

Midterm Discussion in beginning (rewatch for details) → thru first ~6 minutes

Calculus of Variations

→ extremize functionals

Function: dependent variable changes with independent variable, $x(t)$

↳ extremize → Calculus: $\frac{dx(t)}{dt} = 0$

What is a functional?

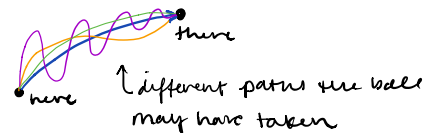
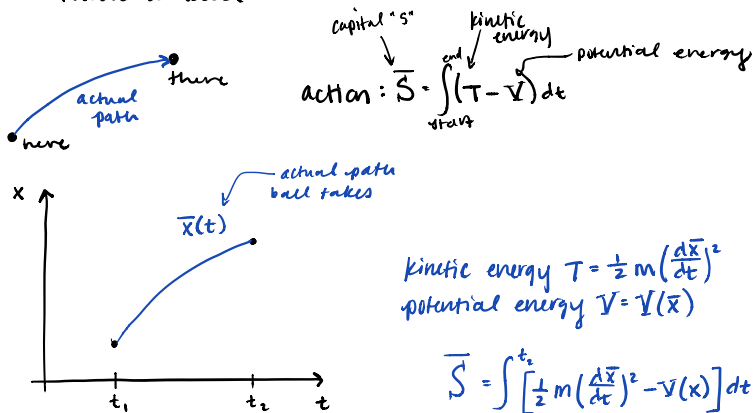
Functional: function of a function of a variable

potential energy $V(\vec{x}(t))$
↑ some vector

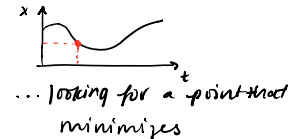
→ extremize → Calculus of variations (... a little more complicated)

Principle of Least Action

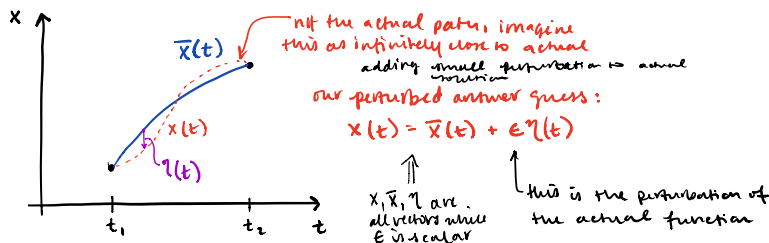
→ throw a ball



(from calculus:)



until here, we're looking for a curve that minimizes
going to get a function as a result of minimizing a functional



action == difference between KE and PE integration over between two time points

*if the blue curve minimizes the action, then any other curve

η added to \bar{x} is going to be larger than \bar{x}

*restriction on η : has to start and stop at same points as blue curve

$$\bar{S} = \int_{t_1}^{t_2} \left[\frac{m}{2} \left(\frac{d\bar{x}}{dt} + \epsilon \frac{d\eta}{dt} \right)^2 - V(\bar{x} + \epsilon \eta) \right] dt \quad \dots \text{now expand and simplify}$$

$$\left(\frac{d\bar{x}}{dt} \right)^2 = \underbrace{\left(\frac{d\bar{x}}{dt} \right)^2}_{O(1)} + \underbrace{2\epsilon \frac{d\bar{x}}{dt} \frac{d\eta}{dt}}_{O(\epsilon)} + \underbrace{\epsilon^2 \left(\frac{d\eta}{dt} \right)^2}_{O(\epsilon^2)}$$

H.O.T. = higher order terms

$V(\bar{x} + \epsilon \eta) = \dots$ take a Taylor Series Expansion around $\eta = 0$ (?)

$$= V(\bar{x}) + \underbrace{\epsilon \eta V'(\bar{x})}_{O(\epsilon)} + \underbrace{\epsilon^2 \frac{\eta^2}{2} V''(\bar{x})}_{O(\epsilon^2)} + \dots$$

so now ...

$$\dot{S} = \int_{t_1}^{t_2} \left[\underbrace{\frac{m}{2} \left(\frac{d\bar{x}}{dt} \right)^2 - V(\bar{x})}_{\text{when integrated} \Rightarrow \dot{S}} + m \epsilon \frac{d\bar{x}}{dt} \frac{d\eta}{dt} - \epsilon \eta V'(\bar{x}) + O(\epsilon^2 \eta^2) \right] dt$$

↑ written with the η term because typically write $x(t) = \bar{x}(t) + \delta \bar{x}(t)$

then rewrite ...

$$\delta S = \dot{S} - \dot{S} = 0 \Rightarrow \text{then have found } \bar{x}$$

this is called the "first variation" since only considered ϵ terms (not ϵ^2 terms for instance)

$$\delta S = 0$$

$$\delta S = \int_{t_1}^{t_2} \left[\underline{m \frac{d\bar{x}}{dt} \epsilon \frac{d\eta}{dt}} - \epsilon \eta V'(\bar{x}) \right] dt = 0$$

↓ if we can factor out η

$$\int_{t_1}^{t_2} \eta \left[m \frac{d\bar{x}}{dt} \frac{d\eta}{dt} - \eta V'(\bar{x}) \right] dt = 0$$

↑ optimise it's exact
 η not zero but can be anything else/arbitrary

↓

then whatever is left on inside must be 0

↓

so we need to get derivative of η out ... the underlined quantity needs to be turned into something times η

*crucial step: can get rid of that derivative by doing integration by parts

Integration by Parts:

- product rule backwards

↓

$$\frac{d}{dx}(uv) = u \frac{dv}{dx} + v \frac{du}{dx}$$

$$\Rightarrow \int u dv = uv - \int v du$$

$$\underbrace{m \frac{d\bar{x}}{dt} \epsilon \frac{d\eta}{dt}}_{\text{from before, what we want to integrate by parts}} \rightarrow \int_{t_1}^{t_2} \underbrace{m \frac{d\bar{x}}{dt}}_u \underbrace{\epsilon \frac{d\eta}{dt}}_{dv} dt = \underbrace{\left[\epsilon \eta m \frac{d\bar{x}}{dt} \right]_{t_1}^{t_2}}_{uv} - \underbrace{\epsilon m \int_{t_1}^{t_2} \eta \frac{d}{dt} \left(\frac{d\bar{x}}{dt} \right) dt}_{\int v du}$$

from before, what we want to integrate by parts

Back to what we're after:

$$\delta S = \epsilon \eta(t) m \frac{d\bar{x}}{dt} \Big|_{t_1}^{t_2} - \epsilon m \int_{t_1}^{t_2} \frac{d^2 \bar{x}}{dt^2} \eta(t) dt - \epsilon \int_{t_1}^{t_2} V'(\bar{x}) \eta(t) dt$$

↑
indicates t_1 and t_2 here

* remember that η is the difference between x and \bar{x}

... but @ t_1 and t_2 there is no difference

$$\therefore \eta(t_1) = \eta(t_2) = 0$$

\therefore can take out this entire term!

first variation of action : $\delta S = \int_{t_1}^{t_2} \left[-m \frac{d^2 \bar{x}}{dt^2} - V'(\bar{x}) \right] \epsilon \eta(t) dt$

$$\downarrow$$

$$-m \frac{d^2 \bar{x}}{dt^2} - V'(\bar{x}) = 0$$

↑
acceleration

↑
force
↑
force = $-V'(\bar{x})$

\Rightarrow we found Newton's Law governing equation!

$$\boxed{F = ma}$$