

Homework Notes: I did not work with anyone else on this homework or refer to resources other than the course notes, textbook, and course Piazza page.

Problem 1

A Figure 1 shows the distribution of eigenvalues for each matrix covariance matrix of X with different values of ψ (X_i uses ψ_i). All of the distributions are right-skewed, but the mean of the eigenvalues increases and the variance decreases as the amount of noise (ψ) in the original matrix increases. The eigenvalues were normalized using the ℓ^2 norm.

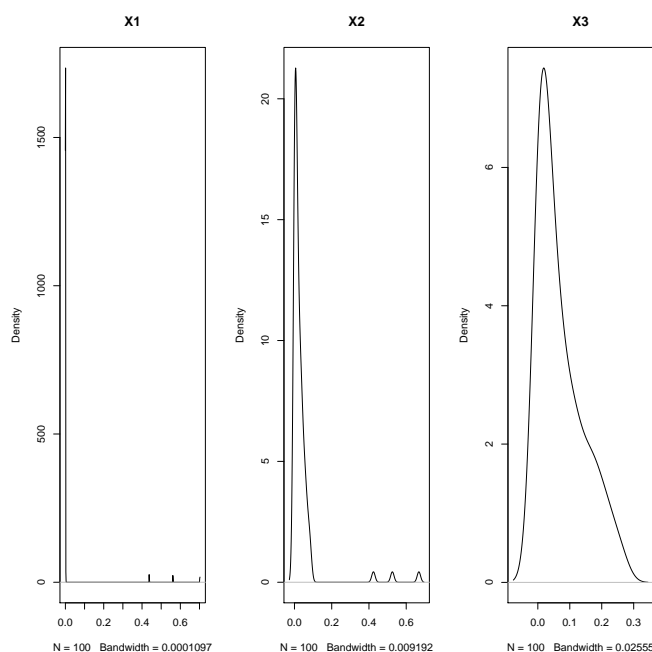


Figure 1: Distribution of Normalized Eigenvalues for Three Values of ψ

B Table 1 presents the root mean squared error (RMSE) between the covariances of the X matrices and the matrix reconstructions using the first three eigenvectors (and eigen values). Overall, the eigenvectors do a good job of recapitulating the original data matrices. Those with less noise (small ψ) do a better job (lower RMSE) than those with more noise.

C When we reconstruct the matrices we are able to obtain an estimate of the covariance of X , subject to some noise. This could be useful for identifying the number of

Table 1: RMSE between $\text{Cov}(\mathbf{X})$ and Matrix Reconstructions

ψ	RMSE
0.2	0.0054
2	0.553
10	13.029

components that could be used in our analysis, as long as we assume that the level of noise is relatively low.