Springer Handbooks provide a concise compilation of approved key information on methods of research, general principles, and functional relationships in physical sciences and engineering. The world's leading experts in the fields of physics and engineering will be assigned by one or several renowned editors to write the chapters comprising each volume. The content is selected by these experts from Springer sources (books, journals, online content) and other systematic and approved recent publications of physical and technical information.

The volumes are designed to be useful as readable desk reference books to give a fast and comprehensive overview and easy retrieval of essential reliable key information, including tables, graphs, and bibliographies. References to extensive sources are provided.

Springer

of Robotics

Bruno Siciliano, Oussama Khatib (Eds.)

With DVD-ROM, 953 Figures, 422 in four color and 84 Tables

