More Synchronization

CS439: Principles of Computer Systems

February 11, 2015

Last Time

- Hardware Support for Mutual Exclusion and Synchronization
  - read-modify-write instructions
- Mutual Exclusion and Synchronization in Software
  - Abstractions built on top of hardware support
  - Locks
  - Semaphores

Semaphore Recap

- Two types: binary and counted
- Used for locking and synchronization
- Two *atomic* operations:
  - down(): wait for semaphore to be available, decrement value
  - up(): signal waiting threads semaphore is available, increment value
- Need separate semaphores for locking and synchronizing

Semaphore Operations

Semaphore::Down(){

   *if value is == 0, sleep

     *on signal, wake up

   *decrement semaphore value

   *return

}

Semaphore::Up{

   *increment semaphore value

   *if any threads are sleeping on semaphore, wake one of them up

   *return

}

Today's Agenda

- ## More Synchronization in Software
    - ### Monitors
        - #### Locks and Condition Variables
        - #### Bounded Buffer problem

- ## Readers/Writers problem

Monitors

Introducing Monitors

- Monitors guarantee mutual exclusion
  - only one thread may execute a given monitor method at a time
- First introduced as a programming language construct (Mesa, Java)
- Now also define a programming convention and can be used in any language (C, C++, …)
- Object-oriented style:
  - Collect related shared data into an object/module
    - Associate a lock with each one
    - All data is private
  - Define methods for accessing the shared data
    - These are critical sections

Monitors, Formally

A monitor defines a *lock* and zero or more *condition variables* for managing concurrent access to shared data.

- uses the *lock* to ensure that only a single thread is active in the monitor at any point
- the *lock* also provides mutual exclusion for shared data
- *Condition variables* enable threads to block waiting for an event inside of critical sections
  - release the lock at the same time the thread is put to sleep

Monitor Implementation

- Goal is to encapsulate shared data
  - Class in C++ or Java
  - Struct or File in C (logical encapsulation)
- Goal is to provide for mutual exclusion
  - Has a lock (exactly one!)
- Goal is to allow for synchronization
  - Has *condition variables*
- Goal is to allow operations on the shared data
  - Has functions or methods

Monitor Functions: Implementation

- Acquire the lock at the start of every function (first thing!)
  - Operate on the shared data
  - Temporarily release the lock if they can't complete due to missing resource (use condition variable for this)
  - Reacquire the lock when they can continue (again, condition variable!)
  - Operate on the shared data
- Release the lock at the end

Semaphore Example: Producers/Consumers (Recall)

```
Semaphore mutex = 1     //access to buffer
Semaphore empty = N     //count of empty slots
Semaphore full = 0      //count of full slots
int buffer[N]
```

```
BoundedBuffer::Producer(){
  <produce item>
  empty->down() //get empty spot
  mutex->down() //get access to
    buffer

  <add item to buffer>

  mutex->up() //release buffer
  full->up() //another item in buffer
}
```

```
BoundedBuffer::Consumer(){
  full->down()   //get item
  mutex->down() //get access to
    buffer

  <remove item from buffer>

  mutex->up() //release buffer
  empty->up() //another empty slot
  <use item>
}
```

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Semaphore mutex = 1      //access to buffer
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int buffer[N]


BoundedBuffer::Producer(){
  <produce item>
  empty->down() //get empty spot
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    buffer

  <add item to buffer>

  mutex->up() //release buffer
  full->up() //another item in buffer
}
```

Condition Variables

- Enable threads to wait efficiently for changes to shared state protected by a lock
- Each one is a queue of waiting threads (no state!)
- Enable the thread to sleep inside a critical section by *atomically* releasing the Lock at the same time the thread is put to sleep

Rule: A thread *must* hold the lock when doing condition variable operations

Condition Variable Operations

1. Wait(Lock lock)
    –   atomic (release lock, move thread to waiting queue, suspend thread)
    –   when the thread wakes up it re-acquires the lock (before returning from wait)
    –   thread will *always* block

2. Signal(Lock lock)
    –   wake up waiting thread, if one exists. Otherwise, it's a no-op

3. Broadcast(Lock lock)
    –   wake up all waiting threads, if any exist. Otherwise, it's a no-op

Monitor Operations

Lock->Acquire()   //acquires lock, when returns, thread has lock

Lock->Release()   //releases lock

CondVar::Wait(lock){

*move thread to waiting queue and suspend thread

*release lock

*on signal, wake up, re-acquire lock

*return

}

CondVar::Signal(){

*wake up a process waiting on condVar

*return

}

CondVar::Broadcast(){

*wake up ALL processes waiting on condVar

*return

}

Resource Variables

- Conditions variables (unlike semaphores) keep no state
- Each condition variable should have a resource variable that tracks the state of that resource
  - *You must maintain this variable*
- Check the resource variable before calling wait on the associated condition variable to ensure the resource really *isn't* available
- Once the resource is available, claim it (subtract the amount you are using!)
- Before signaling that you are finished with a resource, indicate the resource is available by increasing the resource variable

Monitor Example: Items in a Queue

```
Lock lock;
Condition fullCV;
int queue_size;


void Add(item){
   lock->acquire()
   put item on queue;
   queue_size++;
   fullCV->signal(lock)
   lock->release()
}
```

```
void remove(){
   lock->acquire()


   while(queue_size <=0)
      fullCV->wait(lock);
   queue_size--;


   remove item;
   lock->release();
}
```

Signal() Semantics

Which thread executes once signal() is called?

– If there are no waiting threads, the signaler continues and the signal is effectively lost

– If there is a waiting thread (or two):

  • There are at least two ready threads: the one that called signal() and the one that was (or will be) awakened

  • Exactly one of the threads can execute or we will have more than one thread active in the monitor (violates mutual exclusion!)

  • So which thread gets to execute?

Whose turn is it?

Mesa/Hansen Style

- The thread that signals keeps the lock (and thus the processor)
- The waiting thread waits for the lock
  - Signal is only a hint that the condition may be true: shared state may have changed!
  - Adding signals affects performance, but never safety
- Implemented in Java and most real operating systems

Hoare Style

- The thread that signals gives up the lock and the waiting thread gets the lock
  - Signaling is atomic with the resumption of the waiting thread
  - Shared state cannot change before waiting thread is resumed
- When the thread that was waiting and is now executing exits or waits again, it releases the lock back to the signaling thread
- Implemented in most textbooks (not yours!)

More on Turns

- With Mesa-style, waiting thread may need to wait again after it is wakened (Why?), so *while* is important
- With Hoare-style, we can change *while* to *if* because a waiting thread runs immediately

```
public void remove(){
    lock->Acquire()
    while (queue_size <= 0){
        full->wait(lock);
    }
    queue_size--;
    remove item;
    lock->Release();
}
```

Regardless, if you assume there is NO atomicity between signal() and the return from wait(), your code will always work.

Semaphore Example: Producers/Consumers (Recall)

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int buffer[N]

```
BoundedBuffer::Producer(){
  <produce item>
  empty->down() //get empty spot
  mutex->down() //get access to
    buffer

  <add item to buffer>

  mutex->up() //release buffer
  full->up() //another item in buffer
}
```

```
BoundedBuffer::Consumer(){
  full->down()   //get item
  mutex->down() //get access to
    buffer

  <remove item from buffer>

  mutex->up() //release buffer
  empty->up() //another empty slot
  <use item>
}
```

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int buffer[N]

BoundedBuffer::Consumer(){
  full->down()   //get item
  mutex->down() //get access to
   buffer

  <remove item from buffer>

  mutex->up() //release buffer
  empty->up() //another empty slot
  <use item>
}
```

Monitor Example: Producers/Consumers

```
class BBMonitor{
  public: <methods>
  private: item buffer[N];
      Lock lock;
      Condition fullCV, emptyCV;
      int empty=N;
      int full=0;
}

BoundedBuffer::Producer(){
  lock->Acquire()

  while(empty == 0)
    emptyCV->Wait(lock) //get empty spot
  empty--;

  <add item to buffer>

  full += 1
  fullCV->Signal(lock) //another item in
    buffer
  lock->Release()
}
```

```
BoundedBuffer::Consumer(){
  lock->Acquire()

  while(full == 0)
    fullCV->Wait(lock) //get item
  full--

  <remove item from buffer>

  empty++;
  emptyCV->Signal(lock) //another empty
    slot
  lock->Release()
}
```

iClicker Question

Every monitor function should begin with what command?

A. Wait()

B. Signal()

C. Lock->Acquire()

D. Lock->Release()

E. Broadcast()

Monitor Summary

- A monitor wraps operations with a lock
- Condition variables release lock temporarily
- Monitors can be implemented by following the monitor rules for acquiring and releasing locks

Comparing Monitors and Semaphores

- Condition variables do not have any history
  - on signal() if no one is waiting, the signal is a no-op
  - if thread then calls condition->wait(), it waits.

- Semaphores do have history
  - on up() if no one is waiting, the value of the semaphore is incremented
  - if a thread then calls semaphore->down(), the value is decremented and the thread continues

So… signal() and down()

- In semaphores, down() and up() are commutative
  - result is the same regardless of the order of execution
- Condition variables are not commutative
  - so they must be in a critical section to access state variables and do their job

You *can* implement Monitors with Semaphores.

Monitors and Semaphores: Recap

Both

- Provide mutual exclusion and synchronization
- Have signal() and wait()
- Support a queue of processes that are waiting to access a critical section (e.g., to buy milk)
- No busy waiting!

Semaphores

- Semaphores are basically generalized locks
- Binary and counting semaphores
- Used for mutual exclusion and synchronization

Monitors

- Consist of a lock and one or more condition variables
- Encapsulate shared data
- Use locks for mutual exclusion
- Use condition variables for synchronization
- Wrap operations on shared data with a lock
- Condition variables release lock temporarily

A Different Type of Problem

- We've looked at problems where we protect shared data by only allowing one thread in the critical section at a time

- Is this always appropriate? When might we want to let more threads access shared data at once?

Readers/Writers Problem

- Data is shared among several threads
  - Some only read
  - Some only write
- To get correct results, we allow *multiple readers* at a time, but only *one writer* at a time
- How can we control access to the object to permit this protocol?

Correctness Criteria

- Each read or write of the shared data *must* happen within a critical section

- Guarantee mutual exclusion for writers

- Allow multiple readers to execute in the critical section at once

- Allow one writer (and no readers) to execute in the critical section at once

Readers and Writers: Monitor Solution

- What methods do we need?
- How many locks?
- How many condition variables?
- What should we name them?
- Any other variables?

- Assume we're going to say <read> and <write> for accesses to the shared data.

Readers and Writers: Monitor Solution

Variables:

read(){

write(){

Is our solution fair?

}

}

A. Yes

B. No, favors readers

C. No, favors writers

Understanding Our Solution

It works, but it favors readers over writers

- Any reader blocks all writers
- All readers must finish before a writer can start
- Last reader will wake any writer, but a writer wakes all readers and writers
- If a writer exits and a reader goes next, then all readers that are waiting will get through

Readers and Writers: Monitor Solution

Variables: write(){

read(){

}   }

Alternative Semantics

- It may be that you would like a writer to enter its critical section as soon as possible.

- How could we implement that?

Signal vs. Broadcast

- It is always safe to use broadcast() instead of signal()
  - only performance is affected
- signal() is preferable when
  - at most one waiting thread can make progress
  - any thread waiting on the condition variable can make progress
- broadcast() is preferable when
  - multiple waiting threads may be able to make progress
  - the same condition variable is used for multiple predicates
    - some waiting threads can make progress, others can't

Summary

- A monitor wraps operations with a lock
- Condition variables release lock temporarily
- Monitors do not keep state---a call to wait() will *always* wait
- Monitors can be implemented by following the monitor rules for acquiring and releasing locks

Announcements

- Homework 3 due Friday 9:45a
- Project 1 is posted due 2/27
- Exam 1 is in two weeks!
  - Wednesday, 2/25! 7p! UTC 2.112A!