Optimization Algorithms for Machine/Deep Learning

Deterministic optimization methods

$$minf(x), \ x\in X$$
 f : differentiable $||
abla f(x)-
abla f(y)||\leq L||x-y||, \ orall x,y\in X$ e.g. $f(x)=rac{1}{2}X^{\mathrm{T}}AX-b^{\mathrm{T}}x$

 $\nabla f(x) = Ax - b$

$$|| orall f(x) - orall f(y) || = || A(x-y) || \le || A || || |x-y||, \;\; L = || A ||$$

Lemma
$$f(x) \leq f(y) + < riangle f(y), x-y > +rac{1}{2}{||x-y||}^2$$

$$x_{t+1} = argmin_{x \in X}Y_t < riangle f(x), x > +rac{1}{2}{||x-x_t||}^2$$

Optimality condition for the above subproblem

$$\begin{array}{l} \bullet & <\gamma_{t} \triangledown f(x_{t}) + x_{t+1} - x_{t}, x - x_{t+1} > \geq 0, \ \, \forall x \in X \\ \bullet & \gamma < \triangledown f(x_{t}), x_{t+1} - x > \leq \frac{1}{2} ||x - x_{t}||^{2} - \frac{1}{2} ||x - x_{t+1}|| - \frac{1}{2} ||x_{t} - x_{t+1}||^{2} \end{array} \tag{OPT2}$$

Observation

$$f(x_{t+1}) \leq f(x_t)$$
 if $\gamma_t \leq rac{2}{L}$ Fix $x=x_t$ in OPT1, $<
abla f(x_t), x_{t+1}-x_t > \leq -rac{1}{\gamma_t}||x_{t+1}-x_t||^2$ Also, $f(x_{t+1}) \leq f(x_t) + <
abla f(x_t), x_{t+1}-x_t > +rac{L}{2}||x_{t+1}-x_t||^2$

$$\leq f(x_t) - (\frac{1}{\gamma_t} - \frac{L}{2})||x_{t+1} - x_t||^2$$

$$\leq f(x_t)$$

$$f(x_{t+1}) \leq f(x_t) + \langle \nabla f(x_t), x_{t+1} - x_t \rangle + \frac{1}{2}||x_{t+1} - x||^2$$

$$= f(x_t) + \langle \nabla f(x_t), x - x_t \rangle + \langle \nabla f(x_t), x_{t+1} - x \rangle + \frac{L}{2}||x_{t+1} - x_t||^2$$
(Strong) Convexity OPT2
$$\leq f(x) + \frac{1}{2\gamma_t}[||x - x_t||^2 - ||x - x_{t+1}||^2] - \frac{1}{2}(\frac{1}{\gamma_t} - L)||x_{t+1} - x_t||^2$$

$$\leq f(x) + \frac{1}{2\gamma_t}[||x - x_t||^2 - ||x - x_{t+1}||^2]$$
If $\gamma_t = \gamma \leq \frac{1}{L}$, $t \leq 1, 2, \ldots$, then $\sum_{t=1}^k [f(x_{t+1}) - f(x)] \leq \frac{1}{2\gamma}[||x - x_t||^2 - ||x - x_{t+1}||^2]$
Notice $f(x_t) \geq f(x_{t+1})$, $\forall t \leq k+1$

$$\sum_{t=1}^k [f(x_{t+1}) - f(x)] \geq k[f(x_{t+1}) - f(x)]$$
Then $f(x_{t+1}) - f(x) \leq \frac{1}{2\gamma_t}||x - x_1||^2$

$$\gamma = \frac{1}{\tau} \Rightarrow f(x_{t+1}) - f(x^*) \leq \frac{L}{2\tau}||x^* - x_1||^2$$

Strong Convexity

$$\begin{split} f(x) &\geq f(y) + < \triangledown f(y), x - y > + \frac{\mu}{2} ||x - y||^2 \\ \textit{e.g. } f(x) &= \frac{1}{2} x^{\mathrm{T}} A x + b^{\mathrm{T}} x, \;\; \mu = \lambda_{min}(A) \\ f(x_{t+1}) &\leq f(x) - \frac{\mu}{2} ||x - x_t||^2 + \frac{1}{2\gamma} [||x - x_t||^2 - ||x - x_{t+1}||^2] \\ f(x+1) - f(x^*) + \frac{1}{2\gamma} ||x^* - x_{t+1}||^2 &\leq \frac{1}{2} (\frac{1}{\gamma} - \mu) ||x^* - x_t||^2 \\ ||x_{t+1} - x^*|| &\leq (1 - \gamma \mu) ||x^* - x_t||^2 \\ ||f r &= \frac{1}{L}, \, \text{then } ||x_{t+1} - x^*|| &\leq (1 - \frac{\mu}{L})^k ||x_t - x^*||^2 \\ ||x_{k+1} - x^*|| &\leq (1 - \frac{\mu}{L})^k ||x_t - x^*||^2 \end{split}$$

It suffices to have $(1-rac{\mu}{L})^k||x_1-x^*||^2\leq arepsilon$

If we want to have $||x_{k+1} - x^*|| \leq \varepsilon$

$$(1-rac{\mu}{L})^k \leq rac{arepsilon}{||x_1-x^*||^2}$$

$$k \cdot log(1 - rac{\mu}{L}) \leq log rac{arepsilon}{||x_i - x^*||^2}$$

$$k \cdot (-log(1-rac{\mu}{L})) \geq lograc{||x_i-x^*||^2}{arepsilon}$$

$$k \geq rac{1}{-log(1-rac{\mu}{arepsilon})}lograc{||x_1-x^*||^2}{arepsilon} \Leftarrow l \geq rac{L}{\mu}lograc{||x_i-x^*||^2}{arepsilon}$$

 ε : conditional number

$$E[G(x_t, \xi_t)] = \triangledown f(x_t)$$

Define $\delta_t = egin{aligned} & au f(x_t) - G(x_t, \xi_t) \end{aligned}$

- $ullet \ E[\delta_t] = 0 \ \delta_t$ independent of x_t
- $E[||\delta_t||^2] \leq \sigma^2$

$$egin{aligned} x_{t+1} &= argmin_{x \in X} \gamma_t < G(x_t, \xi_t), x > + rac{1}{2} ||x - x_t||^2 \ \gamma_t < G(x_t, \xi_t), x_{t+1} - x > \leq rac{1}{2} [||x - x_t||^2 - ||x - x_{t+1}||^2 - ||x_t - x_{t+1}||^2] \end{aligned} \ ext{(OPT2')}$$
 todo:

Will be inplemented later or you can pull requests my Github Repo

Comments

- 1. $f(x) = E_{\xi}[F(x,\xi)]$, ξ is continuous random variable, SGD nearly optimal
- 2. $f(x) = \frac{1}{N} \sum_{t=1}^{N} f_i(x)$, using randomized incremental gradient method, we can improve the speed of convergence in terms of the dependence on ε . But the convergence depends on N.
- Deep Learning
- ullet Burer-Monteiro Law Rank decomposition $X=LU,\ L\in\mathbb{R}^{m imes r},U\in\mathbb{R}^{r imes n}$ $min_{I,II}||X-LU||^2$

Nonconvex Optimization

$$min_{x\in\mathbb{R}^n}f(x)$$

 ${m f}$ is smooth but not necessarily convex

$$egin{aligned} || orall f(x) - orall f(y) || & \leq L ||x-y||, \ \ orall x, y \ & \ x_{t+1} = x_t - \gamma_t orall f(x_t) \end{aligned}$$

$$egin{aligned} f(x_{t+1}) & \leq f(x_t) + igtriangledown f(x_t)^{ ext{T}}(x_{t+1} - x_t) + rac{L}{2}||x_{t+1} - x_t||^2 \ & = f(x_1) - \gamma_t ||igtriangledown f(x_t)||^2 + rac{L\gamma_t^2}{2}||igtriangledown f(x_t)||^2 \ & = f(x_t) - \gamma_t (1 - rac{L\gamma_t}{2})||igtriangledown f(x_t)||^2 \end{aligned}$$

$$\gamma_t(1-rac{L\gamma_t}{2})||
abla f(x_t)||^2 \leq f(x_t)-f(x_{t+1})$$

$$\sum_{t=1}^{k} \gamma_t (1 - rac{L\gamma_t}{2}) ||igtriangledown f(x_t)||^2 \leq f(x_1) - f(x_{t+1}) \leq f(x_1) - f^*$$

Output
$$\overline{x_k}$$
 s.t. $|| riangledown f(\overline{x_k}) || = min_{t=1,\ldots,k} || riangledown f(\overline{x_t}) ||$

$$0 \le \gamma_t \le \frac{2}{L}$$

$$\sum_{t=1}^k \gamma_t (1-rac{L\gamma_t}{2})|| riangledown f(x_t)||^2 \geq || riangledown f(\overline{x_k})||^2 \sum_{t=1}^k r_t (1-rac{Lr_t}{2})$$

todo:

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$$\sum d_i = n, d_i > = 1$$