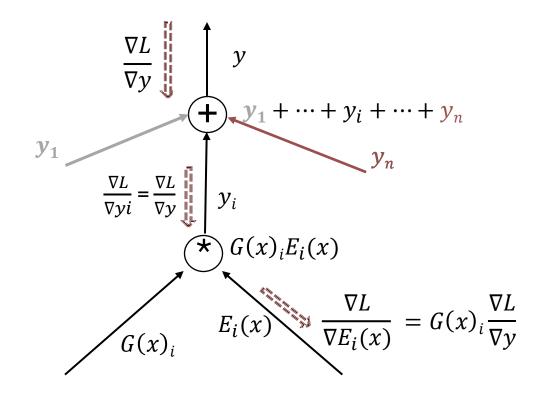
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d-dim.

Scalar

 $\frac{\nabla L}{\nabla E_i(x)} = G(x)_i \frac{\nabla L}{\nabla y}$

d-dim. vector



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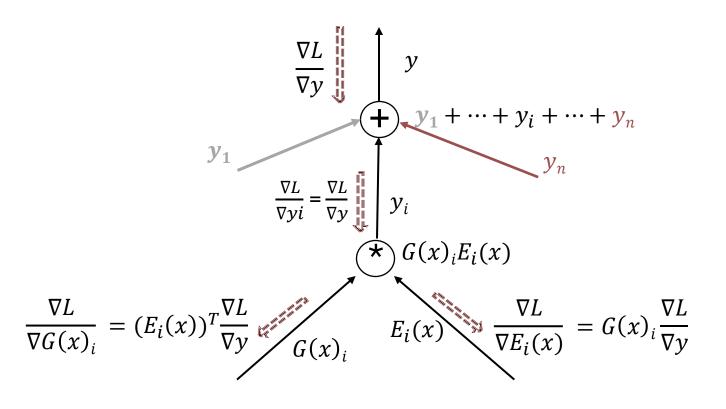
d-dim. vector

$$\frac{\nabla L}{\nabla G(x)_i} = (E_i(x))^T \frac{\nabla L}{\nabla y}$$

Scalar

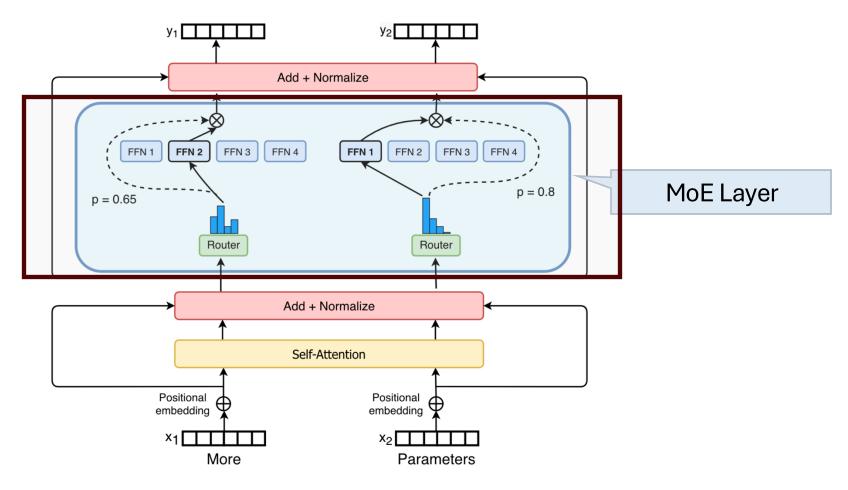
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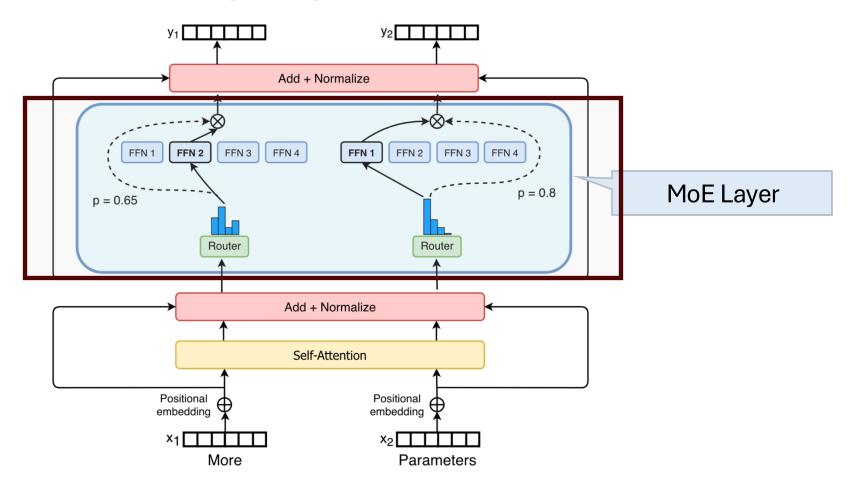






$$G_{\sigma}(x) = \operatorname{Softmax}(x \cdot W_g)$$

 $i * = argmax G_{\sigma}(x)$



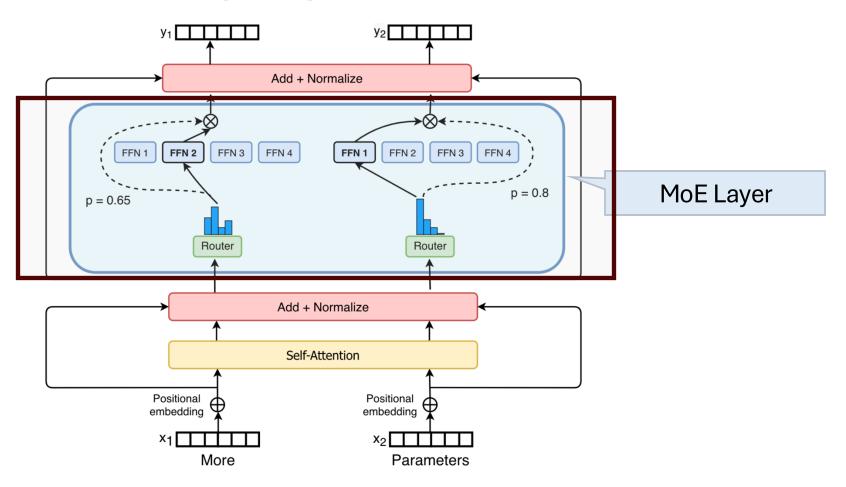




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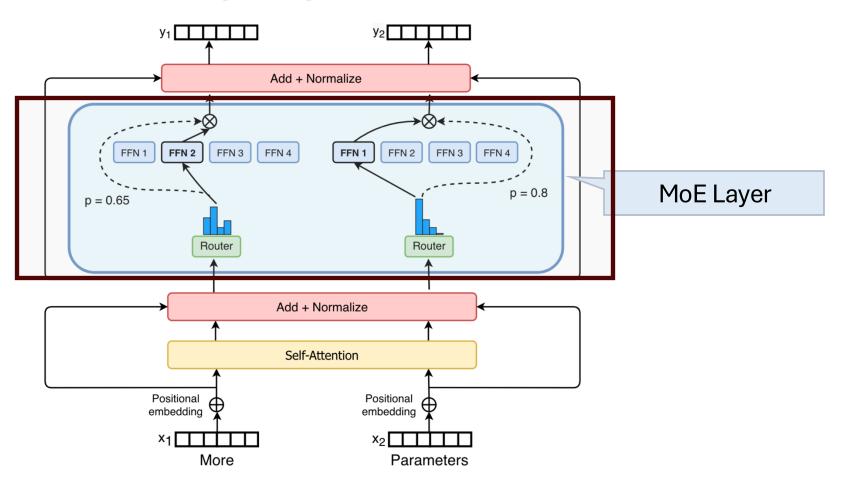


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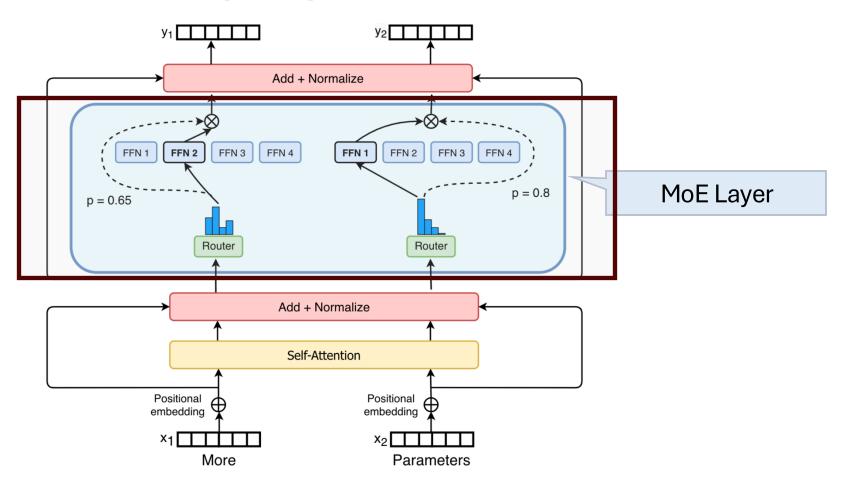
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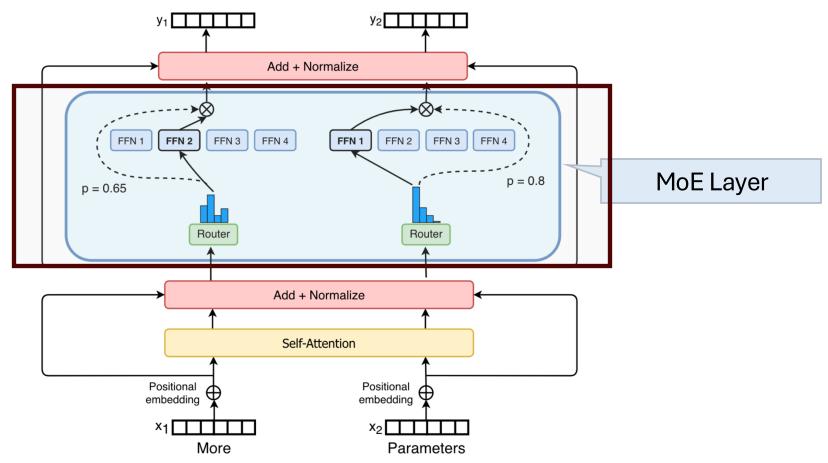
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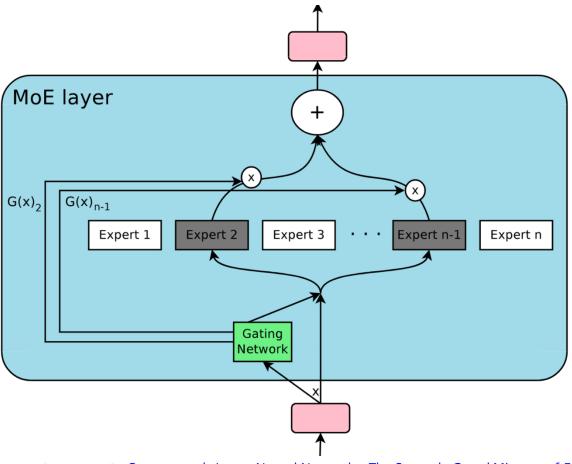
$$\frac{\nabla L}{\nabla G(x)_{i*}} = (E_{i*}(x))^T \frac{\nabla L}{\nabla y}$$

$$\frac{\nabla L}{\nabla E_i(x)} = \mathbf{0}$$
; $\frac{\nabla L}{\nabla G(x)_i} = 0$ for $i \neq i *$









Content credits: Outrageously Large Neural Networks: The Sparsely-Gated Mixture-of-Experts Layer





$$G_{\sigma}(x) = Softmax(H(x))$$



$$H(x)_i = (x \cdot W_g)_i + StandardNormal()$$

$$G_{\sigma}(x) = Softmax(H(x))$$



$$H(x)_i = (x \cdot W_g)_i + StandardNormal() \cdot Softplus((x \cdot W_{noise})_i)$$

$$G_{\sigma}(x) = Softmax(H(x))$$



 $H(x)_i = (x \cdot W_g)_i + StandardNormal() \cdot Softplus((x \cdot W_{noise})_i)$

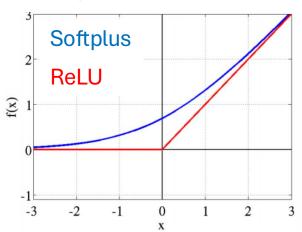
Learnable parameter
Mean

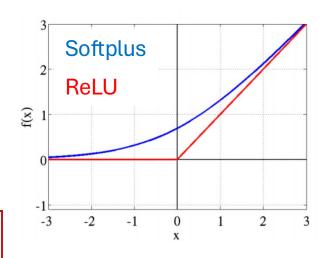
Learnable parameter Std. Dev



$$ext{Softplus}(x) = rac{1}{eta} * \log(1 + \exp(eta * x))$$

$$H(x)_i = (x \cdot W_g)_i + StandardNormal() \cdot \underbrace{Softplus}_{\text{($x \cdot W_{noise}$)}_i)}$$
 Learnable parameter Mean Std. Dev

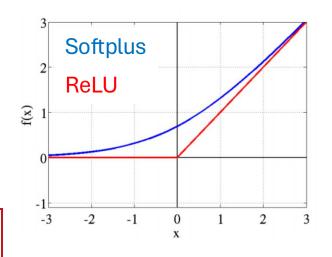




$$KeepTopK(v,k)_i = \begin{cases} v_i & \text{if } v_i \text{ is in the top } k \text{ elements of } v. \\ -\infty & \text{otherwise.} \end{cases}$$



$$H(x)_i = (x \cdot W_g)_i + StandardNormal() \cdot Softplus((x \cdot W_{noise})_i)$$
 Learnable parameter Mean Learnable parameter Std. Dev

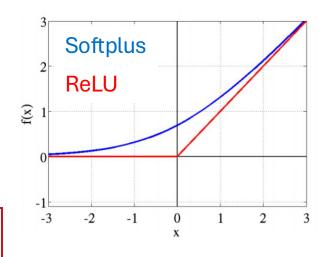


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 Ensures 0 probability after softmax





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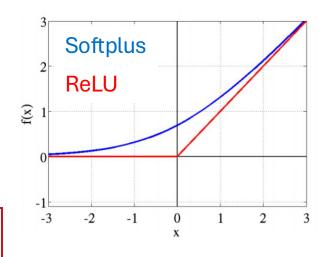
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H(x)





$$H(x)_i = (x \cdot W_g)_i + StandardNormal() \cdot Softplus((x \cdot W_{noise})_i)$$
 Learnable parameter Mean Learnable parameter Std. Dev

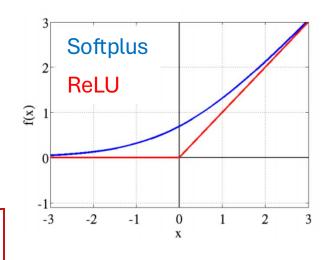


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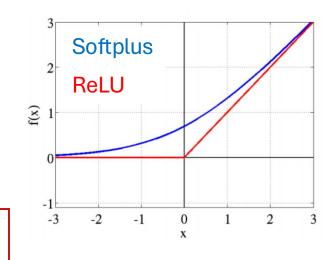
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 Ensures 0 probability after softmax

$$G(x) = Softmax(KeepTopK(H(x), k))$$





$$H(x)_i = (x \cdot W_g)_i + StandardNormal() \cdot Softplus((x \cdot W_{noise})_i)$$
 Learnable parameter Mean Learnable parameter Std. Dev



$$KeepTopK(v,k)_i = \begin{cases} v_i & \text{if } v_i \text{ is in the top } k \text{ elements of } v. \\ -\infty & \text{otherwise.} \end{cases}$$
 Ensures 0 probability after softmax

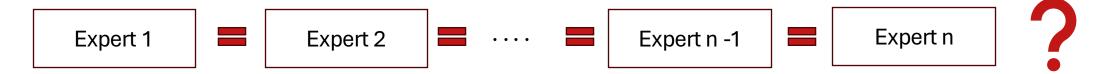
$$G(x) = Softmax(KeepTopK(H(x), k))$$

Only k non-zero elements; add up to 1





- ❖ All experts have:
 - Same architecture
 - Same initialization scheme
 - Trained with same optimizer
- So why don't they collapse? I.e.





Towards Understanding the Mixture-of-Experts Layer in Deep Learning

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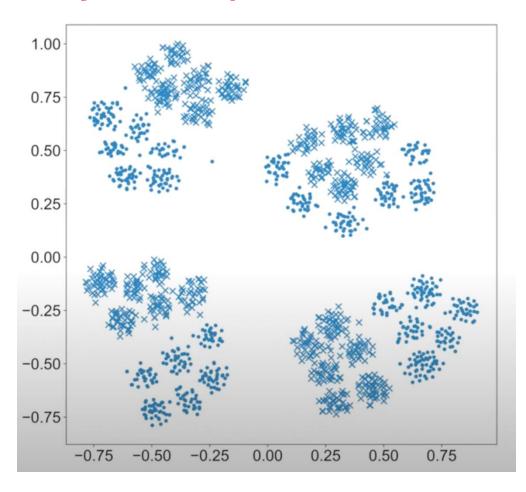
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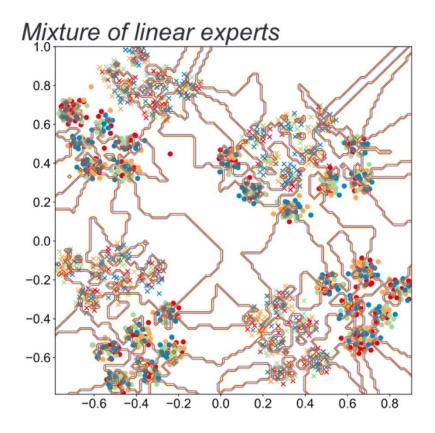






- ✓ Synthetically generated 50 dim. data
- √ Visualization in 2-D space
- √ 4 clusters
- ✓ Each cluster is linearly separable
- ✓ Ideally, a mixture of 4 linear experts sufficient for classification

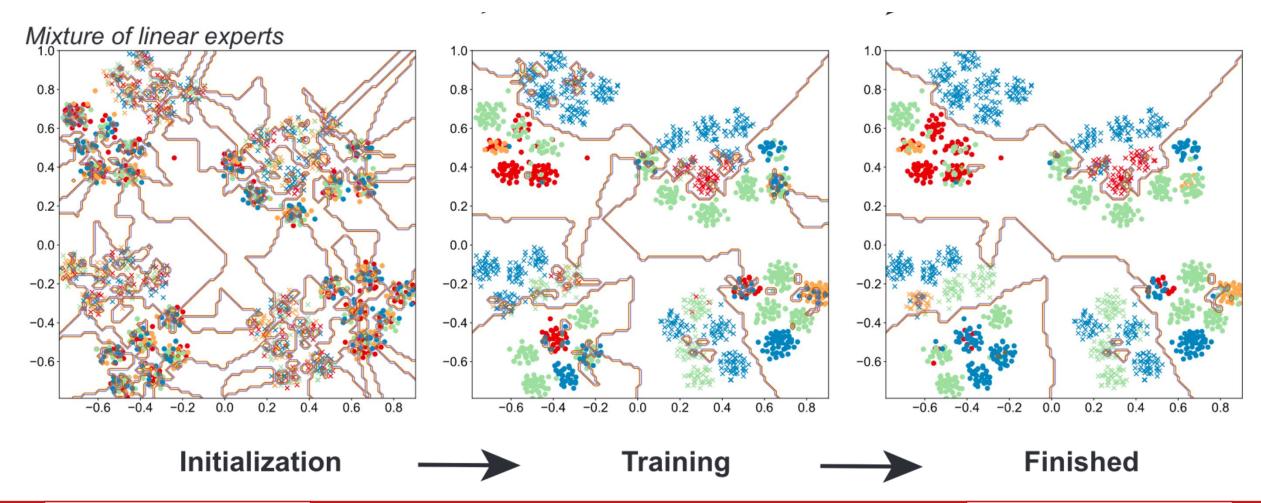




Initialization

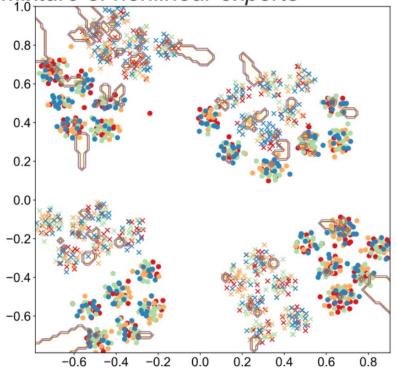








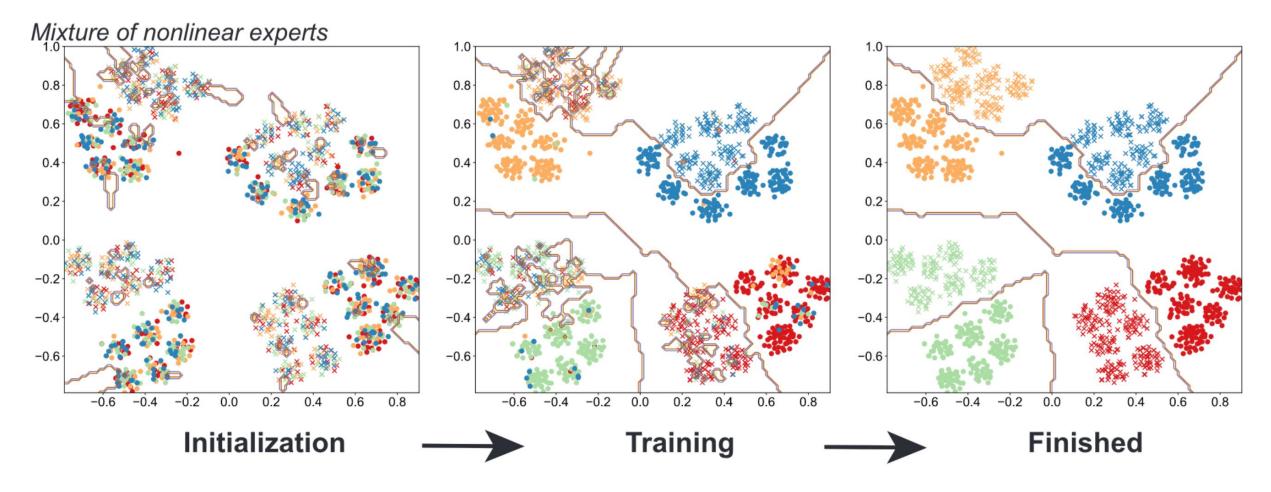




Initialization

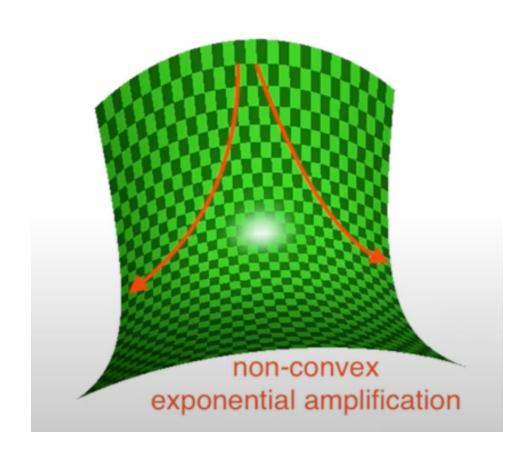


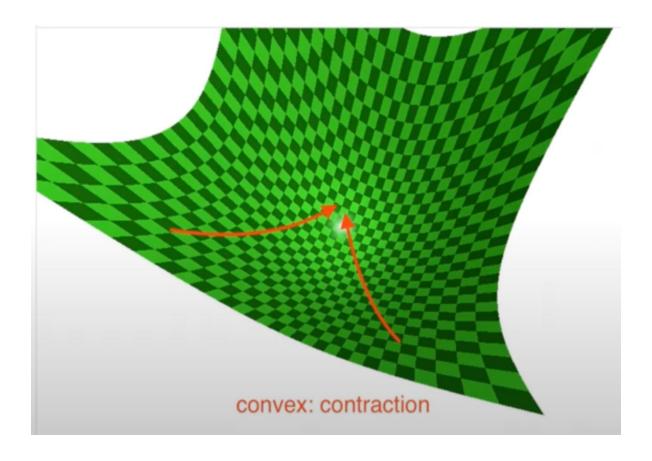














- > Exploration stage:
 - > experts diverge; router nearly untrained
- Router learning stage:
 - router learns to dispatch



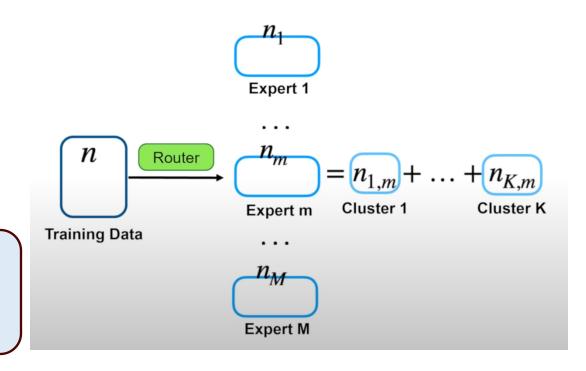


- > Exploration stage:
 - > experts diverge; router nearly untrained
- > Router learning stage:
 - router learns to dispatch

 $n_{k,m}$: # of samples from Cluster k routed to Expert m

 n_m : # of samples routed to Expert $m = \sum_{k=1}^K n_{k,m}$

n : # of total samples = $\sum_{m=1}^{M} n_m$





> Exploration stage:

> experts diverge; router nearly untrained

> Router learning stage:

router learns to dispatch

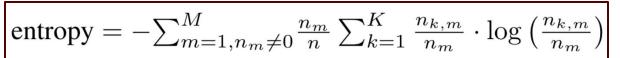
entropy =
$$-\sum_{m=1,n_m\neq 0}^{M} \frac{n_m}{n} \sum_{k=1}^{K} \frac{n_{k,m}}{n_m} \cdot \log\left(\frac{n_{k,m}}{n_m}\right)$$

 $n_{k,m}$: # of samples from Cluster k routed to Expert m

 n_m : # of samples routed to Expert $m = \sum_{k=1}^K n_{k,m}$

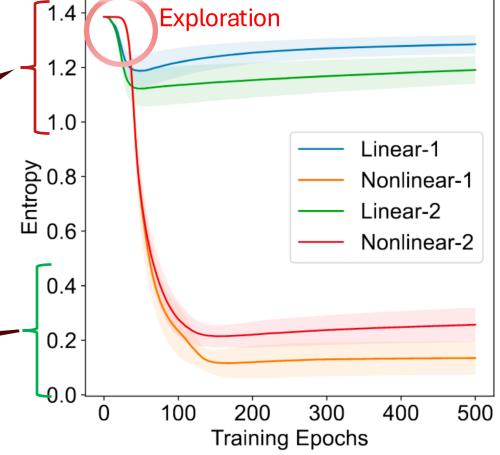
n: # of total samples = $\sum_{m=1}^{M} n_m$





Entropy is high if an input from cluster k is routed uniformly to all the experts

Entropy is low if an input from cluster k is routed to one expert







Pros and Cons of Sparse MoE Layer

Pros



Increased model parameters

Efficient pretraining due to conditional (sparse) computation



Faster inference

Cons



Unstable training

- Router collapse– router sends all tokens to the same expert
- May diverge

High memory requirement - all parameters need to be loaded in vRAM (GPU memory)



