## Robustness and speed



- Two issues remaining to consider
  - Speed: dual and joint filtering computationally complex
  - □ Convergence: do they converge to the correct solution?
- Consider convergence first
  - $\Box$  Dual and joint filtering adapt  $\hat{x}$  and  $\hat{\theta}$  so that model input–output relationship matches system's input-output data closely
  - No built-in guarantee that model state converges to any physical meaning
  - Usually, when employing KF, we desire that state converge to specific meaning
  - Special steps must be taken to ensure that this occurs; otherwise, state and parameter values will quickly diverge away from anything meaningful

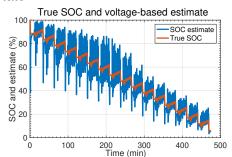
## Ensuring correct convergence



- A very crude cell model may be used, combined with dual/ joint EKF/SPKF to ensure convergence of SOC state
- Specifically, the cell terminal voltage

$$egin{aligned} v_k &pprox ext{OCV}(z_k) - R_0 i_k \ ext{OCV}(z_k) &pprox v_k + R_0 i_k \ \hat{z}_k &= ext{OCV}^{-1}(v_k + R_0 i_k) \end{aligned}$$

■ By measuring cell voltage under load,  $v_k$ , cell current  $i_k$ , and knowing  $R_0$  and inverse OCV function, can compute noisy SOC estimate,  $\hat{z}_k$ 



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# **Ensuring SOC convergence**



Cell model used in KF has its output equation augmented with SOC: For example,

$$g(x_k, u_k, \theta) = \begin{bmatrix} \mathsf{OCV}(z_k) + Mh_k - \sum_i R_i i_{R_i, k} - R_0 i_k \\ z_k \end{bmatrix}$$

Dual/joint xKF run using modified model, with "measured" data used in update being

$$y_k = \left[ \begin{array}{c} v_k \\ \hat{z}_k \end{array} \right]$$

• "Noise" of  $\hat{z}_k$  (short-term bias due to ignoring hysteresis and diffusion voltages) prohibit it from being used as primary SOC estimator, its long-term behavior in dynamic environment is accurate, maintains accuracy of SOC state in dual/joint xKF

# Estimating SOH without full dual EKF/SPKF



- Full dual/joint EKF/SPKF is computationally expensive
- If precise values for full set of cell-model parameters are not necessary, then other methods might be used
- Can determine cell capacity and resistance using simpler KF-based methods
  - Same approaches as you might have seen in honors section of course 3, on bar-delta filtering
  - □ Since these are MMSE methods, estimate of total capacity using this approach is believed to be biased, and TLS methods are preferred

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I.5.5: Addressing issues of robustness and speed

## Estimating resistance using a simple xKF



■ To estimate cell resistance using KF, formulate simple model

$$R_{0,k+1} = R_{0,k} + r_k$$
  
 $v_k = \text{OCV}(z_k) - R_{0,k}i_k + e_k,$ 

where cell resistance  $R_{0,k}$  modeled as a constant value with a fictitious noise process  $r_k$  allowing adaptation

- $\blacksquare$   $v_k$  is crude estimate of cell's voltage,  $i_k$  is cell current,  $e_k$  models estimation error
- If estimate of  $z_k$  is available from an external source, we simply apply KF to this model to estimate cell resistance
- Above model may be extended to handle different values of resistance on dis/charge, or at different SOCs, or at different temperatures, for example

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4.5.5: Addressing issues of robustness and speed

# Estimating capacity using a simple xKF



■ To estimate cell capacity using KF, formulate simple cell model

$$Q_{k+1} = Q_k + r_k$$
  
 
$$d_k = z_k - z_{k-1} + \eta_{k-1} i_{k-1} \Delta t / Q_{k-1} + e_k$$

- Second equation is a reformulation of the SOC state equation such that the expected value of  $d_k$  is equal to zero by construction
- Again, a KF is constructed using the model defined by these two equations to produce a capacity estimate
- As KF runs, computation for  $d_k$  in second equation is compared to known value (zero, by construction), and difference is used to update capacity estimate
- Note that good estimates of the present and previous states-of-charge are required, possibly from a KF estimating SOC

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#### Summary



- It is very difficult to tune dual/joint xKFs due to the very different timescales of states and parameters
- By default, dual/joint xKFs will tend to diverge away from meaningful state and parameter values so must take special steps to make estimates robust
- Augmenting output with approximate SOC estimate helps with this
- Also, if it is not necessary to estimate entire model parameter vector, can estimate only those desired, as illustrated with examples for resistance and total capacity

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