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10 – 13 December 2020

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Learning 3D Functionality Representations

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Speakers



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Learning 3D Functionality Representations

- What is this course about?
 - Cover recent developments that incorporate **functionality** considerations into **shape analysis** in **computer graphics**
 - For the analysis of **3D objects** and **scenes**
 - Discuss work **in learning 3D representations for functionality** and its connections to **deep learning, computer vision, and robotics**
 - Course targeted at **researchers** and **students**



Learning 3D Functionality Representations

- Differences to our SIGGRAPH Asia 2016 course on *Directions in Shape Analysis towards Functionality*:
 - We provide an **organizational framework** to classify prior work
 - We connect functionality to recent works **on learned 3D representations**, especially to connect it to deep learning, computer vision, and robotics



Outline

- Introduction
 - Concept of functionality
 - Motivation: semantics versus functionality in shape analysis
 - Example applications
- Overview of the remaining sections of the course



Course material

- The course material is available at our course Web page:

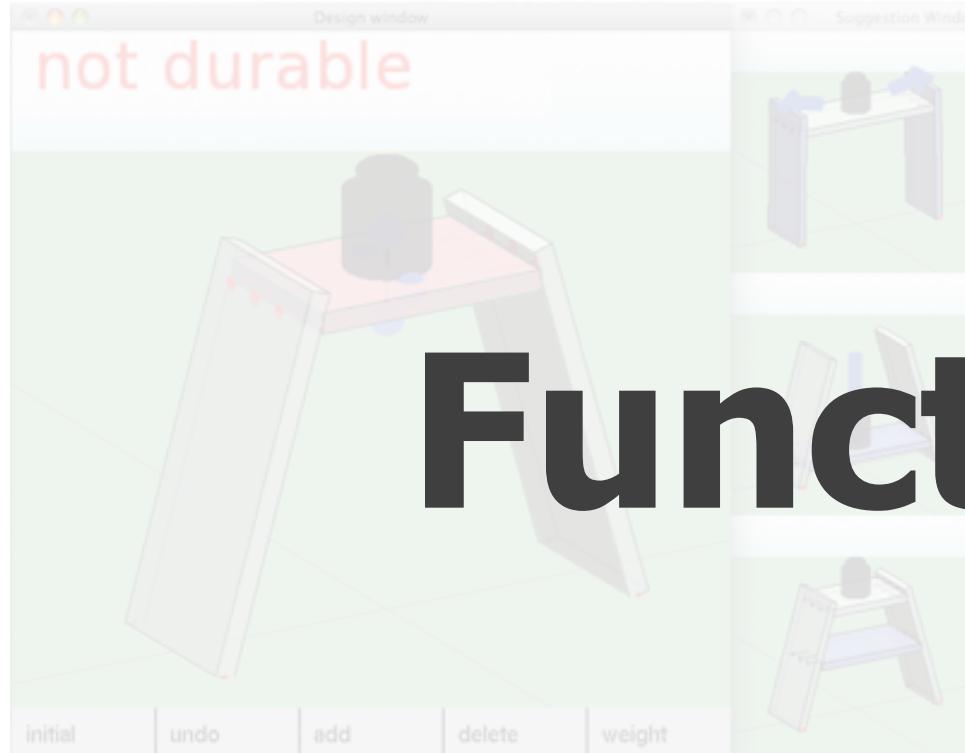
<https://learn3dfunc.github.io/>



Introduction



Shape design and simulation



Functionality

Furniture Design
[UIM12]



Motion simulation
[HLK*17]

What is functionality?

- “The particular use for which an object is designed”

-- [Merriam-Webster dictionary]



What is functionality?

- “The application of an object in a specific context for the accomplishment of a particular purpose” [BB95]



Object recognition vs. functionality recognition



What is this? → Chair

What can we do with this?



Chair



Handcart



Drying Rack

...

Object recognition vs. functionality recognition

- “The essential definition of object classes is functional”



Handcart



Table



Shape analysis and semantics

Several approaches related to **shape understanding**

- Structure-aware shape processing
- Symmetry detection
- Data-driven shape analysis
- Generative models



Shape analysis and semantics

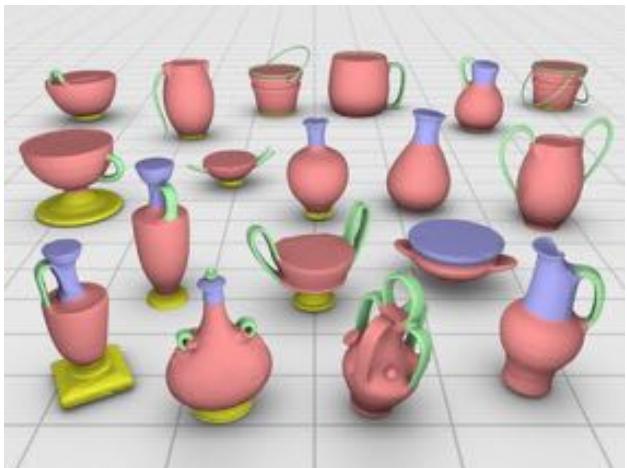
Methods covered in **previous** courses, tutorials, and STARs:

- Symmetry in 3D geometry: Extraction and applications [[MPWC12](#)]
- Structure-aware shape processing [[MWZ*13](#)]
- Data-driven shape analysis and processing [[XKHK17](#)]
- Modeling and remodeling 3D worlds [[YYAZ17](#)]
- Learning generative models of 3D structures [[CXRZ19](#)]

Shape analysis and semantics

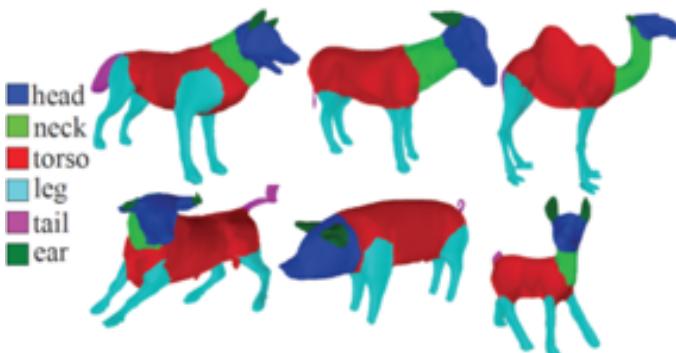
Three general **problems** related to **functionality** analysis:

Unsupervised
segmentation



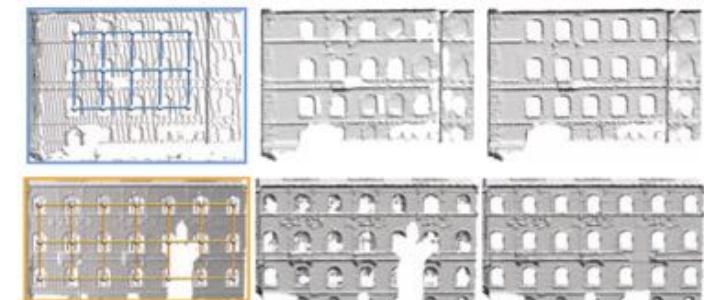
[SvKK*11]

Supervised
segmentation



[KHS10]

Symmetry
detection



[PMW*08]

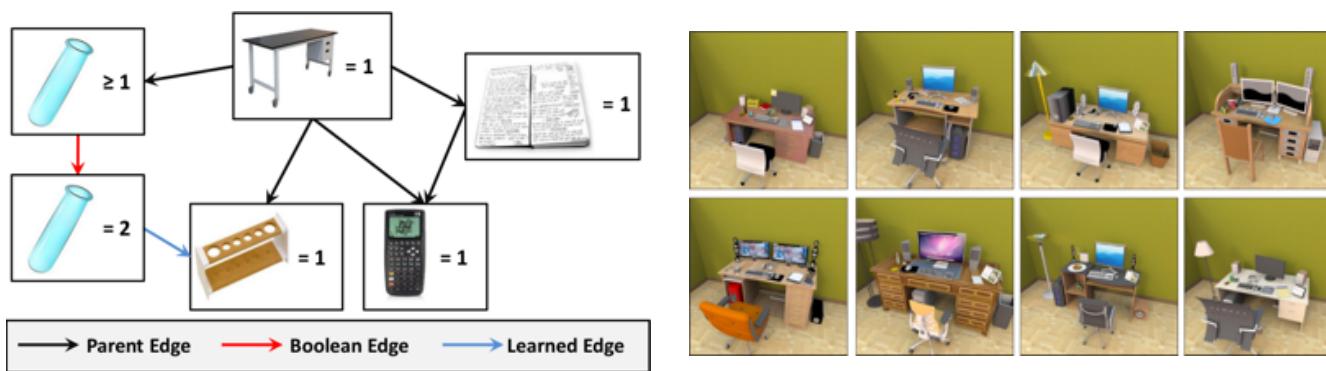
Discussion

- Co-segmentation, symmetry analysis, and classification provide **part labels** and/or **correspondences** among shape **parts**
- Corresponding parts *likely* possess the same **functionality**
- There is some **relation** between **labels** and certain types of **functionality**, e.g., *chair seat* versus *sitting*
- Can constitute a **preliminary analysis** of functionality

Discussion

- Difficult to infer the true **functional similarity**
- Analysis based only on **geometry** and **structural similarity**
- The **functionality** is not directly **named** or **categorized**

Learning generative models of 3D structures



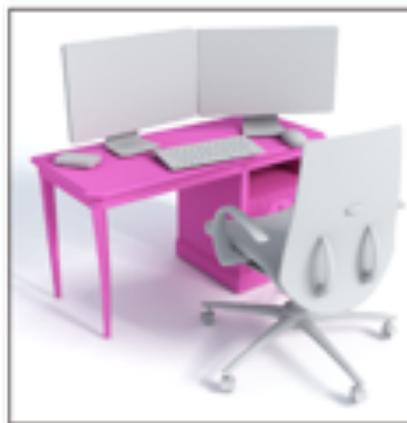
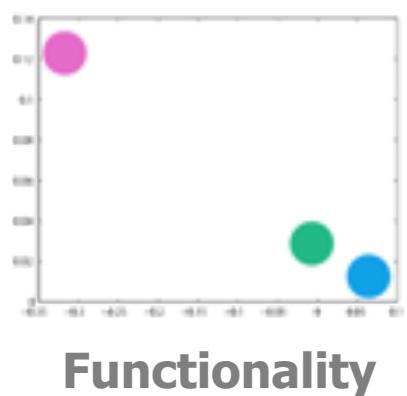
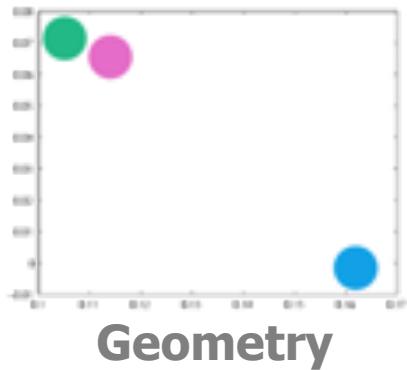
[FRS*12]

Discussion

- Synthesis performed based on **geometric** and/or **structural** similarity of the shapes
- Synthesized shapes **resemble** exemplars in the training data
- Functionality preservation is **not** enforced nor guaranteed

Functionality vs. geometry

- Difference between “geometric appearance” and “functionality”



Challenges in functionality analysis

- Hard to handle large structural variations



Handcart



Table

Challenges in functionality analysis

- Hard to handle large **structural variations**
- Hard to establish the **connection** between **structure** and **functionality**



Modern chair by Valerie Everett



Halo modern chair by Michael Sodeau

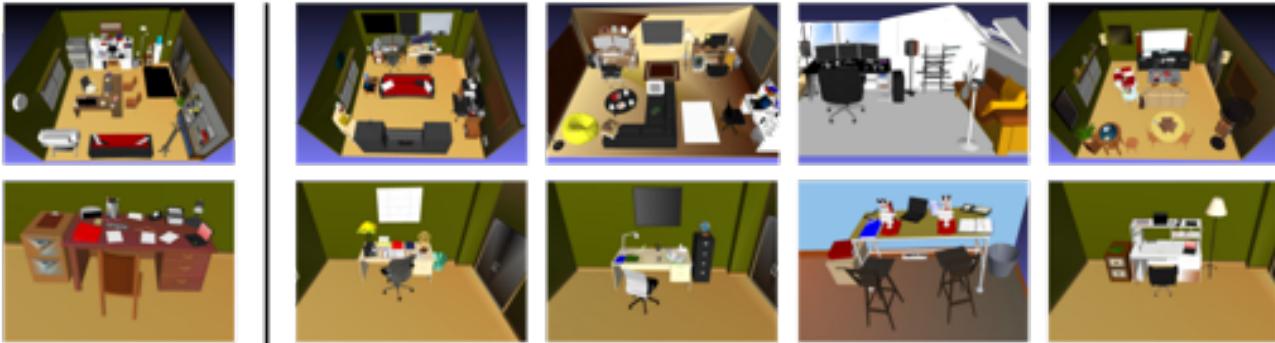


Functionality-aware processing

- **Shape analysis can benefit from functionality**
 - Incorporate a model of shape functionality to analyze and process 3D objects and scenes
- **Why?**
 - Several applications motivate this goal...

Functionality-aware applications

- Object and scene retrieval
- Scene synthesis
- Modeling and editing
- ...



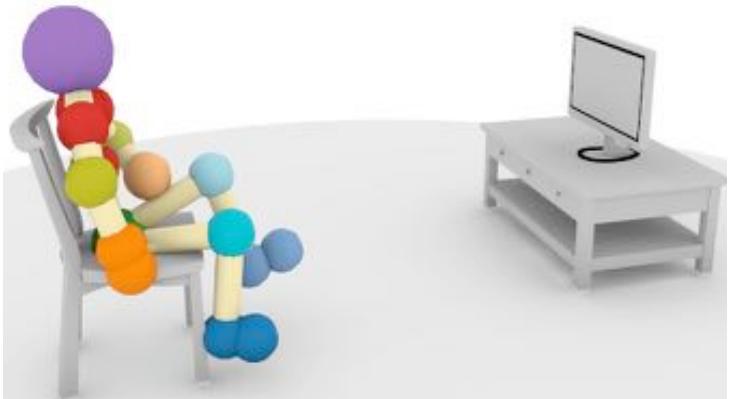
Scene retrieval [SCH*14]



Object-in-scene retrieval
[HZvK*15]

Functionality-aware applications

- Object and scene retrieval
- **Scene synthesis**
- Modeling and editing
- ...



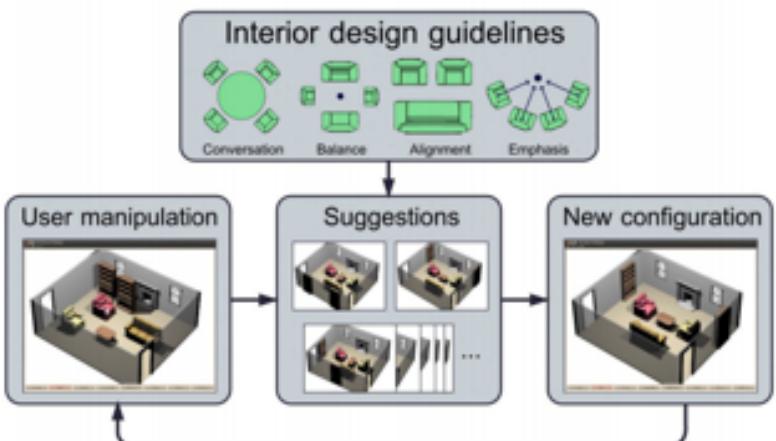
Human interaction synthesis
[SCH*16]



3D scene synthesis
[FSL*15]

Functionality-aware applications

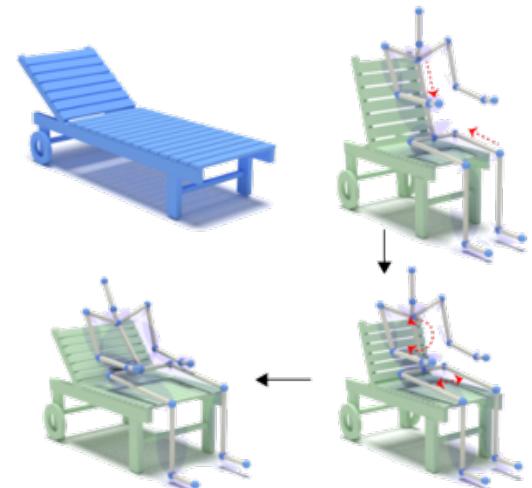
- Object and scene retrieval
- Scene synthesis
- **Modeling and editing**
- ...



Scene editing
[MSL*11]



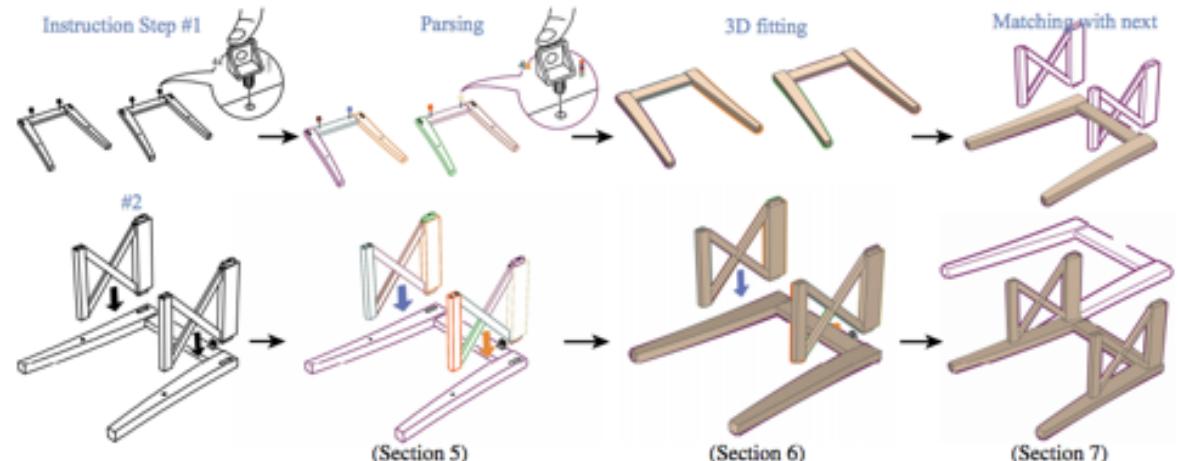
Object hybrid
[HvKW*16]



Object modeling
[ZLDM16]

Functionality-aware applications

- Computer graphics is highly related to the virtual **prototyping** and mass **customization** revolution
- In **prototyping** and **customization**, an understanding of functionality is essential!
- A **fundamental problem**
- Still much to be done...



[SLR*16]

Functionality analysis in computer vision and robotics



Input RGB-D



Grasp detection

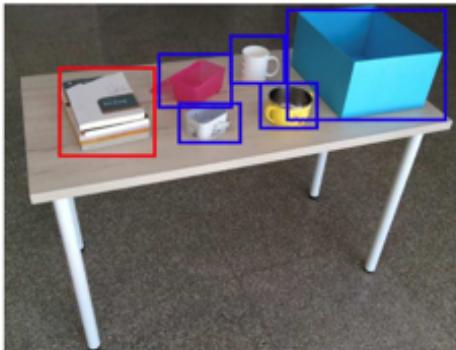


Scoop detection

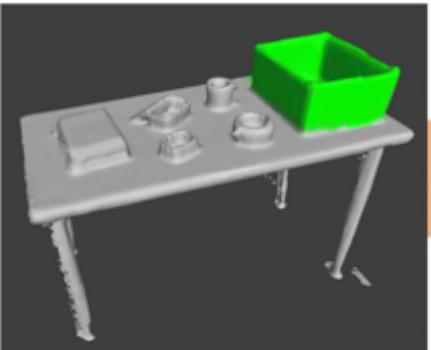


Support detection

Tool Affordance Detection [[MTFA15](#)]



(a) task

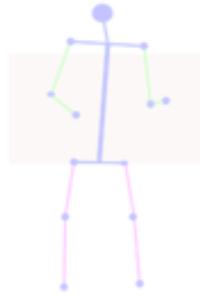


(b) solution

Transferring Objects [[WLY17](#)]



banjo



play



hand truck



push

Knowledge Base
[[ZFFF14](#)]



What is this course about?

- The goal of this course
 - To provide a comprehensive survey of **functionality analysis** in **computer graphics** and related areas such as **computer vision**
- Audience
 - **Researchers** in graphics/vision
- Criteria
 - General **definition** of functionality



Research questions

- How to **represent** functionality?
- How to derive a functionality **model** from such representations?
- How to incorporate functionality models into **shape analysis** and **modeling**?
- How to **learn** such models?
- How to do all of this **efficiently**?
- ...



Research questions

- In this course, we will provide a sampler of different **solutions** to these **questions** as given by existing work
- For various **problem domains** and targeting **diverse applications**



Outline

- Our definition of functionality ([Oliver](#))
- Classification of prior works ([Ruizhen + Manolis](#))
- Functionality-aware applications + future directions ([Manolis](#))

Definition of functionality and classification criteria





Definition of functionality

- **Functionality:** use or purpose of an object
- “Function is the action for which a person or thing is specially fitted or used, or for which a thing exists (purpose)” [[Merriam-Webster](#)]
- “Functionality is the application of an object in a specific context for the accomplishment of a particular purpose” [[BB95](#)]



Our definition of functionality

Goals:

- **Constructive definition** of functionality
- Serve as a **classification guide** for existing work
- Define the functionality of an **entity**



Our definition of functionality

We follow our definition proposed in the following paper:

- Ruizhen Hu, Manolis Savva, and Oliver van Kaick,
“Functionality Representations and Applications for Shape Analysis”, *Computer Graphics Forum (Eurographics State-of-the-art report)*, vol. 37, n. 4, pp. 603-624, 2018.

Our definition of functionality

Functionality = Geometry + Interaction



Our definition of functionality

Functionality = **Geometry** + Interaction



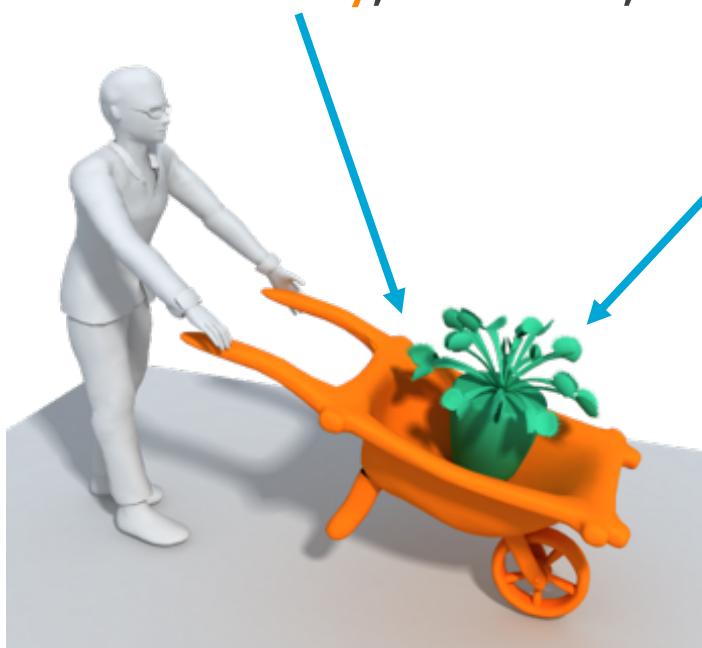
"Form follows function" [Sul96]

Our definition of functionality

Functionality = Geometry + Interaction

Atomic interaction:

<Functional entity, relation, interacting entity>

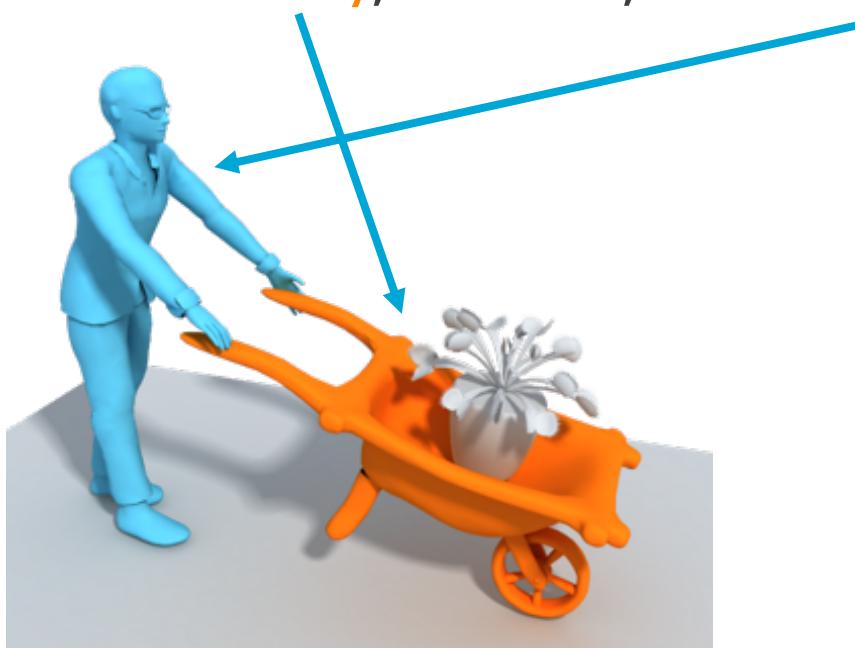


Our definition of functionality

Functionality = Geometry + Interaction

Atomic interaction:

<Functional entity, relation, interacting entity>





Components of atomic interactions

- Type of **entity**
- Level of **entity**
- Type of **relation**
- Representation of the **relation**

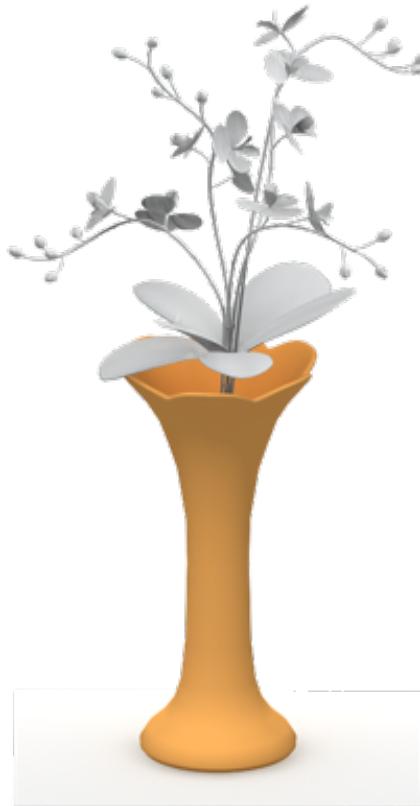


Type of entity

- Static entity
- Dynamic entity
- Human(-oid) agent

Type of entity

- **Static entity**
- Dynamic entity
- Human(-oid) agent



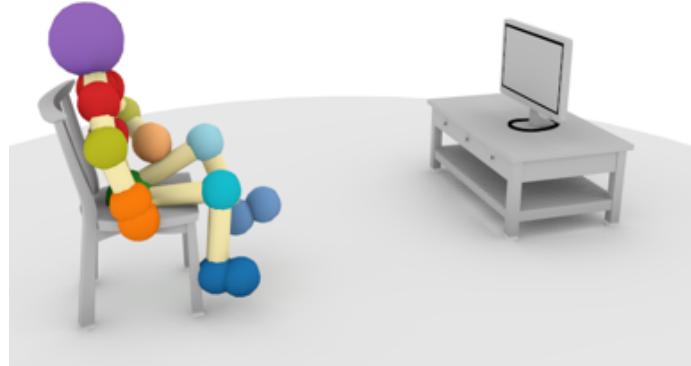
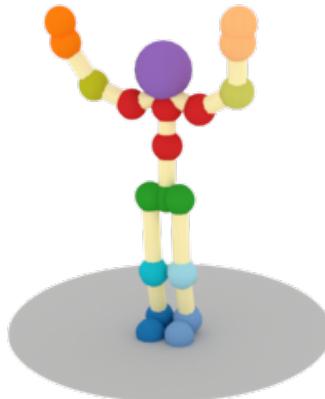
Type of entity

- Static entity
- **Dynamic entity**
- Human(-oid) agent



Type of entity

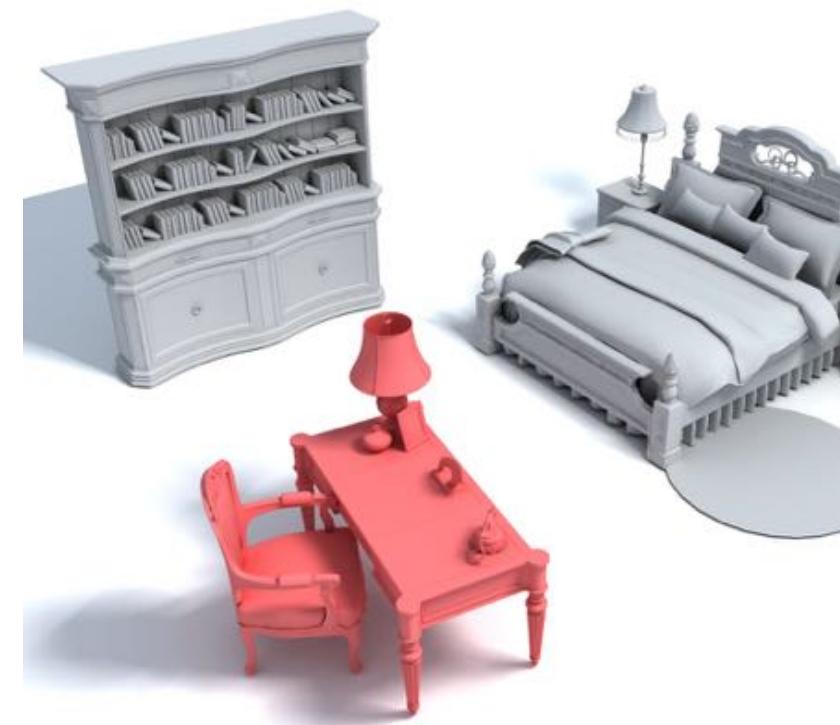
- Static entity
- Dynamic entity
- Human(-oid) agent



Level of entity



Scene



Multi-object

Type of relation

- Atemporal
- Time-varying

Type of relation

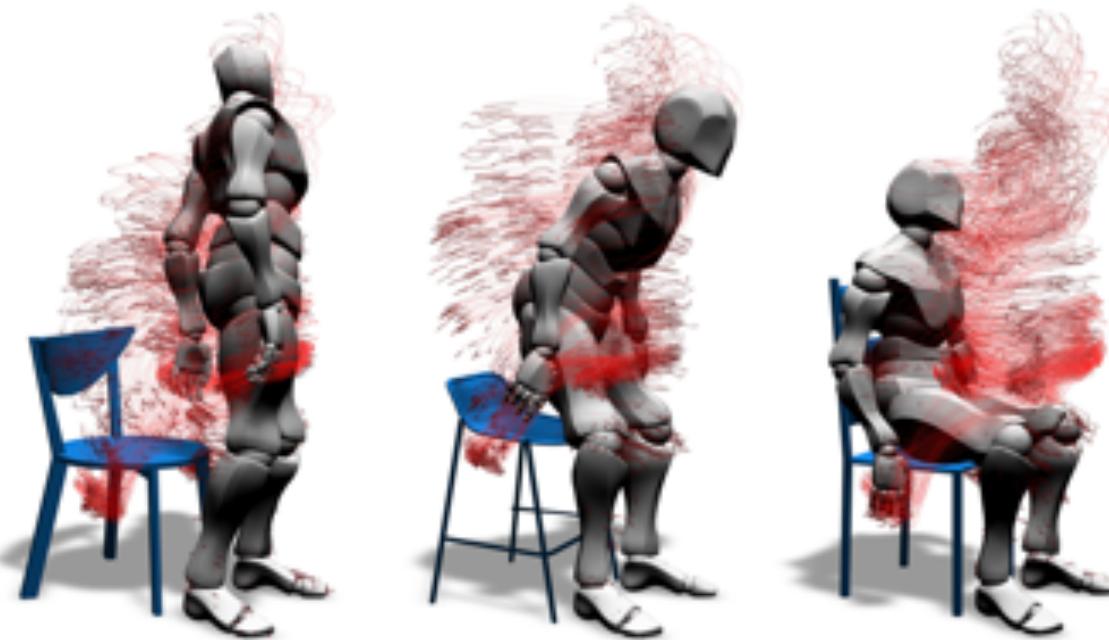
- Atemporal
- Time-varying



- ICON descriptor [HZvK*15]

Type of relation

- Atemporal
- **Time-varying**



- Interaction landscapes [PKH*17]

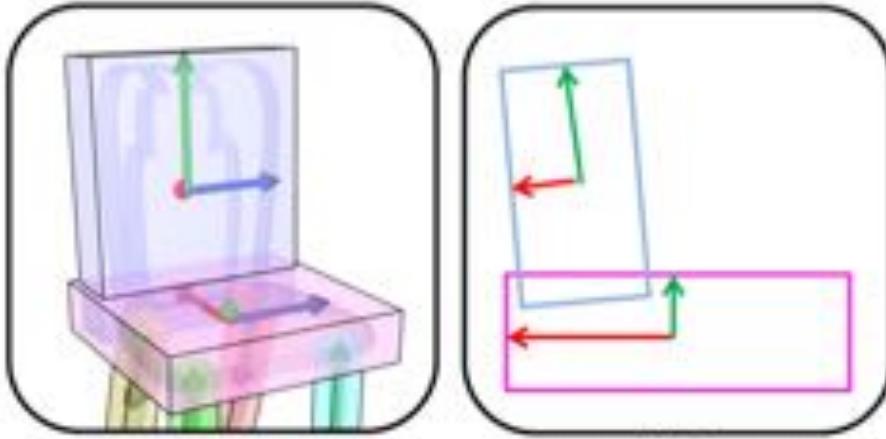


Representation of the relation

- Spatial arrangement
- Boundary representation
- Dense volume feature
- Gestalt and symmetry grouping
- Mechanical relations
- Humanoid actions

Representation of the relation

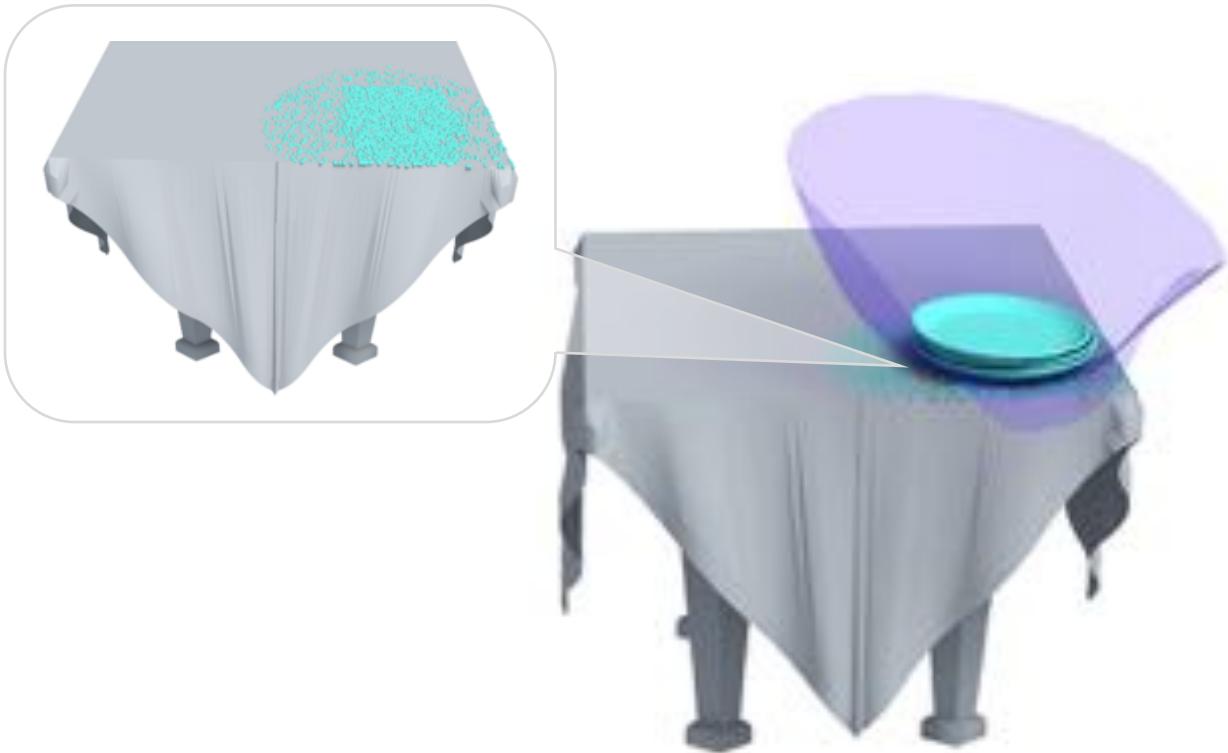
- **Spatial arrangement**
- Boundary representation
- Dense volume feature
- Gestalt and symmetry grouping
- Mechanical relations
- Humanoid actions



- Relative position
- Co-occurrence
- Gravitational support
- Attachment
- Enclosure
- RAID descriptor [GMW16]

Representation of the relation

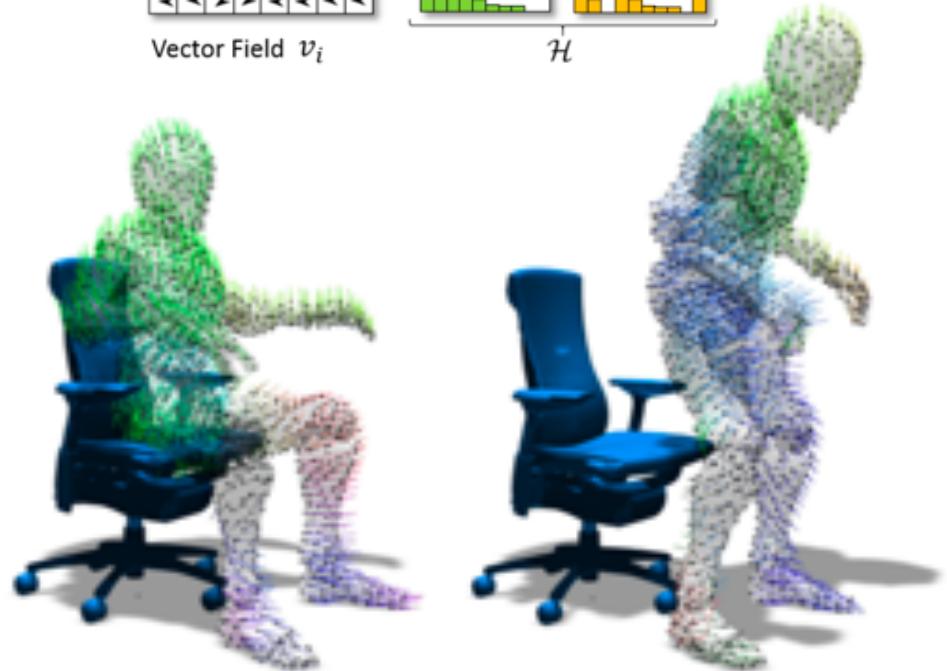
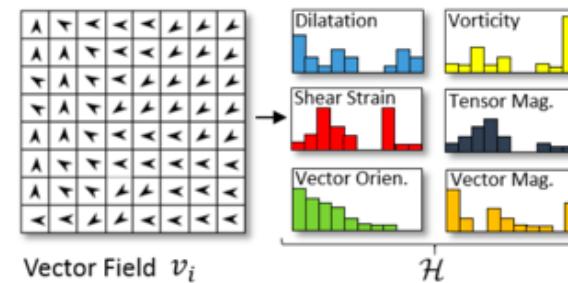
- Spatial arrangement
- **Boundary representation**
- Dense volume feature
- Gestalt and symmetry grouping
- Mechanical relations
- Humanoid actions



- Intersection bisector surface (IBS) [[ZWK14](#)]
- Interaction regions (IR) [[HZvK*15](#)]

Representation of the relation

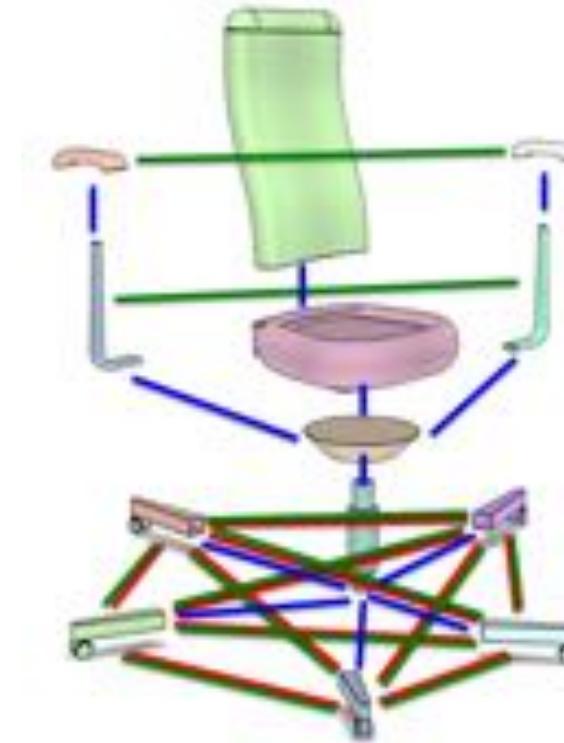
- Spatial arrangement
- Boundary representation
- **Dense volume feature**
- Gestalt and symmetry grouping
- Mechanical relations
- Humanoid actions



- Interaction landscapes [PKH*17]

Representation of the relation

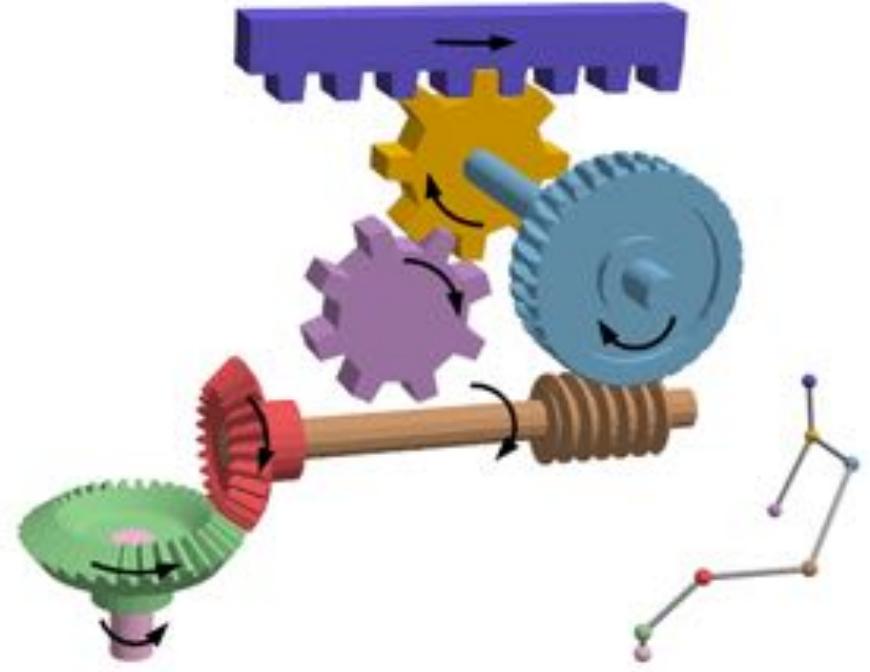
- Spatial arrangement
- Boundary representation
- Dense volume feature
- **Gestalt and symmetry grouping**
- Mechanical relations
- Humanoid actions



- Symmetry hierarchy [[WXL*11](#)]

Representation of the relation

- Spatial arrangement
- Boundary representation
- Dense volume feature
- Gestalt and symmetry grouping
- **Mechanical relations**
- Humanoid actions



- Force drivers, joints, and gears
[LOMI11, KLY*14, MYY*10, XLX*16]

Representation of the relation

- Spatial arrangement
- Boundary representation
- Dense volume feature
- Gestalt and symmetry grouping
- Mechanical relations
- **Humanoid actions**



- Gazing, grasping, holding, pushing, pulling, and sitting [SCH*14, FSL*15, SCH*16, MLZ*16]



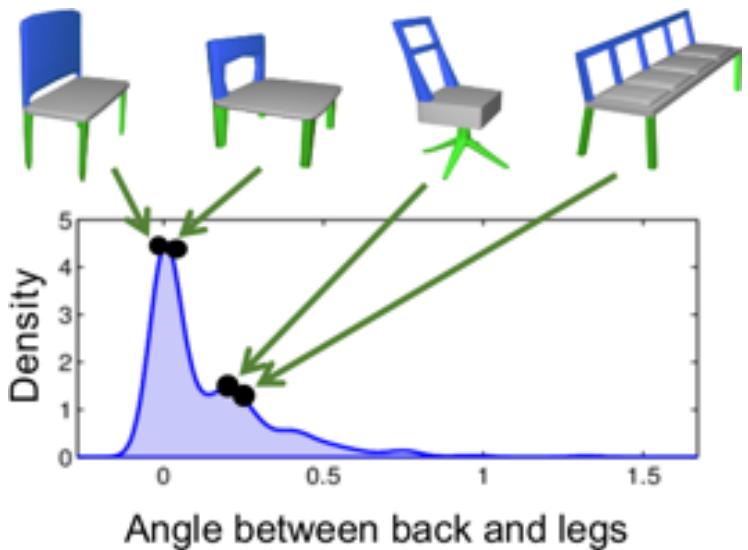
Representations of functionality

Functionality = Geometry + Interaction

Representations of functionality

Functionality = Geometry + Interaction X

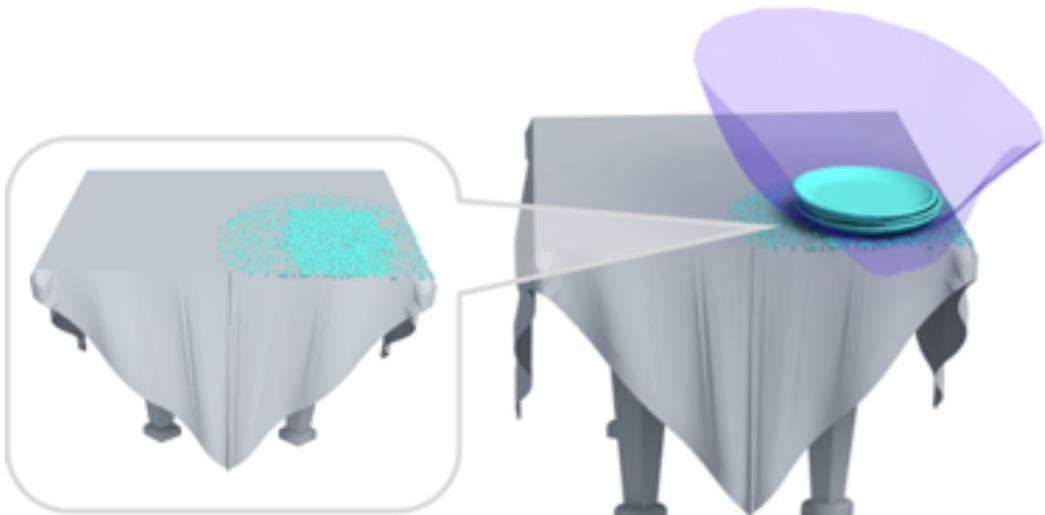
Geometry-only (G) methods



Meta-representation
of shape families
[FavK*14]

Representations of functionality

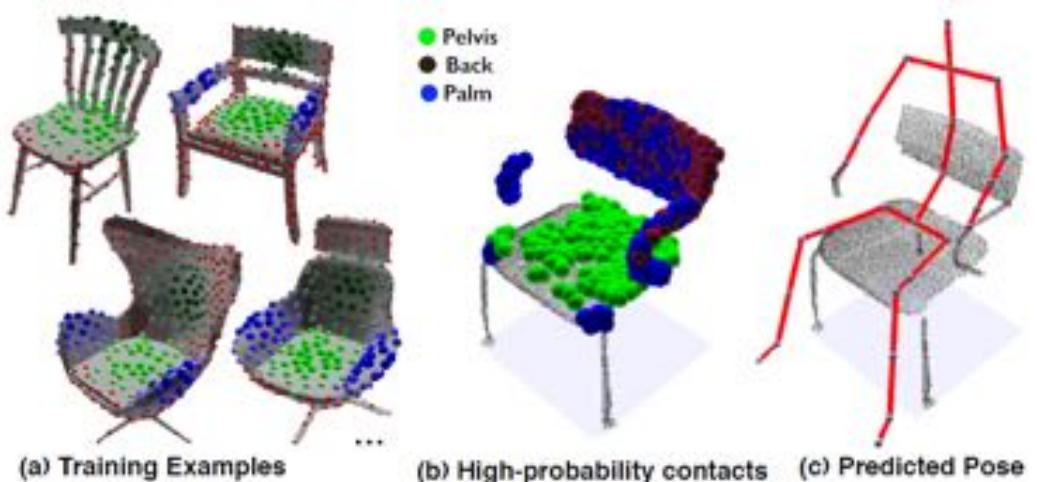
Functionality = Geometry + Interaction ✓
Geometry + interaction (GI) methods



Interaction context
(ICON) descriptor
[HZvK*15]

Representations of functionality

Functionality = Geometry + Interaction ✓
Geometry + agent (GA) methods



Shape2pose: Human-centric shape analysis
[KCGF14]



Additional classification criteria

- **Model type:** discriminative or generative
- **Approach:** supervised, unsupervised, or handcrafted
- **Input data representation:** RGB-D image, point cloud, mesh

Classification criteria

| Works | Functional entity | Representation of geometry or interactions | | | Additional classification criteria | | |
|--------------------------|-------------------|--|------------|-----------|------------------------------------|--------------|----------------|
| | | Component / interacting entity | Dynamicity | Relations | Input | Approach | Model type |
| Geometry-only (G) | | | | | | | |
| Xu et al. [XSF02] | scene | object-geo | stat | SA | mesh | handcrafted | generative |
| Memell et al. [MSL*11] | scene | object-geo | stat | SA | mesh | handcrafted | generative |
| Yu et al. [YYT*11] | scene | object-geo | stat | SA | mesh | supervised | generative |
| Fisher et al. [FSH11] | scene | object-geo | stat | SA | mesh | handcrafted | discriminative |
| Fisher et al. [FRS*12] | multi-object | object-geo | stat | SA | mesh | supervised | generative |
| Zhao et al. [ZWK14] | multi-object | object-geo | stat | BR | pcl | handcrafted | discriminative |
| Zhao et al. [ZHG*16] | multi-object | object-geo | stat | BR | mesh | supervised | generative |
| Zheng et al. [ZC0M13] | object | part-geo | stat | SG | mesh | handcrafted | generative |
| Mitra et al. [MYY*10] | object | part-geo | stat | SG | mesh | handcrafted | discriminative |
| Xu et al. [NLX*16] | object | part-geo | stat | SG | rgbd | handcrafted | discriminative |
| Fish et al. [FAvK*14] | object | part-geo | stat | SA | mesh | supervised | generative |
| Yumer et al. [YKI4] | object | part-geo | stat | SA | mesh | supervised | generative |
| Pechuk et al. [PSR08] | part | part-geo | stat | SA | rgbd | supervised | discriminative |
| Gelfand et al. [GG04] | part | - | - | - | mesh | handcrafted | discriminative |
| Andries et al. [ADSV20] | object | - | stat | - | - | supervised | generative |
| Krs et al. [KMG*20] | object | part-geo | stat | - | - | unsupervised | generative |

Classification criteria

| Works | Functional entity | Representation of geometry or interactions | | | Additional classification criteria | | |
|------------------------------------|-------------------|--|------------|-----------|------------------------------------|-------------|----------------|
| | | Component / interacting entity | Dynamicity | Relations | Input | Approach | Model type |
| Geometry + interaction (GI) | | | | | | | |
| Hu et al. [HZvK*15] | object | stat-inter | stat | BR | pcl | handcrafted | discriminative |
| Hu et al [HvKW*16] | object | stat-inter | stat | BR | pcl | supervised | discriminative |
| Pirk et al. [PKH*17] | object | dyn-inter | dyn | VF | mesh | handcrafted | discriminative |
| Myers et al. [MTFA15] | part | stat-inter | stat | SA | rgbd | supervised | discriminative |
| Kim et al. [KS14] | part | stat-inter | stat | SA | rgbd | supervised | discriminative |
| Laga et al. [LMS13] | part | stat-inter | stat | SA+SG | mesh | supervised | discriminative |
| Hu et al. [HLK*17] | part | stat-inter | dyn | SA+BR | pcl | supervised | discriminative |
| Xiang et al. [XQM*20] | part | stat-inter | dyn | SA | mesh | supervised | discriminative |
| Hu et al. [HYZ*18] | object | stat-inter | stat | SA+BR | vol | supervised | generative |
| Yi et al. [YHL*18] | part | stat-inter | dyn | SA | pcl | supervised | discriminative |
| Wang et al. [WZS*19] | part | stat-inter | dyn | SA | pcl | supervised | discriminative |
| Yan et al. [YHY*19] | part | stat-inter | dyn | SA | pcl | supervised | discriminative |
| Li et al. [LWY*20] | part | stat-inter | dyn | SA | pcl | supervised | discriminative |
| Kokic et al. [KSHK17] | part | stat-inter | dyn | SA | pcl | supervised | generative |
| Li et al. [LSK20] | part | stat-inter | dyn | SA | pcl | supervised | generative |

Classification criteria

| Works | Functional entity | Representation of geometry or interactions | | | Additional classification criteria | | | |
|----------------------------|-------------------|--|------------|-----------|------------------------------------|--------------|----------------|--|
| | | Component / interacting entity | Dynamicity | Relations | Input | Approach | Model type | |
| Geometry+agent (GA) | | | | | | | | |
| Grabner et al. [GGVG11] | scene | agent-inter | stat | HA | mesh | supervised | generative | |
| Savva et al. [SCH*14] | scene | agent-inter | stat | SA+HA | mesh | supervised | discriminative | |
| Zhu et al. [ZJZ*16] | scene | agent-inter | stat | SA | mesh | supervised | generative | |
| Jiang et al. [JKS13] | multi-object | agent-inter | stat | SA | rgbd | supervised | discriminative | |
| Wang et al. [WLY17] | multi-object | agent-inter | stat | SA+HA | mesh | supervised | discriminative | |
| Fisher et al. [FSL*15] | multi-object | agent-inter | stat | SA+HA | mesh | supervised | generative | |
| Savva et al. [SCH*16] | multi-object | agent-inter | stat | SA+HA | mesh | supervised | generative | |
| Ma et al. [MLZ*16] | multi-object | agent-inter | dyn | SA+HA | mesh | unsupervised | generative | |
| Zheng et al. [ZLDM16] | object | agent-inter | stat | SA | mesh | handcrafted | generative | |
| Kim et al. [KCGF14] | object | agent-inter | stat | SA | mesh | supervised | generative | |
| Bar-Aviv & Rivlin [BAR06] | object | agent-inter | stat | SA+HA | mesh | handcrafted | discriminative | |
| Zhu et al. [ZZCZ15] | object | agent-inter | dyn | SA+HA | rgbd | supervised | discriminative | |
| Zhao et al. [ZCK17] | object | agent-inter | dyn | SA+HA | mesh | handcrafted | discriminative | |
| Lee et al. [LCI06] | object | agent-inter | dyn | SA | mesh | supervised | generative | |
| Li et al. [LLK*19] | scene | agent-inter | stat | SA+HA | rgbd | supervised | generative | |
| Zhang et al. [ZHN*20] | scene | agent-inter | stat | SA+HA | rgbd | supervised | generative | |
| Mao et al. [MZK*19] | object | agent-inter | stat | SA | mesh | supervised | generative | |
| Fu et al. [FFY*20] | scene | agent-inter | stat | SA+HA | mesh | supervised | discriminative | |
| Monszpart et al. [MGC*19] | scene | agent-inter | stat | SA | rgbd | supervised | generative | |
| Raiz et al. [RMC19] | scene | agent-inter | stat | SA+BR | mesh | supervised | generative | |
| Starke et al. [SZKS19] | object | agent-inter | dyn | SA | vol | supervised | generative | |

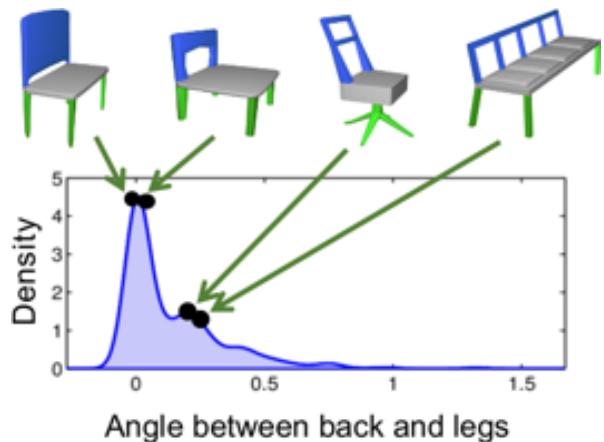


Summary for definition

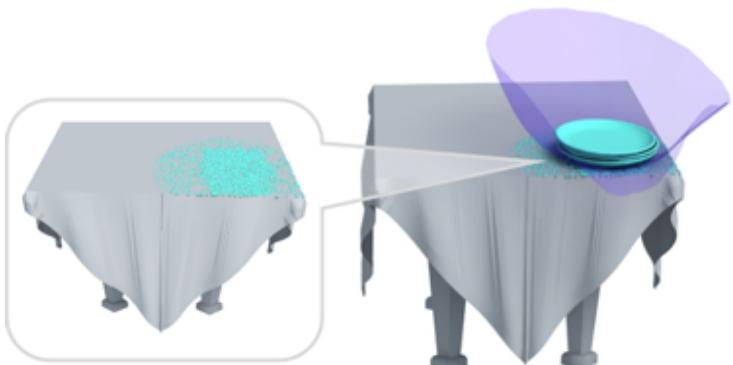
- Use **definition of functionality** and **additional criteria** to classify and discuss **previous work**
- Definition provides **three groups of functionality methods**
- **Classification** also useful when discussing **unexplored areas of research and future work**

Next: discussion of methods

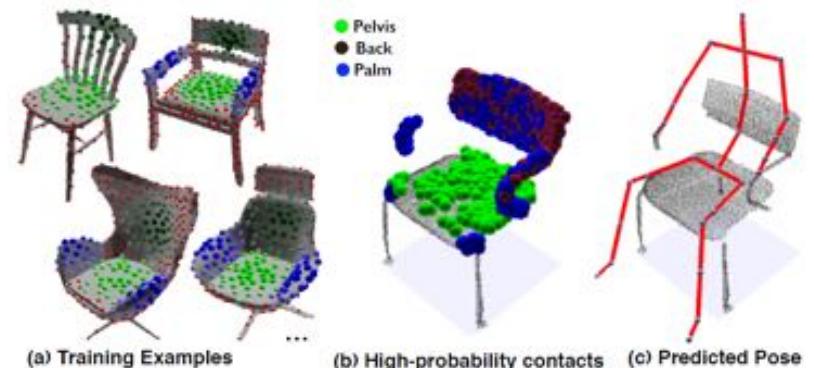
Functionality = Geometry + Interaction



G methods

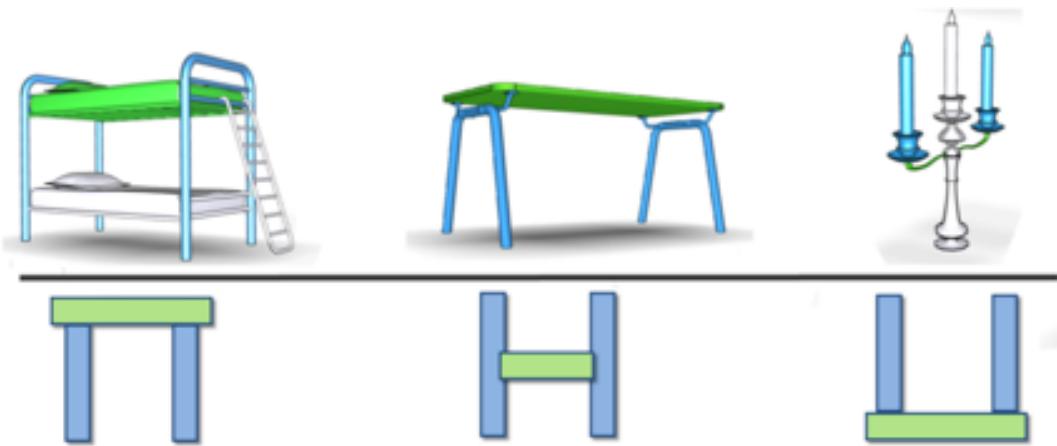


GI methods



GA methods

Geometry-only (G) methods

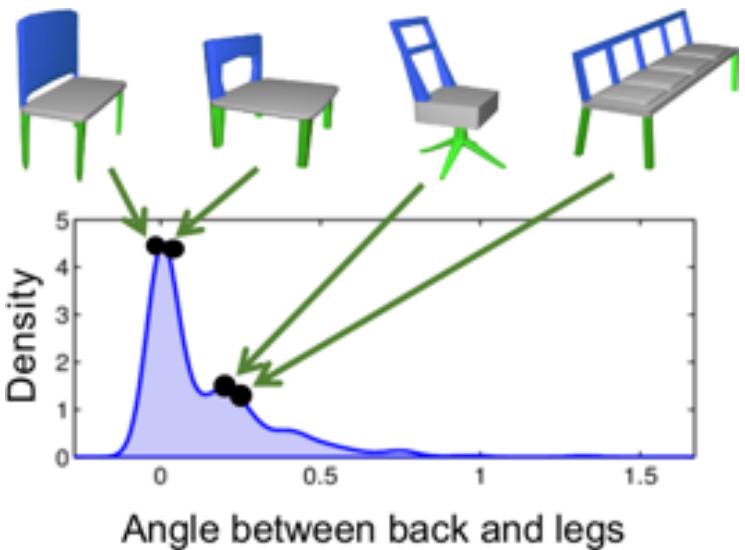


Geometry-only methods

Functionality = Geometry + Interaction



Geometry-only (G) methods



Meta-representation
of shape families
[FavK*14]

Geometry-only methods

- Derive **functionality** only from **geometry** and **structure**
- Geometry and structure of **parts, objects, or scenes**
- **Interactions** with other entities are **not considered**
- Relations considered in the analysis are **static**



Geometry-only methods

Discussion follows **level of the entity**:

- Scene-level functionality
- Object-level functionality
- Part-level functionality



Geometry-only methods

Discussion follows **level of the entity**:

- **Scene-level functionality**
- Object-level functionality
- Part-level functionality



Scene-level functionality

- Describe the **functionality of a scene**
- Specific **object arrangements** enable certain functionalities
- Consider **relations between objects** in the scene
- **Spatial arrangements or boundary representations**

Scene-level functionality



Constrained placement
[XSF02]



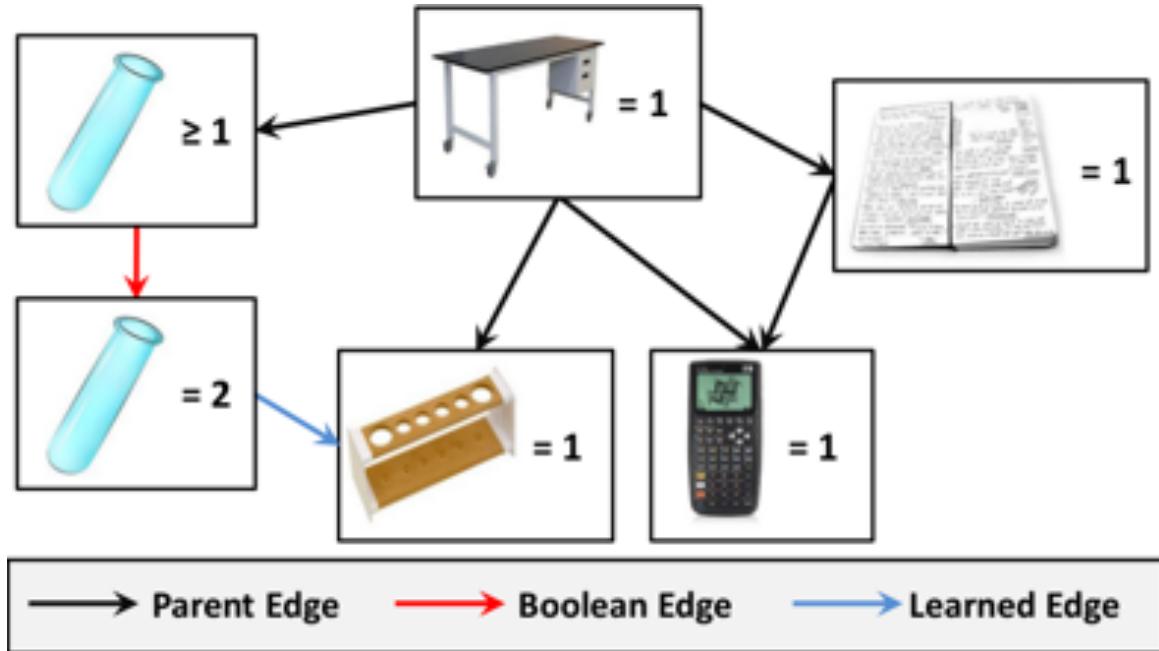
Interior design guidelines
[MSL*11]



"Make it home"
[YYT*11]

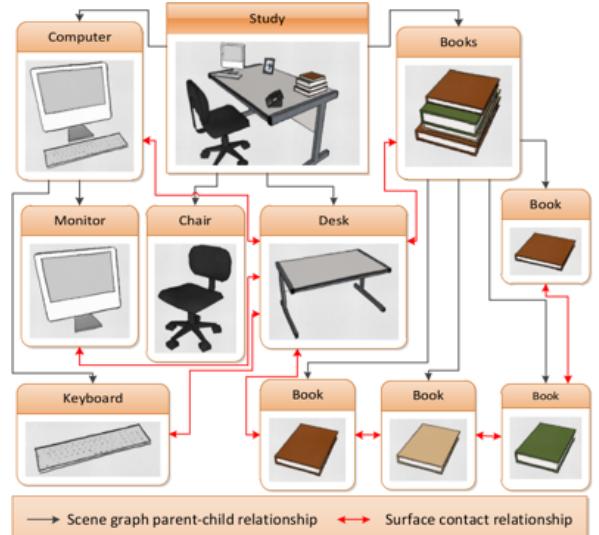
- Automatically **place objects** to **generate a scene**
- Using **placement constraints and rules, pseudo-physics, interior design guidelines, and ergonomic factors**

Scene-level functionality

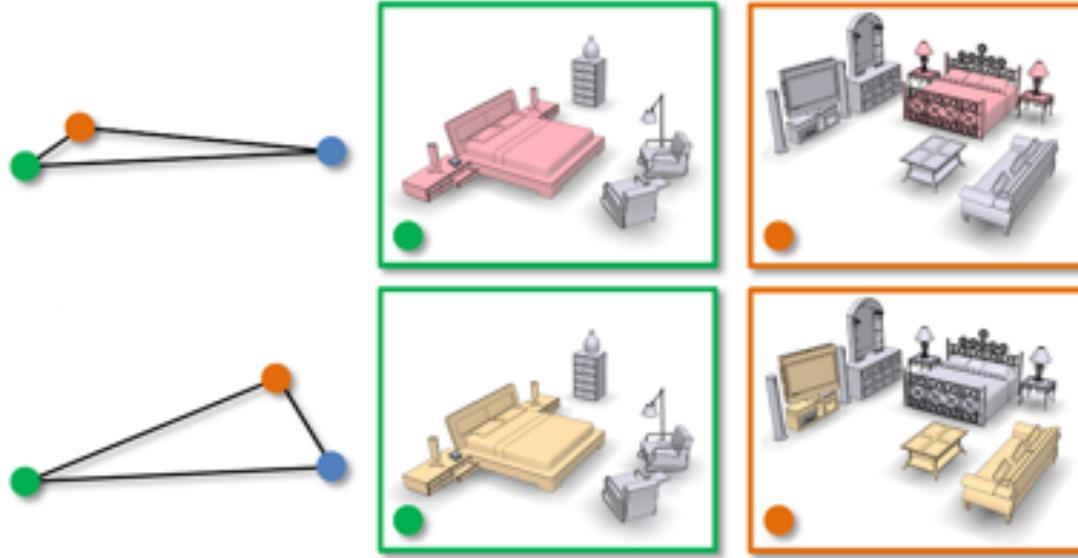


- “Example-based synthesis of 3D object arrangements” [FRS*12]
- **Synthesize scenes** with a **learned object co-occurrence model**

Scene-level functionality



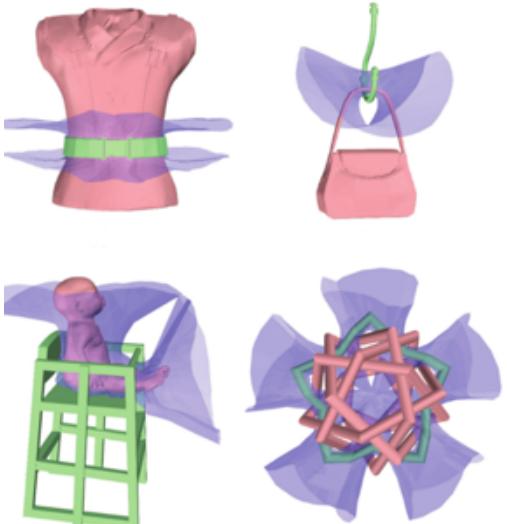
Graph kernels
[\[FSH11\]](#)



Focal points
[\[XMZ*14\]](#)

- Content-based **comparison** for **scene retrieval**
- Considering **co-occurrence of objects**

Scene-level functionality



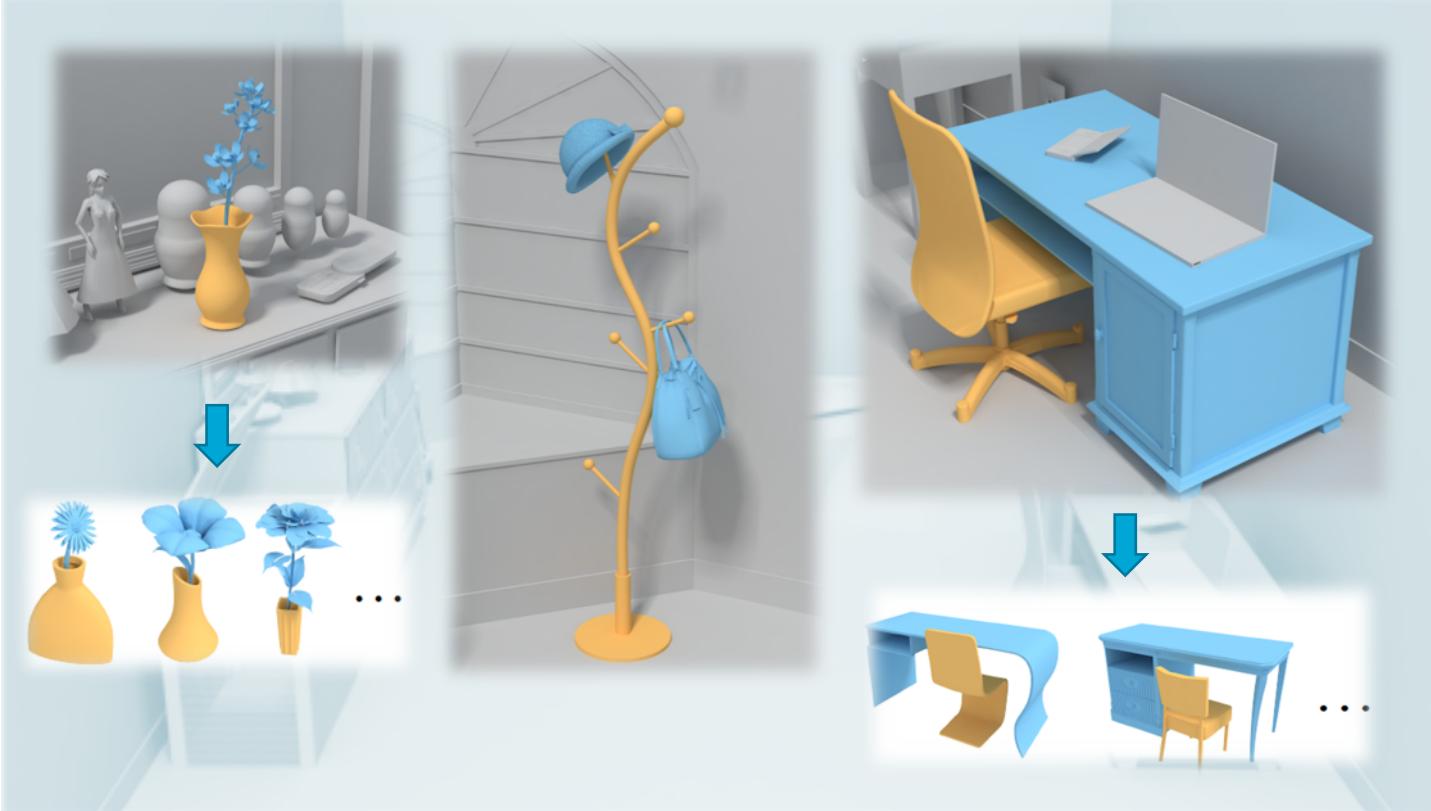
Interaction Bisector Surface
[ZWK14]



- Represent the **spatial boundary** between objects
- Applicable to **scene comparison** and **template-based synthesis**

Relationship templates

[ZHG*16]

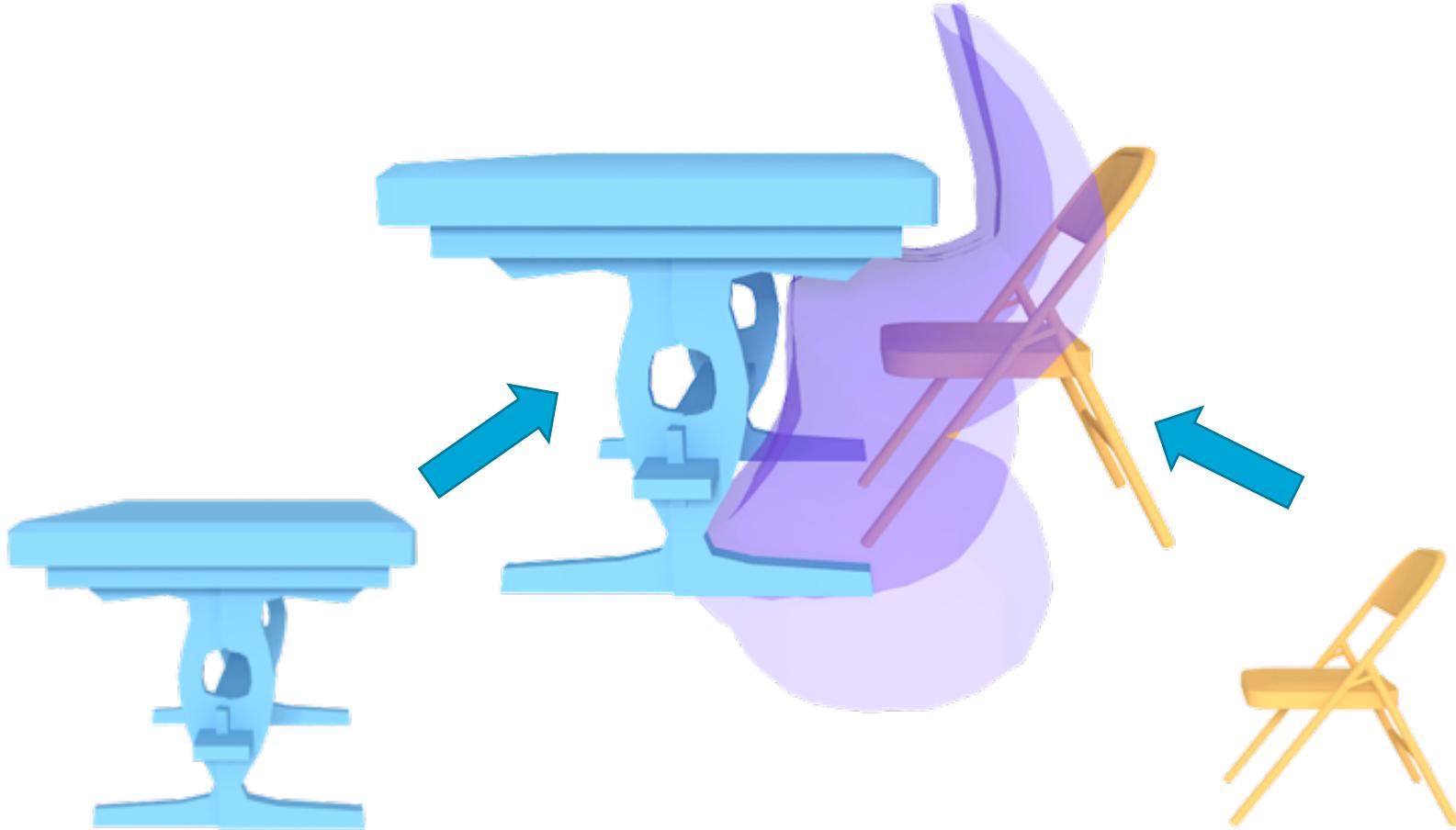


How to make variations of complex relationship?

Relationship templates

[ZHG*16]

Example scene :

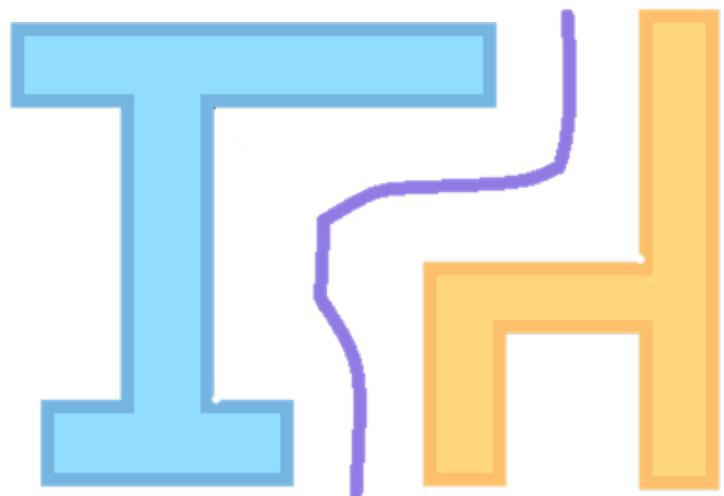


Novel object 1

Novel object 2

Relationship templates

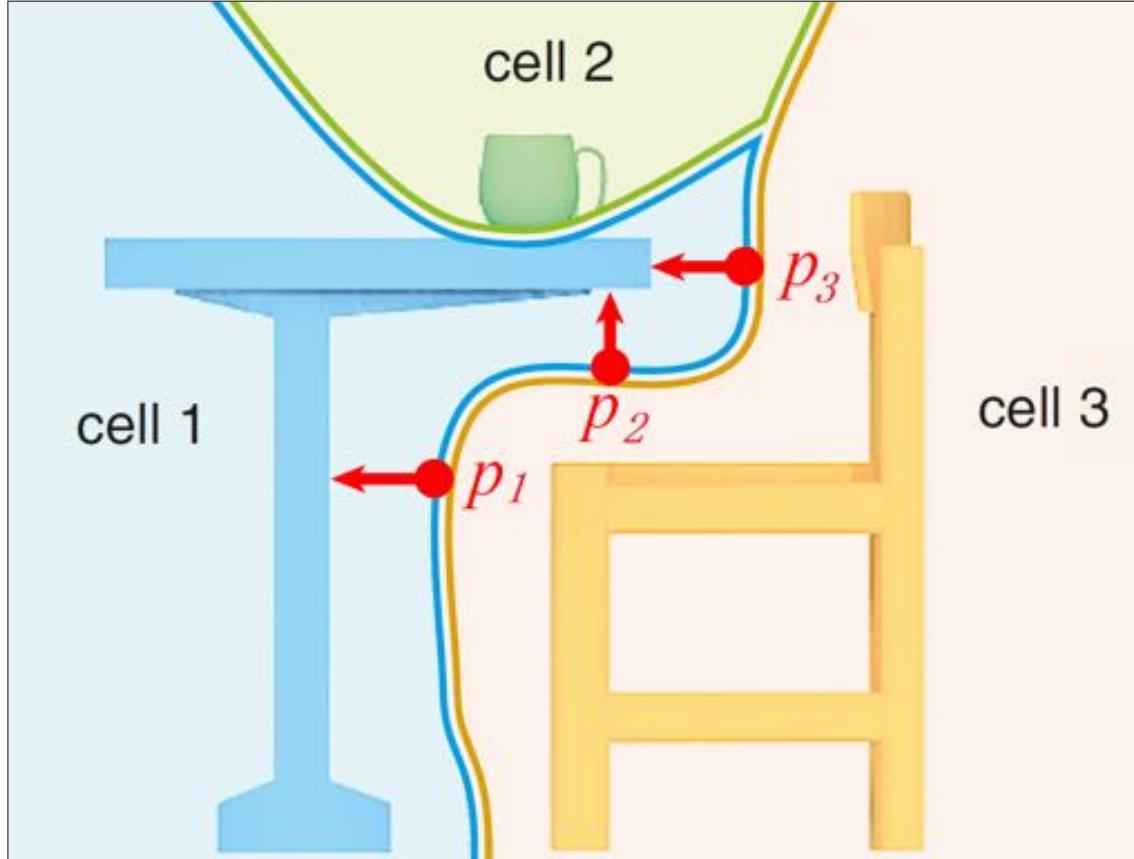
[ZHG*16]



Template construction: IBS

Relationship templates

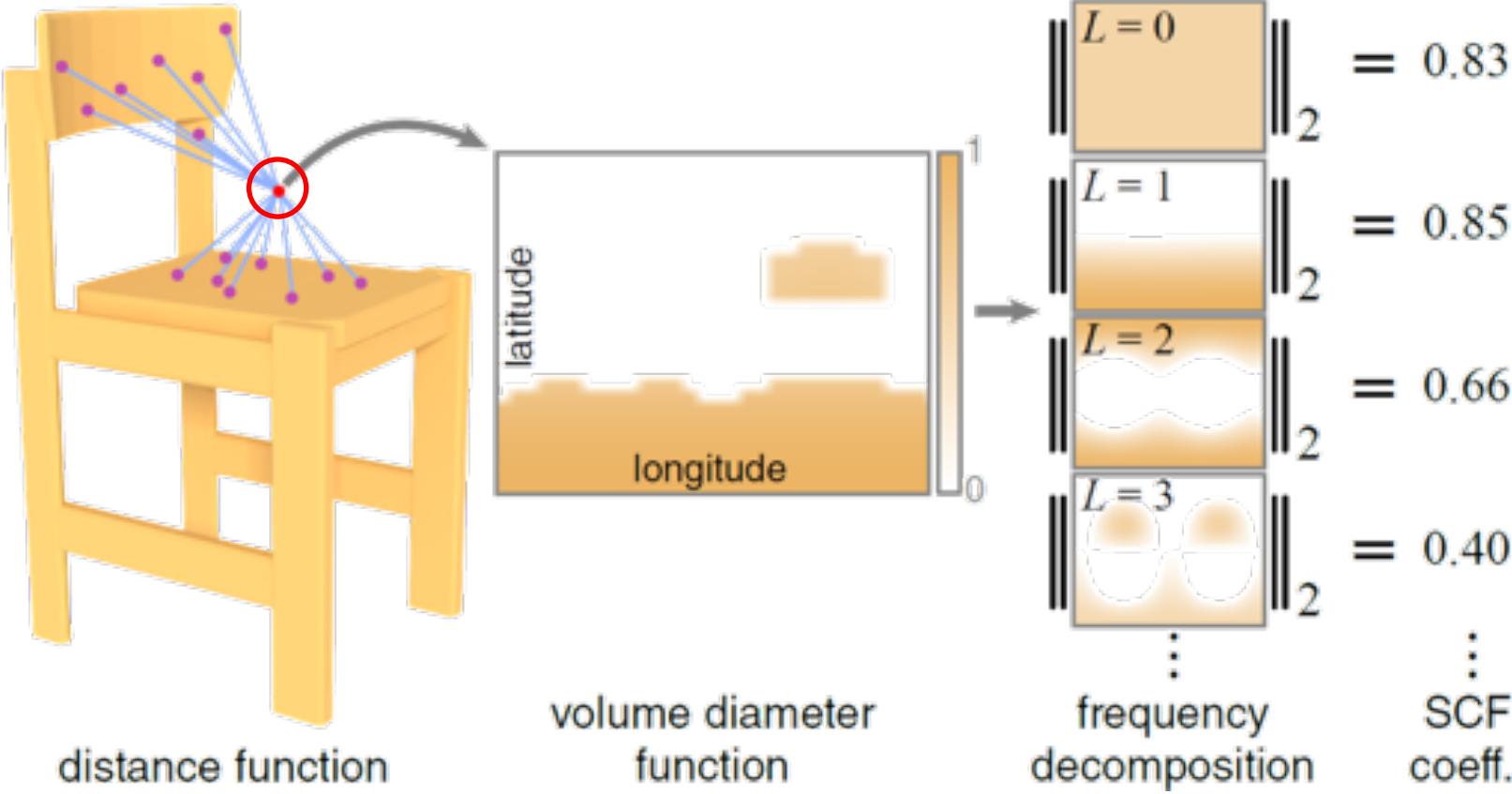
[ZHG*16]



Template construction: cells and features

Relationship templates

[ZHG*16]



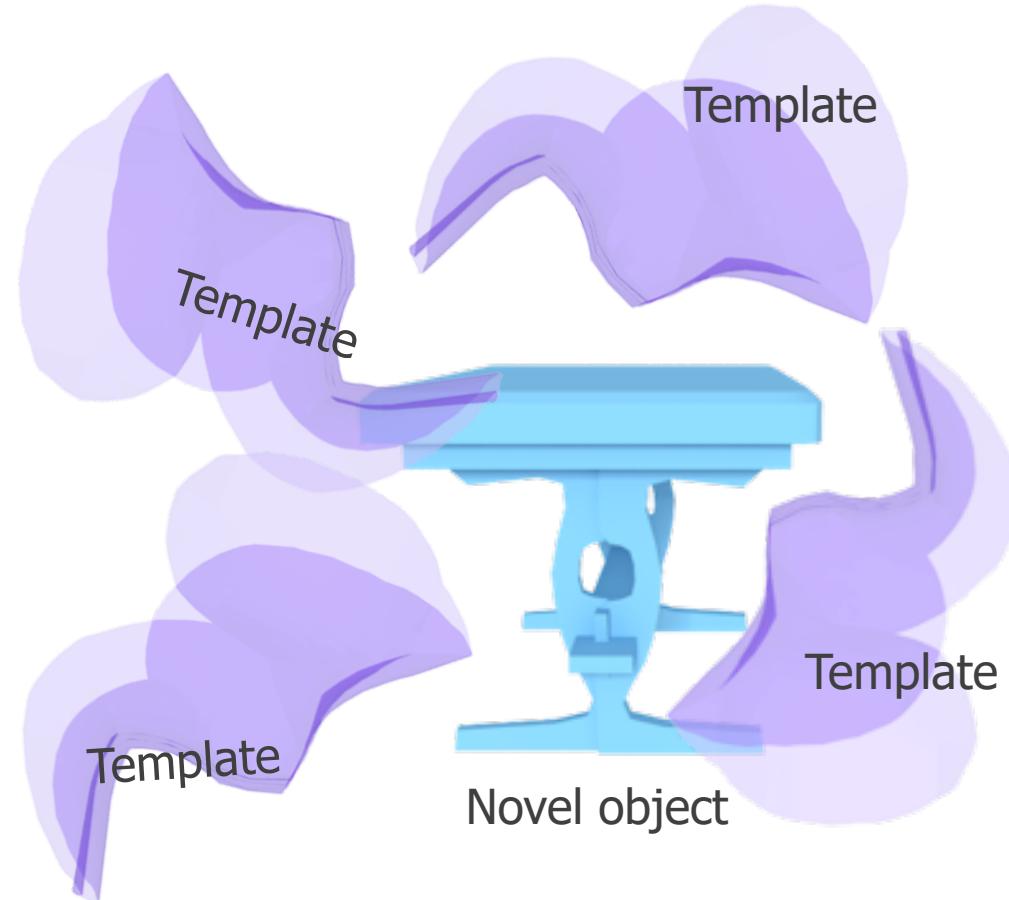
Shape Coverage Feature (SCF)

Example scene :



Relationship templates

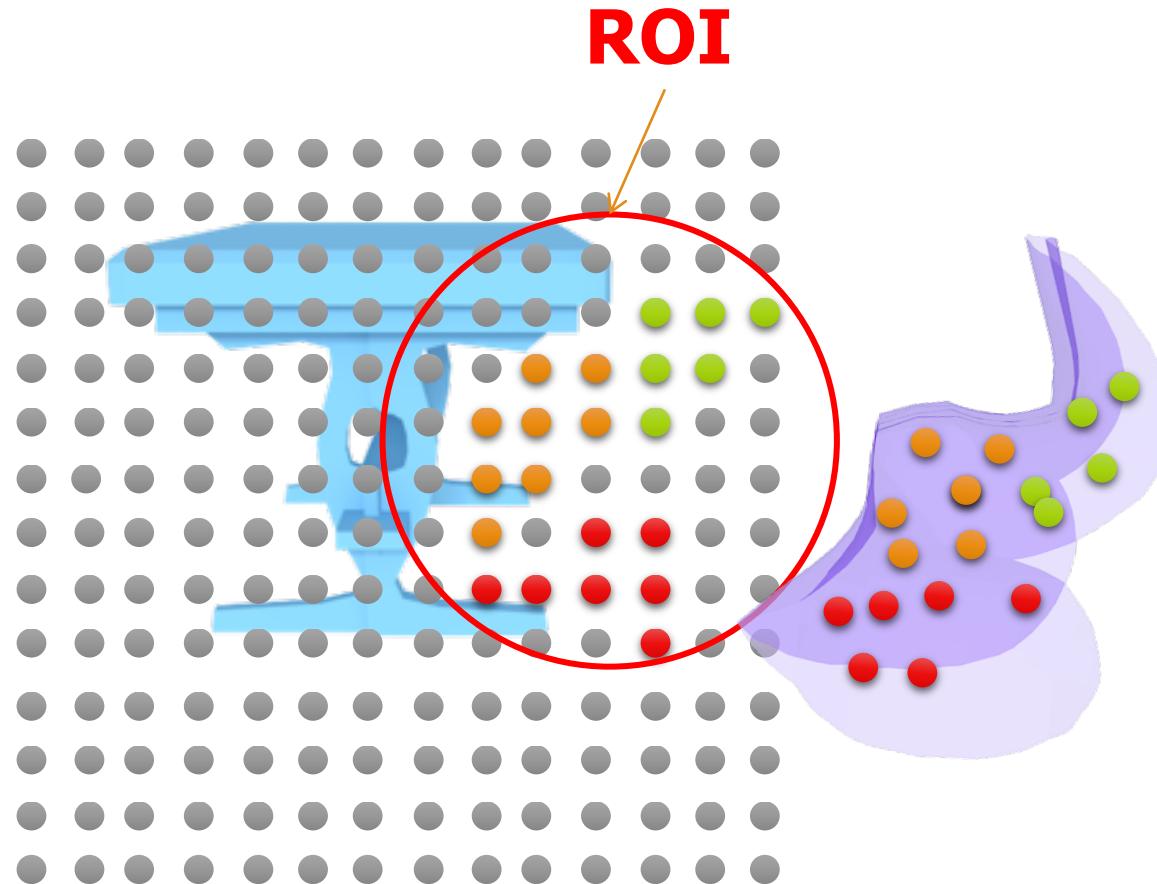
[ZHG*16]



Novel Object Fitting

Relationship templates

[ZHG*16]



Novel Object Fitting: initial matching

Relationship templates

[ZHG*16]

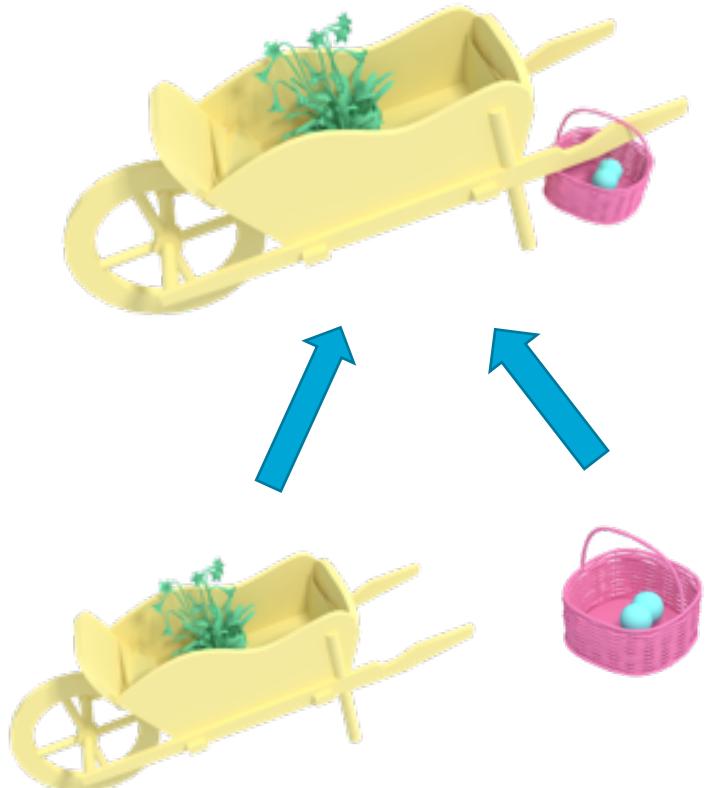


Novel Object Fitting: refinement

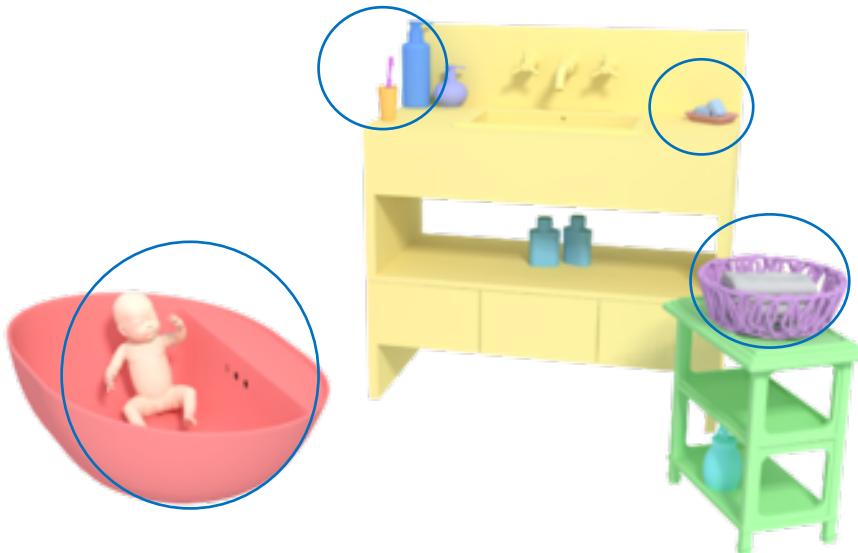
Relationship templates

[ZHG*16]

Scene hierarchy



Combine with other scene synthesis system



M. Fisher, D. Ritchie, M. Savva, T. Funkhouser, and P. Hanrahan, “**Example-based Synthesis of 3D Object Arrangements**” *SIGGRAPH ASIA 2012*



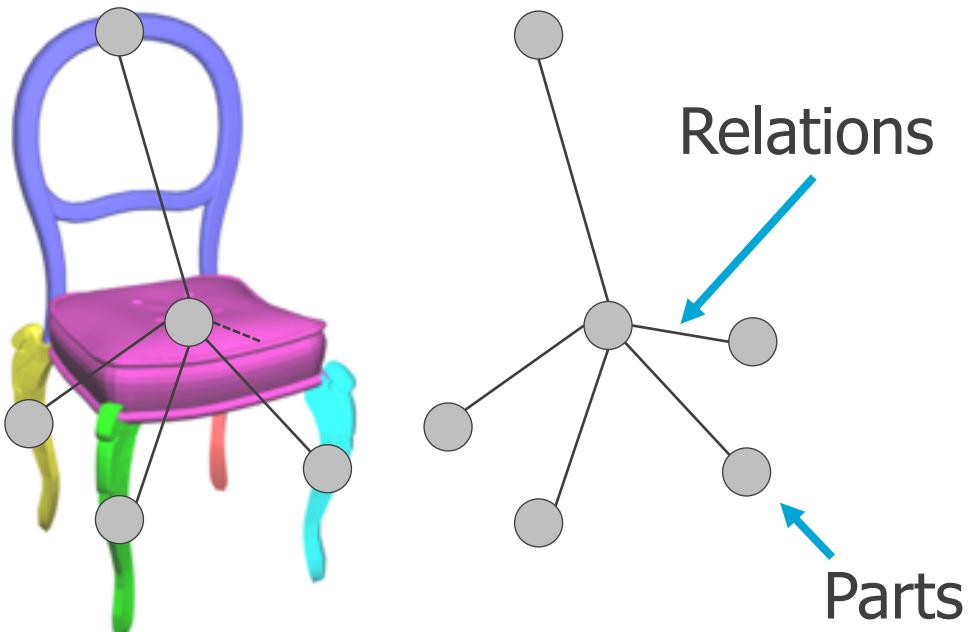
Geometry-only methods

Discussion follows **level of the entity**:

- Scene-level functionality
- **Object-level functionality**
- Part-level functionality

Object-level functionality

- Examine the **geometry** and **structure** of the object
- Structure: represent a shape as a **graph of parts**
- Edges represent **relations** between connected parts

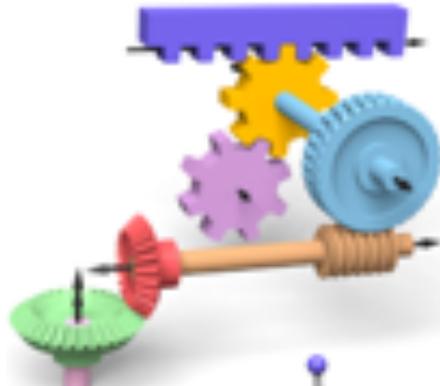


Object-level functionality

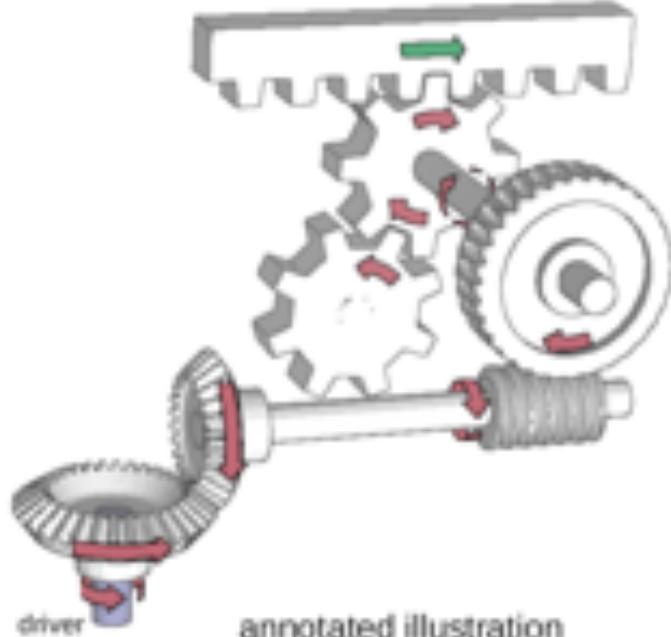


- Symmetric functional arrangements (**sFARRs**) [[ZCOM13](#)]
- **Handcrafted rules** to detect **special groupings of parts**
- **Exchange sFARRs** between shapes to **generate plausible shapes**

Object-level functionality

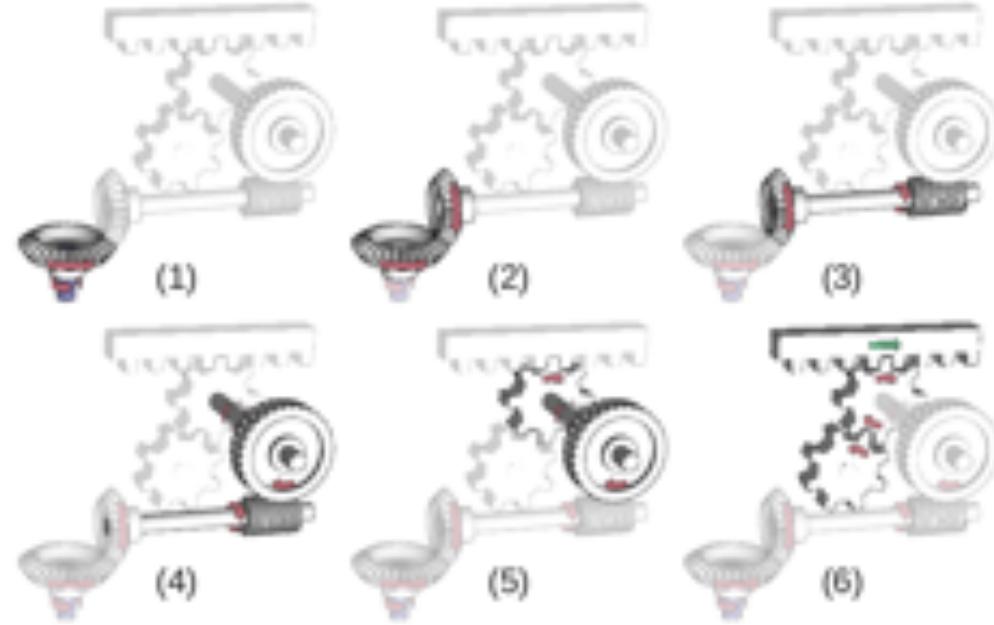


motion analysis



driver

annotated illustration



causal chain

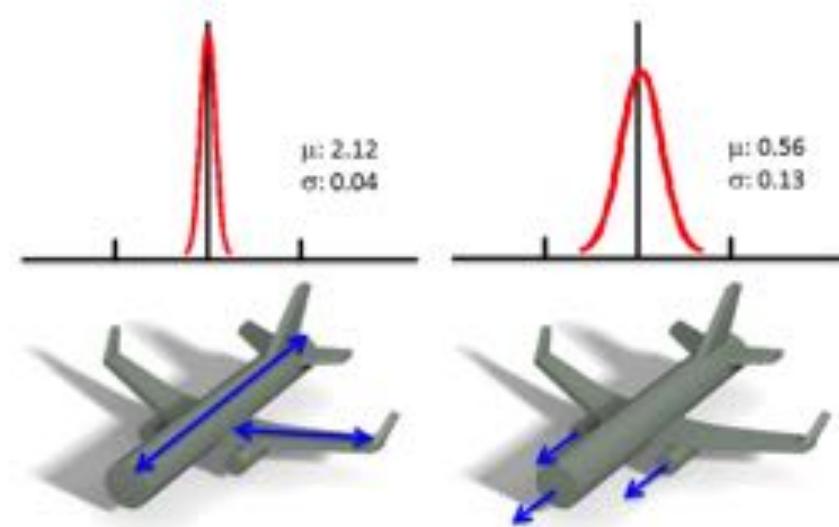
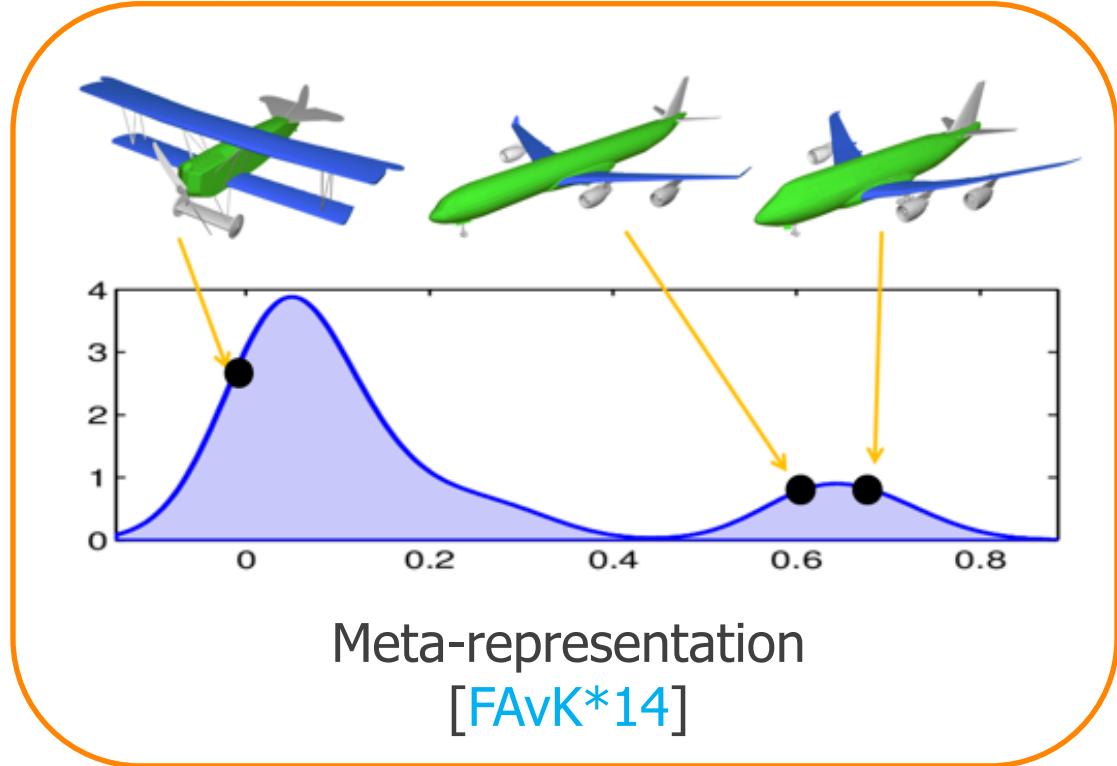
- Illustrate the **functioning** of **mechanical assemblies** [MYY*10]
- Assemblies composed of mechanical components such as **gears**
- Infer **motion** with **handcrafted rules** based on **symmetry relations**

Object-level functionality



- Recover **functioning of mechanical assemblies** from **images** [XLX*16]
- Analysis of the **geometry of linked parts** in **multiple views**

Object-level functionality



- Learn a **part configuration model** from a set of shapes of same family
- Evaluate **validity** of a shape based on how well it **fits the model**

Meta-representation of shapes [FAvK*14]



Are these shapes “valid”?

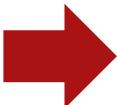
Meta-representation of shapes [FAvK*14]



Learn validity from a collection

Meta-representation of shapes [FAvK*14]

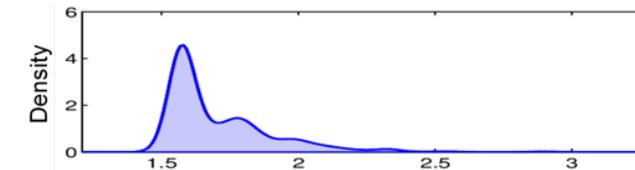
Input



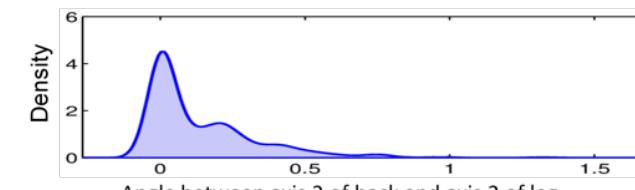
Analysis



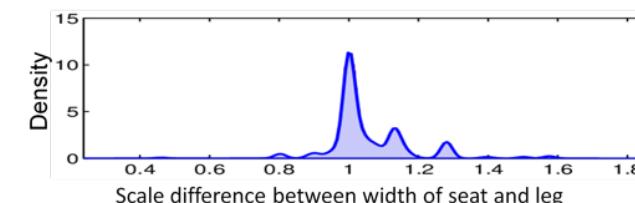
Meta-representation



Angle between axis 1 of back and axis 2 of leg



Angle between axis 2 of back and axis 2 of leg

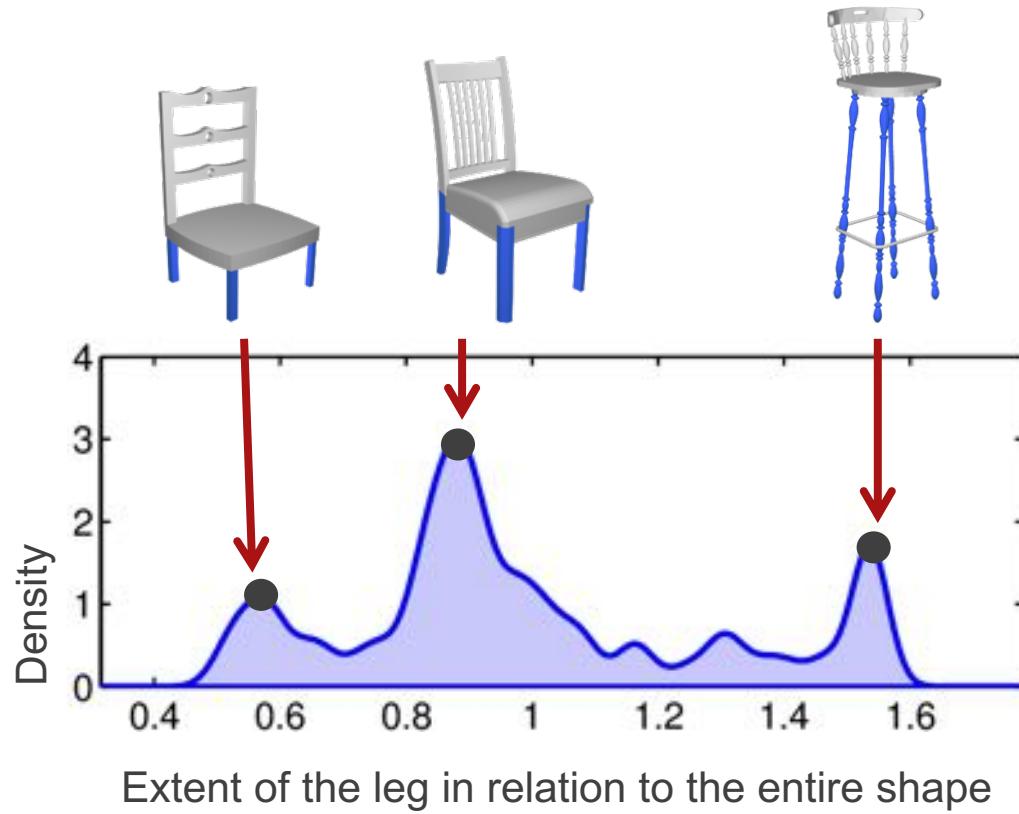


Scale difference between width of seat and leg

■
■
■

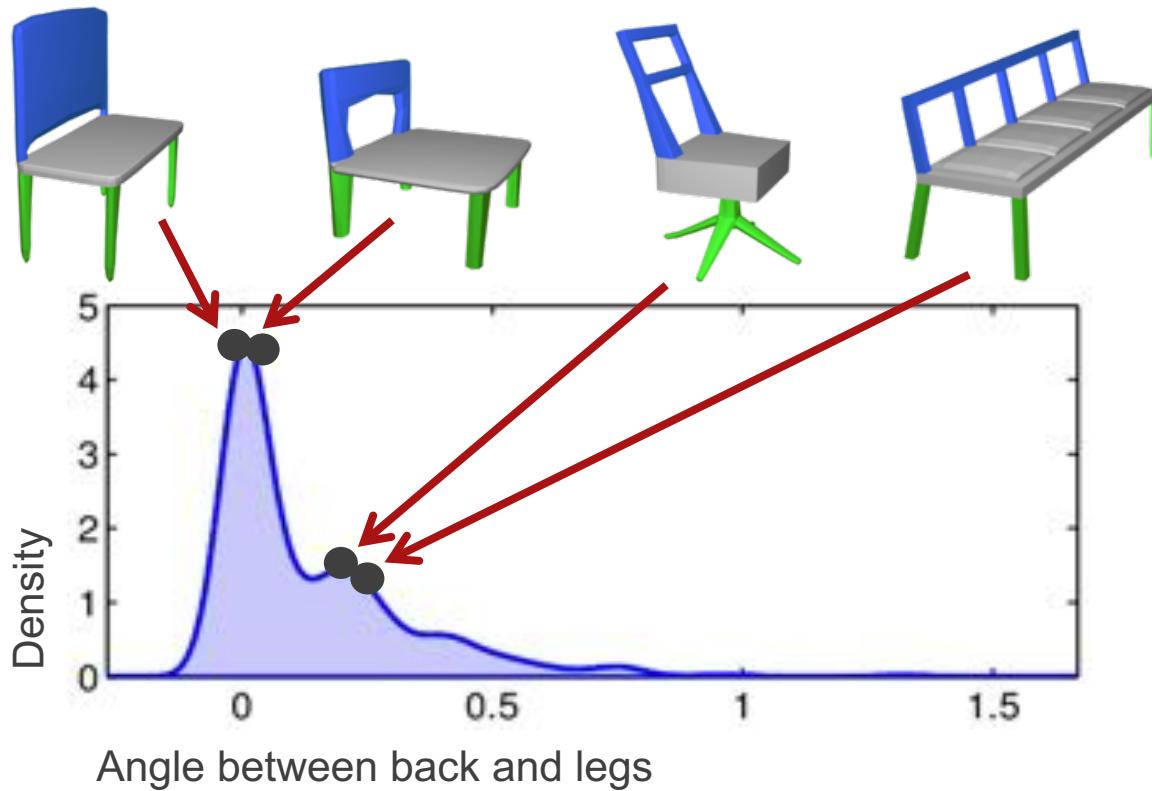
How to characterize “validity”?

Meta-representation of shapes [FAvK*14]



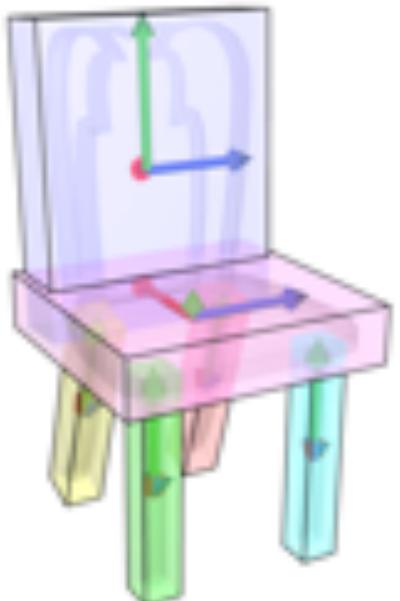
Relations for single parts

Meta-representation of shapes [FAvK*14]

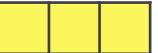


Relations for pairs of parts

Meta-representation of shapes [FAvK*14]



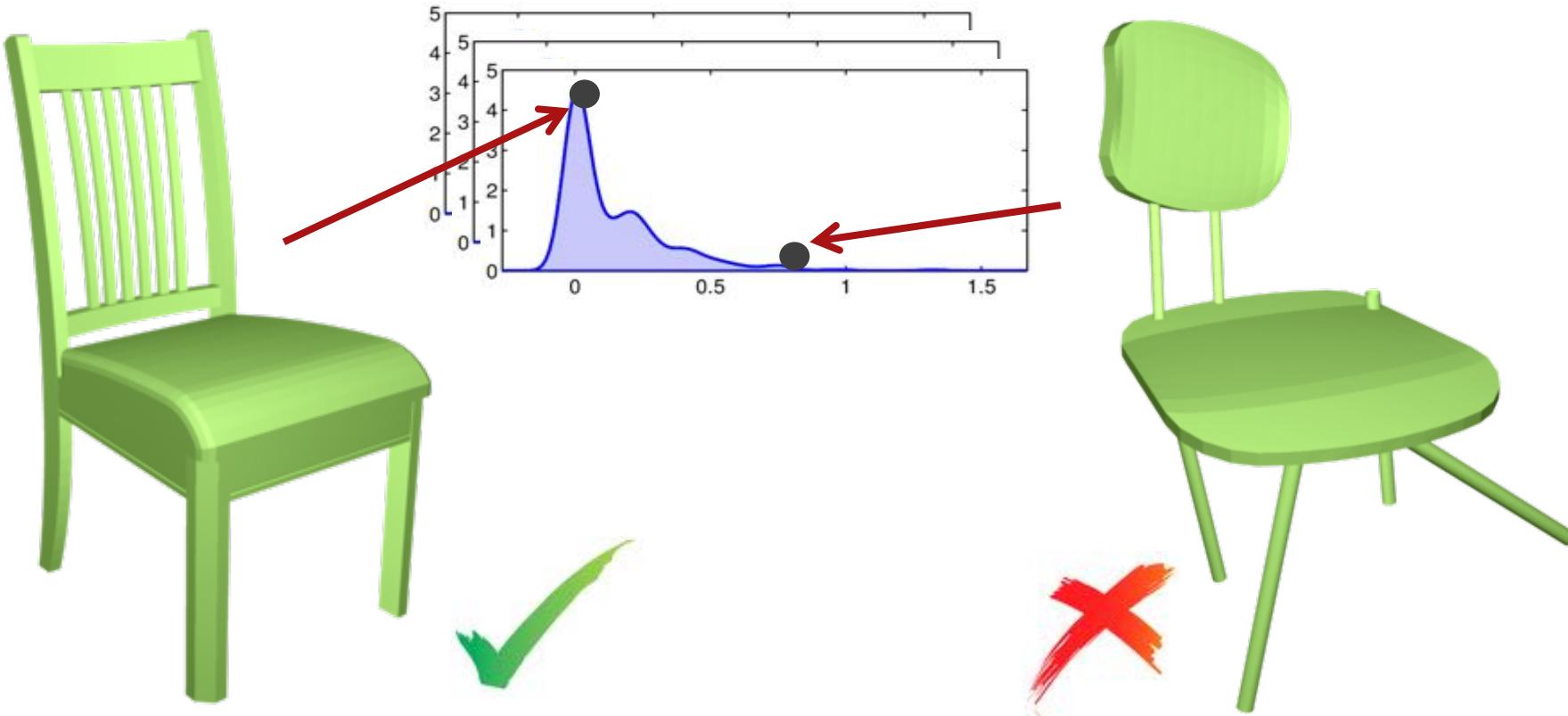
| | Back | Seat | Leg |
|-------------|-------------|-------------|------------|
| Back | unary | binary | binary |
| Seat | | unary | binary |
| Leg | | | unary |

Extent
Unary: 

Scale Rotation Contact
Binary: 

Relations per shape

Meta-representation of shapes [FAvK*14]



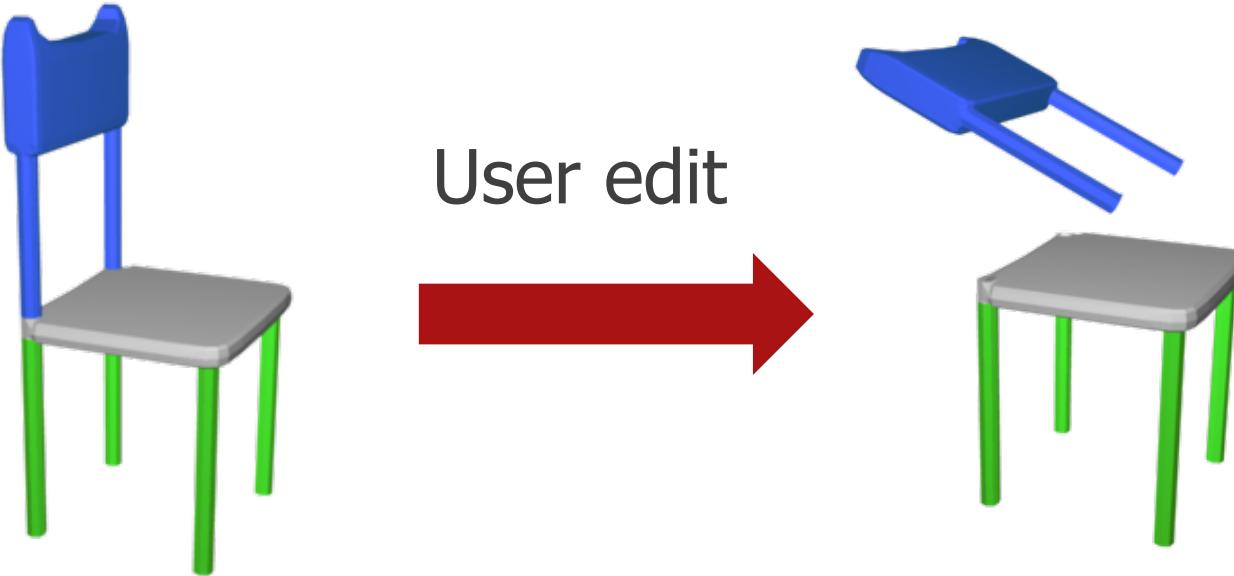
Characterize validity with the relations



Meta-representation of shapes [FAvK*14]

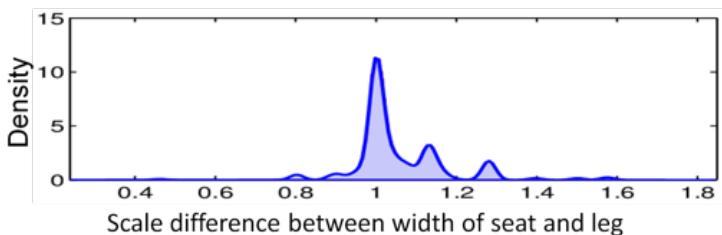
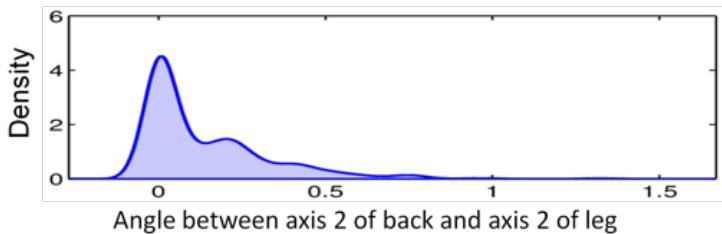
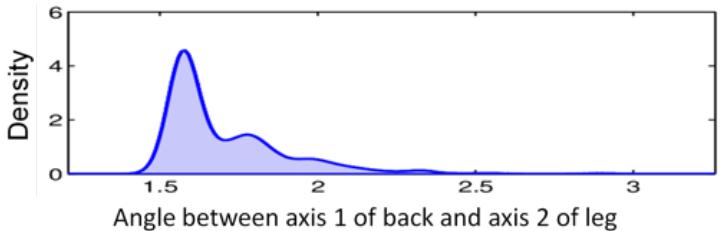
- Validity is useful in several applications:
 - Exploration
 - Guided modeling
 - Coupled editing

Meta-representation of shapes [FAvK*14]

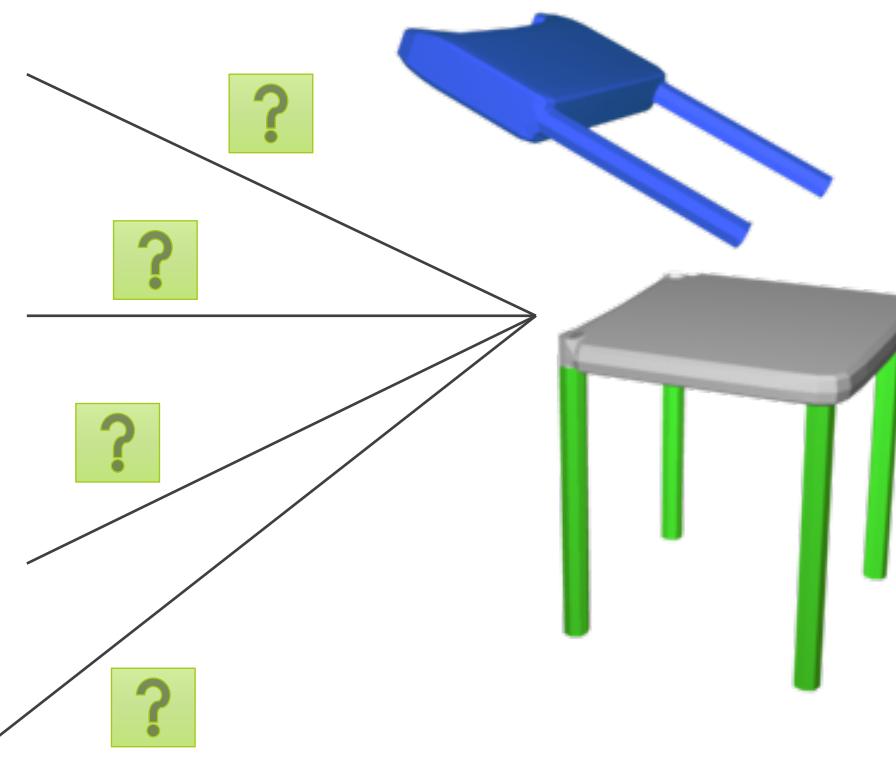


General editing approach

Meta-representation of shapes [FAvK*14]

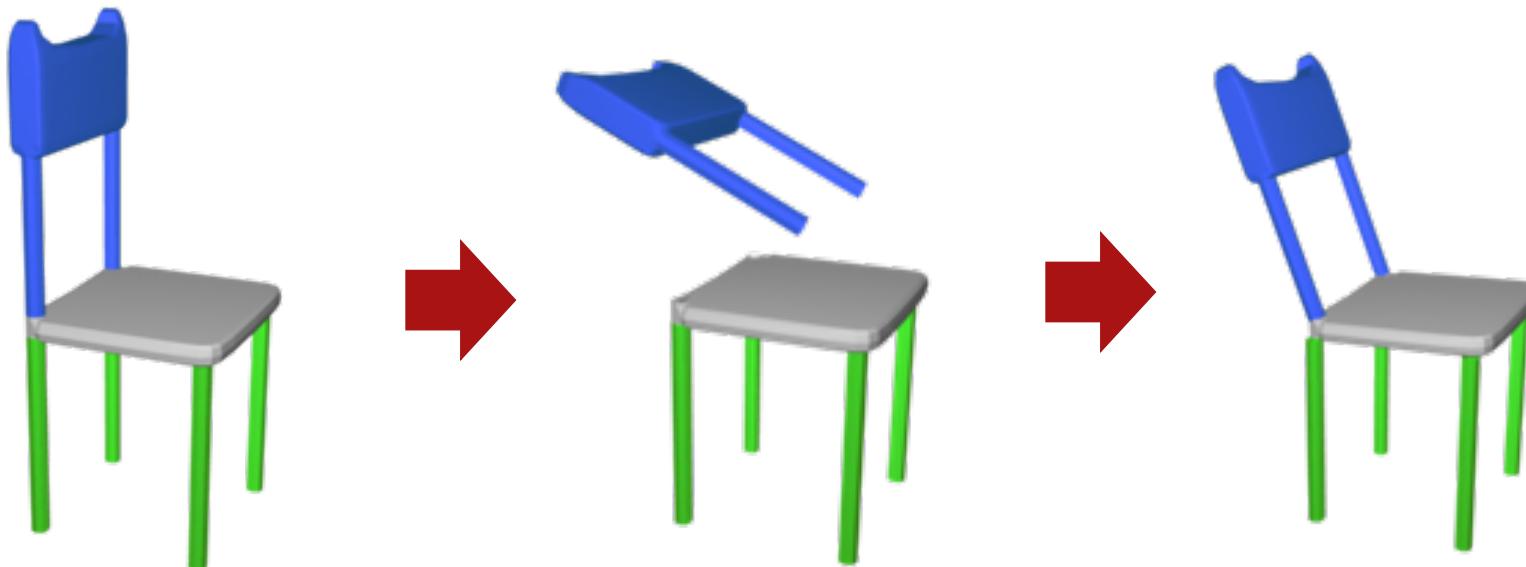


⋮



General editing approach

Meta-representation of shapes [FAvK*14]



General editing approach

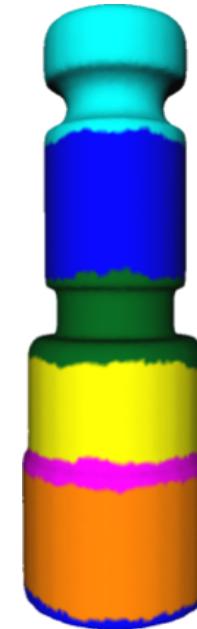
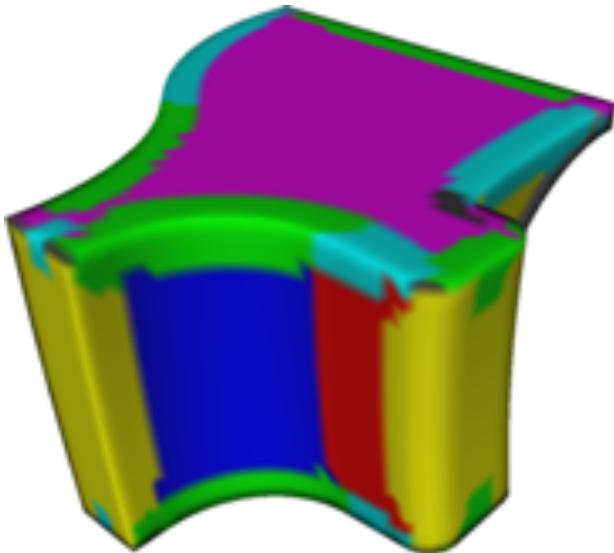
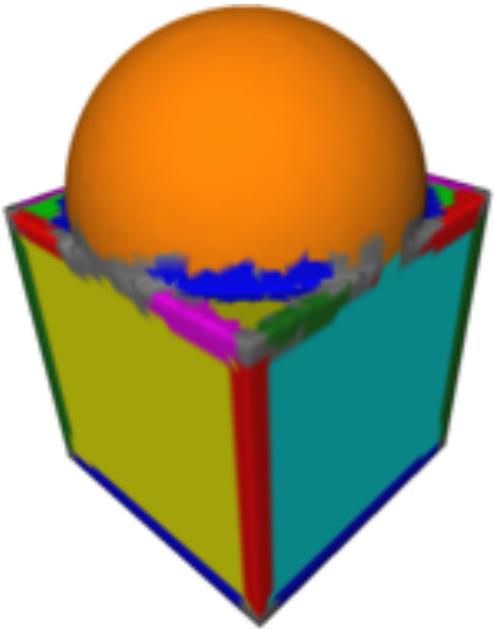


Geometry-only methods

Discussion follows **level of the entity**:

- Scene-level functionality
- Object-level functionality
- **Part-level functionality**

Part-level functionality



- “Shape segmentation using local slippage analysis” [[GG04](#)]
- Discover **slippable motions** of a shape
- Reveal **regions of shapes** that are **kinematic surfaces** with same motion

Discussion

- Functionality models derived from **geometry** and **structure**
- Models **often** capture **functional properties** of a shape
- **But not all** discovered **properties** relate to **functionality**
- **Handcrafted models** often include only few **manually-defined functionality types**



Geometry + Interaction



Our definition of functionality

Functionality = Geometry + Interaction

Atomic interaction:

<Functional entity, relation, interacting entity>



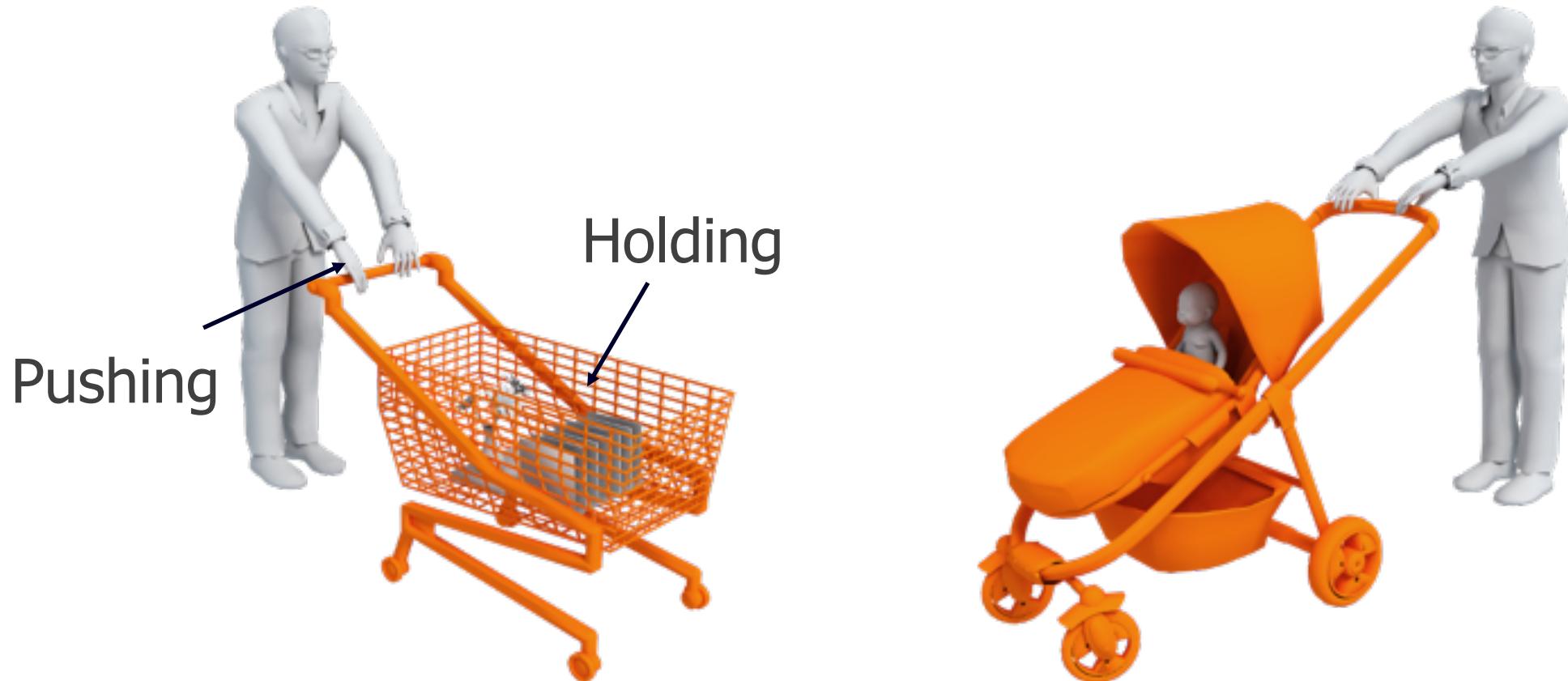
Key observation

- The functionality of an entity is well reflected by **the way how the entity is used when performing its functionality**



Challenges

- Capture multiple, different interactions



Challenges

- Insensitivity to object geometry and count



Books



Trophies

Challenges

- Group interactions in a meaningful manner



Structural organization

Geometry + interaction methods

| Works | Functional entity | Representation of geometry or interactions | | Additional classification criteria | | | |
|----------------------------------|-------------------|--|--|------------------------------------|-----------|-------|----------------|
| | | Component / interacting entity | | Dynamicity | Relations | Input | Approach |
| Geometry+interaction (GI) | | | | | | | |
| Hu et al. [HZvK*15] | object | stat-inter | | stat | BR | pcl | handcrafted |
| Hu et al [HvKW*16] | object | stat-inter | | stat | BR | pcl | supervised |
| Pirk et al. [PKH*17] | object | dyn-inter | | dyn | VF | mesh | handcrafted |
| Myers et al. [MTFA15] | part | stat-inter | | stat | SA | rgbd | supervised |
| Kim et al. [KS14] | part | stat-inter | | stat | SA | rgbd | discriminative |
| Laga et al. [LMS13] | part | stat-inter | | stat | SA+SG | mesh | supervised |
| Hu et al. [HLK*17] | part | stat-inter | | dyn | SA+BR | pcl | supervised |
| Xiang et al. [XQM*20] | part | stat-inter | | dyn | SA | mesh | supervised |
| Hu et al. [HYZ*18] | object | stat-inter | | stat | SA+BR | vol | supervised |
| Yi et al. [YHL*18] | part | stat-inter | | dyn | SA | pcl | supervised |
| Wang et al. [WZS*19] | part | stat-inter | | dyn | SA | pcl | supervised |
| Yan et al. [YHY*19] | part | stat-inter | | dyn | SA | pcl | supervised |
| Li et al. [LWY*20] | part | stat-inter | | dyn | SA | pcl | supervised |
| Kokic et al. [KSHK17] | part | stat-inter | | dyn | SA | pcl | supervised |
| Li et al. [LSK20] | part | stat-inter | | dyn | SA | pcl | generative |



Geometry + interaction methods

- Handcrafted descriptors
 - Atemporal interaction
 - Time-varying interaction
- Supervised learning
 - Object-level functionality
 - Discriminative recognition
 - Generative modeling
 - Part-level functionality
 - Atemporal interaction
 - Time-varying interaction



Geometry + interaction methods

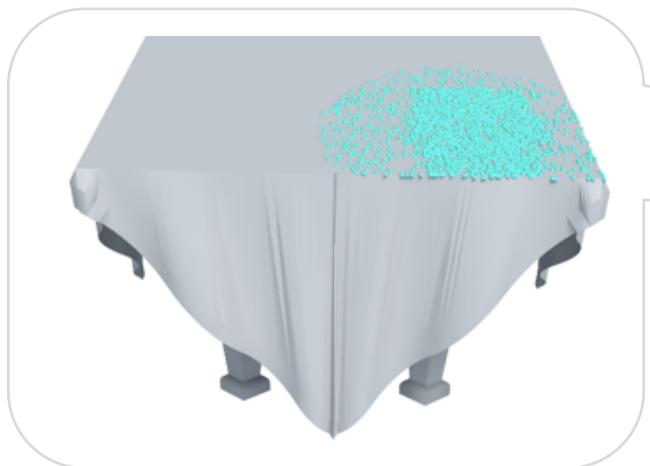
- **Handcrafted descriptors**
 - Atemporal interaction
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Geometry + interaction methods

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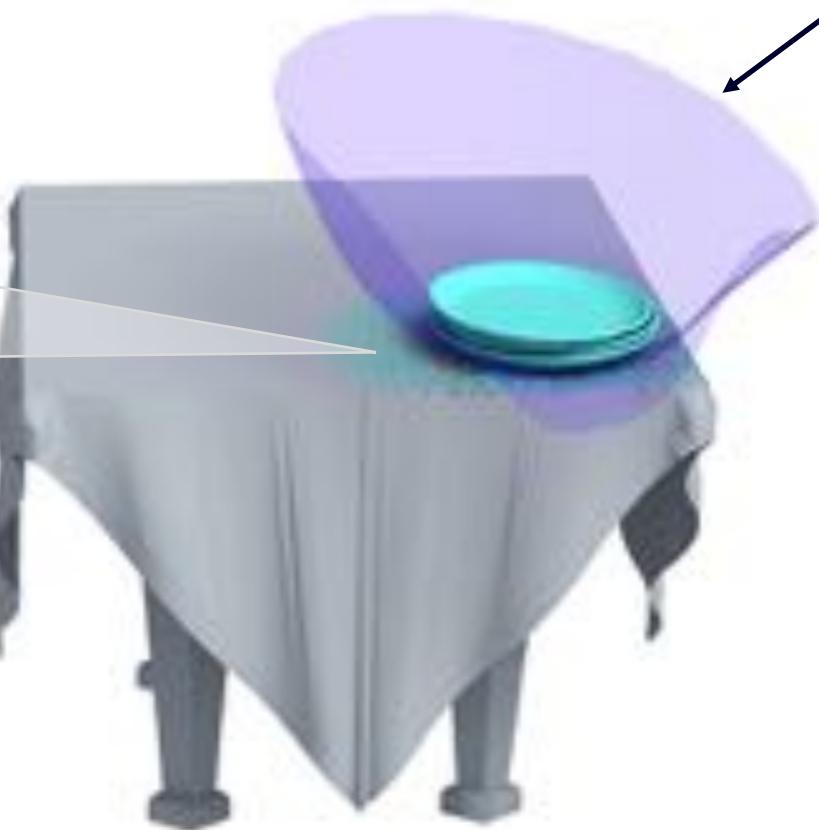


Atemporal interaction representation



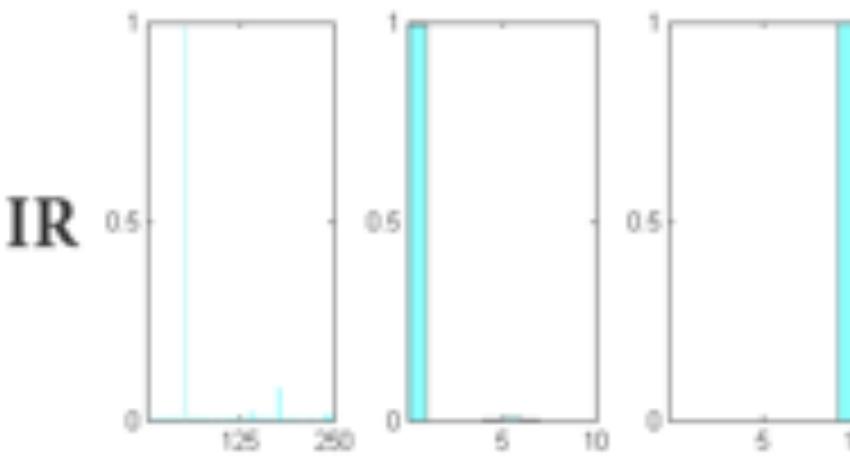
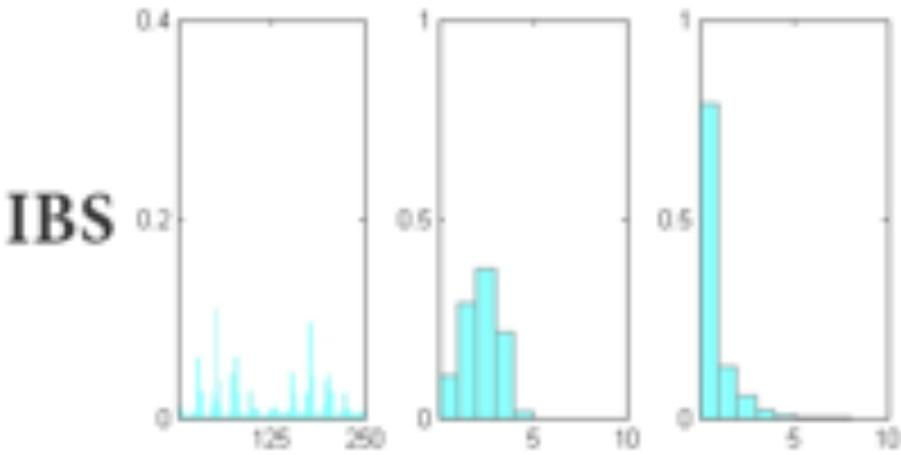
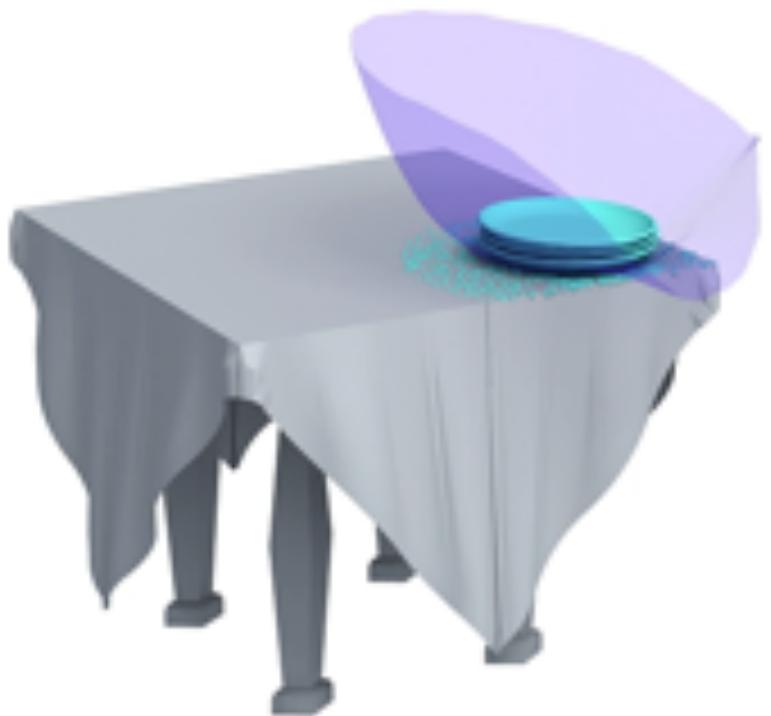
Interaction Region

[HZvK*15]

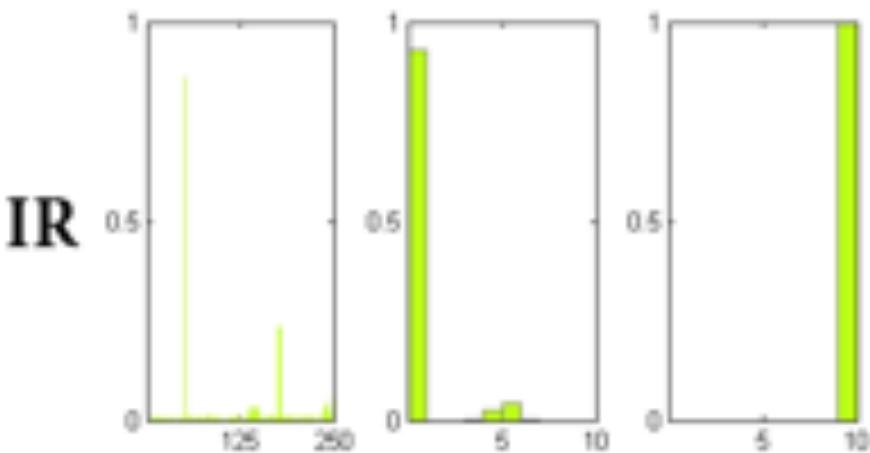
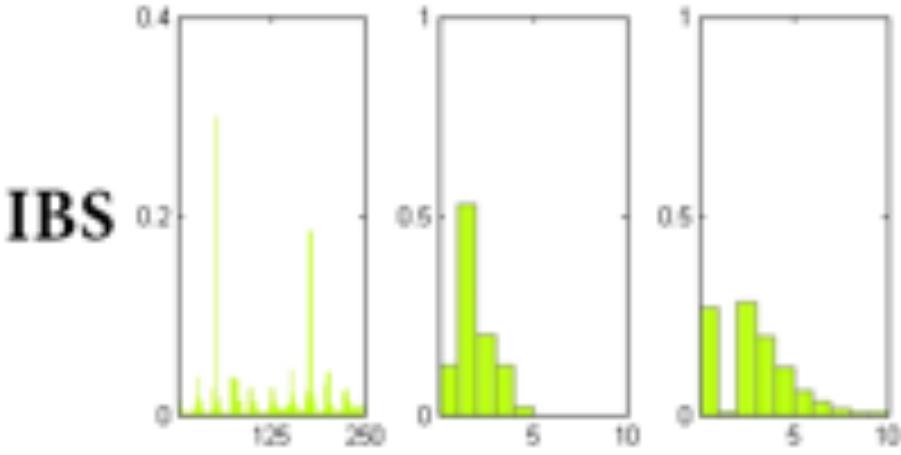
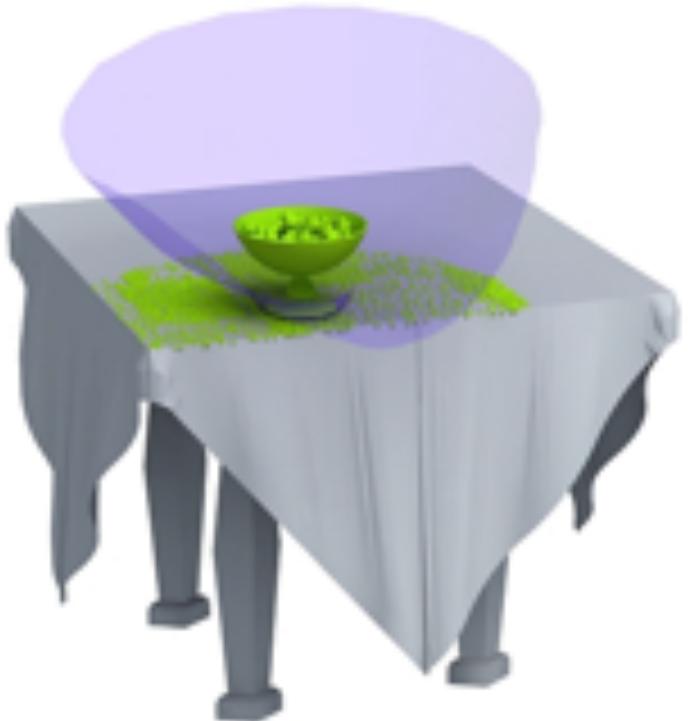


Interaction Bisector Surface
[ZWK14]

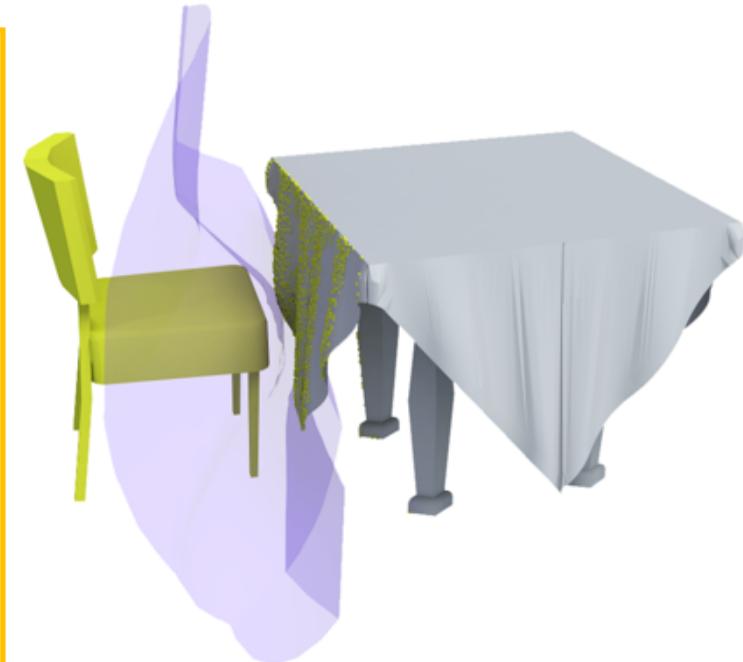
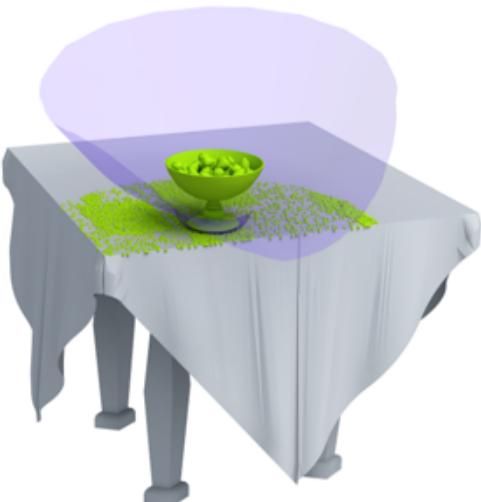
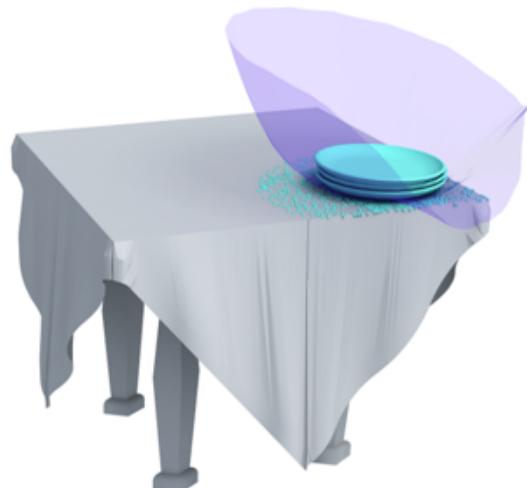
Atemporal interaction representation



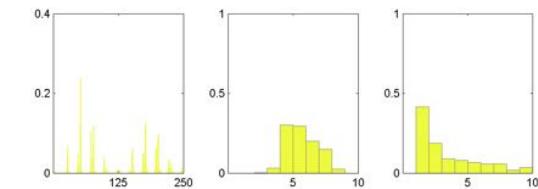
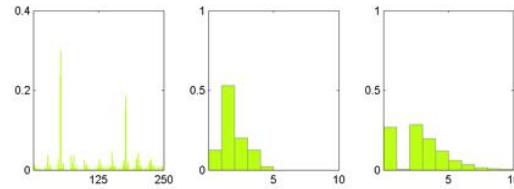
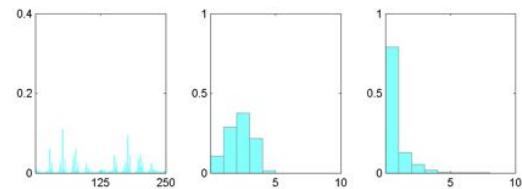
Atemporal interaction representation



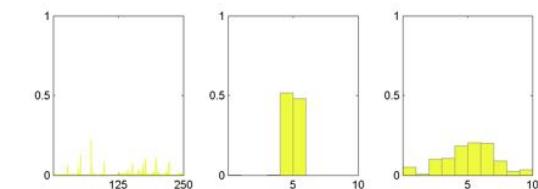
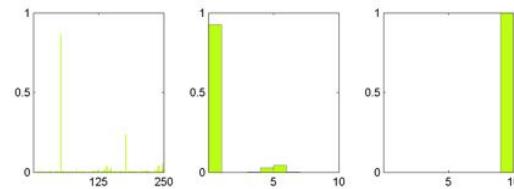
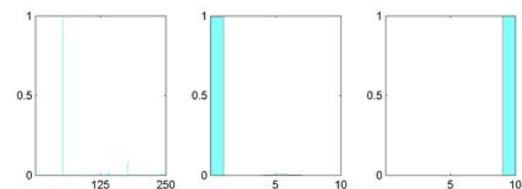
Atemporal interaction representation



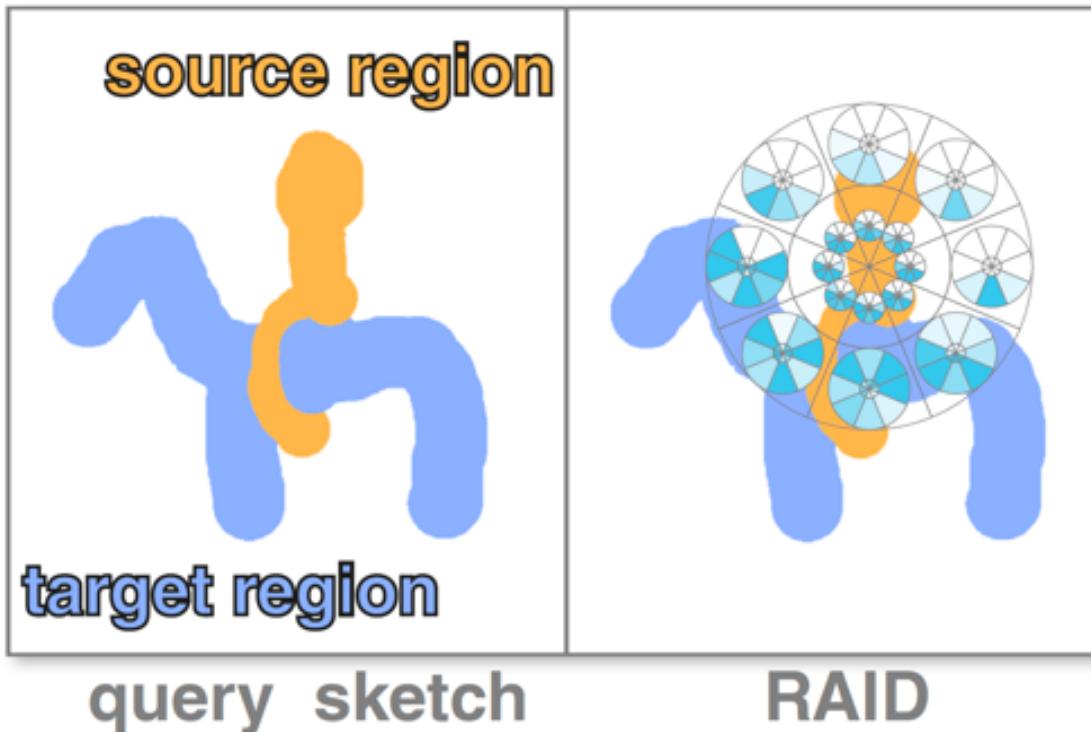
IBS



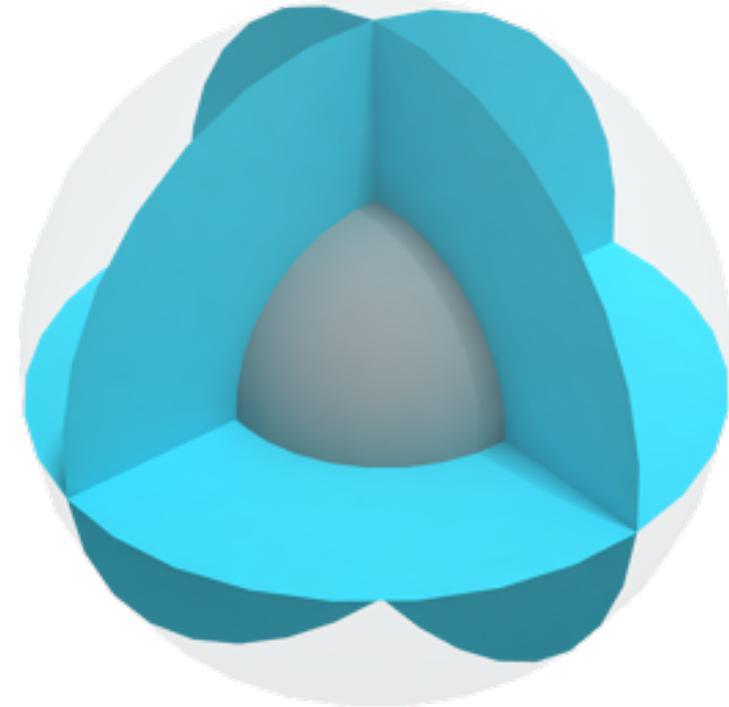
IR



Atemporal interaction representation

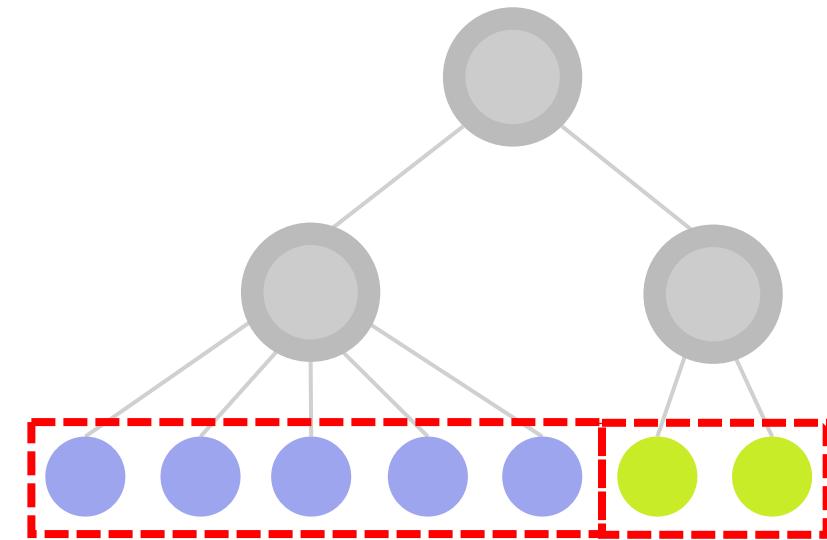
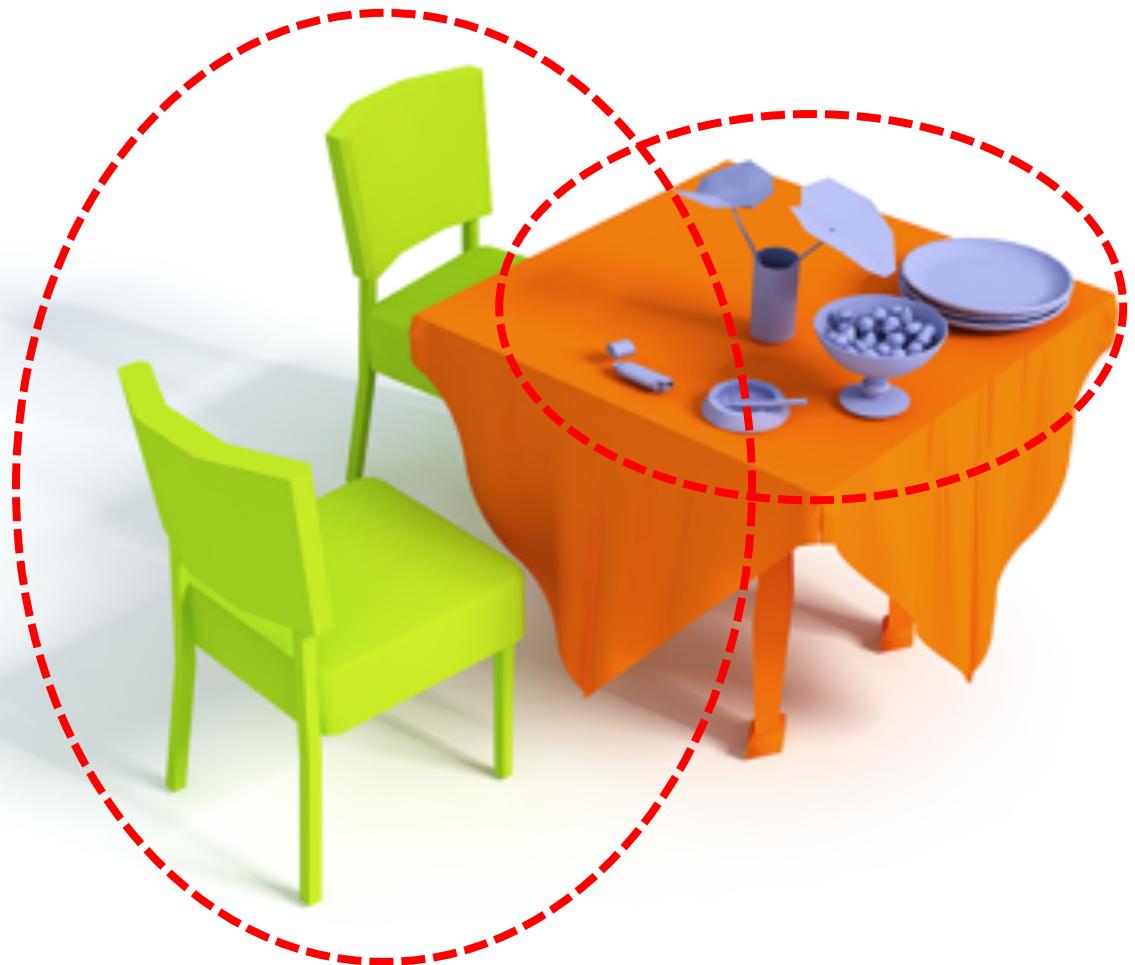


RAID: A Relation-Augmented Image Descriptor
[GMW16]



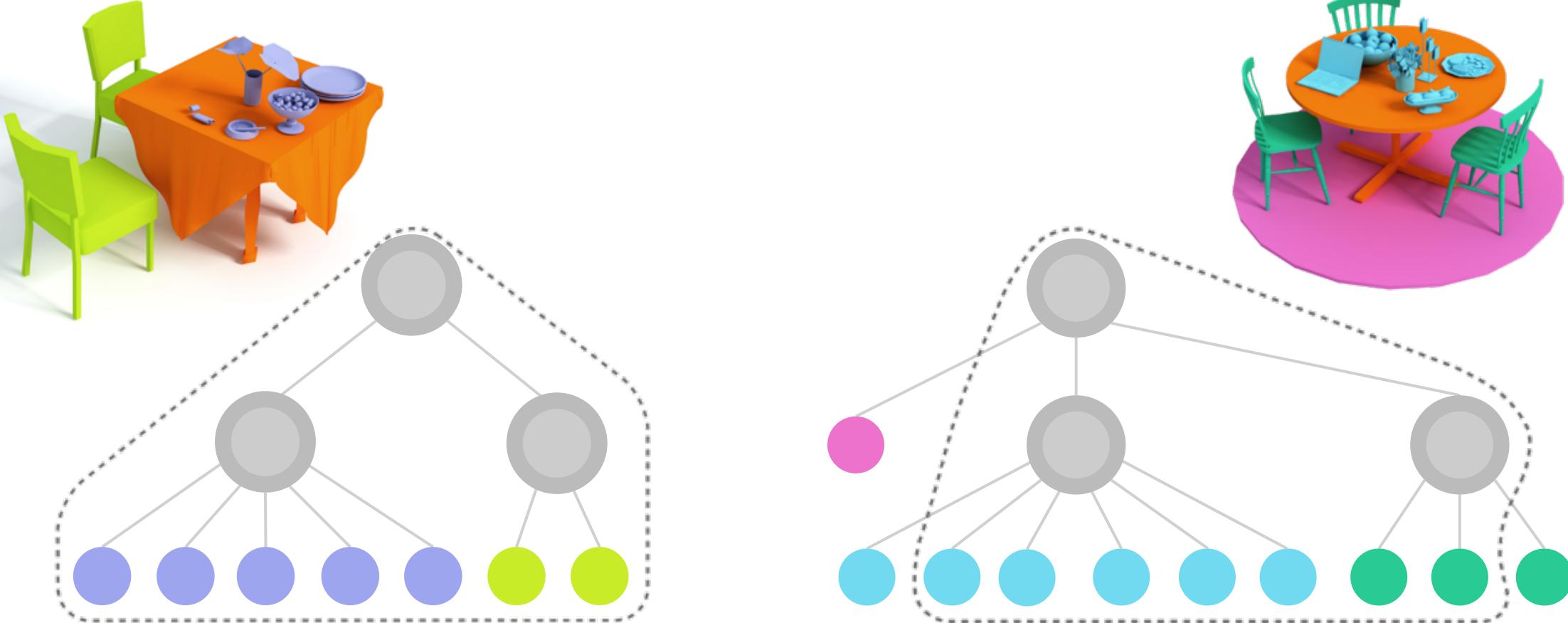
3D RAID
[HLK*17]

Atemporal multi-interaction organization



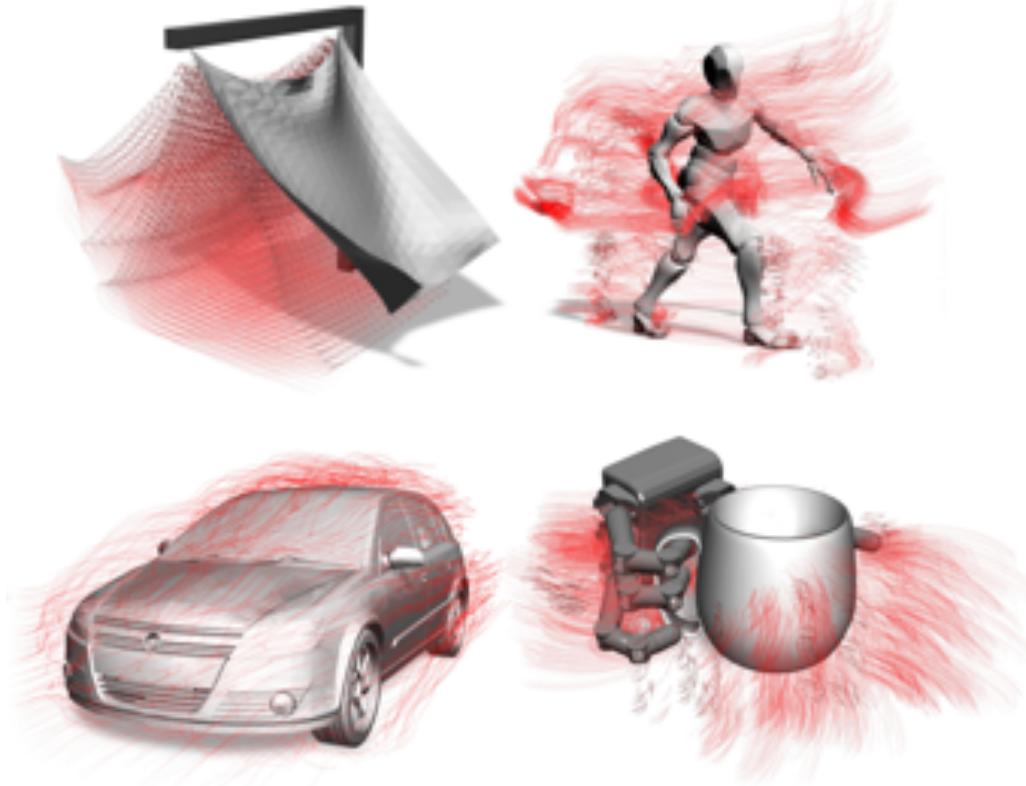
Interaction context (ICON)
[HzvK*15]

Atemporal multi-interaction organization



Geometry + interaction methods

- **Handcrafted descriptors**
 - Atemporal interaction
 - **Time-varying interaction**
- Supervised learning
 - Object-level functionality
 - Discriminative recognition
 - Generative modeling
 - Part-level functionality
 - Atemporal interaction
 - Time-varying interaction



[PKH*17]

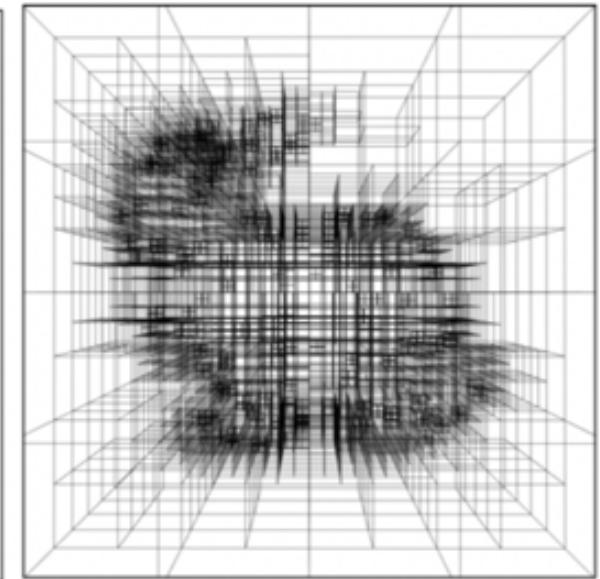
Time-varying interaction representation



Motion particles



Sensor regions



Interaction Landscapes descriptor
[PKH*17]

Application: interaction-based retrieval

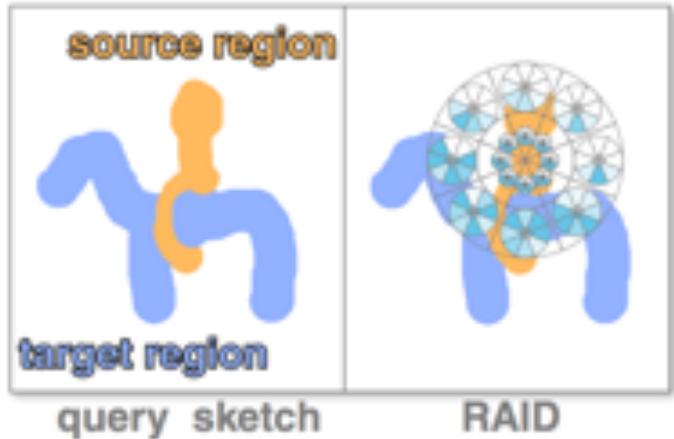


image
retrieval
→



RAID
[GMW16]



ICON [HZvK*15]



Interaction Landscapes descriptor [PKH*17]

Functionality recognition



Backpack

Chair

Drying Rack

Handcart

Hook

⋮



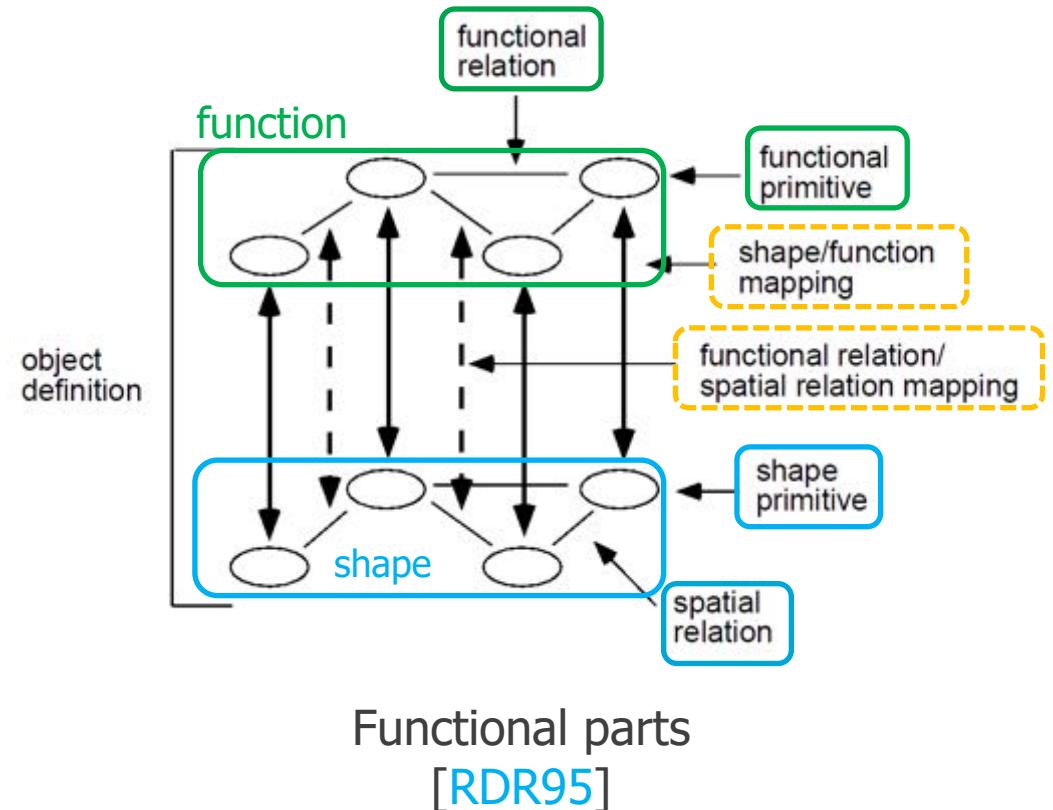


Geometry + interaction methods

- Handcrafted descriptors
 - Atemporal interaction
 - Time-varying interaction
- **Supervised learning**
 - Object-level functionality
 - Discriminative recognition
 - Generative modeling
 - Part-level functionality
 - Atemporal interaction
 - Time-varying interaction

Geometry + interaction methods

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 - **Part-level functionality**
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 - Time-varying interaction



Object-level functionality recognition



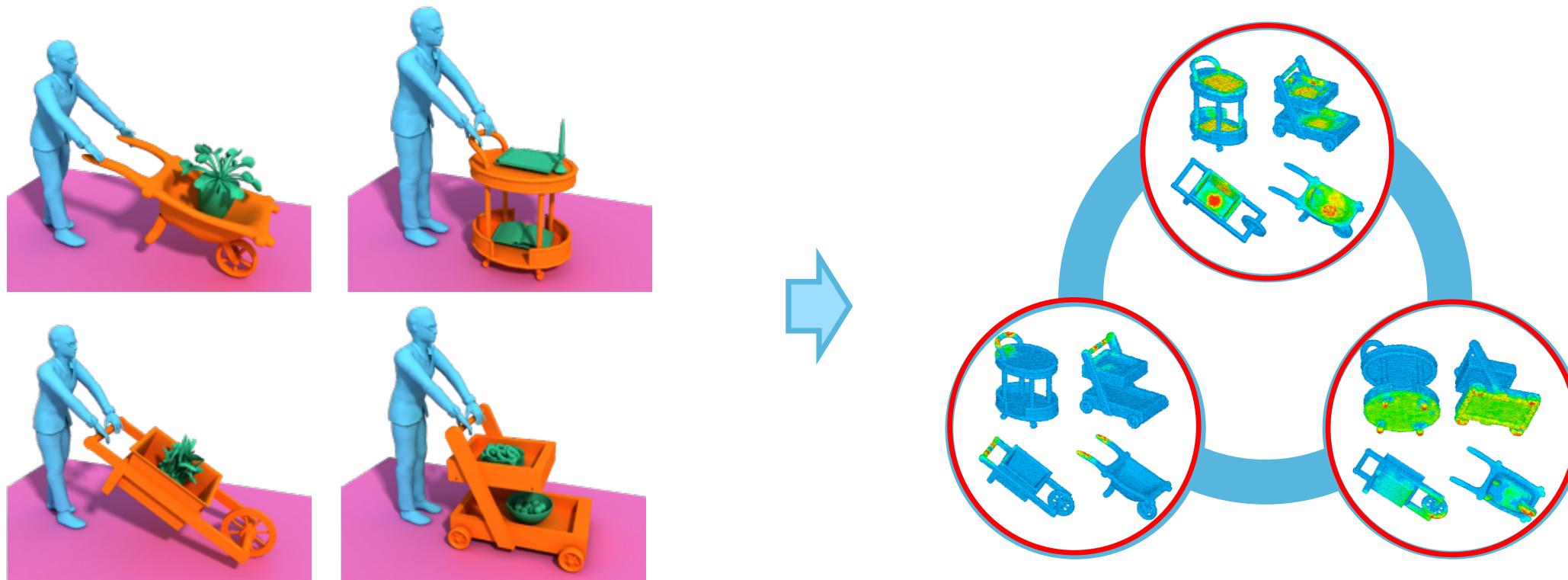
Learning how objects function via co-analysis of interactions
[HvKW*16]

Object-level functionality recognition



Learning how objects function via co-analysis of interactions
[HvKW*16]

Object-level functionality recognition



Learning how objects function via co-analysis of interactions
[HvKW*16]

Object-level functionality recognition



Learning how objects function via co-analysis of interactions
[HvKW*16]

Application: function enhancement



Learning how objects function via co-analysis of interactions
[HvKW*16]

Generative model



Object usage hallucination

Functionality recognition and context generation



Table



Desk



PG-DNN

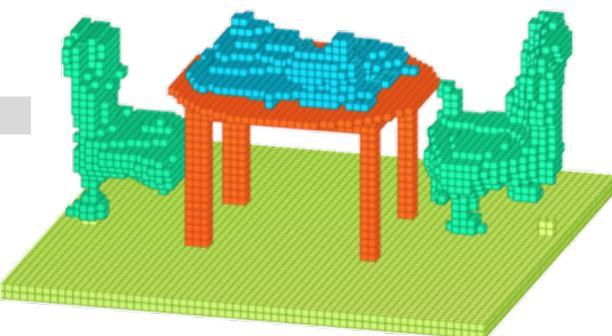


fSIM-NET

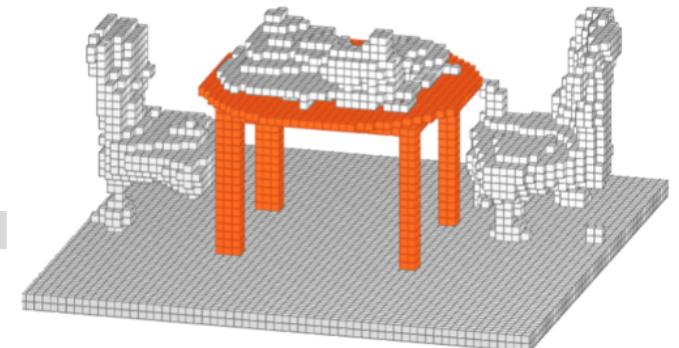
Desk
Bench

Table

iGEN-NET

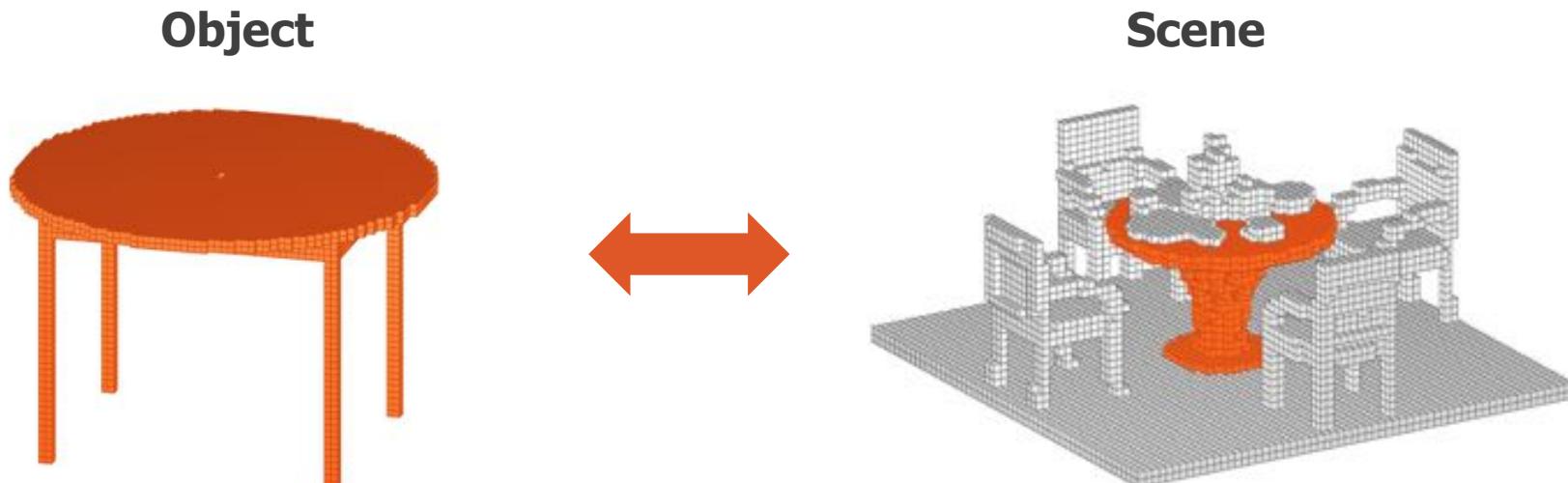


iSEG-NET

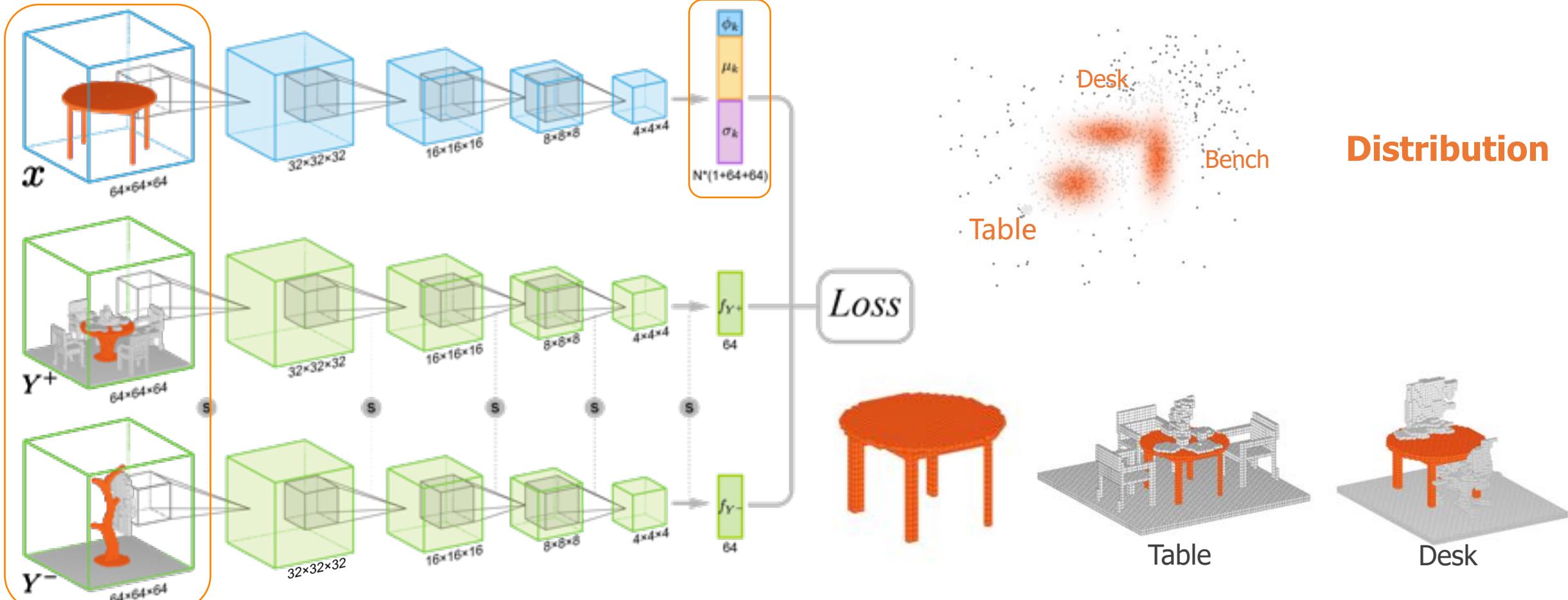


Goal 1: Functionality prediction

- Map given object to scenes showing suitable functionalities
 - Learn a functional similarity measure between **objects** and **scenes**

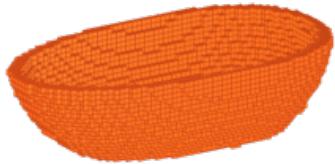


fSIM-NET



Multi-functionality

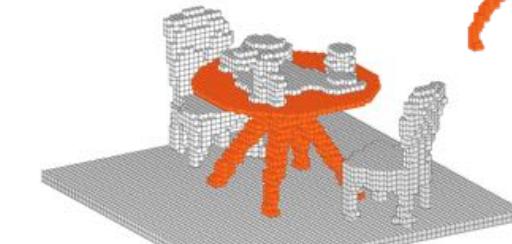
Bathtub



Bowl



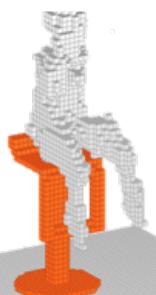
Table



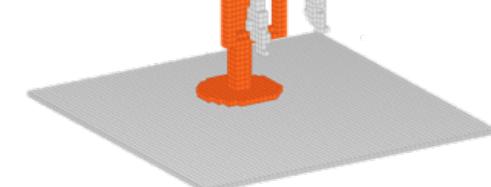
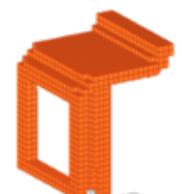
Desk



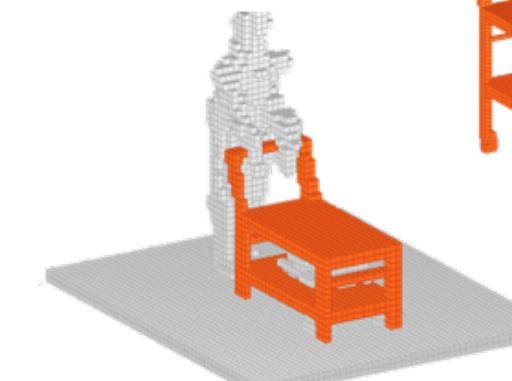
Stool



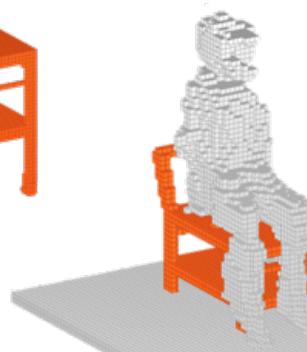
Lamp



Handcart



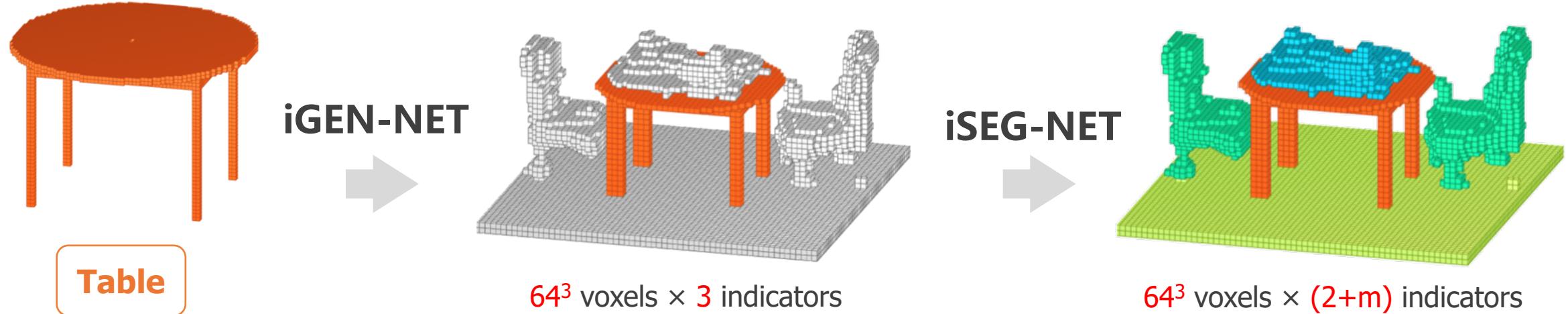
Chair



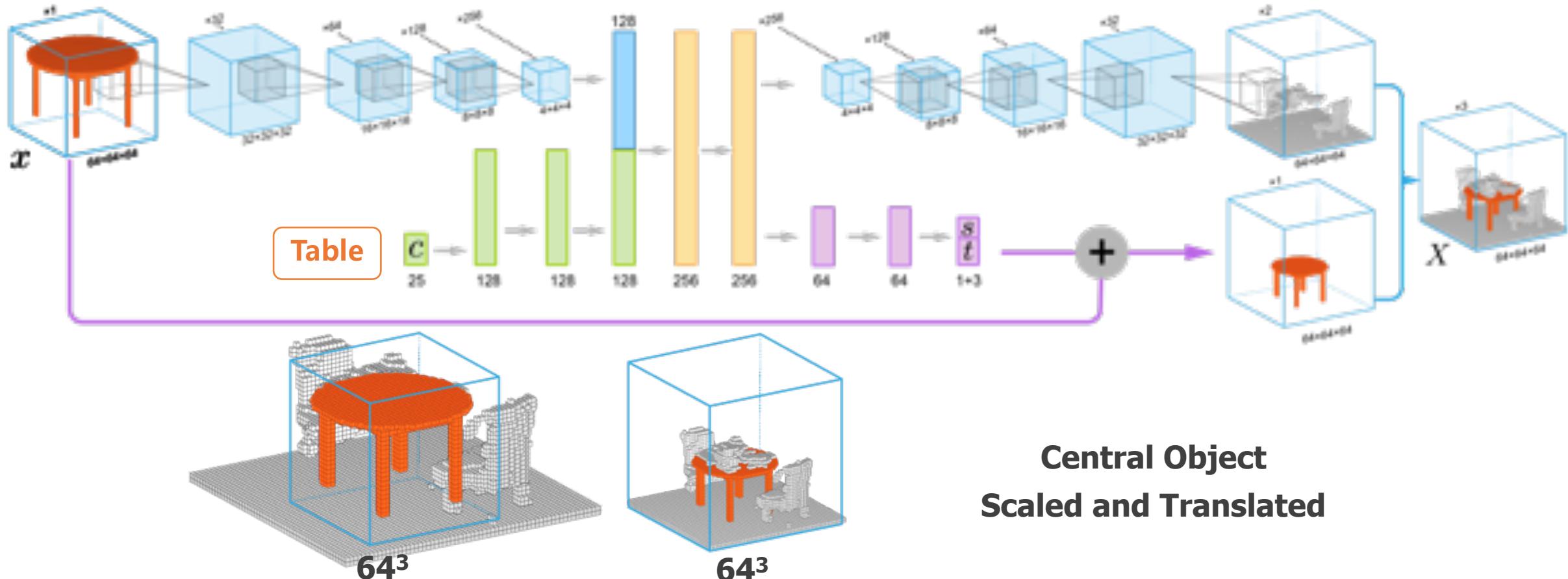
Predictive and Generative Neural Networks for Object Functionality
[HYZ*18]

Goal 2: Object usage hallucination

- Achieve into two steps: context generation and segmentation

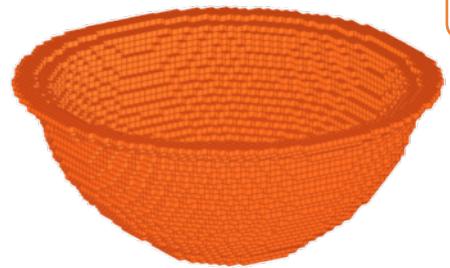


iGEN-NET

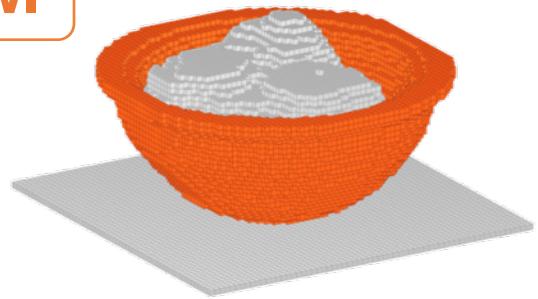


Predictive and Generative Neural Networks for Object Functionality
[HYZ*18]

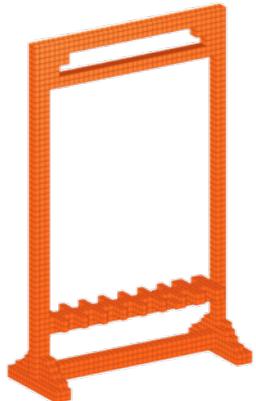
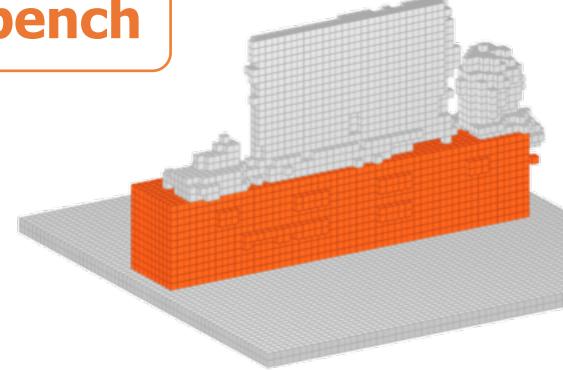
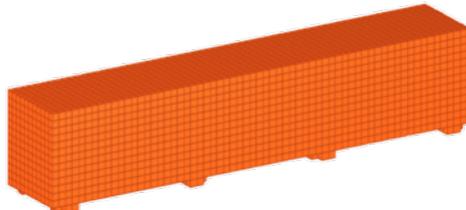
Generation results



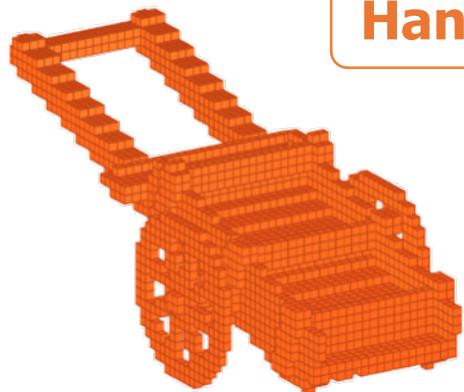
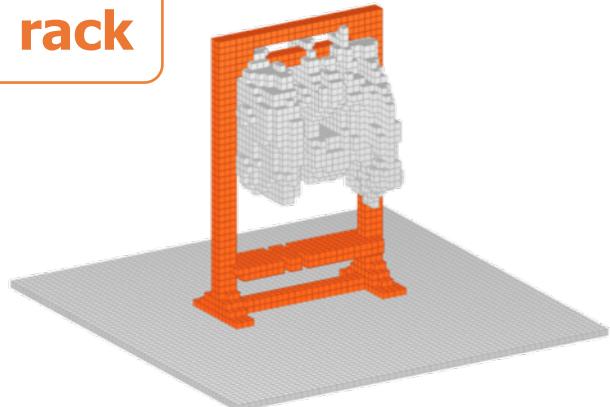
Bowl



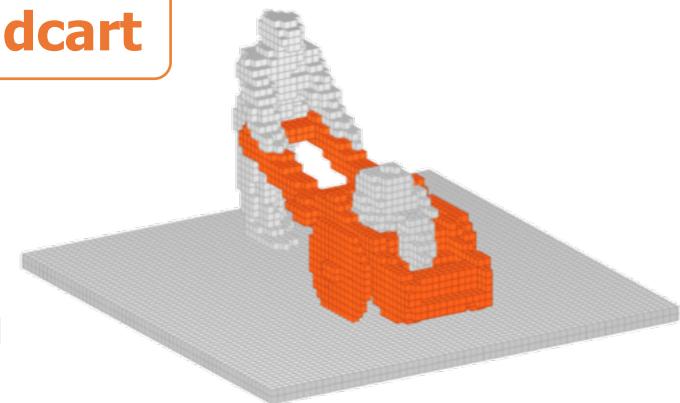
TV bench



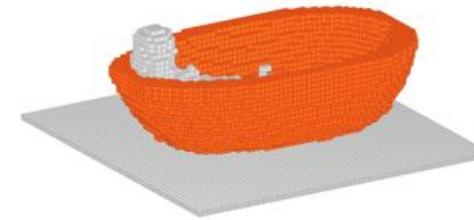
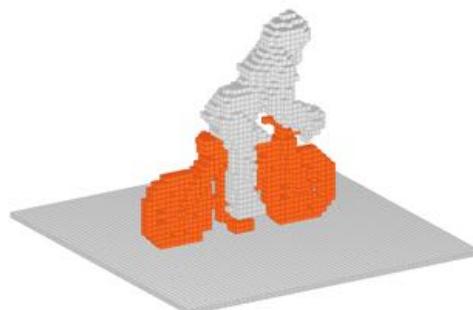
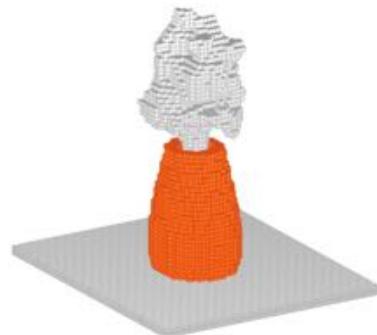
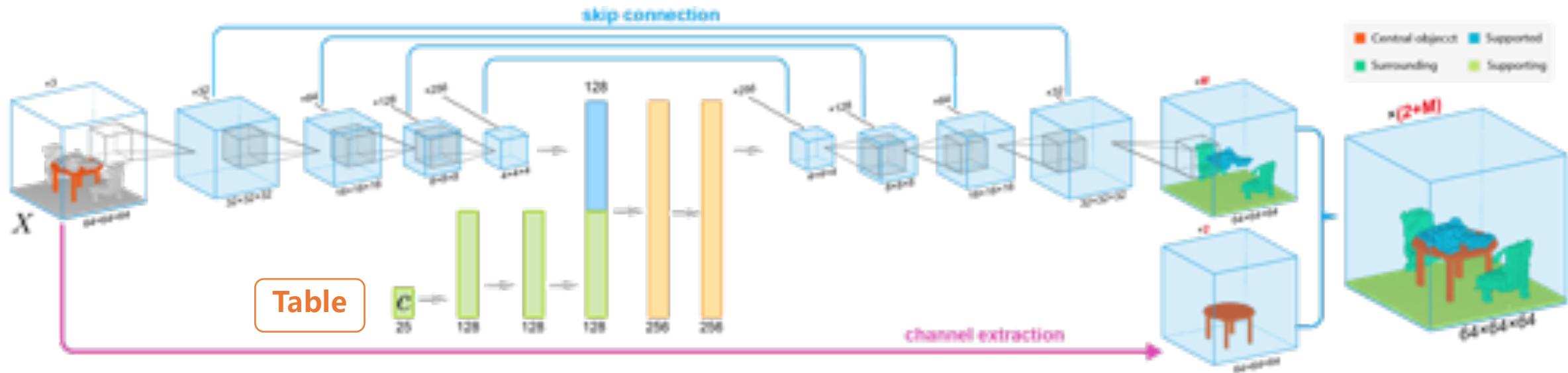
Drying rack



Handcart



iSEG-NET

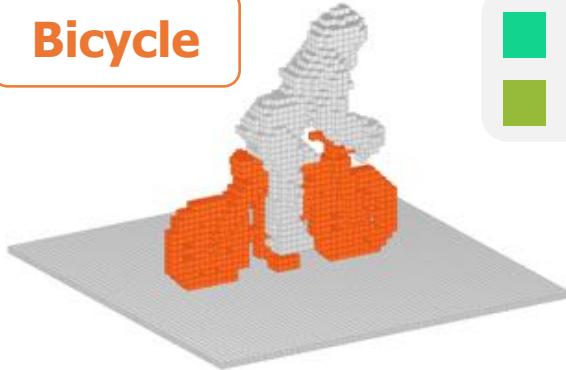


Central Object
Fixed

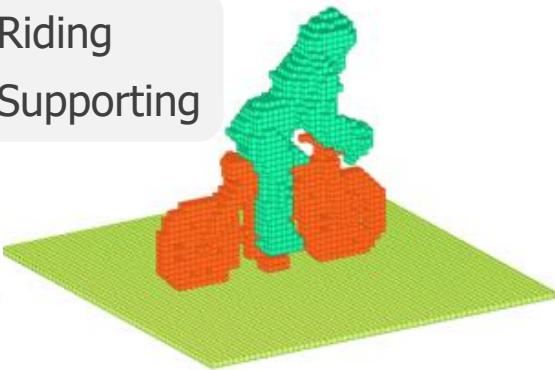
Predictive and Generative Neural Networks for Object Functionality
 [HYZ*18]

Segmentation results

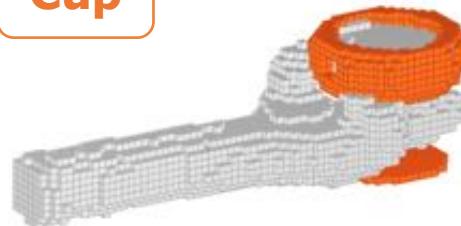
Bicycle



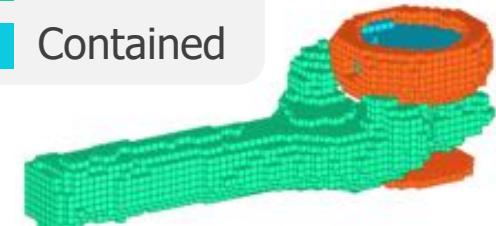
Riding
Supporting



Cup



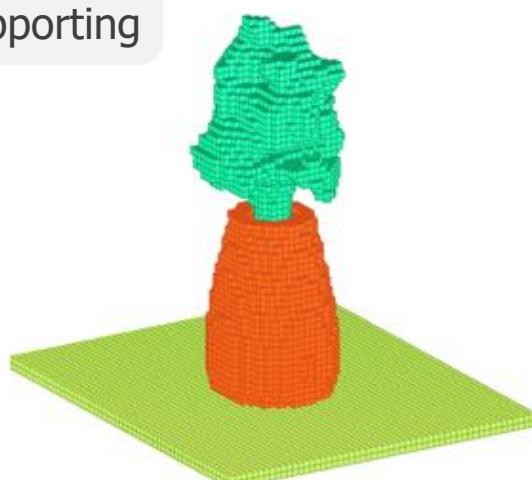
Holding
Contained



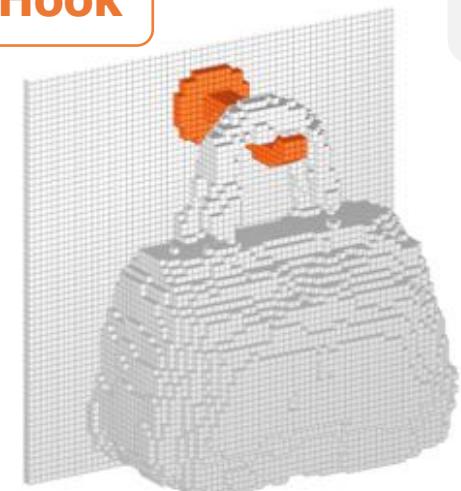
Vase



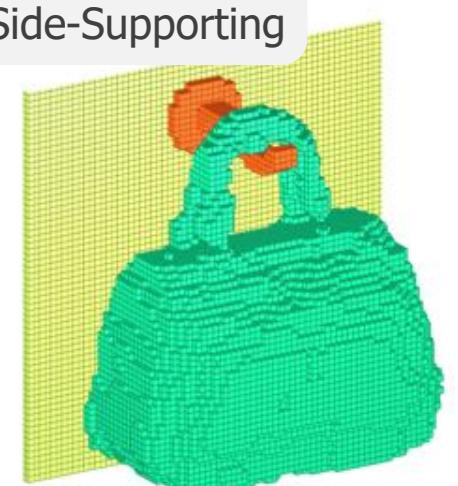
Contained
Supporting



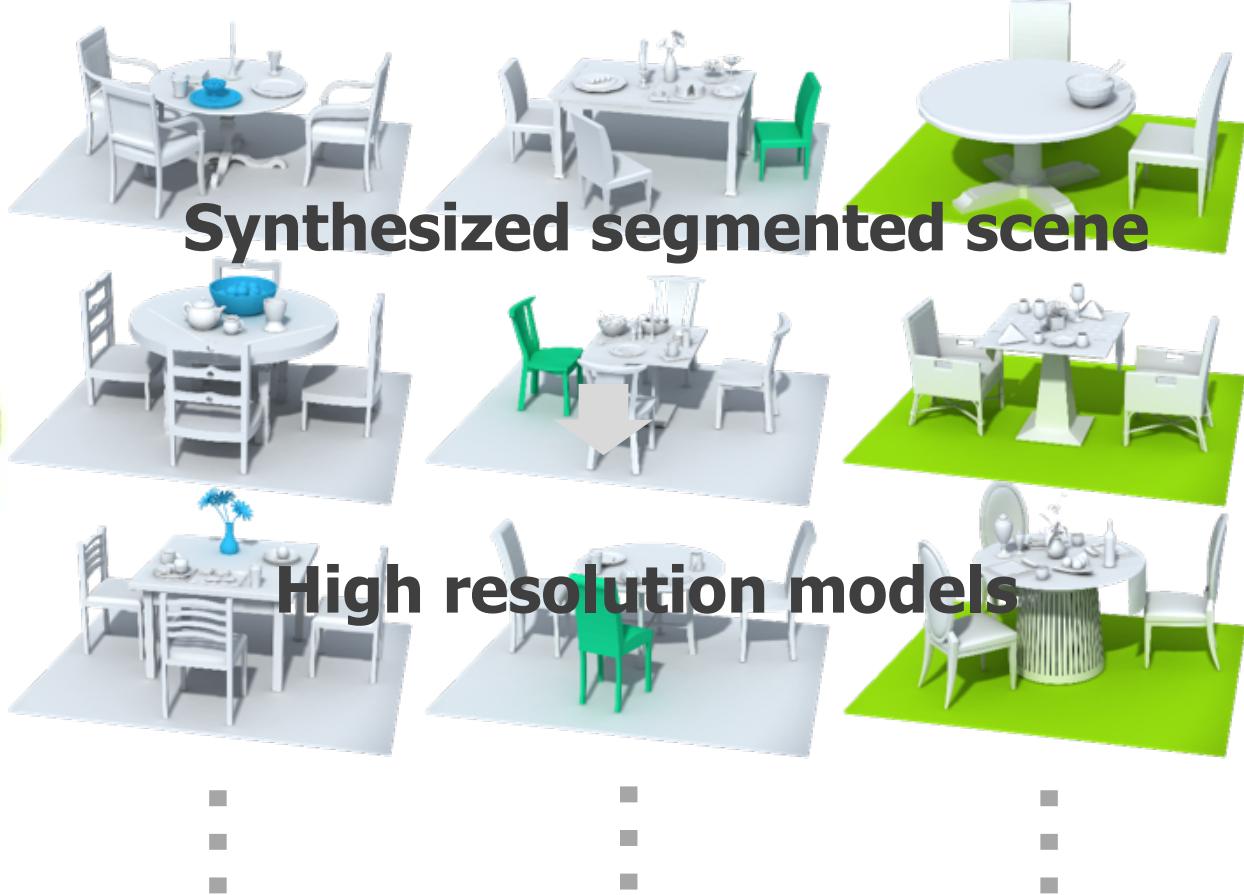
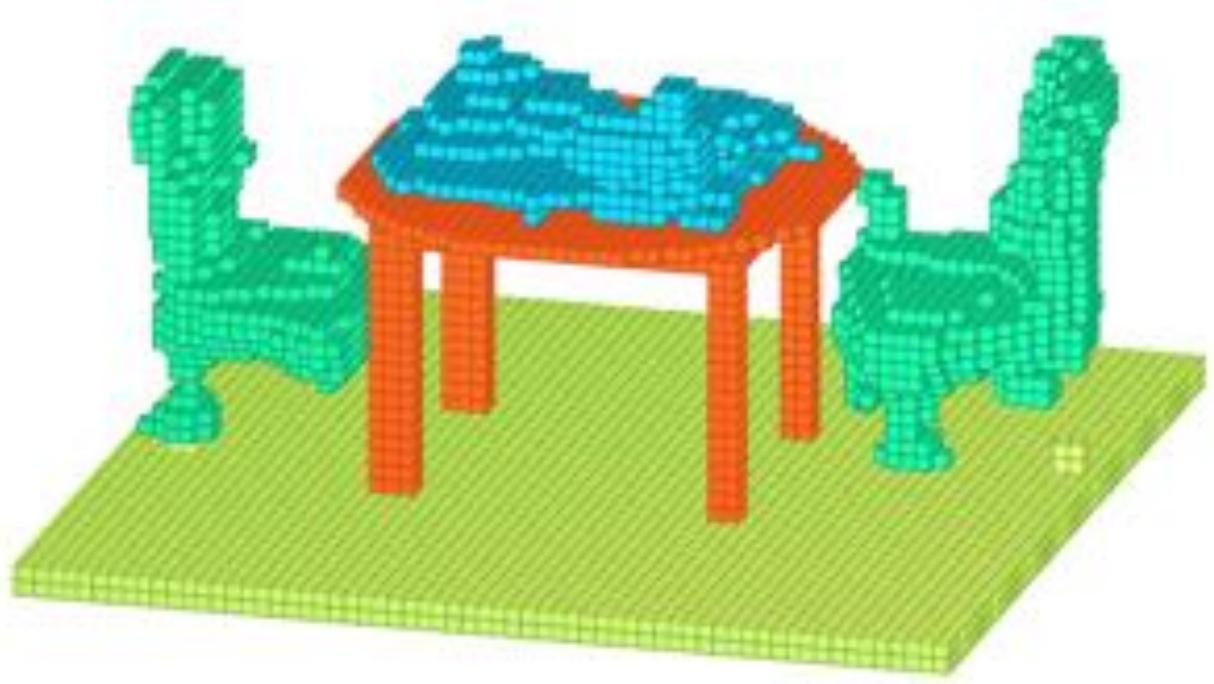
Hook



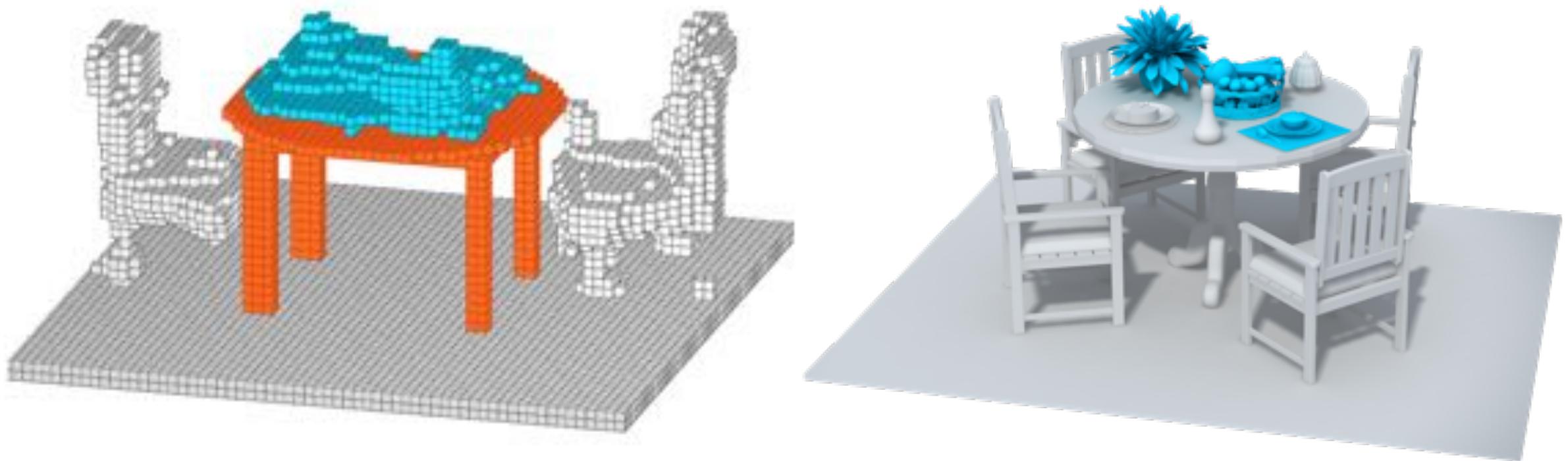
Hanging
Side-Supporting



Scene refinement

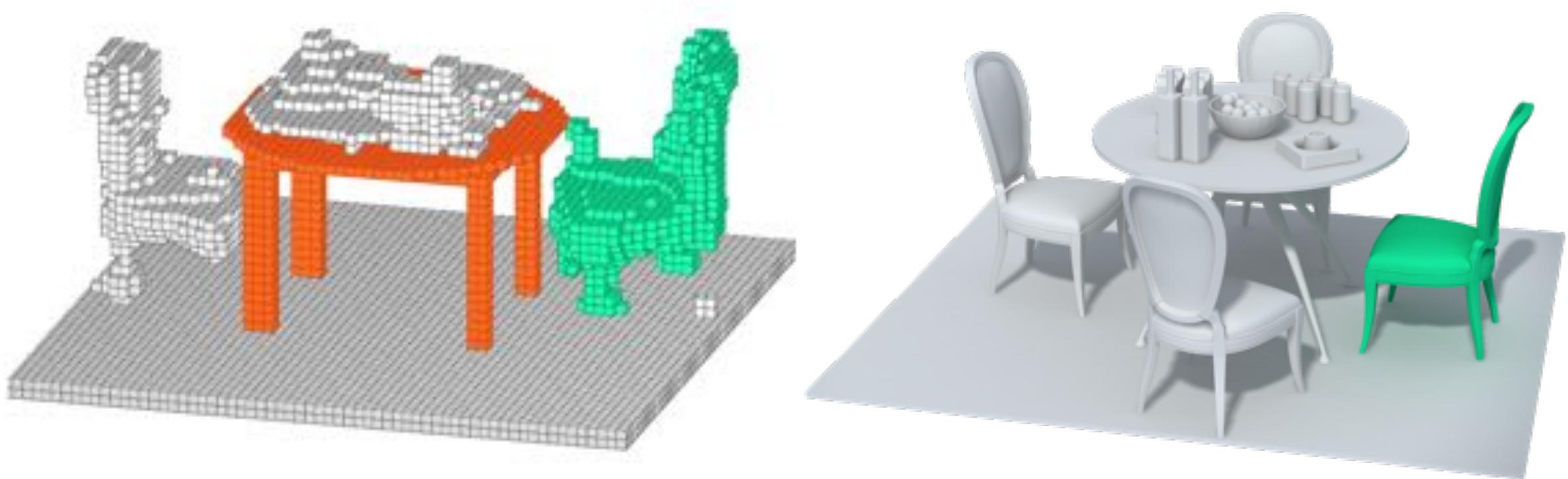


Scene refinement



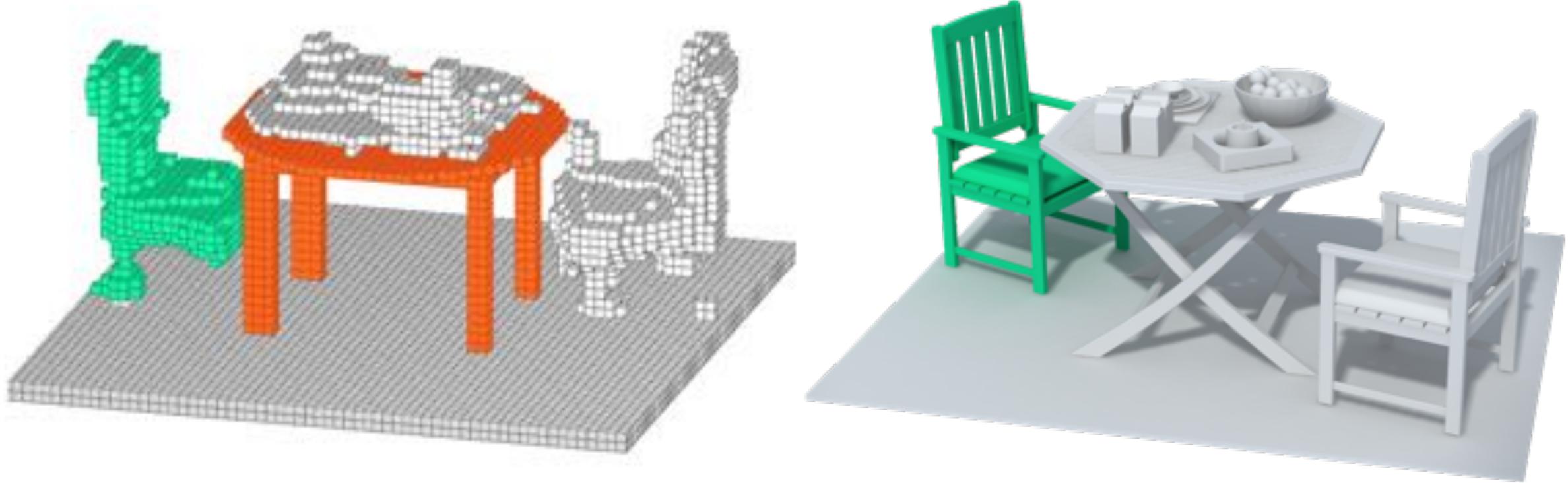
Predictive and Generative Neural Networks for Object Functionality
[HYZ*18]

Scene refinement



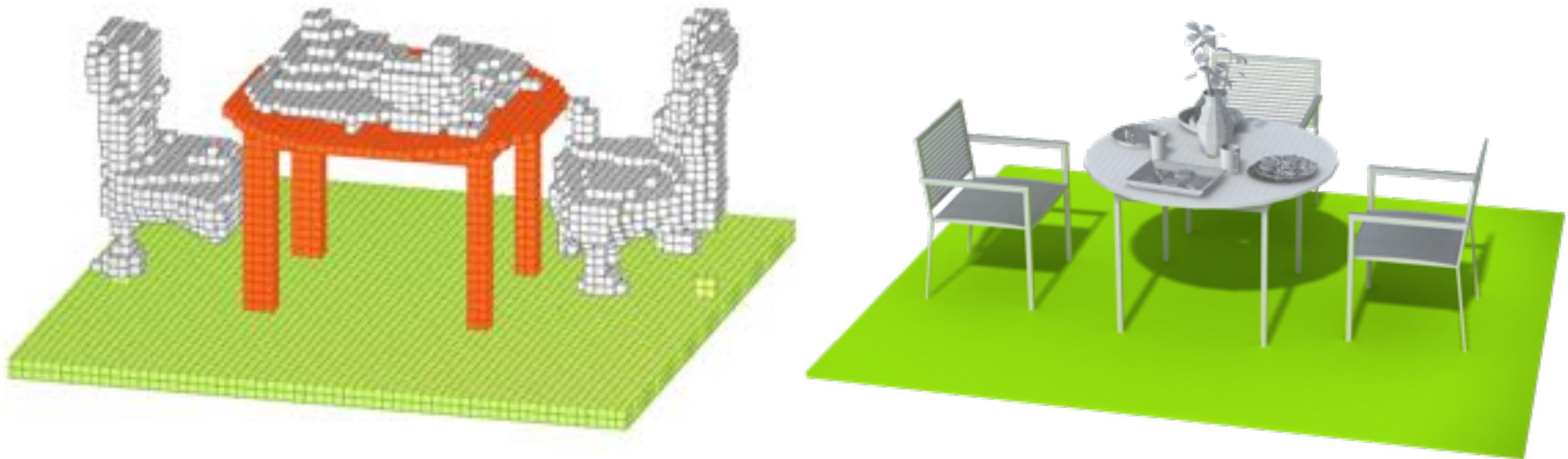
Predictive and Generative Neural Networks for Object Functionality
[HYZ*18]

Scene refinement



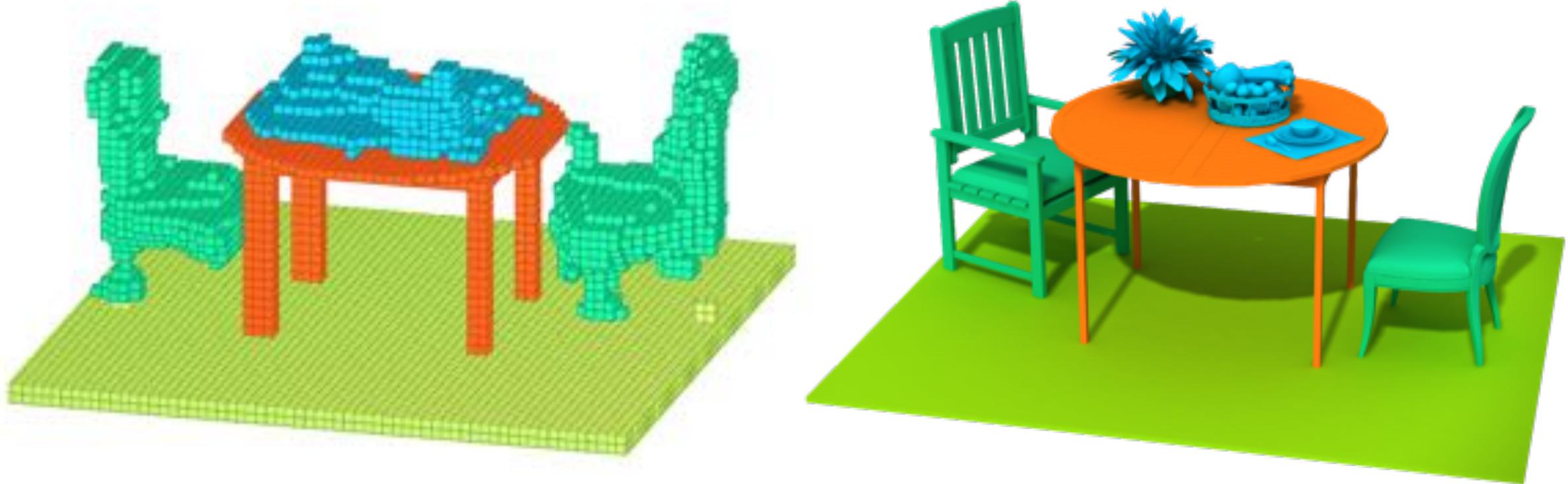
Predictive and Generative Neural Networks for Object Functionality
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Scene refinement

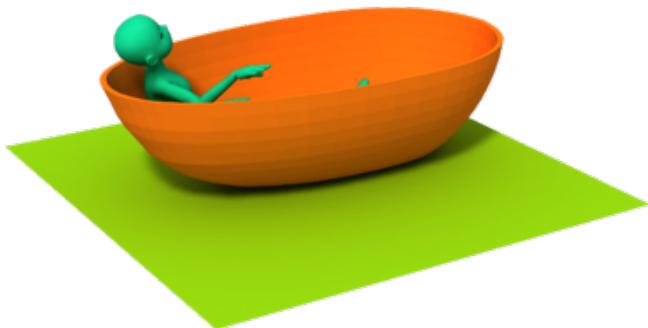
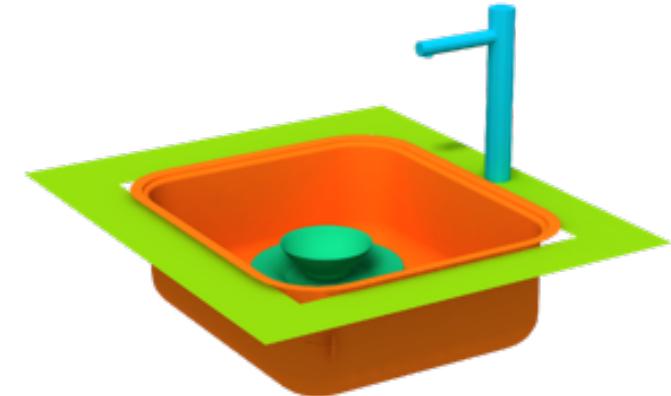
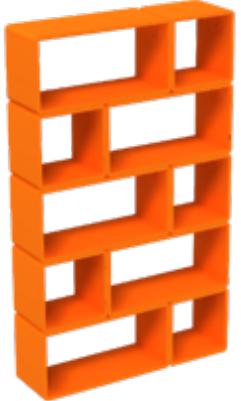


Predictive and Generative Neural Networks for Object Functionality
[HYZ*18]

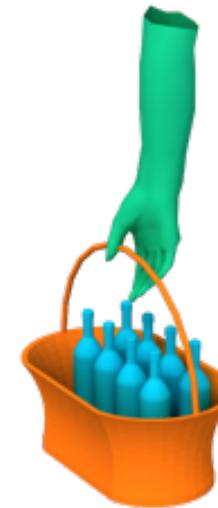
Scene refinement



Final results



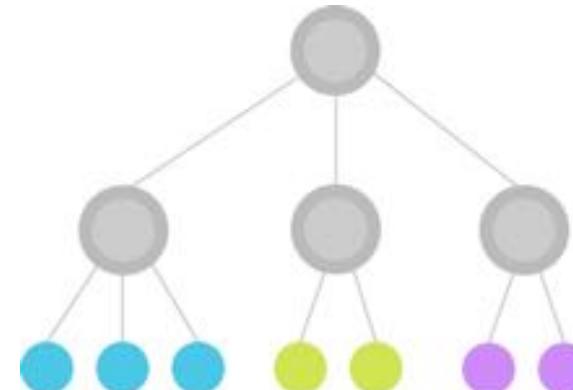
Final results



Predictive and Generative Neural Networks for Object Functionality
[HYZ*18]

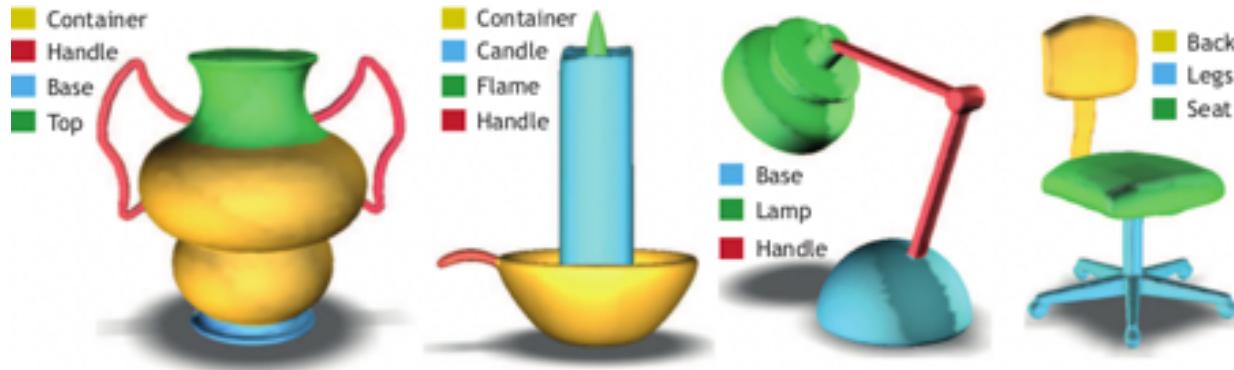
Geometry + interaction methods

- Handcrafted descriptors
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 - Time-varying interaction
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 - Object-level functionality
 - Discriminative recognition
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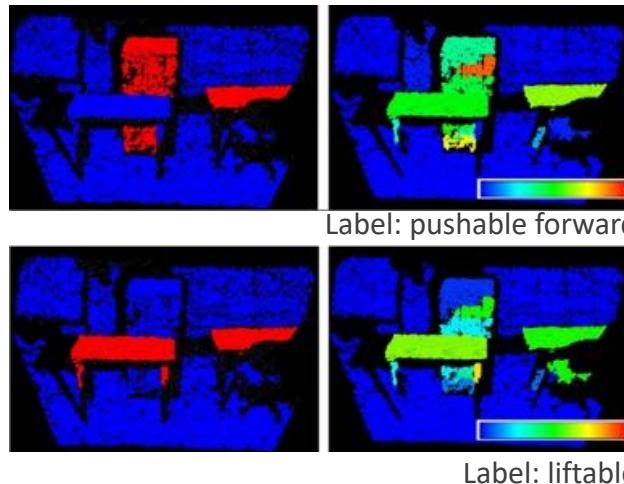


[HZvK*15]

Part-level semantic labeling (atemporal)

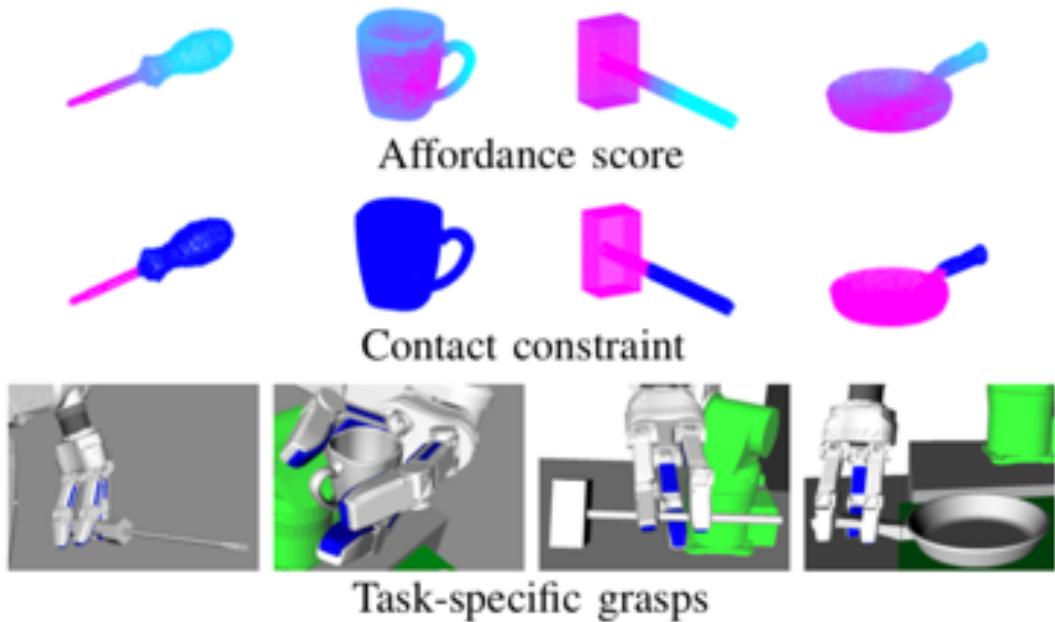


Segmentation and semantic labeling
[LMS13]

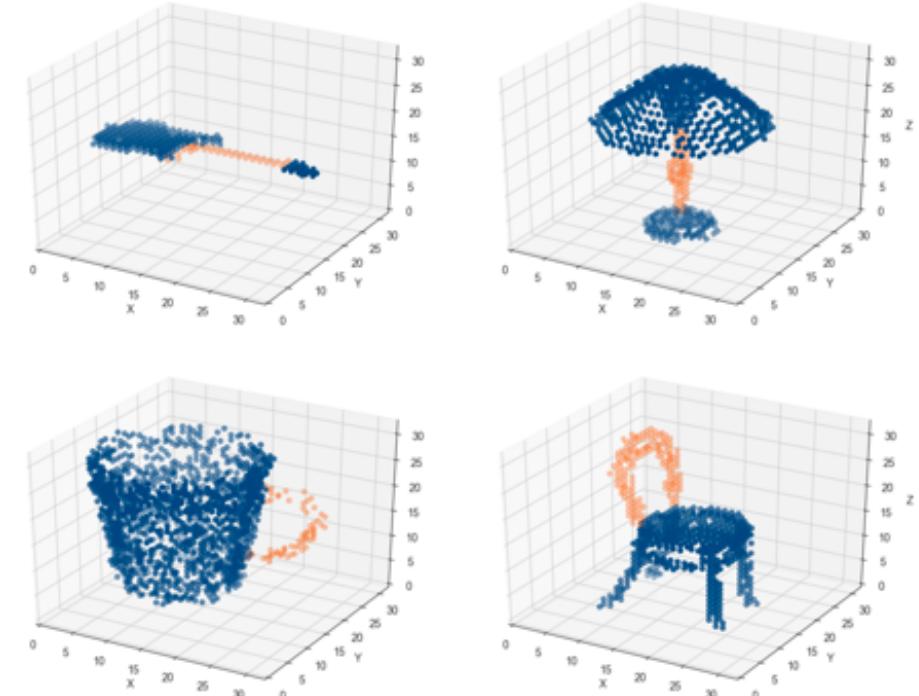


Semantic labeling with object affordance
[KS14]

Part-level grasping affordance prediction (atemporal)



Affordance detection for task-specific grasping
[KSHK17]



Learning to grasp 3d objects
[LSK20]

Part-level mobility prediction (Time-varying interaction)



Static shape



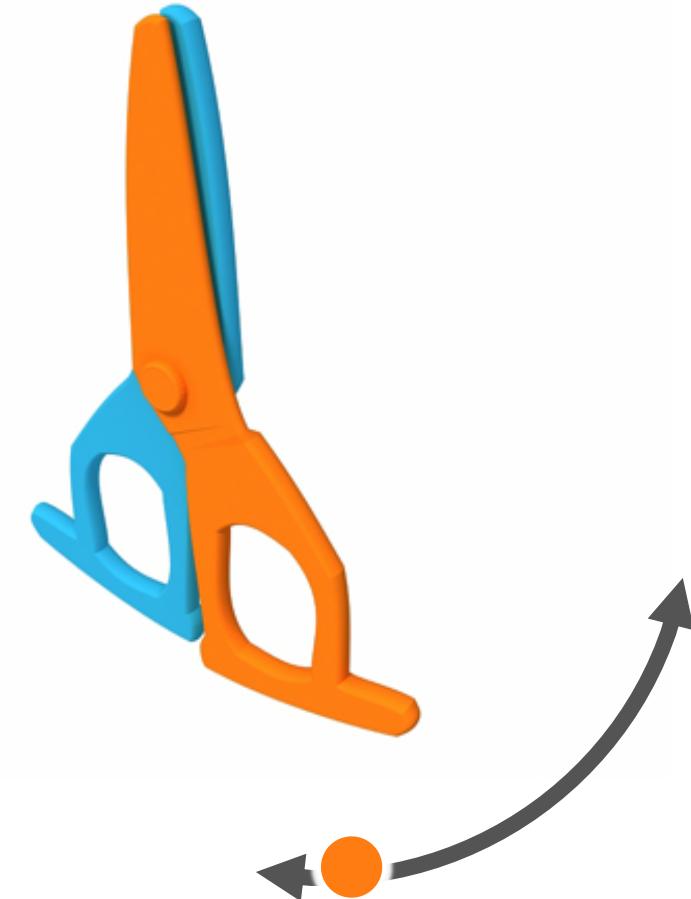
**Pre-segmented
input**



Dynamic motion

Learning to predict part mobility from a single static snapshot
[HLK*17]

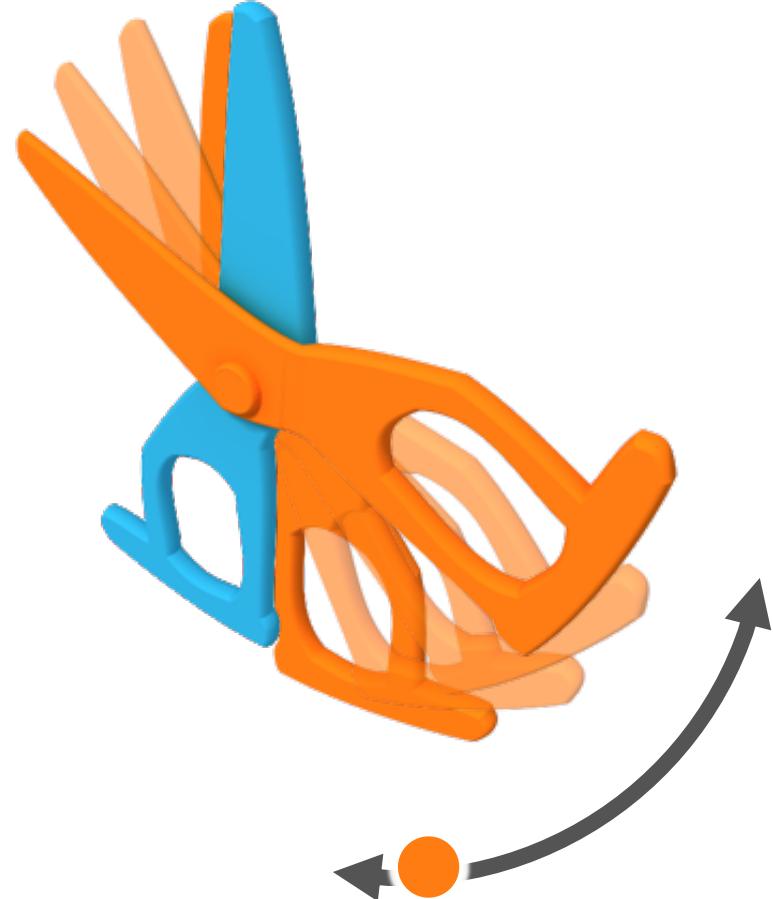
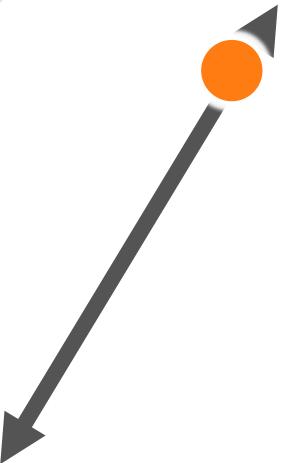
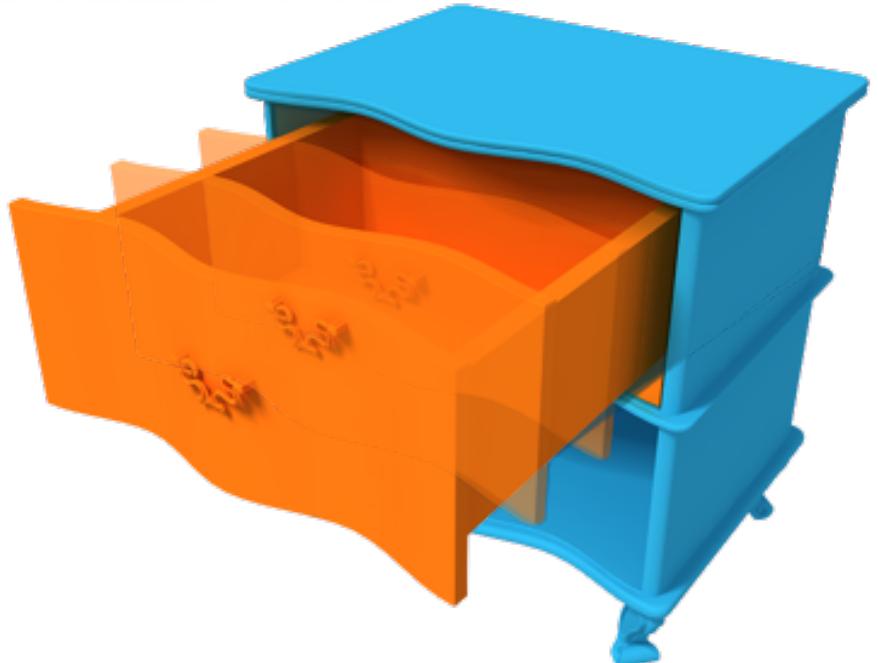
Key observation: linearity of motion



Learning to predict part mobility from a single static snapshot

[HLK*17]

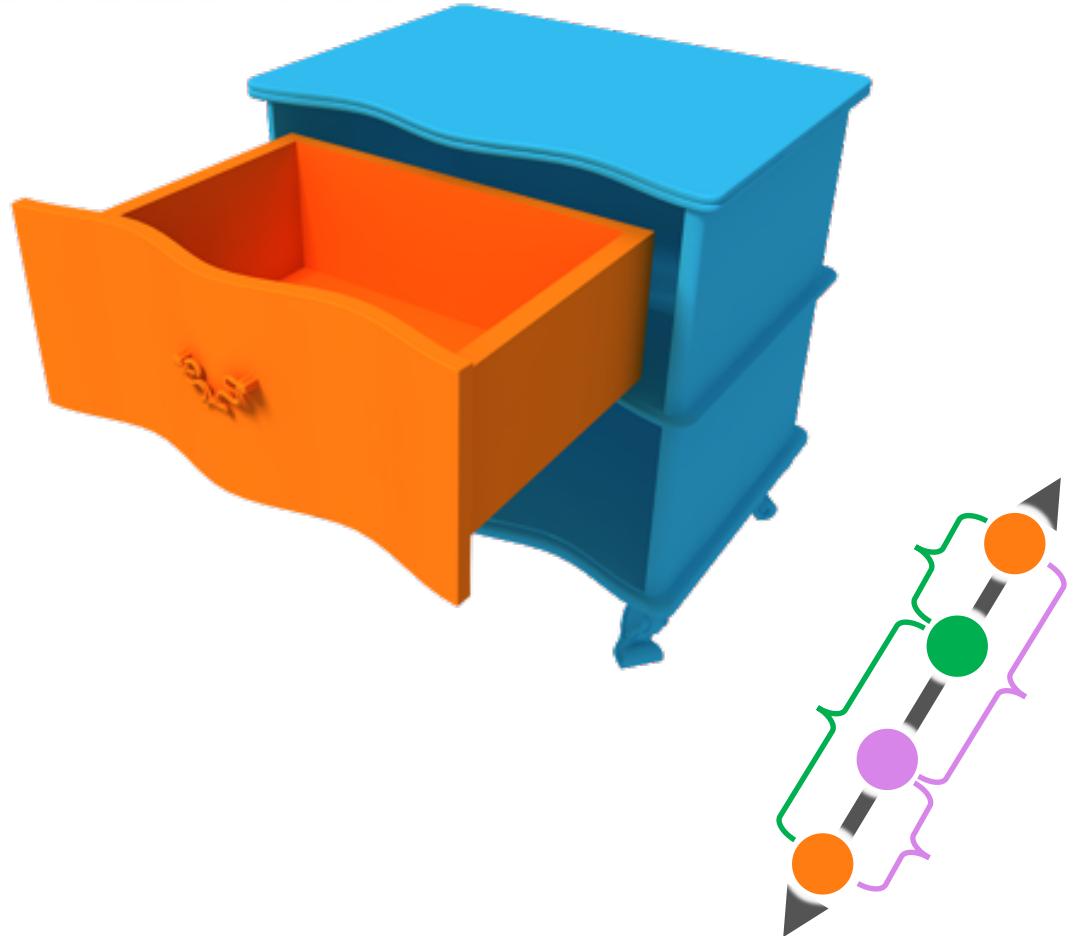
Linearity of motion



Learning to predict part mobility from a single static snapshot

[HLK*17]

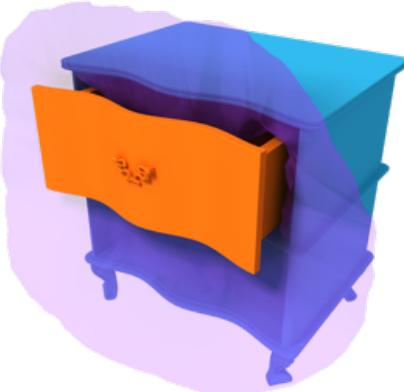
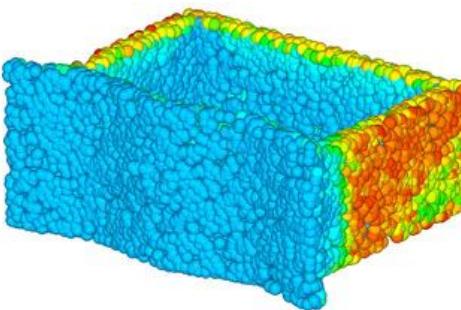
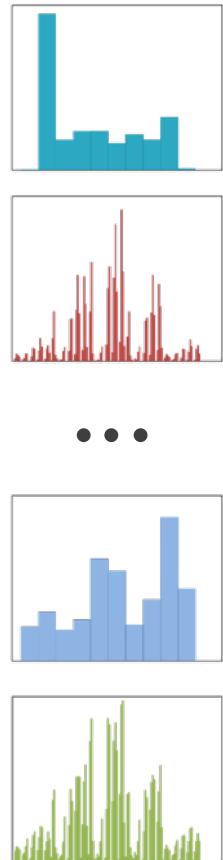
Start & end snapshots



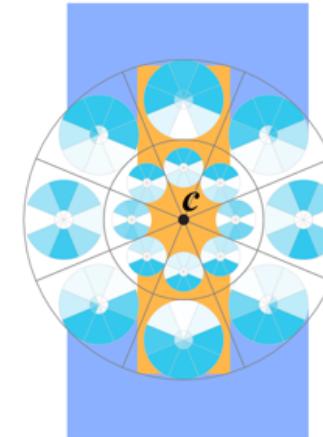
Learning to predict part mobility from a single static snapshot

[HLK*17]

Snapshot descriptor



Interaction Bisector Surface
[Zhao et al. 2014]

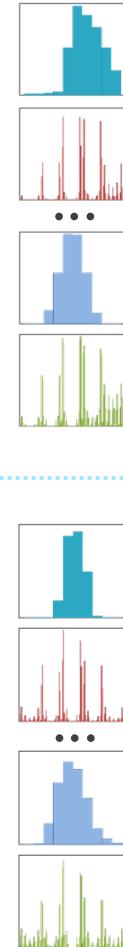
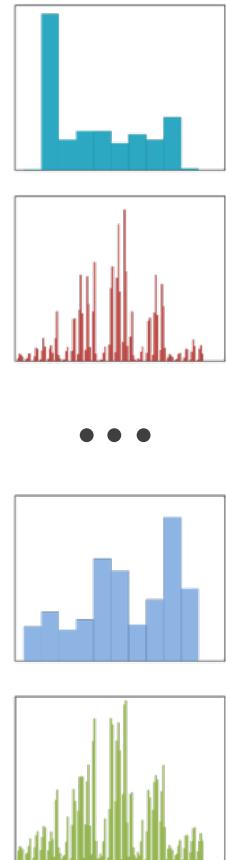


RAID-3D
[Guerrero et al. 2016]

Interaction Region
[Hu et al. 2015]

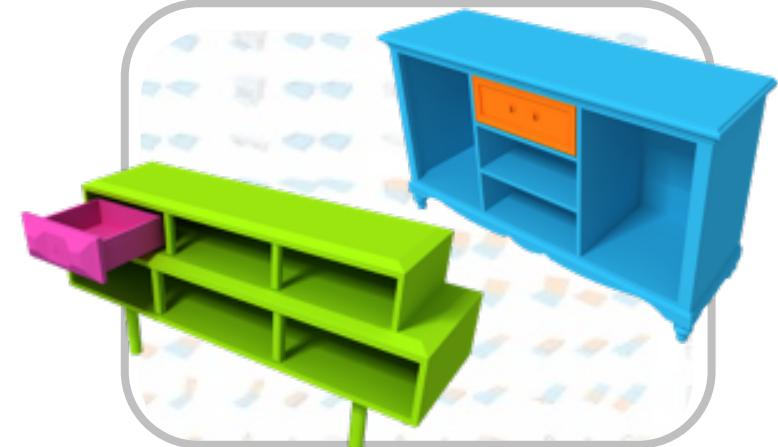
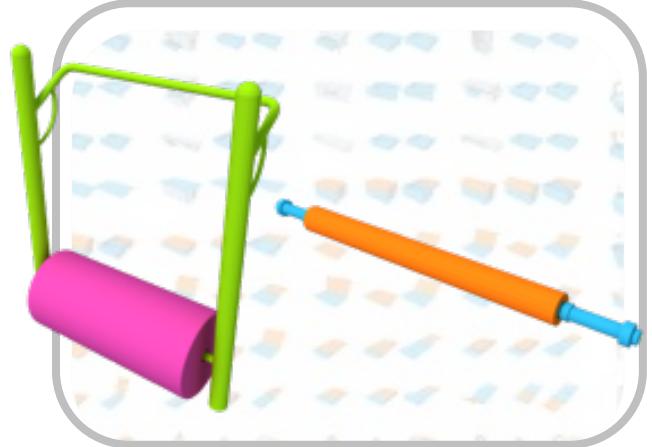
Learning to predict part mobility from a single static snapshot
[HLK*17]

Snapshot-to-unit distance



Learning to predict part mobility from a single static snapshot
[HLK*17]

Nearest neighbor Retrieval



Learning to predict part mobility from a single static snapshot

[HLK*17]

Motion transfer



Learning to predict part mobility from a single static snapshot

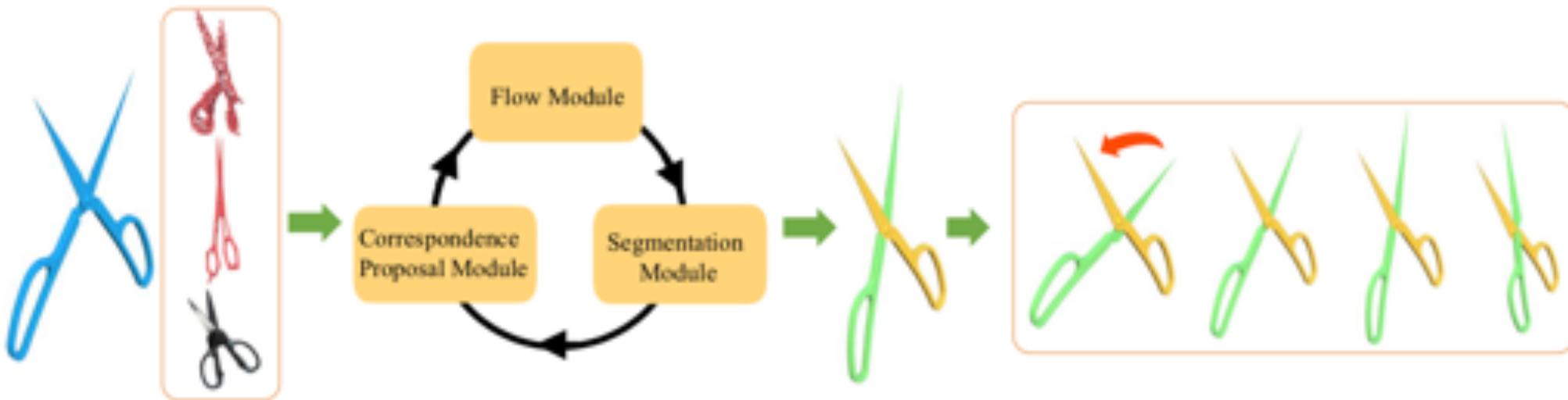
[HLK*17]

Limitation



Pre-segmented 

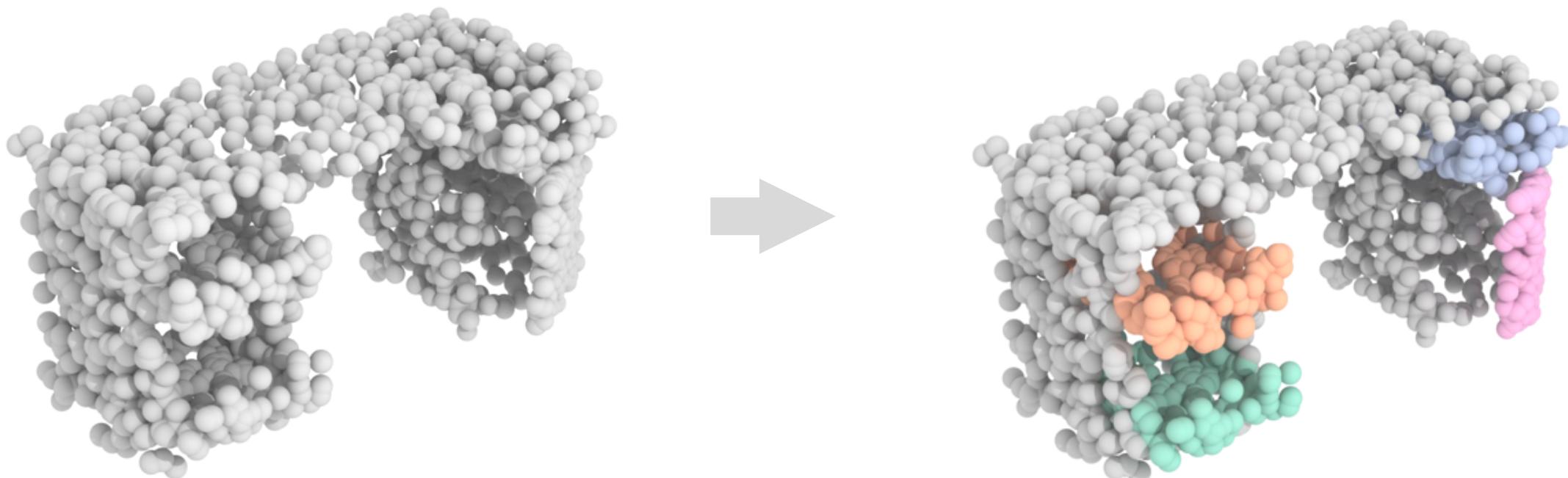
Part-level mobility prediction (Time-varying interaction)



Paired input

Deep part induction from articulated object pairs
[YHL*18]

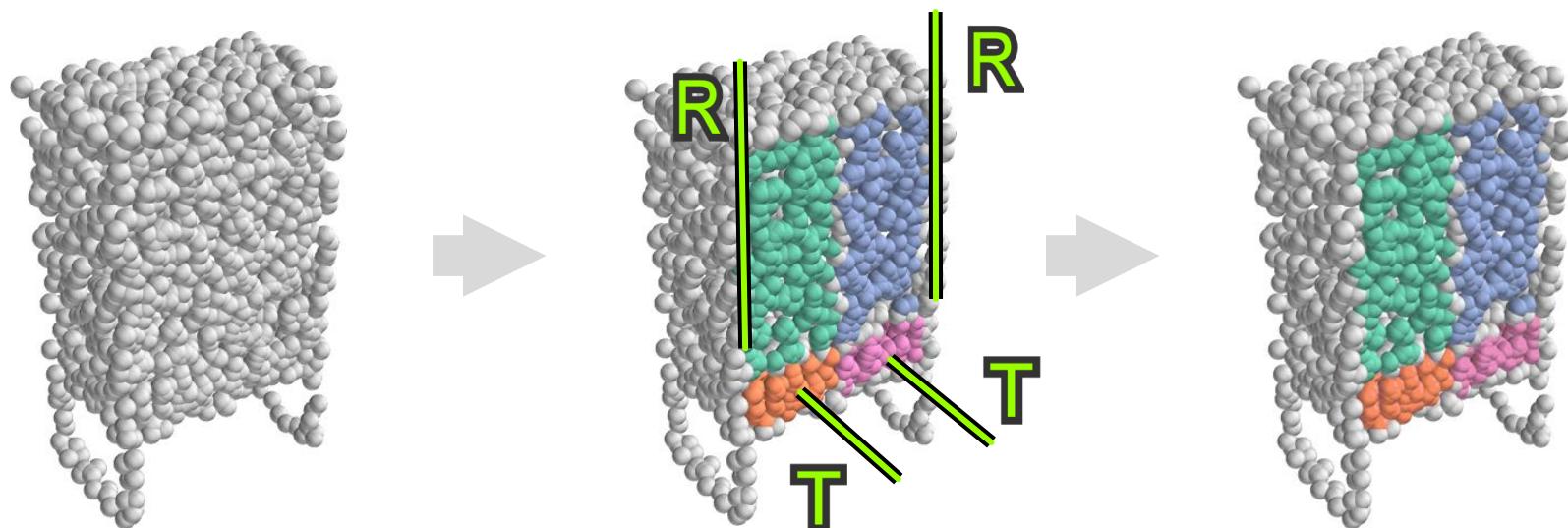
Part-level mobility prediction (Time-varying interaction)



single un-segmented partial

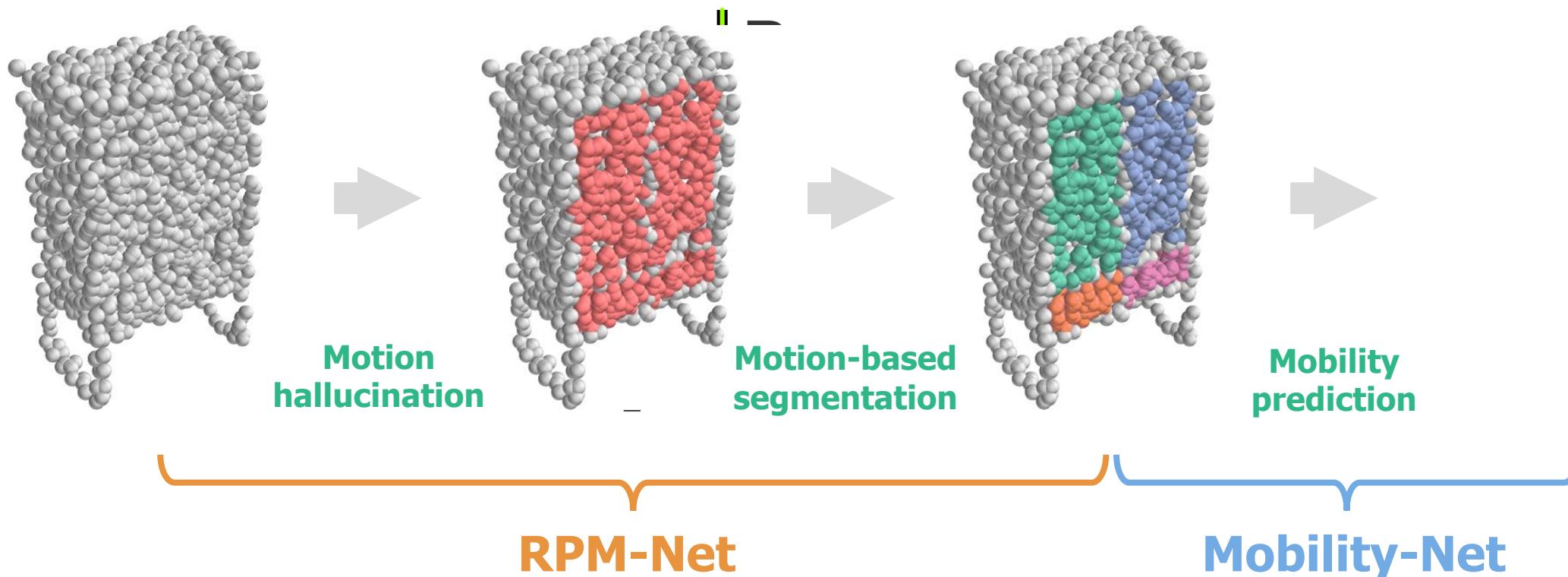
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Direct mobility prediction



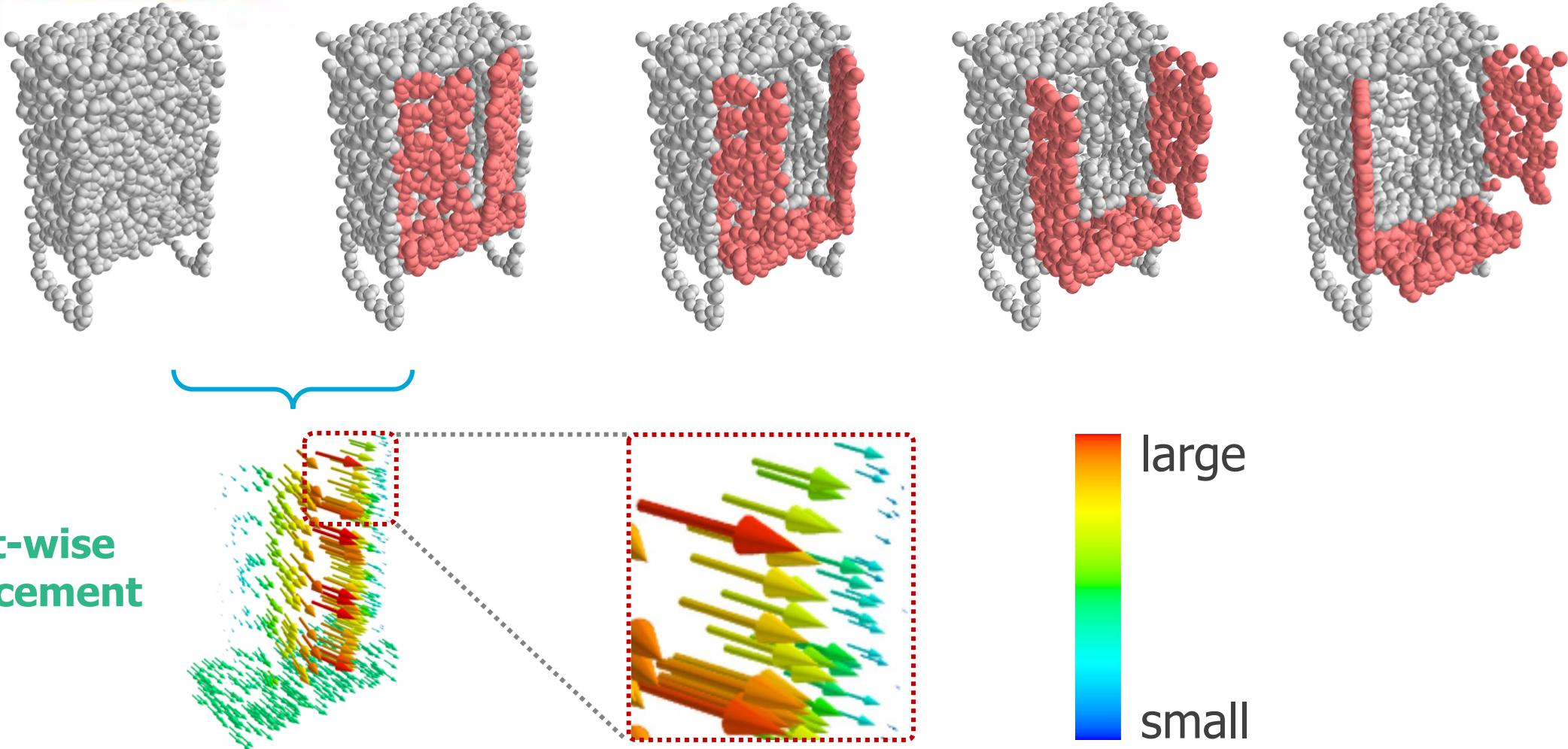
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Key contribution



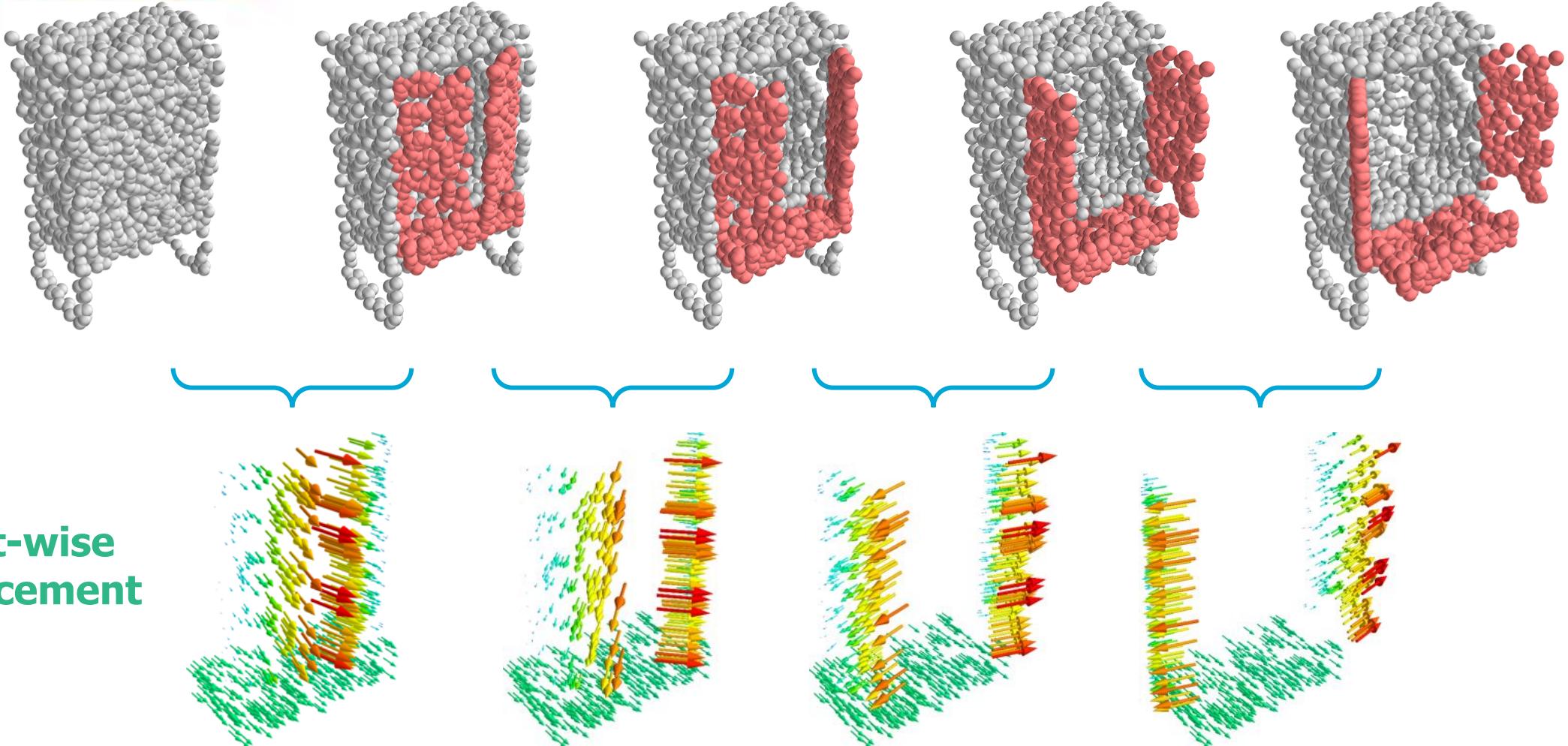
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Motion displacement

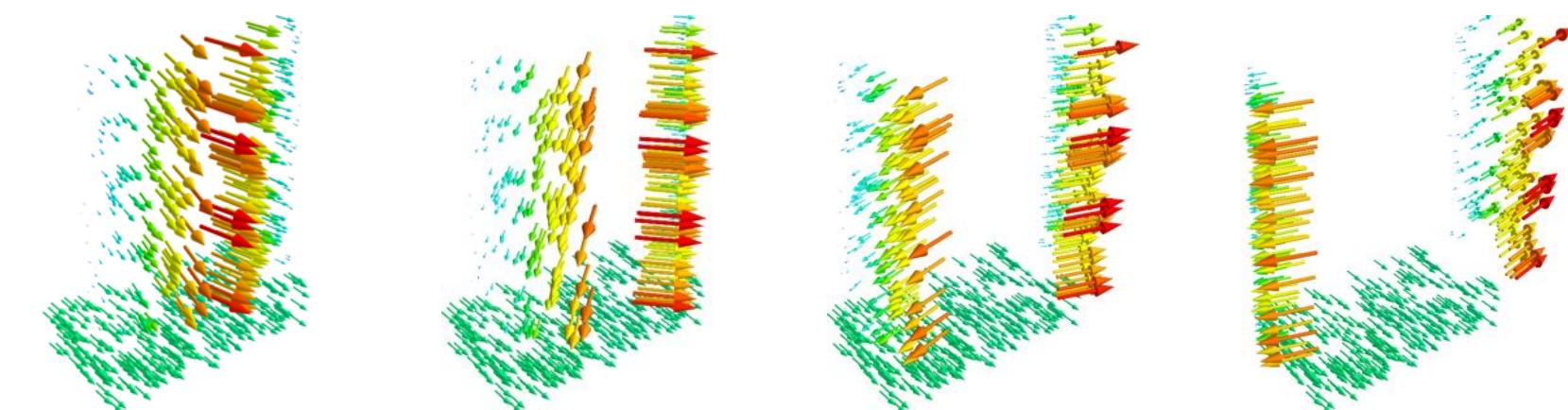


RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Motion displacement

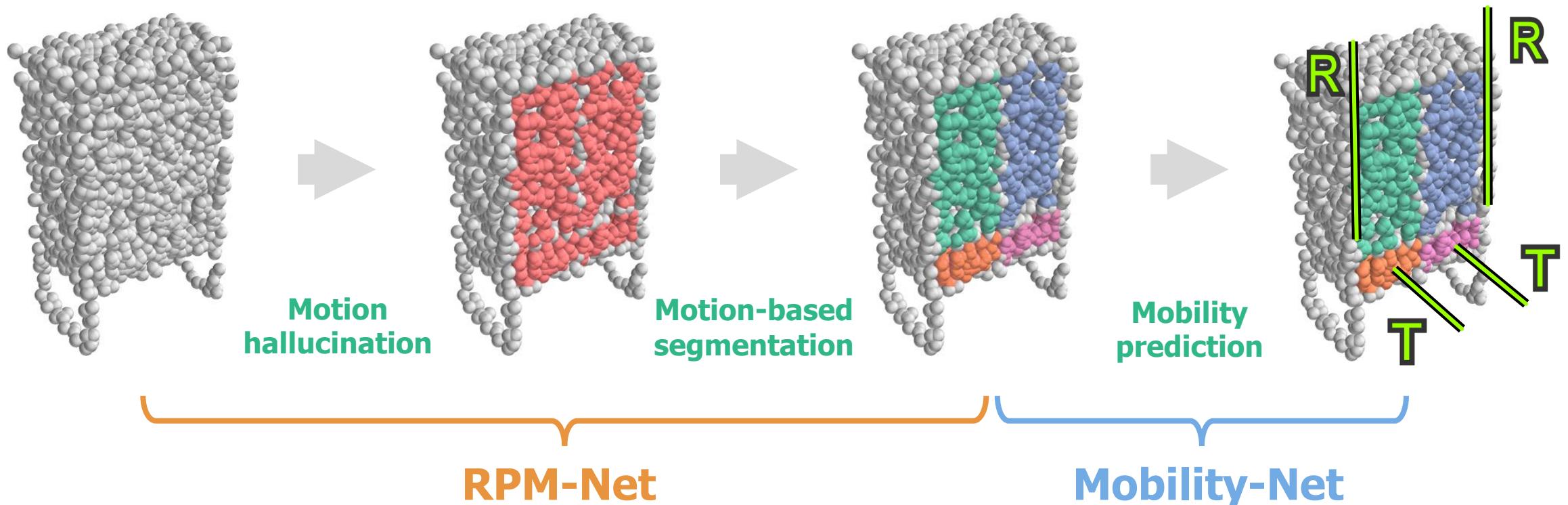


**Point-wise
displacement**



RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Overview

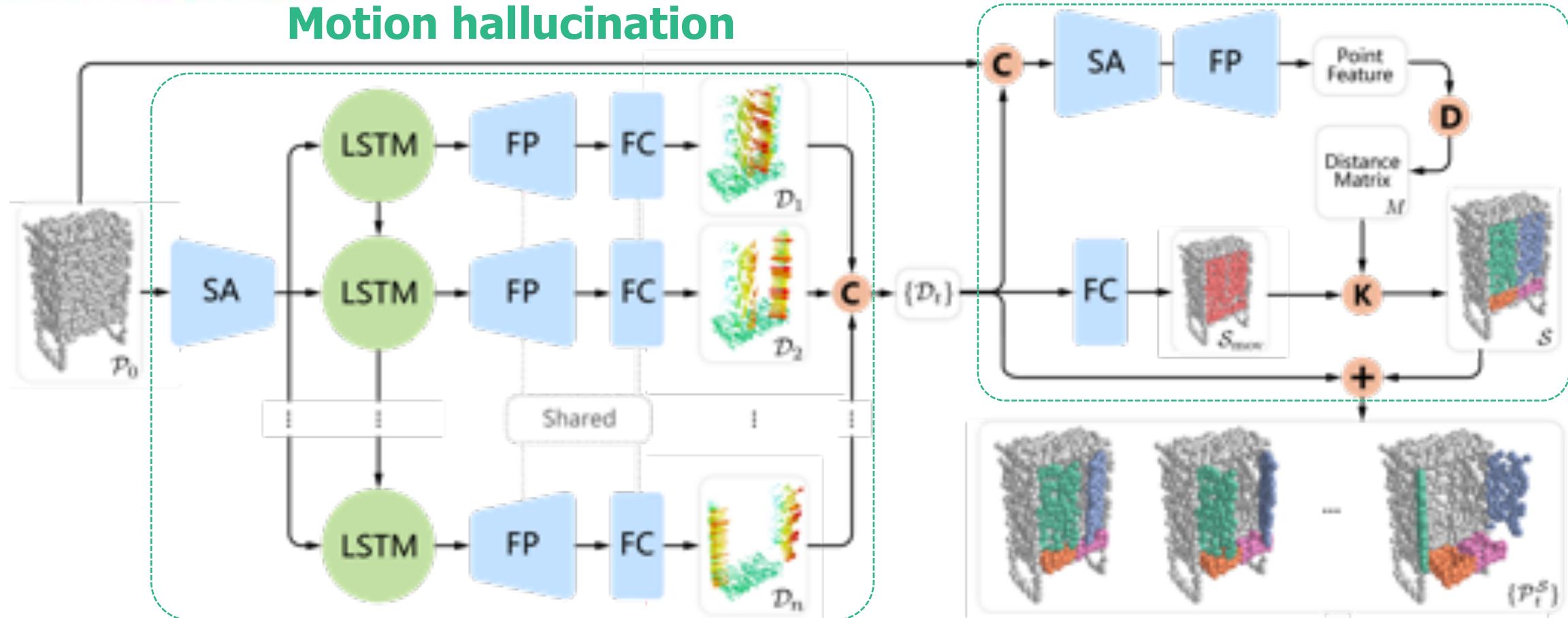


RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

RPM-Net

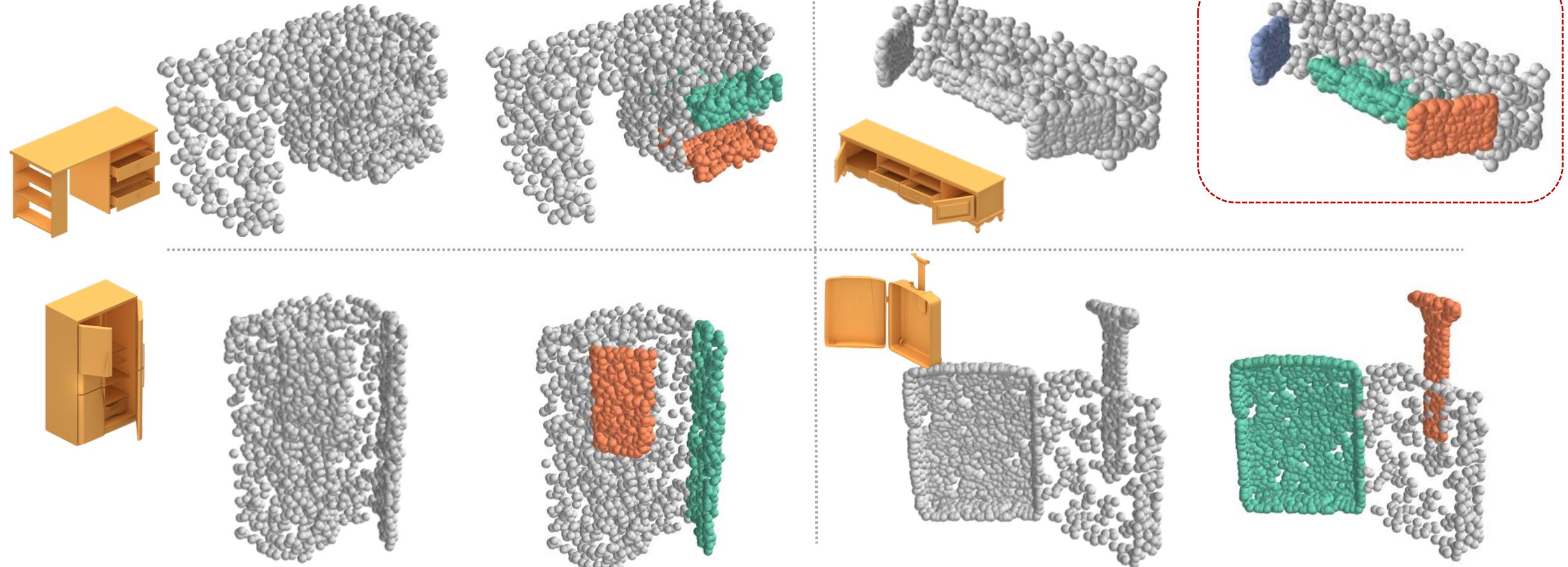
Motion-based segmentation

Motion hallucination



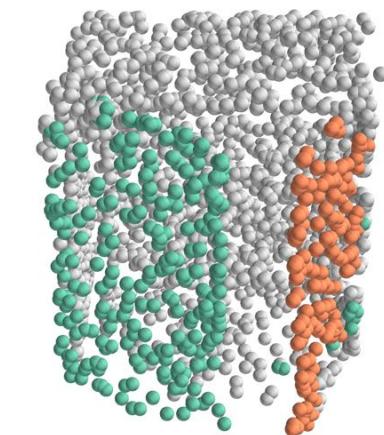
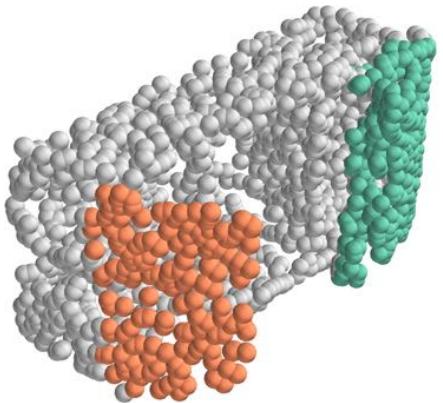
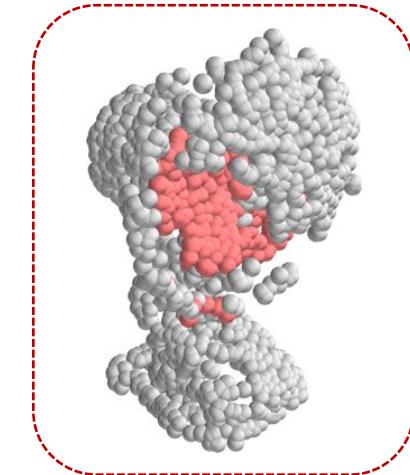
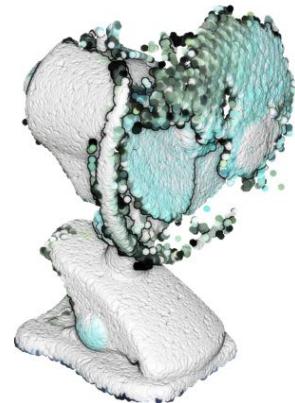
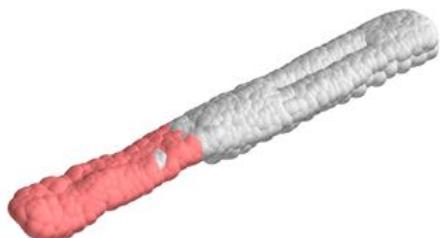
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

RPM-Net results



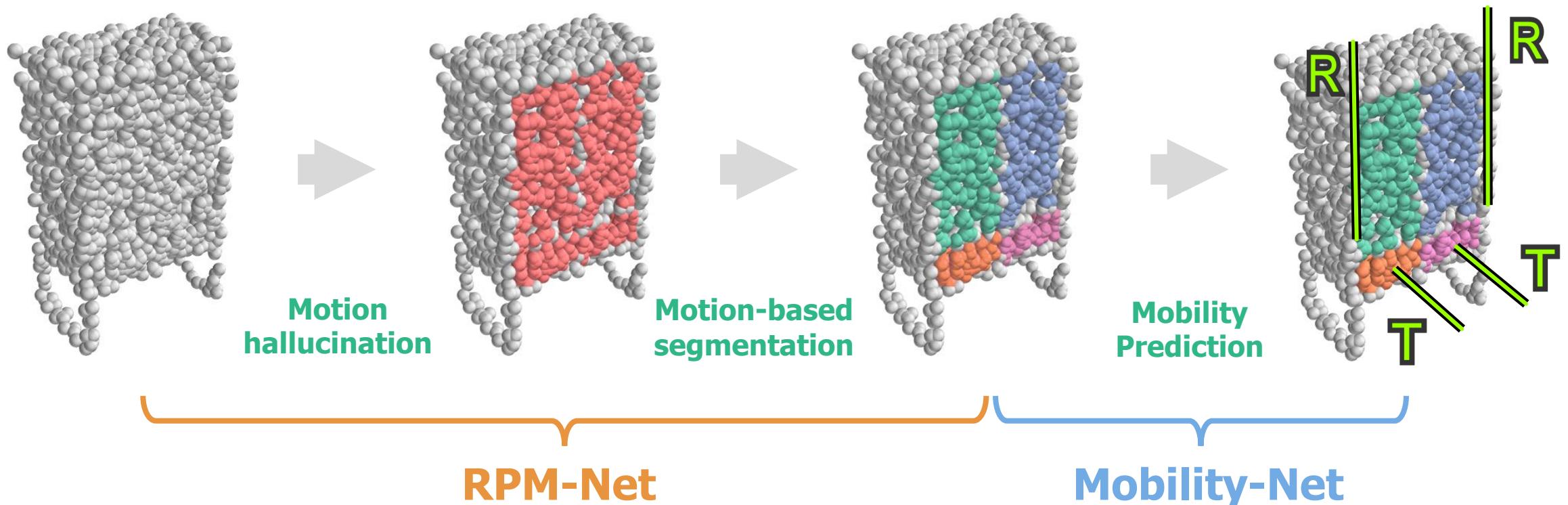
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

RPM-Net results



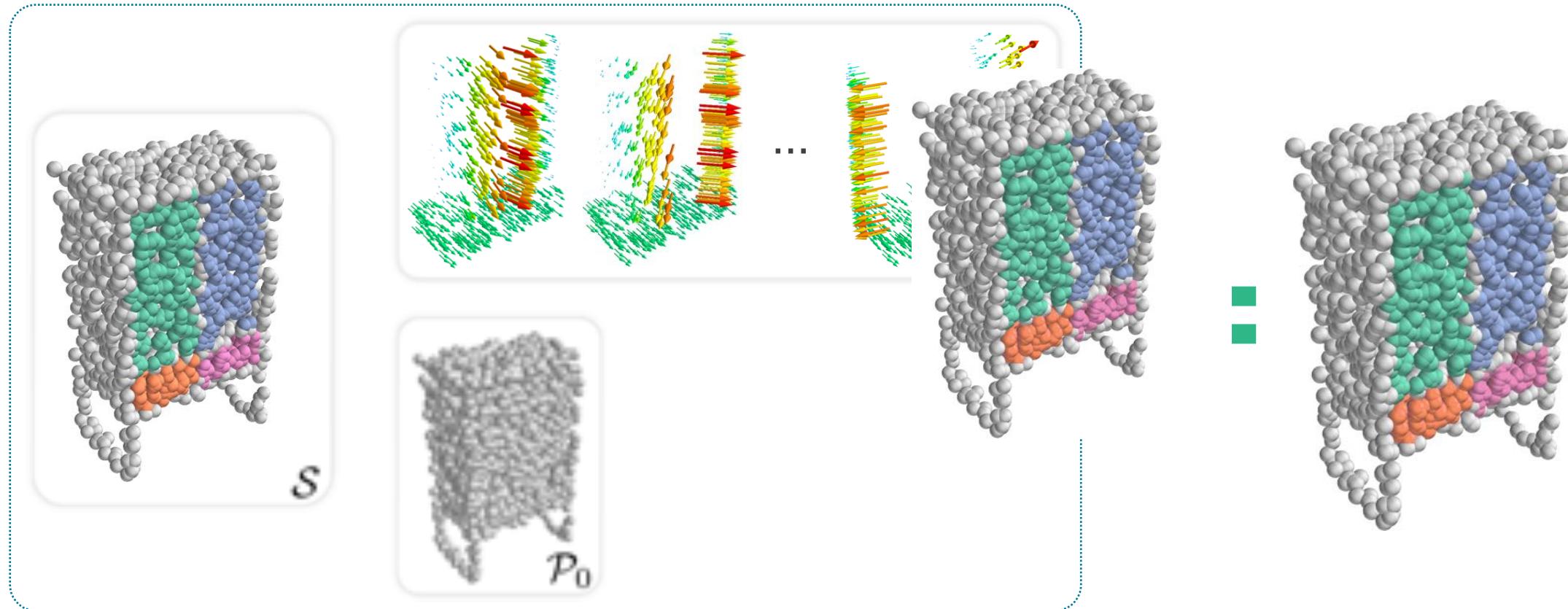
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Overview



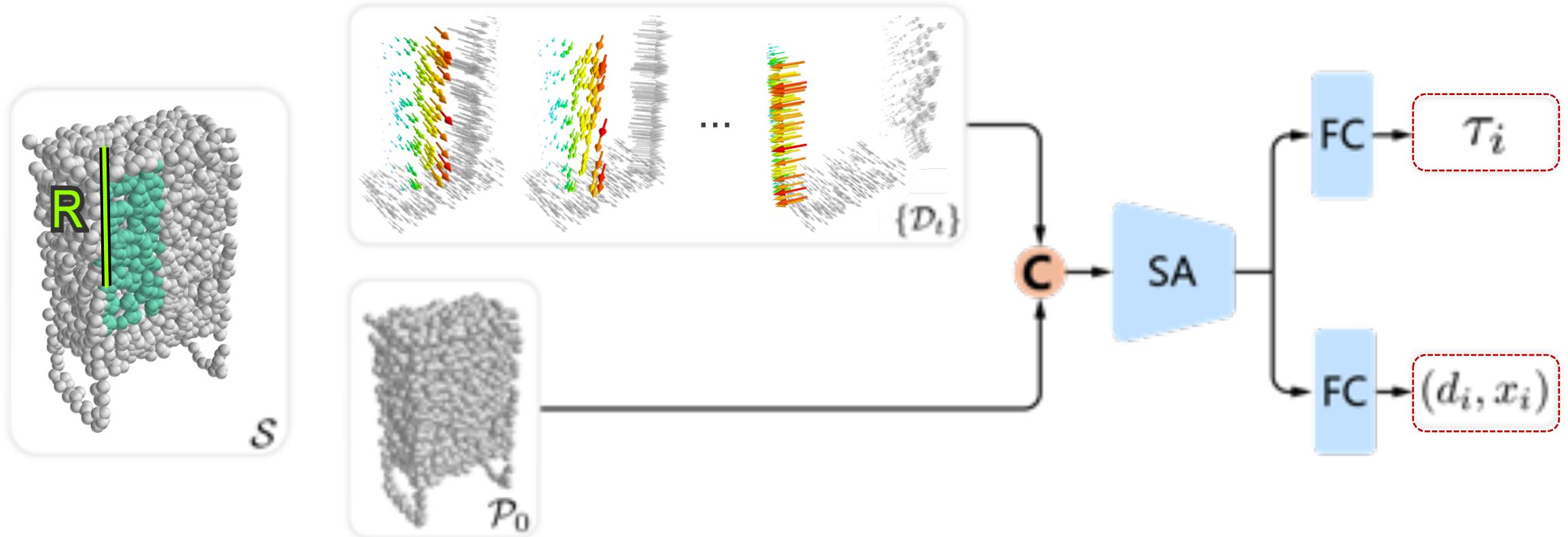
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Mobility-Net: mobility prediction



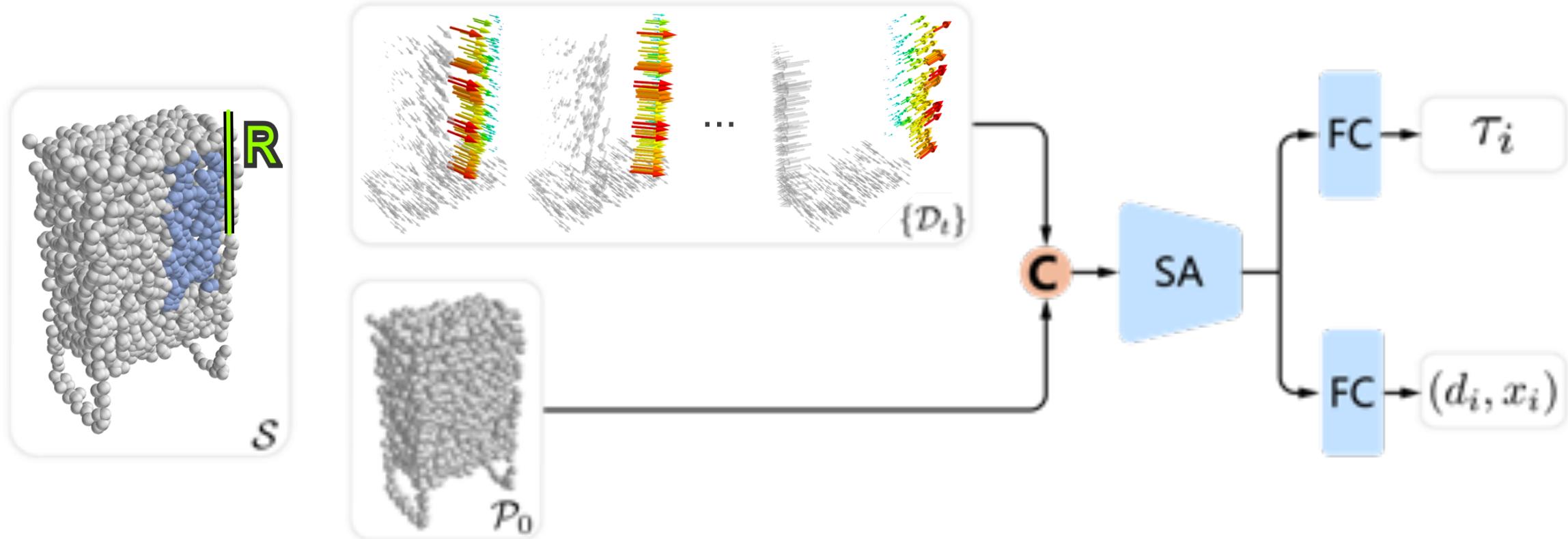
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Mobility-Net: mobility prediction



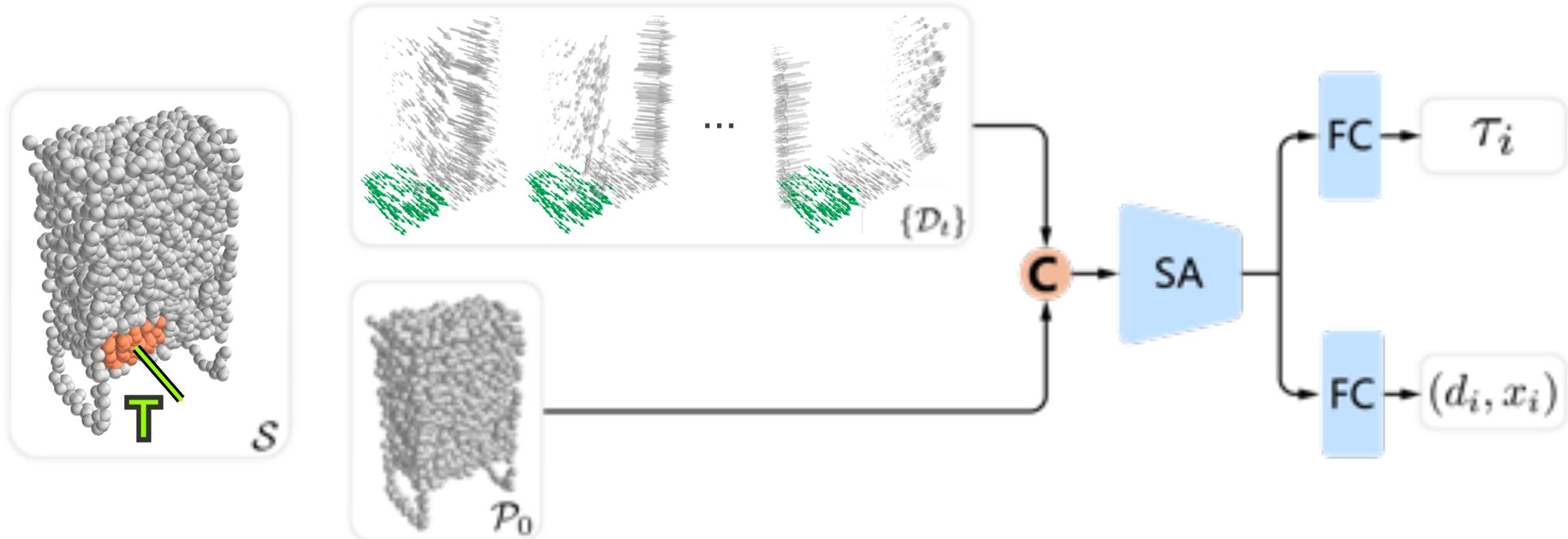
RPM-Net: recurrent prediction of motion and parts from point cloud
 [YHY*19]

Mobility-Net: mobility prediction



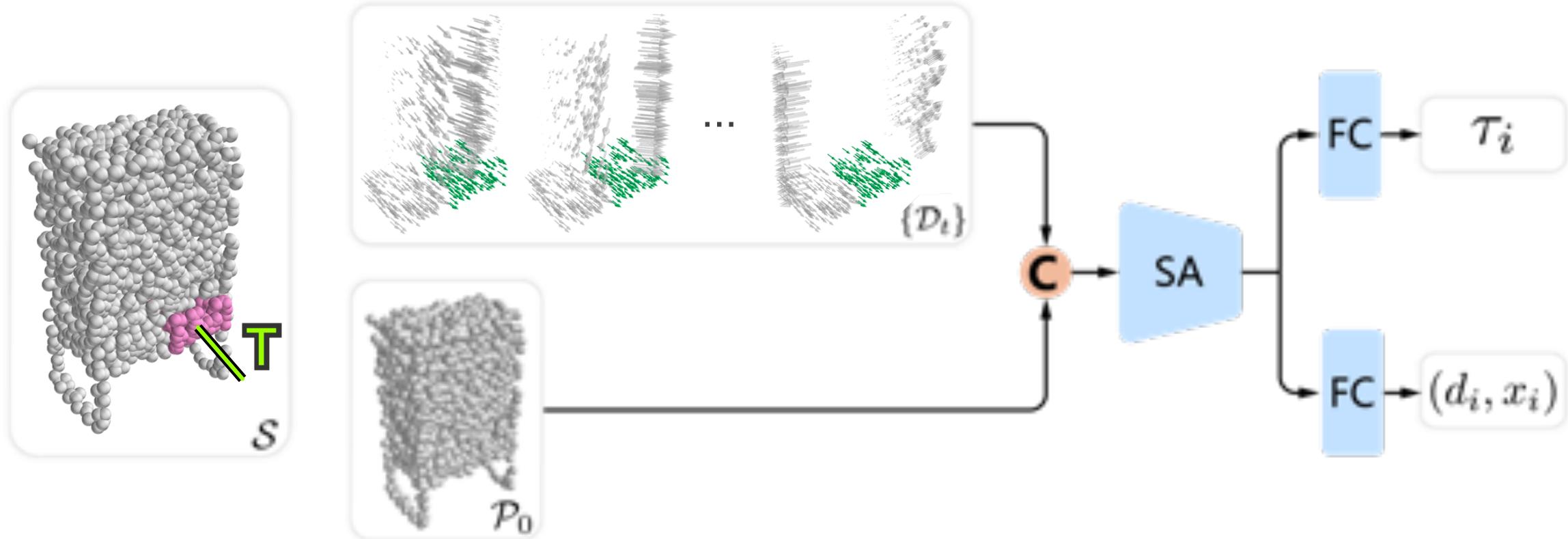
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Mobility-Net: mobility prediction



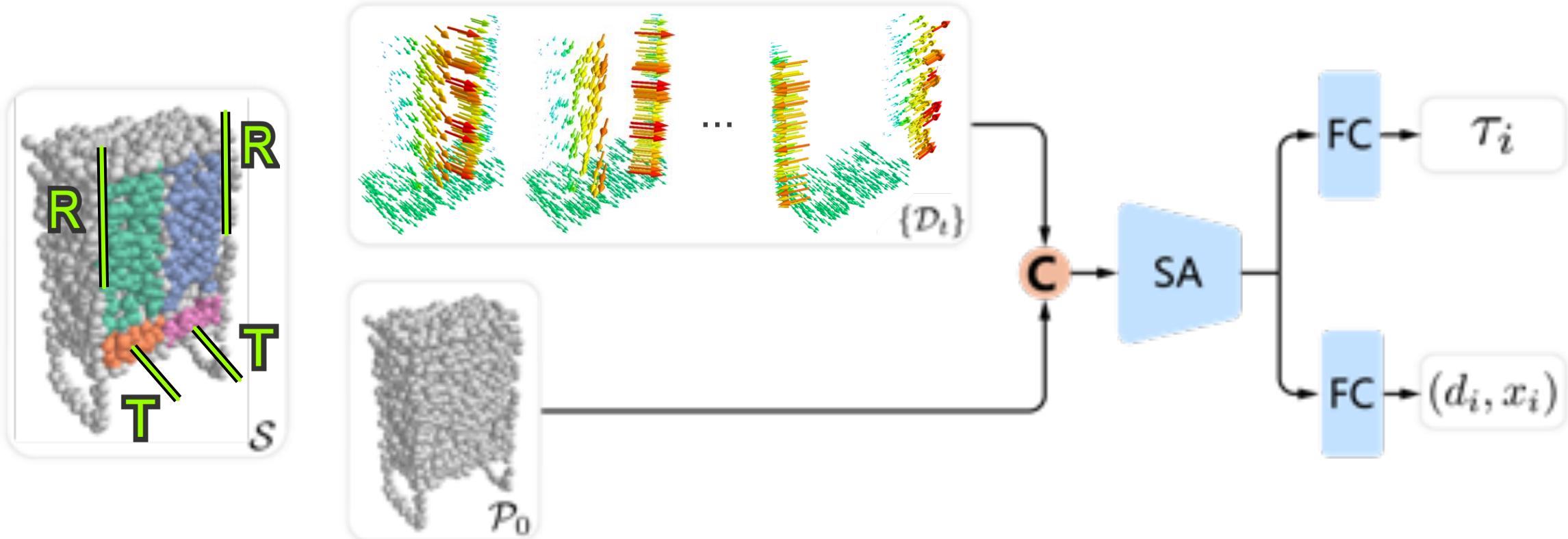
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Mobility-Net: mobility prediction



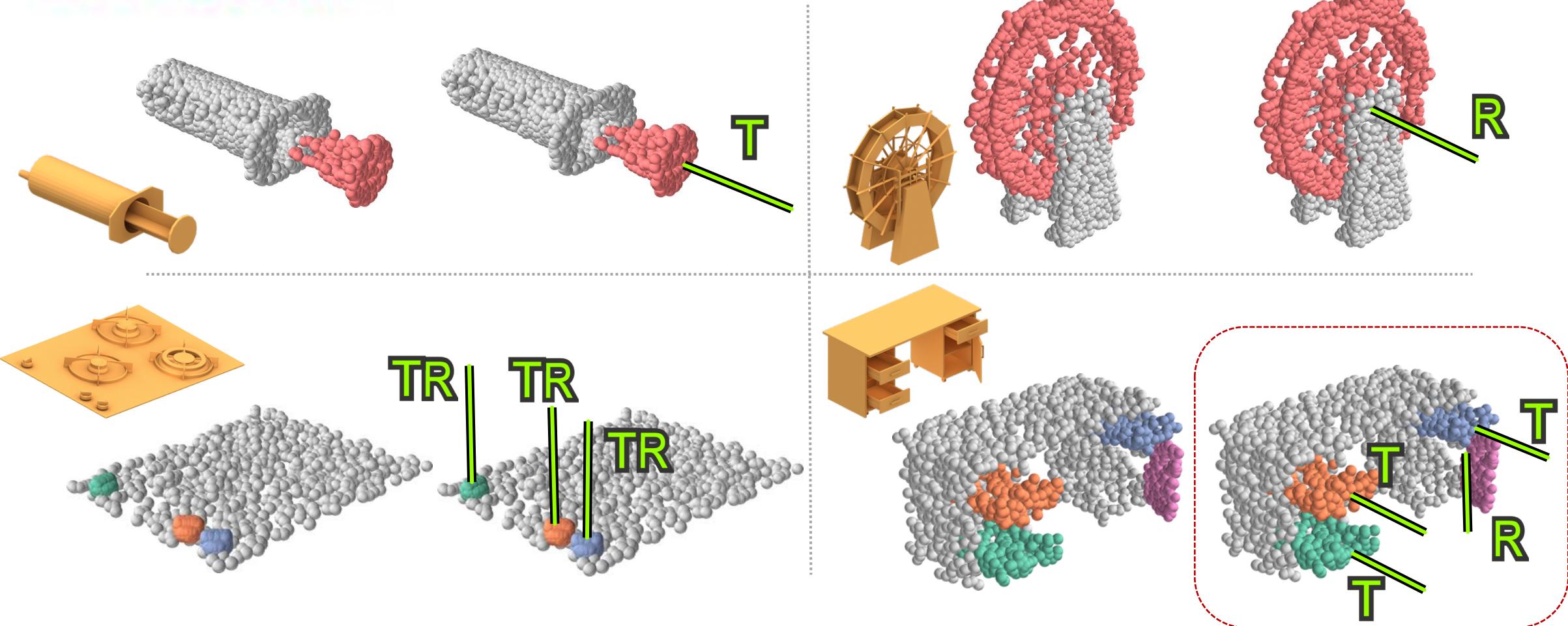
RPM-Net: recurrent prediction of motion and parts from point cloud
 [YHY*19]

Mobility-Net: mobility prediction



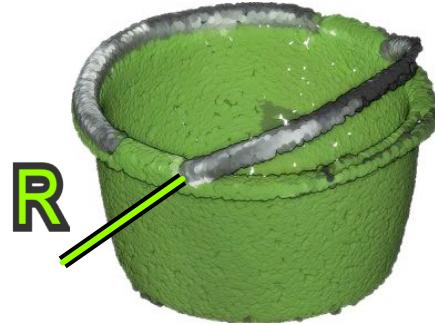
RPM-Net: recurrent prediction of motion and parts from point cloud
 [YHY*19]

Mobility-Net results



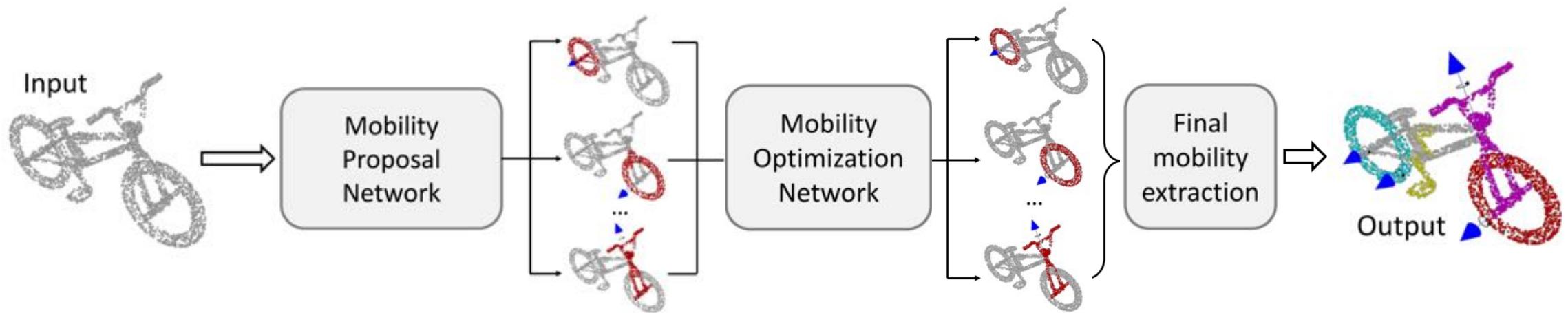
RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Mobility-Net results



RPM-Net: recurrent prediction of motion and parts from point cloud
[YHY*19]

Part-level mobility prediction (Time-varying interaction)

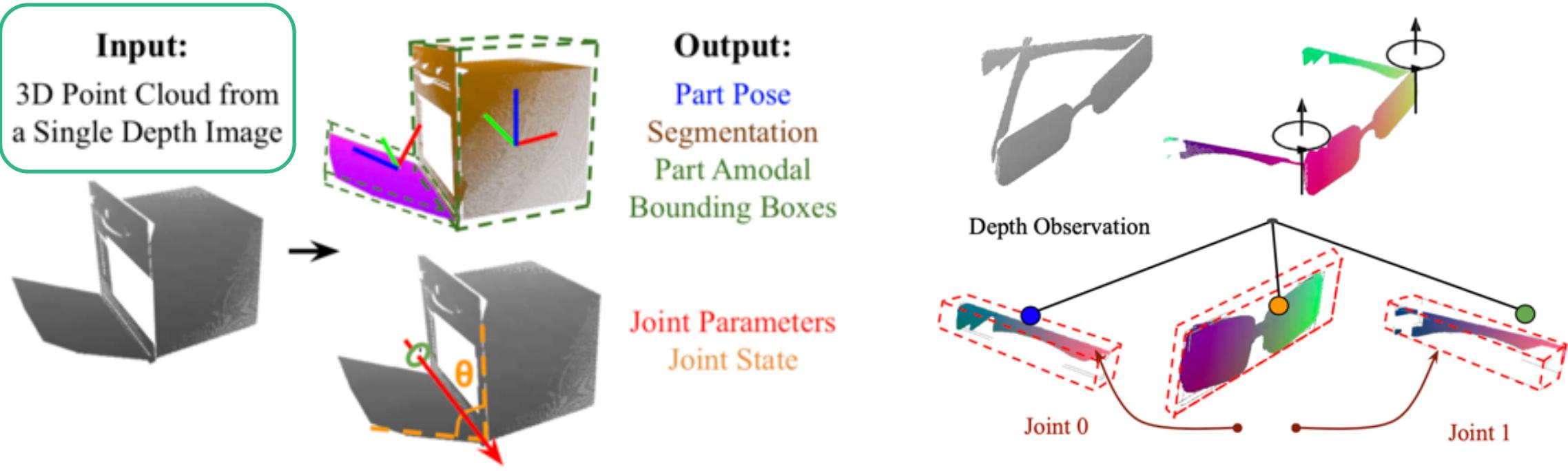


**Single
unsegmented
input**

**Predict the segmentation and mobility
parameters simultaneously**

Shape2Motion: joint analysis of motion parts and attributes from 3D shapes
[WZS*19]

Part-level mobility prediction (Time-varying interaction)



Category-level articulated object pose estimation
[LWY*20]

Geometry + interaction methods

| Works | Functional entity | Representation of geometry or interactions | | | Additional classification criteria | | |
|----------------------------------|-------------------|--|------------|-----------|------------------------------------|-------------|----------------|
| | | Component / interacting entity | Dynamicity | Relations | Input | Approach | Model type |
| Geometry+interaction (GI) | | | | | | | |
| Hu et al. [HZvK*15] | object | stat-inter | stat | BR | pcl | handcrafted | discriminative |
| Hu et al [HvKW*16] | object | stat-inter | stat | BR | pcl | supervised | discriminative |
| Pirk et al. [PKH*17] | object | dyn-inter | dyn | VF | mesh | handcrafted | discriminative |
| Myers et al. [MTFA15] | part | stat-inter | stat | SA | rgbd | supervised | discriminative |
| Kim et al. [KS14] | part | stat-inter | stat | SA | rgbd | supervised | discriminative |
| Laga et al. [LMS13] | part | stat-inter | stat | SA+SG | mesh | supervised | discriminative |
| Hu et al. [HLK*17] | part | stat-inter | dyn | SA+BR | pcl | supervised | discriminative |
| Xiang et al. [XQM*20] | part | stat-inter | dyn | SA | mesh | supervised | discriminative |
| Hu et al. [HYZ*18] | object | stat-inter | stat | SA+BR | vol | supervised | generative |
| Yi et al. [YHL*18] | part | stat-inter | dyn | SA | pcl | supervised | discriminative |
| Wang et al. [WZS*19] | part | stat-inter | dyn | SA | pcl | supervised | discriminative |
| Yan et al. [YHY*19] | part | stat-inter | dyn | SA | pcl | supervised | discriminative |
| Li et al. [LWY*20] | part | stat-inter | dyn | SA | pcl | supervised | discriminative |
| Kokic et al. [KSHK17] | part | stat-inter | dyn | SA | pcl | supervised | generative |
| Li et al. [LSK20] | part | stat-inter | dyn | SA | pcl | supervised | generative |

Discussion

- Focus on **object** and **part** level functionalities
- Start with **handcrafted** functionality descriptors
- Recent learning-based methods for **prediction** and **generation**
- Both **atemporal** and **time-varying** interactions

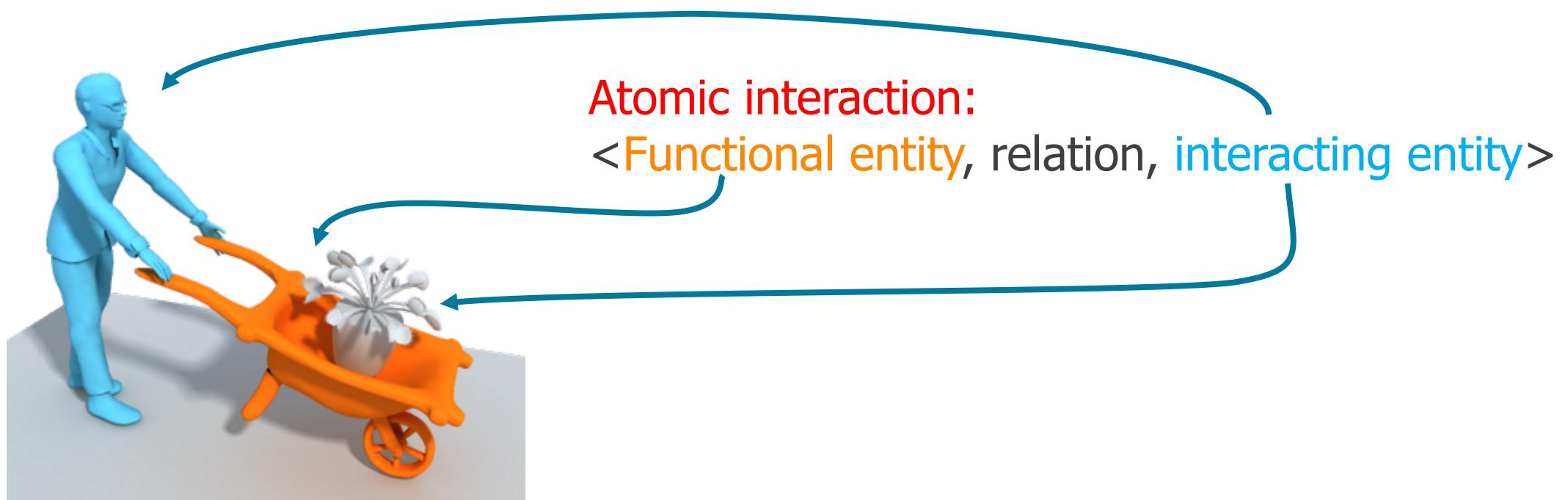


Geometry + Agent



Our definition of functionality

Functionality = Geometry + Interaction





Geometry + agent methods

- Interaction with (humanoid) agent
- Can be special case of geometry + interaction methods
- Critical for human-centric functionality
- Recent interest in applications for fabrication, VR/AR

Much recent work

| Works | Functional entity | Representation of geometry or interactions | | | Additional classification criteria | | |
|----------------------------|-------------------|--|------------|-----------|------------------------------------|--------------|----------------|
| | | Component / interacting entity | Dynamicity | Relations | Input | Approach | Model type |
| Geometry+agent (GA) | | | | | | | |
| Grabner et al. [GGVG11] | scene | agent-inter | stat | HA | mesh | supervised | generative |
| Savva et al. [SCH*14] | scene | agent-inter | stat | SA+HA | mesh | supervised | discriminative |
| Zhu et al. [ZZJ*16] | scene | agent-inter | stat | SA | mesh | supervised | generative |
| Jiang et al. [JKS13] | multi-object | agent-inter | stat | SA | rgbd | supervised | discriminative |
| Wang et al. [WLY17] | multi-object | agent-inter | stat | SA+HA | mesh | supervised | discriminative |
| Fisher et al. [PSL*15] | multi-object | agent-inter | stat | SA+HA | mesh | supervised | generative |
| Savva et al. [SCH*16] | multi-object | agent-inter | stat | SA+HA | mesh | supervised | generative |
| Ma et al. [MLZ*16] | multi-object | agent-inter | dyn | SA+HA | mesh | unsupervised | generative |
| Zheng et al. [ZLDM16] | object | agent-inter | stat | SA | mesh | handcrafted | generative |
| Kim et al. [KCGF14] | object | agent-inter | stat | SA | mesh | supervised | generative |
| Bar-Aviv & Rivlin [BAR06] | object | agent-inter | stat | SA+HA | mesh | handcrafted | discriminative |
| Zhu et al. [ZZCZ15] | object | agent-inter | dyn | SA+HA | rgbd | supervised | discriminative |
| Zhao et al. [ZCK17] | object | agent-inter | dyn | SA+HA | mesh | handcrafted | discriminative |
| Lee et al. [LCJ06] | object | agent-inter | dyn | SA | mesh | supervised | generative |
| Li et al. [LLK*19] | scene | agent-inter | stat | SA+HA | rgbd | supervised | generative |
| Zhang et al. [ZHN*20] | scene | agent-inter | stat | SA+HA | rgbd | supervised | generative |
| Mao et al. [MZK*19] | object | agent-inter | stat | SA | mesh | supervised | generative |
| Fu et al. [FPY*20] | scene | agent-inter | stat | SA+HA | mesh | supervised | discriminative |
| Monszpart et al. [MGC*19] | scene | agent-inter | stat | SA | rgbd | supervised | generative |
| Ruiz et al. [RMC19] | scene | agent-inter | stat | SA+BR | mesh | supervised | generative |
| Starke et al. [SZKS19] | object | agent-inter | dyn | SA | vol | supervised | generative |
| Akizuki et al. [AA18] | object | agent-inter | dyn | SA+HA | rgbd | supervised | discriminative |



Axes of variation

- Representation focus: agent-centric or functional entity-centric
- Functional entity level
- Relation type: time-varying or not
- Generation: agent(s) \leftrightarrow scene
- Discrimination: scene quality metrics and object understanding

Axes of variation

| Works | Functional entity | Representation of geometry or interactions | | Additional classification criteria | | | | Model type |
|----------------------------|-------------------|--|------------|------------------------------------|-------|--------------|--|----------------|
| | | Component / interacting entity | Dynamicity | Relations | Input | Approach | | |
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| Zhu et al. [ZZJ*16] | scene | agent-inter | stat | SA | mesh | supervised | | generative |
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| Wang et al. [WLY17] | multi-object | agent-inter | stat | SA+HA | mesh | supervised | | discriminative |
| Fisher et al. [PSL*15] | multi-object | agent-inter | stat | SA+HA | mesh | supervised | | generative |
| Savva et al. [SCH*16] | multi-object | agent-inter | stat | SA+HA | mesh | supervised | | generative |
| Ma et al. [MLZ*16] | multi-object | agent-inter | dyn | SA+HA | mesh | unsupervised | | generative |
| Zheng et al. [ZLDM16] | object | agent-inter | stat | SA | mesh | handcrafted | | generative |
| Kim et al. [KCGF14] | object | agent-inter | stat | SA | mesh | supervised | | generative |
| Bar-Aviv & Rivlin [BAR06] | object | agent-inter | stat | SA+HA | mesh | handcrafted | | discriminative |
| Zhu et al. [ZZCZ15] | object | agent-inter | dyn | SA+HA | rgbd | supervised | | discriminative |
| Zhao et al. [ZCK17] | object | agent-inter | dyn | SA+HA | mesh | handcrafted | | discriminative |
| Lee et al. [LCJ06] | object | agent-inter | dyn | SA | mesh | supervised | | generative |
| Li et al. [LLK*19] | scene | agent-inter | stat | SA+HA | rgbd | supervised | | generative |
| Zhang et al. [ZHN*20] | scene | agent-inter | stat | SA+HA | rgbd | supervised | | generative |
| Mao et al. [MZK*19] | object | agent-inter | stat | SA | mesh | supervised | | generative |
| Fu et al. [FFY*20] | scene | agent-inter | stat | SA+HA | mesh | supervised | | discriminative |
| Monszpart et al. [MGC*19] | scene | agent-inter | stat | SA | rgbd | supervised | | generative |
| Ruiz et al. [RMC19] | scene | agent-inter | stat | SA+BR | mesh | supervised | | generative |
| Starke et al. [SZKS19] | object | agent-inter | dyn | SA | vol | supervised | | generative |
| Akizuki et al. [AA18] | object | agent-inter | dyn | SA+HA | rgbd | supervised | | discriminative |

Representation focus

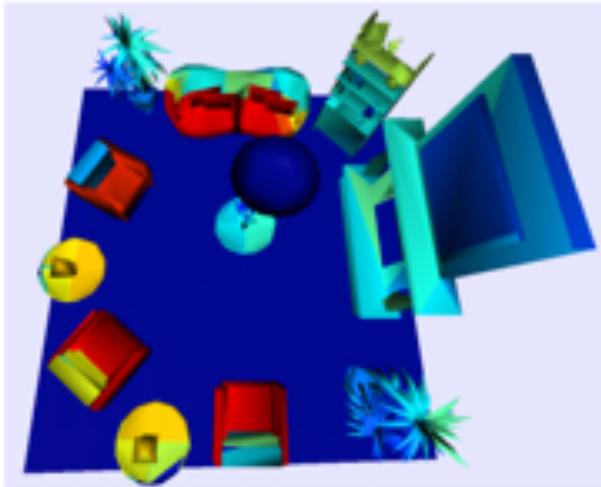
Geometry-centric



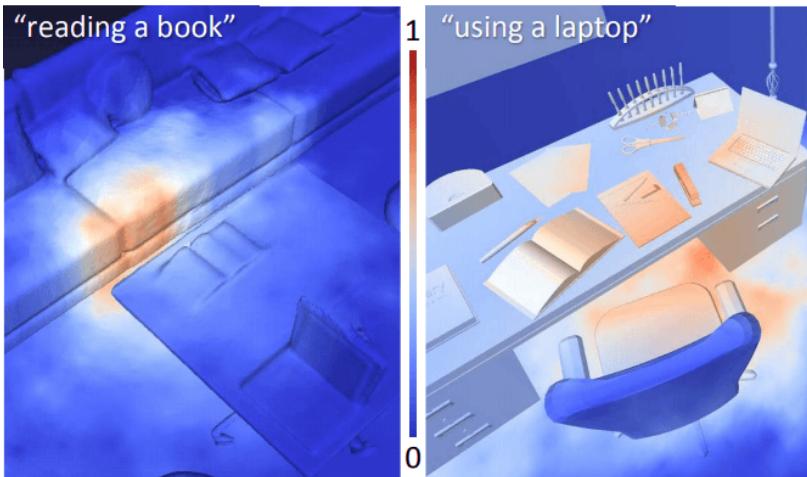
Agent-centric



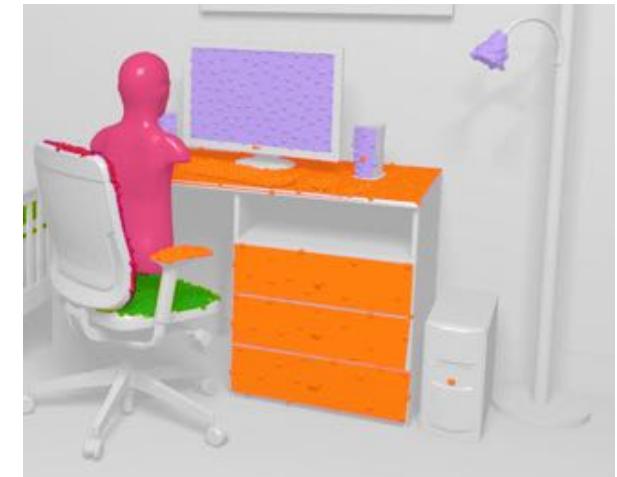
Geometry-centric representations



Sittability prediction
[GGVG11]



Action maps
[SCH*14]

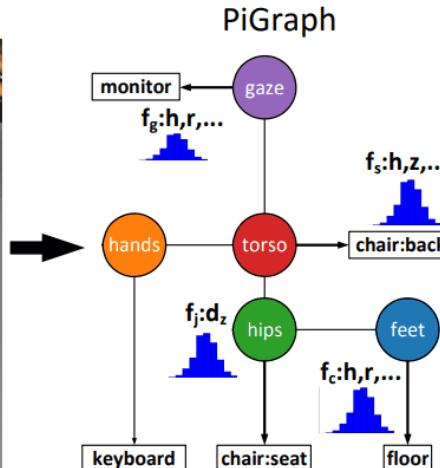
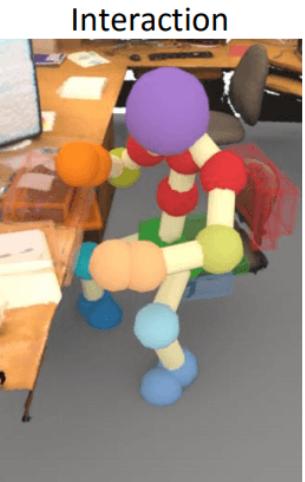


Object interactions
[FSL*15]

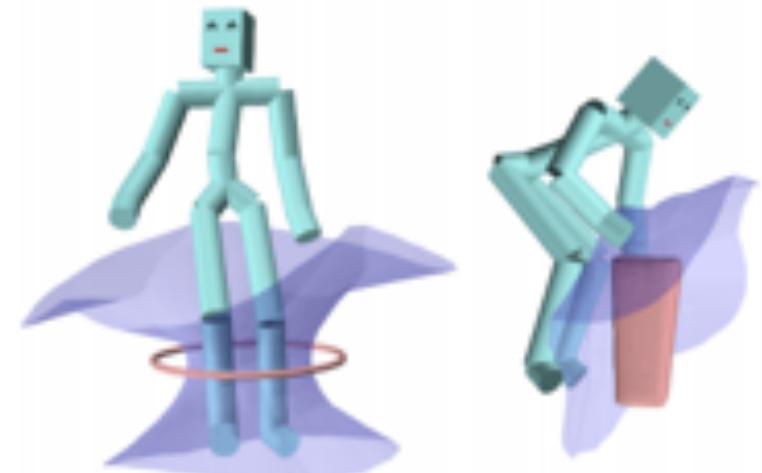
Agent-centric representations



Shape2pose
[KCGF14]



PiGraphs
[SCH*16]



Character-object IBS
[ZCK17]

Functional entity level



Scene



Multi-object



Object

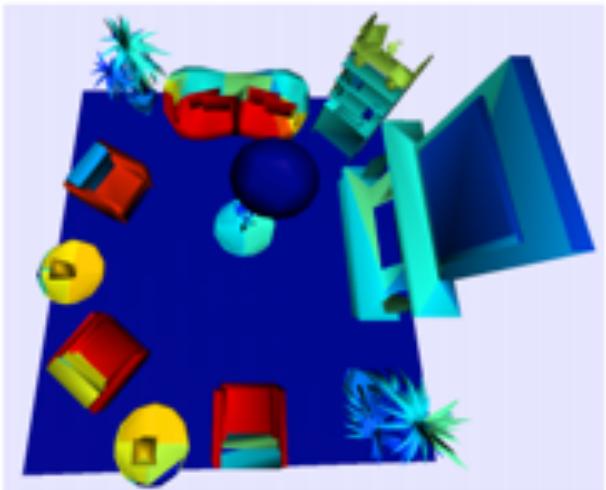


Multi-part

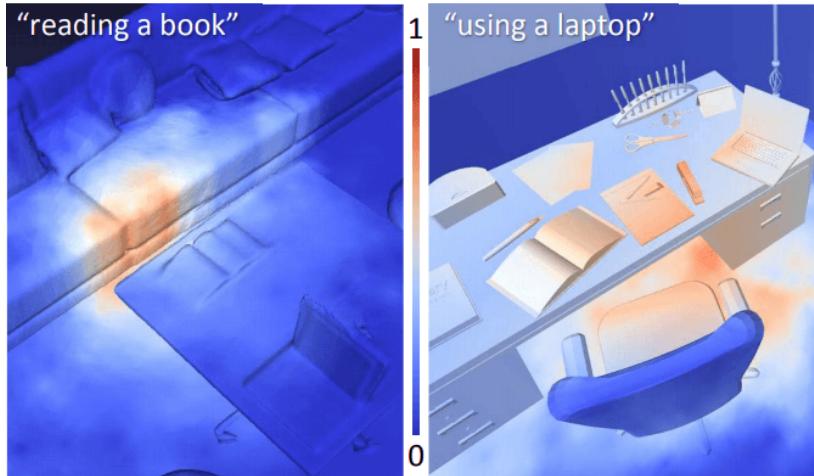


Part

Functional entity level: scene



Sittability prediction
[GGVG11]

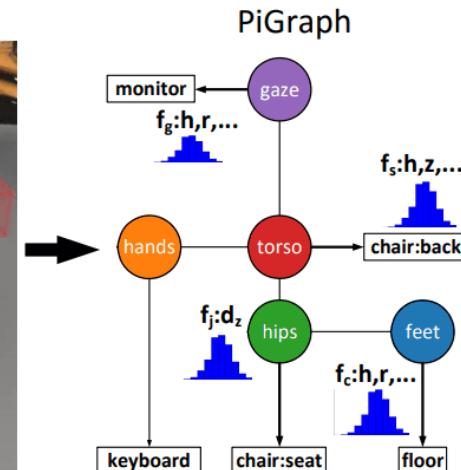


Action maps
[SCH*14]

Functional entity level: multi-object

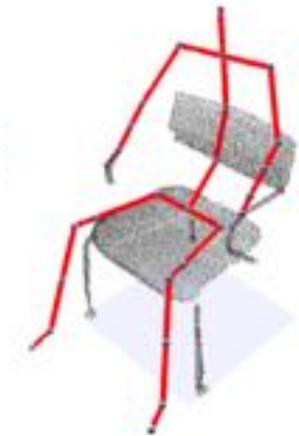


Object interactions
[FSL*15]

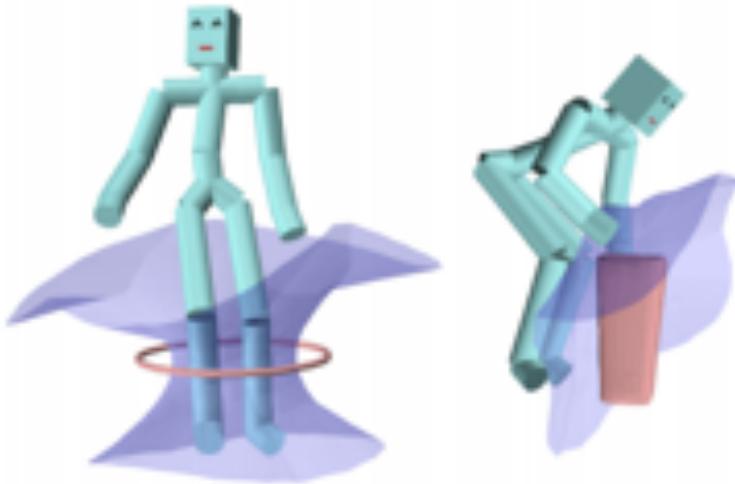


PiGraphs
[SCH*16]

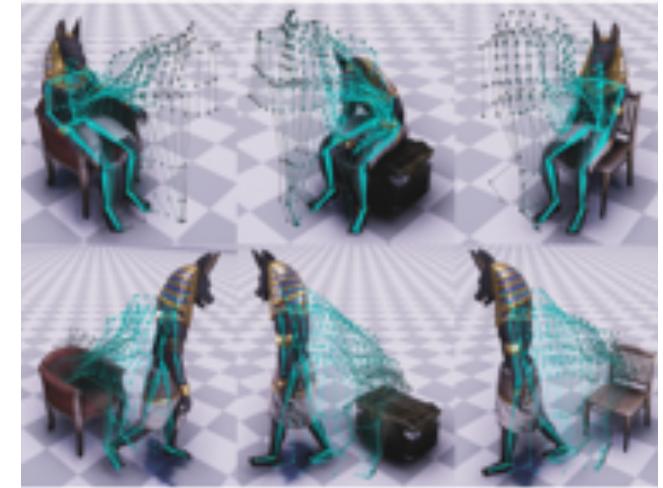
Functional entity level: object



Shape2pose
[KCGF14]



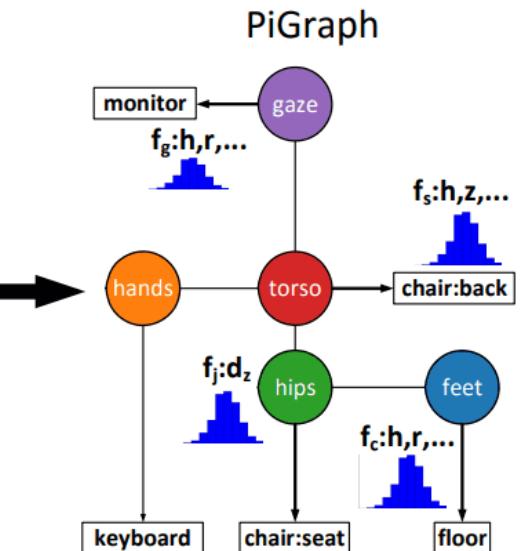
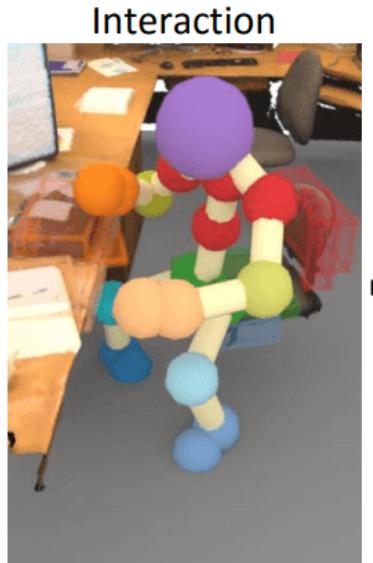
Character-object IBS
[ZCK17]



Character interactions
[SZKS19]

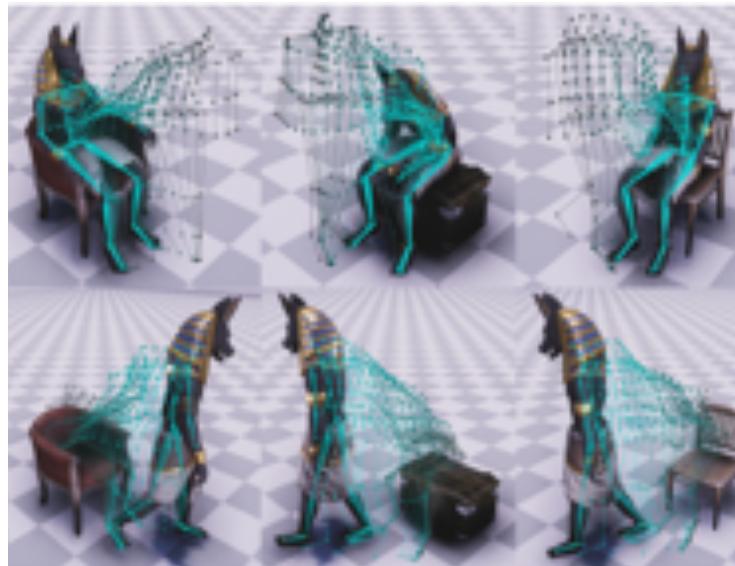
Relation type

Atemporal



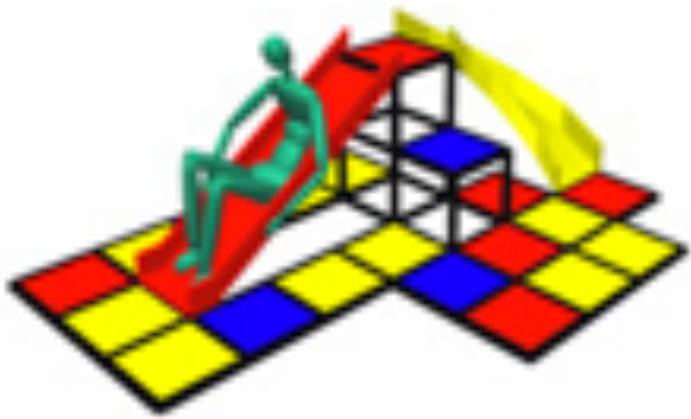
[SCH*16]

Time-varying

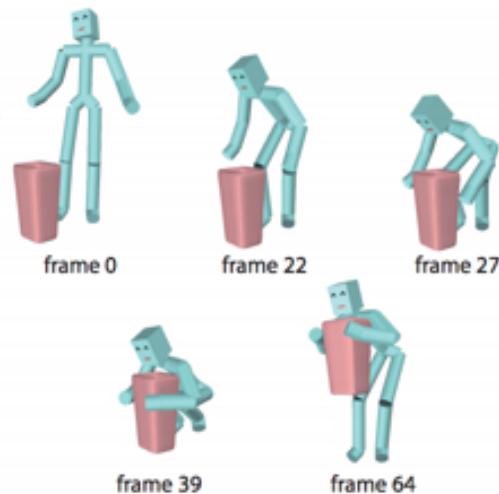


[SZKS19]

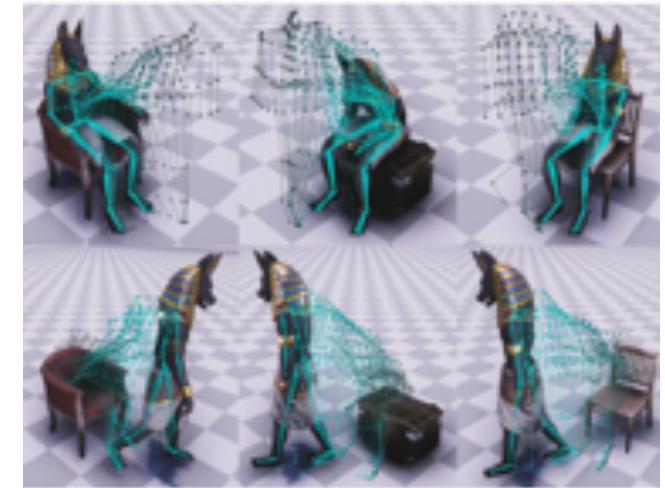
Relation type: time-varying



Motion patches
[LCL06]



Character-object IBS
[ZCK17]

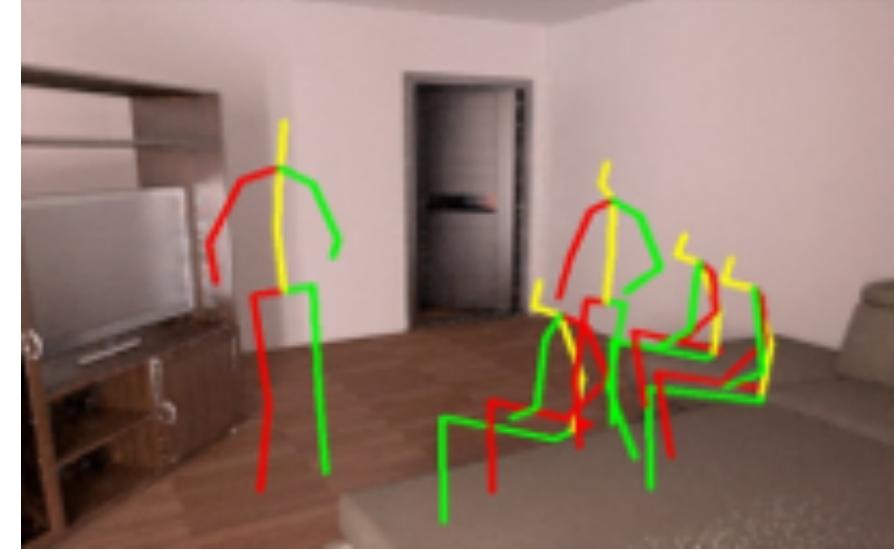


Character interactions
[SZKS19]

Generation: scene → agent(s)

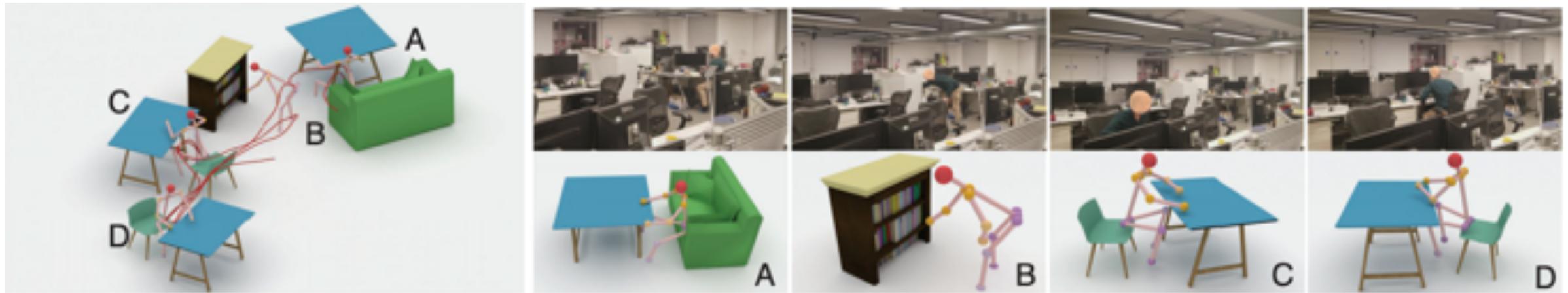


Generating 3D people
[ZHN*20]



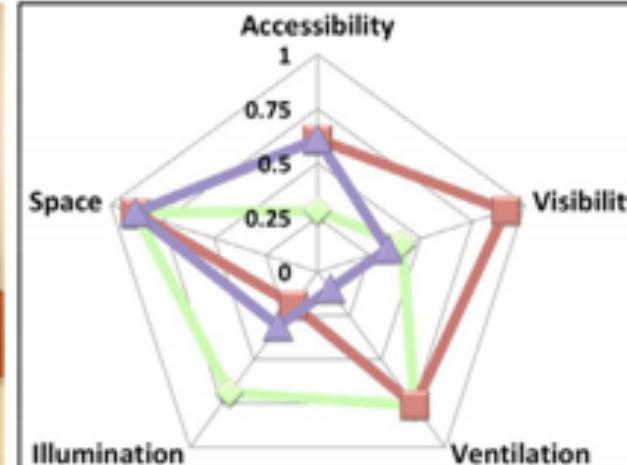
Putting humans in a scene
[LLK*19]

Generation: agent → scene



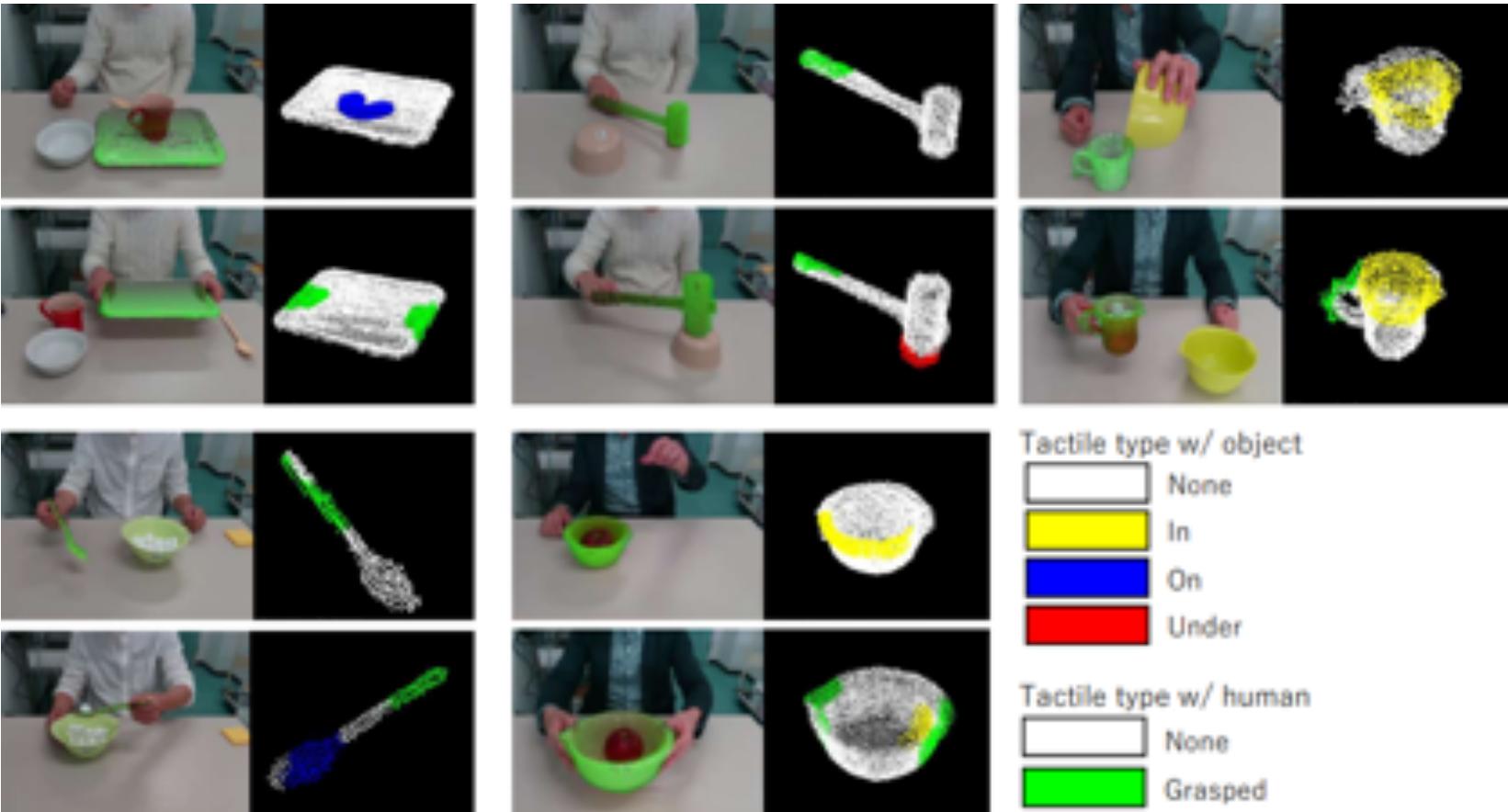
iMapper
[MGC*19]

Discrimination: scene quality metrics



Human-centric scene assessment metrics
[FFY*20]

Discrimination: object understanding



Tool use classification
[AA18]

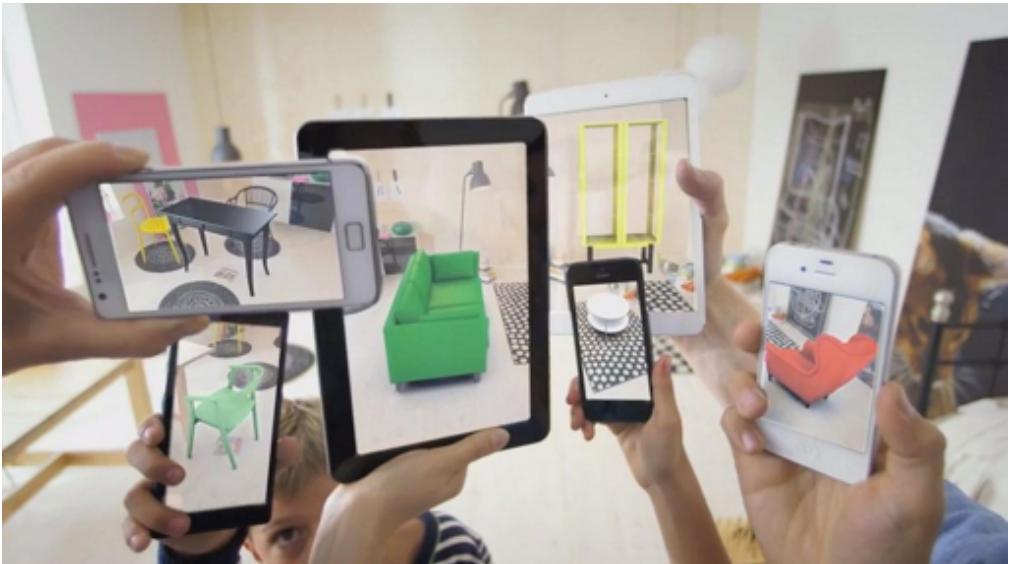


Future directions for geometry + agent methods

- Finer scale actions
- Social actions and hierarchical actions
- Time-varying relations in time-varying scenes
- Connections with robotics, computer vision, embodied AI

Summary: geometry + agent methods

Virtual and augmented reality



[image source:
<https://commons.wikimedia.org/wiki/File:Augmented-reality.jpg>]

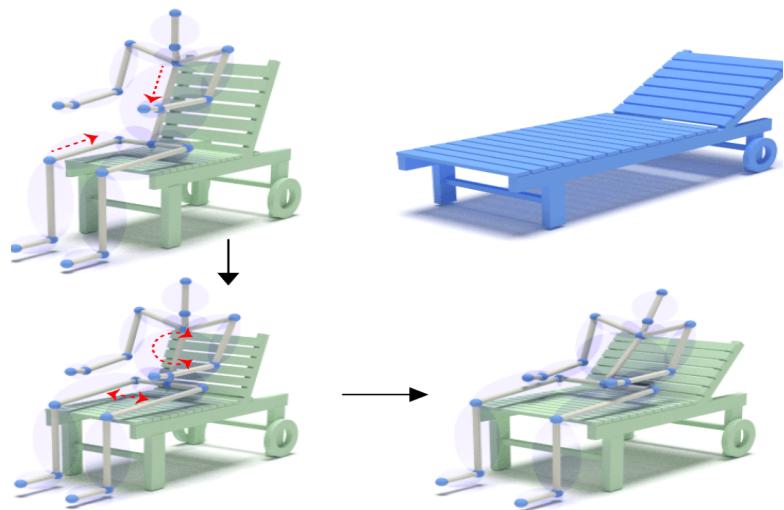
Fabrication



[image source:
https://commons.wikimedia.org/wiki/File:GENERATIC-collection-by-Emmanuel_Touraine-for-VENTURY-027.jpg]



Applications



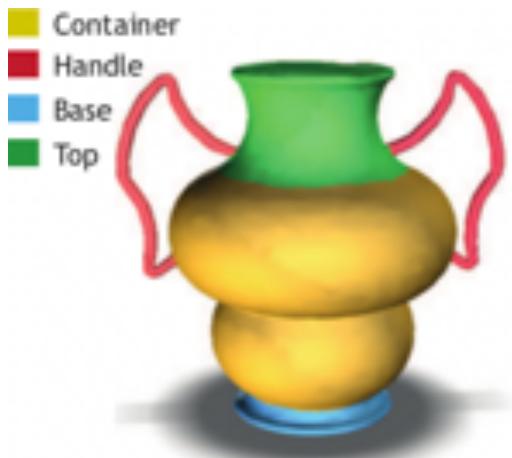


Application domains

- Classification, segmentation, and labeling
- Retrieval
- Synthesis
- Modeling and editing
- Visualization and fabrication
- Robotics and AI

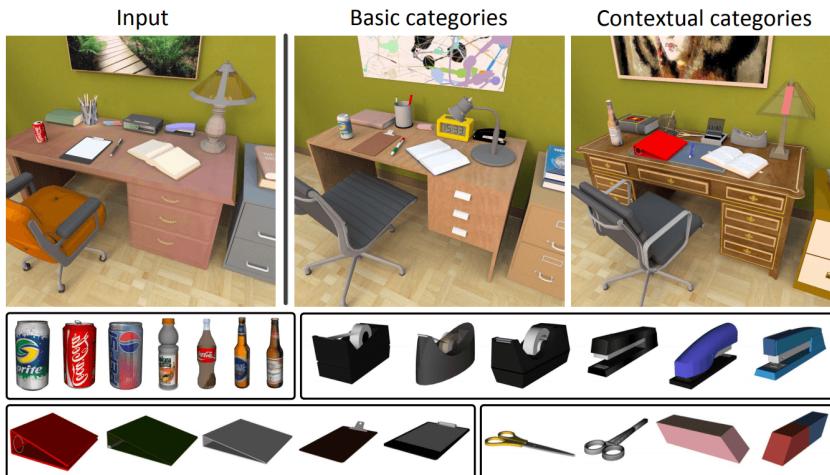
Classification, segmentation, labeling

Part classification



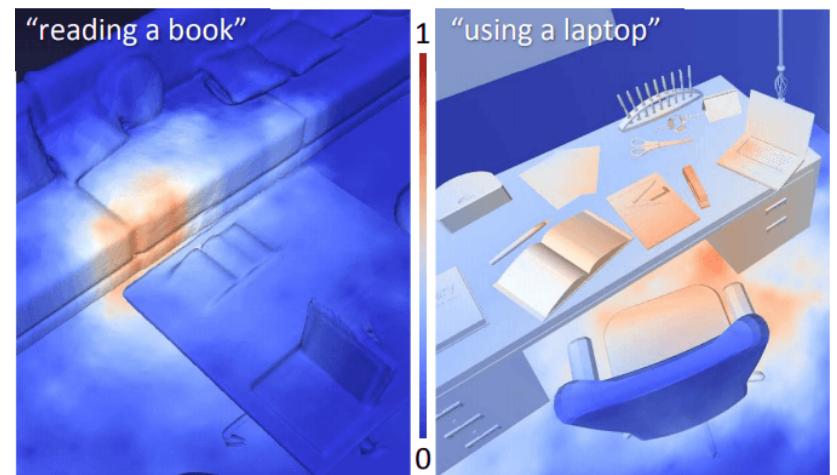
[LMS13]

Object classification



[FRS*12]

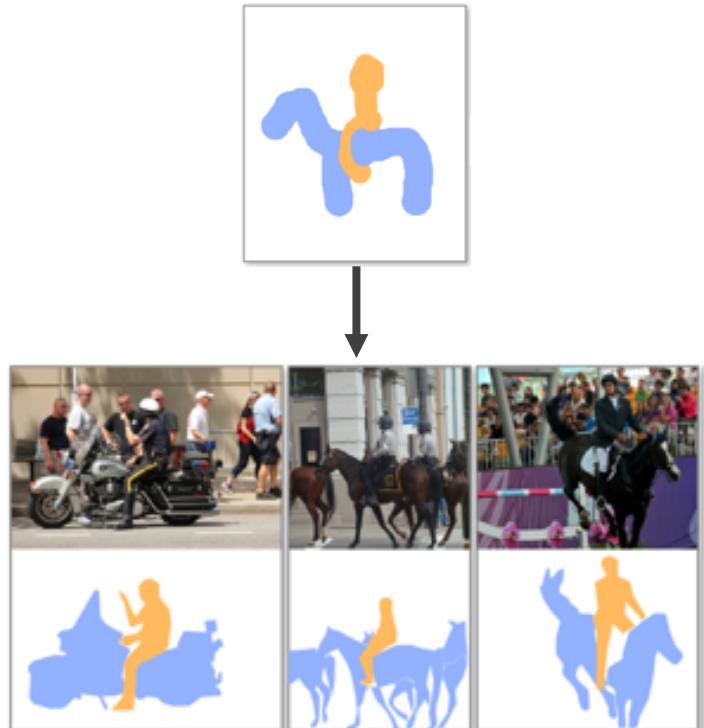
Scene classification



[SCH*14]

Retrieval

Part retrieval



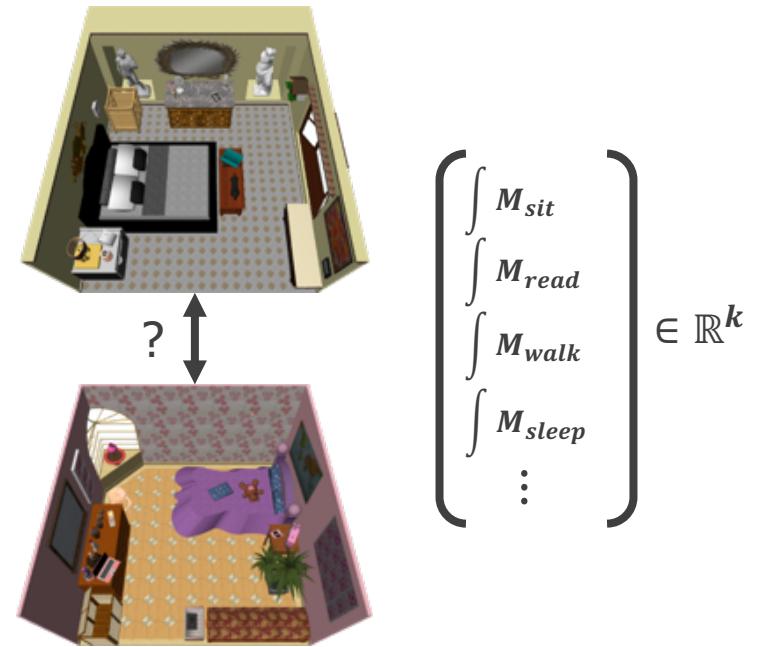
[GMW16]

Object-in-scene retrieval



[HZvK*15]

Scene retrieval



[SCH*14]

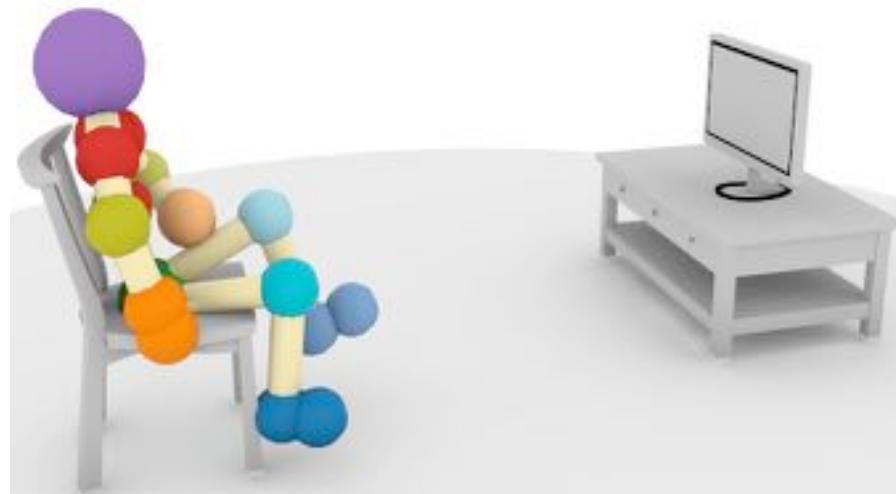
Synthesis

3D scene synthesis



[FSL*15]

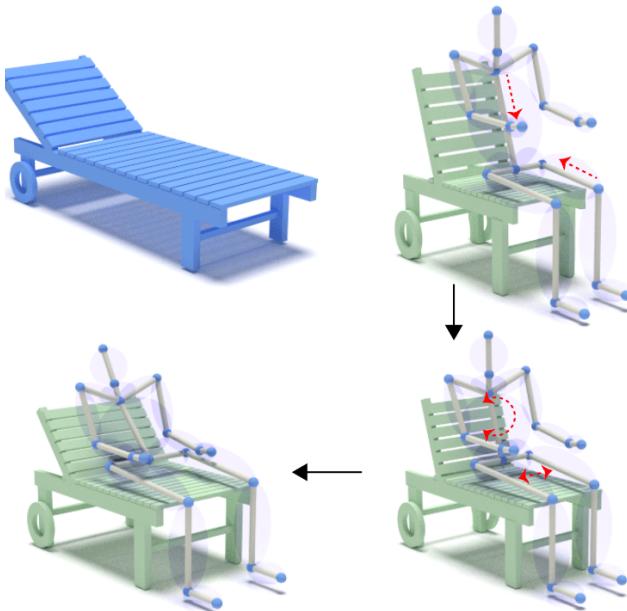
Human interaction synthesis



[SCH*16]

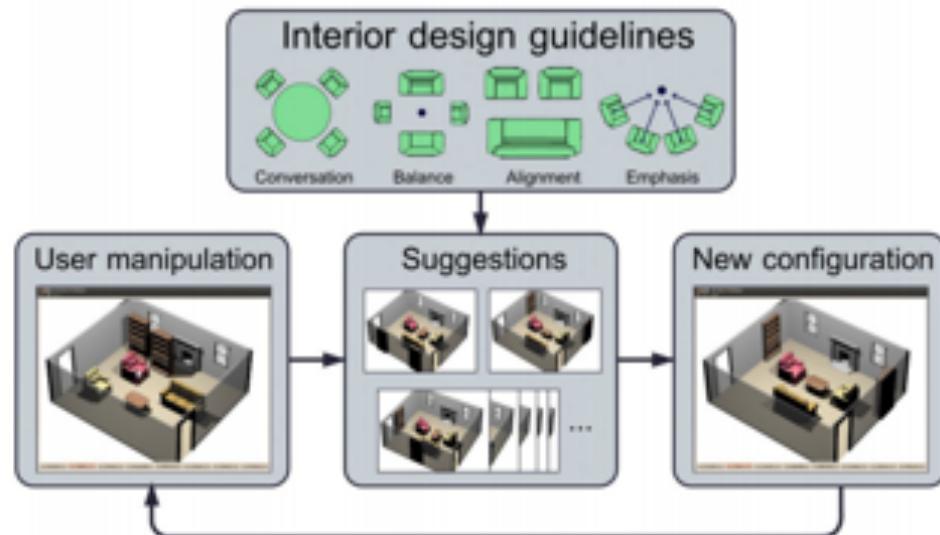
Modeling and editing

Object modeling



[ZLDM16]

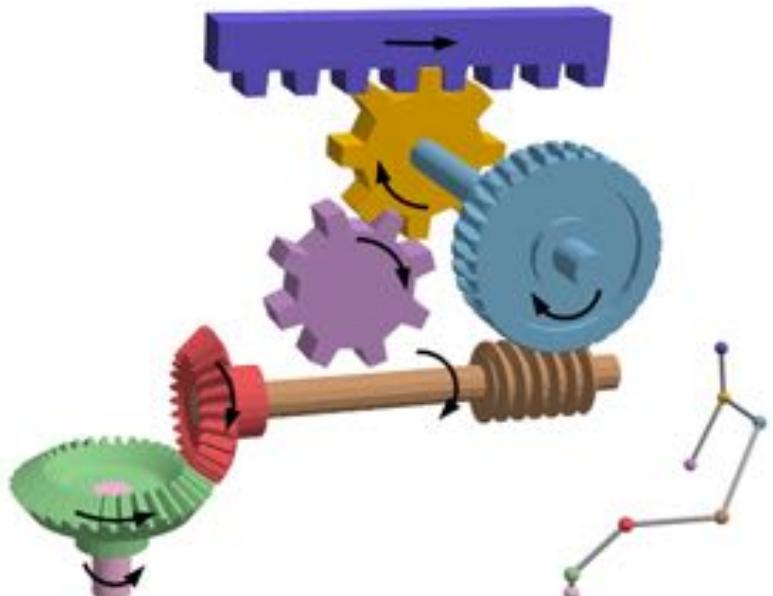
Scene editing



[MSL*11]

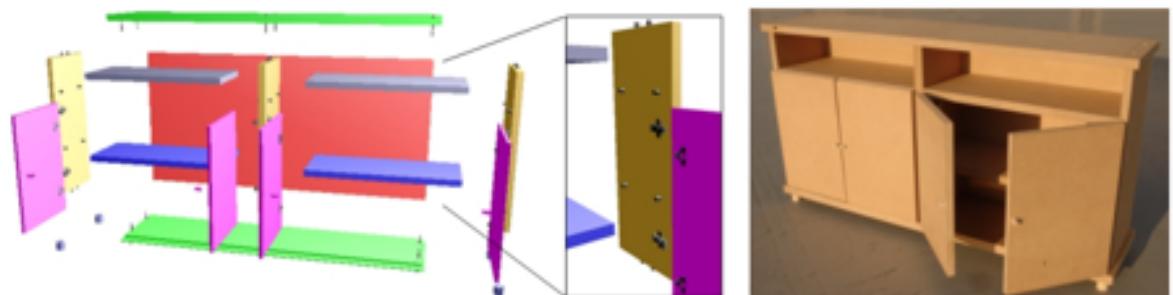
Visualization and fabrication

Assembly visualization



[MYY*10]

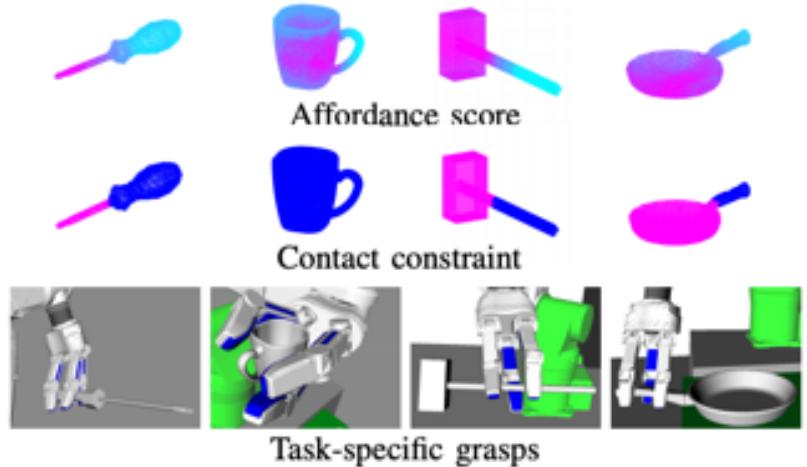
Fabrication



[LOMI11]

Robotics and AI

Affordance detection for grasping



[KSHK17]

SAPIEN: interactive 3D simulation



[XQM*20]



Applications: summary

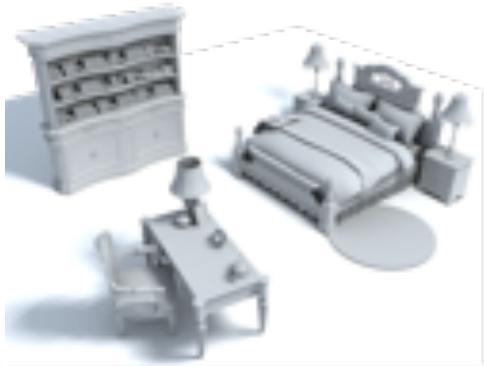
- Many application domains
- Functionality critical for both analysis and synthesis tasks
- Despite much recent work, open research questions abound



Future Directions



Different levels of functional entities



(a) Scene



(b) Object-union



(c) Object



(d) Part-union

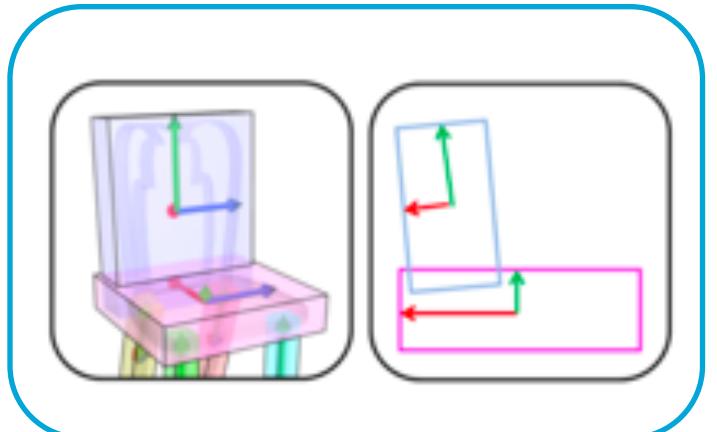


(e) Part

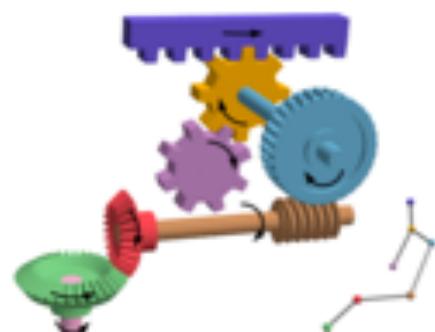
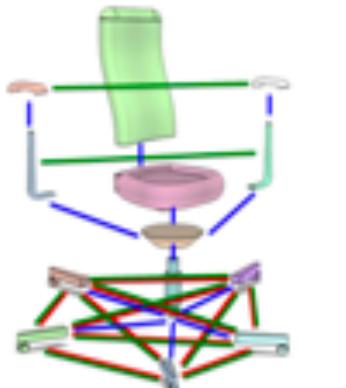
Multi-level treatment?

Hierarchical representation?

Interaction representation



**More informative
representation?**

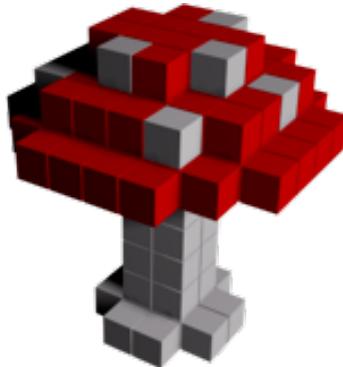




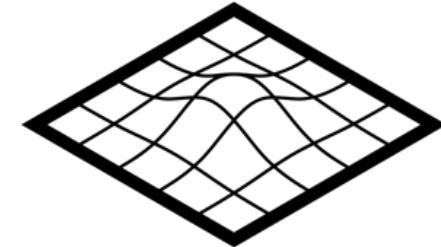
Mesh [HLK*17]



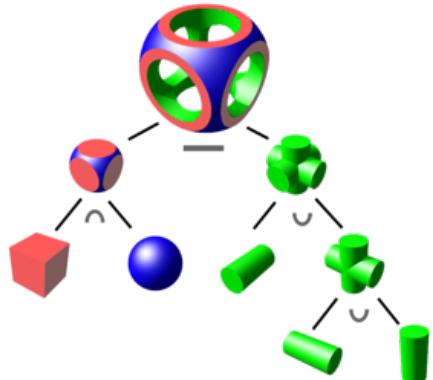
Point cloud [ZWK14]



Volumetric data



Parametric surface



Constructive solid geometry



Raw scan [FSL*15]

incomplete / partially regions

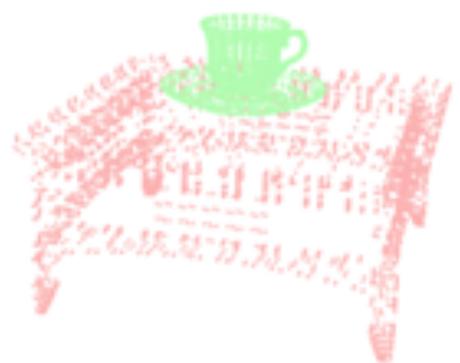
**presence
of noise**

**imperfect
registration**

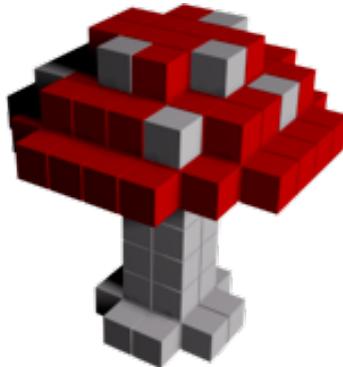
...



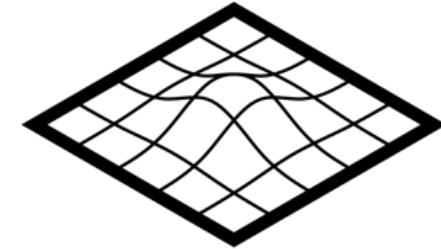
Mesh [HLK*17]



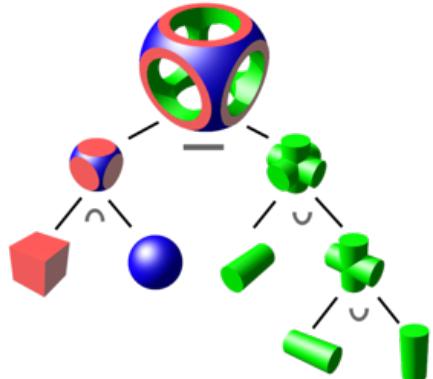
Point cloud [ZWK14]



Volumetric data



Parametric surface



Constructive solid geometry

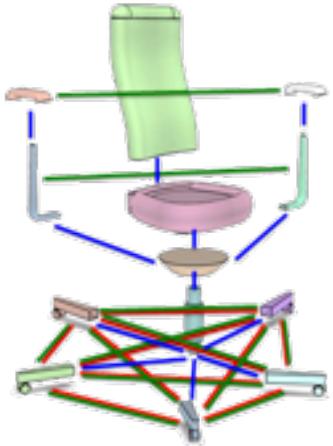


Raw scan [FSL*15]



RGB image
[ZFFF14]

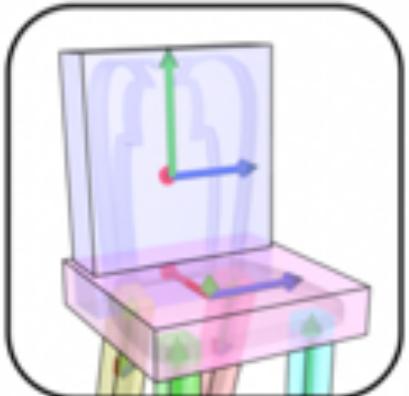
Static vs. dynamic



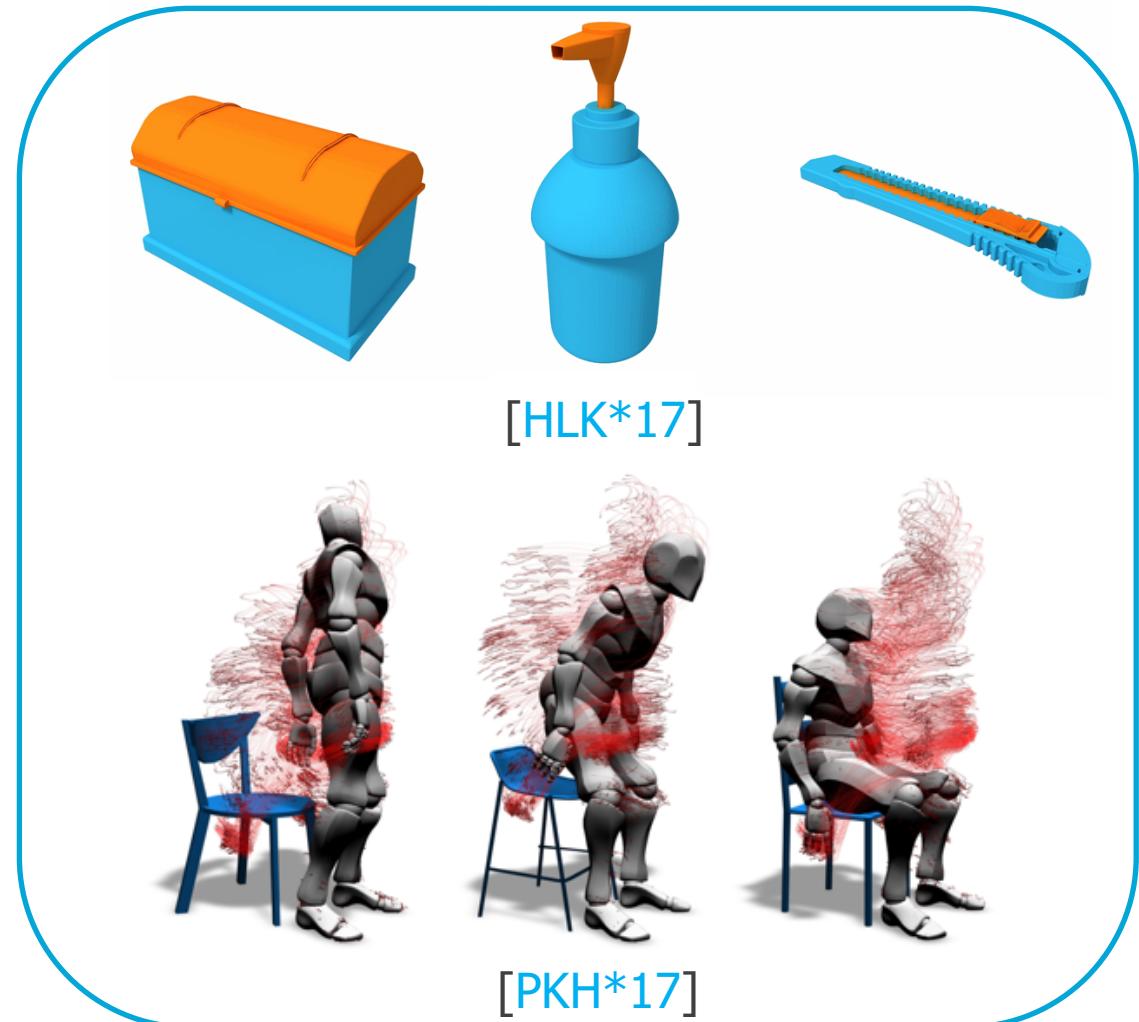
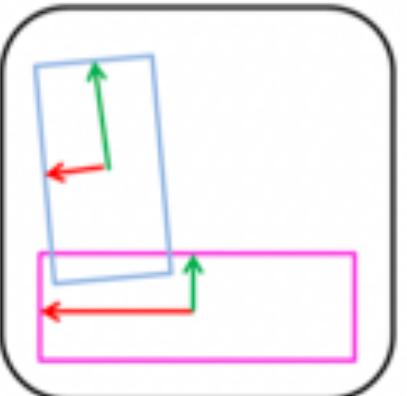
[WXL*11]



[FSL*15]

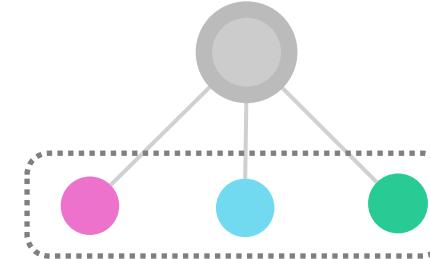


[FAvK*14]

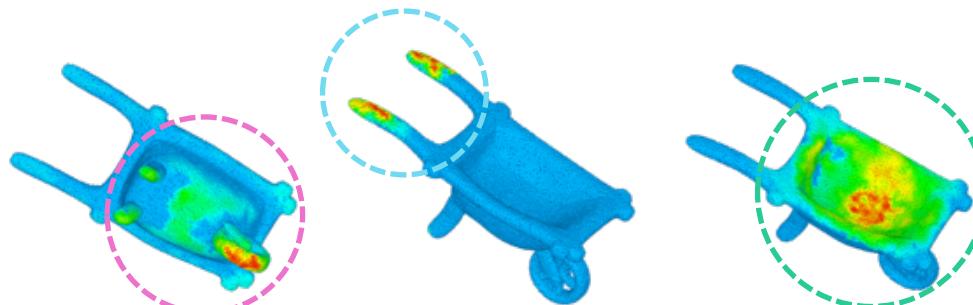
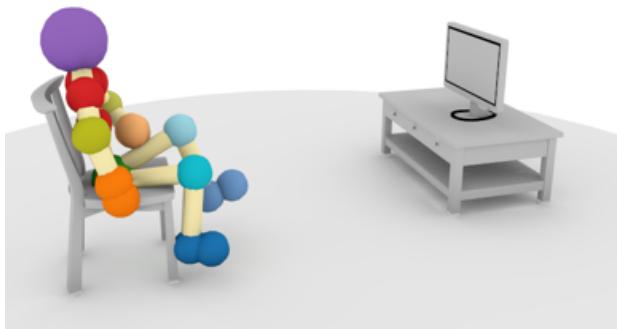


Real data collection?

Handcrafted vs. data-driven

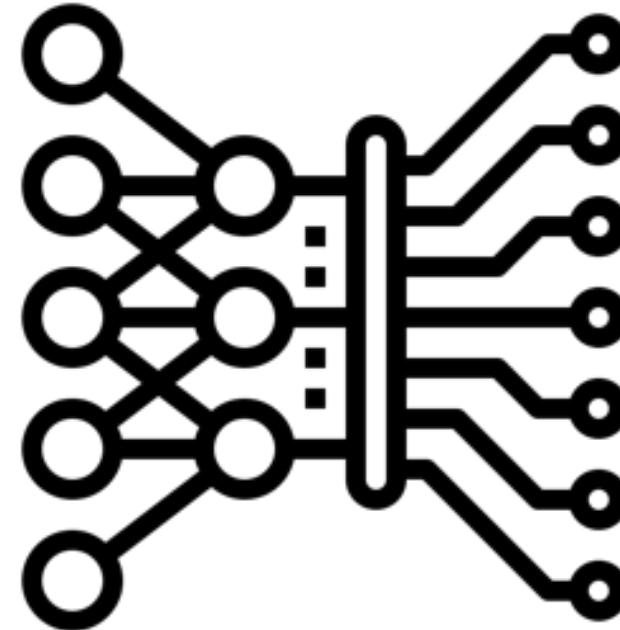
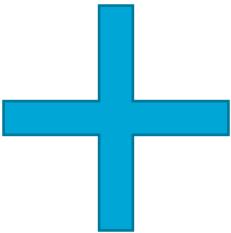
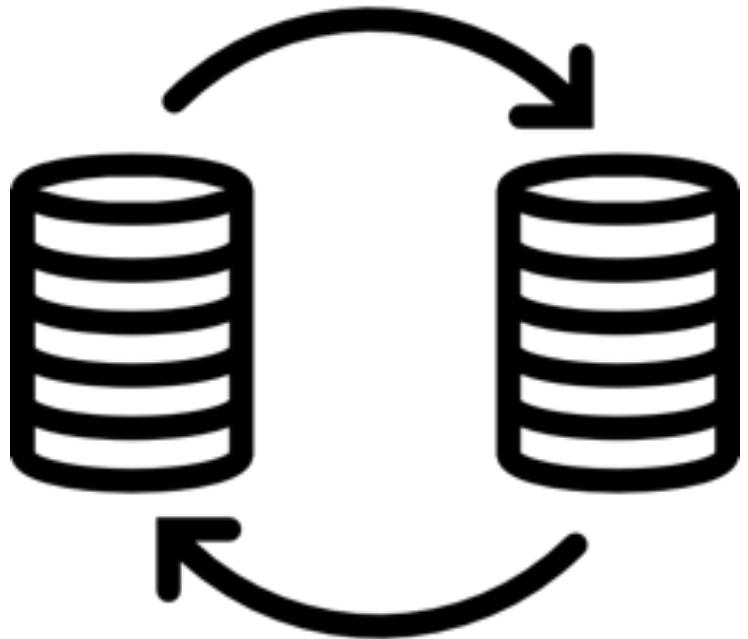


**prior
knowledge**



**handcrafted
features**

Handcrafted vs. data-driven



Large-scale 3D functionality dataset

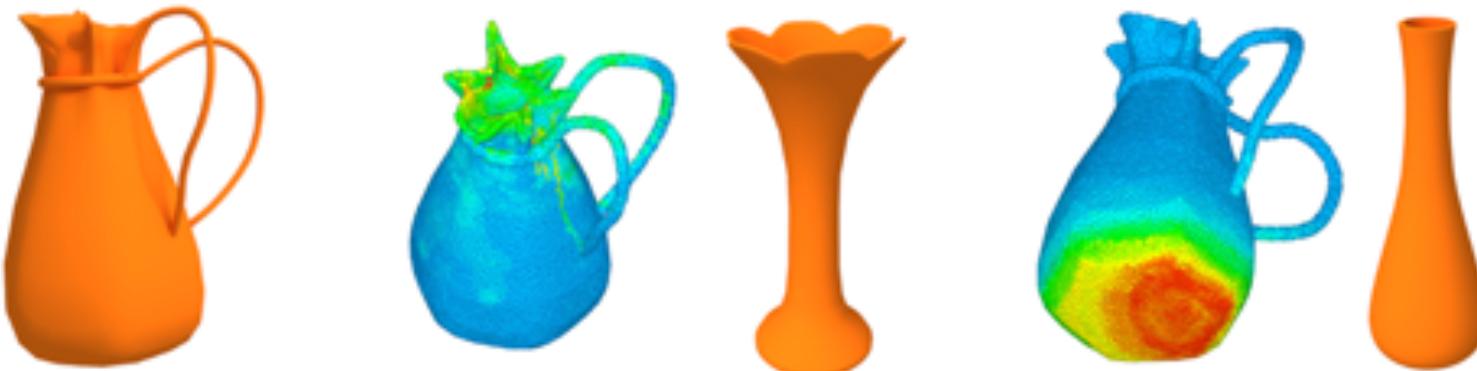
[Image source: Icons made by Pause08 www.flaticon.com]

Machine learning advances

[Image source: Icons made by Becris www.flaticon.com]

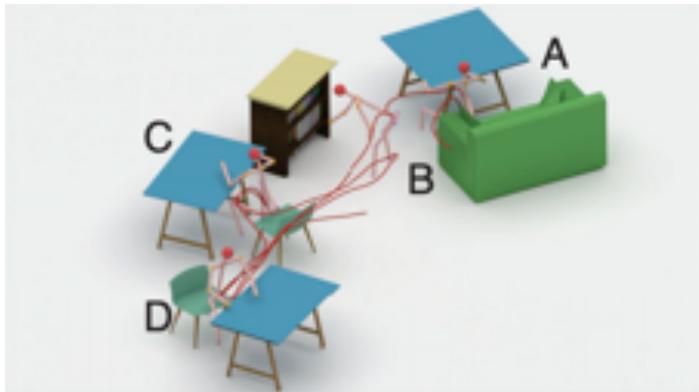
Beyond geometry

- Materials for physical reasoning
- Acoustic properties for sound-based functions

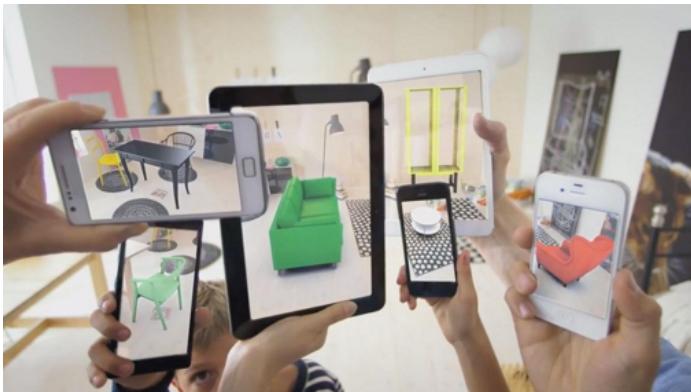


Emerging applications

- Functionality-guided scene synthesis
- Functionality-driven AR/VR
- Functionality-driven interactive 3D simulation



[MGC*19]



[image source:
<https://commons.wikimedia.org/wiki/File:Augmented-reality.jpg>]



[XQM*20]

Full understanding of 3D shape



{

Same functionality

Material

Weight

Size

⋮

Full understanding of 3D shape



Same functionality

Same style

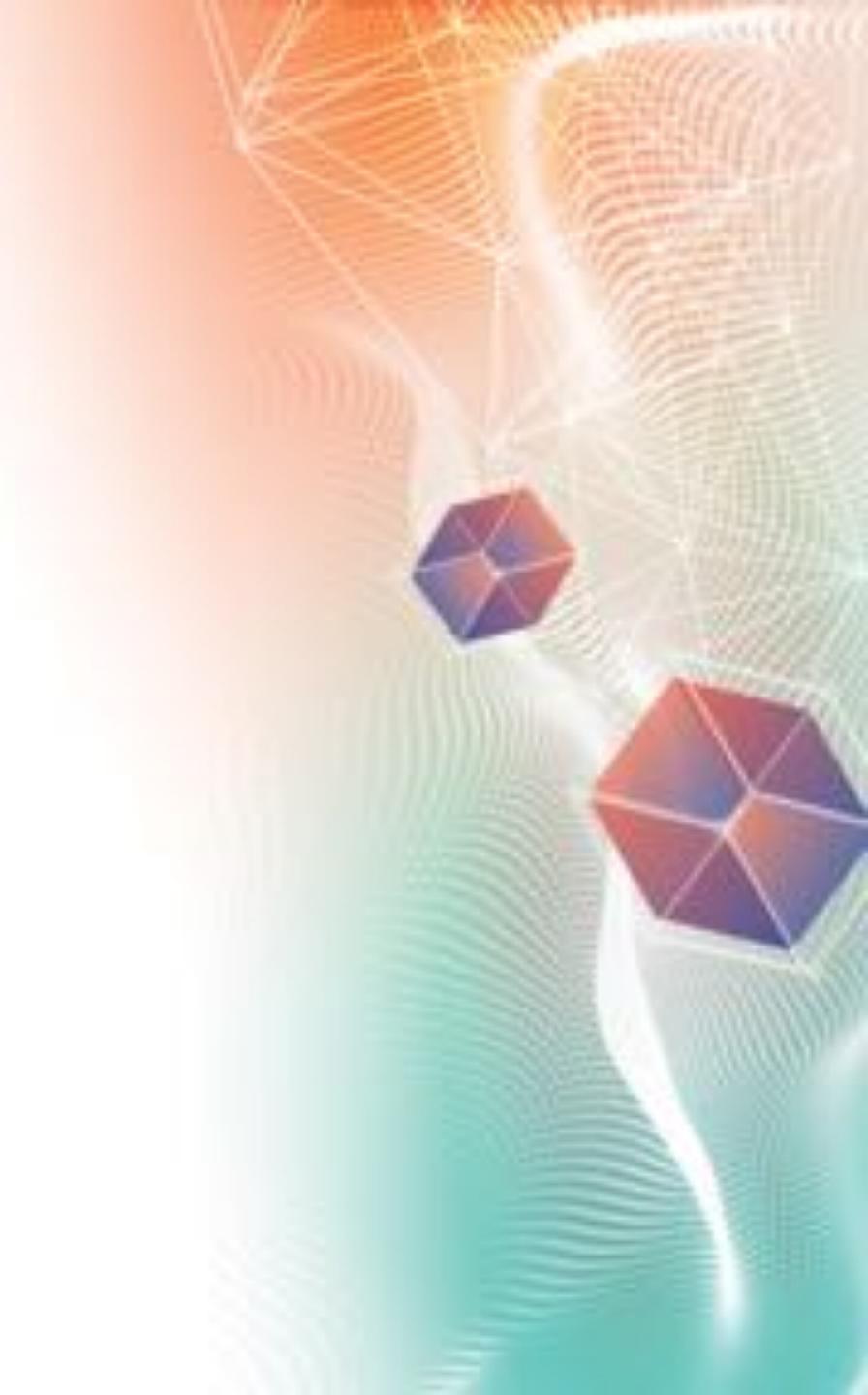


"Grand challenge"

- Model covering a range of functionality aspects
 - Human-object
 - Object-object
 - Dynamic settings
 - Physical properties
 - ...
- Use the model for analysis and synthesis
- E.g., realistic shape and scene synthesis



Conclusion



Summary

- Comprehensive survey of work on functionality
- Definition of functionality: geometry + interaction
- Three classes of methods:
geometry-only, geometry + interaction, geometry + agent
- Factorization into intrinsic and extrinsic properties

Limitations

- Functionality definition is not complete or perfect
- What are other ways of encoding functionality?
- What are the fundamental properties of parts, objects, scenes?
- Key question: form from function or function from form?



Thank you!

- Reasoning about functionality is ubiquitous
- Emerging connections between applications in graphics, vision, robotics, and AI
- Check out the course website for more information and for our contact details!

<https://learn3dfunc.github.io/>