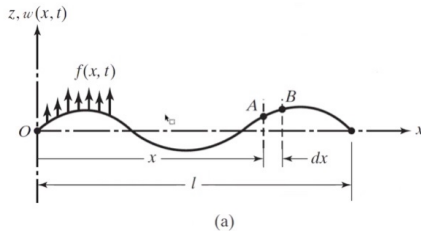


## Transverse Vibration of a String or Cable

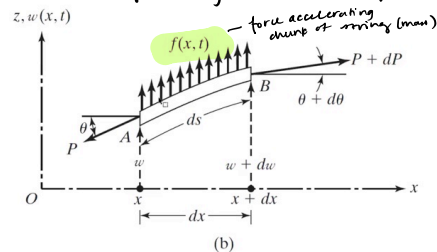
Vibrations - Lec 15

Tue., 2021-03-23

- the vibrating string is a continuous system
  - everything we've done before is a discrete system (mass, spring, dashpot, certain # of displacements you're tracking aka DoF) ... FEA
- no more linear algebra, now treat continuous system as continuous PDE



cut a chunk of string that is infinitesimally small



$ds$  is length of string  
 $dx$  is distance between end points of string

↳ if lying down on x-axis, as in string at rest and not vibrating, then  $ds = dx$

Can this string be stretched?

→ yes, but our analysis will treat this as inextensible

What could  $f(x, t)$  be? ex. drag force like on an instrument, maybe also magnetism

This equation is Newton's Law in the vertical direction for the string:

$$\uparrow \oplus \quad (P + dP) \sin(\theta + d\theta) + f dx - P \sin \theta = f dx \frac{\partial^2 w}{\partial t^2} \quad \text{(left side is forces in vertical direction, right side is } ma \text{)}$$

where  $P$  is the tension,  $f$  is mass per unit length,  $\theta$  is angle deflected string makes w/ x-axis

$$\hookrightarrow \text{for an elemental length } dx: dP = \frac{\partial P}{\partial x} dx$$

$$\hookrightarrow \sin \theta \approx \tan \theta = \frac{\partial w}{\partial x} \quad \leftarrow \text{small } \theta \text{ assumption}$$

$$\hookrightarrow \sin(\theta + d\theta) \approx \tan(\theta + d\theta) = \frac{\partial w}{\partial x} + \frac{\partial^2 w}{\partial x^2} dx \quad \leftarrow \text{almost like a Taylor series}$$

$w$  = xverse displacement of string,  $w(x, t)$   
 $f$  = xverse force per unit length,  $f(x, t)$

The Linearized Equation (most-general):  $P$  is allowed to depend on displacement

$$\frac{\partial}{\partial x} \left[ P \frac{\partial w(x, t)}{\partial x} \right] + f(x, t) = \rho(x) \frac{\partial^2 w(x, t)}{\partial t^2}$$

The Wave Equation: when  $P$  is constant

$$P \frac{\partial^2 w(x, t)}{\partial x^2} + f(x, t) = \rho \frac{\partial^2 w(x, t)}{\partial t^2}$$

\* hallmarks of wave equation:  
 2nd derivate wrt displacement on one side, 2nd derivative wrt time on other

→ if  $f(x,t) = 0$  then we obtain the free-vibration equation (no forcing)

$$\rho \frac{\partial^2 w(x,t)}{\partial x^2} = \rho \frac{\partial^2 w(x,t)}{\partial t^2}$$

⇓

$$c^2 \frac{\partial^2 w}{\partial x^2} = \frac{\partial^2 w}{\partial t^2}$$

$c$  = the speed at which your wave will travel

Let's solve this wave equation

$$c = \text{wave speed} = \sqrt{\frac{P}{\rho}} = \sqrt{\frac{F}{\mu/L}} = \sqrt{\frac{\mu L / T}{\mu/L}} = \sqrt{\frac{L^2}{T}} = \frac{L}{T} \quad \checkmark$$

Initial conditions: need to know

$$w(x, t=0) = w_0(x) \quad \leftarrow \text{initial displacement}$$

$$\frac{\partial w}{\partial t}(x, t=0) = \dot{w}_0(x) \quad \leftarrow \text{initial velocity}$$

(we're assuming that the string is pinned at both ends @  $t=0$ )

Boundary conditions:

$$w(x=0, t) = w(x=L, t) = 0$$

Separation of Variables:  $w(x, t)$

make a guess:  $w(x, t) = W(x) T(t)$  ← make two separate functions multiplied by each other that each take one variable (note that not every function can do this, such as  $x^t$  or  $\log_x t$ )

$$\frac{\partial^2 w}{\partial x^2} = W'' T$$

$$\frac{\partial^2 w}{\partial t^2} = W T''$$

plug them into our wave equation

$$c^2 W'' T = W T'' \quad \left( \text{we want dependence on } x \text{ on one side, dependence on } t \text{ on other side} \right)$$

$$c^2 \frac{W''(x)}{W(x)} = \frac{T''(t)}{T(t)}$$

↑  
true for all  $x$  from 0 to  $L$

↑  
true for time @ zero and on

∴  
what if we call this ratio a constant  $a$ ?

... then  $a$  must also be equal to the time ratio

...  $a$  is a "separation constant"

So now we've taken a PDE and split it into 2 ODE's

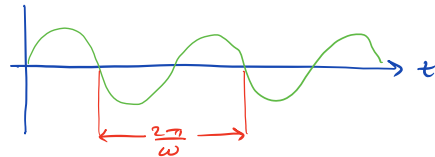
$$c^2 \frac{W''}{W} = a \Rightarrow c^2 W'' - aW = 0 \quad (\text{a displacement equation})$$

$$\frac{T''}{T} = a \Rightarrow T'' - aT = 0 \quad (\text{a time equation})$$

↑ we typically see  $\omega^2$  here...  
 set  $a = -\omega^2$  ← this is omega, as in  $\omega = \text{rad/s}$

$$T'' + \omega^2 T = 0$$

↑ to omega is the frequency of this function:  
 ↗ to the time equation →  $T(t) = C \cos \omega t + D \sin \omega t$



$$W'' + \frac{\omega^2}{c^2} W = 0$$

↑  
 $W(x) = A \cos\left(\frac{\omega x}{c}\right) + B \sin\left(\frac{\omega x}{c}\right)$  ← to the spatial equation

In Acoustics (not in book):

$$k = \frac{\omega}{c} \quad \text{aka the "wave number"}$$

$$\begin{aligned} W(x) &= A \cos(kx) + B \sin(kx) \\ T(t) &= C \cos(\omega t) + D \sin(\omega t) \end{aligned}$$

$$\begin{array}{ccc} x & \longleftrightarrow & t \\ \left(\frac{1}{m}\right) k & & \omega \left(\frac{\text{rad}}{s}\right) \end{array}$$

remember, can't take -sine or cosine of a dimensional #

$$\text{Period} : \frac{2\pi}{\omega}$$

↑ the wavelength  $\lambda$  is the analogous in the spatial domain  
 $\Rightarrow \lambda = \frac{2\pi}{k}$

