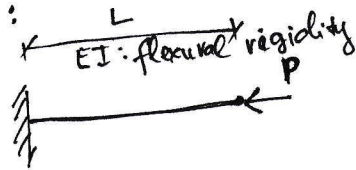


TOPIC 1. BUCKLING OF BEAMS

1. Definition:

- Buckling is instability that leads to a failure mode
- It happens when the structure or elements are subjected to a compressive load or stress, especially when the structure has slender members such as a beam

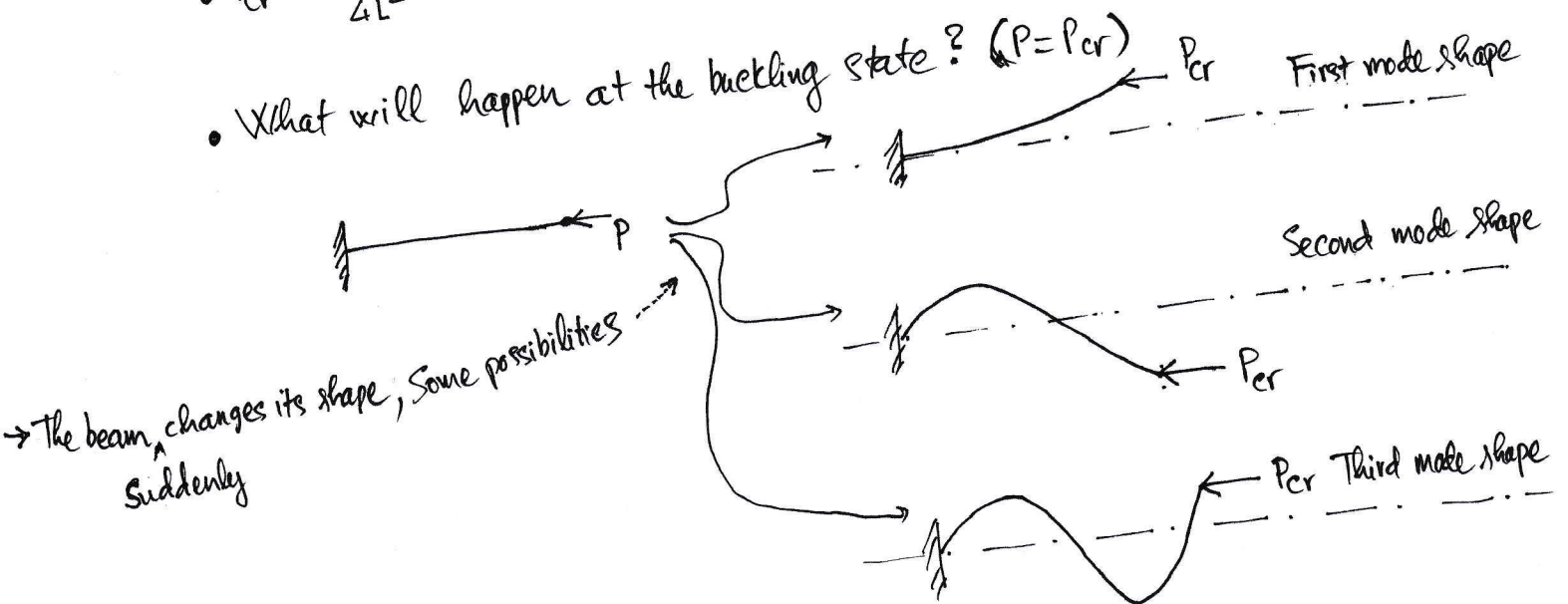
2. Phenomenon description:



- Assume that the axial rigidity of the beam (EA) is infinitely large, so the beam does not undergo any stretching
- Increase P continuously until $P = P_{cr}$: buckling phenomenon occurs

- $P_{cr} = \frac{\pi^2 EI}{4L^2}$: critical buckling load $\therefore L \uparrow, P \downarrow$

- What will happen at the buckling state? ($P = P_{cr}$)



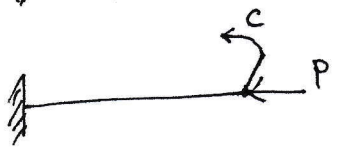
3. Target of this topic:

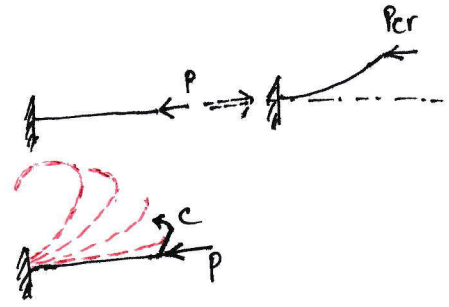
- Understand buckling phenomenon
- Can calculate P_{cr} and predict mode shape of beam or column buckling

4. End shortening due to compressive load: (Key section)

• Classify two problems:

Ⓐ  : buckling analysis

Ⓑ  : bending analysis



• Buckling analysis: increase P until $P = P_{cr}$, the beam suddenly changes its shape

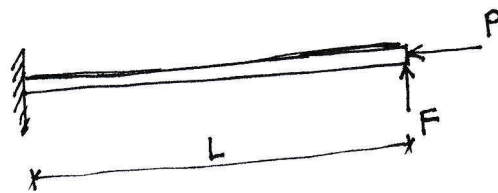
• Bending analysis: P and C ^{increase} ~~are constants~~, the beam continuously changes its shape right after applying the load.

• Problem A (buckling analysis) is a special case of problem B when $C = 0$

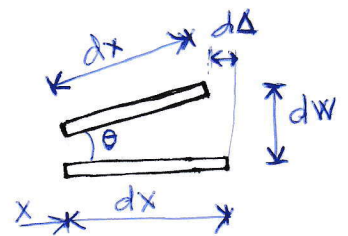
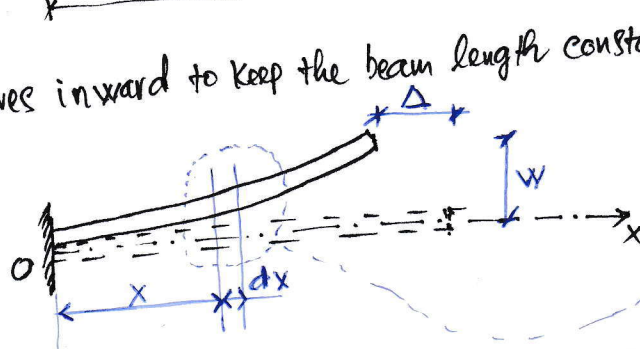
⇒ we establish formulation of problem B, when vertical forces are zeros we can obtain formulation of problem A.

• Now, we calculate end shortening of beam/column:

⊕ Assume: the beam does not undergo any stretching due to high axial rigidity



Under P and F , the tip moves inward to keep the beam length constant:



deformation of
Instead of looking at whole structure
we look at the deformation of an infinitesimal
length dx

End shortening $\Delta_e = ?$
of an element

θ is rotation of element

$$dx = dx \cos \theta + d\Delta$$

$$\begin{aligned} d\Delta &= dx - dx \cos \theta \\ &= dx(1 - \cos \theta) \\ &= dx \cdot 2 \sin^2 \frac{\theta}{2} \\ &= 2dx \sin^2 \frac{\theta}{2} \end{aligned} \quad (1)$$

We use the assumption: small rotation and large deflection. Therefore:

$$\text{Rotation: } \theta \approx \sin \theta \approx \frac{dw}{dx}$$

$$\begin{aligned} \frac{\theta}{2} &\approx \sin \frac{\theta}{2} = \frac{1}{2} \cdot \frac{dw}{dx} \\ \sin^2 \frac{\theta}{2} &= \frac{1}{4} \left(\frac{dw}{dx} \right)^2 \end{aligned} \quad (2)$$

$$(2) \xrightarrow{\text{into}} (1): d\Delta = 2dx \cdot \frac{1}{4} \left(\frac{dw}{dx} \right)^2$$

$$= \frac{1}{2} \left(\frac{dw}{dx} \right)^2 dx$$

: end shortening of an infinitesimal length dx

$$\text{For whole element: } \Delta_e = \int_0^L d\Delta = \frac{1}{2} \int_0^L \left(\frac{dw}{dx} \right)^2 dx ; L: \text{length of } \text{element}$$

End shortening of ~~beam~~ ^{an element} due to compressive load:

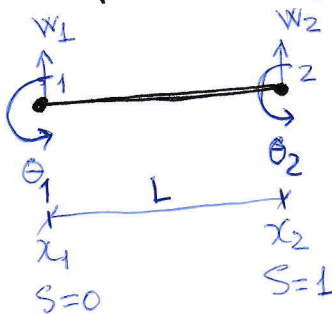
$$\Delta_e = \frac{1}{2} \int_0^L \left(\frac{dw}{dx} \right)^2 dx \quad (3)$$

Remind: Finite element interpolation using Hermite functions

$$w(s) = N_1(s)w_1 + N_2(s)\theta_1 + N_3(s)w_2 + N_4(s)\theta_2$$

$$= \begin{bmatrix} N_1 & N_2 & N_3 & N_4 \end{bmatrix} \begin{bmatrix} w_1 \\ \theta_1 \\ w_2 \\ \theta_2 \end{bmatrix}$$

$$w(s) = \mathbf{N} \mathbf{w}_e \quad (4)$$



$$s = \frac{x - x_1}{L}$$

$$L ds = dx$$

$$\frac{dw}{ds} = \begin{bmatrix} N_1' & N_2' & N_3' & N_4' \end{bmatrix} \mathbf{w}_e$$

$$= \mathbf{N}' \mathbf{w}_e \quad (5)$$

N_1, N_2, N_3, N_4 are Hermite functions of s

Interpolate and shortening Δ_e using Hermite functions :

$$\begin{aligned}
 \text{In (3)} : \Delta_e &= \frac{1}{2} \int_0^L \left(\frac{dw}{dx} \right)^2 dx \\
 &= \frac{1}{2} \int_0^1 \left(\frac{dw}{L ds} \right)^2 L ds \\
 &= \frac{1}{2} \cdot \frac{1}{L} \int_0^1 \left(\frac{dw}{ds} \right)^2 ds \\
 &= \frac{1}{2} \cdot \frac{1}{L} \int_0^1 (\mathbf{N}' \mathbf{w}_e) (\mathbf{N}' \mathbf{w}_e) ds \\
 &= \frac{1}{2} \cdot \frac{1}{L} \int_0^1 (\mathbf{w}_e^T \mathbf{N}') (\mathbf{N}' \mathbf{w}_e) ds \\
 &= \frac{1}{2} \cdot \mathbf{w}_e^T \cdot \frac{1}{L} \int_0^1 \mathbf{N}'^T \mathbf{N}' ds \cdot \mathbf{w}_e \\
 \Rightarrow \Delta_e &= \frac{1}{2} \mathbf{w}_e^T \cdot \mathbf{K}_{e,inc} \cdot \mathbf{w}_e \quad (6)
 \end{aligned}$$

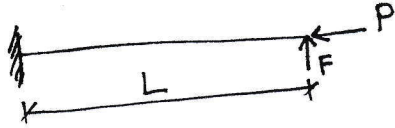
$$\begin{aligned}
 \mathbf{K}_{e,inc} &= \frac{1}{L} \int_0^1 \mathbf{N}'^T \mathbf{N}' ds \\
 &= \frac{1}{L} \int_0^1 \begin{bmatrix} N'_1 \\ N'_2 \\ N'_3 \\ N'_4 \end{bmatrix} \begin{bmatrix} N'_1 & N'_2 & N'_3 & N'_4 \end{bmatrix} ds \quad (7)
 \end{aligned}$$

Homework 1: Calculate all elements of $\mathbf{K}_{e,inc}$ (perform 16 integrations)

Result:

$$\mathbf{K}_{e,inc} = \frac{1}{30L} \begin{bmatrix} 36 & 3L & -36 & 3L \\ 3L & 4L^2 & -3L & -L^2 \\ -36 & -3L & 36 & -3L \\ 3L & -L^2 & -3L & 4L^2 \end{bmatrix}$$

- Calculate energies:
 - Strain energy: U
 - External work done by F : W
 - External work done by P : V



External work of element done by P

$$\begin{aligned}
 V_e &= P_e \cdot \Delta_e \\
 &= P_e \cdot \frac{1}{2} \mathbf{w}_e^T \mathbf{K}_{e,inc} \mathbf{w}_e \\
 &= \frac{P_e}{P_{cr}} \cdot P_{cr} \cdot \frac{1}{2} \mathbf{w}_e^T \mathbf{K}_{e,inc} \mathbf{w}_e ; P_{cr}: \text{critical buckling load} \\
 V_e &= P_{cr} \cdot \frac{1}{2} \mathbf{w}_e^T \frac{P_e}{P_{cr}} \mathbf{K}_{e,inc} \mathbf{w}_e
 \end{aligned}$$

Assemble elements:

$$V = \sum_{e=1}^N V_e = \sum_{e=1}^N P_{cr} \cdot \frac{1}{2} \mathbf{w}_e^T \frac{P_e}{P_{cr}} \mathbf{K}_{e,inc} \mathbf{w}_e$$

$$V = \frac{1}{2} P_{cr} \cdot \mathbf{w}^T \mathbf{K}_{inc} \mathbf{w}$$

$$\mathbf{K}_{inc} = \sum \frac{P_e}{P_{cr}} \cdot \mathbf{K}_{e,inc}$$

Total strain potential energy of an element:

$$\Pi = U - W - V$$

$$\Pi = \frac{1}{2} \mathbf{w}^T \mathbf{K} \mathbf{w} - \mathbf{w}^T \mathbf{f} - \frac{1}{2} \mathbf{w}^T P_{cr} \mathbf{K}_{inc} \mathbf{w}$$

FEM solutions are obtained when Lagrange principle is satisfied: (compressive)

$$\frac{\partial \Pi}{\partial \mathbf{w}} = 0 \Leftrightarrow (\mathbf{K} - P_{cr} \mathbf{K}_{inc}) \mathbf{w} = \mathbf{f} : \text{for } \begin{array}{c} \text{vertical and axial loads} \\ \text{P} \\ \text{F} \end{array}$$

if P is tensile load: $(\mathbf{K} + P_{cr} \mathbf{K}_{inc}) \mathbf{w} = \mathbf{f}$

if $F=0$ (no vertical load): $(\mathbf{K} - P_{cr} \mathbf{K}_{inc}) \mathbf{w} = 0$: buckling analysis $\left\{ \begin{array}{l} \text{critical buckling load} \\ \text{mode shapes} \end{array} \right.$

if $P=0$: $\mathbf{K} \mathbf{w} = \mathbf{f}$