Critério de Sassenfeld: $S_1 = \frac{1}{|a_{11}|} (|a_{12}| + |a_{13}| + |a_{14}| + \cdots + |a_{1n}|),$

$$S_{2} = \frac{1}{|a_{22}|} (|a_{21}|S_{1} + |a_{23}| + |a_{24}| + \dots + |a_{2n}|), \qquad S_{3} = \frac{1}{|a_{33}|} (|a_{31}|S_{1} + |a_{32}|S_{2} + |a_{34}| + \dots + |a_{3n}|), \dots$$

$$\dots S_{n} = \frac{1}{|a_{nn}|} (|a_{n1}|S_{1} + |a_{n2}|S_{2} + \dots + |a_{nn-1}|S_{n-1})$$

Método de Newton para sistemas: $x_{i+1} = x_i - \left[\frac{f g_y - g f_y}{|J|}\right]_i$, $y_{i+1} = y_i - \left[\frac{g f_x - f g_x}{|J|}\right]_i$ $|J| = (f_x g_y - f_y g_x)_i$

Interpolação polinomial (Lagrange):
$$p_n(x) = y_0L_0(x) + y_1L_1(x) + \cdots + y_nL_n(x)$$

$$L_k(x) = \frac{(x - x_0)(x - x_1) \dots (x - x_{k-1})(x - x_{k+1}) \dots (x - x_n)}{(x_k - x_0)(x_k - x_1) \dots (x_k - x_{k-1})(x_k - x_{k+1}) \dots (x_k - x_n)}$$

Interpolação polinomial (Newton - diferenças divididas):

$$p_n(x) = d_0 + d_1(x - x_0) + d_2(x - x_0)(x - x_1) + \dots + d_n(x - x_0)(x - x_1) \dots (x - x_{n-1}) \text{ onde}$$

$$d_k = f[x_k, x_{k-1}, \dots, x_0]$$

$$f[x_i] = f(x_i), \quad f[x_{i+1}, x_i] = \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i}, \quad f[x_{i+2}, x_{i+1}, x_i] = \frac{f[x_{i+2}, x_{i+1}] - f[x_{i+1}, x_i]}{x_{i+2} - x_i}$$

Interpolação polinomial (Newton - diferenças simples):

$$p_n(x) = y_0 + \frac{x - x_0}{h} \Delta y_0 + \frac{(x - x_0)(x - x_1)}{2! h^2} \Delta^2 y_0 + \dots + \frac{(x - x_0)(x - x_1) \dots (x - x_{n-1})}{n! h^n} \Delta^n y_0$$

$$\Delta y_i = y_{i+1} - y_i, \quad \Delta^2 y_i = \Delta y_{i+1} - \Delta y_i = y_{i+2} - 2 y_{i+1} + y_i, \quad \Delta^k y_i = \Delta^{k-1} y_{i+1} - \Delta^{k-1} y_i$$

Estimativas de erro para o polinômio interpolador:

$$|E_n(x)| \le |(x - x_0)(x - x_1)(x - x_2)\dots(x - x_n)| \max_{x \in I} \frac{|f^{(n+1)}(x)|}{(n+1)!},$$

$$|E_n(x)| \approx |(x - x_0)(x - x_1)\dots(x - x_n)| |f[x_{n+1}, x_n, \dots, x_0]|,$$

$$|E_n(x)| \approx |(x - x_0)(x - x_1)\dots(x - x_n)| \left|\frac{\Delta^{n+1}y_0}{(n+1)! h^{n+1}}\right|$$

Spline Cúbica

$$S_{i}(x) = f(x_{i}) + (x - x_{i})(c_{i} + (x - x_{i})(b_{i} - (x - x_{i})a_{i}))$$

$$z_{i-1} + 4z_{i} + z_{i+1} = \frac{6}{h^{2}}(y_{i+1} - 2y_{i} + y_{i-1}), \text{ para } i = 1, 2, \dots, n-1 \text{ e } z_{0} = z_{n} = 0$$

$$a_{i} = \frac{1}{6h}(z_{i+1} - z_{i})$$

$$b_{i} = \frac{z_{i}}{2}$$

$$c_{i} = -\frac{h}{6}z_{i+1} - \frac{h}{3}z_{i} + \frac{y_{i+1} - y_{i}}{h}$$

Mínimos quadrados: $g(x) = \sum_{k=0}^{m} a_k g_k(x)$

 $\textbf{Ajustamento a um polinômio de grau p:} \begin{vmatrix} n+1 & \sum\limits_{i=0}^{n} x_i & \dots & \sum\limits_{i=0}^{n} x_i^p \\ \sum\limits_{i=0}^{n} x_i & \sum\limits_{i=0}^{n} x_i^2 & \dots & \sum\limits_{i=0}^{n} x_i^{p+1} \\ \vdots & \vdots & & \vdots \\ \sum\limits_{i=0}^{n} x_i y_i \end{vmatrix} = \begin{vmatrix} \sum\limits_{i=0}^{n} y_i \\ a_1 \\ \vdots \\ a_p \end{vmatrix} = \begin{vmatrix} \sum\limits_{i=0}^{n} x_i y_i \\ \vdots \\ a_p \end{vmatrix}$