MAS 4

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No Group

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```
[34]: import pandas as pd
  import numpy as np
  from scipy.stats import pearsonr as r
  import matplotlib.pyplot as plt
  from scipy.stats import norm, uniform
  %config InlineBackend.figure_format = 'retina'
  plt.rcParams["figure.dpi"] = 93
  plt.rcParams["figure.figsize"] = (12,7)
  plt.style.use("default")
```

0.0.1 4.1.1

For i.i.d sample $X_1, X_2, \dots, X_n \sim N(0, 1)$ with pdf f we have

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

with

$$E[\bar{X}_n] = \mu = 0$$

and

$$Var[\bar{X}_n] = \frac{\sigma^2}{n} = \frac{1}{n}$$

For $g(x) = \cos^2(x)$ the MC-estimate with samples drawn from f is

$$E[g(X)] \approx \widetilde{g_n}(x) = \frac{1}{n} \sum_{i=1}^n g(x_i)$$

However, the MC-estimator is a random variable itself:

$$\widetilde{g_n}(X) \sim N(\mu, \frac{\sigma^2}{n})$$

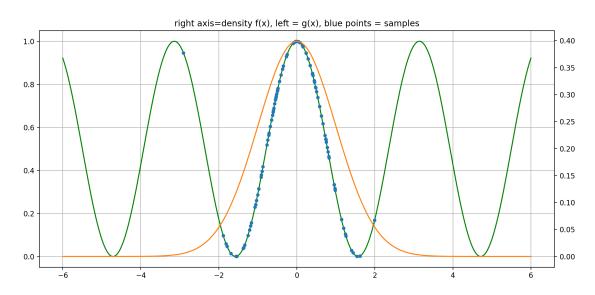
The uncertainty of the MC-estimator is given by its variance:

$$\operatorname{Var}(\widetilde{g_n}(X)) = \operatorname{Var}[E[g(X)]] \approx \frac{\sigma^2}{n}$$

```
[2]: # Define function
def g(x): return np.cos(x)**2
# Instantiate density
N = norm(0, np.sqrt(1))
```

```
[37]: ax = func.plot(color="green",figsize=(13,6))
sim.plot(ax=ax, style=".",ms=7.73)
pdf_x.plot(ax=ax, secondary_y=True,grid=True,title="right axis=density f(x),
→left = g(x), blue points = samples")
```

[37]: <AxesSubplot:label='be37b585-0741-4cc6-9e12-66495072af7c'>



```
[21]: sim.mean(), sim.var()
```

[21]: (0.5642320564431826, 0.11467367026497269)

The blue dots represent samples $g(X_i)$. The orange line is the original density and the green line is g(x). The chart shows nicely why the MC-estimate is sharp for large values of n.

The simulation reveals E[g(x)] = 0.56. The estimate has a variance of Var[g(x)] = 0.12.

A better way of estimating uncertainty is to look at the variance of the *estimator* and not the variance of the *estimate*.

Repeating the experiment 50 times (n = 100 each) yields the distribution of the MC-estimator, with

$$E[E[g(x)]] = 0.5675 = E[g(x)] = 0.56 \approx \mu Var[E[g(x)]] = 0.0012 = \frac{Var[g(x)]}{n} = \frac{0.12}{100} \approx \frac{\sigma^2}{n}$$

```
[28]: sims.mean(), sims.var() # For 50 simulation with n=100 each [MC-ESTIMATOR DIST]
```

[28]: (0.5595546837689471, 0.000924285604112229)

```
[29]: sim.mean(), sim.var() # Single simulation with n=100 [ESTIMATE DIST]
```

[29]: (0.5642320564431826, 0.11467367026497269)

```
[30]: # CLT Induce, blue: VAR[g(x)], orange: AVG[g(x)]

ax = pd.Series([pd.Series([g(np.random.normal(0,1)) for _ in range(1000)]).

→var() for _ in range(100)]).plot.density()

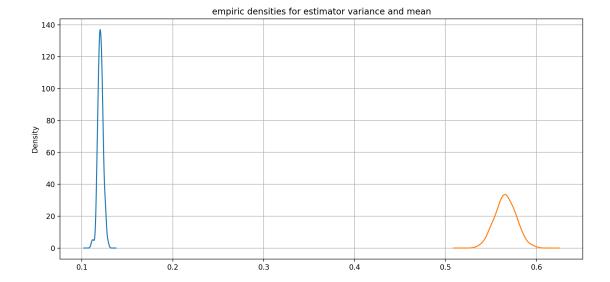
pd.Series([pd.Series([g(np.random.normal(0,1)) for _ in range(1000)]).mean()

→for _ in range(100)]).plot.density(ax=ax,

grid=True,figsize=(13,6),

title="empiric densities for estimator

→variance and mean")
```



$0.0.2 \quad 4.1.2$

For the plain vanilla p-test we have df = 10 - 2 = 8 and critical values of -0.632 and 0.632, which translates to insignificant values for $r \in [-0.632, 0.632]$ and therefore also for r = 0.3. Note that p-values are never useful other than for synthetic data where the assumptions of the significance test are met.

Using MC, we can setup a simulation to evaluate how random the found result might be, without assuming the shapes of f_S and f_A .

Let
$$A \leftarrow [a_1, a_2, ..., a_{10}]$$
 and $S \leftarrow [s_1, s_2, ..., s_{10}]$ with linear correlation $r(A, S)$

Now to check if r(A, S) is non-random (i.e significant), simulate the initial experiment n times to obtain N different values for r(A, S), where in each of the N simulations, S (or both A and S) is permuted $(s_i^t \neq s_i^{t+1})$.

Now after obtaining N values $(r_1, r_2, ..., r_N)$, for a one-tailed test sort the correlations, for a two tailed test sort the absolute correlations. The result is a sorted set R indexed i. Now the c CI level corresponds to the $N \times c$ -th element of R, which is $r_{N \times c}$, e.g, r_{990} for N = 1000 and c = .99.

0.0.3 4.2.1

Let $\varphi(X) = X^2$ and $X \sim N(0,1)$ with density f and $g \sim U(-5,5)$ with density g. Then

$$E_f[\varphi(X)] = E_g\left[\varphi(X)\frac{f(X)}{g(X)}\right] \approx \frac{1}{n}\sum_{i=1}^n \varphi\left(X_i\right)\frac{f\left(X_i\right)}{g\left(X_i\right)}$$

where X_i is drawn from g.

First of all, $g(X_i)$ will never be 0, while $f(X_i)$ gets very close to zero for unlikeli values, especially if $|X_i| > 1.96$.

In particular, any X_i drawn from U yields $g(X_i) = \frac{1}{10}$. Therefore likelihood ratio can be simplified

$$\frac{f\left(X_{i}\right)}{g\left(X_{i}\right)} \leftarrow f\left(X_{i}\right) \times 10$$

Therefore I predict the following estimate.

$$E_f[\varphi(X)] \approx \frac{1}{n} \sum_{i=1}^n 10\varphi(X_i) f(X_i)$$

and

$$VAR_f[\varphi(X)] \approx \frac{1}{n} \sum_{i=1}^{n} [10\varphi(X_i) f(X_i) - E_f[\varphi(X)]]^2$$

And subsequently the *estimator*

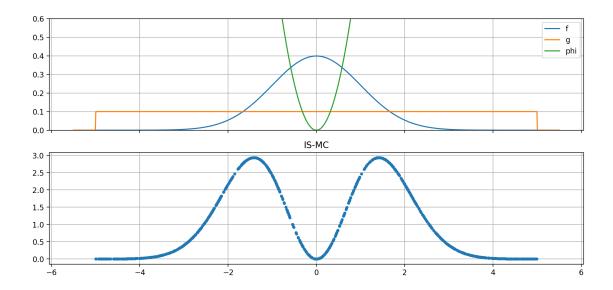
$$E[E_f[\varphi(X)]] = \mu Var[E_f[\varphi(X)]] = \frac{\sigma^2}{n}$$

```
[39]: # Instanciate densities
N = norm(0, np.sqrt(1))
U = uniform(loc=-5, scale=10)
```

```
[40]: n_draws = 1000
draws = pd.Series(U.rvs(n_draws))
sim = pd.Series([(xi**2)*10*N.pdf(xi) for xi in draws],index=draws)
sim.mean(), sim.var()
```

[40]: (1.0327807495961905, 1.1611606847404532)

[41]: Text(0.5, 1.0, 'IS-MC')



The IS-MC-estimate is $E_f[X^2] \approx 1$, with $VAR_f[X^2] \approx 1.05$. (Please note !!! : $E_f[X^2] = E_g\left[X^2\frac{f(X)}{g(X)}\right]$, similar to VAR, as described earlier).

If we look at the distribution of the IS-MC-Estimator, for example 50 simulations, each n=100 draws, we get :

[43]: sims.mean(), sims.var() # For 50 simulation with n=1000 each [IS-MC-ESTIMATOR_
$$\rightarrow$$
 DIST]

[43]: (1.004474884074828, 0.001067546583881102)

```
[44]: sim.mean(), sim.var() # For single sim with n=1000 [IS-MC-ESTIMATE DIST]
```

[44]: (1.0327807495961905, 1.1611606847404532)

[45]: 1.067546583881102

Repeating the experiment 50 times (n = 1000 each) yields the distribution of the MC-estimator, with

$$E[E[g(x)]] = 1 = E[g(x)] = 1 \approx \mu Var[E[g(x)]] = 0.00099 = \frac{Var[g(x)]}{n} = \frac{1}{1000} \approx \frac{\sigma^2}{n}$$

0.0.4 4.2.2

From the exercise it is not clear whether f_X is the target or proposal distribution. I assume that you meant f_X as the target dist using again U to draw from. In this case, we should use

$$q \sim U(-1,1)$$

because f_X is not defined for values outside of [-1,1].

Let $\varphi(X) = X^2$ and $x \in [-1,1]$ with target density $f(x) = \frac{1+\cos(\pi x)}{2}$ and proposal density $g \sim U(-1,1)$.

Again

$$E_f[\varphi(X)] = E_g\left[\varphi(X)\frac{f(X)}{g(X)}\right] \approx \frac{1}{n}\sum_{i=1}^n \varphi(X_i)\frac{f(X_i)}{g(X_i)}$$

For $g \sim (-1,1)$ we have

$$\frac{f\left(X_{i}\right)}{g\left(X_{i}\right)} \leftarrow f\left(X_{i}\right) \times 2$$

s.t.

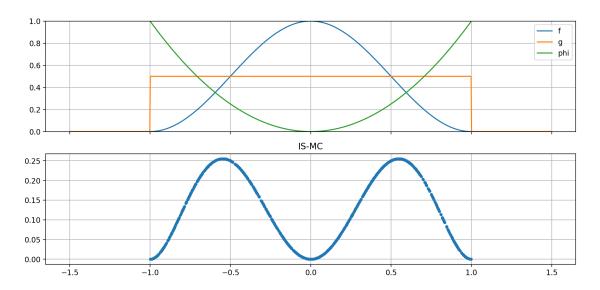
$$E_f[\varphi(X)] \approx \frac{1}{n} \sum_{i=1}^{n} 2\varphi(X_i) f(X_i)$$

```
[46]: # Define new target density
def fx(x) : return (1+np.cos(np.pi*x))/2 if -1 <= x <= 1 else 0
# Instanciate new proposal density
U = uniform(loc=-1, scale=2)</pre>
```

```
[47]: n_draws = 1000
draws = pd.Series(U.rvs(n_draws))
sim = pd.Series([(xi**2)*2*fx(xi) for xi in draws],index=draws)
sim.mean(), sim.var()
```

[47]: (0.12879984635877567, 0.0083807124088555)

[48]: Text(0.5, 1.0, 'IS-MC')



The IS-MC-estimate is $E_f[X^2] \approx 0.13$, with $VAR_f[X^2] \approx 0.008$. (Please note !!! : $E_f[X^2] = E_g\left[X^2\frac{f(X)}{g(X)}\right]$, similar to VAR, as described earlier).

```
[49]: n_draws = 1000
n_sims = 50
sims = pd.Series([pd.Series([(xi**2)*2*fx(xi) for xi in U.rvs(n_draws)]).mean()__
for n_sim in range(n_sims)])
```

If we look at the distribution of the IS-MC-Estimator, for example 50 simulations, each n=1000 draws, we get :

```
[52]: sims.mean(), sims.var() # For 50 simulation with n=1000 each [IS-MC-ESTIMATOR_ \hookrightarrow DIST]
```

[52]: (0.13101941825232205, 6.673497253745432e-06)

```
[53]: sim.mean(), sim.var() # For single sim with n=1000 [IS-MC-ESTIMATE DIST]
```

[53]: (0.12879984635877567, 0.0083807124088555)

```
[54]: sims.var() * n_draws # Fits theoretical Approximation
```

[54]: 0.006673497253745432

Repeating the experiment 50 times (n = 1000 each) yields the distribution of the MC-estimator, with

$$E[E[g(x)]] = 0.13 = E[g(x)] = 0.13 \approx \mu Var[E[g(x)]] = 9.322359799403895e^{-06} = \frac{Var[g(x)]}{n} = \frac{0.008}{1000} \approx \frac{\sigma^2}{n}$$

$0.0.5 \quad 4.3.1$

Let

$$KL(f,g) = \int_{-\infty}^{\infty} f(x) \log \frac{f(x)}{g(x)} dx f \sim N(\mu, \sigma^2)$$
 and $g \sim N(\nu, \tau^2)$

plug the two univariate gaussians into the equation.

...
$$KL(f,g) = \log(\frac{\tau}{\sigma}) - \frac{1}{2} + [\sigma^2 + (\mu - \nu)^2] \times 2\tau^{-2}$$

yields something like that (derivation in latex is impossible..)

Obviously KL is not symmetric $(KL(f,g) \neq KL(g,f))$, $\log(\frac{\tau}{\sigma})$ swaps coefficients

[220]: np.log((b/a))

[220]: 0.49247648509779424

[55]: # In code

def KL(p, q): return np.log(q.std()/p.std()) + (p.var() + (p.mean() - q.

→mean())**2)/(2*q.var()) - (1/2)

0.0.6 4.3.2

MC-Estimators

$$\hat{KL}(f,g) = \frac{1}{n} \sum_{i \sim f}^{n} log \frac{f(x_i)}{g(x_i)}$$

$$\hat{KL}(g,f) = \frac{1}{n} \sum_{i \sim g}^{n} \log \frac{g(x_i)}{f(x_i)}$$

Let

$$f_X \leftarrow N(10, 2)g_X \leftarrow N(1, 3)$$

```
for xi in f.rvs(n):
    f_xi = f.pdf(xi)
    g_xi = g.pdf(xi)
    res = np.log(f_xi / g_xi)
    estimate.append(res)
pd.Series(estimate).mean()
```

[58]: 13.554201304736548

The MC-estimate of $KL(f,g) = \hat{KL}(f,g) = 13.548$. This is consistent when using the previously derived formula.

```
[59]: KL(f, g)
```

[59]: 13.536065887387418

```
[60]: # KL(g, f)
    estimate = []
    n=5000
    for xi in g.rvs(n):
        f_xi = f.pdf(xi)
        g_xi = g.pdf(xi)
        res = np.log(g_xi / f_xi)
        estimate.append(res)
    pd.Series(estimate).mean()
```

[60]: 20.155027335922334

```
[61]: KL(g, f)
```

[61]: 20.297267445945913

Again, $KL(q, f) = \hat{KL}(q, f)$

0.0.7 5.1 k-armed-bandit

Let

$$L(t) = E\left(\sum_{i=1}^{t} (q^* - q(a_i))\right)$$

be the total (cumulative) regret at time t.

Let

$$Q_t(a) \simeq E[R_t \mid A_t = a] = \frac{\sum_{i=1}^{N_a} r_i}{N_a}$$

be the estimate for action a at time t. (i.e. the sample mean).

with update rule that is equivalent to sample-mean-sharpening (i.e linear)

$$Q_{t+1}(a) = Q_t(a) + \frac{1}{N_a + 1} \left[r_{t+1} - Q_t(a) \right]$$

0.0.8 5.1.0 Theoretical optimal lower bound

$$L(t) \ge A \log(t)$$
 where $A = \sum_{a: \Delta_a \ne 0} \frac{\Delta_a}{KL(f_a||f_a^*)}$ and $\Delta_a = q^* - q(a)$

0.0.9 5.1.1 ϵ -greedy

Action probabilities are handy in this approach:

$$P(a^*) = (1 - \epsilon)$$
 for $a^* = \arg\max_a Q_t(a)$
$$P(A_{-a^*}) = \epsilon$$

```
[63]: def greedy_bandit(e,k, init_dists, T,
                         opt_init=1.05):
          k_dists = init_dists
          q_star = [_for _in k_dists if _.mean() == max([_.mean() for __ in_u)]
       \rightarrowk_dists]) ][0]
          q_init = q_star.mean()*opt_init
          # Placeholder for Q values
          Q = { t : {a : q_init if t == 0 else None for a in range(k)} for t in_
       →range(T) }
          # Placeholder for action choices
          N = \{ a : 1 \text{ for a in range(k)} \}
          # Placeholder for regrets
          L = { t : None for t in range(T)}
          # Placeholder for rewards
          R = { t : None for t in range(T)}
          for t in range(T-1):
              ## Choice policy
```

```
argmax_a = [a for a in Q[t] if Q[t][a] == max([Q[t][a] for a in_u])
→Q[t]])][0]
       A_ = [a for a in Q[t] if a != argmax_a]
       choice = argmax_a if np.random.binomial(1, e) == 0 else np.random.
\hookrightarrow choice(A_)
       # Get reward from chosen density
       reward = k_dists[choice].rvs(1)[0]
       # Upadte chosen action estimate
       Q[t+1][choice] = (Q[t][choice] + (1/(N[choice]+1))*(reward -_{\sqcup})
\rightarrowQ[t][choice]))
       # Add 1 obs to N_choice
       N[choice] += 1
       # Update all other
       for a in Q[t]:
           if a == choice:
                continue
           Q[t+1][a] = Q[t][a]
       ## Regret
       regret = q_star.mean() - k_dists[choice].mean()
       L[t] = regret
       ## Reward
       R[t] = reward
   return dict(Q=Q, R=R, L=L, N=N, dists=k_dists, q_star=q_star)
```

0.0.10 5.1.2 UCB

UCB is even simpler, with decision rule according to the most promising action according to its upper boundary.

Choose a s.t.

$$\arg\max_{a} \left(Q_t(a) + c\sqrt{\frac{\log t}{N_t(a)}} \right)$$

```
Q = \{ t : \{a : q_{init} \text{ if } t == 0 \text{ else None for a in } range(k) \} \text{ for } t \text{ in}_{\sqcup} \}
\rightarrowrange(T) }
   # Placeholder for action choices
   N = \{ a : 0 \text{ for a } in \text{ range(k)} \}
   # Placeholder for regrets
   L = { t : None for t in range(T)}
   # Placeholder for rewards
   R = { t : None for t in range(T)}
   for t in range(T-1):
        ## Choice policy
       U = \{ a : c * np.sqrt((np.log(t)/N[a])) \text{ for a in } range(k) \}
       choice_values = [ U[a] + Q[t][a] for a in range(k)]
       ucb_argmax_a = choice_values.index(max(choice_values))
       choice = ucb_argmax_a
       A_ = [a for a in Q[t] if a != choice]
        # Get reward from chosen density
       reward = k_dists[choice].rvs(1)[0]
        # Upadte chosen action estimate
       Q[t+1][choice] = (Q[t][choice] + (1/(N[choice]+1))*(reward -__
→Q[t][choice] ))
        # Add 1 obs to N_choice
       N[choice] += 1
        # Update all other
       for a in Q[t]:
            if a == choice:
                continue
            Q[t+1][a] = Q[t][a]
        ## Regret
       regret = q_star.mean() - k_dists[choice].mean()
       L[t] = regret
        ## Reward
       R[t] = reward
   return dict(Q=Q, R=R, L=L, N=N, dists=k_dists, q_star=q_star)
```

The arm densities are instantiated as follows:

```
[160]: k = 5
    unit_std = 30
    mean_space=list(range(-100,500,30))
    k_dists = [norm(np.random.choice(mean_space),unit_std) for _ in range(k)]
    [(a.mean(), a.std()) for a in k_dists]
```

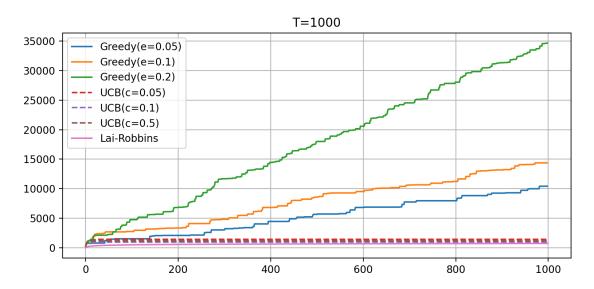
[160]: [(230.0, 30.0), (20.0, 30.0), (380.0, 30.0), (410.0, 30.0), (440.0, 30.0)]

/opt/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:19:
RuntimeWarning: divide by zero encountered in log
/opt/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:19:
RuntimeWarning: invalid value encountered in sqrt
/opt/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:19:
RuntimeWarning: invalid value encountered in double_scalars
/opt/anaconda3/lib/python3.7/site-packages/ipykernel_launcher.py:19:
RuntimeWarning: divide by zero encountered in double_scalars

```
[164]: df_cumul.plot(style=["-","-","-","--","--"],grid=True,__

ofigsize=(9,4),title="T=1000")
```

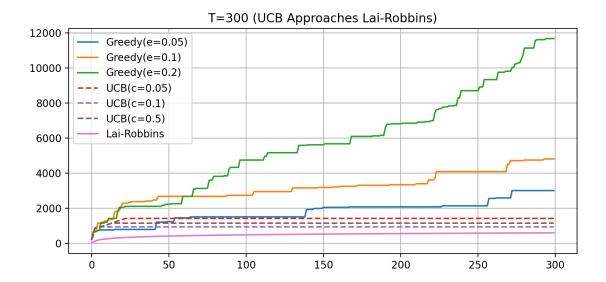
[164]: <AxesSubplot:title={'center':'T=1000'}>



```
[216]: df_cumul[0:300].plot(style=["-","-","-","--","--","--"],grid=True,__

ofigsize=(9,4),title="T=300 (UCB Approaches Lai-Robbins)")
```

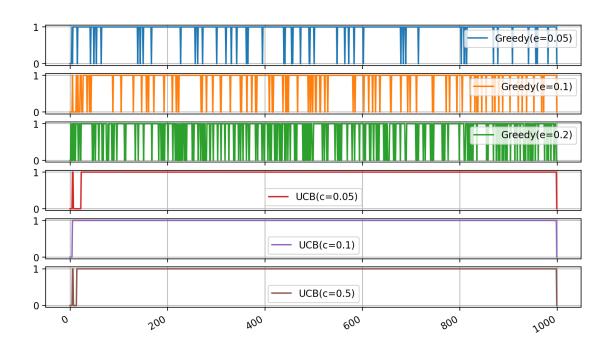
[216]: <AxesSubplot:title={'center':'T=300 (UCB Approaches Lai-Robbins)'}>



0.0.11 Correct choices

Distribution:

```
[167]: correct.sum()/len(correct)
[167]: Greedy(e=0.05)
                        0.946
      Greedy(e=0.1)
                        0.896
      Greedy(e=0.2)
                        0.798
      UCB(c=0.05)
                        0.978
      UCB(c=0.1)
                        0.994
      UCB(c=0.5)
                        0.987
      dtype: float64
[218]: correct.plot(grid=True, style=".-",ms=0.2,figsize=(10,6),subplots=True)
[218]: array([<AxesSubplot:>, <AxesSubplot:>, <AxesSubplot:>,
             <AxesSubplot:>, <AxesSubplot:>], dtype=object)
```



[]: