

# Cosmic Galois Group

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# 1 Statement of main results

Marcolli and Connes defined it

**Theorem 1.1.** *For any Feynman graph  $G$  with generic kinematics  $q, m$  there is a canonical way to associate to a **convergent integral***

- *an object  $\text{mot}_G$  in  $\mathcal{H}(S)$ , where  $S$  is a Zariski open in a space of kinematics*
- *.....*
- *....*

# 2 Feynman graph and graph polynomials

A Feynman graph is a graph  $G$  defined by  $(V_G, E_G, E_G^{\text{ext}})$ , where  $V_G$  is the set of vertices of  $G$ ,  $E_G$  is the set of internal edges of  $G$ , and  $E_G^{\text{ext}}$  is a set of external legs. Their endpoints are encoded by the maps  $\partial : E_G \rightarrow \text{Sym}^2 V_G$  and  $\partial : E_G^{\text{ext}} \rightarrow V_G$ . We shall assume that the vertices with external legs lie in a single connected component of  $G$ . A Feynman graph additionally comes with kinematic data:

- a particle mass  $m_e \in \mathbb{R}$  for every internal edge  $e \in E_G$ .
- a momentum  $q_i \in \mathbb{R}^d$  for every external leg  $i \in E_G^{\text{ext}}$ ,

where  $d \geq 0$  is the dimension of space-time. All the external legs will be oriented inwards, so all momenta are incoming and are subject to momentum conservation.

In this paper, a subgraph  $H$  of  $G$  will be graph defined by a triple  $(V_H, E_H, E_H^{\text{ext}})$  where  $V_H \subset V_G$ ,  $E_H \subset E_G$  and either  $E_H^{\text{ext}} = E_G^{\text{ext}}$  or  $E_H^{\text{ext}} = \emptyset$ .

A tadpole is a subgraph of the the form  $\{\{v\}, \{v, v\}, \emptyset\}$ . We shall use the following notation for the basic combinatorial invariants of  $G$ :

- $h_G = \dim(H^1(G))$  the loop number of  $G$
- $\kappa_G = \dim(H^0(G))$  the number of connected components of  $G$
- $N_G = |E_G|$  the number of connected components of  $G$ .

They do not depend on the external legs of  $G$ . Euler's formula states that

$$N_G - V_G = h_G - \kappa_G.$$

We define that If a vertex  $v \in V_G$  has several incoming momenta  $q_1, \dots, q_n$  we can replace it with a single incoming momentum  $q_1 + \dots + q_n$ . Our notion of Feynman subgraph respects this equivalence relation. Then the graph polynomial defined latter would only depend on the equivalence classes.

We say that a Feynman graph is **of type**  $(Q, M)$  if it is equivalent to a graph with at most  $Q$  external kinematic parameters and at most  $M$  nonzero particle mass. We shall call a graph one-particle irreducible, or 1PI, if every connected component is 2-edge connected (i.e. deleting any edge causes the loop number to drop).

## 2.1 Graph polynomials

Let  $G$  be a Feynman graph. Recall that a tree is a connected graph  $T$  with  $h_T = 0$ . A forest is any graph with  $h_T = 0$ .

**Definition 2.1.** *Let  $G$  be a connected Feynman graph. The **Kirchhoff polynomial** (or first Symanzik polynomial) is the polynomial in  $\mathbb{Z}[\alpha_e, e \in E_G]$  defined by*

$$\Psi_G = \sum_{T \subset G} \prod_{e \notin T} \alpha_e, \quad (1)$$

where the sum is over all spanning trees  $T$  of  $G$ . If  $G$  has several connected components  $G_1, \dots, G_n$ , we shall define

$$\Psi_G = \prod_1^n \Psi_{G_i}$$

The second Symanzik polynomial is defined for connected  $G$  by

$$\Phi_G(q) = \sum_{T_1 \cup T_2 \subset G} (q^{T_1})^2 \prod_{e \notin T_1 \cup T_2} \alpha_e, \quad (2)$$

where the sum is over all spanning 2-trees  $T = T_1 \cup T_2$  of  $G$ , and  $q^{T_1} := \sum_{i \in E_{T_1}^{ext}} q_i$  is the total momentum entering  $T_1$ .

**Remark 2.2.**  $\alpha_e$  are just the Schwinger parameters

**Definition 2.3.** Let  $G$  be a Feynman graph. Define

$$\Xi_G(q, m) = \Phi_G(q) + \left( \sum_{e \in E_G} m_e^2 \alpha_e \right) \Psi_G.$$

It is the denominator of Feynman integral, and it is homogeneous in  $\alpha_e$  of degree  $h_G + 1$

Since the graph polynomials only depend on the total momentum flow, they are well-defined on equivalence classes of graphs.

## 2.2 Feynman integral in projective space

After omitting certain pre-factors, we define the Feynman integral

$$I_G(q, m) = \int_{\sigma} \omega_G(q, m),$$

where

$$\omega_G(q, m) = \frac{1}{\Psi_G^{d/2}} \left( \frac{\Psi_G}{\Xi_G(q, m)} \right)^{N_G - h_G d/2} \Omega_G$$

and

$$\Omega_G = \sum_{i=1}^{N_G} (-1)^i \alpha_i d\alpha_1 \wedge \dots \wedge \widehat{d\alpha_i} \wedge \dots \wedge d\alpha_{N_G}$$

Following from the fact that  $\deg(\Psi_G) = h_G$  and  $\deg(\Xi_G) = h_G + 1$ , we know that  $\omega_G$  is homogeneous of degree 0.

Finally, let  $\sigma \subset \mathbb{P}^{N_G-1}(\mathbb{R})$  be the coordinate simplex defined in projective coordinates by

$$\sigma = \{(\alpha_1 : \dots : \alpha_{N_G}) \in \mathbb{P}^{N_G-1}(\mathbb{R}) : \alpha_i \geq 0\}.$$

## 2.3 Edge subgraphs and their quotients

Let  $G = (V_G, E_G, E_G^{ext})$  be a Feynman graph. A set of internal edges  $\gamma \subset E_G$  defines a subgraph of  $G$  as follows. Write  $E_\gamma = \gamma$  and let  $V_\gamma$  be the set of endpoints of elements of  $E_\gamma$ .

**Definition 2.4.** A set of edges  $\gamma \subset E_G$  is **momentum-spanning** if  $\partial E_G^{ext} \subset V_\gamma$ , and the vertices  $E_G^{ext}$  lie in a single connected component of the graph  $(V_\gamma, E_\gamma)$ .

we define the subgraph associated to  $\gamma \subset E_G$  by

$$(V_\gamma, E_\gamma, E_\gamma^{ext}),$$

where  $E_\gamma^{ext} = E_G^{ext}$  if  $\gamma$  is momentum-spanning and  $E_\gamma^{ext} = \emptyset$  otherwise. We call  $(V_\gamma, E_\gamma, E_\gamma^{ext})$  the edge-subgraph associated to  $\gamma$  and denote it also by  $\gamma$  when no confusion arises.

The quotient of  $G$  by an edge-subgraph  $\gamma$  is defined by

$$G/\gamma = (V_G/\sim, (E_G \setminus \gamma)/\sim, E_G^{ext}/\sim),$$

where  $\sim$  is the equivalence relation on vertices of  $G$  where two vertices are equivalent if and only if they are vertices of the same connected component of  $\gamma$ , and the induced equivalence relation on edges (unordered pairs of vertices). It is a Feynman graph. Every connected components of  $\gamma$  corresponds to a unique vertex in  $G/\gamma$ . Note that  $\gamma$  is momentum-spanning if and only if  $G/\gamma$  is equivalent to a graph with no external momenta. (which amounts to compress each component of  $\gamma$  to a single vertex.).

In this way, exactly one of the two Feynman graphs  $\gamma$  and  $G/\gamma$  is equivalent to a Feynman graph with non-zero external momenta: if  $\gamma$  is momentum spanning it is  $\gamma$ , otherwise it is  $G/\gamma$ .

## 2.4 Contraction-deletion

Let  $G = (V_G, E_G, E_G^{ext})$  be a Feynman graph. The deletion of an edge  $e$  in  $G$  is the graph  $G/e$  defined by deleting the edge  $e$  but retaining its endpoints:

$$G/e = (V_G, E_G \setminus \{e\}, E_G^{ext}).$$

In general, it is not a union of Feynman graphs since momentum conservation may not hold on each of its connected components.

One sometimes encounters the following variant of the previous notion of graph-quotient. It will be denoted by a double slash to distinguish it from the ordinary quotient. For an edge-subgraph  $\gamma$ , let  $G//\gamma$  be the empty graph if  $h_\gamma > 0$  and

$$G//\gamma = G/\gamma$$

if  $\gamma$  is a forest. In the case of a single edge  $e$ ,  $G/e$  is empty whenever  $e$  is a tadpole.

It follows from Euler's formula that  $h_G = h_\gamma + h_{G/\gamma}$  for any edge-subgraph  $\gamma \subset G$  (which is not necessarily connected).

**Lemma 2.5.** (*Contraction-deletion*) Let  $G$  be connected and  $e \in E_G$ . Then

$$\Psi_G = \Psi_{G \setminus e}^0 \alpha_e + \Psi_{G//e},$$

$$\Phi_G(q) = \Phi_{G \setminus e}^0(q) \alpha_e + \Phi_{G//e}(q),$$

where  $\Psi_{G \setminus e}^0$  is given by the right hand side of Eq 1: it is  $\Psi_{G \setminus e}$  if  $G \setminus e$  is connected and 0 otherwise. Likewise  $\Phi_{G \setminus e}^0(q)$  is given by the right-hand side of Eq 2: it equals to  $\Phi_{G \setminus e}(q)$  if  $G \setminus e$  is connected and equals to  $\Psi_{G_1} \Psi_{G_2} (q^{G_1})^2 = \Psi_{G_1} \Psi_{G_2} (q^{G_2})^2$  if  $G \setminus e$  has two connected components  $G_1, G_2$ .

*Proof.* Let  $T$  be a spanning  $k$ -tree of  $G$ . The edge  $e$  is not an edge of  $T$  if and only if  $T$  is a spanning  $k$ -tree of  $G \setminus e$ . By the definition of graph polynomials, this gives rise to the first terms in the right-hand side of above equations in the lemma. Note that if  $e$  is a tadpole, this is the only case which can occur. Now suppose that  $e$  is not a tadpole. If  $e$  is an edge of  $T$ , the  $T/e$  is a spanning  $k$ -tree of  $G \setminus e$ . Conversely, if  $T'$  is a spanning  $k$ -tree of  $G/e$ , then there is a unique component of  $T'$  which meets the vertex in  $G/e$ . It follows that the inverse image of  $T'$  in  $G$  with the edge  $e$ , is a spanning  $k$ -tree in  $G$ . This establishes a bijection between the set of spanning  $k$ -trees in  $T$  which contain  $e$  and those  $G/e$ . The rest just follows from the definition of graph polynomials.  $\square$