SAÉ3.02

Developer documentation

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1 Introduction

This document is the developer documentation for the remote control program made for the SAÉ3.04.

2 Server

The server consists of two Python files, main.py which contains the main server class and action.py which is used to obtain information about the machine and execute commands.

2.1 Server class

The server is implemented using a Python class and is relatively simple, as it only accepts one client at a time.

```
class Server:
def __init__(self, host: tuple):
self.host = host
self.killed = False
```

Listing 1: Server constructor

The server class only takes a tuple (host, port) as an argument. It does not connect automatically, instead the start() method has to be used, this allows for a "clean" shutdown of the server if we except for a KeyboardInterrupt.

```
if __name__ == "__main__":
    server = Server((host, port))

try:
    server.start()

except KeyboardInterrupt:
    logging.info("KeyboardInterrupt: killing server...")
server.kill()
```

Listing 2: Starting the server

Once the **start()** method is called, the server creates the socket, listens on the specified port. Once a client is connected, it will wait for incoming messages.

```
def start(self):
        while not self.killed:
2
            self.server = socket.socket()
3
            # While True loop
            self.__bind(self.host)
            self.server.listen(1)
            message = ""
            while not self.killed and message != "reset":
                self.client, addr = self.server.accept()
                message = "" # reset so we can reconnect
10
                while (
11
                    not self.killed and message != "reset" and message != "disconnect"
12
                ):
                    # Here we wait for a message
14
                    self.__handle(message, addr)
15
                # Close connection to client
16
            # Close the server
17
        # Kill the process
```

Listing 3: start() method simplified

The server will try to indefinitely bind itself to the specified port (at line 5 in Listing 3), this is done to ensure that the server can rebind to the port after a reset.

Once a message is received it is sent to the __handle(message, addr) (line 15), this method serves no purposes other than code readability and maintainability. This is where new features would be added.

```
def __handle(self, message: str, addr: tuple):
       if message == "kill":
2
           logging.info(f"Kill requested by {addr}...")
3
           self.killed = True  # avoid adding a condition to while loops
       elif message == "reset":
5
           logging.info(f"Client at {addr} requested a reset.")
       elif message == "info":
           self.client.send(("info" + json.dumps(actions.get_all())).encode())
       elif message[:7] == "command":
           command = json.loads(message[7:])
           rep = "cmmd"
11
           if command["shell"] == "dos":
                if sys.platform == "win32":
13
                    rep += actions.send_command(command["com"], "dos")
14
15
                    rep += "Cannot execute a DOS command on this operating system."
16
            # ... More elif to handle other OSs
17
           self.client.send(rep.encode())
18
```

Listing 4: Handle method simplified

The first two conditions do not do much except print a log in the console. However, if the server receive "info" from a client, it replies with a JSON encoded dict object containing information about the machine (the info is gathered using action.py).

If a message starts with the word "command", the server will try executing the given command if the shell selected by the user is available and send the output back to the client.

3 Client