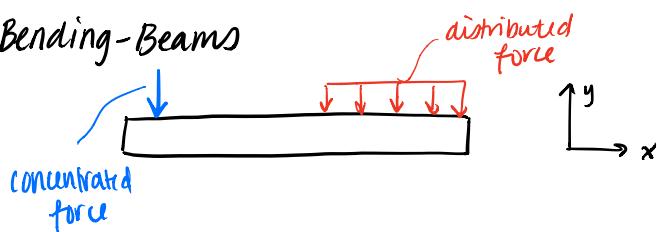
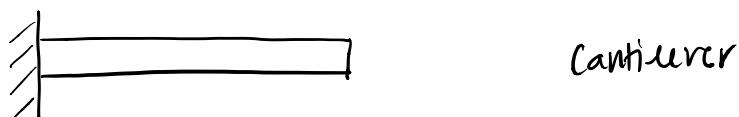


## Materials - Lecture #13

### Bending-Beams



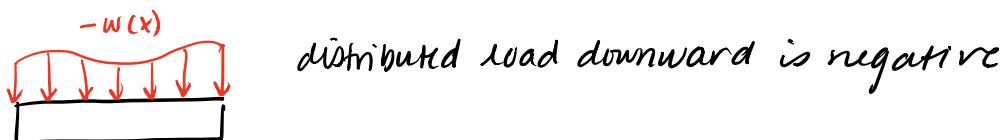
- beams are long, straight bars w/constant area
- beams are classified according to support



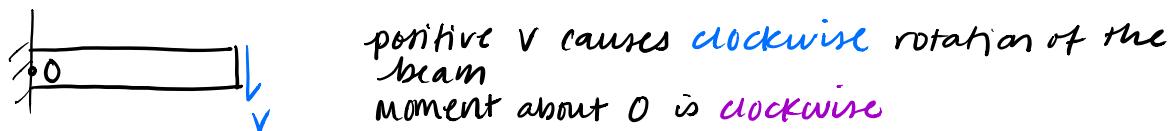
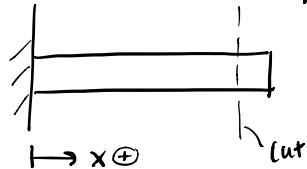
Issue: ① Beams develop internal shear and moment, varies from pt to pt.

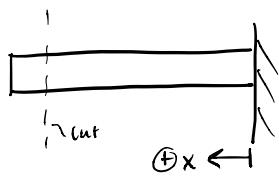
② where is shear force ( $V$ ), moment ( $M$ ) maximized along beam length?

### Beam sign convention

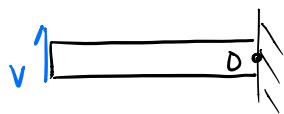


### Internal shear sign convention

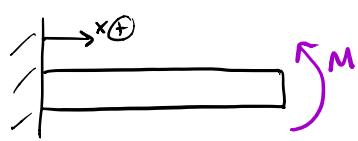




$V$  still causes clockwise rotation

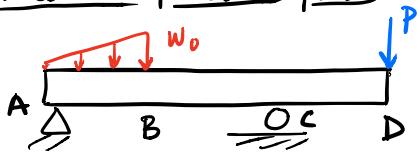


Sign Convention for internal moments



Both positive moments cause compression of top surface, tension of bottom surface

Procedure for analysis

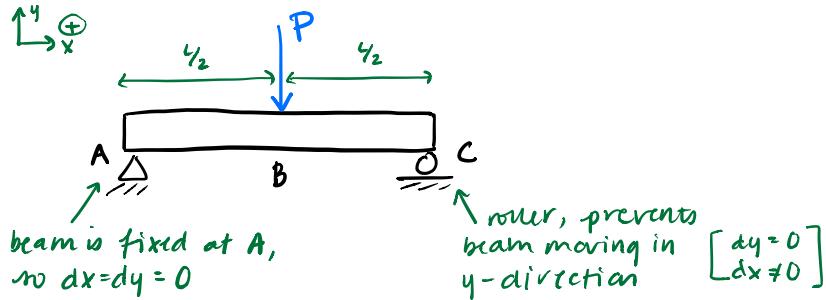


- Use method of sections to find  $V$  and  $M$  at any point  
→ BUT, shear/moment are discontinuous

- Find shear/moment diagrams for each region between the discontinuities

1. Calculate support reactions (force + moments)
2. Start at left end of beam, specify separate coordinates extending to regions of beam between concentrated loads (forces/moments)
3. Section beam according to (2), draw FBDs, find internal shear and moment

### Example #1 (by Prof. Park)



Step 1: Reaction forces

$$\begin{aligned} & \text{① } \sum F_x = 0 = A_x & A_x = 0 \\ & \text{② } \sum M_A = R_c L - P\left(\frac{L}{2}\right) = 0 & R_c = \frac{P}{2} \\ & \text{③ } \sum F_y = 0 = R_A + R_c - P & R_A = \frac{P}{2} \end{aligned}$$

Step 2: Internal shear/moment

→ first section: A to B

$$\begin{aligned} & \text{④ } \sum F_y = 0 = \frac{P}{2} - V & V = \frac{P}{2} \\ & \text{⑤ } \sum M_0 = 0 = M - \left(\frac{P}{2}\right)x_1 & M = \frac{P}{2}x_1 \end{aligned}$$

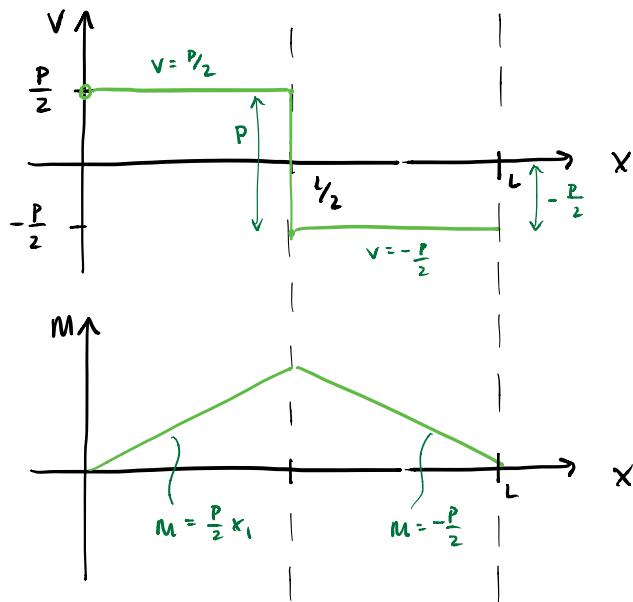
Relationship between  $V$  and  $M$ ?

$$\rightarrow \frac{dM}{dx_1} = V$$

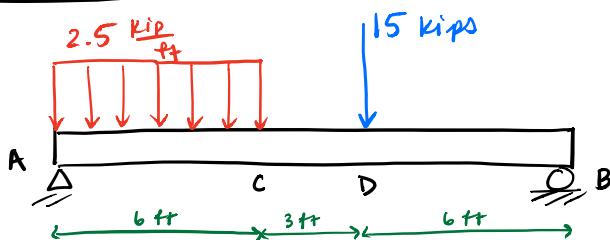
→ section A to C

$$\begin{aligned} & \text{⑥ } \sum F_y = 0 = \frac{P}{2} - P - V & V = -\frac{P}{2} \\ & \text{⑦ } \sum M_0 = 0 = M - \frac{P}{2}x_2 + P\left(x_2 - \frac{L}{2}\right) & \text{note that this differs from } \uparrow \\ & M = \frac{P}{2}(L - x_2) & \text{section AB by } P \\ & \frac{dM}{dx_2} = -\frac{P}{2} = V & \text{moment arm for conc force } P \end{aligned}$$

### Step 3: Plot Shear/Moment Diagrams



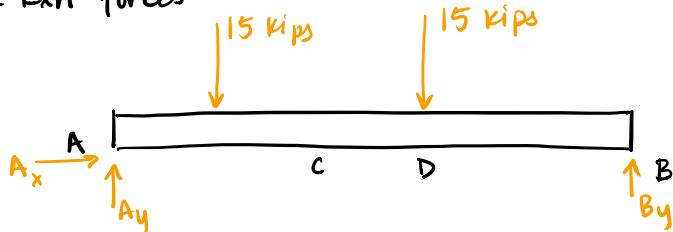
### In-class Example



Find: Maximum absolute value of shear.

Maximum absolute value of bending moment

#### 1. Rxn forces



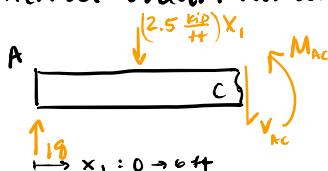
How many beam sections?  
 ① AC ② CD ③ DB

$$\textcircled{\$} \sum F_x = 0, A_x = 0$$

$$\textcircled{+} \sum M_A = 0 = -15 \text{ kip}(3 \text{ ft}) - 15 \text{ kip}(9 \text{ ft}) + B_y(15 \text{ ft}) \Rightarrow B_y = 12 \text{ kip}$$

$$\textcircled{+} \uparrow \sum F_y = 0 = A_y - 15 \text{ kips} - 15 \text{ kips} + 12 \text{ kip} \Rightarrow A_y = 18 \text{ kip}$$

#### 2. Internal shear/moment



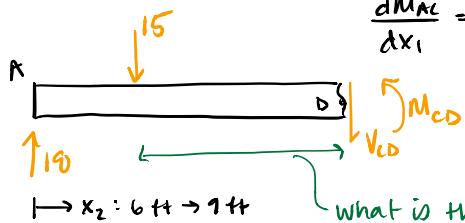
$$\textcircled{+} \uparrow \sum F_y : 18 - 2.5x_1 - V_{AC} = 0 \quad V_{AC} = 18 - 2.5x_1$$

$$\textcircled{+} G \sum M_C : M_{AC} + 2.5x_1(x_1/2) - 18(x_1) = 0$$

$$M_{AC} = 18x_1 - 1.25x_1^2$$

check  $M_{AC}$  by taking derivative:

$$\frac{dM_{AC}}{dx_1} = 18 - 2.5x_1 = V_{AC} !$$



$\mapsto x_2: 6 \text{ ft} \rightarrow 9 \text{ ft}$

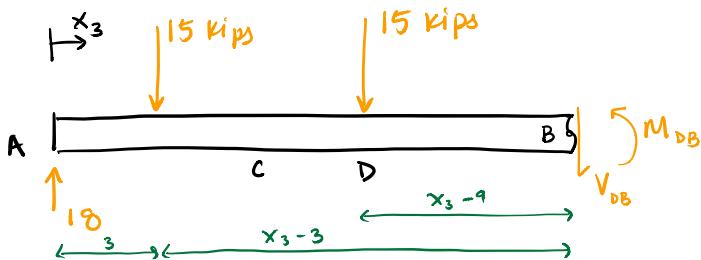
what is this distance?  
→ only goes past pt. C, gone over whole distributed load  
so this distance can be written as  $x_2 - 3$

$$\textcircled{+} \uparrow \sum F_y = 0 = 18 - 15 - V_{CD} \Rightarrow V_{CD} = 3$$

$$\textcircled{+} \curvearrowleft \sum M_B = 0 = M_{CD} + 15(x_2 - 3) - 18x_2 \Rightarrow M_{CD} = 3x_2 + 45$$

check by taking derivative...

$$\frac{dM_{CD}}{dx_2} = 3 = V_{CD}$$

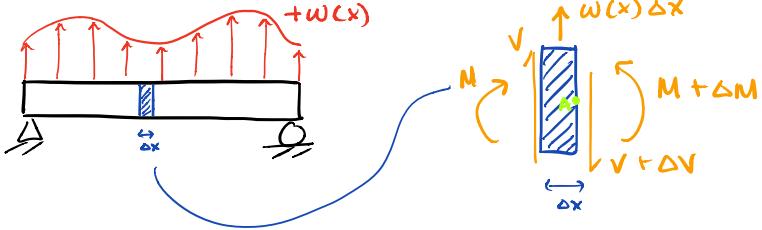


$$\textcircled{+} \uparrow \sum F_y = 0 = 18 - 15 - 15 - V_{DB} \Rightarrow V_{DB} = -12$$

$$\textcircled{+} \curvearrowleft \sum M_B = 0 = M_{DB} - 18x_3 + 15(x_3 - 3) + 15(x_3 - 9) \Rightarrow M_{DB} = -12x_3 + 180$$

$$\text{check ... } \frac{dM_{DB}}{dx_3} = -12 = V_{DB}$$

## Hibbeler 6.2: Graphical Shear/Moment Diagrams



$$\textcircled{+} \uparrow \sum F_y = 0 = V - w(x)\Delta x - (V + \Delta V)$$

$$\Delta V = w(x)\Delta x$$

$$\textcircled{+} \curvearrowleft \sum M_A = 0 = -V\Delta x - M + M + \Delta M - w(x)\Delta x \left(\frac{1}{2}\right)\Delta x$$

$$\Delta M = V\Delta x + w(x)\Delta x \left(\frac{1}{2}\right)\Delta x$$

$$\lim_{\Delta x \rightarrow 0} \frac{\Delta V}{\Delta x} = w(x)$$

$$\lim_{\Delta x \rightarrow 0} \frac{\Delta M}{\Delta x} = V + \frac{1}{2}w(x)\Delta x$$

$$\text{so... } \frac{dV}{dx} = w(x)$$

$$\text{so... } \frac{dM}{dx} = V$$

We can also rewrite equations...

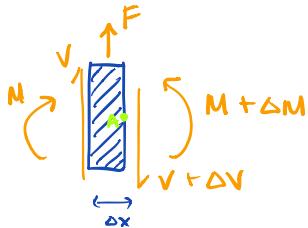
$$\Delta V = \int w(x) dx$$

change in shear = area under distributed loading

$$\Delta M = \int V(x) dx$$

change in moment = area under shear diagram

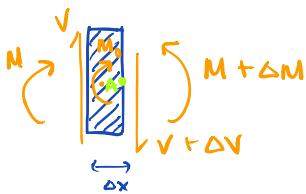
## Regions of concentrated force/moment



$$\textcircled{+} \uparrow \sum F_y = 0 = F + V - (V + \Delta V)$$

$$\Delta V = F$$

$\rightarrow$  this means that if have  $\oplus F$  applied,  $\Delta V$  jumps upward  
 $\rightarrow$  if have  $\ominus F$  applied,  $\Delta V$  jumps downward



$$\textcircled{+} \curvearrowleft \sum M_A = 0 = M + \Delta M - M_0 - M - V\Delta x$$

$$\Delta M = M_0$$

$\rightarrow$  so concentrated moment gives jump in moment diagram