



Machine Learning Applications for Particle Accelerators

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Exercises



Exercise 1

Build a Gaussian Process to model

$$f(x) = \sin(x).$$

For this first exercise, build the GP with only numpy and scipy (i.e. do not use scikit-learn, BoTorch,...).

Choose a prior with any kernel and $\mu(x) = 0$, define a method to compute the posterior and plot the posterior and the true function with 5 test points.

Tipp:

e.g. RBF kernel

covariance matrix element $K_{ij} = k_{RBF}(x_i, x_j)$, ... build entire matrix.



Exercise 1a

Build your own Bayesian Optimisation algo.

Use the GP and data from Exercise 1 and optimise it between $[0, 2\pi]$.

- Define the Acquisition Function UCB method for a single data point
 - * e.g. `def acq_ucb(x):...`

Iteratively find the optimum of $f(x)$ by optimising the Acquisition Function at each iteration.



Exercise 2

Solve Exercise 1 and 1a with BoTorch.

Exercise 3

Optimise the RMS of the AWAKE e^- in the horizontal plane with Bayesian Optimisation.

Start with a random corrector settings (method `initialise_trajectory_random()`)

Work with bounds $\pm 300\mu\text{rad}$

- **Electron beam trajectory steering problem for CERN's AWAKE**
[Advanced Proton Driven Plasma Wakefield Acceleration Experiment](#)

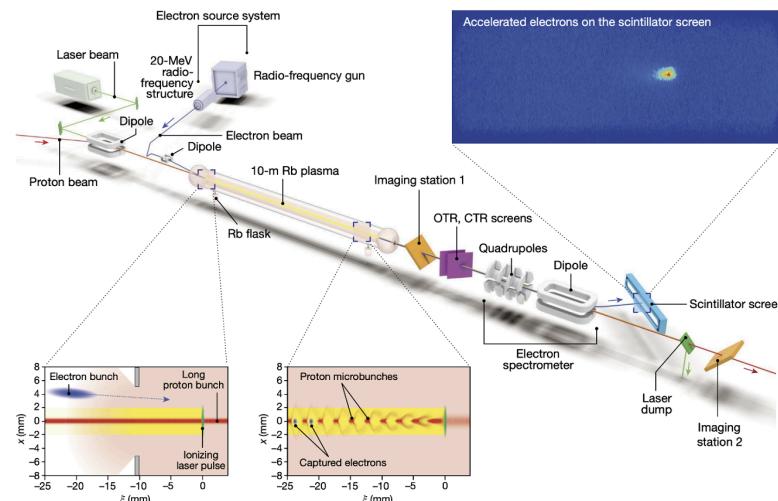
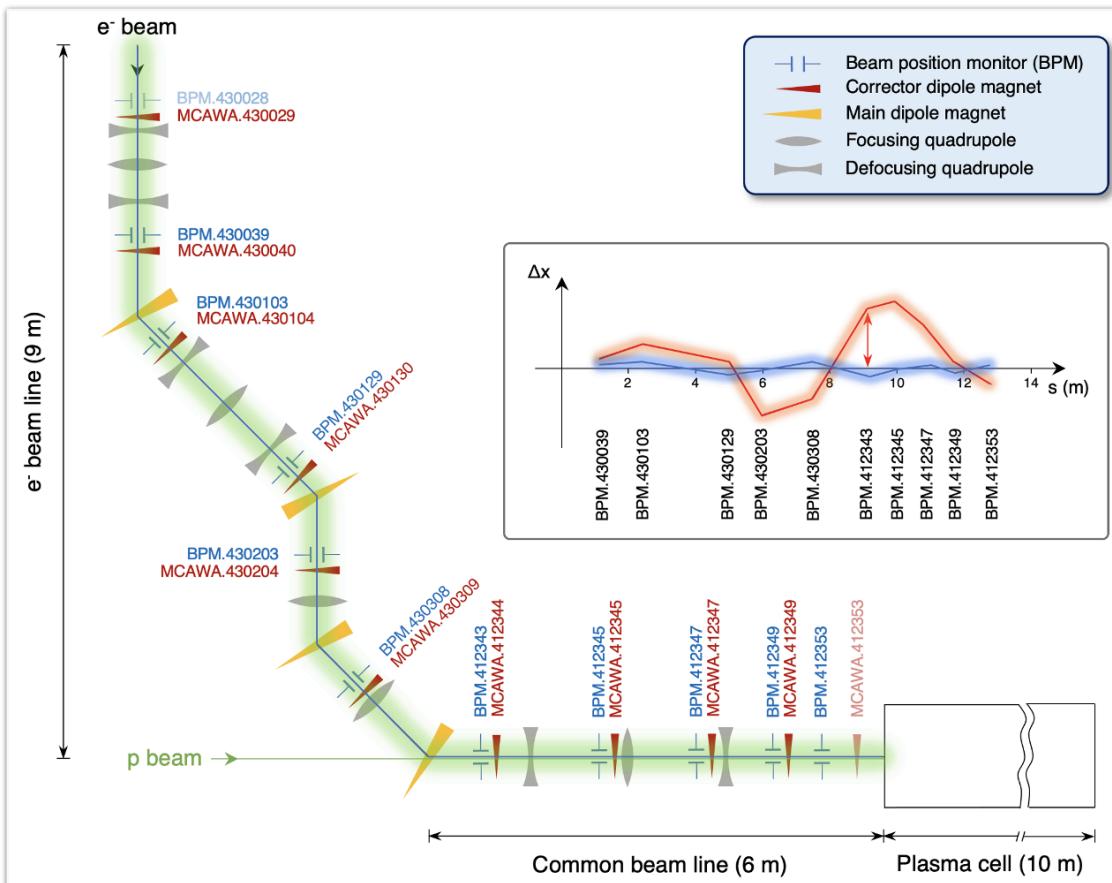


image by [AWAKE Collaboration](#)

Exercise 3 - instructions (1)



Exercise 3 - instructions (2)

Install the following package and work with swan; **choose awake-machine-demo.ipynb**

1 Go to: swan.cern.ch and pick configuration

2 Clone from: <https://gitlab.cern.ch/mischenk/rl-exercises.git>



Exercise 4

The goal of this exercise is to understand Q-learning.

Choose the project `rl-intro.ipynb`



Exercise 5

Implement model-free RL (based on SB3) with a Gymnasium environment to optimise the RMS of the AWAKE e^- trajectory in the horizontal plane.

Tipps:

Each episode should start with a new random trajectory and the agent needs to correct below RMS threshold (e.g. 1.5 mm).

The units of the example are: actors in radian, positions in m

Truncate the episodes: e.g. maximum number of iterations = 50