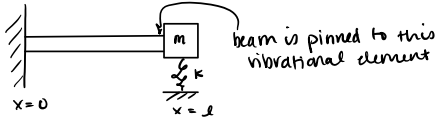
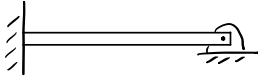


Assignment #7 last minute notes:

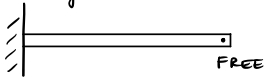
Vibrations - Lecture 22
Thur. 2021-04-15



if k or m are infinite

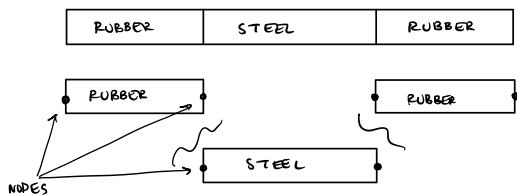


if k or $m = 0$



~ Rao Ch. 12 ~

FINITE ELEMENT METHOD

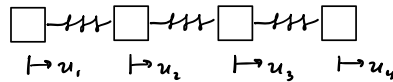


what are the boundary conditions?

← break up into three pieces to find boundary conditions ... this is essentially FEM

NODE in FEM: pt where you node something

↳ not unlike:



$$[m] \ddot{\vec{u}} + [k] \vec{u} = \vec{0}$$

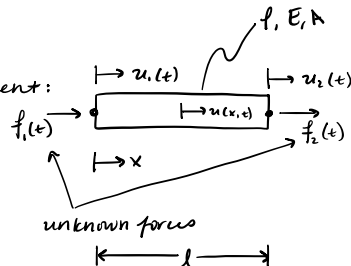
smaller element size leads to more accurate model → MESHING

h-p adaptive

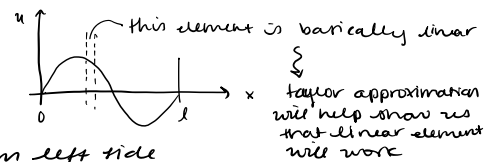
↳ polynomial order
↳ element size

~ Section 12.3 ~

uniform bar element:



... we'll make mass + stiffness matrices for one element



Approximation $u(x, t) = a(t) + b(t)x$
linear element

x = distance from left side
 a, b = coefficients that are time-dependent

$$u(x=0, t) = u_1(t) = a(t)$$

$$u(x=l, t) = u_2(t) = a(t) + b(t)l$$

\uparrow
 $u_1(t)$

solve for $b(t)$:

$$b(t) = (u_2(t) - u_1(t)) / l$$

substitute $a(t)$ & $b(t)$ into $u(x, t)$:

$$u(x, t) = \left(1 - \frac{x}{l}\right) u_1(t) + \left(\frac{x}{l}\right) u_2(t)$$

$$u(x, t) = N_1(x) u_1(t) + N_2(x) u_2(t)$$

$$N_1(x) = 1 - x/l \quad N_2(x) = x/l \quad N_1 + N_2 \text{ are shape functions}$$

What would be the kinetic energy, T , of this bar?

$$T = \frac{1}{2} \int_0^l \rho A \left(\frac{\partial u(x, t)}{\partial t} \right)^2 dx$$

\uparrow
 velocity
 like $\frac{1}{2}mv^2$

substitute u for the expression we have above:

$$T = \frac{1}{2} \int_0^l \rho A \left[\left(1 - \frac{x}{l}\right) \dot{u}_1 + \left(\frac{x}{l}\right) \dot{u}_2 \right]^2 dx$$

$$\rightarrow \text{side note: } \int_0^l \left(1 - \frac{x}{l}\right)^2 dx = \int_0^l \left(1 - 2\frac{x}{l} + \frac{x^2}{l^2}\right) dx = \left(x - \frac{x^2}{l} + \frac{1}{3} \frac{x^3}{l^2}\right) \Big|_0^l = l - l + \frac{1}{3}l = \frac{1}{3}l$$

$$\int_0^l 2\left(1 - \frac{x}{l}\right)\left(\frac{x}{l}\right) dx = 2 \int_0^l \left(\frac{x}{l} - \frac{x^2}{l^2}\right) dx = 2 \left(\frac{x^2}{2l} - \frac{x^3}{3l^2}\right) \Big|_0^l = l - \frac{2}{3}l = \frac{1}{3}l$$

$$\int_0^l \left(\frac{x}{l}\right)^2 dx = \int_0^l \frac{x^2}{l^2} dx = \frac{x^3}{3l^2} \Big|_0^l = \frac{1}{3}l$$

\rightarrow back to T :

$$T = \frac{1}{2} \rho A \frac{1}{3} (\dot{u}_1^2 + \dot{u}_1 \dot{u}_2 + \dot{u}_2^2) \quad \dot{\vec{u}}(t) = \begin{Bmatrix} \dot{u}_1 \\ \dot{u}_2 \end{Bmatrix}$$

$$T = \frac{1}{2} \dot{\vec{u}}^T [M] \dot{\vec{u}} \quad \uparrow \text{find } [M] \text{ based on this}$$

$$= \frac{1}{2} [\dot{u}_1 \quad \dot{u}_2] \begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{Bmatrix} \dot{u}_1 \\ \dot{u}_2 \end{Bmatrix} = \frac{1}{2} [\dot{u}_1 \quad \dot{u}_2] \begin{Bmatrix} m_{11}\dot{u}_1 + m_{12}\dot{u}_2 \\ m_{21}\dot{u}_1 + m_{22}\dot{u}_2 \end{Bmatrix}$$

$$= \frac{1}{2} (m_{11}\dot{u}_1^2 + m_{12}\dot{u}_1\dot{u}_2 + m_{21}\dot{u}_1\dot{u}_2 + m_{22}\dot{u}_2^2)$$

now match the coefficients w/ $T = (\frac{1}{2}) \rho A (\frac{l}{3}) (\dot{u}_1^2 + \dot{u}_1 \dot{u}_2 + \dot{u}_2^2)$

$$T = \frac{1}{2} (m_{11} \dot{u}_1^2 + m_{12} \dot{u}_1 \dot{u}_2 + m_{21} \dot{u}_1 \dot{u}_2 + m_{22} \dot{u}_2^2)$$

$$\therefore m_{11} = \rho A \left(\frac{l}{3}\right) \quad m_{22} = \rho A \left(\frac{l}{3}\right) \quad \text{and} \quad m_{12} + m_{21} = \frac{\rho A l}{3}$$

so to make the mass matrix symmetric, we say m_{12} and m_{21} are equal

\therefore the mass matrix is:

$$[m] = \frac{\rho A l}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$