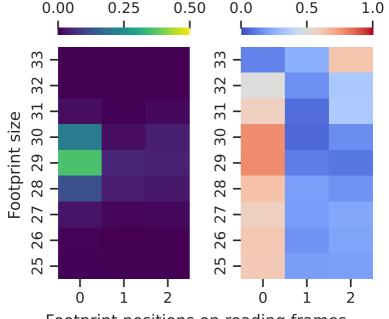
## 0.00 0.25 0.50 0.0 0.5

SRR3306588



Footprint positions on reading frames