## inst.eecs.berkeley.edu/~cs61c CS61C : Machine Structures

## Lecture 20 Almost Thread Level Parallelism



#### Da'Miki

#### **Intel Xeon Phi**



#### Review

- Flynn Taxonomy of Parallel Architectures
  - SIMD: Single Instruction Multiple Data
  - MIMD: Multiple Instruction Multiple Data
  - SISD: Single Instruction Single Data
  - MISD: Multiple Instruction Single Data (unused)
- Intel SSE SIMD Instructions
  - One instruction fetch that operates on multiple operands simultaneously
  - 64/128 bit XMM registers
  - (SSE =  $\underline{S}$ treaming  $\underline{S}$ IMD  $\underline{E}$ xtensions)
- Threads and Thread-level parallelism



#### Intel SSE Intrinsics

- Intrinsics are C functions and procedures for putting in assembly language, including SSE instructions
  - With intrinsics, can program using these instructions indirectly
  - One-to-one correspondence between SSE instructions and intrinsics



## **Example SSE Intrinsics**

#### **Instrinsics:**

Corresponding SSE instructions:

Vector data type:

• Load and store operations:

```
_mm_load_pd
_mm_store_pd
_mm_loadu_pd
_mm_storeu_pd
```

MOVAPD/aligned, packed double MOVAPD/aligned, packed double MOVUPD/unaligned, packed double MOVUPD/unaligned, packed double

Load and broadcast across vector

MOVSD + shuffling/duplicating

• Arithmetic:

ADDPD/add, packed double MULPD/multiple, packed double



**Definition of Matrix Multiply:** 

$$C_{i,j} = (A \times B)_{i,j} = \sum_{k=1}^{2} A_{i,k} \times B_{k,j}$$

$$C_{i,j} = (A \times B)_{i,j} = \sum_{k=1}^{n} A_{i,k} \times B_{k,j}$$

$$K = 1$$

$$\begin{bmatrix} A_{1,1} & A_{1,2} \\ A_{2,1} & A_{2,2} \end{bmatrix} \times \begin{bmatrix} B_{1,1} & B_{1,2} \\ B_{2,1} & B_{2,2} \end{bmatrix} = \begin{bmatrix} C_{1,1} = A_{1,1}B_{1,1} + A_{1,2}B_{2,1} & C_{1,2} = A_{1,1}B_{1,2} + A_{1,2}B_{2,2} \\ C_{2,1} = A_{2,1}B_{1,1} + A_{2,2}B_{2,1} & C_{2,2} = A_{2,1}B_{1,2} + A_{2,2}B_{2,2} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} = \begin{bmatrix} C_{1,1} = 1*1 + 0*2 = 1 & C_{1,2} = 1*3 + 0*4 = 3 \\ C_{2,1} = 0*1 + 1*2 = 2 & C_{2,2} = 0*3 + 1*4 = 4 \end{bmatrix}$$



- Using the XMM registers
  - 64-bit/double precision/two doubles per XMM reg



Stored in memory in Column order





Initialization

$C_1$	0	0
C <sub>2</sub>	0	0



#### Initialization

$C_1$	0	0
$C_2$	0	0

#### • | = 1



\_mm\_load\_pd: Load 2 doubles into XMM
reg, Stored in memory in Column order

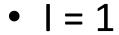




#### First iteration intermediate result

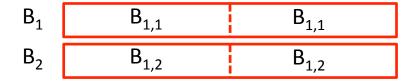
$$\begin{array}{c|ccccc}
C_1 & 0+A_{1,1}B_{1,1} & 0+A_{2,1}B_{1,1} \\
C_2 & 0+A_{1,1}B_{1,2} & 0+A_{2,1}B_{1,2}
\end{array}$$

c1 = \_mm\_add\_pd(c1,\_mm\_mul\_pd(a,b1));
c2 = \_mm\_add\_pd(c2,\_mm\_mul\_pd(a,b2));
SSE instructions first do parallel multiplies
and then parallel adds in XMM registers





\_mm\_load\_pd: Stored in memory in Column order





#### First iteration intermediate result

$$\begin{array}{c|ccccc}
C_1 & 0+A_{1,1}B_{1,1} & 0+A_{2,1}B_{1,1} \\
C_2 & 0+A_{1,1}B_{1,2} & 0+A_{2,1}B_{1,2}
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SSE instructions first do parallel multiplies
and then parallel adds in XMM registers

#### • I = 2



\_mm\_load\_pd: Stored in memory in Column order





#### Second iteration intermediate result

c1 = \_mm\_add\_pd(c1,\_mm\_mul\_pd(a,b1));
c2 = \_mm\_add\_pd(c2,\_mm\_mul\_pd(a,b2));
SSE instructions first do parallel multiplies
and then parallel adds in XMM registers

| = 2



\_mm\_load\_pd: Stored in memory in Column order





**Definition of Matrix Multiply:** 

$$C_{i,j} = (A \times B)_{i,j} = \sum_{k=1}^{2} A_{i,k} \times B_{k,j}$$

$$C_{i,j} = (A \times B)_{i,j} = \sum_{k=1}^{n} A_{i,k} \times B_{k,j}$$

$$K = 1$$

$$\begin{bmatrix} A_{1,1} & A_{1,2} \\ A_{2,1} & A_{2,2} \end{bmatrix} \times \begin{bmatrix} B_{1,1} & B_{1,2} \\ B_{2,1} & B_{2,2} \end{bmatrix} = \begin{bmatrix} C_{1,1} = A_{1,1}B_{1,1} + A_{1,2}B_{2,1} & C_{1,2} = A_{1,1}B_{1,2} + A_{1,2}B_{2,2} \\ C_{2,1} = A_{2,1}B_{1,1} + A_{2,2}B_{2,1} & C_{2,2} = A_{2,1}B_{1,2} + A_{2,2}B_{2,2} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} = \begin{bmatrix} C_{1,1} = 1*1 + 0*2 = 1 & C_{1,2} = 1*3 + 0*4 = 3 \\ C_{2,1} = 0*1 + 1*2 = 2 & C_{2,2} = 0*3 + 1*4 = 4 \end{bmatrix}$$



# Example: 2 x 2 Matrix Multiply (Part 1 of 2)

```
#include <stdio.h>
// header file for SSE compiler intrinsics
#include <emmintrin.h>
// NOTE: vector registers will be represented in
    comments as v1 = [a | b]
// where v1 is a variable of type m128d and
    a, b are doubles
int main(void) {
  // allocate A,B,C aligned on 16-byte boundaries
  double A[4] attribute ((aligned (16)));
  double B[4] attribute ((aligned (16)));
  double C[4] attribute ((aligned (16)));
  int Ida = 2;
  int i = 0;
  // declare several 128-bit vector variables
    m128d c1,c2,a,b1,b2;
```

```
// Initialize A, B, C for example
/* A =
                      (note column order!)
    10
    01
  A[0] = 1.0; A[1] = 0.0; A[2] = 0.0; A[3] = 1.0;
/* B =
                       (note column order!)
    13
    24
   */
  B[0] = 1.0; B[1] = 2.0; B[2] = 3.0; B[3] = 4.0;
/* C =
                       (note column order!)
    00
    00
  C[0] = 0.0; C[1] = 0.0; C[2] = 0.0; C[3] = 0.0;
```



# Example: 2 x 2 Matrix Multiply (Part 2 of 2)

```
// used aligned loads to set
  //c1 = [c_11 | c_21]
  c1 = mm load pd(C+0*lda);
  //c2 = [c 12 | c 22]
  c2 = mm load pd(C+1*lda);
  for (i = 0; i < 2; i++) {
    /* a =
     i = 0: [a 11 | a 21]
     i = 1: [a 12 | a 22]
     */
     a = mm load pd(A+i*lda);
    /* b1 =
     i = 0: [b 11 | b 11]
     i = 1: [b 21 | b 21]
     */
    b1 = mm load1 pd(B+i+0*lda);
    /* b2 =
     i = 0: [b 12 | b 12]
     i = 1: [b_22 | b 22]
     b2 = mm load1 pd(B+i+1*lda);
```

```
/* c1 =
   i = 0: [c 11 + a 11*b 11 | c 21 + a 21*b 11]
   i = 1: [c 11 + a 21*b 21 | c 21 + a 22*b 21]
  c1 = mm add pd(c1, mm mul pd(a,b1));
  /* c2 =
   i = 0: [c 12 + a 11*b 12 | c 22 + a 21*b 12]
   i = 1: [c 12 + a 21*b 22 | c 22 + a 22*b 22]
  c2 = mm add pd(c2, mm mul pd(a,b2));
// store c1,c2 back into C for completion
mm store pd(C+0*lda,c1);
mm store pd(C+1*lda,c2);
// print C
printf("%g,%g\n%g,%g\n",C[0],C[2],C[1],C[3]);
return 0;
```

## Inner loop from gcc –O -S

```
(%rax,%rsi), %xmm1 //Load aligned A[i,i+1]->m1
L2: movapd
   movddup (%rdx), %xmm0 //Load B[j], duplicate->m0
            %xmm1, %xmm0
                              //Multiply m0*m1->m0
  mulpd
            %xmm0, %xmm3 //Add m0+m3->m3
  addpd
   movddup 16(%rdx), %xmm0 //Load B[j+1], duplicate->m0
  mulpd
            %xmm0, %xmm1 //Multiply m0*m1->m1
  addpd
                              //Add m1+m2->m2
            %xmm1, %xmm2
                              // rax+16 -> rax (i+=2)
  addq
            $16, %rax
            $8, %rdx
                              // rdx + 8 -> rdx (j+=1)
  addq
            $32, %rax
                              // rax == 32?
  cmpq
                               // jump to L2 if not equal
  jne
            L2
                              //store aligned m3 into C[k,k+1]
            %xmm3, (%rcx)
   movapd
                              //store aligned m2 into C[l,l+1]
            %xmm2, (%rdi)
  movapd
```



### You Are Here!

#### Software

Harness

Parallelism &

**Parallel Requests** Assigned to computer e.g., Search "Katz"

Parallel Threads

Assigned to core e.g., Lookup, Ads Hardware

Warehouse

Scale Computer



Smart Phone



arcia, Lustig Fall 2014 © UCB

**Parallel Instructions** >1 instruction @ one time

e.g., 5 pipelined instructions

Parallel Data

>1 data item @ one time e.g., Add of 4 pairs of words

Hardware descriptions

All gates functioning in parallel at same time

Achieve High Computer Performance Core Core (Cache) Project 3 Memory Input/Output Core Functional nstruction Unit(s) Unit(s)  $A_0 + B_0 A_1 + B_1 A_2 + B_2 A_3 + B_3$ Main Memory **Logic Gates** 

CS61C L20 Thread Level Parallelism I (18)

## Thoughts about Threads



"Although threads seem to be a small step from sequential computation, in fact, they represent a huge step. They discard the most essential and appealing properties of sequential computation: understandability, predictability, and determinism. Threads, as a model of computation, are wildly non-deterministic, and the job of the programmer becomes one of pruning that nondeterminism."

— The Problem with Threads, Edward A. Lee, UC Berkeley, 2006



## Background: Threads

- A Thread stands for "thread of execution", is a single stream of instructions
  - A program / process can split, or fork itself into separate threads, which can (in theory) execute simultaneously. Process
  - An easy way to describe/think about parallelism
- A single CPU can execute many threads by <u>Time Division Multipexing</u>

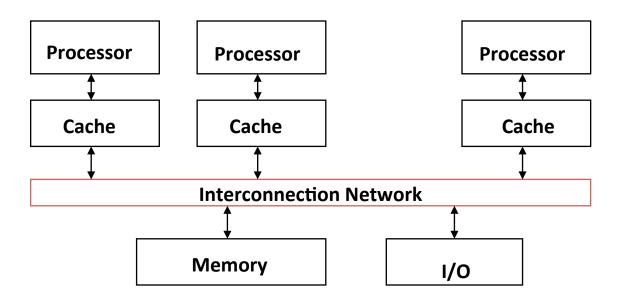


 Multithreading is running multiple threads through the same hardware



# Parallel Processing: Multiprocessor Systems (MIMD)

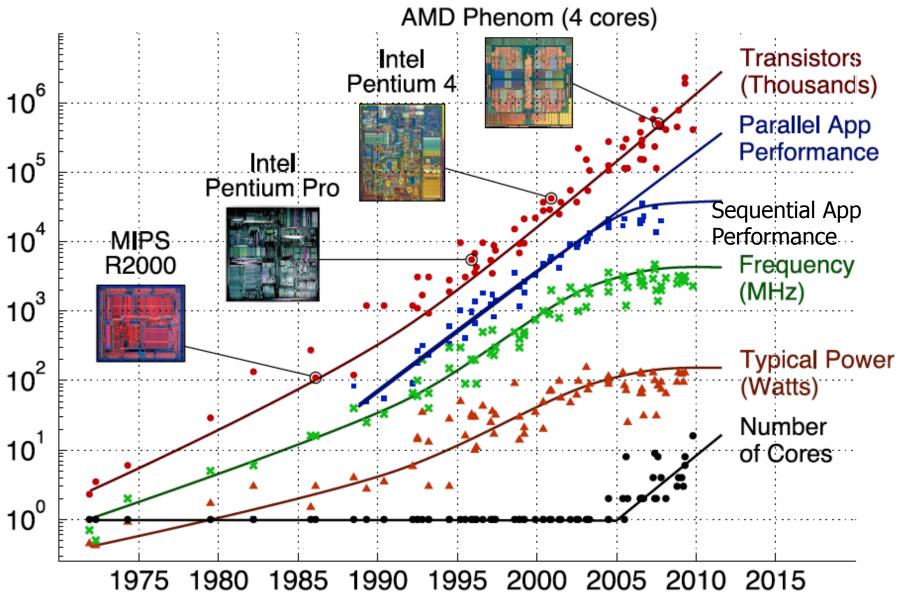
Multiprocessor (MIMD): a computer system with at least 2 processors



- 1. Deliver high throughput for independent jobs via job-level parallelism
- 2. Improve the run time of a single program that has been specially crafted to run on a multiprocessor a parallel processing program

Now Use term *core* for processor ("Multicore") because "Multiprocessor Microprocessor" too redundant

### Transition to Multicore



## Multiprocessors and You

- Only path to performance is parallelism
  - Clock rates flat or declining
  - SIMD: 2X width every 3-4 years
    - 128b wide now, 256b 2011, 512b in 2014?, 1024b in 2018?
    - Advanced Vector Extensions are 256-bits wide!
  - MIMD: Add 2 cores every 2 years: 2, 4, 6, 8, 10, ...
- A key challenge is to craft parallel programs that have high performance on multiprocessors as the number of processors increase – i.e., that scale
  - Scheduling, load balancing, time for synchronization, overhead for communication
- Will explore this further in labs and projects



### Parallel Performance Over Time

Year	Cores	SIMD bits /Core	Core * SIMD bits	Peak DP FLOPs
2003	2	128	256	4
2005	4	128	512	8
2007	6	128	768	12
2009	8	128	1024	16
2011	10	256	2560	40
2013	12	256	3072	48
2015	14	512	7168	112
2017	16	512	8192	128
2019	18	1024	18432	288
2021	20	1024	20480	320

## So, In Conclusion...

- Sequential software is slow software
  - SIMD and MIMD only path to higher performance
- SSE Intrinsics allow SIMD instructions to be invoked from C programs
- MIMD uses multithreading to achieve high parallelism

