

Homework Notes: I did not work with anyone else on this homework or refer to resources other than the course notes, textbook, and course Piazza page.

Problem 1

A Figure 1 shows the eigenvalues for each matrix X with different values of ψ (X_i uses ψ_i). All of the distributions are similarly skewed, but the mean and variance of the eigenvalues increase as the amount of noise (ψ) in the original matrix increases.

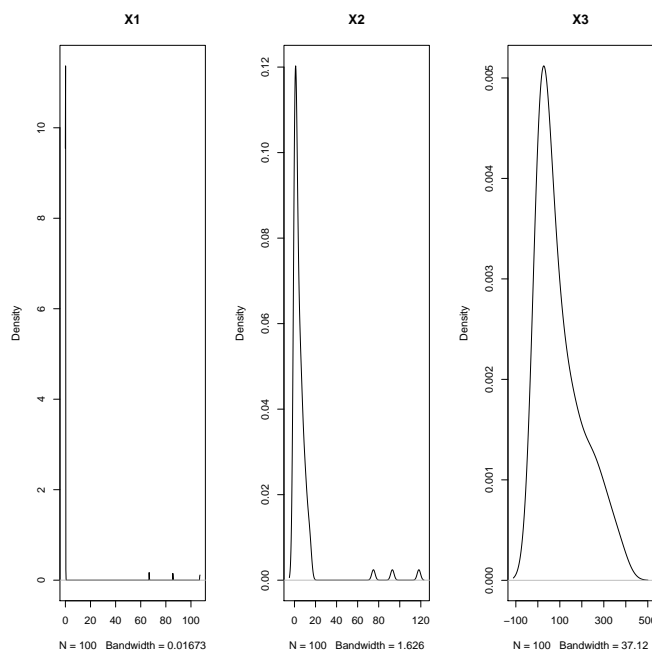


Figure 1: Distribution of Eigenvalues for Three Values of ψ

B Table 1 presents the root mean squared error (RMSE) between the covariances of the X matrices and the matrix reconstructions using the first three eigenvectors (and eigen values). Overall, the eigenvectors do a good job of recapitulating the original data matrices. Those with less noise (small ψ) do a better job (lower RMSE) than those with more noise.

C When we reconstruct the matrices we are able to obtain an estimate of the covariance of X , subject to some noise. This could be useful for identifying the number of components that could be used in our analysis, as long as we assume that the level of noise is relatively low.

Table 1: RMSE between $\text{Cov}(X)$ and Matrix Reconstructions

ψ	RMSE
0.2	0.0054
2	0.553
10	13.029