

Heap Memory Management: Garbage Collection

CS439: Principles of Computer
Systems

March 23, 2015

Last Time

- Finished Virtual Memory
 - Load control
 - Page sizes
- Discussed explicit memory management
 - Allocation policies (bump pointer, free list)
 - De-allocation policies (free)
 - Free-list management

Today's Agenda

- Garbage Collection
 - How to automatically find garbage
 - Heap management
 - Incremental vs. Whole
 - Age-based collection
- Virtual Memory Review

Garbage Collection: Automatic Memory Management

- Reduces programmer burden
 - Less user code compared to explicit memory management
 - Eliminates sources of errors
 - Less user code to get correct
 - Protects against some classes of memory errors
 - No `free()`, thus no premature `free()`, no double `free()`, or forgetting to `free()`
 - Not perfect, memory can still leak
- Integral to modern object-oriented languages
- Now part of mainstream computing

Garbage Collection brought to you by...

- “Safe” pointers!
 - Used in managed languages that provide garbage collection
 - Programs may not access arbitrary addresses in memory
 - The compiler can identify and provide to the garbage collector all the pointers, thus
 - “Once garbage, always garbage”
 - Runtime system can move objects by updating pointers
- “Unsafe” languages can do non-moving GC by assuming anything that looks like a pointer is one.

Challenge

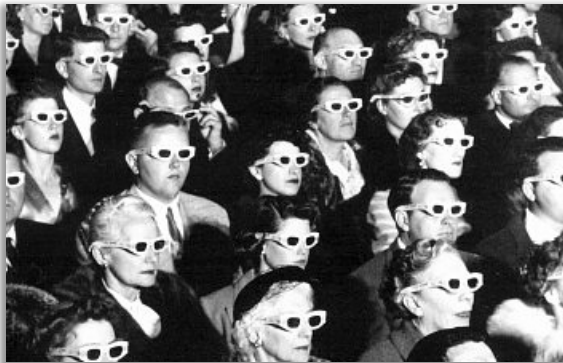
Performance efficiency!

Identifying garbage is hard and expensive.

- Time proportional to dead objects or live objects
 - Which depends on method used
- Collecting less frequently typically reduces total time but increases space requirements and pause times (Space/Time Tradeoff!)
 - *Pause time* is the time the program is paused from doing its work while the garbage is being collected

Garbage Collection is Not New

Mark-Sweep
McCarthy, 1960



Mark-Compact
Styger, 1967



Semi-Space
Cheney, 1970



Garbage Collection Fundamentals

Algorithmic Components

Allocation

Free List



Bump Pointer Allocation



Identification

Tracing
(*implicit*)

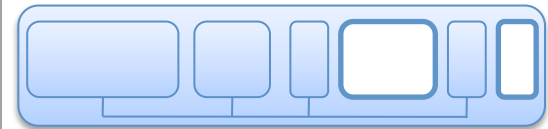


Reference Counting
(*explicit*)



Reclamation

Sweep-to-Free



Compact



Evacuate



Garbage Collection Fundamentals: Text Description

- Algorithmic Components
 - Allocation (Same as explicit memory management)
 - Free List
 - Bump Allocation
 - Identification
 - Tracing – implicit
 - Traces pointers program objects to identify what is reachable in the program
 - Definitions in a few slides
 - Reference Counting – explicit
 - A programmer/ program keeps track of how many objects are using a pointer
 - Reclamation: taking back the heap
 - Sweep-to-Free
 - Compact
 - Evacuate
- Emphasis for this slide is on the Allocation and Identification components, description of Reclamation soon.

What is Garbage?

- In theory, any object the program will never reference again
 - Called *dead* objects
 - Dead objects cannot be identified by the compiler or runtime system
- In practice, any object the program cannot reach is garbage
 - Called *unreachable* objects

Finding Reachable Objects

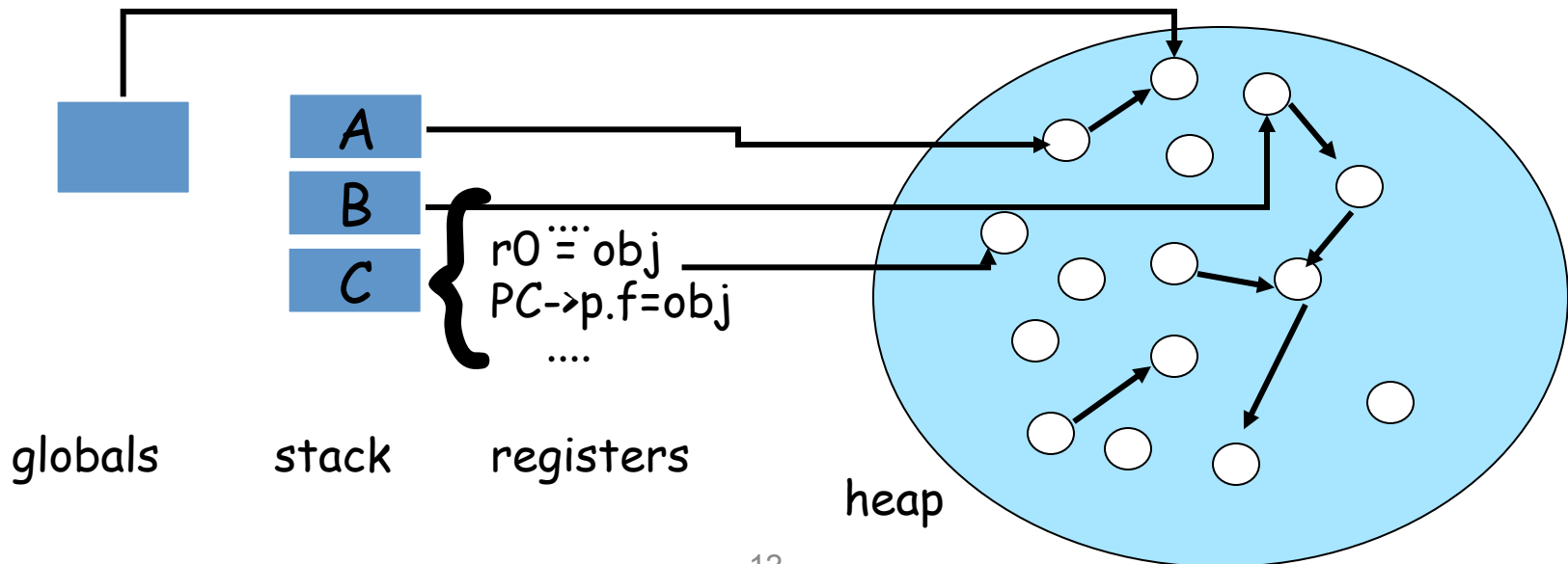
Two methods:

- Reference Counting
 - Count the number of references to each object
 - If the reference count is 0, the object is garbage
 - Does not work for cycles
- Tracing
 - Trace reachability from program *roots*
 - Roots are: registers, stack, static variables
 - Objects not traced are unreachable

Reachability

Tracing:

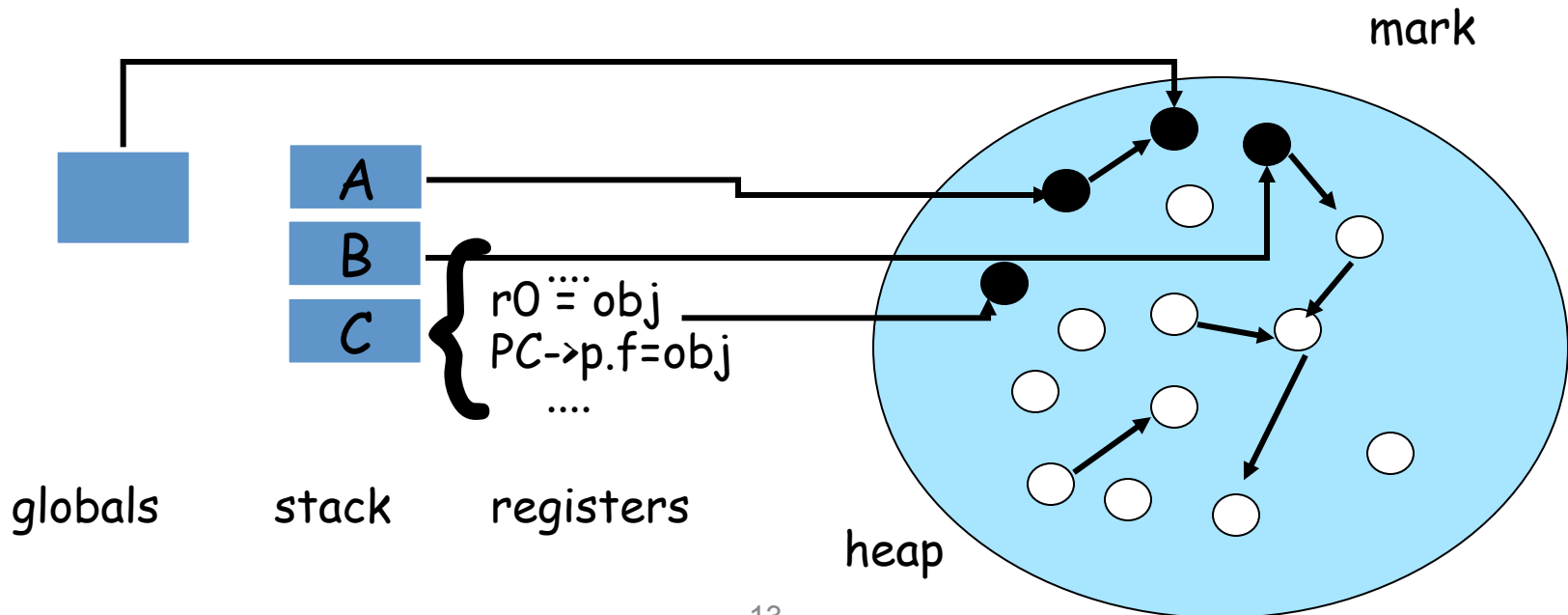
- Marks the objects reachable from the roots live, and then performs a transitive closure over them



Reachability

Tracing:

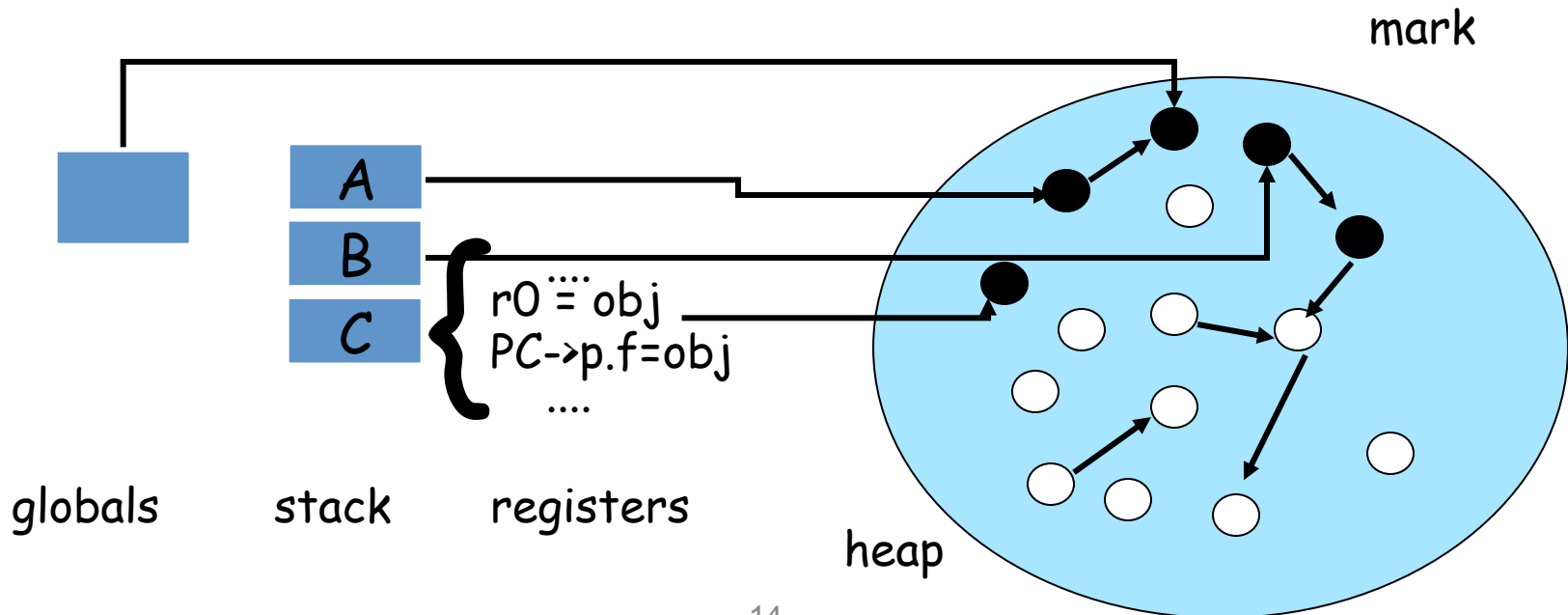
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Reachability

Tracing:

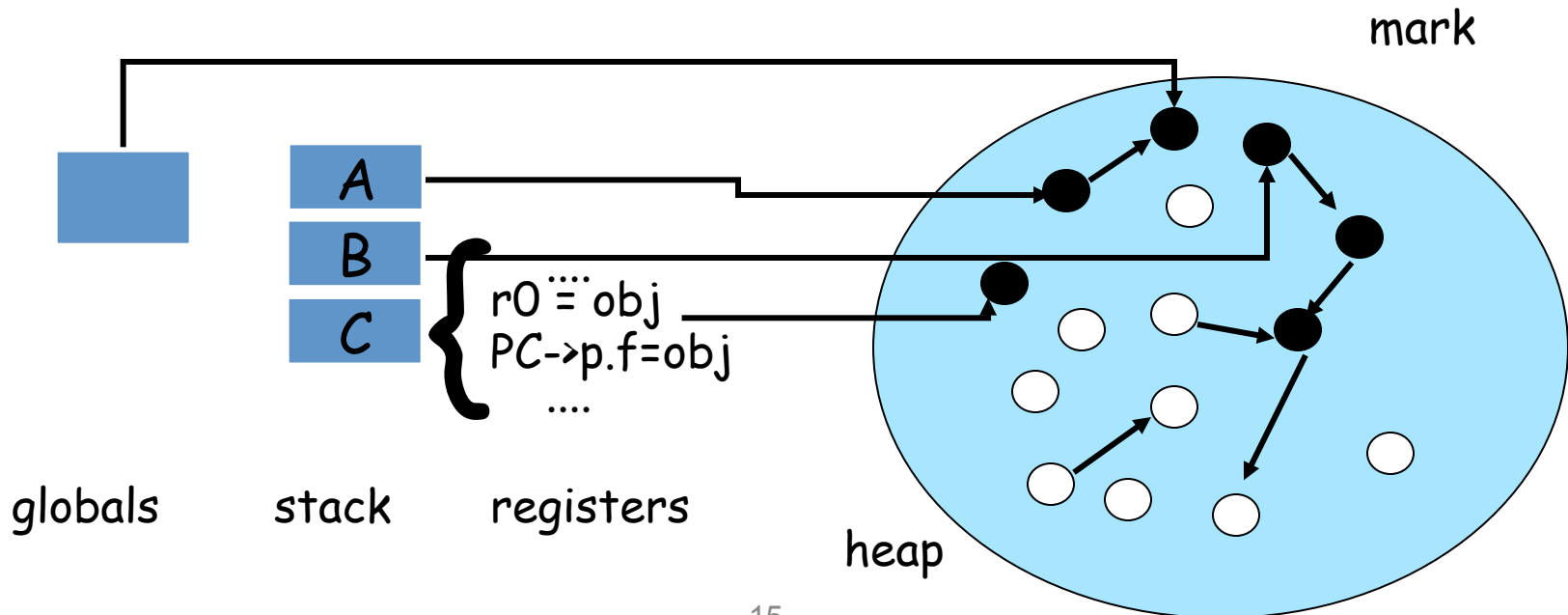
- Marks the objects reachable from the roots live, and then performs a transitive closure over them



Reachability

Tracing:

- Marks the objects reachable from the roots live, and then performs a transitive closure over them

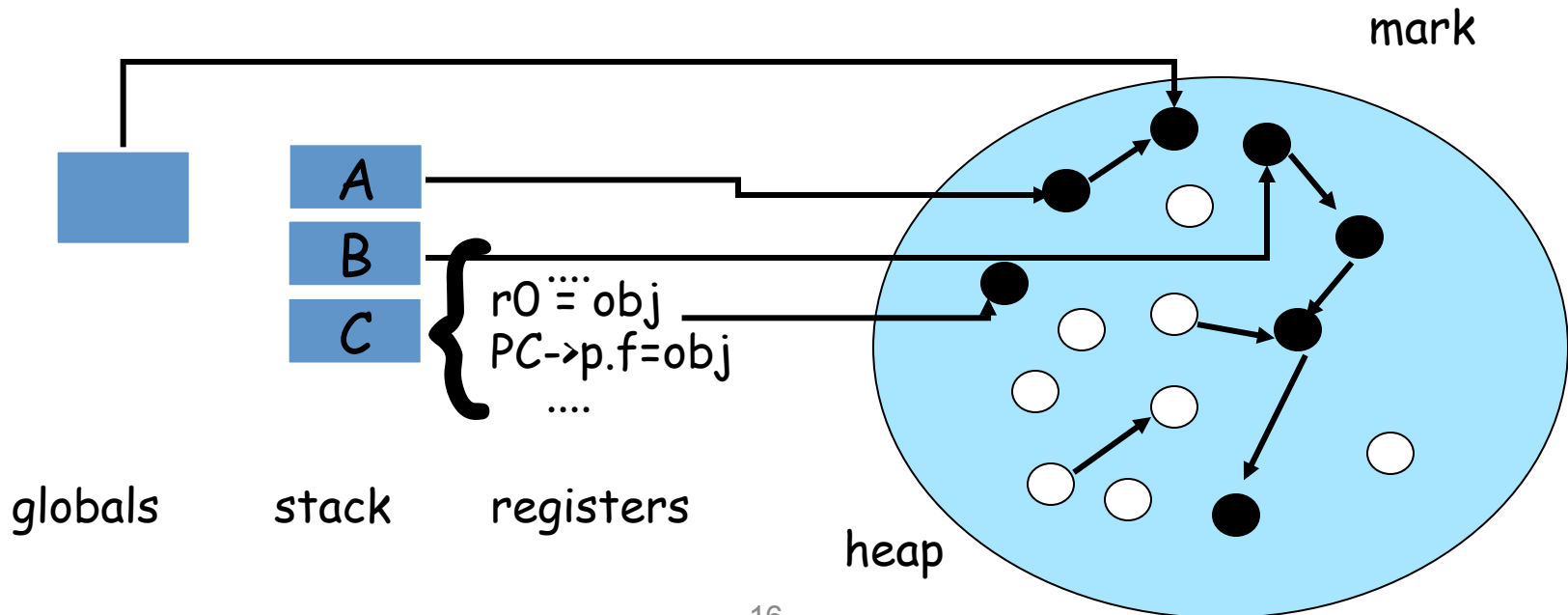


Reachability

Tracing:

- Marks the objects reachable from the roots live, and then performs a transitive closure over them

All unmarked objects are dead and can be reclaimed

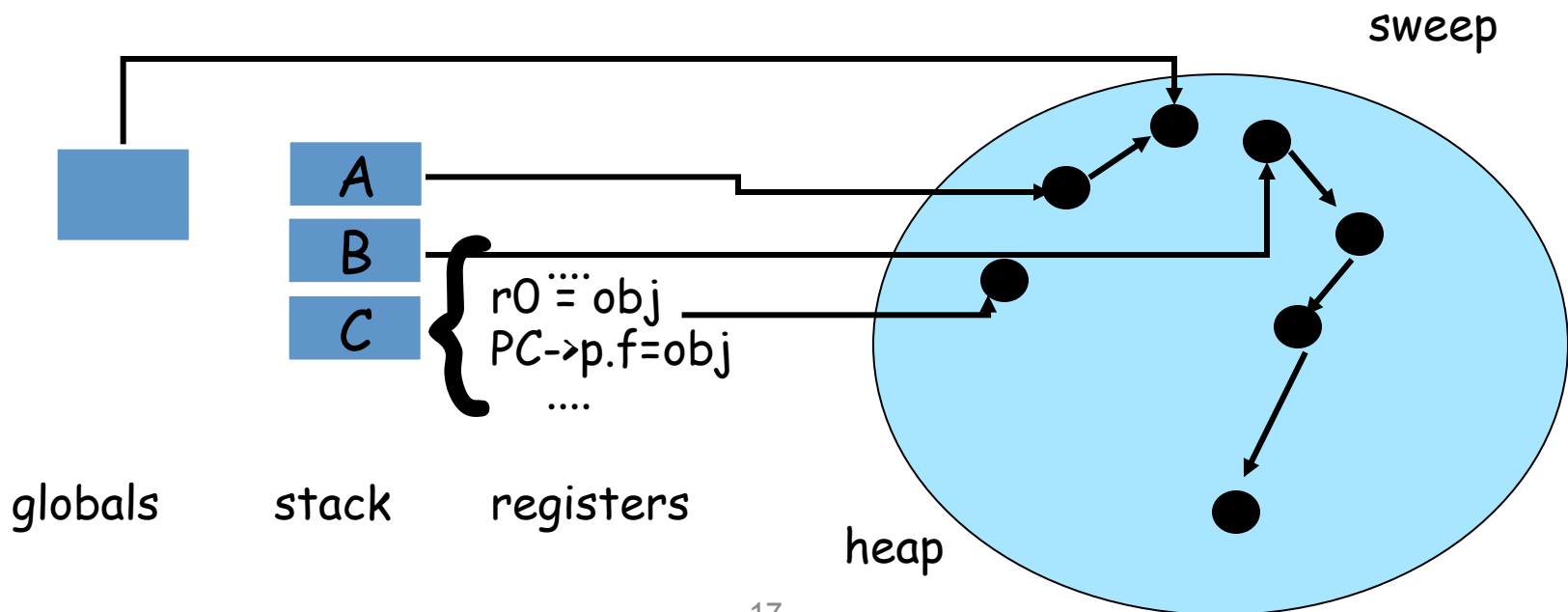


Reachability

Tracing:

- Marks the objects reachable from the roots live, and then performs a transitive closure over them

All unmarked objects are dead and can be reclaimed



Reachability: Text Description

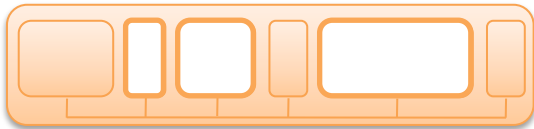
- Tracing
 - Marks the objects reachable from the root as reachable and then performs a transitive closure over them
- Example Setup
 - We are looking at 4 parts of the memory system
 - 1 global variable
 - 3 stack variables
 - Some register values, which are living in one of the stack variables (but we would look at the registers regardless)
 - Heap allocated memory
 - The global variable, stack variables, and registers all point to space allocated on the heap
- Steps:
 - 1. Mark the objects on the heap that are directly pointed to by our variables, which are the roots of our example
 - 2. Keep marking any objects that are reachable from those objects in the heap
 - For example, Stack variable B points to object alpha which points to object beta, which points to objects delta and omega. So alpha, beta, delta and omega are all reachable from B.
 - Must follow all trails until they end
 - 3. “Sweep” all dead objects
 - All unmarked objects are dead and can be reclaimed
 - Now that heap memory can be recycled
 - 4. Wait for garbage collection algorithm to be run again.

Garbage Collection Fundamentals

Algorithmic Components

Allocation

Free List



Bump Pointer Allocation

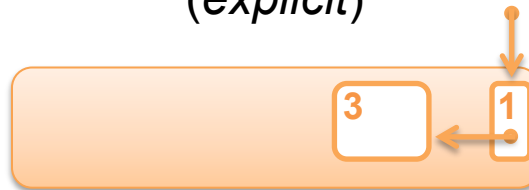


Identification

Tracing
(*implicit*)

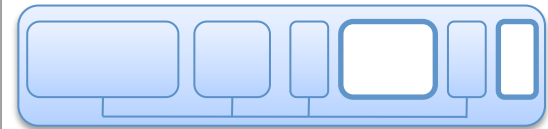


Reference Counting
(*explicit*)

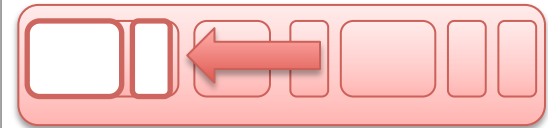


Reclamation

Sweep-to-Free



Compact



Evacuate



Garbage Collection Fundamentals: Text Description

- This slide is a repeat of the one described in slide 9, but the emphasis has changed as we step through the algorithmic components of garbage collection.
- Algorithmic Components
 - Allocation
 - Free List
 - Bump Allocation
 - Identification
 - Tracing
 - Reference Counting
 - Reclamation - taking back the heap
 - Sweep-to-Free
 - Compact
 - Evacuate
- Emphasis for this slide is on the Reclamation component

Evaluating Garbage Collection Algorithms

- Space efficiency
- Efficiency of allocator
 - Time to allocate
 - Locality of contemporaneously allocated objects
 - Why?
- Time to collect garbage
 - Is it fast?
 - Is incremental reclamation an option?

Reclamation

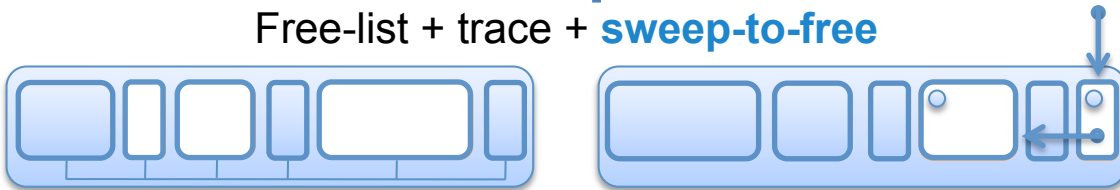
Two broad approaches:

- Non-copying
 - Uses free-list allocation and reclamation
 - Only way for explicit memory management
 - Example: Mark-Sweep
- Copying
 - (Generally) uses bump pointer allocation
 - En masse reclamation (sort of)
 - Example: Mark-Compact, Semi-Space

Garbage Collectors

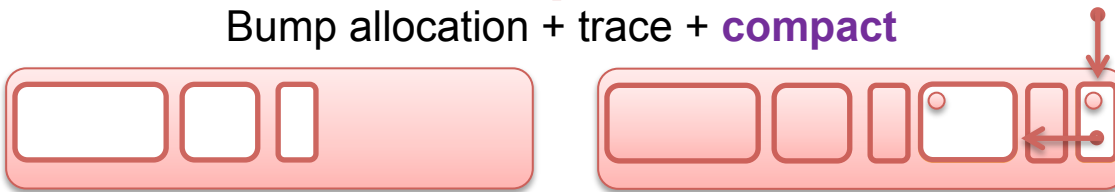
Mark-Sweep [McCarthy 1960]

Free-list + trace + **sweep-to-free**



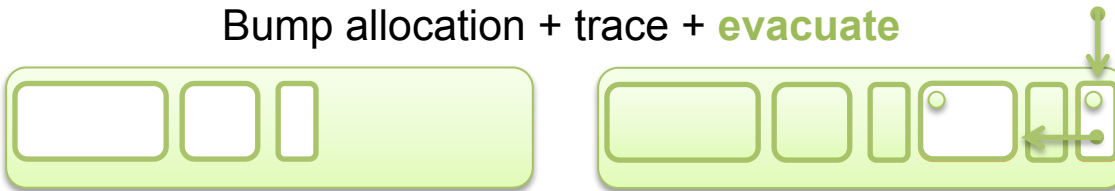
Mark-Compact [Styger 1967]

Bump allocation + trace + **compact**

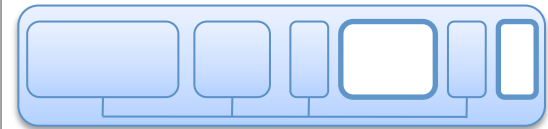


Semi-Space [Cheney 1970]

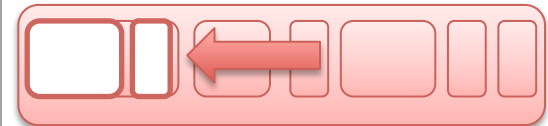
Bump allocation + trace + **evacuate**



Sweep-to-Free



Compact



Evacuate

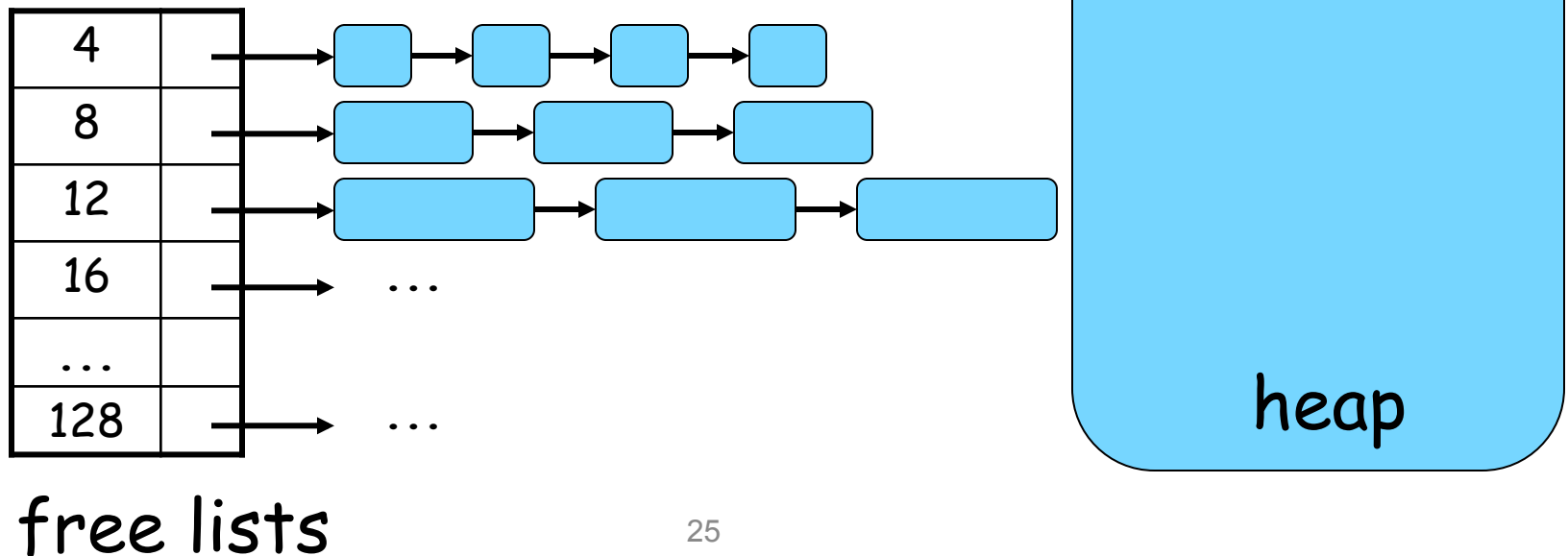


Garbage Collectors: Text Description

- Mark-Sweep - McCarthy 1960
 - free-list + trace + sweep-to-free
- Mark-Compact - Styger 1967
 - Bump allocation + trace + compact
- Semi-Space - Cheney 1970
 - Bump allocation + trace + evacuate
- Focus of this slide is Mark-Sweep, which is described in the upcoming slides

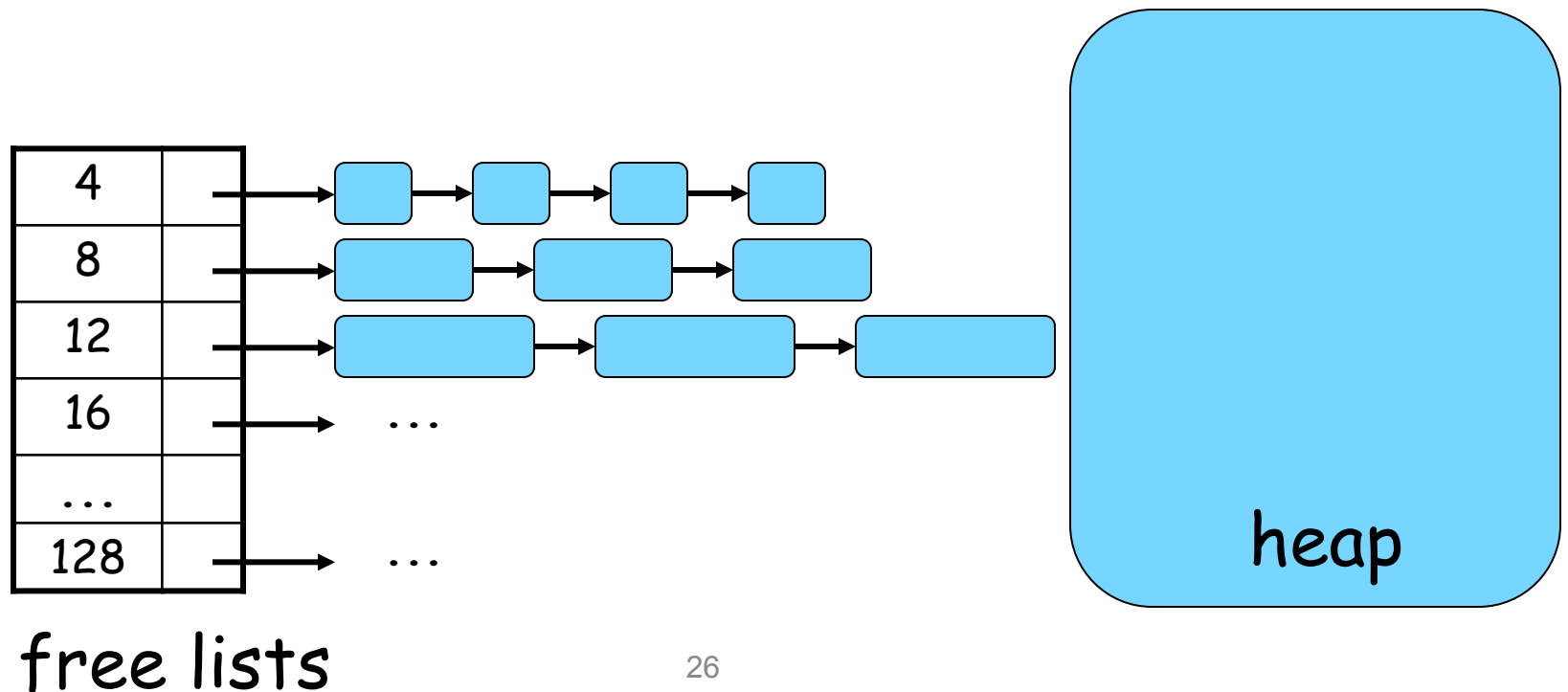
Mark-Sweep

- Free lists organized by size (binning!)
 - blocks of same size, or
 - individual objects of same size
- Most objects are small < 128 bytes



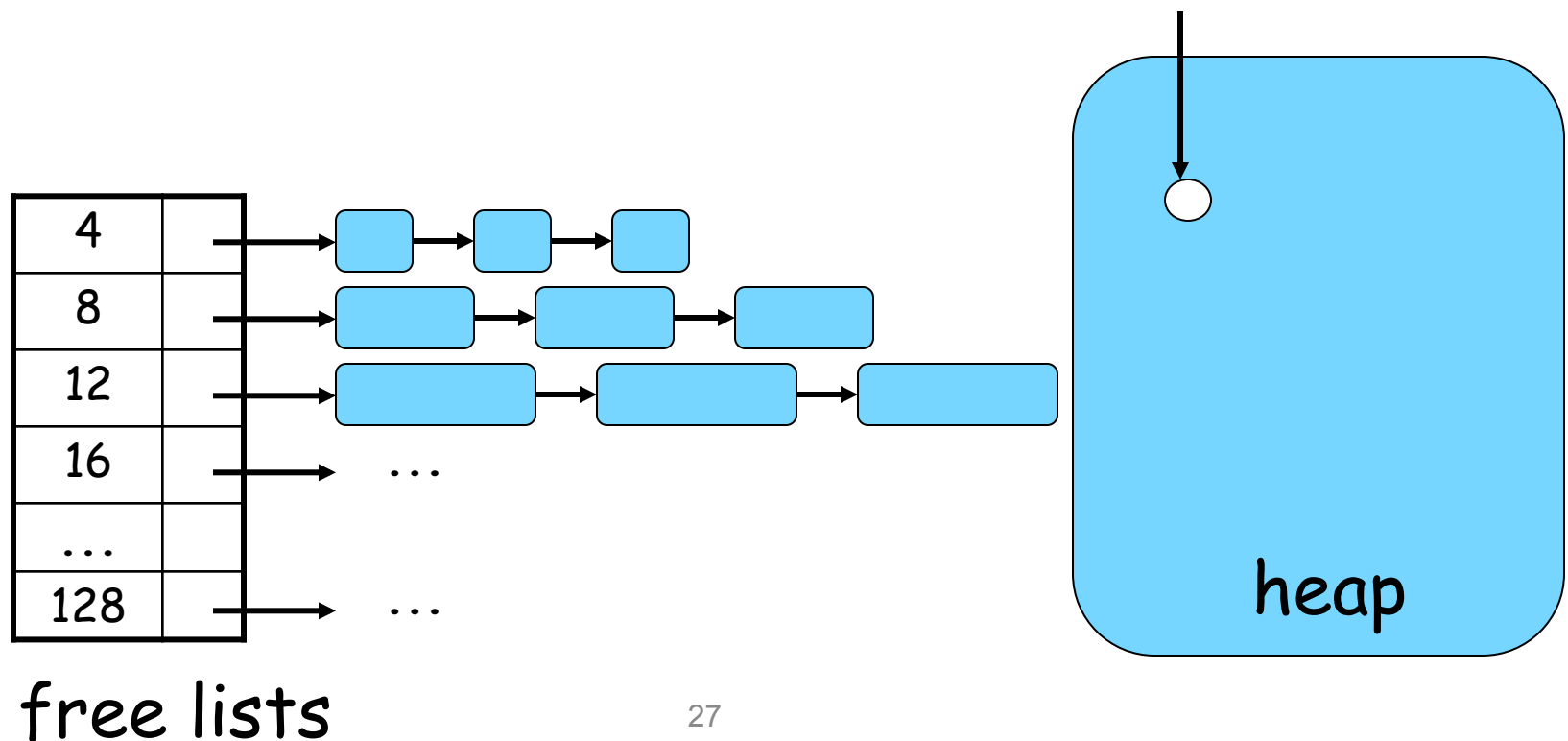
Mark-Sweep

- Allocation
 - Grab a pointer to free space off the free list



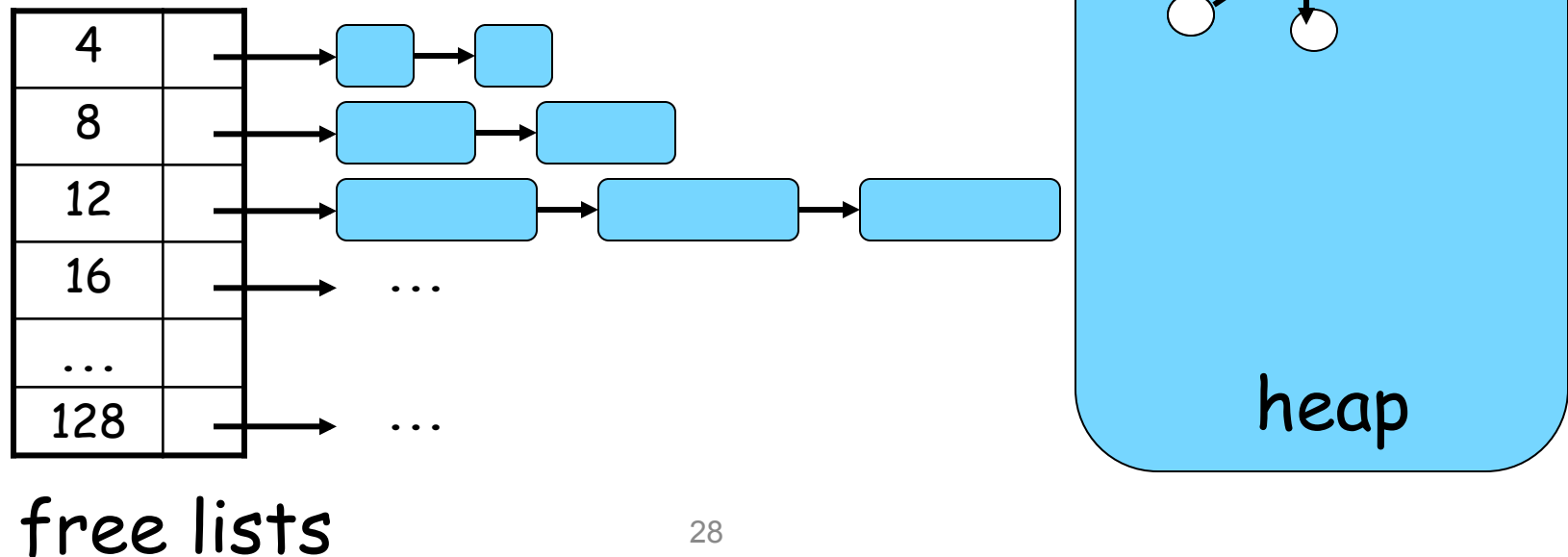
Mark-Sweep

- Allocation
 - Grab a pointer to free space off the free list



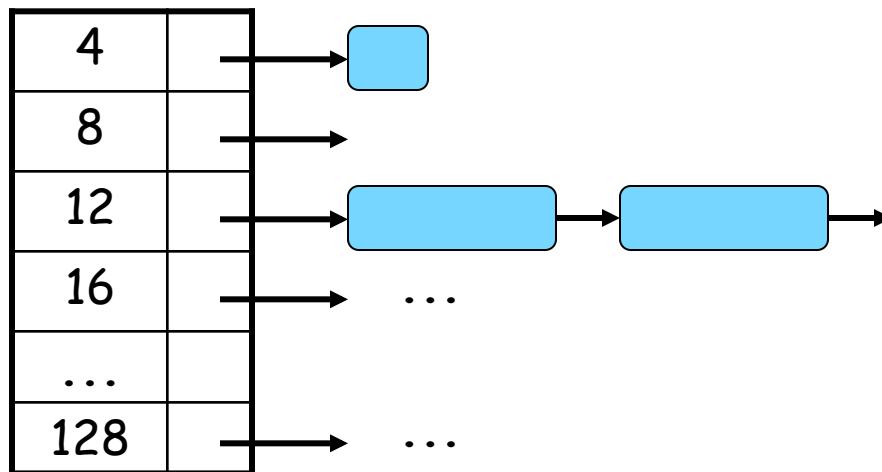
Mark-Sweep

- Allocation
 - Grab a pointer to free space off the free list

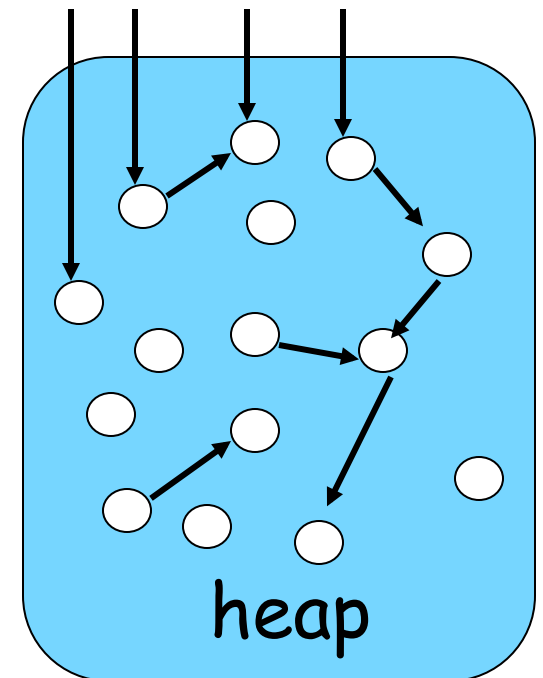


Mark-Sweep

- Allocation
 - Grab a pointer to free space off the free list
 - No more memory of the right size triggers a collection
 - Mark phase - find the reachable objects
 - Sweep phase - put unreachable ones on the free list

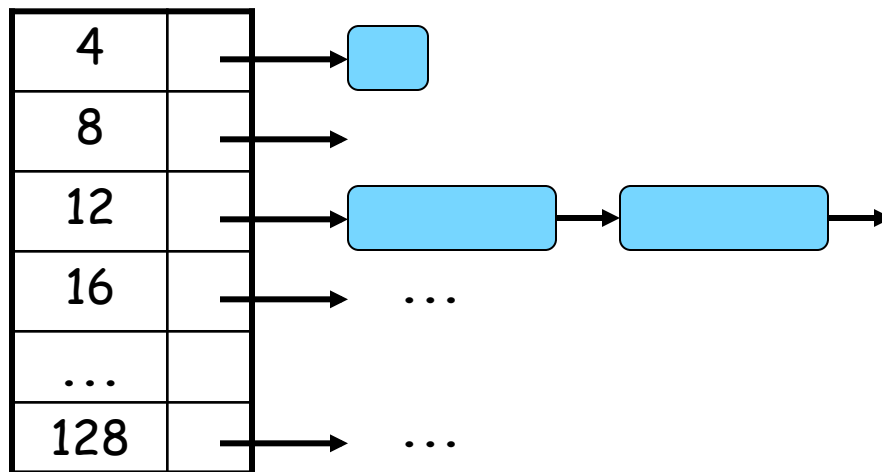


free lists

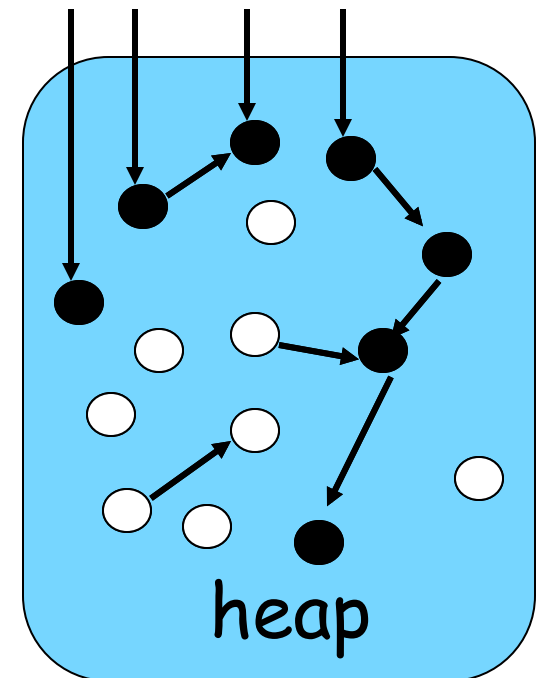


Mark-Sweep

- Mark phase
 - Transitive closure marking all the reachable objects
- Sweep phase
 - sweep the memory for unreachable objects populating free list

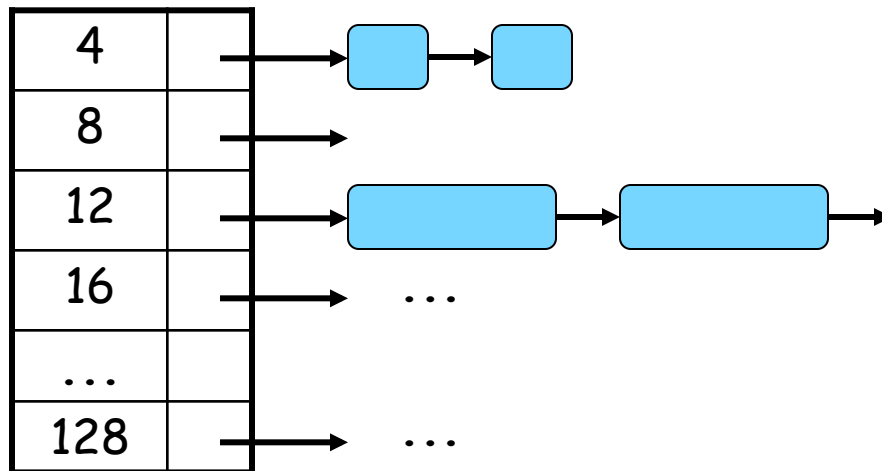


free lists

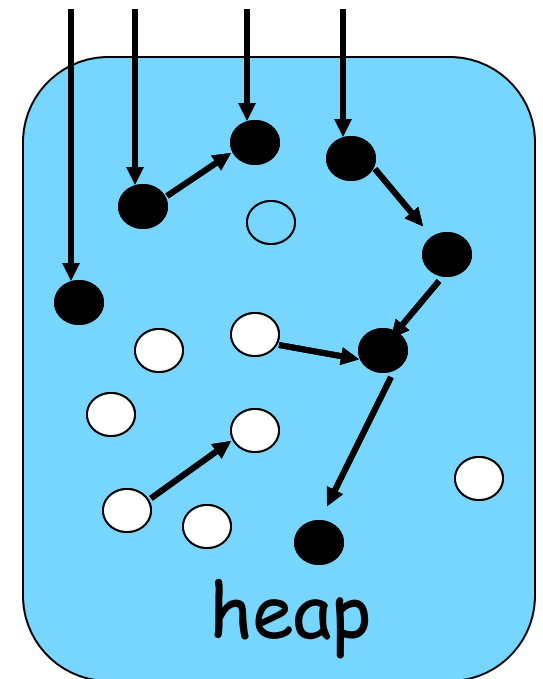


Mark-Sweep

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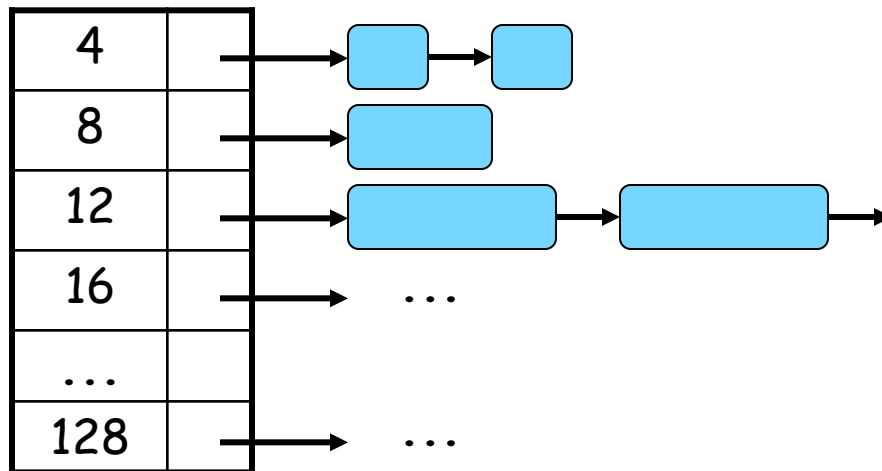


free lists

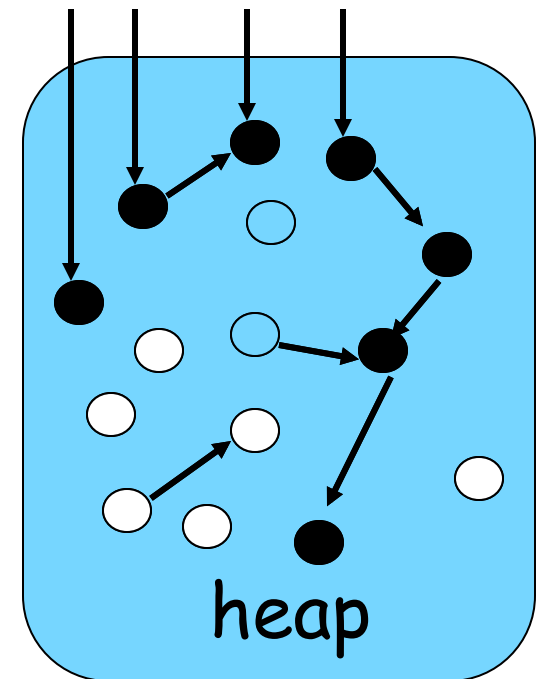


Mark-Sweep

- Mark phase
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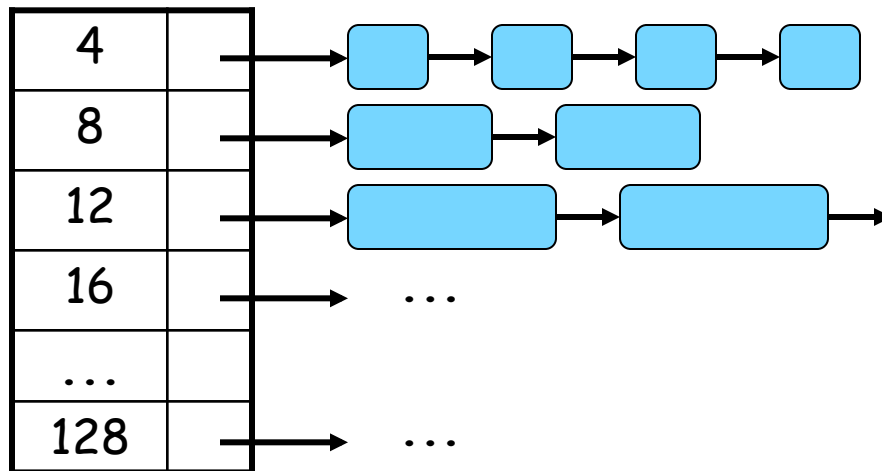


free lists

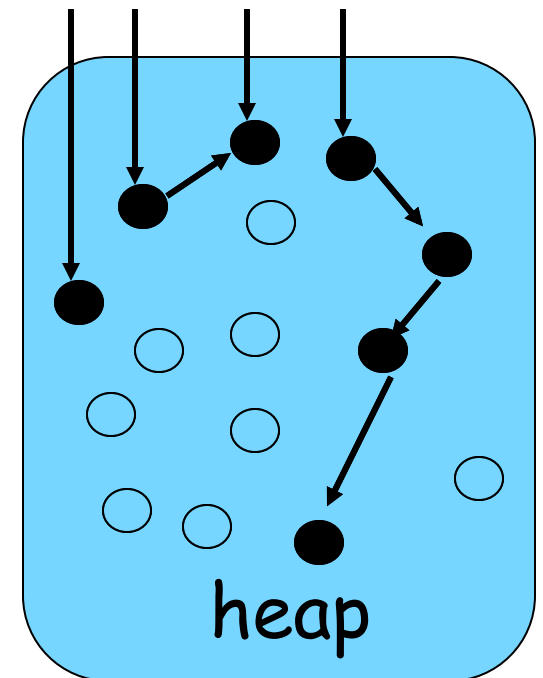


Mark-Sweep

- Mark phase
 - Transitive closure marking all the unreachable objects
- Sweep phase
 - sweep the memory for unreachable objects populating free list
 - can be made incremental by organizing the heap in blocks and sweeping one block at a time on demand

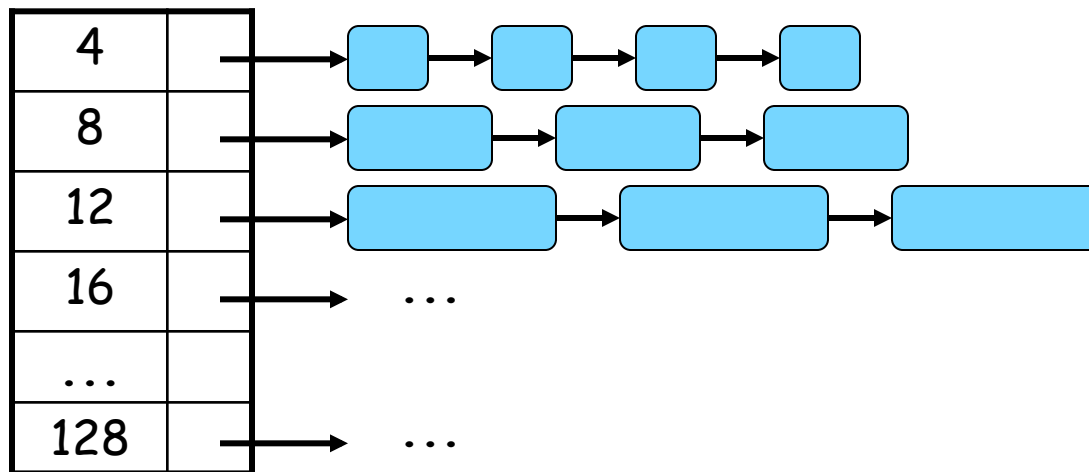


free lists

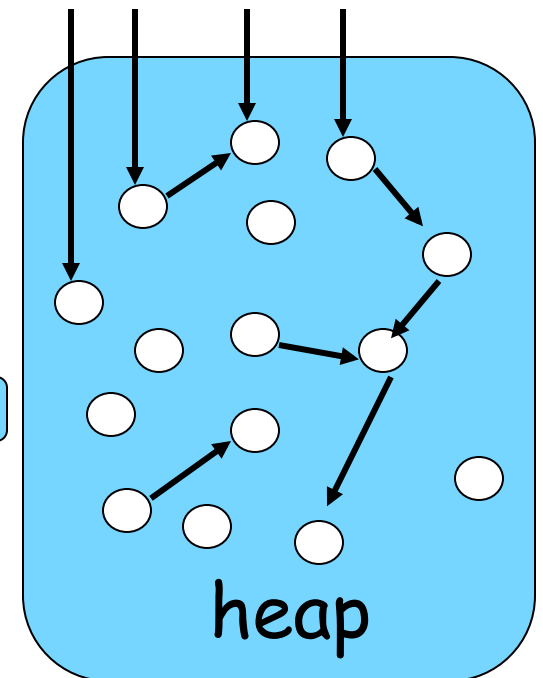


Mark-Sweep

- ✓ space efficiency
- ✓ Incremental object reclamation
- ✗ relatively slower allocation time
- ✗ poor locality of contemporaneously allocated objects



free lists

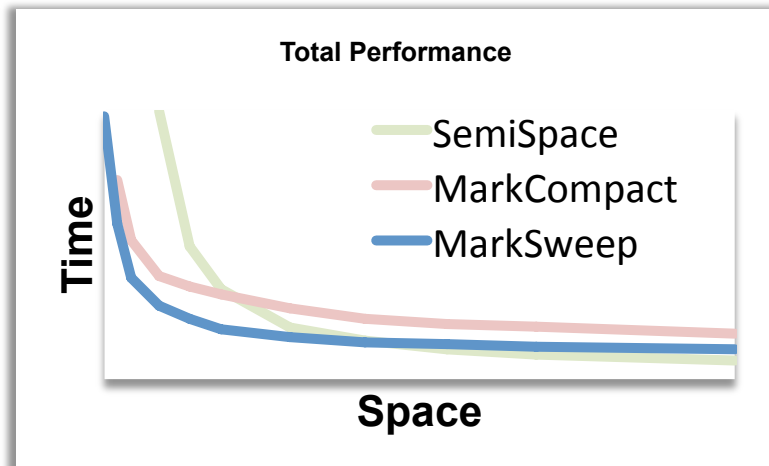
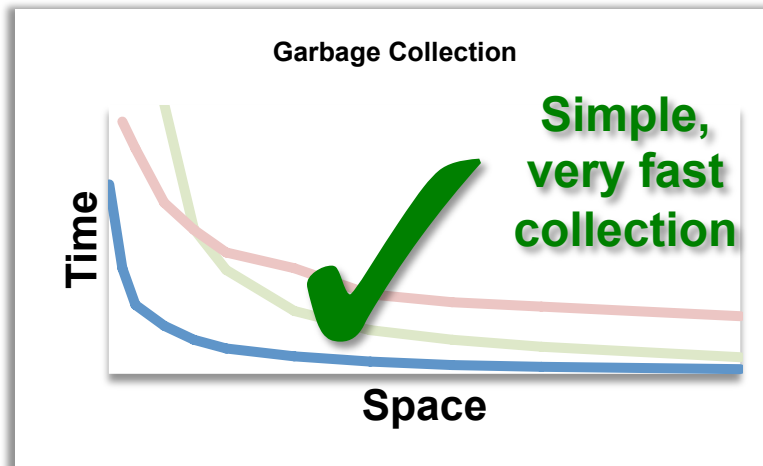
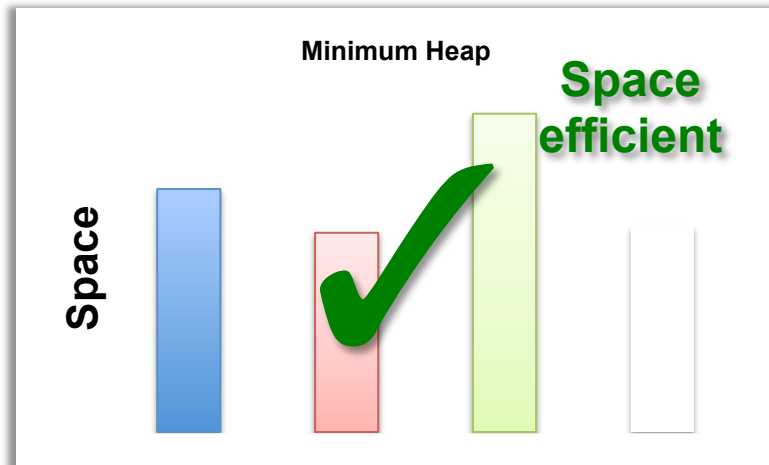
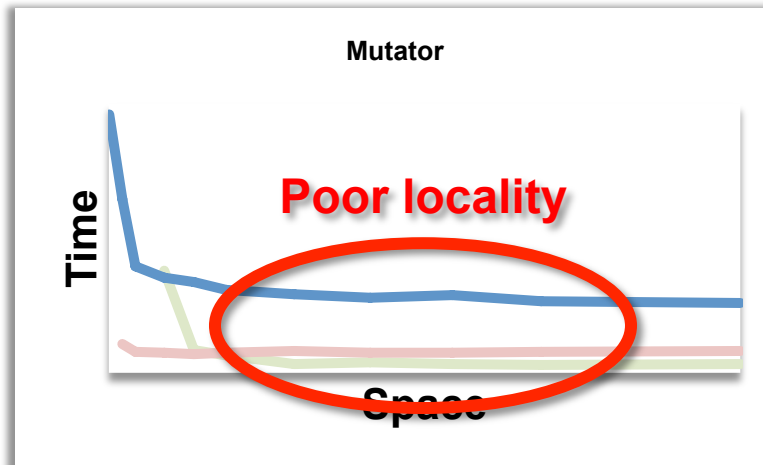


Mark-Sweep: Text Description

- Free lists organized by size (binning!)
 - blocks of same size or
 - individual objects of same size
- Most objects are small < 128 bytes
- Free List Setup:
 - have free lists for sizes 4, 8, 12, 16, ... 128
 - each list has x number of free chunks of memory that it tracks
 - each chunk resides somewhere in the heap
- Allocation
 - grab a pointer to free space off the free list
 - first object is allocated on the heap
 - more objects are allocated on the heap and referenced by this first object
 - no more memory of the right size triggers a collection
- Mark phase: find the reachable objects
 - transitive closure marking all the live objects
- Sweep phase
 - sweep the memory for unreachable objects populating free lists
 - free lists grow again during this phase
 - can be made in incremental by organizing the heap in blocks and sweeping one block at a time on demand
- Result:
 - Good space efficiency
 - Incremental object reclamation possible
 - Relatively slow allocation time
 - Poor locality of contemporaneously allocated objects
 - contemporaneous means allocated close to each other in time

Mark-Sweep Evaluation

Free List Allocation + Trace + Sweep-to-Free



Actual data, taken from geomean of DaCapo, jvm98, and jbb2000 on 2.4GHz Core 2 Duo

Mark-Sweep Evaluation:

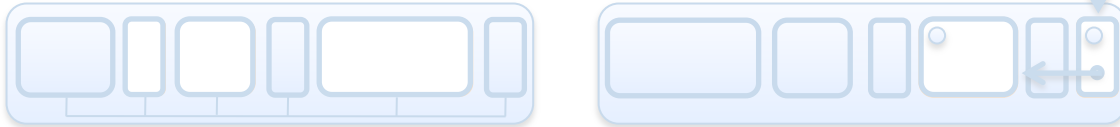
Text Description

- Allocator has a slow allocation time as opposed to other methods
- Algorithm is space efficient
- Allocation and recycled space method results in poor locality
- Garbage collection method is simple and very fast
- Total performance is decent

Garbage Collectors

Mark-Sweep [McCarthy 1960]

Free-list + trace + **sweep-to-free**



Mark-Compact [Styger 1967]

Bump allocation + trace + **compact**



Semi-Space [Cheney 1970]

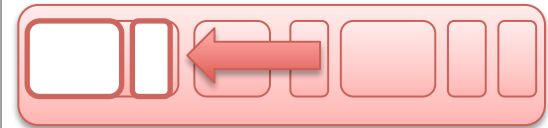
Bump allocation + trace + **evacuate**



Sweep-to-Free



Compact



Evacuate

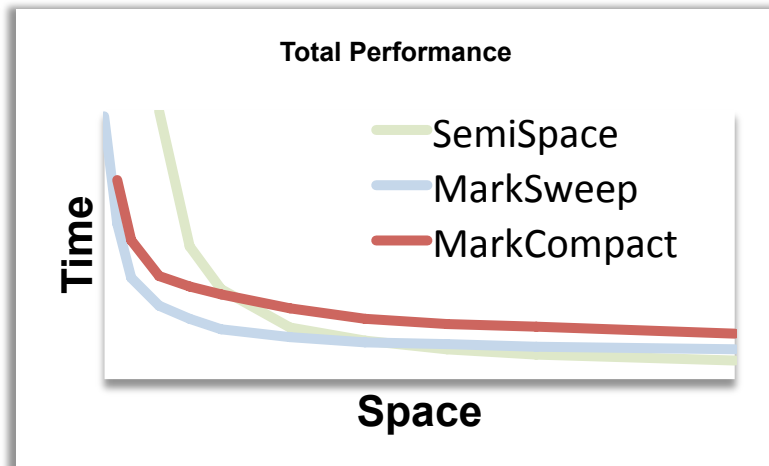
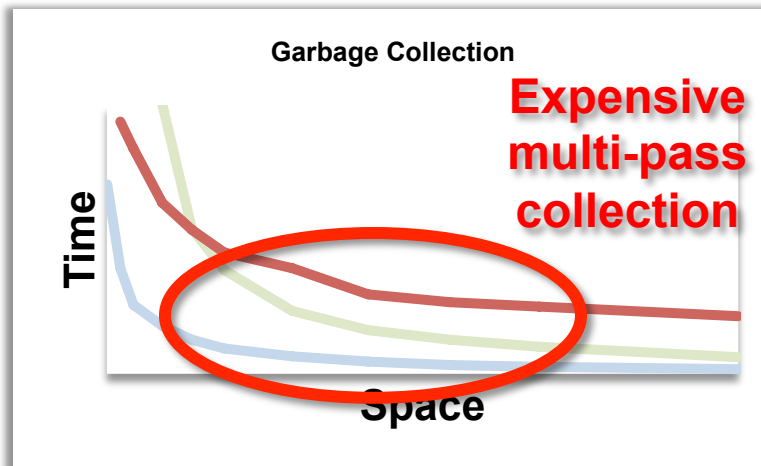
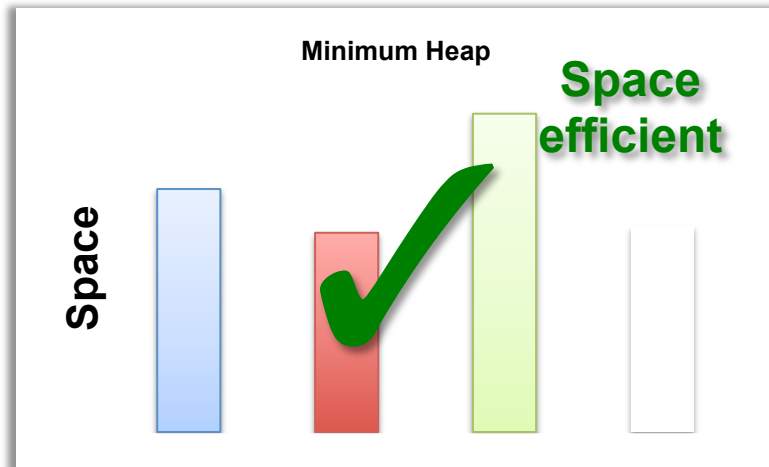
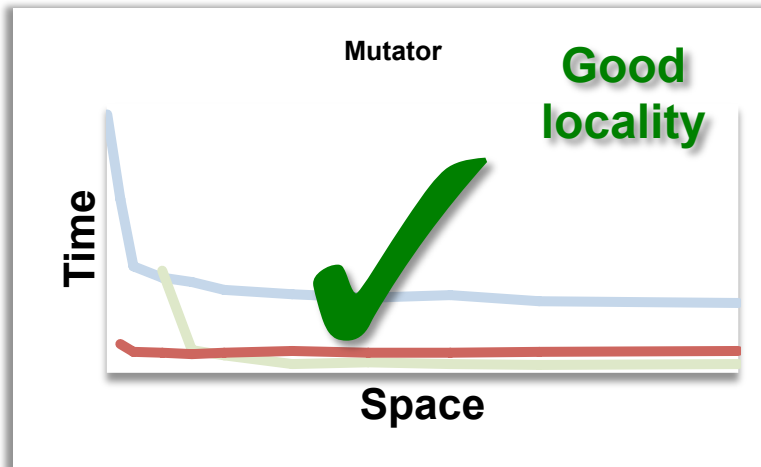


Garbage Collectors: Text Description

- This slide is the same as the one described in 24, but the emphasis is shifted to mark-compact
- Mark-Sweep - McCarthy 1960
 - free-list + trace + sweep-to-free
- Mark-Compact - Styger 1967
 - Bump pointer allocation + trace + compact
- Semi-Space - Cheney 1970
 - Bump pointer allocation + trace + evacuate
- Focus of this slide is Mark-Compact
 - Mark-compact is very similar to mark-sweep
 - One additional reclamation step: copy all objects remaining in the heap to one end of the heap (compact)
 - That additional reclamation step allows mark-compact to use bump pointer allocation (rather than free-list)
 - There are no further slides describing mark-compact

Mark-Compact Evaluation

Bump Allocation + Trace + Compact



Actual data, taken from geomean of DaCapo, jvm98, and jbb2000 on 2.4GHz Core 2 Duo

Mark-Compact Evaluation:

Text Description

- Allocator is fast and exhibits good locality
 - Better than mark-sweep
- Garbage collector has expensive multi-pass collection
 - Slower than mark-sweep
- Algorithm is space efficient
- Total performance is worse than that of mark-sweep

Garbage Collectors

Mark-Sweep [McCarthy 1960]

Free-list + trace + **sweep-to-free**



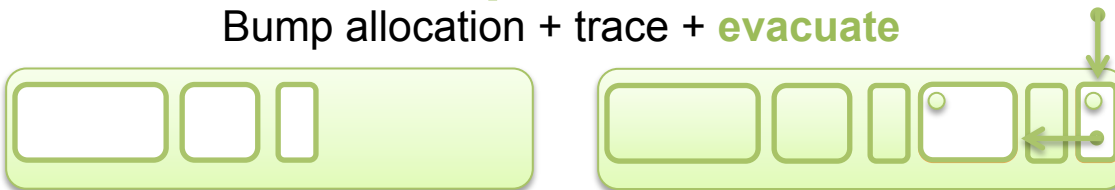
Mark-Compact [Styger 1967]

Bump allocation + trace + **compact**



Semi-Space [Cheney 1970]

Bump allocation + trace + **evacuate**



Sweep-to-Free



Compact



Evacuate



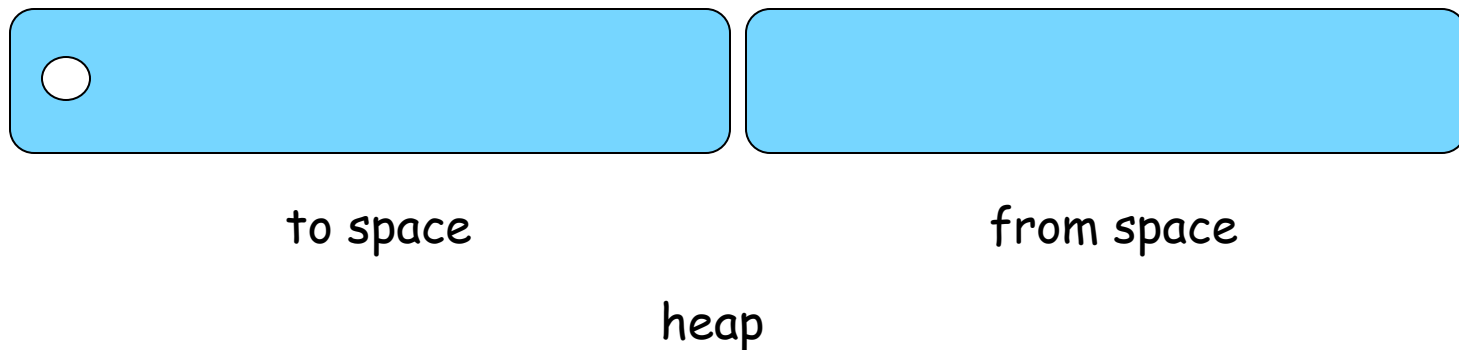
Garbage Collectors:

Text Description

- This slide is the same as the one described in 24 and 39, but the emphasis is shifted to semi-space
- Mark-Sweep - McCarthy 1960
 - free-list + trace + sweep-to-free
- Mark-Compact - Styger 1967
 - Bump allocation + trace + compact
- Semi-Space - Cheney 1970
 - Bump allocation + trace + evacuate
- Focus of this slide is Semi-Space, which is described in the upcoming slides.

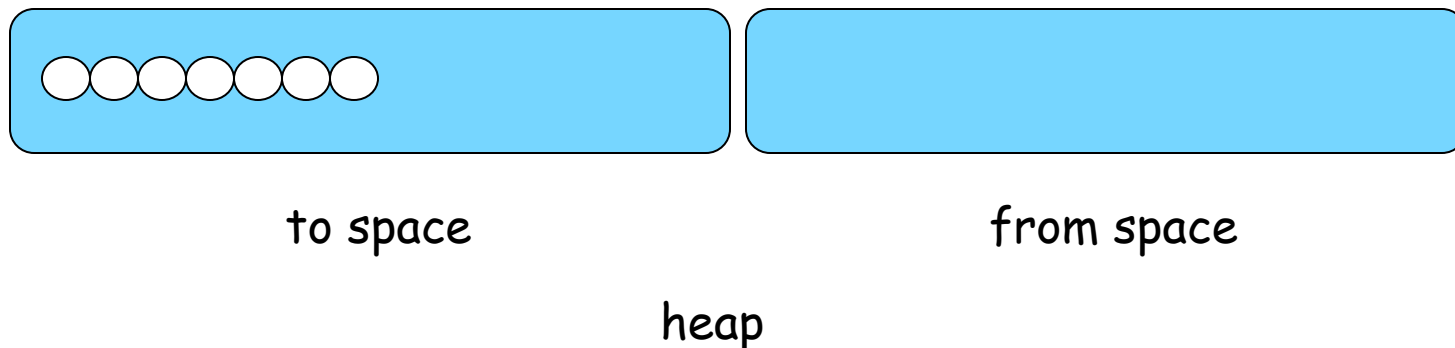
Semi-Space

- Fast **bump pointer** allocation
- Requires copying collection
- Cannot incrementally reclaim memory, must free en masse
- Reserves half of the heap to copy into, in case all objects are reachable



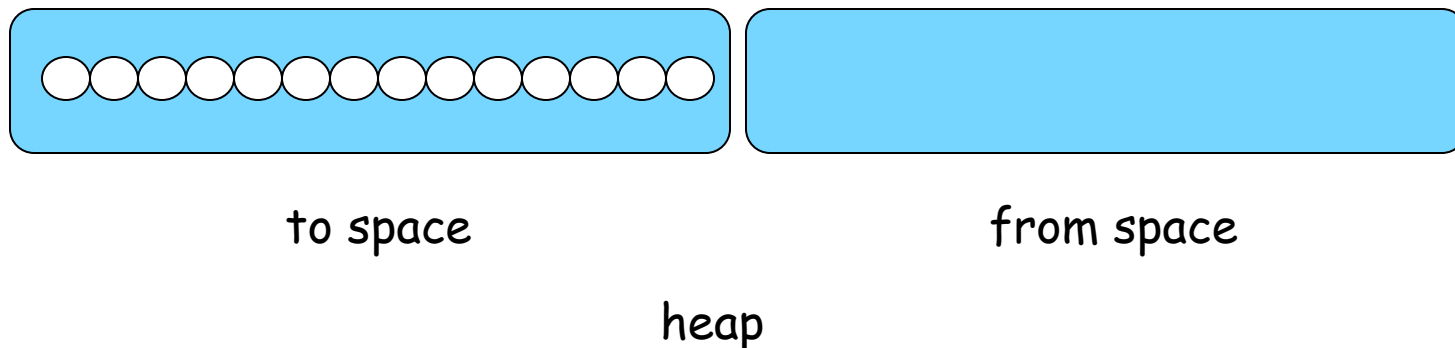
Semi-Space

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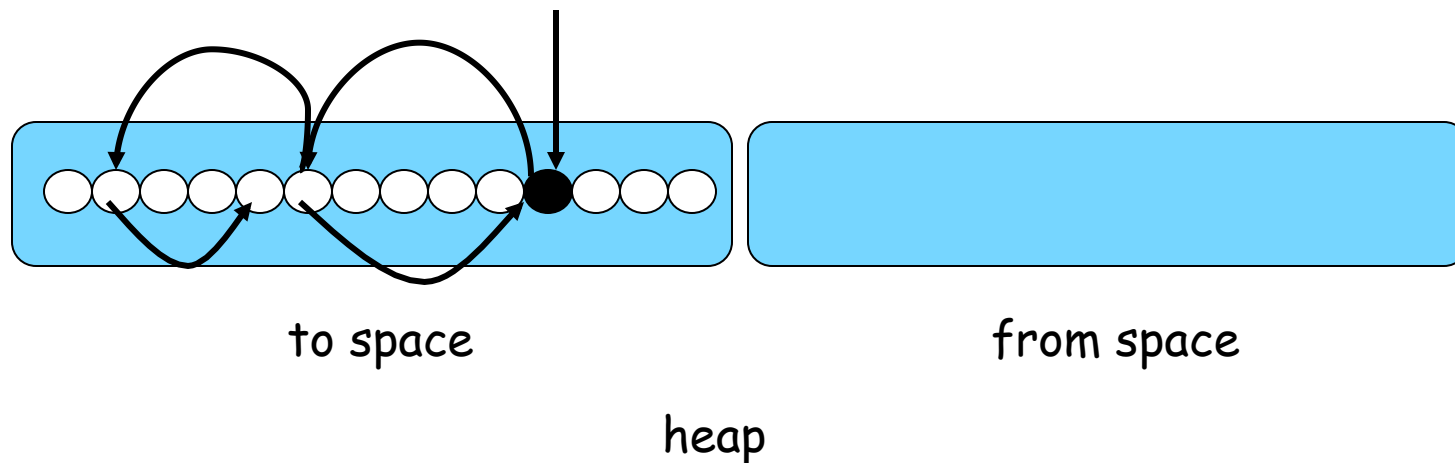
Semi-Space

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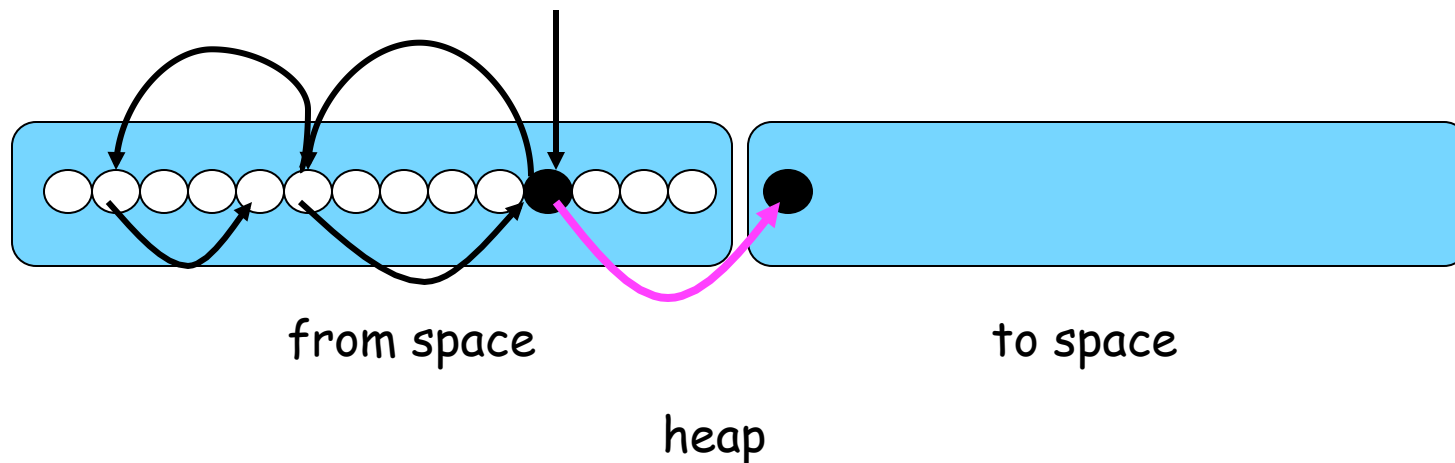
Semi-Space

- Fast **bump pointer** allocation
- Requires copying collection
- Cannot incrementally reclaim memory, must free en masse
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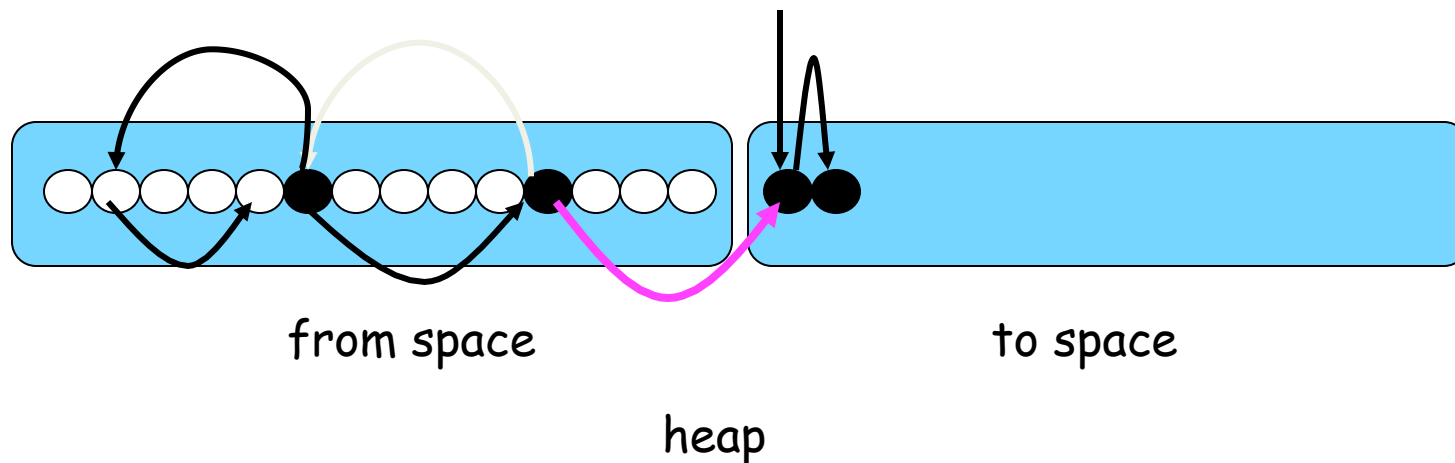
Semi-Space

- Mark phase:
 - copies object when collector first encounters it
 - installs **forwarding pointers**



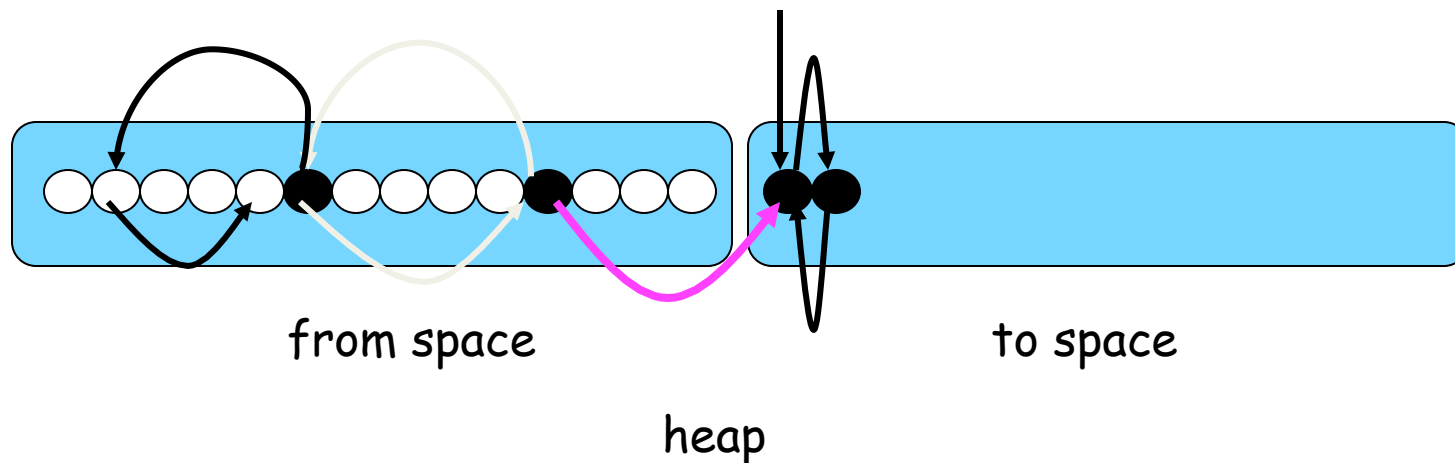
Semi-Space

- Mark phase:
 - copies object when collector first encounters it
 - installs **forwarding pointers**
 - performs transitive closure, updating pointers as it goes



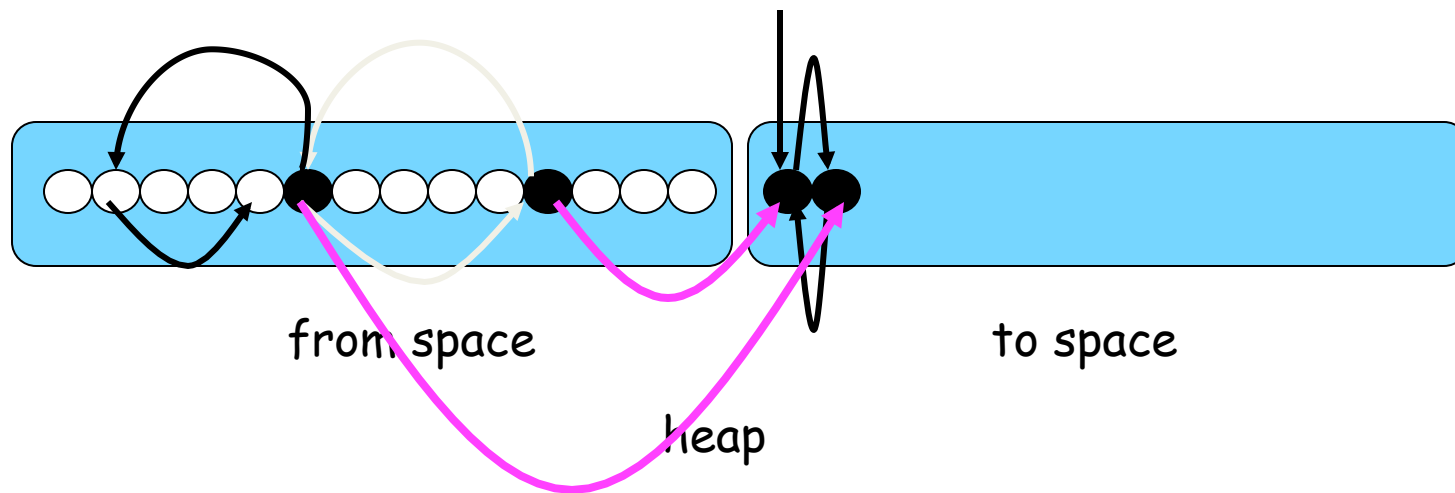
Semi-Space

- Mark phase:
 - copies object when collector first encounters it
 - installs **forwarding pointers**
 - performs transitive closure, updating pointers as it goes



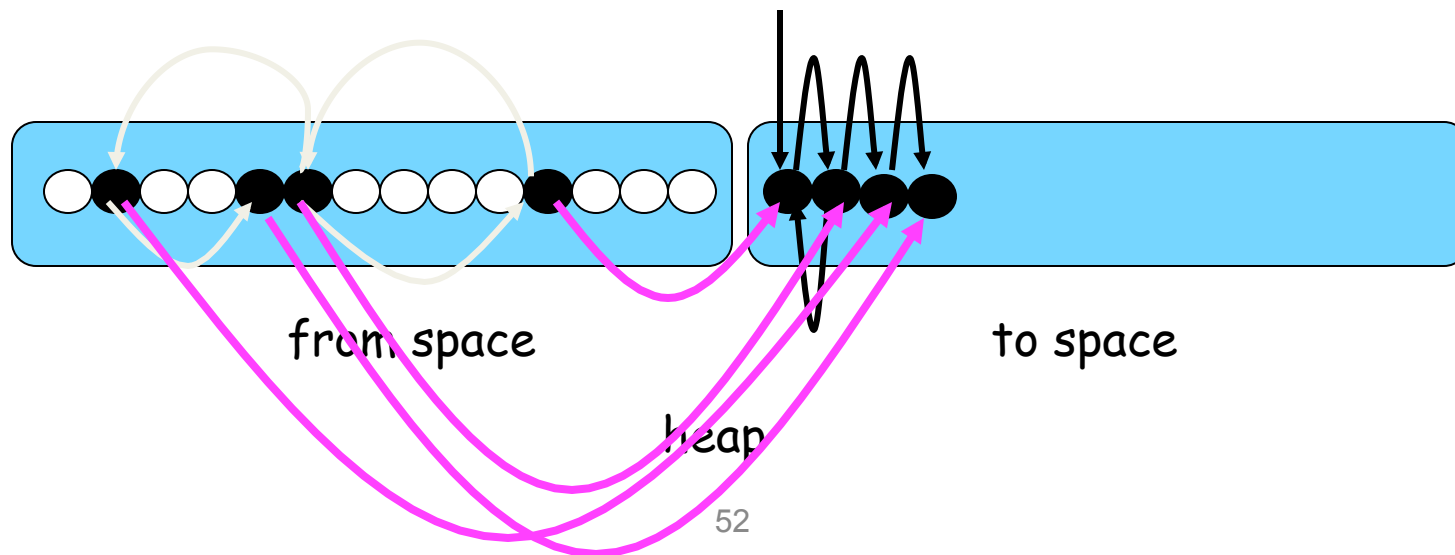
Semi-Space

- Mark phase:
 - copies object when collector first encounters it
 - installs **forwarding pointers**
 - performs transitive closure, updating pointers as it goes



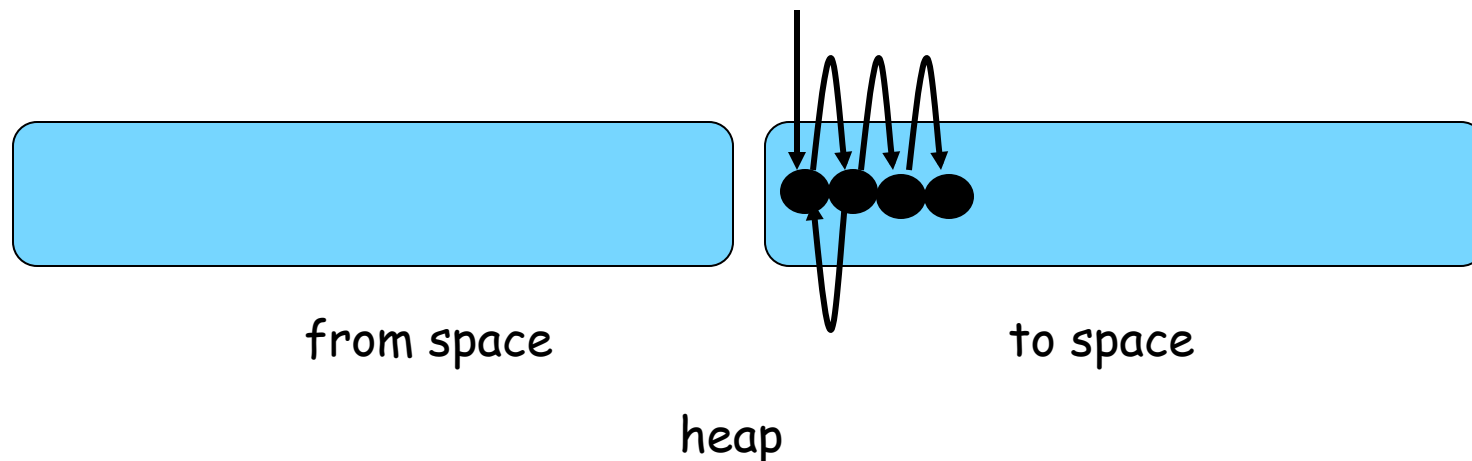
Semi-Space

- Mark phase:
 - copies object when collector first encounters it
 - installs **forwarding pointers**
 - performs transitive closure, updating pointers as it goes
 - reclaims “from space” en masse



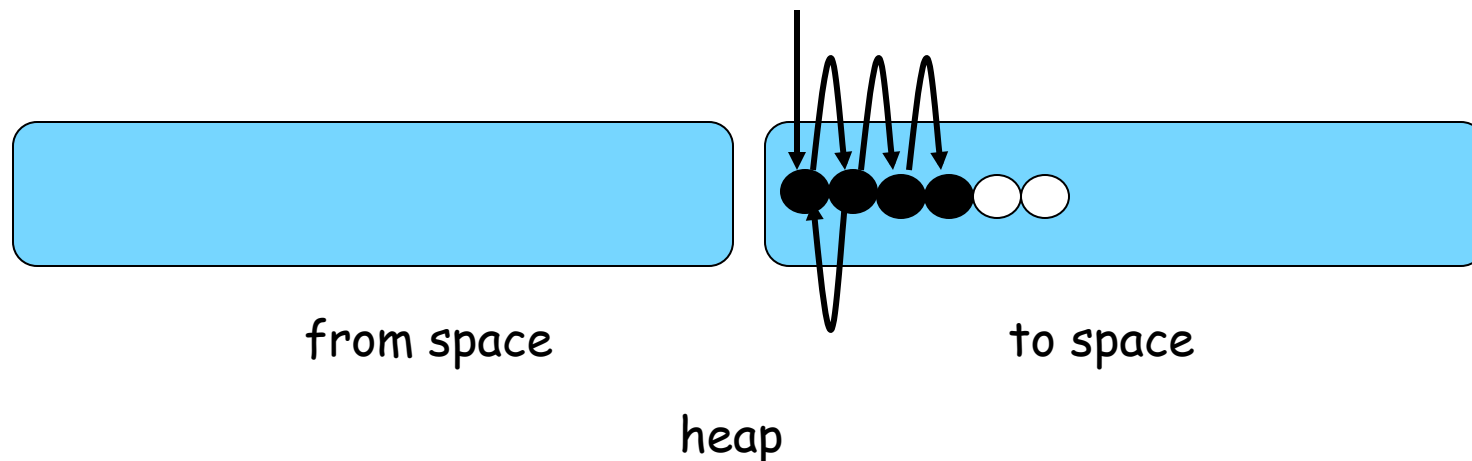
Semi-Space

- Mark phase:
 - copies object when collector first encounters it
 - installs **forwarding pointers**
 - performs transitive closure, updating pointers as it goes
 - reclaims “from space” en masse
 - start allocating again into “to space”



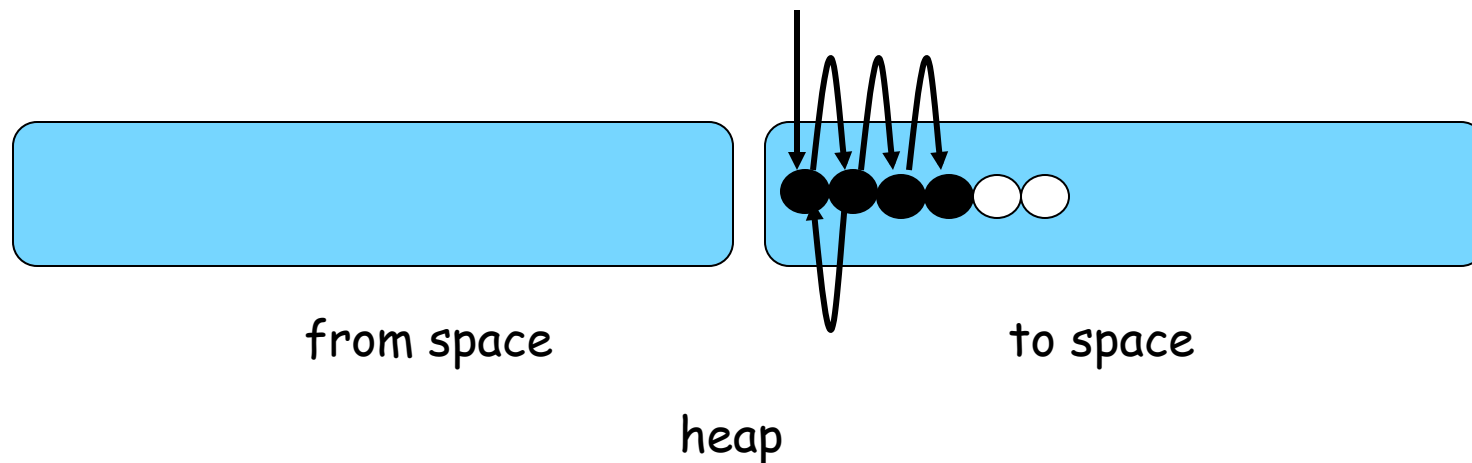
Semi-Space

- Mark phase:
 - copies object when collector first encounters it
 - installs **forwarding pointers**
 - performs transitive closure, updating pointers as it goes
 - reclaims “from space” en masse
 - start allocating again into “to space”



Semi-Space

- Notice:
 - ✓ fast allocation
 - ✓ locality of contemporaneously allocated objects
 - ✓ locality of objects connected by pointers
 - ✗ wasted space



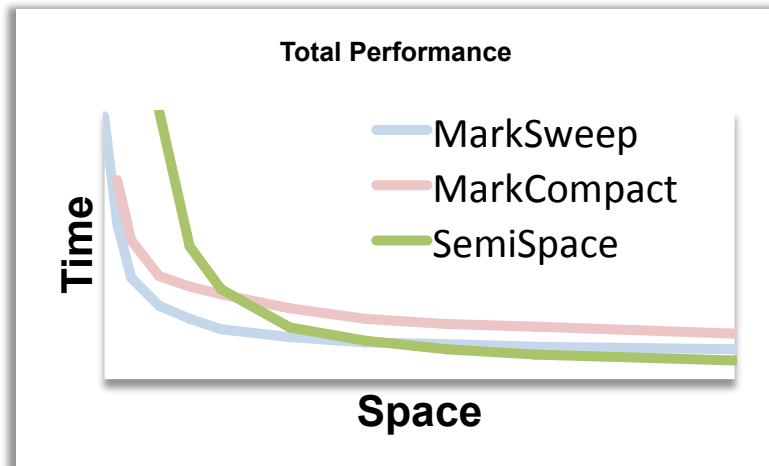
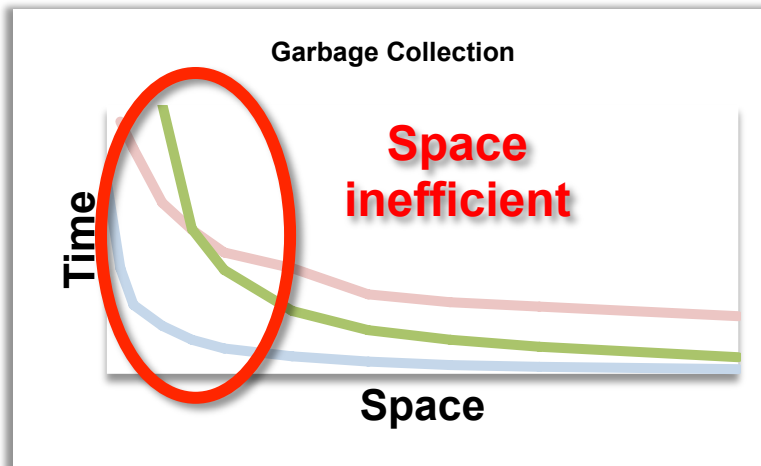
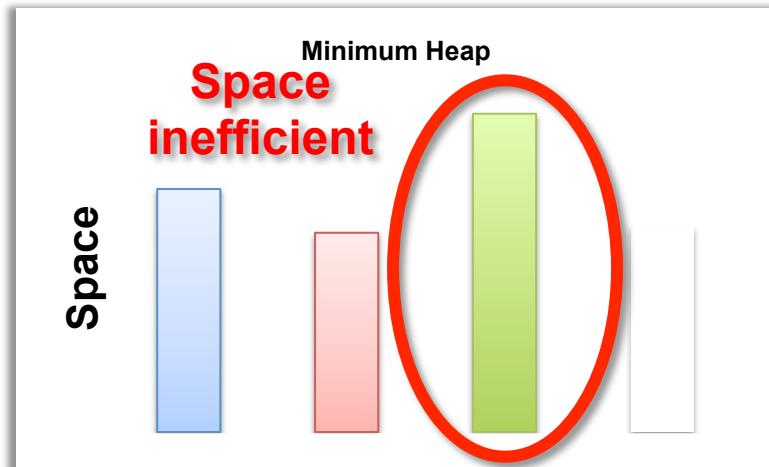
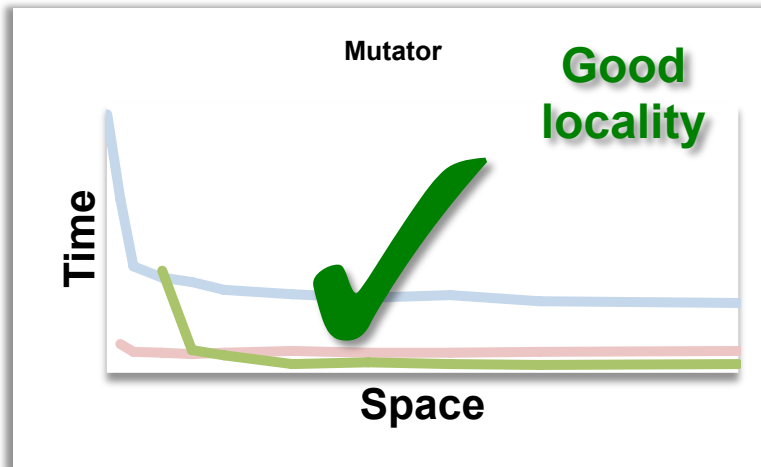
Semi-Space

Text Description

- Fast bump pointer allocation
- Reserves half the heap to copy into, in case all objects are reachable
 - 2 parts of heap: “to space” and “from space”
- Originally objects are allocated into the “to space”
 - Once the “to space” has been fully allocated the trace algorithm is run
 - The “to space” becomes the “from space” as reachable objects are copied into the other part of the heap
- Mark Phase
 - Copies object when collection first encounters it
 - object is copied into the “to space” in the other half of the heap
 - Installs forwarding pointers
 - Forwarding pointers tell where the object is now in case another pointer still points to the old spot
 - Performs transitive closures, updating pointers as it goes
 - so “to space” will end up with only reachable objects in it
 - Collects “from space” en masse
 - So once all the reachable objects have been moved over the other half of the heap is just wiped clean
 - Start allocating again into “to space”
- Requires copying collection
- Cannot incrementally reclaim memory, must free en masse
- Result:
 - Awful space efficiency
 - Fast allocation time
 - Good locality of contemporaneously allocated objects
 - Good locality of objects connected by pointers

Semi-Space Evaluation

Bump Allocation + Trace + Evacuate



Actual data, taken from geomean of DaCapo, jvm98, and jbb2000 on 2.4GHz Core 2 Duo

Semi-Space Evaluation: Text Description

- Allocator is fast and has good locality
 - Its speed is the same as Mark-Compact (both use bump pointer)
 - Its locality is the best out of the 3
 - Copying during the trace causes objects that are related to be copied near each other
- Garbage collector is faster than mark-compact
 - Collection done in a single pass
- Algorithm is space inefficient
 - Can only use half the heap at a time
- Total performance is better than the other algorithms for large heap sizes

iClicker Question

True or false: older objects are more likely to survive garbage collection.

A. True

B. False

One Big Heap?

Pause time

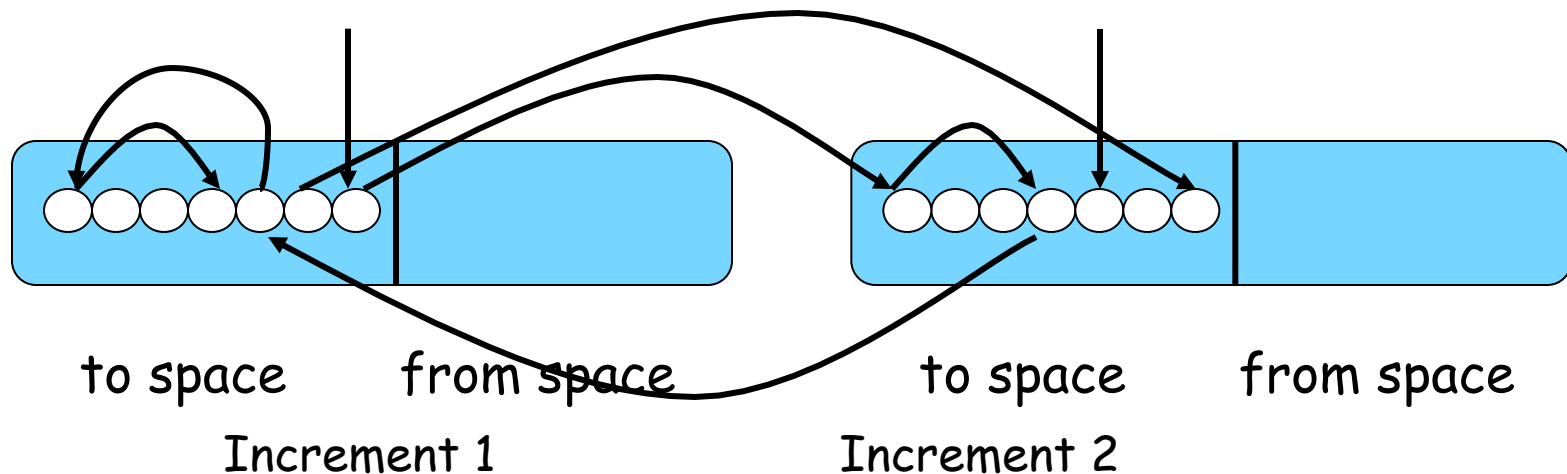
- it takes too long to trace the whole heap at once

Throughput

- the heap contains lots of long lived objects, why collect them over and over again?

Incremental collection

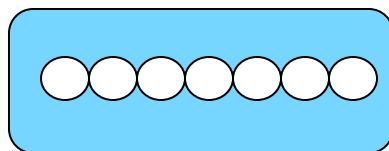
- divide up the heap into increments and collect one at a time.



Heap Organization

What objects should we put where?

- **Generational hypothesis**
 - **young objects die more quickly than older ones** (or, most objects have short lifetimes) [Lieberman & Hewitt'83, Ungar'84]
- Organize the heap into young and old, collect young objects preferentially



to space
Young

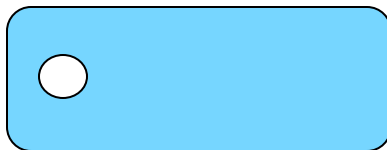


to space
Old

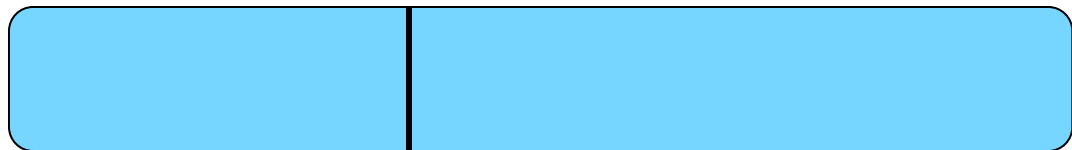
from space

Generational Heap Organization

- **Divide the heap in to two spaces: young and old**
- Allocate into the young space
- When the young space fills up,
 - collect it, copying into the old space
- When the old space fills up
 - collect both spaces
 - Generalizing to m generations
 - if space $n < m$ fills up, collect n through $n-1$



to space
Young

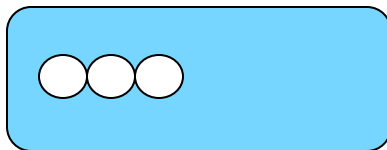


to space
Old

from space

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to space
Young

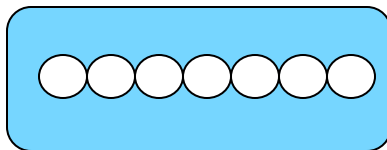


to space
Old

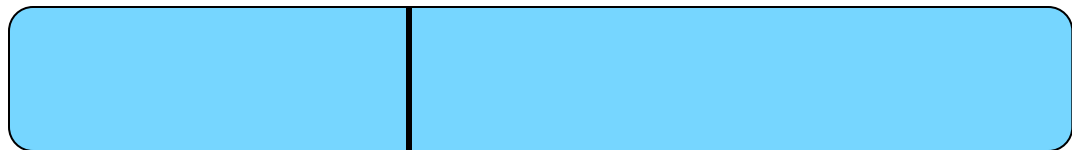
from space

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to space
Young

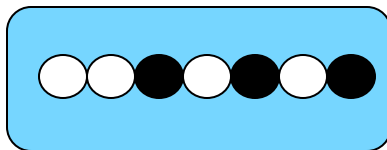


to space
Old

from space

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to space
Young



to space
Old

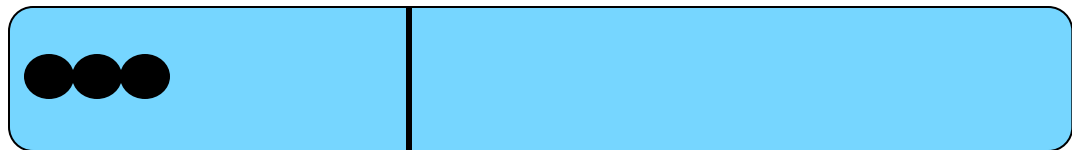
from space

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to space
Young

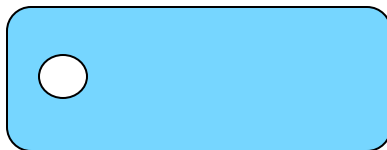


to space
Old

from space

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to space
Young

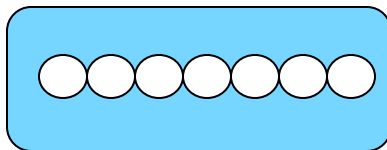


to space
Old

from space

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to space
Young

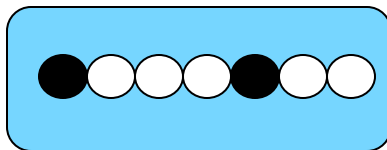


to space
Old

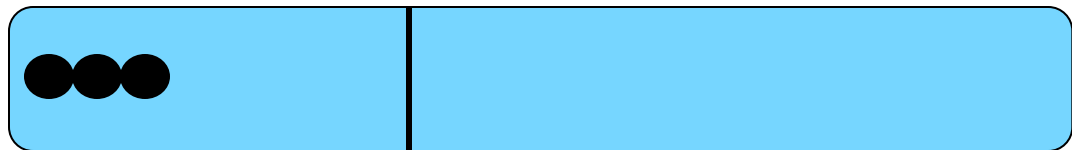
from space

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to space
Young

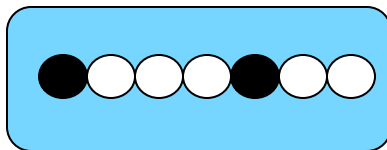


to space
Old

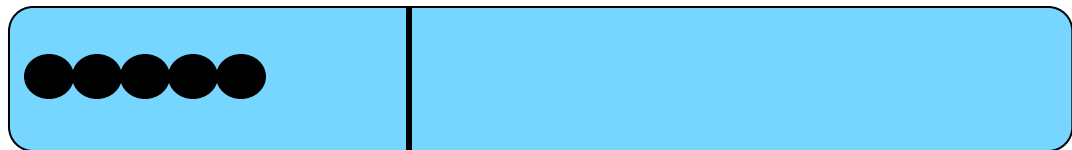
from space

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to space
Young

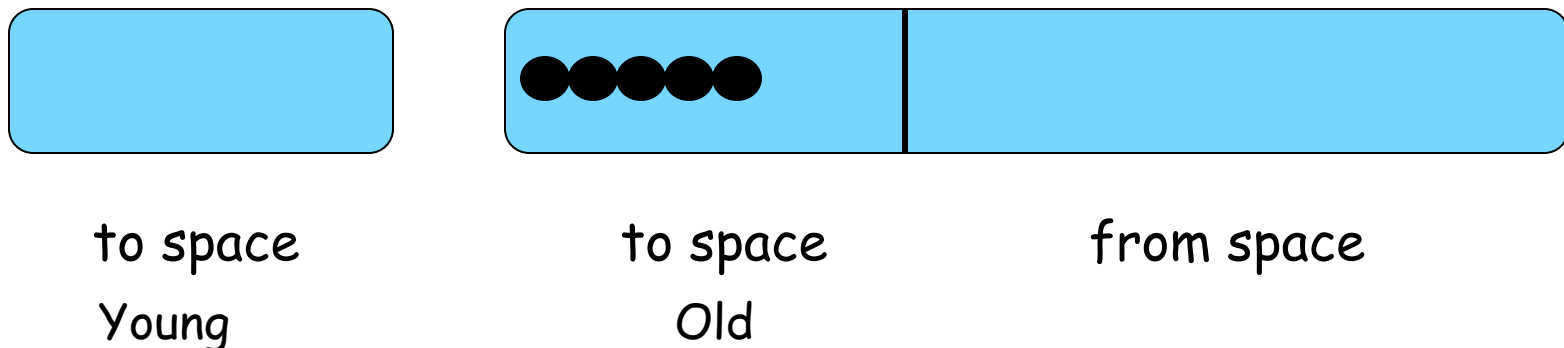


to space
Old

from space

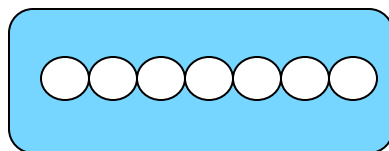
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Generational Heap Organization

- Divide the heap in to two spaces: young and old
- Allocate in to the young space
- When the young space fills up,
 - collect it, copying into the old space
- **When the old space fills up**
 - **collect both spaces**
 - Generalizing to m generations
 - if space $n < m$ fills up, collect n through $n-1$



to space
Young

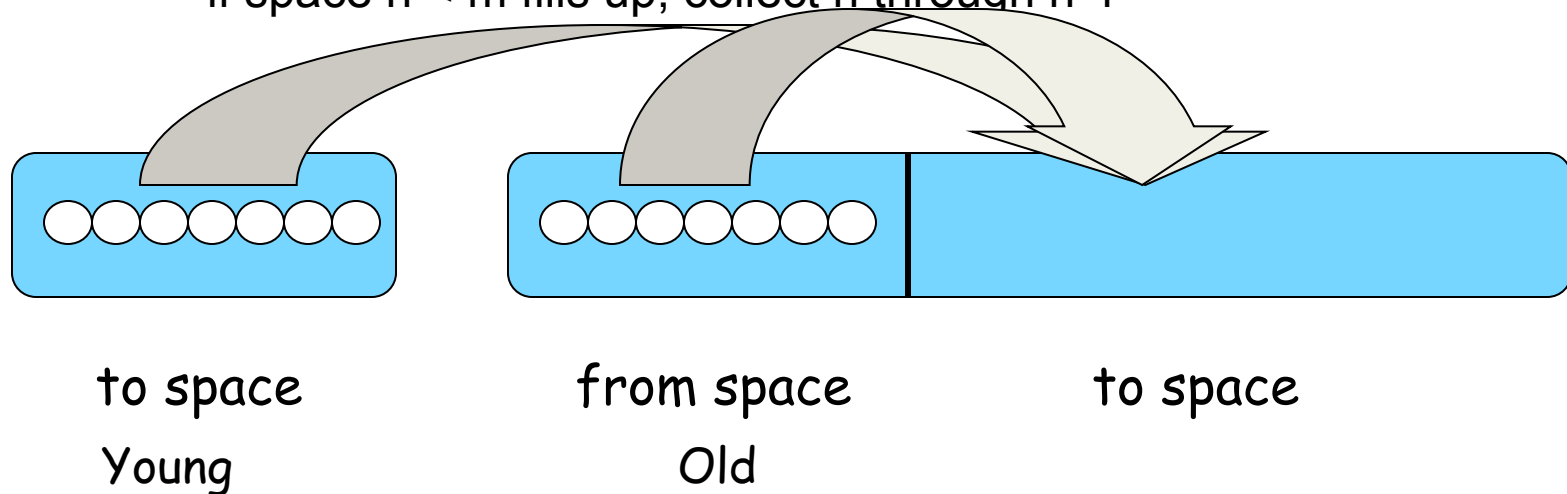


to space
Old

from space

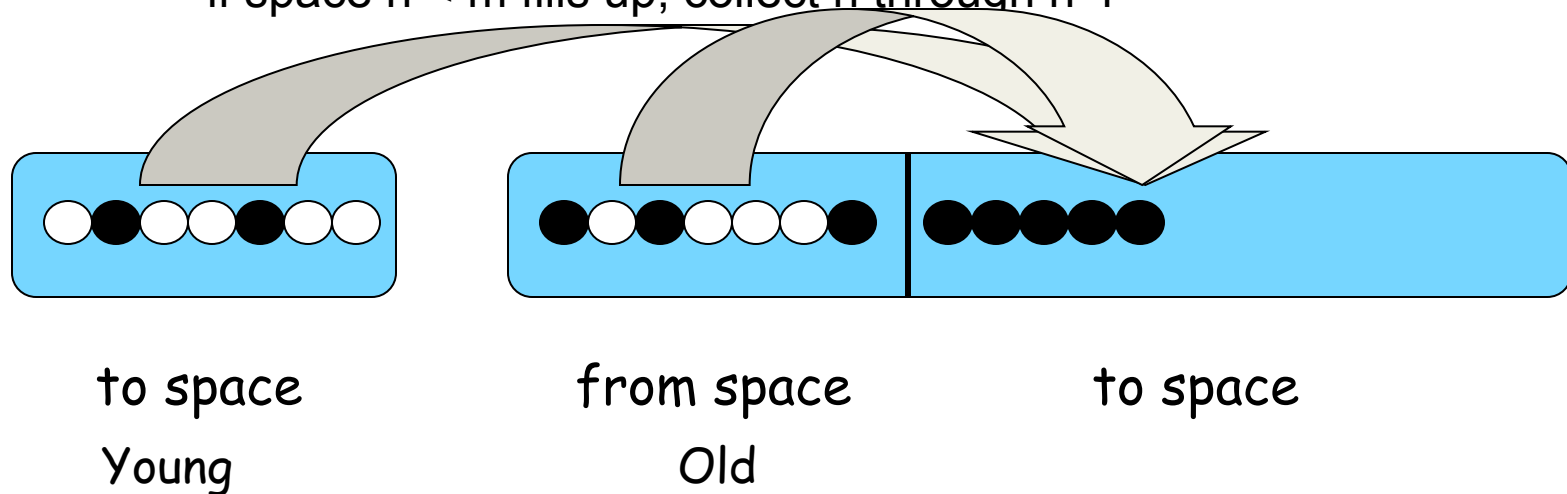
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- **When the old space fills up**
 - **collect both spaces**
 - Generalizing to m generations
 - if space $n < m$ fills up, collect n through $n-1$



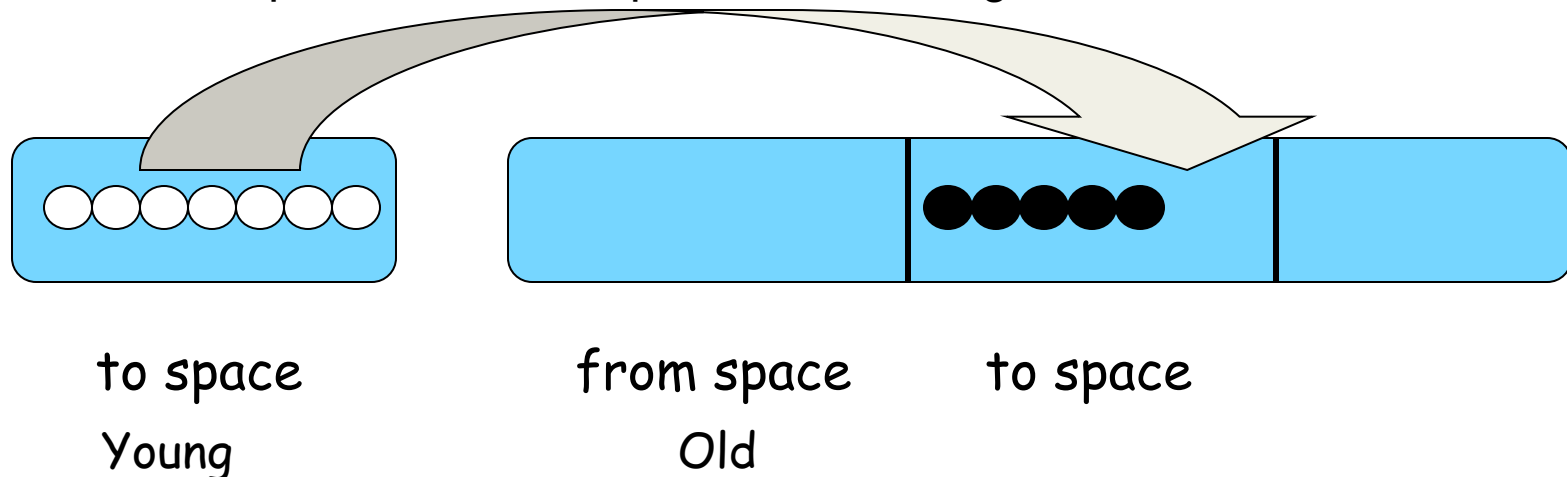
Generational Heap Organization

- Divide the heap in to two spaces: young and old
- Allocate in to the young space
- When the young space fills up,
 - collect it, copying into the old space
- **When the old space fills up**
 - **collect both spaces - ignore remembered sets**
 - Generalizing to m generations
 - if space $n < m$ fills up, collect n through $n-1$



Generational Heap Organization

- Divide the heap in to two spaces: young and old
- Allocate in to the young space
- When the young space fills up,
 - collect it, copying into the old space
- **When the old space fills up**
 - **collect both spaces - ignore remembered sets**
 - Generalizing to m generations
 - if space $n < m$ fills up, collect 1 through $n-1$



Generational Heap Organization: Text Description

- Divide the heap into two spaces: young and old
- Allocate into the young space
- When young space fills up
 - collect it, copying into the old space
- When the old space fills up
 - collect both spaces
 - move still live objects into new “to space”
 - generalizing to m generations
 - if space $n < m$ fills up, collect n through $n-1$

Garbage Collectors:

Taxonomy of Design Choices

- Incrementality
 - Bounded tracing time
 - Conservative assumption: All objects in rest of heap are live
 - *Remember* pointers from rest of heap: Add '*remembered set*' to roots for tracing
- Composability
 - Creation of hybrid collectors
- Concurrency
 - 'Mutator' and GC operate concurrently
- Parallelism
 - Concurrency among multiple GC threads
- Distribution
 - Distributed across multiple machines
 - Implies other four

Garbage Collection Recap

- Copying improves locality
- Incrementality improves responsiveness
- Generational hypothesis
 - Young objects: Most very short lived
 - Infant mortality: ~90% die young (within 4MB of allocation)
 - Old objects: most very long lived (bimodal)
 - Mature mortality: ~5% die each 4MB of new allocation

Summary

- Discussed explicit and automatic memory management
 - Allocation policies (bump pointer, free list)
 - De-allocation policies (free, various collection algorithms)
 - Free-list management
- What principles did we learn about virtual memory management that we applied to heap memory management?
 - Programs have locality
 - Internal vs. external fragmentation
 - Keep paging to a minimum

Virtual Memory Review

Announcements

- Homework 7 due Friday 8:45a
- Project 2 due Friday 11:59p
- Project 3 is posted due Friday, 4/17
 - Project 2 must be working
 - Except multi-oom
 - No, we will not give you solutions
- Exam 2 in two weeks (Wednesday, 4/8)
 - UTC 2.122A 7p-9p