



# Real-Time Systems

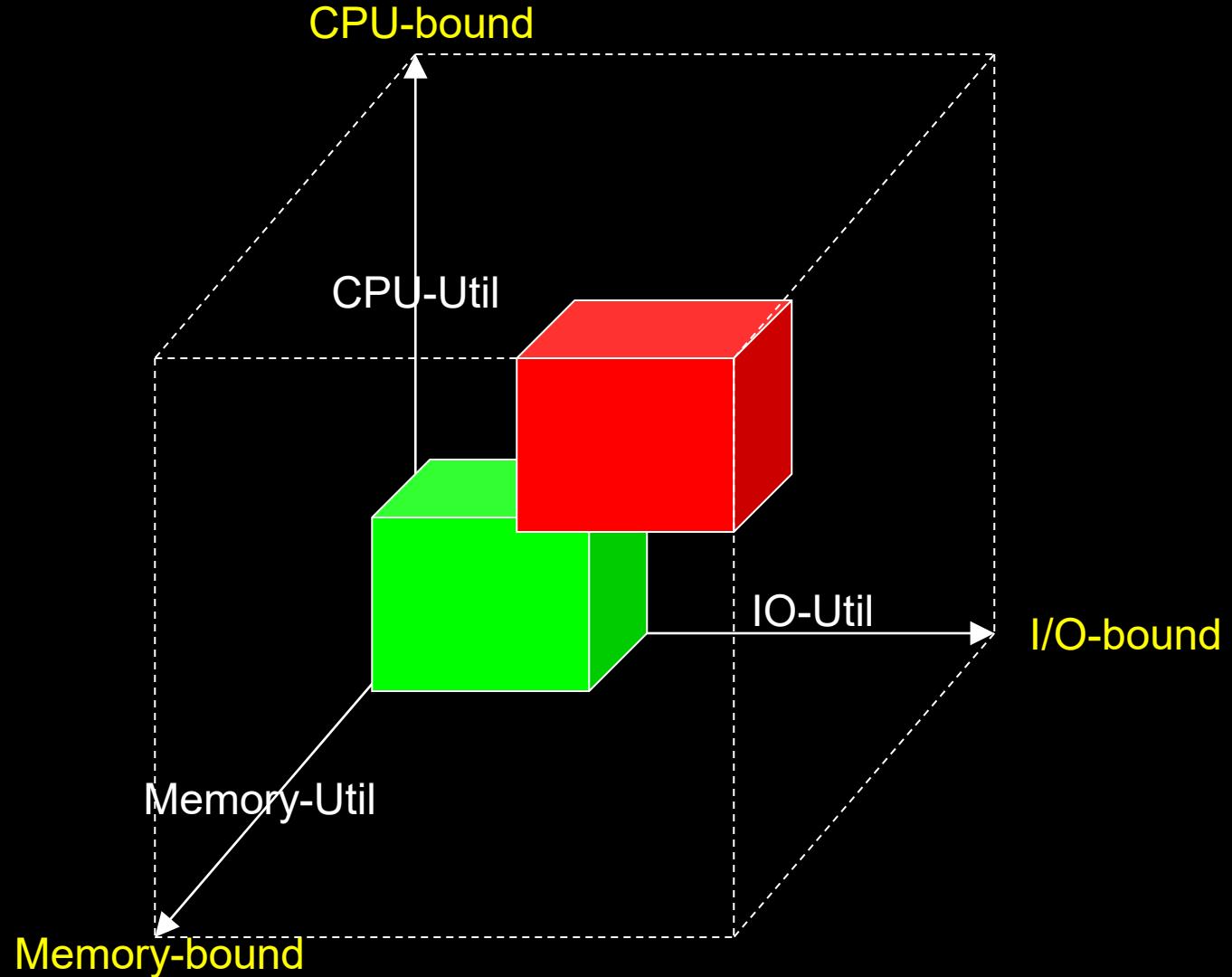
*Lecture Topic - Device Interface Drivers and MMIO*

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# Resource View of HW/SW Interface



- Three-Space View of Utilization Requirements
  - CPU Margin – 30% for LUB
  - IO Latency (Bandwidth) Margin?
  - Memory Capacity (Latency) Margin?
- Upper Right Front Corner – Low-Margin
- Origin – High-Margin

# Camera Demo - Linux Devices

- Computer Vision Application
  - OpenCV API – User Space
  - V4L2 API – Kernel, User Space Interface
  - UVC – Driver, Kernel Space Module
  - USB – Driver, Kernel Space Module
- `sudo cat /proc [PIPs, meminfo, cpuinfo,interrupts, slabinfo, devices, bus/pci, bus/input, ...]`
- `sudo lshw`, **lusb**, **lspci**, **lsscsi**, **lsmod**, **lscpu**, **slabtop** [[more](#)]
- `dmesg`, **htop**, **iostat from sysstat** [[more](#)];  
`free`, **lsof**, **netstat**, **strace**, **vmstat** [[more](#)]
- Trace, Profile, Debug Tools (coming up ...) –
  - [KernelShark](#) (`sudo apt-get install kernelshark`),
  - [wireshark](#) (`sudo apt-get install wireshark`),
  - [ftrace](#), [sysprof](#), [systemtap](#), etc.

## Demo Camera Applications On Linux Laptop

For OpenCV hit “q” in imshow window to properly shutdown

[Reset USB](#) bus and device  
If you happen to exit badly – e.g.  
with Ctrl-C or **run camorama**  
[sigint could catch and handle]

- Use [syslog](#) instead of `printf`
- Buffers for output in slack time
  - Avoids immediate blocking I/O that can delay a service
  - Similar features
  - Add custom time-stamp
- Linux kernel modules
- Must use “[printk](#)”
  - [Kernel Modules, Drivers](#)

# Embedded I/O (HW View)

## ■ Analog I/O

- DAC analog output: servos, motors, heaters, ...
- ADC analog input: photodiodes, thermistors, ...

## ■ Digital I/O

- Direct TTL I/O or GPIO
- Digital Serial (I2C, SPI, ... - Chip-to-Chip)
- Digital Interface to UART/Line Driver, Serializer-deserializer (Serdes), or Physical I/F
  - Digital I/O to Line Driver Interface (e.g. RS232)
  - 10/100 MII, 1G RGMII, 10G XGMII interfaces to Serdes to Phy

# CPU Core I/O (SW View)

## ■ Word

- Register Control/Config, Status, Data
- Typical of Low-Rate I/O Interfaces (RS232)

## ■ Block

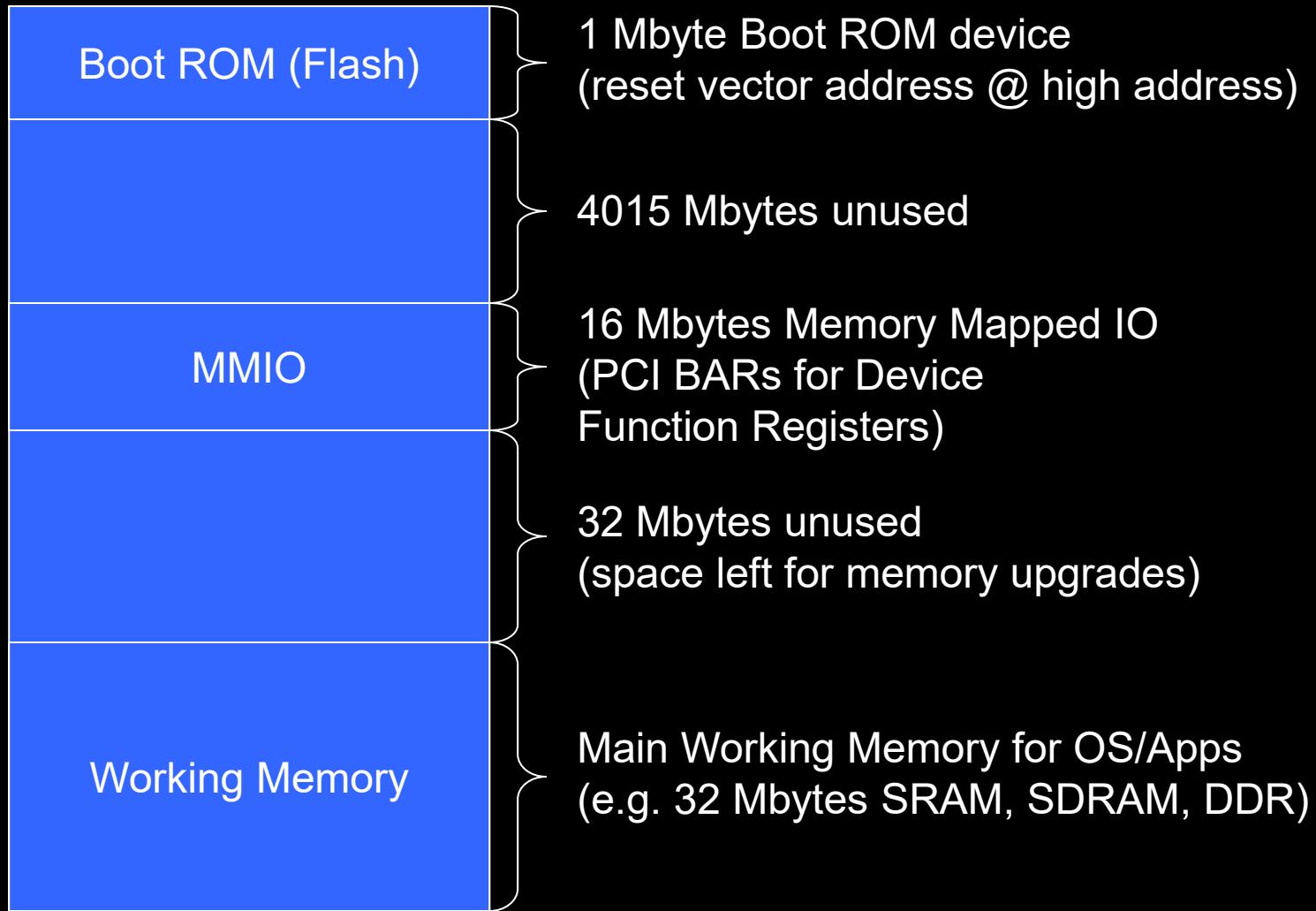
- FIFOs (2-32K), Dual-Port RAM and DMA
- Typical of High-Rate I/O Interfaces

## ■ System Memory Map (32 or 64 bit space)

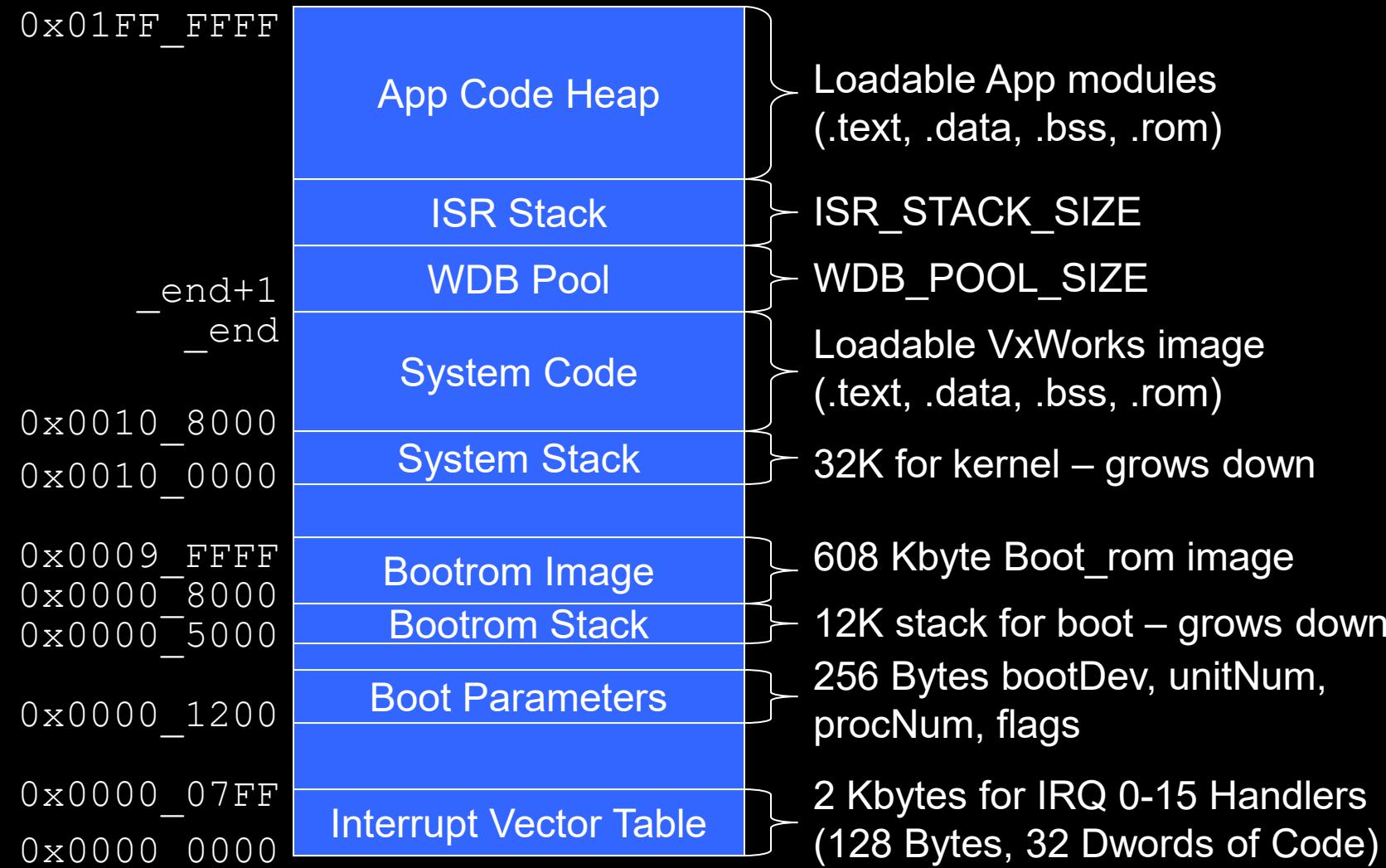
- Physical Memory (SDRAM, DDR, SRAM)
- BootROM (Typically Flash)
- Configuration and Control Registers

# Example 4Gb System Memory Map

0xFFFF\_FFFF  
0xFFF0\_0000  
0xFFEF\_FFFF  
  
0x0500\_0000  
0x04FF\_FFFF  
  
0x0400\_0000  
0x03FF\_FFFF  
  
0x0200\_0000  
0x01FF\_FFFF  
  
0x0000\_0000



# OS and App Use of 32 Mb Memory



# Platform/RTOS I/O (FW View)

## ■ Driver Interfaces Used By Applications

- Top-Half: Application Interface
- Bottom-Half: FW Interface to HW

## ■ Application Interface Examples

- Word-at-a-Time I/O Drivers
  - Serial byte streams
  - Device Configuration, Control, and Status
- Block I/O Drivers
  - Disk, Flash, High-Rate Network (Typically DMA)
- Stack I/O Drivers
  - Filesystem, TFFS/DOC, TCP/IP

Network Stack – Driver Interface

L7	Application
L6	Data Presentation
L5	Sockets API - Session
L4	<b>TCP</b>
L3	IP
L2	IEEE 802.3z - GigE
L1	Cat-6 UTP

Layer 1 - Physical (Port)

Layer 2 - Link (Hub)

Layer 3 - Network (Switch)

Layer 4 - Transport (Router)

# Platform/RTOS I/O (FW View) – Device Interfaces

Word-at-a-Time - RS-232/422 UART, GPIO, RELAY, ADC

Block I/O - Common Flash Interface, Ethernet Link Layer

Stack I/O - E.g. Flash Filesystem and Network Stack

```
[ 0.871116] mmc0: sdhost-bcm2835 loaded - DMA enabled (>1)
[ 0.873353] Waiting for root device /dev/mmcblk0p7...
[ 0.930047] mmc0: host does not support reading read-only switch, assuming write-enable
[ 0.932946] mmc0: new high speed SDHC card at address 0001
[ 0.934278] mmcblk0: mmc0:0001 EB1QT 29.8 GiB
[ 0.938366] mmcblk0: p1 p2 < p5 p6 p7 >
[ 0.949017] mmc1: new high speed SDIO card at address 0001
[ 0.979784] EXT4-fs (mmcblk0p7): mounted filesystem with ordered data mode. Opts: (null)
[ 2.761221] EXT4-fs (mmcblk0p7): re-mounted. Opts: (null)
[ 25.240038] EXT4-fs (mmcblk0p5): mounted filesystem with ordered data mode. Opts: (null)
pi@raspberrypi:~/Downloads $ █
```

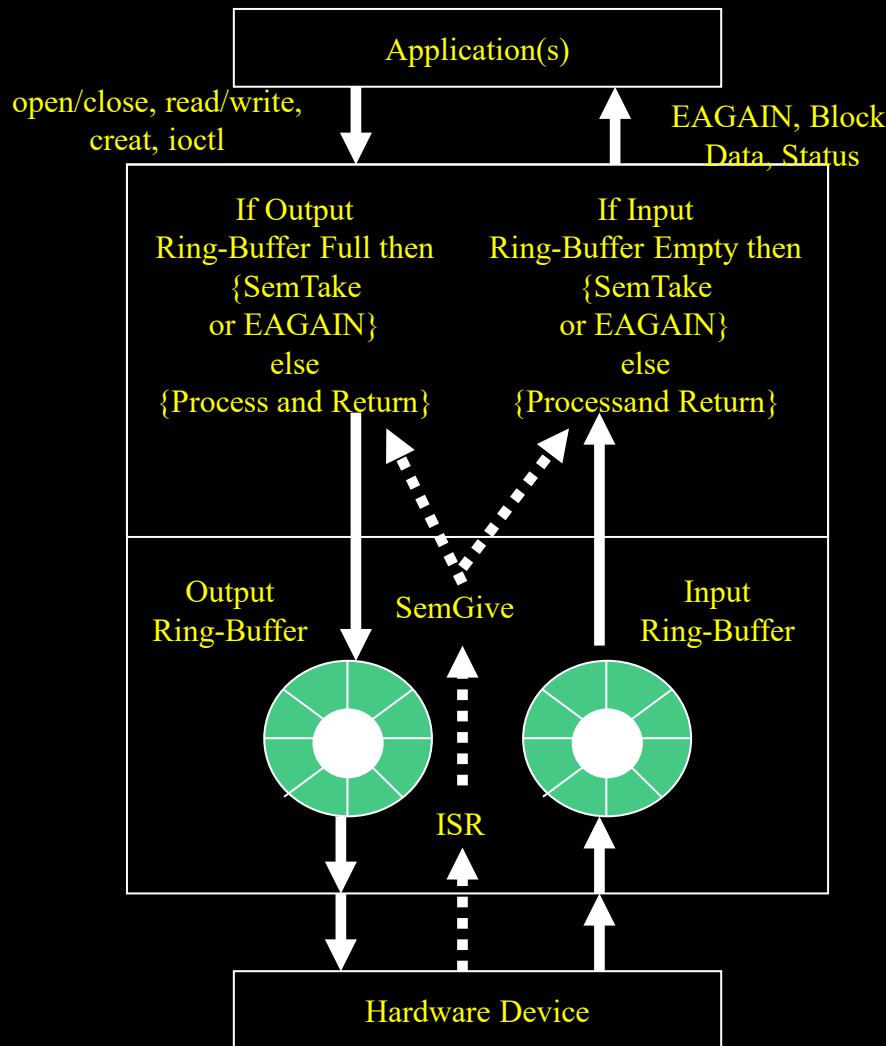
## Linux Block Interfaces

mmcblk is the block interface to SD card Nand flash on Linux

Disk drivers are normally SCSI (SAS) or ATA (SATA) – including SSD

The mmcblk driver interface is critical to I/O performance for stored data

# Driver Design



## ■ Application Interface

- Application Policy
- Blocking/Non-Blocking
- Multi-thread access
- Abstraction

## ■ Device Interface

- SW/HW Interface
- Immediate Buffering
- Interrupt Service Routine

## ■ HAL Interface

# Cached Memory and DMA

## ■ Cache Coherency

- Making sure that cached data and memory are in sync
- Can become out of sync due to DMAs and Multi-Processor Caches
- Push Caches Allow for DMA into and out of Cache Directly
- Cache Snooping by HW may Obviate Need for Invalidate

## ■ Drivers Must Ensure Cache Coherency

- Invalidate Memory Locations on DMA Read Completion
  - `cacheInvalidate()`
- Flush Cache Prior to DMA Write Initiation
  - `cacheFlush()`

## ■ IO Data Cache Line Alignment

- Ensure that IO Data is Aligned on Cache Line Boundaries
- Other Data That Shares Cache Line with IO Data Could Otherwise Be Errantly Invalidated

# Disadvantages of Abstracted Driver

- Generally the Software Engineering Value Outweighs any Inefficiency
- PDL – Peripheral Driver Library, Focus on Device Interfaces [Devices Interfaces and HAL]
- Full Driver Abstraction Adds Overhead and Complexity
  - Function calls and table look-up
  - More Code than Single Layer API
- Adds Buffering and Copy Features
  - Can Use Zero-Copy Buffering (Pointers) to Minimize Impact
  - Zero-Copy Buffers can be Complex

# Advantages of Abstracted Driver

- **Portability**
  - If SW/HW Interface changes, change Device Interface
  - If Application Interface changes, change Application Interface
- **Testability (Test HW Interface and User Space Application Interface Separately)**
- **Single Point of Access and Maintenance**
- **Enforce Multi-Thread Usage Policies**
- **Separate Buffering and ISR from Usage**
- **Common Application Entry Points**
- **Scheduled I/O (Most Work in Task Context rather than ISR Context)**

# Driver Writer Resources

## ■ Linux Device Drivers

- Kernel Modules (Loaded After Boot)
- Built-in Drivers (Loaded with Kernel Image)
- Linux 2.6.x Device Drivers, by Rubini and Corbet [[Web Version](#)]
- Jerry Cooperstein's Linux Device Drivers
- [Linux Foundation](#) [most current]

## ■ VxWorks RTOS Device Interfaces

- All applications and drivers are kernel modules (E.g. [Btvid](#) analog NTSC Video Decoder)
- Driver entry point registration table
- Section 3.9 of VxWorks Programmer's Guide, pages 166-174
- VxWorks Programmer's Guide, Appendix D for x86 Architecture – pages 431-478

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