

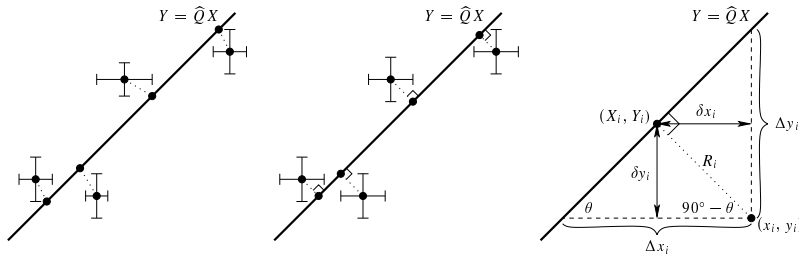


## Desire a simple WTLS solution

- Know that WLS solution is biased, but WTLS demands too much computation to use in practical BMS
- Have seen proportional-uncertainty version of WTLS—which we call TLS—which is feasible to implement: but, uncertainties are not necessarily proportional in practice
- We desire solution that approximates WTLS problem but allows  $\sigma_{x_i}^2$  and  $\sigma_{y_i}^2$  to be nonproportional, but which yields a recursive solution for feasible implementation in an embedded system
- In this lesson, you will learn an approach we can take, based on geometry of WTLS solution



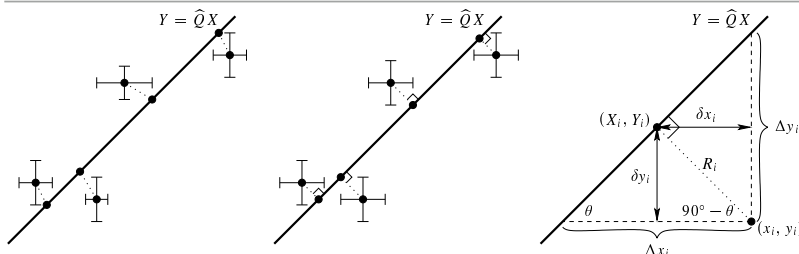
## WTLS geometry (1/2)



- Figure shows WTLS geometry, motivates approximate solution to be developed
- Left frame shows relationship between data point  $(x_i, y_i)$  and its optimized map  $(X_i, Y_i)$  on  $Y_i = \hat{Q} X_i$  when  $\sigma_{x_i}^2$  and  $\sigma_{y_i}^2$  are arbitrary
  - The error bars on each data point illustrate the uncertainties in each dimension, which are proportional to  $\sigma_{x_i}$  and  $\sigma_{y_i}$



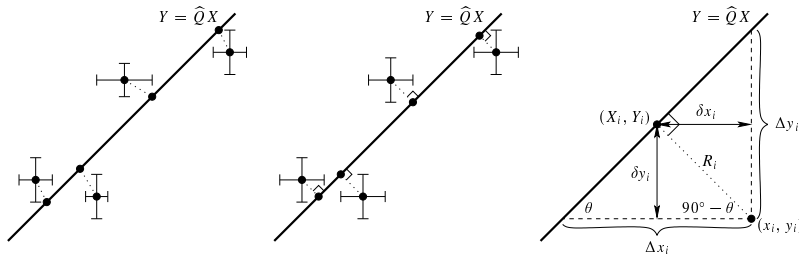
## WTLS geometry (2/2)



- We see that the distance between  $x_i$  and  $X_i$  is not necessarily equal to the distance between  $y_i$  and  $Y_i$ —depends on respective error bounds
- If quality of  $x_i$  is better (poorer) than quality of  $y_i$ , distance to its map  $X_i$  should be shorter (greater) than the distance from  $y_i$  to its map  $Y_i$



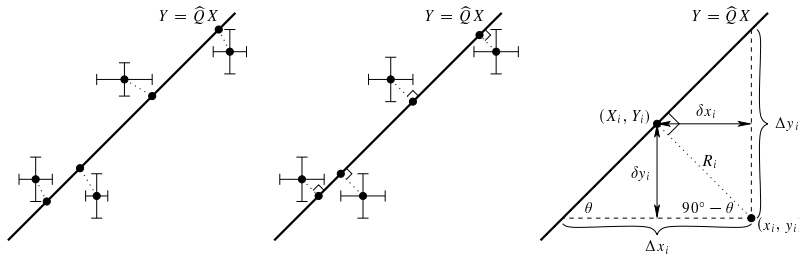
## TLS geometry



- Middle frame shows relationship between data point  $(x_i, y_i)$  and its optimized map  $(X_i, Y_i)$  on  $Y_i = \hat{Q} X_i$  when  $\sigma_{x_i}^2$  and  $\sigma_{y_i}^2$  are equal
- Distance between  $x_i$  and  $X_i$  is equal to distance between  $y_i$  and  $Y_i$ , and line joining data point  $(x_i, y_i)$  and  $(X_i, Y_i)$  is perpendicular to the line  $Y_i = \hat{Q} X_i$ 
  - If  $\sigma_{x_i}$  and  $\sigma_{y_i}$  are unequal but proportional,  $x$ - or  $y$ -axis may be scaled to yield transformed data points with equal variances, and hence same idea applies



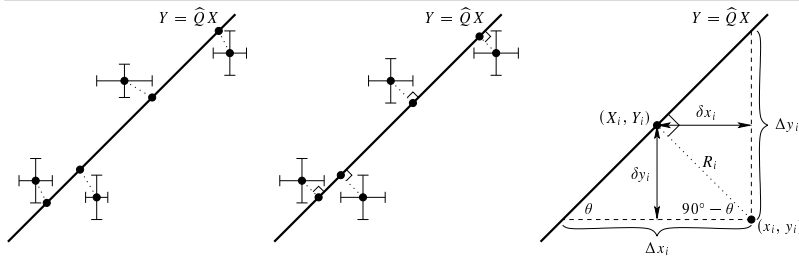
## Approximated geometry (1/2)



- Right frame illustrates definitions that will be used to derive an approximate weighted total least squares (AWTLS) solution
- Motivated by TLS, we enforce that line joining data point  $(x_i, y_i)$  and  $(X_i, Y_i)$  be perpendicular to line  $Y_i = \hat{Q} X_i$ —will result in a recursive solution



## Approximated geometry (2/2)



- However, as with the WTLS solution, we weight distance between  $x_i$  and  $X_i$  differently from distance between  $y_i$  and  $Y_i$  in optimization cost function
- This will give a better total capacity estimate than TLS when the uncertainties on  $x_i$  and  $y_i$  are not proportional



## Summary

- WTLS solution maps  $(x_i, y_i)$  to  $(X_i, Y_i)$  on  $Y = \hat{Q}X$  with nonperpendicular line
  - Optimal but not practical to implement
- TLS maps with perpendicular line
  - Optimal only for proportional  $\sigma_{x_i}$  and  $\sigma_{y_i}$  but practical
- Will use observation of orthogonality to propose sub-optimal mapping  $(x_i, y_i)$  to  $(X_i, Y_i)$  that is perpendicular, but also weights uncertainties in  $\sigma_{x_i}$  and  $\sigma_{y_i}$
- Will continue to use geometry from figure to right as we proceed beyond this point

