Summary of this course



- Have seen good and bad ways to estimate SOC for all cells
- Model-based methods are preferred; KF-based methods are "optimal" in some sense
- Additionally, KF estimates entire state—not only SOC—therefore can also be used for conservative power-limits estimates, etc.
- Lots of nuances unexplored in this short course
 - Can invest a lifetime to studying KF and applications!
- Our next step is to look at state-of-health estimation, which is a form of parameter estimation

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3.5.7: Where from here?

Decision point



- This brings us to the end of the non-honors version of course 3 in the BMS algorithms specialization
- Decision point:
 - □ Honors track has one more week in course 3, looking into real-world issues regarding implementing model-based estimators on full-scale battery packs
 - Remaining courses focus on how to estimate battery state-of-health, and how to control battery operation



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Where from here?



- Course 4 focusses on state-of-health estimation
 - □ How do battery cells degrade?
 - □ The difficulty of estimating capacity loss, and problems with "standard" ordinary least-squares regression to do so
 - An improved method using total least-squares and some approximations
 - How to extend nonlinear Kalman filtering theory to estimate time-varying model parameters as well as model state

3.5.7: Where from here?

Credits



Credits for photos in this lesson

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