More Synchronization

CS439: Principles of Computer Systems February 11, 2015

Last Time

- Hardware Support for Mutual Exclusion and Synchronization
 - read-modify-write instructions
- Mutual Exclusion and Synchronization in Software
 - Abstractions built on top of hardware support
 - Locks
 - Semaphores

Semaphore Recap

- Two types: binary and counted
- Used for locking and synchronization
- Two atomic operations:
 - down(): wait for semaphore to be available, decrement value
 - up(): signal waiting threads semaphore is available, increment value
- Need separate semaphores for locking and synchronizing

Semaphore Operations

Semaphore::Down(){

```
*if value is == 0, sleep

*on signal, wake up

*decrement semaphore
value

*return
```

Semaphore::Up{

```
*increment semaphore value
*if any threads are sleeping
on semaphore, wake one of
them up
*return
```

Today's Agenda

- More Synchronization in Software
 - Monitors
 - Locks and Condition Variables
 - Bounded Buffer problem
- Readers/Writers problem

Monitors

Introducing Monitors

- Monitors guarantee mutual exclusion
 - only one thread may execute a given monitor method at a time
- First introduced as a programming language construct (Mesa, Java)
- Now also define a programming convention and can be used in any language (C, C++, ...)
- Object-oriented style:
 - Collect related shared data into an object/module
 - Associate a lock with each one
 - All data is private
 - Define methods for accessing the shared data
 - These are critical sections

Monitors, Formally

A monitor defines a *lock* and zero or more *condition variables* for managing concurrent access to shared data.

- uses the *lock* to ensure that only a single thread is active in the monitor at any point
- the *lock* also provides mutual exclusion for shared data
- Condition variables enable threads to block waiting for an event inside of critical sections
 - release the lock at the same time the thread is put to sleep

Monitor Implementation

- Goal is to encapsulate shared data
 - Class in C++ or Java
 - Struct or File in C (logical encapsulation)
- Goal is to provide for mutual exclusion
 - Has a lock (exactly one!)
- Goal is to allow for synchronization
 - Has condition variables
- Goal is to allow operations on the shared data
 - Has functions or methods

Monitor Functions: Implementation

- Acquire the lock at the start of every function (first thing!)
 - Operate on the shared data
 - Temporarily release the lock if they can't complete due to missing resource (use condition variable for this)
 - Reacquire the lock when they can continue (again, condition variable!)
 - Operate on the shared data
- Release the lock at the end

Semaphore Example: Producers/Consumers (Recall)

```
Semaphore mutex = 1 //access to buffer
  Semaphore empty = N //count of empty slots
  Semaphore full = 0 //count of full slots
  int buffer[N]
BoundedBuffer::Producer(){
                                      BoundedBuffer::Consumer(){
                                        full->down() //get item
 mutex->down() //get access to buffer
 empty->down() //get empty spot
 mutex->down() //get access to buffer
                                        <remove item from buffer>
 <add item to buffer>
                                        mutex->up() //release buffer
 mutex->up() //release buffer
                                        empty->up() //another empty slot
 full->up() //another item in buffer
                                        <use item>
```

```
Semaphore mutex = 1 //access to buffer
Semaphore empty = N //count of empty slots
Semaphore full = 0 //count of full slots
int buffer[N]
BoundedBuffer::Producer(){
 oduce item>
 empty->down() //get empty spot
 mutex->down() //get access to buffer
 <add item to buffer>
 mutex->up() //release buffer
 full->up() //another item in buffer
```

Condition Variables

- Enable threads to wait efficiently for changes to shared state protected by a lock
- Each one is a queue of waiting threads (no state!)
- Enable the thread to sleep inside a critical section by atomically releasing the Lock at the same time the thread is put to sleep

Rule: A thread *must* hold the lock when doing condition variable operations

Condition Variable Operations

1. Wait(Lock lock)

- atomic (release lock, move thread to waiting queue, suspend thread)
- when the thread wakes up it re-acquires the lock (before returning from wait)
- thread will always block

2. Signal(Lock lock)

wake up waiting thread, if one exists. Otherwise, it's a no-op

3. Broadcast(Lock lock)

wake up all waiting threads, if any exist. Otherwise, it's a no-op

Monitor Operations

```
Lock->Acquire() //acquires lock, when returns, thread has lock Lock->Release() //releases lock
```

**CondVar::Wait(lock){ *move thread to waiting queue and suspend thread *release lock *on signal, wake up, re-acquire lock *return }

CondVar::Signal(){

```
*wake up a process waiting on condVar
```

*return

CondVar::Broadcast(){

```
*wake up ALL processes waiting on condVar
```

*return

j

Resource Variables

- Conditions variables (unlike semaphores) keep no state
- Each condition variable should have a resource variable that tracks the state of that resource
 - You must maintain this variable
- Check the resource variable before calling wait on the associated condition variable to ensure the resource really isn't available
- Once the resource is available, claim it (subtract the amount you are using!)
- Before signaling that you are finished with a resource, indicate the resource is available by increasing the resource variable

Monitor Example: Items in a Queue

```
Lock lock;
                               void remove(){
Condition fullCV;
                                lock->acquire()
int queue size;
                                while(queue_size <=0)
void Add(item){
                                  fullCV->wait(lock);
  lock->acquire()
                                queue_size--;
  put item on queue;
  queue size++;
                                remove item;
  fullCV->signal(lock)
                                lock->release();
  lock->release()
```

Signal() Semantics

Which thread executes once signal() is called?

- If there are no waiting threads, the signaler continues and the signal is effectively lost
- If there is a waiting thread (or two):
 - There are at least two ready threads: the one that called signal() and the one that was (or will be) awakened
 - Exactly one of the threads can execute or we will have more than one thread active in the monitor (violates mutual exclusion!)
 - So which thread gets to execute?

Whose turn is it?

Mesa/Hansen Style

- The thread that signals keeps the lock (and thus the processor)
- The waiting thread waits for the lock
 - Signal is only a hint that the condition may be true: shared state may have changed!
 - Adding signals affects performance, but never safety
- Implemented in Java and most real operating systems

Hoare Style

- The thread that signals gives up the lock and the waiting thread gets the lock
 - Signaling is atomic with the resumption of the waiting thread
 - Shared state cannot change before waiting thread is resumed
- When the thread that was waiting and is now executing exits or waits again, it releases the lock back to the signaling thread
- Implemented in most textbooks (not yours!)

More on Turns

- With Mesa-style, waiting thread may need to wait again after it is wakened (Why?), so while is important
- With Hoare-style, we can change while to if because a waiting thread runs immediately

```
public void remove(){
  lock->Acquire()
  while (queue_size <= 0){
    full->wait(lock);
  }
  queue_size--;
  remove item;
  lock->Release();
}
```

Regardless, if you assume there is NO atomicity between signal() and the return from wait(), your code will always work.

Semaphore Example: Producers/Consumers (Recall)

```
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  int buffer[N]
BoundedBuffer::Producer(){
                                      BoundedBuffer::Consumer(){
                                        full->down() //get item
 mutex->down() //get access to buffer
 empty->down() //get empty spot
 mutex->down() //get access to buffer
                                        <remove item from buffer>
 <add item to buffer>
                                        mutex->up() //release buffer
 mutex->up() //release buffer
                                        empty->up() //another empty slot
 full->up() //another item in buffer
                                        <use item>
```

Semaphore Example: Producers/Consumers (Recall)

```
Semaphore mutex = 1 //access to buffer
Semaphore empty = N //count of empty slots
Semaphore full = 0 //count of full slots
int buffer[N]
BoundedBuffer::Consumer(){
 full->down() //get item
 mutex->down() //get access to buffer
 <remove item from buffer>
 mutex->up() //release buffer
 empty->up() //another empty slot
 <use item>
```

Monitor Example: Producers/Consumers

```
class BBMonitor{
 public: <methods>
 private: item buffer[N];
   Lock lock;
   Condition fullCV, emptyCV;
                                                 BoundedBuffer::Consumer(){
   int empty=N;
                                                  lock->Acquire()
   int full=0;
                                                  while(full == 0)
                                                    fullCV->Wait(lock)
                                                                         //get item
BoundedBuffer::Producer(){
                                                  full--
 lock->Acquire()
                                                  <remove item from buffer>
 while(empty == 0)
   emptyCV->Wait(lock) //get empty spot
                                                  empty++;
                                                  emptyCV->Signal(lock) //another empty slot
 empty--;
                                                  lock->Release()
 <add item to buffer>
 full += 1
 fullCV->Signal(lock) //another item in buffer
 lock->Release()
```

iClicker Question

Every monitor function should begin with what command?

- A. Wait()
- B. Signal()
- C. Lock->Acquire()
- D. Lock->Release()
- E. Broadcast()

Monitor Summary

- A monitor wraps operations with a lock
- Condition variables release lock temporarily
- Monitors can be implemented by following the monitor rules for acquiring and releasing locks

Comparing Monitors and Semaphores

- Condition variables do not have any history
 - on signal() if no one is waiting, the signal is a no-op
 - if thread then calls condition->wait(), it waits.
- Semaphores do have history
 - on up() if no one is waiting, the value of the semaphore is incremented
 - if a thread then calls semaphore->down(), the
 value is decremented and the thread continues

So... signal() and down()

- In semaphores, down() and up() are commutative
 - result is the same regardless of the order of execution
- Condition variables are not commutative
 - so they must be in a critical section to access state variables and do their job

You can implement Monitors with Semaphores.

Monitors and Semaphores: Recap

Both

- Provide mutual exclusion and synchronization
- Have signal() and wait()
- Support a queue of processes that are waiting to access a critical section (e.g., to buy milk)
- No busy waiting!

Semaphores

- Semaphores are basically generalized locks
- Binary and counting semaphores
- Used for mutual exclusion and synchronization

Monitors

- Consist of a lock and one or more condition variables
- Encapsulate shared data
- Use locks for mutual exclusion
- Use condition variables for synchronization
- Wrap operations on shared data with a lock
- Condition variables release lock temporarily

A Different Type of Problem

- We've looked at problems where we protect shared data by only allowing one thread in the critical section at a time
- Is this always appropriate? When might we want to let more threads access shared data at once?

Readers/Writers Problem

- Data is shared among several threads
 - Some only read
 - Some only write
- To get correct results, we allow multiple
 readers at a time, but only one writer at a time
- How can we control access to the object to permit this protocol?

Correctness Criteria

- Each read or write of the shared data must happen within a critical section
- Guarantee mutual exclusion for writers
- Allow multiple readers to execute in the critical section at once
- Allow one writer (and no readers) to execute in the critical section at once

Readers and Writers: Monitor Solution

- What methods do we need?
- How many locks?
- How many condition variables?
- What should we name them?
- Any other variables?
- Assume we're going to say <read> and
 <write> for accesses to the shared data.

Readers and Writers: Monitor Solution

Variables: write(){

read(){

Is our solution fair?

}

A. Yes

B. No, favors readers

C. No, favors writers

Understanding Our Solution

It works, but it favors readers over writers

- Any reader blocks all writers
- All readers must finish before a writer can start
- Last reader will wake any writer, but a writer wakes all readers and writers
- If a writer exits and a reader goes next, then all readers that are waiting will get through

Readers and Writers: Monitor Solution

Variables: write(){

read(){

}

Alternative Semantics

- It may be that you would like a writer to enter its critical section as soon as possible.
- How could we implement that?

Signal vs. Broadcast

- It is always safe to use broadcast() instead of signal()
 - only performance is affected
- signal() is preferable when
 - at most one waiting thread can make progress
 - any thread waiting on the condition variable can make progress
- broadcast() is preferable when
 - multiple waiting threads may be able to make progress
 - the same condition variable is used for multiple predicates
 - some waiting threads can make progress, others can't

Summary

- A monitor wraps operations with a lock
- Condition variables release lock temporarily
- Monitors do not keep state---a call to wait() will always wait
- Monitors can be implemented by following the monitor rules for acquiring and releasing locks

Announcements

- Homework 3 due Friday 9:45a
- Project 1 is posted due 2/27
- Exam 1 is in two weeks!
 - Wednesday, 2/25! 7p! UTC 2.112A!