## Open-circuit voltage (OCV)



- While using PDEs in a BMS is unreasonable, some cell-level variables can be understood quite easily from them In this lesson: OCP, capacity, SOC, (single-particle approximate) voltage
- Open-circuit voltage is steady-state terminal voltage when cell is allowed to rest
- Steady-state condition means that both  $c_{s,e}$  and  $c_e$  are uniform
- lacktriangledown OCV can be related to *open-circuit potentials* of the electrodes  $U_{
  m ocv}^{
  m cell}=U_{
  m ocp}^{
  m pos}$
- High cell voltages (for high energy density), require high positive-electrode potential and low negative-electrode potential (vs. Li/Li+)

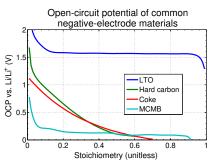
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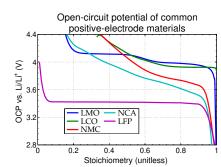
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#### **Example OCP curves**



OCP curves for common electrode materials plotted below





■ Negative and positive plotted versus  $x = c_s^{\text{neg}}/c_{s,\text{max}}^{\text{neg}}$  and  $y = c_s^{\text{pos}}/c_{s,\text{max}}^{\text{pos}}$  where  $c_{s.\text{max}}^{\text{reg}}$  is amount of Li stored when electrode crystal lattice structure completely full

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5.5.3: Single-particle reduced-order models

# Cell total capacity Q



- In "ideal" case, cell uses capacity from  $c_s = 0$  to  $c_s = c_{s,max}$
- Practical cells don't use entire range  $\Box$  Use only from  $x_{0\%}$  to  $x_{100\%}$  in negative and  $y_{0\%}$  to  $y_{100\%}$  in positive electrode
- In terms of physical cell-model parameter values,

$$\begin{split} Q^{\rm neg} &= AFL^{\rm neg} \varepsilon_s^{\rm neg} c_{s,{\rm max}}^{\rm neg} \left| x_{100\%} - x_{0\%} \right| / 3600 \, {\rm Ah} \\ Q^{\rm pos} &= AFL^{\rm pos} \varepsilon_s^{\rm pos} c_{s,{\rm max}}^{\rm pos} \left| y_{100\%} - y_{0\%} \right| / 3600 \, {\rm Ah} \end{split}$$

- These capacities are matched, by definition of compatible  $x_{0\%}$ ,  $x_{100\%}$ ,  $y_{0\%}$ ,  $y_{100\%}$
- Notice that cell total capacity is not a function of temperature, rate, and so forth

## Cell state of charge (SOC)



- Cell SOC can be related either to total amount of lithium in negative or positive electrodes (or, average concentrations)
- When the cell is fully charged,  $c_{s,\text{avg}}^{\text{neg}}/c_{s,\text{max}}^{\text{neg}}=x_{100\%}$  and  $c_{s,\text{avg}}^{\text{pos}}/c_{s,\text{max}}^{\text{pos}}=y_{100\%}$
- When the cell is fully discharged,  $c_{s,\text{avg}}^{\text{neg}}/c_{s,\text{max}}^{\text{neg}} = x_{0\%}$  and  $c_{s,\text{avg}}^{\text{pos}}/c_{s,\text{max}}^{\text{pos}} = y_{0\%}$  (where  $x_{0\%} < x_{100\%}$  and  $y_{0\%} > y_{100\%}$ )
- State-of-charge varies linearly as electrode stoichiometry varies
- $\blacksquare$  Therefore, we can compute cell-level state of charge z as either

$$z = \frac{c_{s,\text{avg}}^{\text{neg}}/c_{s,\text{max}}^{\text{neg}} - x_{0\%}}{x_{100\%} - x_{0\%}} = \frac{c_{s,\text{avg}}^{\text{pos}}/c_{s,\text{max}}^{\text{pos}} - y_{0\%}}{y_{100\%} - y_{0\%}}$$

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5.5.3: Single-particle reduced-order model

## Single-particle model



- Diffusion of lithium inside solid particles is slowest process in a cell, so its dynamic contribution dominates
- So, can consider a single-particle model (SPM) of a cell, modeling electrodes as a single spherical particle representative of a typical particle within the electrode
  - □ Electrolyte concentration and potential dynamics are ignored
- While crude, SPM is good learning tool for understanding how Li-ion cells respond to different input stimuli; can also be used to give good SOC estimates
- To simulate SPM, introduce finite-volume method for discretizing diffusion equation
  - □ Particle divided into equal-thickness spherical shells (like an idealized onion)
  - □ Each time step, lithium flux from one shell to another is calculated, and the concentration of lithium within each shell is updated
  - Imposed cell current forces lithium into/out of the outermost shell

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5.5.3: Single-particle reduced-order models

# Finite-volume simulation method (geometry)



- lacksquare Particle modeled with  $N_r$  equal-thickness onion-like "shells"
  - $\ \square$  So, thickness of any given shell is  $\mathrm{d}R=R_s/N_r$
- Must know outer surface area and volume of each shell
  - □ Innermost shell has volume  $dV_1 = \frac{4}{3}\pi(dR)^3$ , outer surface area  $Sa_1 = 4\pi(dR)^2$
  - $\Box$  Next has volume  $\mathrm{d}V_2 = \frac{4}{3}\pi(2\mathrm{d}R)^3 \mathrm{d}V_1$ , outer surface area  $Sa_2 = 4\pi(2\mathrm{d}R)^2$
  - $\Box$  *n*th has volume  $\mathrm{d}V_n = \frac{4}{3}\pi(n\mathrm{d}R)^3 \frac{4}{3}\pi((n-1)\mathrm{d}R)^3$ , area  $Sa_n = 4\pi(n\mathrm{d}R)^2$
- The variables dV and Sa in the code (coming up!) are vectors containing volumes and outer surface areas of all shells, respectively

# Finite-volume simulation method (flux)



Now, convert molar flux from continuous function of distance r to discrete function at shell boundaries (units mol m<sup>-2</sup> s<sup>-1</sup>)

$$N = -D_s \nabla c_s = -D_s \frac{\partial c_s}{\partial r} \approx -D_s \frac{\Delta c_s}{\Delta r}$$

- $\Box$  Flux at boundary between shells n and n+1 is  $N_n \approx -D_s \frac{c_{n+1}-c_n}{dR}$
- $\square$  When  $N_n$  is negative, flux enters nth shell from (n+1)st shell; when it is positive, flux leaves nth shell to (n+1)st shell
- The vector N in the code computes this flux at all shell boundaries, except at outer surface of particle, which is computed separately
- Rate of material transfer equals N multiplied by the surface area of shell through which flux passes: vector M in code (units mol s<sup>-1</sup>)

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## Finite-volume simulation method (concentration)



- Net Li flux into nth shell is  $Sa_nN_n Sa_{n-1}N_{n-1}$  (mol s<sup>-1</sup>)
- Change in concentration multiplies this flux by  $\Delta t$ , divided by volume of nth shell (mol m<sup>-3</sup>)
- At particle boundary, a flux j is applied (mol m<sup>-2</sup> s<sup>-1</sup>)

  □ Multiplying j by  $Sa_n \Delta t / V_n$  gives change in outer-shell concentration due to j
- Assuming particles spherical with radius  $R_s$ , have volume fraction  $\varepsilon_s$ , define

$$a_s = \frac{\text{total surface area of spheres in a given volume}}{\text{total volume of a sphere}} = \varepsilon_s \frac{4\pi R_s^2}{\frac{4}{3}\pi R_s^3} = \frac{3\varepsilon_s}{R_s} \, \text{m}^2 \, \text{m}^{-3}$$

■ Convert cell current from A to mol s<sup>-1</sup> (divide by F), using total surface area  $a_s AL$ ,

$$j = \frac{i_{\rm app}}{a_s FAL} \, \mathrm{mol} \, \mathrm{m}^{-2} \, \mathrm{s}^{-1}$$

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5.5.3: Single-particle reduced-order models

# Finite-volume simulation method (voltage)



- Finally, while SOC depends on average concentration of Li in electrode, voltage depends on *surface* concentration of Li
- lacktriangle The code calls this cse, which is what we have termed  $c_{s,e}$  elsewhere
- When simulating cell using SPM, one particle models negative electrode and a second (using a copy of the code) models positive electrode
- Cell voltage is then computed as  $U_{\text{ocp}}^{\text{pos}}(y) U_{\text{ocp}}^{\text{neg}}(x)$ , where  $y = c_{s,e}/c_{s,\text{max}}$  and  $x = c_{s,e}/c_{s,\text{max}}$

#### SPM code: Setting up problem



- First segment of code sets up problem for one electrode
  - Initialize constants, input profile, geometry

```
R = 10e-6;
             % particle radius [m]
Cmax = 12000;
                   % [mol/m^3]
c0 = 9500;
                  % initial concentration [mol/m^3]
j0 = 5000*R/3/1800; % lithium flux [mol/m^2/sec]
                  % solid diffusivity, [m^2/s]
D = 1e-14;
jk = [j0*ones(1,1800), zeros(1,3600)]; % discharge and rest
jk = [jk - jk];
                   % discharge and rest, then charge and rest
% Simulation control
Nr = 20;
                   % number of "shells" radially
dR = R/Nr;
                    % width of each "shell"
Sa = 4*pi*(R*(1:Nr)/Nr).^2; % outer surface area of each shell
% time steps of 1 second
```

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#### SPM code: Simulation loop



- Remainder of code simulates SPM over time
- □ Initialize, loop through input profile, plot results

```
% initialize concentration profile versus "r" dimension
c = c0*ones(1,Nr);
cse = zeros(size(jk)); % concentration at surface
cse(1) = c0;
for timestep = 1:length(jk),
 N = -D*diff(c)/dR;  % flux at surfaces between "bins"
M = N.*Sa(1:end-1);  % total moles crossing surfaces
 c = c + ([0 M] - [M 0])*dt./dV; % conc. change via diffusion
 c(end) = c(end) - jk(timestep)*Sa(end)*dt/dV(end); % at boundary
  cse(timestep+1) = c(end);
figure(1); clf; plot((0:length(jk))/3600,cse/1000);
title('Surface concentration of particle')
xlabel('Time (h)'); ylabel('Concentration (kmol m^{-3})')
```

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5.5.3: Single-particle reduced-order models

## Summary



- In this lesson, you learned:
  - How to find OCV from electrode OCPs
  - How to compute total capacity and SOC
  - How to use finite-volume method to simulate a single particle
- Example output from sample code plotted to right
- To simulate full cell using SPM method, simulate two (positive, negative electrode) particles
  - □ Then, convert surface concentrations to OCPs
  - □ Then, compute voltage from OCPs

Surface concentration of particle Concentration (kmol 0.5 2.5 Time (h)

# For further study



- The single-particle model is presented in Chapter 3 of
  - □ Plett, Gregory L., Battery Management Systems, Volume 1: Battery Modeling
  - □ See also http://mocha-java.uccs.edu/BMS1/index.html.
- There are detailed lecture notes and lecture videos on the topics in this lesson from  $which you can \ learn \ at \ \texttt{http://mocha-java.uccs.edu/ECE5710/index.html}$ (Topics in section 3).

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