



NHD-0216K1Z-NSB-FBW-L

Character Liquid Crystal Display Module

NHD-**Newhaven Display** 0216-2 Lines x 16 Characters

K1Z-Model

Transmissive

SB-Side Blue LED Backlight

F-**FSTN Negative** B-6:00 Optimal View W-Wide Temperature L-Low Power 20mA

RoHS Compliant

Newhaven Display International, Inc.

2661 Galvin Ct. Elgin IL, 60124

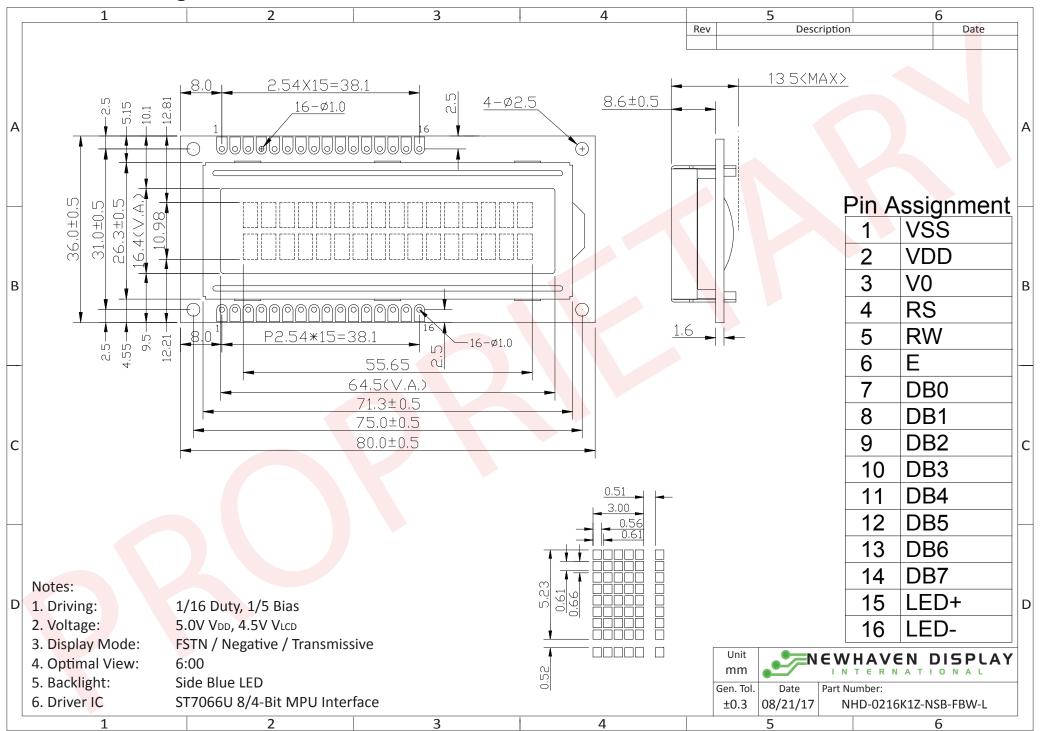
Ph: 847-844-8795 Fax: 847-844-8796 **Document Revision History**

| Revision | Date | Description | Changed by |
|----------|------------|---|------------|
| 0 | 10/5/2007 | Initial Release | - |
| 1 | 12/11/2009 | User Guide Reformat | BE |
| 2 | 12/16/2009 | Mechanical drawing updated | BE |
| 3 | 1/7/2010 | Optical revised | BE |
| 4 | 1/6/2011 | Alternate controller information updated | AK |
| 5 | 5/2/2011 | Electrical characteristics updated | AK |
| 6 | 9/20/16 | Mechanical Drawing, Electrical & Optical Char. Updated | SB |
| 7 | 8/21/17 | Mechanical Drawing & Electrical Characteristics Updated | SB |

Functions and Features

- 2 lines x 16 characters
- Built-in controller (ST7066U)
- +5.0V Power Supply
- 1/16 duty, 1/5 bias
- RoHS compliant

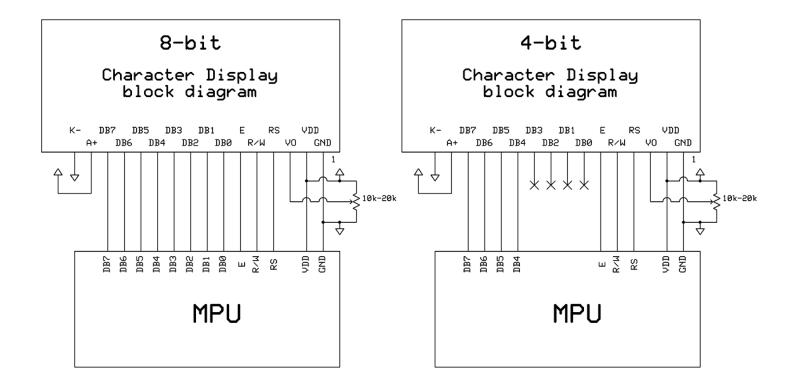
Mechanical Drawing



Pin Description and Wiring Diagram

| Pin No. | Symbol | External Connection | Function Description |
|---------|-----------|----------------------------|---|
| 1 | V_{SS} | Power Supply | Ground |
| 2 | V_{DD} | Power Supply | Supply Voltage for Logic (+5.0V) |
| 3 | V_0 | Adj. Power Supply | Supply Voltage for Contrast (approx. 0.5V) |
| 4 | RS | MPU | Register Select signal. RS=0: Command, RS=1: Data |
| 5 | R/W | MPU | Read/Write select signal, R/W=1: Read R/W: =0: Write |
| 6 | Е | MPU | Operation Enable signal. Falling edge triggered. |
| 7-10 | DB0 – DB3 | MPU | Four low order bi-directional three-state data bus lines. These |
| | | | four are not used during 4-bit operation. |
| 11-14 | DB4 – DB7 | MPU | Four high order bi-directional three-state data bus lines. |
| 15 | LED+ | Power Supply | Backlight Anode (+5.0V via on-board resistor) |
| 16 | LED- | Power Supply | Backlight Cathode (Ground) |

Recommended LCD connector: 2.54mm pitch pins **Backlight connector:** --- **Mates with:** ---



Electrical Characteristics

| Item | Symbol | Condition | Min. | Тур. | Max. | Unit |
|-----------------------------|------------------|------------------------|---------------------|------|----------|------|
| Operating Temperature Range | T _{OP} | Absolute Max | -20 | - | +70 | °C |
| Storage Temperature Range | T _{ST} | Absolute Max | -30 | 1 | +80 | °C |
| Supply Voltage | V_{DD} | - | 4.8 | 5.0 | 5.2 | V |
| Supply Current | I _{DD} | $V_{DD} = 5.0V$ | 1.0 | 1.5 | 3.0 | mA |
| Supply for LCD (contrast) | V_{LCD} | T _{OP} = 25°C | 4.2 | 4.4 | 4.6 | V |
| "H" Level input | V _{IH} | - | 0.7*V _{DD} | - | V_{DD} | V |
| "L" Level input | V_{IL} | - | V_{SS} | - | 0.6 | V |
| "H" Level output | V _{OH} | - | 3.9 | - | V_{DD} | V |
| "L" Level output | V _{OL} | - | V_{SS} | - | 0.4 | V |
| | | | | | | |
| Backlight Supply Voltage | V_{LED} | - | 4.8 | 5.0 | 5.2 | V |
| Backlight Supply Current | I _{LED} | $V_{LED} = 5.0V$ | 10 | 15 | 20 | mA |

Optical Characteristics

| | lte | em | Symbol | Condition | Min. | Тур. | Max. | Unit |
|------------------------------|------|------|----------------|------------------------|------|------|------|------|
| Omtime | Тор | | φΥ+ | | - | 40 | - | 0 |
| Optimal Viewing Angles | Bot | tom | φΥ- | CR ≥ 2 | - | 60 | - | 0 |
| | Left | | θХ- | CR ≥ 2 | - | 60 | - | 0 |
| Angles | Righ | nt | θХ+ | | - | 60 | - | 0 |
| Contrast Rat | io | | CR | - | 2 | 5 | - | - |
| Dosponso T | ina | Rise | T_R | T - 25°C | - | 150 | 250 | ms |
| Response T | ime | Fall | T _F | $T_{OP} = 25^{\circ}C$ | - | 200 | 300 | ms |

Controller Information

Built-in ST7066U Controller.

Please download specification at http://www.newhavendisplay.com/app notes/ST7066U.pdf

DDRAM Address

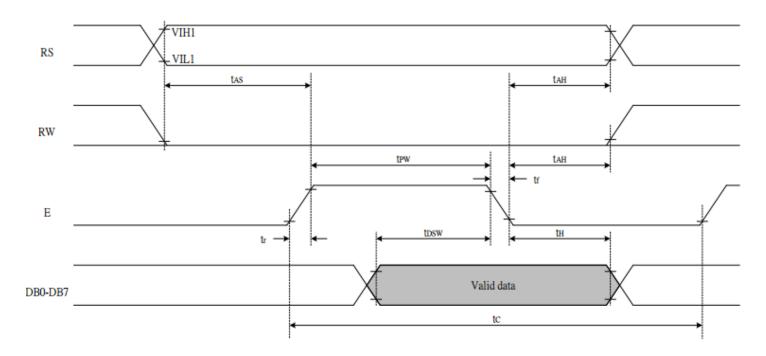
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 |
|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| 00 | 01 | 02 | 03 | 04 | 05 | 06 | 07 | 08 | 09 | 0A | OB | 0C | 0D | 0E | 0F |
| 40 | 41 | 42 | 43 | 44 | 45 | 46 | 47 | 48 | 49 | 4A | 4B | 4C | 4D | 4E | 4F |

Table of Commands

| | | | | Ins | tructi | ion co | ode | | | | | Execution |
|----------------------------------|----|-----|-----|-----|--------|--------|-----|-----|-----|-----|--|-------------------------------------|
| Instruction | RS | R/W | DB7 | DB6 | DB5 | DB4 | DB3 | DB2 | DB1 | DB0 | Description | time (f _{osc} = 270 KHZ |
| Clear Display | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | Write "20H" to DDRAM and set DDRAM address to "00H" from AC | 1.52ms |
| Return Home | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | Set DDRAM Address to "00H" from AC and return cursor to its original position if shifted. The contents of DDRAM are not changed. | 1.52ms |
| Entry mode Set | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | I/D | SH | Sets cursor move direction and specifies display shift. These parameters are performed during data write and read. | 37μs |
| Display ON/ OFF control | 0 | 0 | 0 | 0 | 0 | 0 | 1 | D | С | В | D=1: Entire display on C=1: Cursor on B=1: Blinking cursor on | 37µs |
| Cursor or Display shift | 0 | 0 | 0 | 0 | 0 | 1 | S/C | R/L | - | , | Sets cursor moving and display shift control bit, and the direction without changing DDRAM data. | 37µs |
| Function set | 0 | 0 | 0 | 0 | 1 | DL | N | F | - | ı | DL: Interface data is 8/4 bits N: Number of lines is 2/1 F: Font size is 5x11/5x8 | 37µs |
| Set CGRAM Address | 0 | 0 | 0 | 1 | AC5 | AC4 | AC3 | AC2 | AC1 | AC0 | Set CGRAM address in address counter | 37µs |
| Set DDRAM Address | 0 | 0 | 1 | AC6 | AC5 | AC4 | AC3 | AC2 | AC1 | AC0 | Set DDRAM address in address counter. | 37µs |
| Read busy Flag and Address | 0 | 1 | BF | AC6 | AC5 | AC4 | AC3 | AC2 | AC1 | AC0 | Whether during internal operation or not can be known by reading BF. The contents of address counter can also be read. | 0s |
| Write data To Address | 1 | 0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Write data into internal RAM (DDRAM/CGRAM). | 37µs |
| Read data From RAM | 1 | 1 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Read data from internal RAM (DDRAM/CGRAM). | 37µs |

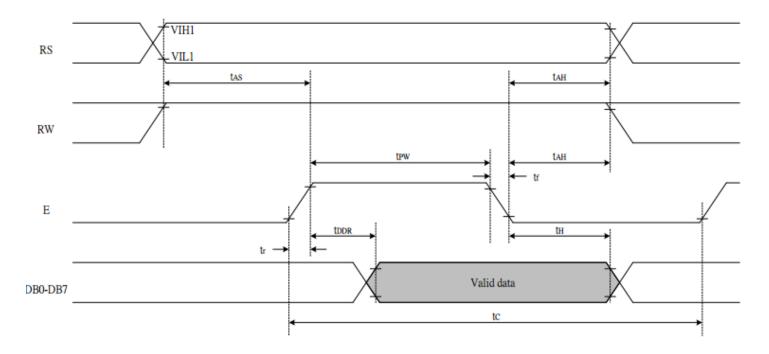
Timing Characteristics

Writing data from MPU to ST7066U



| | Write Mode (Writing data from MPU to ST7066U) | | | | | | | | | |
|------------------|---|-----------------|------|---|----|----|--|--|--|--|
| T _C | Enable Cycle Time | Pin E | 1200 | • | ı | ns | | | | |
| T _{PW} | Enable Pulse Width | Pin E | 140 | • | ı | ns | | | | |
| T_R,T_F | Enable Rise/Fall Time | Pin E | • | • | 25 | ns | | | | |
| T _{AS} | Address Setup Time | Pins: RS,RW,E | 0 | • | ı | ns | | | | |
| T _{AH} | Address Hold Time | Pins: RS,RW,E | 10 | • | 1 | ns | | | | |
| T _{DSW} | Data Setup Time | Pins: DB0 - DB7 | 40 | ı | ı | ns | | | | |
| T _H | Data Hold Time | Pins: DB0 - DB7 | 10 | ı | 1 | ns | | | | |

Reading data from ST7066U to MPU



| | Read Mode (Reading Data from ST7066U to MPU) | | | | | | | | | |
|------------------|--|-----------------|------|---|-----|----|--|--|--|--|
| Tc | Enable Cycle Time | Pin E | 1200 | ı | ı | ns | | | | |
| T _{PW} | Enable Pulse Width | Pin E | 140 | ı | ı | ns | | | | |
| T_R,T_F | Enable Rise/Fall Time | Pin E | • | ı | 25 | ns | | | | |
| T _{AS} | Address Setup Time | Pins: RS,RW,E | 0 | ı | ı | ns | | | | |
| T _{AH} | Address Hold Time | Pins: RS,RW,E | 10 | ı | ı | ns | | | | |
| T _{DDR} | Data Setup Time | Pins: DB0 - DB7 | 1 | • | 100 | ns | | | | |
| T _H | Data Hold Time | Pins: DB0 - DB7 | 10 | • | - | ns | | | | |

Built-in Font Table

| b7-b4 | 0000 | 0001 | 0010 | 0011 | 0100 | 0101 | 0110 | 0111 | 1000 | 1001 | 1010 | 1011 | 1100 | 1101 | 1110 | 1111 |
|-------|------------------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|------|
| 0000 | CG RAM (1) | | | | | | | | | | | | | | | |
| 0001 | (2) | | | | | | | | | | | | | | | |
| 0010 | (3) | | | | | | | | | | | | | | | |
| 0011 | (4) | | | | | | | | | | | | | | | |
| 0100 | (5) | | | | | | | | | | | | | | | |
| 0101 | (6) | | | | | | | | | | | | | | | |
| 0110 | (7) | | | | | | | | | | | | | | | |
| 0111 | (8) | | | | | | | | | | | | | | | |
| 1000 | (1) | | | | | | | | | | | | | | | |
| 1001 | (2) | | | | | | | | | | | | | | | |
| 1010 | (3) | | | | | | | | | | | | | | | |
| 1011 | (4) | | | | | | | | | | | | | | | |
| 1100 | (5) | | | | | | | | | | | | | | | |
| 1101 | (6) | | | | | | | | | | | | | | | |
| 1110 | (7) | | | | | | | | | | | | | | | |
| 1111 | (8) | | | | | | | | | | | | | | | |

Example Initialization Program

```
8-bit Initialization:
/************************
void command(char i)
     P1 = i;
                                  //put data on output Port
     D_I = 0;
                                  //D/I=LOW : send instruction
     R_W = 0;
                                  //R/W=LOW : Write
     E = 1;
                                  //enable pulse width >= 300ns
     Delay(1);
      E = 0;
                                  //Clock enable: falling edge
void write(char i)
     P1 = i;
                                  //put data on output Port
     DI = 1;
                                 //D/I=HIGH : send data
     RW=0;
                                 //R/W=LOW : Write
     E = 1;
     Delay(1);
                                 //enable pulse width >= 300ns
     E = 0;
                                  //Clock enable: falling edge
void init()
     E = 0;
                                  //Wait >40 msec after power is applied
     Delay(100);
     command(0x30);
                                  //command 0x30 = Wake up
                               //must wait 5ms, busy flag not available
//command 0x30 = Wake up #2
//must wait 160us, busy flag not available
//command 0x30 = Wake up #3
//must wait 160us, busy flag not available
//Function set: 8-bit/2-line
//Set cursor
//Display 0x1 6
                                 //must wait 5ms, busy flag not available
     Delay(30);
     command(0x30);
     Delay(10);
     command(0x30);
     Delay(10);
     command(0x38);
     command(0x10);
                                 //Display ON; Cursor ON
     command(0x0c);
     command(0x06);
                                 //Entry mode set
```

```
4-bit Initialization:
void command(char i)
     P1 = i;
                              //put data on output Port
     DI = 0;
                              //D/I=LOW : send instruction
                              //R/W=LOW : Write
     R_W = 0;
    Nybble();
                              //Send upper 4 bits
     i = i << 4;
                              //Shift over by 4 bits
     P1 = i;
                              //put data on output Port
     Nybble();
                              //Send upper 4 bits
void write(char i)
     P1 = i;
                              //put data on output Port
    D_I = 1;
                              //D/I=HIGH : send data
    R_W = 0;
                             //R/W=LOW : Write
    Nybble();
                             //Clock upper 4 bits
     i = i << 4;
                              //Shift over by 4 bits
    P1 = i;
                              //put data on output Port
    Nybble();
                              //Clock upper 4 bits
/**********************
void Nybble()
     E = 1;
    Delay(1);
                             //enable pulse width >= 300ns
    E = 0;
                              //Clock enable: falling edge
void init()
{
     P1 = 0;
     P3 = 0;
     Delay(100);
                              //Wait >40 msec after power is applied
     P1 = 0x30;
                              //put 0x30 on the output port
     Delay(30);
                              //must wait 5ms, busy flag not available
     Nybble();
                              //command 0x30 = Wake up
     Delay(10);
                              //must wait 160us, busy flag not available
                              //command 0x30 = Wake up #2
     Nybble();
                              //must wait 160us, busy flag not available
     Delay(10);
                              //command 0x30 = Wake up #3
     Nybble();
                              //can check busy flag now instead of delay
     Delay(10);
     P1 = 0x20;
                             //put 0x20 on the output port
     Nybble();
                             //Function set: 4-bit interface
     command(0x28);
                              //Function set: 4-bit/2-line
     command(0x10);
                              //Set cursor
     command(0x0F);
                              //Display ON; Blinking cursor
     command(0x06);
                              //Entry Mode set
          *************
```

Quality Information

| Test Item | Content of Test | Test Condition | Note |
|--|---|--|------|
| High Temperature storage | Endurance test applying the high storage temperature for a long time. | +80°C , 48hrs | 2 |
| Low Temperature storage | Endurance test applying the low storage temperature for a long time. | -30°C , 48hrs | 1,2 |
| High Temperature Operation | Endurance test applying the electric stress (voltage & current) and the high thermal stress for a long time. | +70°C 48hrs | 2 |
| Low Temperature Operation | Endurance test applying the electric stress (voltage & current) and the low thermal stress for a long time. | -20°C , 48hrs | 1,2 |
| High Temperature / Humidity Operation | Endurance test applying the electric stress (voltage & current) and the high thermal with high humidity stress for a long time. | +40°C, 90% RH, 48hrs | 1,2 |
| Thermal Shock resistance | Endurance test applying the electric stress (voltage & current) during a cycle of low and high thermal stress. | 0°C,30min -> 25°C,5min -> 50°C,30min = 1 cycle 10 cycles | |
| Vibration test | Endurance test applying vibration to simulate transportation and use. | 10-55Hz , 15mm amplitude. 60 sec in each of 3 directions X,Y,Z For 15 minutes | 3 |
| Static electricity test | Endurance test applying electric static discharge. | VS=800V, RS=1.5k Ω , CS=100pF One time | |

Note 1: No condensation to be observed.

Note 2: Conducted after 4 hours of storage at 25°C, 0%RH.

Note 3: Test performed on product itself, not inside a container.

Precautions for using LCDs/LCMs

See Precautions at www.newhavendisplay.com/specs/precautions.pdf

Warranty Information and Terms & Conditions

http://www.newhavendisplay.com/index.php?main_page=terms

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