# Attention is all you need

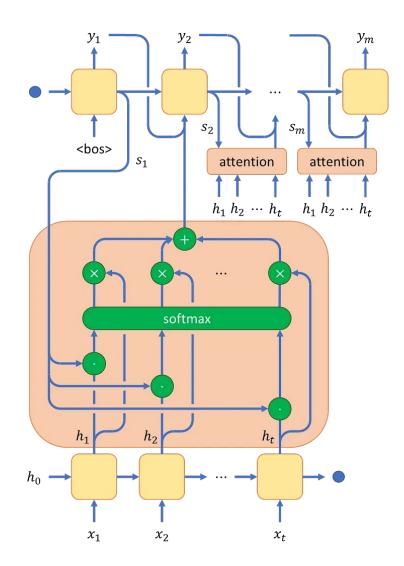
RNN is unnecessary

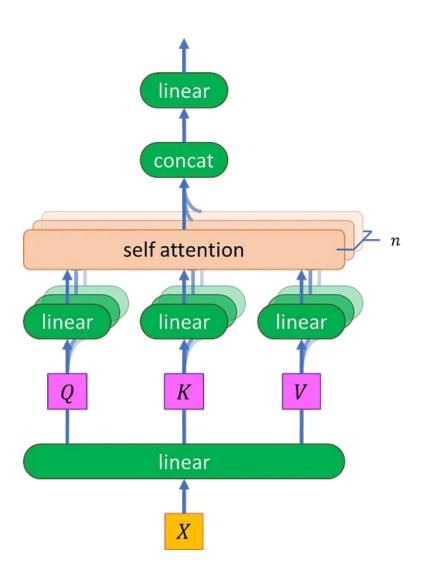
Liang Hong 17 Mar, 2023

### Outline

- How inference change from RNN style to Transformer style
- How attention deal with token order
- What's next

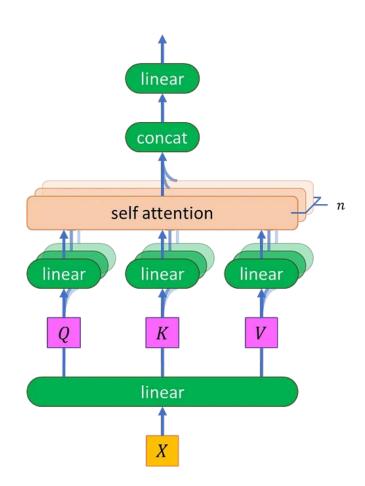
# Inference style change





### Token order

• Without sequential input, how token order is perceived?



Attention is performed with dot product, and the previous linear layers are shared.

-> permutation irrelevant

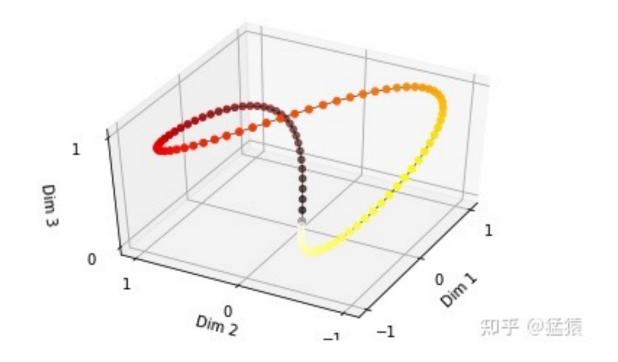
### Positional encoding

$$egin{cases} PE(pos,2i) = \sin\Bigl(pos/10000^{2i/d_{model}}\Bigr) \ PE( ext{pos},2i+1) = \cos\Bigl(pos/10000^{2i/d_{model}}\Bigr) \end{cases}$$

#### Why this frequency

X int type

**X** 0~1 representation



Credit to @lemonround

# Positional encoding

$$egin{cases} PE(pos,2i) = \sin\Bigl(pos/10000^{2i/d_{model}}\Bigr) \ PE( ext{pos},2i+1) = \cos\Bigl(pos/10000^{2i/d_{model}}\Bigr) \end{cases}$$

(now we have unique and continuous position rep vectors)

How can we get relative position from position encoding?

$$egin{aligned} PE_t^T*PE_{t+ riangle t} &= \sum_{i=0}^{rac{d_{model}}{2}-1} [sin(w_it)sin(w_i(t+ riangle t)+cos(w_it)cos(w_i(t+ riangle t))] \ &= \sum_{i=0}^{rac{d_{model}}{2}-1} cos(w_i(t-(t+ riangle t))) \ &= \sum_{i=0}^{rac{d_{model}}{2}-1} cos(w_i riangle t) \ &= \sum_{i=0}^{rac{d_{model}}{2}-1} cos(w_i riangle t) \end{aligned} egin{aligned} PE_t^{(i)} &= egin{cases} \sin(w_it), & if \ k=2i \ \cos(w_it), & if \ k=2i+1 \end{cases}$$

# Positional encoding

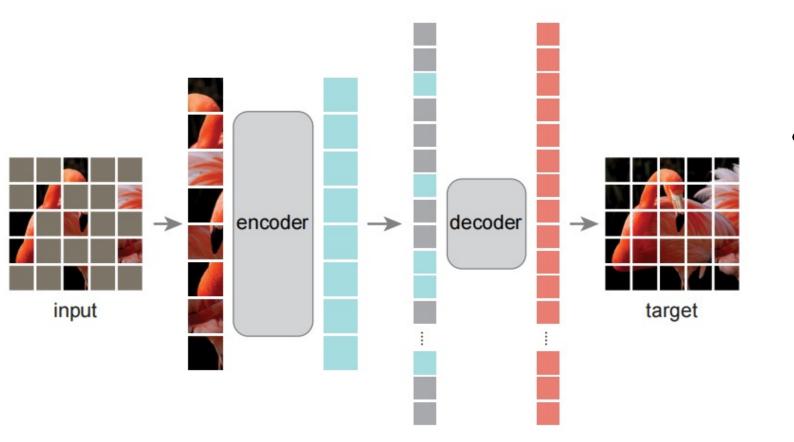
$$egin{cases} PE(pos,2i) = \sin\Bigl(pos/10000^{2i/d_{model}}\Bigr) \ PE( ext{pos},2i+1) = \cos\Bigl(pos/10000^{2i/d_{model}}\Bigr) \end{cases}$$

(now we can get relative positions from positional encoding)

$$egin{align*} PE_t^T * PE_{t+ riangle t} &= \sum_{i=0}^{rac{d_{model}}{2}}^{-1} [sin(w_i t) sin(w_i (t+ riangle t) + cos(w_i t) cos(w_i (t+ riangle t))] \ &= \sum_{i=0}^{rac{d_{model}}{2}}^{-1} cos(w_i (t-(t+ riangle t))) \ &= \sum_{i=0}^{rac{d_{model}}{2}}^{-1} cos(w_i riangle t) egin{align*} igodom{ index}{distance aware direction aware } \ igodom{ index}{direction aware } \ igod$$

$$PE_t^{(i)} = egin{cases} \sin(w_i t), & if \ k=2i \ \cos(w_i t), & if \ k=2i+1 \end{cases}$$

### What's next



 MAE: Masked Autoencoders Are Scalable Vision Learners

### What's next

