



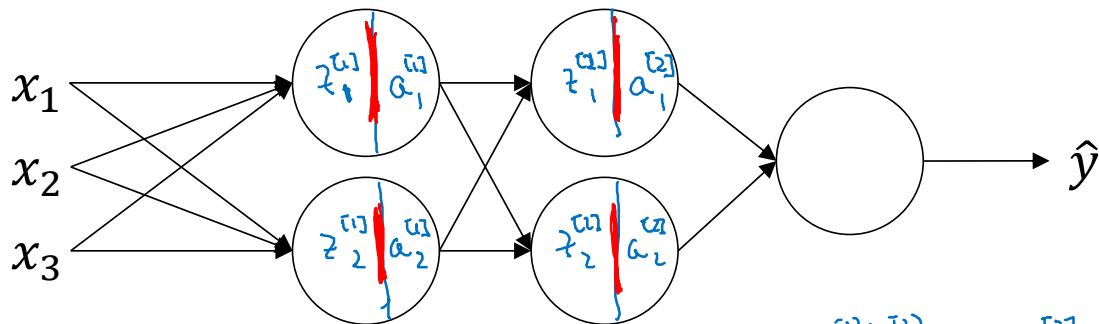
deeplearning.ai

# Batch Normalization

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Fitting Batch Norm  
into a neural network

# Adding Batch Norm to a network



$$x \xrightarrow{w^{[1]}, b^{[1]}} \underline{z^{[1]}} \xrightarrow[\text{Batch Norm (BN)}]{\beta^{[1]}, \gamma^{[1]}} \underline{z^{[1]}} \xrightarrow{w^{[1]}, b^{[1]}} \underline{a^{[1]} = g(z^{[1]})} \xrightarrow{w^{[2]}, b^{[2]}} \underline{z^{[2]}} \xrightarrow[\text{BN}]{\beta^{[2]}, \gamma^{[2]}} \underline{z^{[2]}} \xrightarrow{w^{[2]}, b^{[2]}} \underline{a^{[2]} \rightarrow \dots}$$

Parameters:  $\left\{ w^{[1]}, b^{[1]}, w^{[2]}, b^{[2]}, \dots, w^{[L]}, b^{[L]} \right\}$   
 $\rightarrow \underline{\beta^{[1]}, \gamma^{[1]}, \beta^{[2]}, \gamma^{[2]}, \dots, \beta^{[L]}, \gamma^{[L]}}$   
 $\rightarrow \underline{\beta}$

$$d\beta^{[L]} \quad \beta = \beta - \alpha d\beta^{[L]}$$

tf.nn.batch-normalization ←

# Working with mini-batches

$$\tilde{X}^{\{1\}} \xrightarrow{W^{(1)}, b^{(1)}} z^{(1)} \xrightarrow[\text{BN}]{\beta^{(1)}, \gamma^{(1)}} \tilde{z}^{(1)} \rightarrow g^{(1)}(\tilde{z}^{(1)}) = a^{(1)} \xrightarrow{W^{(2)}, b^{(2)}} z^{(2)} \rightarrow \dots$$

$$\boxed{X^{\{2\}}} \rightarrow \underline{z^{(2)}} \xrightarrow[\text{BN}]{\beta^{(2)}, \gamma^{(2)}} \underline{\tilde{z}^{(2)}} \rightarrow \dots$$

$$X^{\{2\}} \rightarrow \dots$$

Parameters:  $W^{(1)}, \cancel{b^{(1)}}, \beta^{(1)}, \gamma^{(1)}$

$\uparrow$   $(n^{(1)}, 1)$       $\uparrow$   $(n^{(1)}, 1)$       $\uparrow$   $(n^{(1)}, 1)$

$$\tilde{z}^{(1)} \uparrow (n^{(1)}, 1)$$

no point

$$\rightarrow \underline{\tilde{z}^{(1)}} = W^{(1)} a^{(1-1)} + \cancel{b^{(1)}}$$

$\uparrow$

$$\tilde{z}^{(1)} = W^{(1)} a^{(1-1)}$$

$$\rightarrow \tilde{z}^{(1)}_{\text{norm}} = \gamma^{(1)} z_{\text{norm}} + \boxed{\beta^{(1)}}$$

# Implementing gradient descent

for  $t = 1 \dots \text{num Mini Batches}$

Compute forward pass on  $X^{\{t\}}$ .

In each hidden layer, use BN to repair  $\underline{z}^{\{t\}}$  with  $\underline{\hat{z}}^{\{t\}}$ .

Use backprop to compute  $\underline{dw}^{\{t\}}$ ,  ~~$\underline{db}^{\{t\}}$~~ ,  $\underline{d\beta}^{\{t\}}$ ,  $\underline{df}^{\{t\}}$

Update params 
$$\left. \begin{aligned} W^{\{t\}} &:= W^{\{t\}} - \alpha \underline{dw}^{\{t\}} \\ \beta^{\{t\}} &:= \beta^{\{t\}} - \alpha \underline{d\beta}^{\{t\}} \\ \gamma^{\{t\}} &:= \dots \end{aligned} \right\}$$

Can Works w/ momentum, RMSprop, Adam.