Part 1 — Poles and zeros

clear

1ab. Roots

Calculate the roots of each of the following polynomials

```
P_1 = s^6 + s^5 + 2 s^4 + 8 s^3 + 7 s^2 + 15 s + 12
P_2 = s^6 + s^5 + 4 s^4 + 3 s^3 + 7 s^2 + 15 s + 18
```

The roots for each polynomial are

```
% display the roots in two tables showing both forms
P1_roots_Cartesian = complexTable(P_roots{1})
```

P1_roots_Cartesian = 6×3 table

	CartesianForm	r	thetaDeg
1	0.9979 + 1.6070i	1.8916	58.1624
2	0.9979 - 1.6070i	1.8916	301.8376
3	-1.8615 + 0.0000i	1.8615	180
4	-0.1302 + 1.4299i	1.4358	95.2009
5	-0.1302 - 1.4299i	1.4358	264.7991
6	-0.8739 + 0.0000i	0.8739	180

P2_roots_Cartesian = complexTable(P_roots{2})

P2_roots_Cartesian = 6×3 table

	CartesianForm	r	thetaDeg
1	1.0375 + 1.3227i	1.6811	51.8922
2	1.0375 - 1.3227i	1.6811	308.1078
3	-0.4632 + 1.9333i	1.9880	103.4723
4	-0.4632 - 1.9333i	1.9880	256.5277
5	-1.0743 + 0.6764i	1.2695	147.8047
6	-1.0743 - 0.6764i	1.2695	212.1953

2. Polynomial form

Calculate the polynomial form and roots of

```
% the polynomial
P3_poly = poly(-[5 2 3 -1 -2 4]);

% display factored out in terms of s
syms P3 s
disp(P3 == prod(factor(poly2sym(P3_poly, s))))
```

$$P_3 = (s-1)(s-2)(s+2)(s+3)(s+4)(s+5)$$

The polynomial form is

```
syms s
P3_s = poly2sym(P3_poly, s)
```

P3 s =
$$s^6 + 11 s^5 + 31 s^4 - 31 s^3 - 200 s^2 - 52 s + 240$$

The roots of the polynomial are

```
P3_roots = roots(P3_poly)
```

```
P3\_roots = 6 \times 1
```

- -5.0000
- -4.0000
- -3.0000
- -2.0000
- 2.0000
- 1.0000

3a. Converting to polynomial numerator and denominator.

Represent

```
% the transfer function in zero-pole-gain form
```

```
G1 = zpk(-[2 3 -6 8], -[0 7 -2 10 -3], 9)
```

```
G1 =

9 (s+2) (s+3) (s+8) (s-6)

-----

s (s+7) (s+10) (s-3) (s-2)
```

Continuous-time zero/pole/gain model.

using polynomials in the numerator and denominator.

In polynomial numerator and denominator, the transfer function

3b. Converting to zero-pole-gain form.

Represent

```
% the transfer function in polynomial numerator and denominator form G2 = tf([1\ 17\ 99\ 223\ 140], [1\ 32\ 363\ 2092\ 5052\ 4320])
```

```
G2 =

s^4 + 17 s^3 + 99 s^2 + 223 s + 140

s^5 + 32 s^4 + 363 s^3 + 2092 s^2 + 5052 s + 4320
```

Continuous-time transfer function.

using factored forms of the polynomials in the numerator and denominator.

In zero-pole-gain form, the transfer function

```
G2_zpk = zpk(G2)
```

```
G2_zpk =

(s+7) (s+5) (s+4) (s+1)

(s+16.79) (s^2 + 4.097s + 4.468) (s^2 + 11.12s + 57.6)
```

Continuous-time zero/pole/gain model.

4abc. Partial fraction expansion

Calculate the partial fraction expansion of each of the following transfer functions.

$$G_3 = \frac{5(s+2)}{s(s^2+8s+15)}, \ G_4 = \frac{5(s+2)}{s(s^2+6s+9)}, \ G_5 = \frac{5(s+2)}{s(s^2+6s+34)},$$

which have the zero-pole-gain forms

```
% allocate G polynomials
% 2 factors per line
%
  3-nominal max for each factor
  2 lines for numerator and denominator
% 5 functions (first 2 unused)
G_{roots} = zeros(2, 3, 2, 5);
% get the size of G
[nFactors, nRootTerms, ~, nTfs] = size(G_roots);
% G3
G_{roots}(:, :, :, 3) = cat(3, [0 0 5; 0 1 2], [0 1 0; 1 8 15]);
G_{roots}(:, :, :, 4) = cat(3, [0 0 5; 0 1 2], [0 1 0; 1 6 9]);
% G5
G_{roots}(:, :, :, 5) = cat(3, [0 0 5; 0 1 2], [0 1 0; 1 6 34]);
% convolve the factors in each line giving G_poly:
\% * the resulting length of convolution for operands of length (M + 1),
% (N + 1)  is (M + N + 1), so C convolutions of N-vectors each will give
% a length of C(N - 1) + 1
nPolyTerms = (((nRootTerms - 1)*nFactors) + 1);
% allocate
G poly = zeros(nPolyTerms, 2, nTfs);
% loop through the transfer functions (skip first 2)
for (iTf=3:nTfs)
    for (iLine=1:2)
        G poly(:, iLine, iTf) = convRows(G roots(:, :, iLine, iTf));
    end % next iLine
end % next iTf
% print the polynominal forms of each transfer function:
% allocate room for the transfer functions
G = cell(1, nTfs);
% loop through the transfer functions
for iTf=3:nTfs
    G\{iTf\} = zpk(tf(G poly(:, 1, iTf)', G poly(:, 2, iTf)'));
end % next iTf
% print each one
G3 = G\{3\}
```

```
G3 =

5 (s+2)

5 (s+5) (s+3)

Continuous-time zero/pole/gain model.
```

```
G4 = G{4}

G4 = 

5 (s+2)

-----

5 (s+3)^2
```

```
G5 = G\{5\}
```

```
G5 =

5 (s+2)

5 (s^2 + 6s + 34)

Continuous-time zero/pole/gain model.
```

Continuous-time zero/pole/gain model.

The partial fraction expansions are

```
% an (n + 1)-nomial will have n roots.
nPolesPred = (nPolyTerms - 1);
% allocate R (coefficients), P (poles), K (direct term)
RP = zeros(nPolesPred, 2, nTfs);
% all the transfer functions have degree 1-(1+2) = -2,
% so expect no direct function
K = zeros(0, nTfs);
% loop through the transfer functions
for iTf=3:nTfs
    % the #roots predicted may be more than necessary
    [G345_R, G345_P, G345_K] = ...
        residue(G_poly(:, 1, iTf), G_poly(:, 2, iTf));
    % so 0-pad R, P, K
    nPolesActual = numel(G345 P);
    G345_R = [ zeros((nPolesPred - nPolesActual), 1); G345_R ];
    G345_P = [ zeros((nPolesPred - nPolesActual), 1); G345_P ];
    % collect the residue
    RP(:, 1, iTf) = G345_R;
    RP(:, 2, iTf) = G345_P;
    K(:, iTf) = G345_K;
end % next iTf
```

Well, we see that each of their residues (column #1), poles (column #2 in RP matrix), and their direct functions (K)

```
% copy R, P, K for each function, filtering out zero rows
% (for future use)
G3_RP = RP((RP(:,1,3) \sim 0), :, 3)
G3_RP = 3 \times 2
   -1.5000
            -5.0000
            -3.0000
    0.8333
    0.6667
                  0
G3_K = K(:, 3)
G3_K =
  0×1 empty double column vector
G4_{RP} = RP((RP(:,1,4) \sim 0), :, 4)
G4 RP = 3 \times 2
   -1.1111
            -3.0000
    1.6667
            -3.0000
    1.1111
G4_K = K(:, 4)
G4_K =
  0×1 empty double column vector
G5_{RP} = RP((RP(:,1,5) \sim 0), :, 5)
G5 RP = 3 \times 2 complex
  -0.1471 - 0.4118i -3.0000 + 5.0000i
  -0.1471 + 0.4118i -3.0000 - 5.0000i
   0.2941 + 0.0000i 0.0000 + 0.0000i
G5_K = K(:, 5)
G5_K =
```

Thus the partial fraction expansions

0×1 empty double column vector

```
% cause syntax error if misspelled
OMITNAN = 'omitnan';

% allocate room for the transfer functions
syms G_partial [1 nTfs]
% in terms of s
syms s
% loop through the transfer functions
for iTf=3:nTfs
    % filter out zero rows
```

```
Tf_RP = RP((RP(:,1,iTf) \sim 0), :, iTf);
    % get the poles
    Tf poles = Tf RP(:, 2);
    % loop through remaining rows
    nTf_RP = numel(Tf_poles);
    % initialize to 0
    G partial(iTf) = 0;
    % loop through the residue-pole rows
    for iRP = 1:nTf RP
         % count the number of repeats so far for this pole (including
         % this one):
         % * poles are ordered so that an increase in previous instances
         % means an increase in order of the current instance
         nInstances = (sum(Tf_poles(1:iRP) == Tf_poles(iRP)));
         % add the fraction to G_partial: R/(s - P)^n
         G partial(iTf) = (G partial(iTf) + (Tf RP(iRP,1)./(s - Tf poles(iRP))^nInstances));
    end % next iRP
    % add all of the direct terms
    G partial(iTf) = G partial(iTf) + sum(K(:, iTf));
end % next iTf
% print each one
G3_partial = G_partial(3)
G3_partial =
\frac{5}{6(s+3)} - \frac{3}{2(s+5)} + \frac{2}{3s}
G4 partial = G partial(4)
G4 partial =
\frac{5}{3(s+3)^2} - \frac{10}{9(s+3)} + \frac{10}{9s}
G5_partial = G_partial(5)
G5 partial =
\frac{5}{17s} + \frac{-\frac{5}{34} - \frac{7}{17}i}{s+3-5i} + \frac{-\frac{5}{34} + \frac{7}{17}i}{s+3+5i}
```

```
function complexTable = complexTable(complex)
```

complexTable(complex)

Creates a table showing the Cartesian forms, magnitudes and angles (in [0, 360) [deg]) of the given complex numbers.

Input Arguments

complex: double = vector of complex numbers

Output Arguments

complexTable: table (3-columns) = the table of the Cartesian forms, magnitudes and angles (in [0, 360) [deg]) of each complex numbers

```
CartesianForm = complex;
    r = abs(complex);
    thetaDeg = angle360(complex);
    complexTable = table(CartesianForm, r, thetaDeg);
end % function complexTable(complex)
function angle360 = angle360(vector)
```

angle360(vector)

Gets an angle from a vector of complex numbers in the domain of [0, 360) [deg].

Input Arguments

vector: double = representing the vector of complex numbers

Output Arguments

acc: the vector of arrays in the domain of [0, 360) [deg

```
angle360 = mod(rad2deg(angle(vector)) + 360, 360);
end % function angle360(vector)

function acc = convRows(matrix)
```

conv_rows(matrix)

Convolves the rows of a matrix into a row vector.

Input Arguments

T: double = 2D array whose rose to convolve

Output Arguments

acc: the resulting convolved row vector

```
% initialize
acc = 1;
% transpose to loop the matrix by row
% because Matlab defaults to by column
```