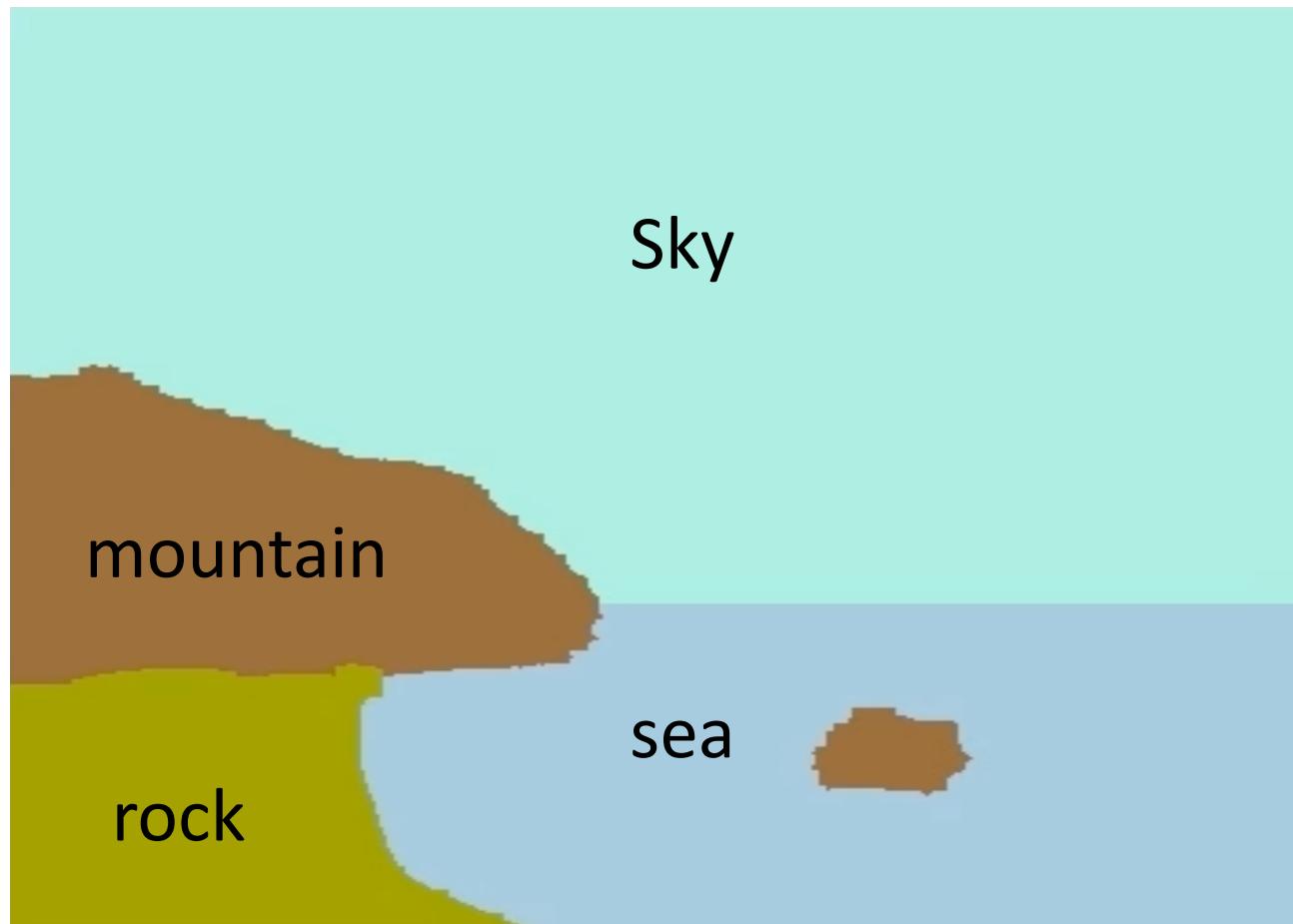


# Conditional GANs, Image-to-Image Translation

Jun-Yan Zhu

16-726, Spring 2023

# Problem Statement



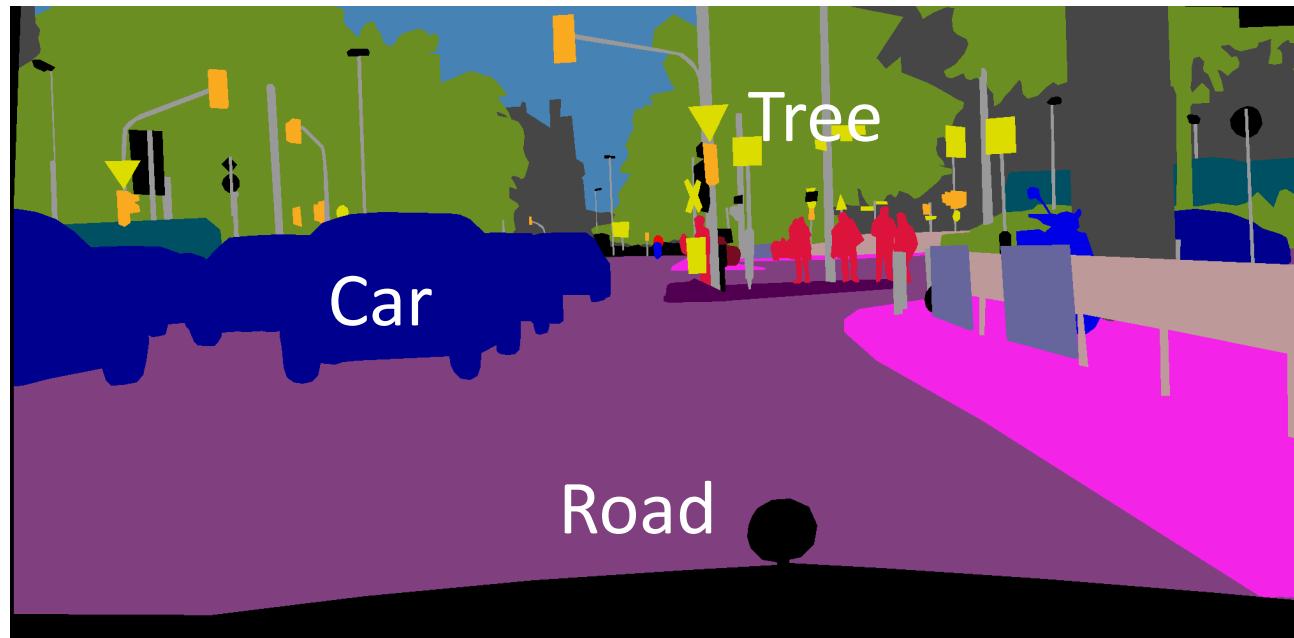
Input



Output

Goal: synthesize a photograph given an input image

# Problem Statement



Input



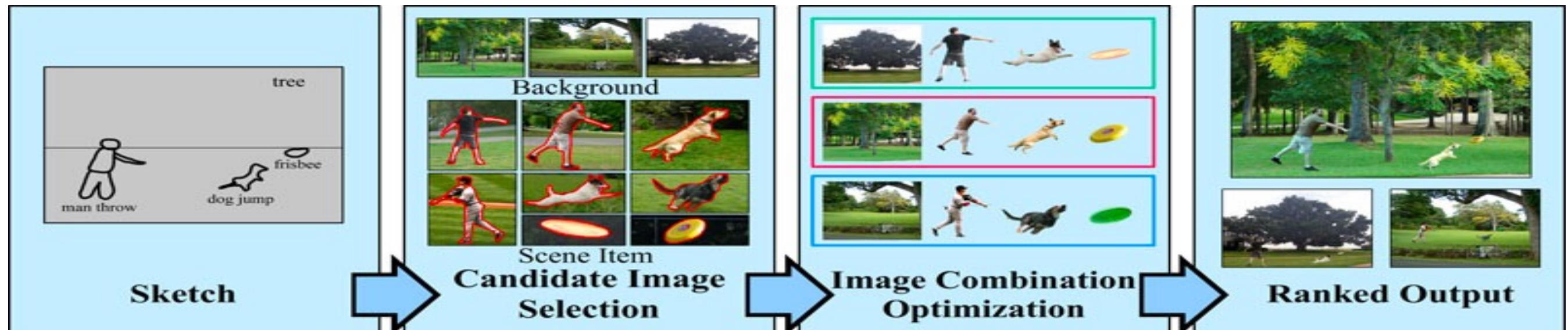
Output

Goal: synthesize a photograph given an input image

# Early work (Example-based)

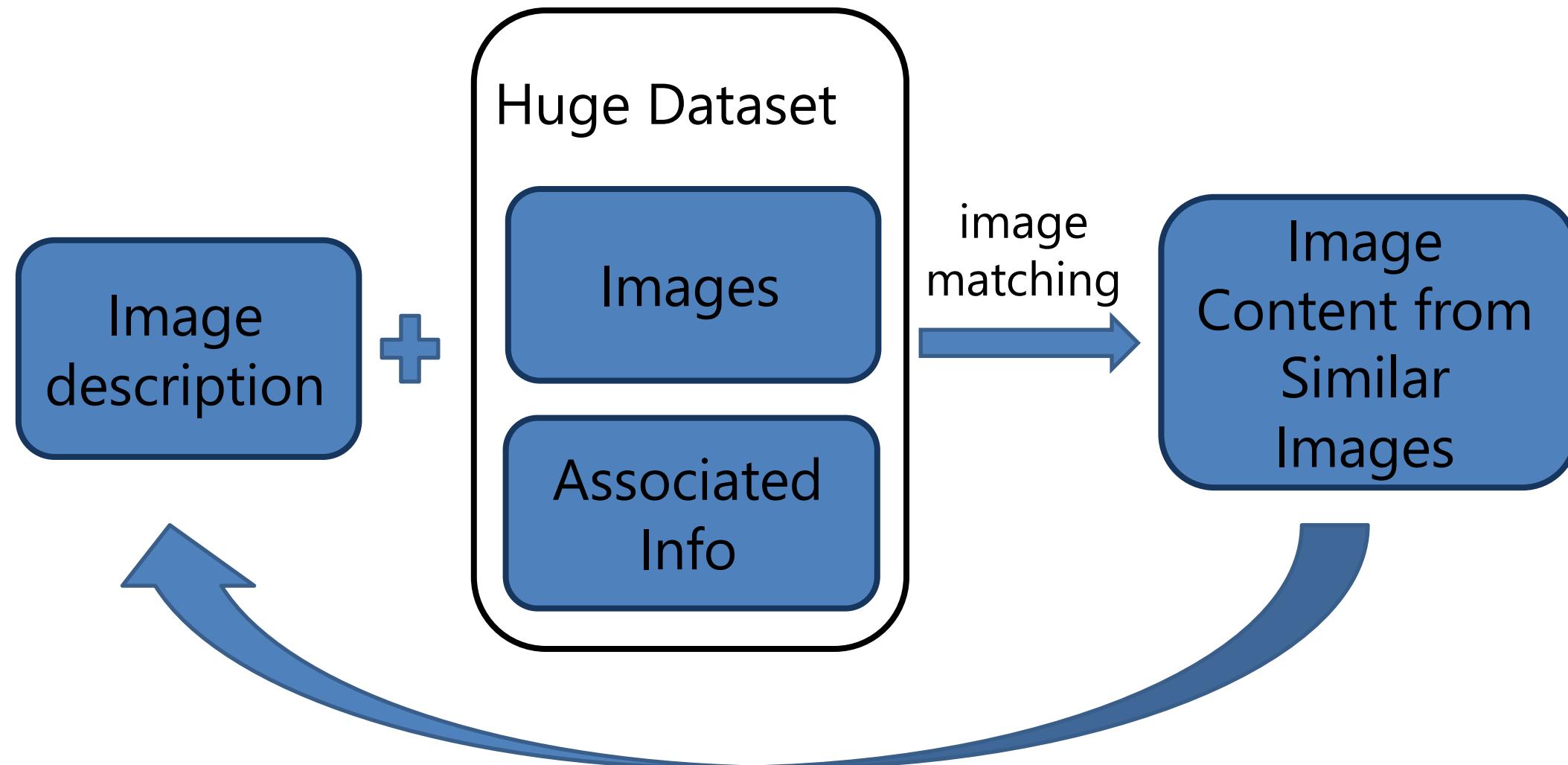


Semantic Photo Synthesis [Johnson et al., Eurographics 2006]



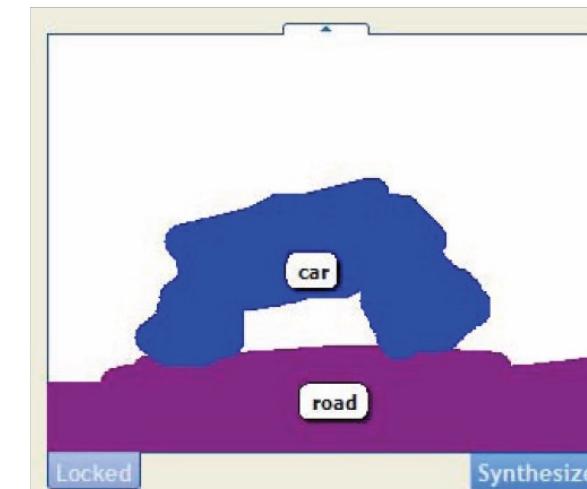
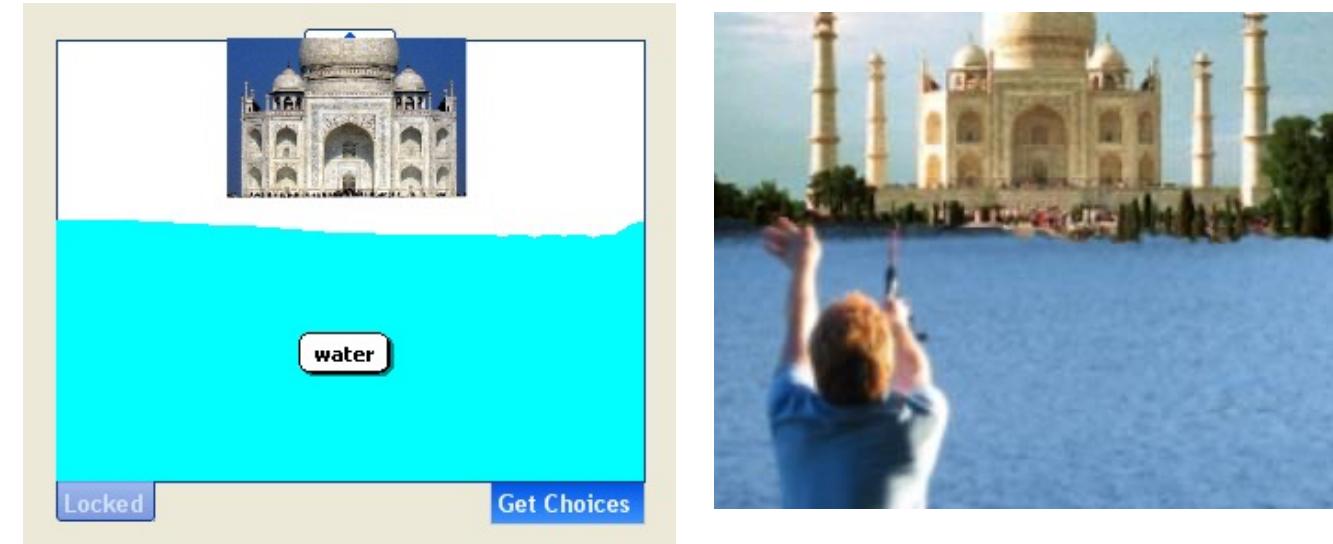
Sketch2Photo [Tao et al., SIGGRAPH Asia 2009]

# Semantic Photo Synthesis



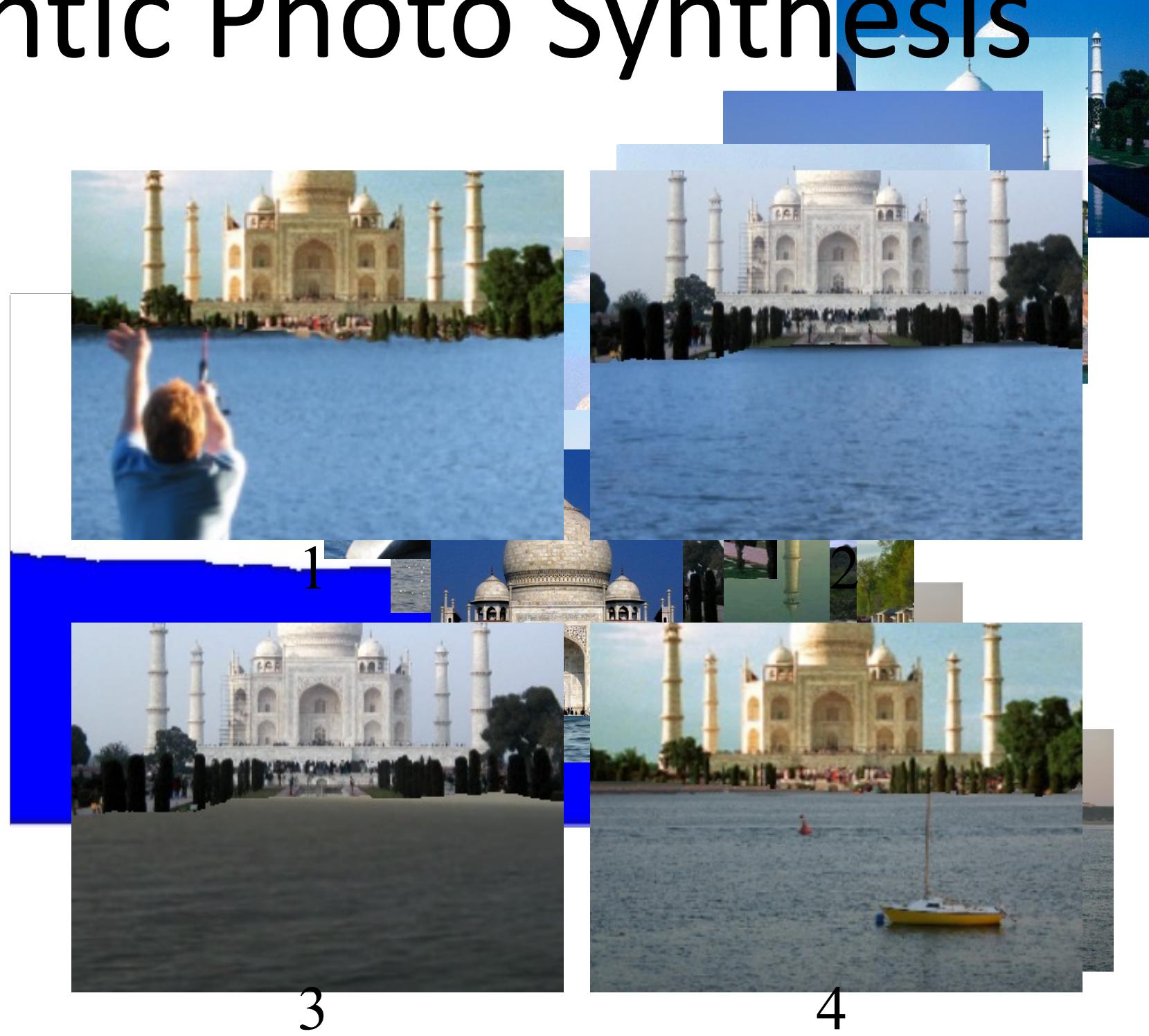
M. Johnson, G. Brostow, J. Shotton, O. A. c, and R. Cipolla, "Semantic Photo Synthesis,"  
Eurographics 2006

# Semantic Photo Synthesis [EG'06]

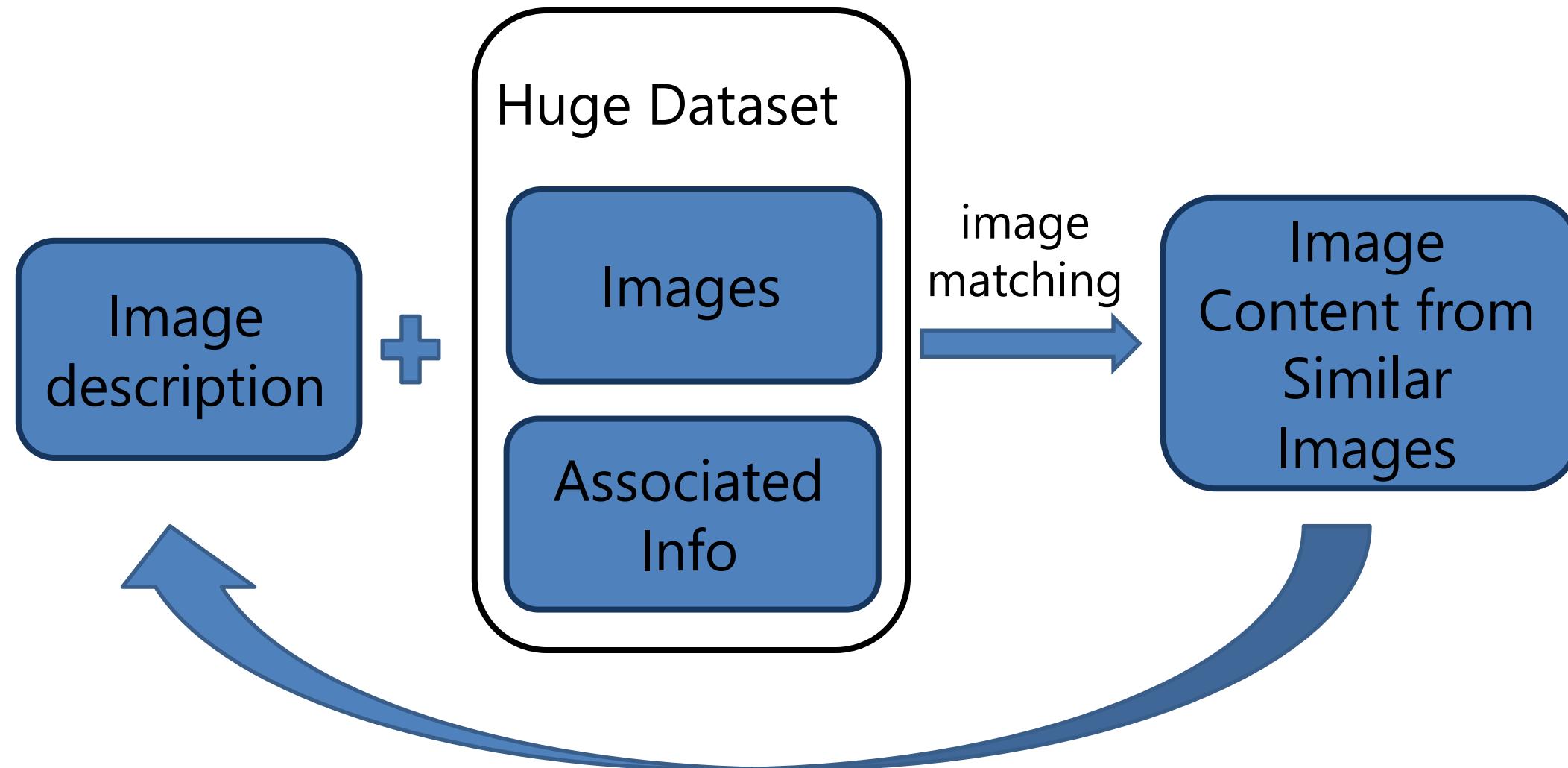


M. Johnson, G. Brostow, J. Shotton, O. A. c, and R. Cipolla, "Semantic Photo Synthesis,"  
Eurographics 2006

# Semantic Photo Synthesis



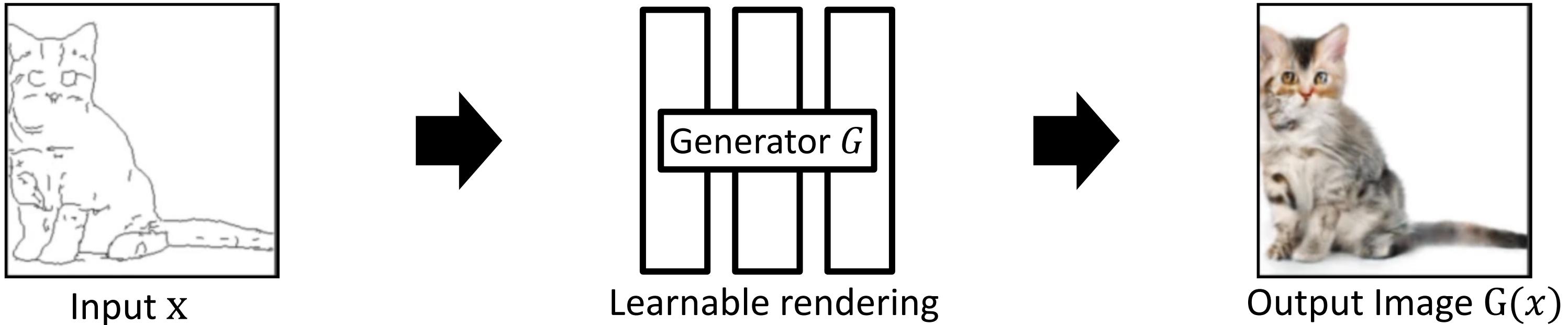
# Semantic Photo Synthesis



M. Johnson, G. Brostow, J. Shotton, O. A. c, and R. Cipolla, "Semantic Photo Synthesis," Computer Graphics Forum Journal (Eurographics 2006), vol. 25, no. 3, 2006.

# Learning-based methods

# Loss functions for Image Synthesis



What is a good objective  $\mathcal{L}$ ?

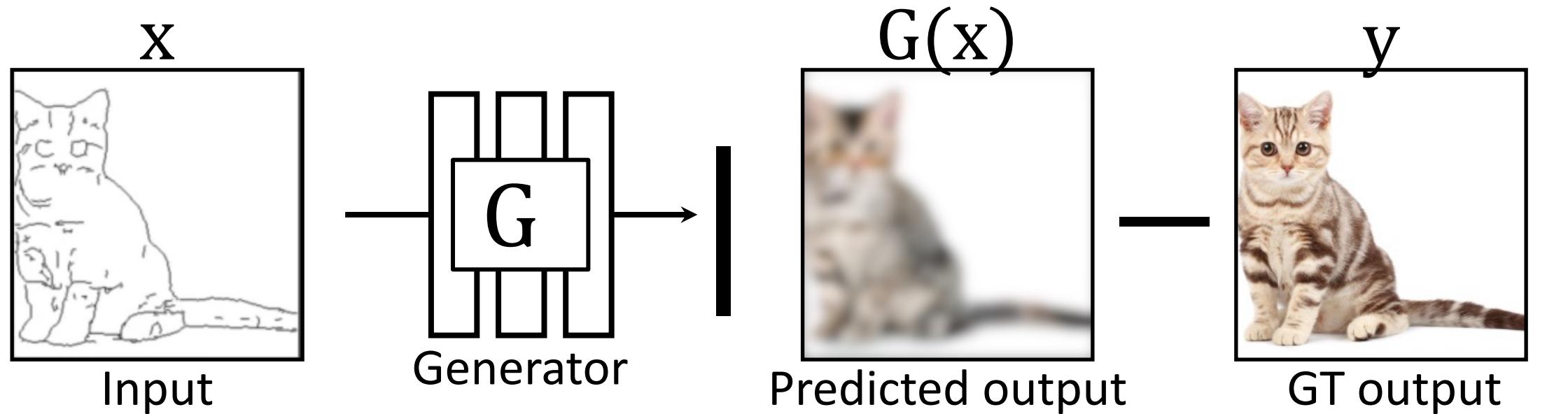
- What is a good loss?
- How to calculate it efficiently?
- How to collect data  $(x, y)$ ?

**Problem Statement**

$$\arg \min_G \mathcal{L}(G(x), y)$$

↓  
Loss function  
Generator      Input Info      Output image

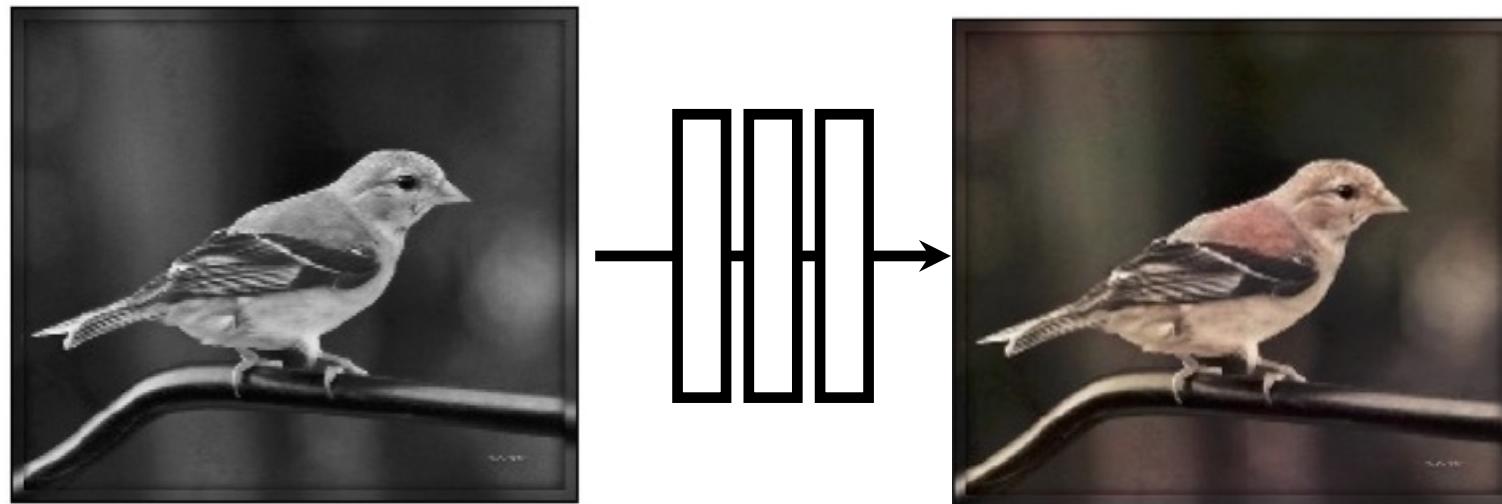
# Designing Loss Functions



**L2 regression**  $\arg \min_G \mathbb{E}[ \|G(x) - y\| ]$

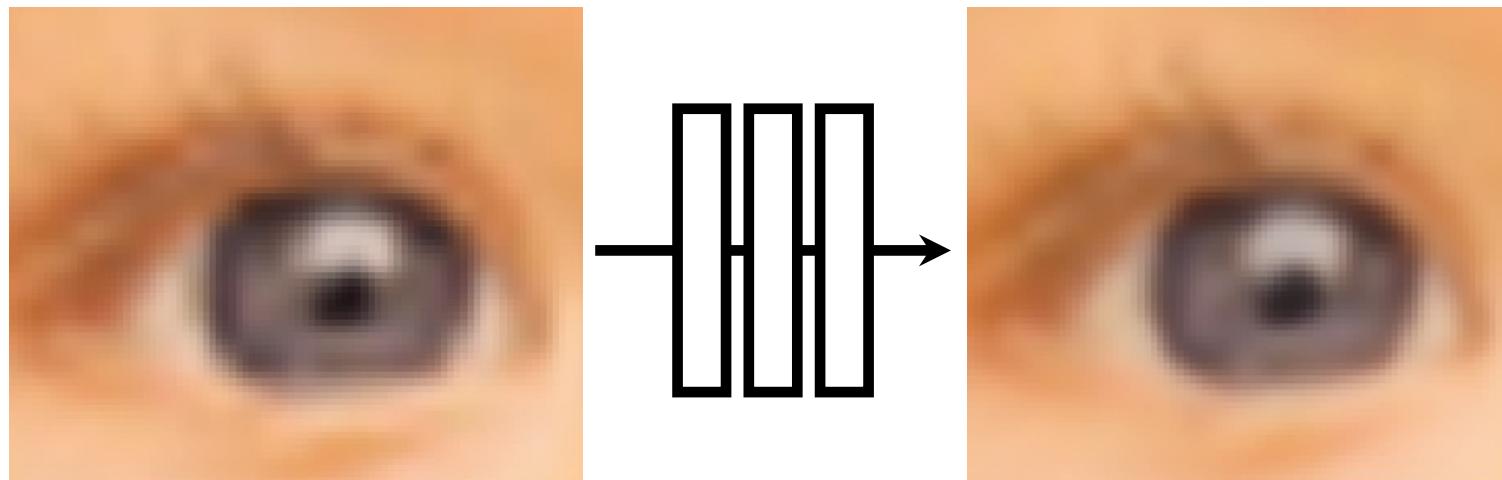
# Designing Loss Functions

Image colorization



L2 regression

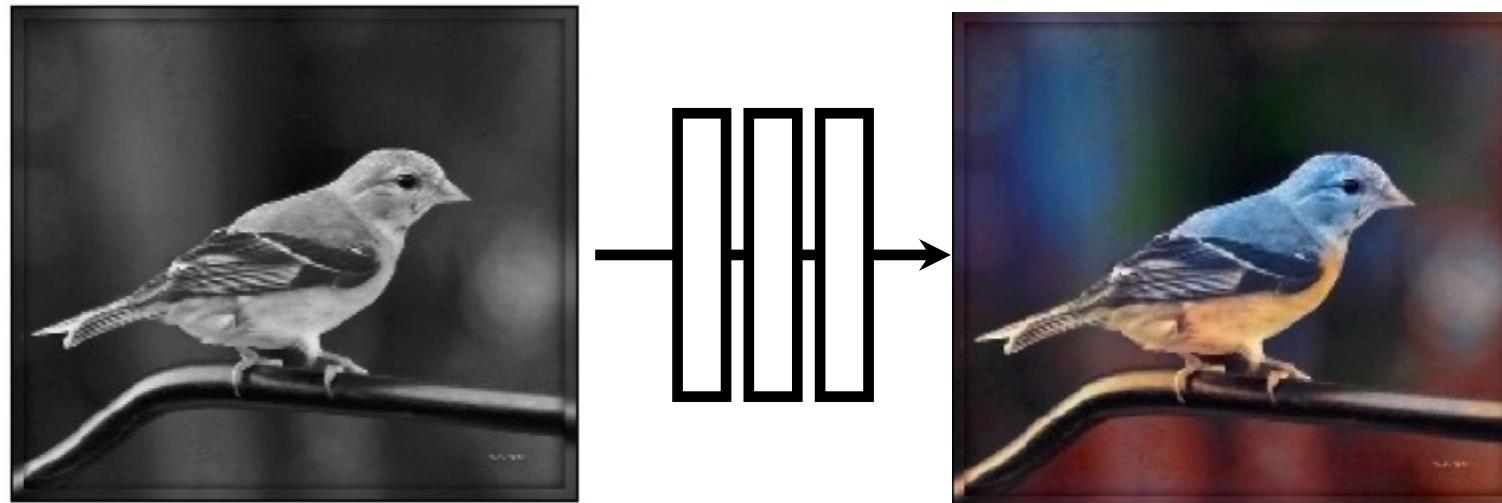
Super-resolution



L2 regression

# Designing Loss Functions

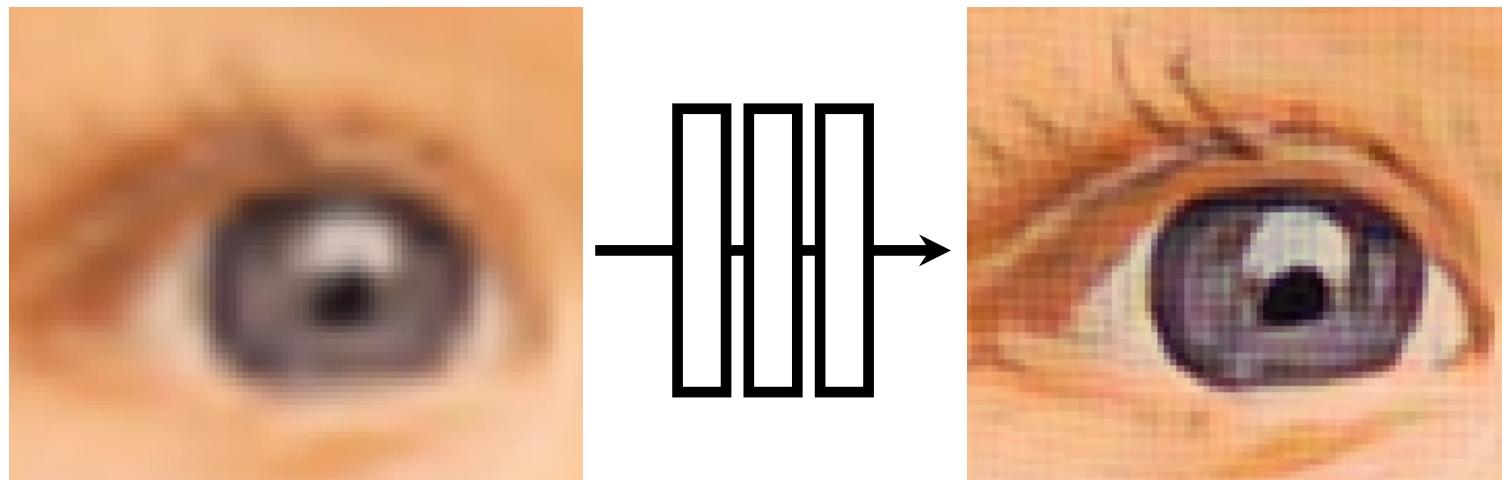
Image colorization



[Zhang et al. 2016]

Classification Loss:  
Cross entropy objective,  
with colorfulness term

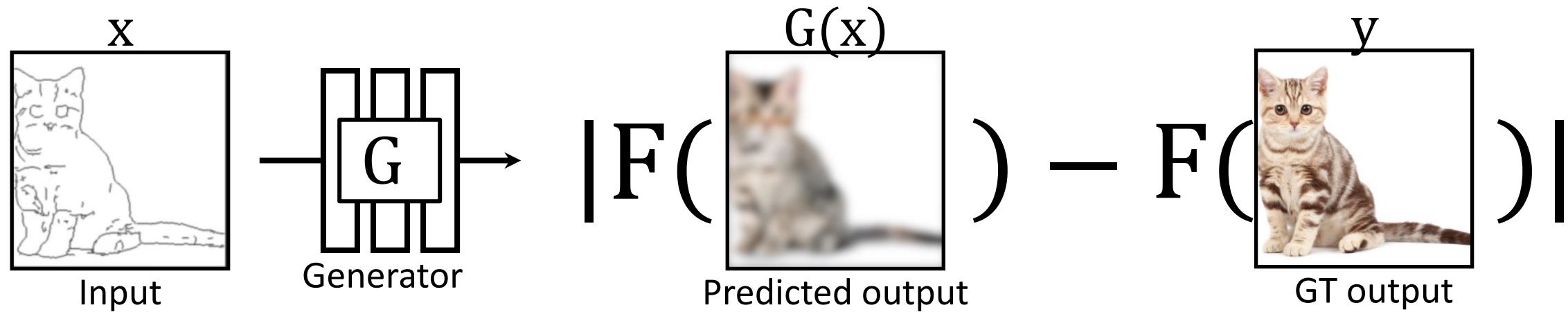
Super-resolution



Feature/Perceptual loss  
Deep feature matching  
objective

[Gatys et al., 2016], [Johnson et al. 2016], [Dosovitskiy and Brox. 2016]

# CNNs as a Perceptual Metric



$F$  is a deep network (e.g., ImageNet classifier)

## Perceptual Loss

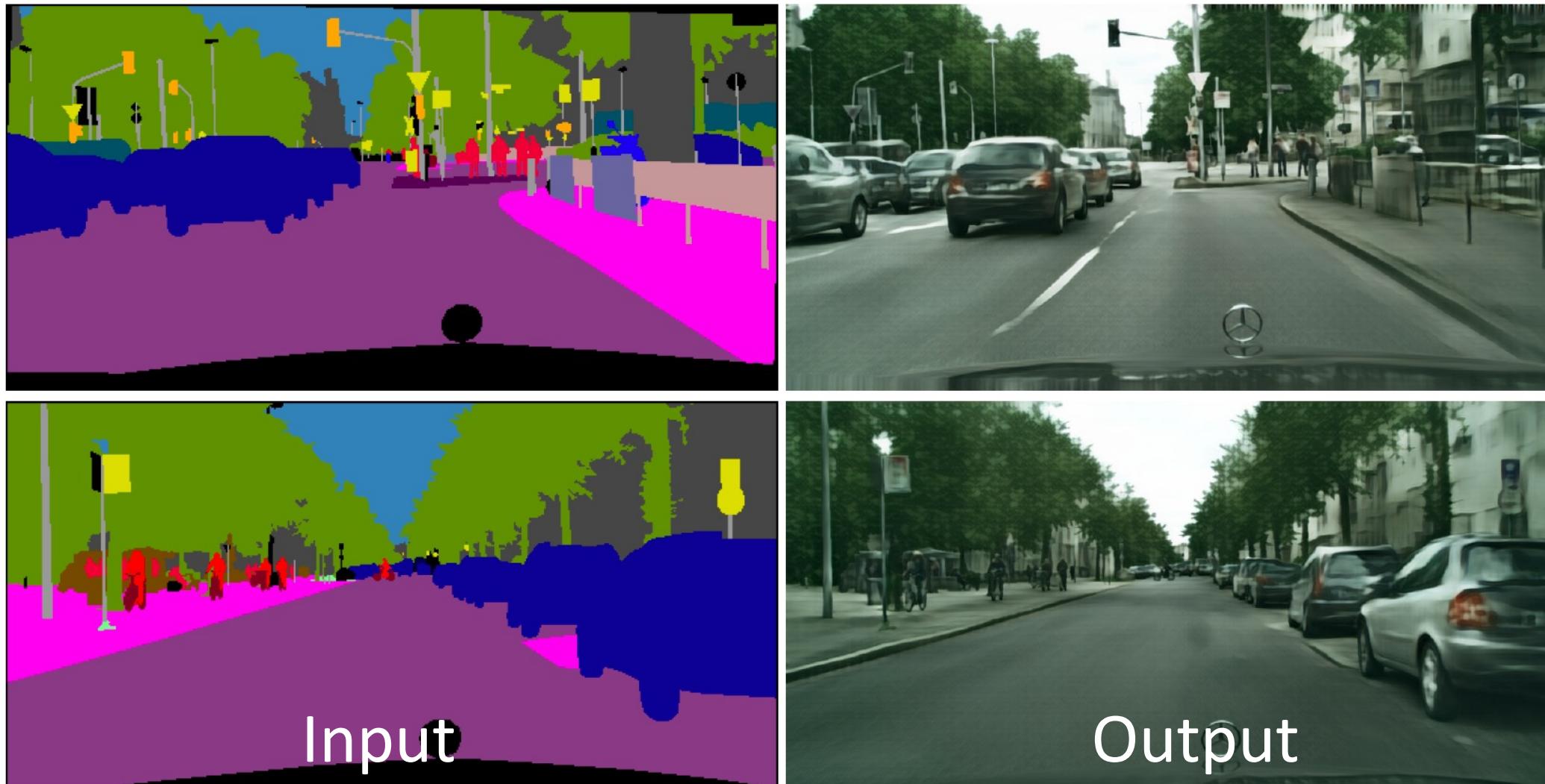
$$\arg \min_G \mathbb{E}_{(x,y)} \sum_{i=1}^N \lambda_i \frac{1}{M_i} \left\| F^{(i)}(G(x)) - F^{(i)}(y) \right\|_2^2$$

The number of elements in the (i)-th layer

Annotations for the equation:

- An arrow labeled "weight" points to  $\lambda_i$ .
- An arrow labeled "(i)-th layer" points to  $F^{(i)}$ .
- An arrow labeled "The number of elements in the (i)-th layer" points to  $M_i$ .

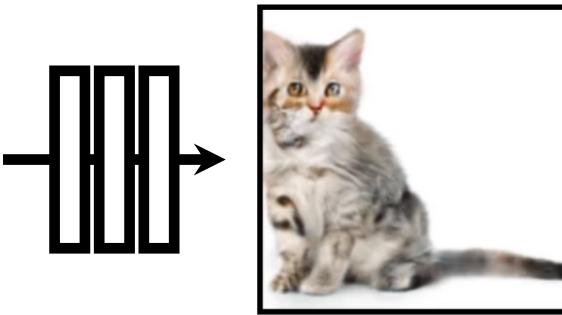
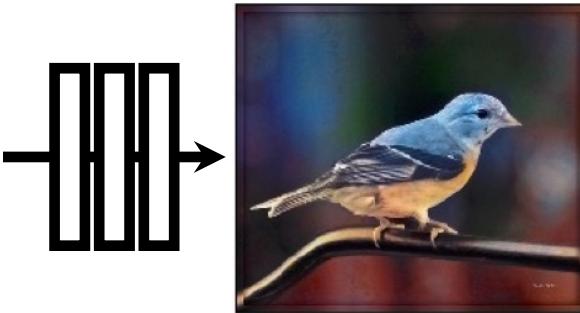
# Learning with Perceptual Loss



Training objective:  $\arg \min_G \mathbb{E}_{(x,y)} \sum_{i=1}^N \lambda_i \frac{1}{M_i} \|F^{(i)}(G(x)) - F^{(i)}(y)\|_2^2$

CRN [Chen and Koltun, 2017]

## Generated images



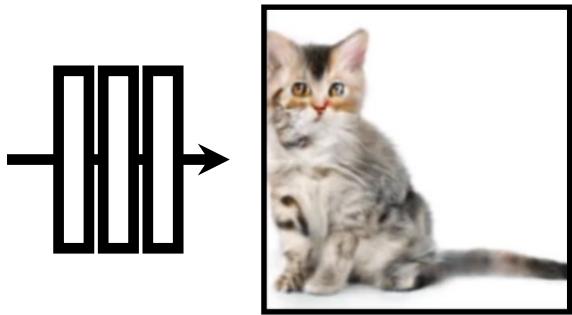
⋮

⋮



Universal loss?

Generated images



:

:

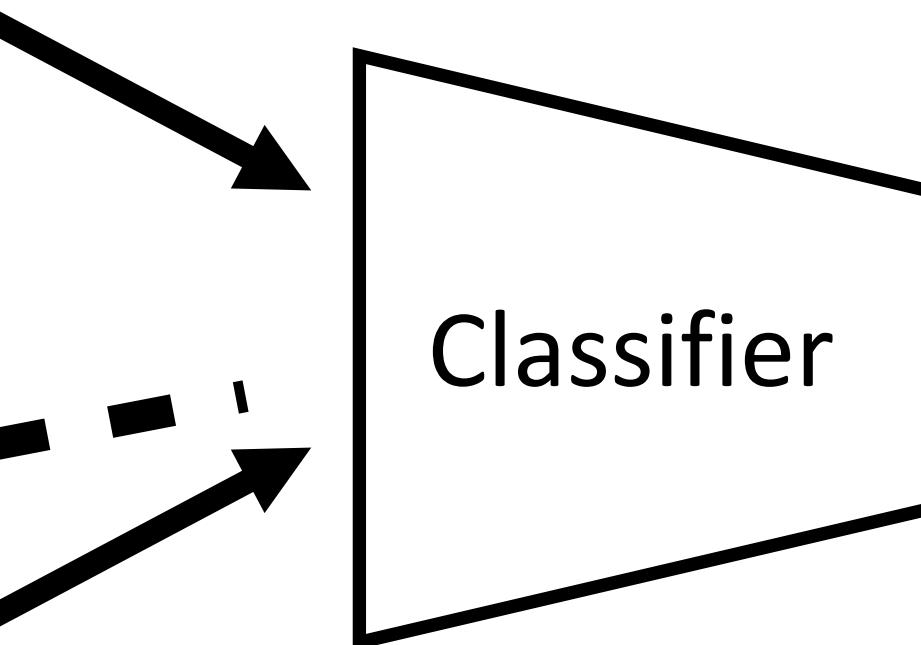


# Generative Adversarial Network (GANs)

Real photos



...



Real vs. Fake



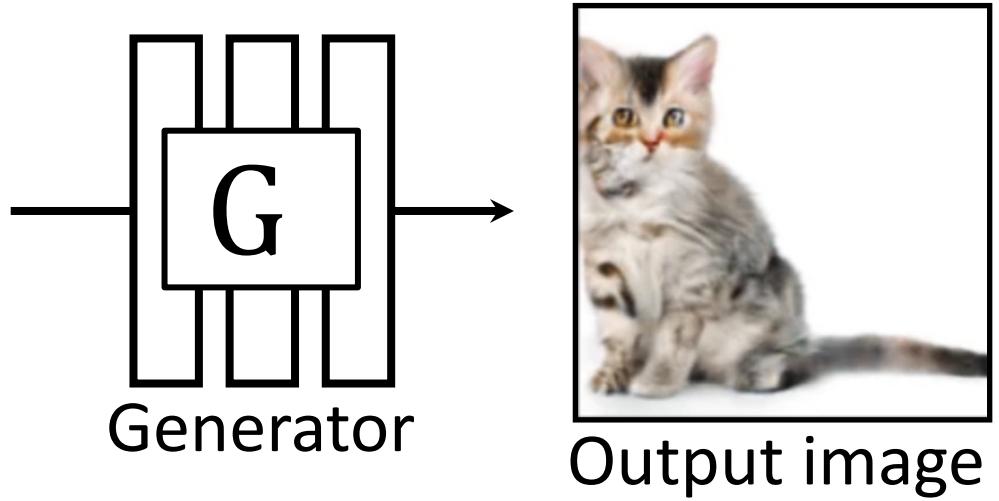
[Goodfellow, Pouget-Abadie, Mirza, Xu, Warde-Farley, Ozair, Courville, Bengio 2014]

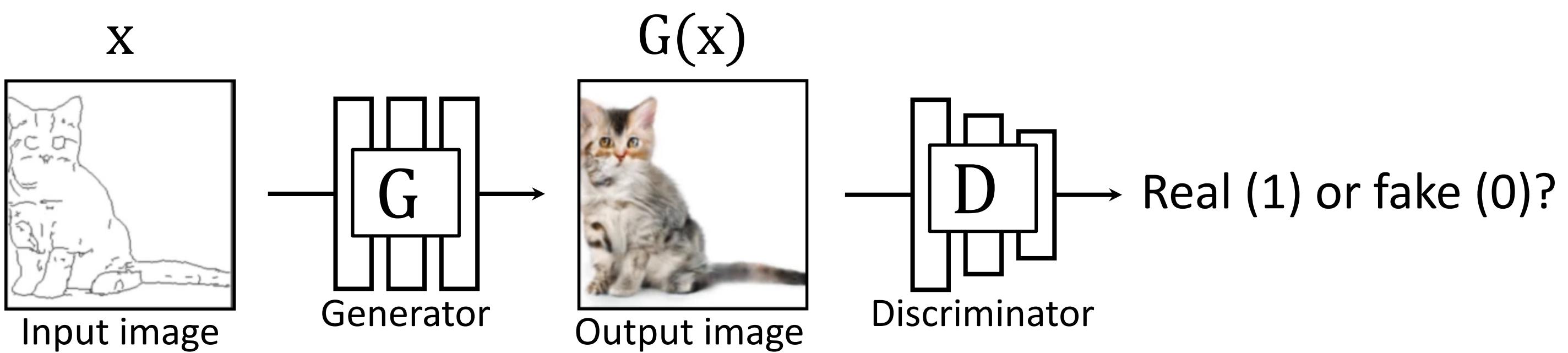
$x$



Input image

$G(x)$





A two-player game:

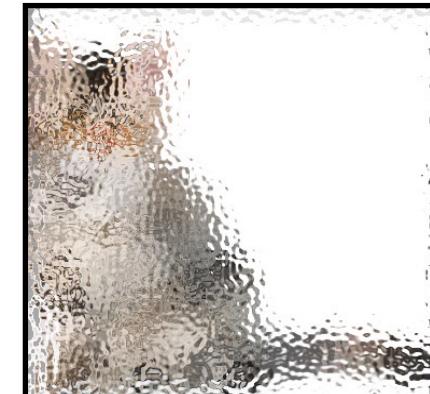
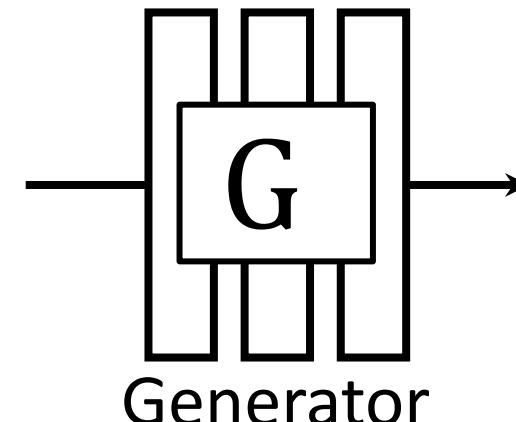
- **G** tries to generate fake images that can fool **D**.
- **D** tries to detect fake images.

$x$

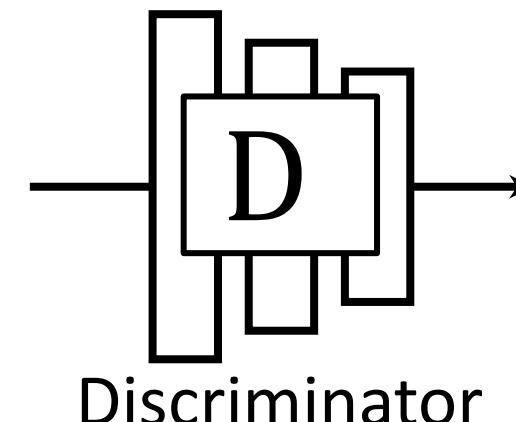


Input image

$G(x)$



Output image

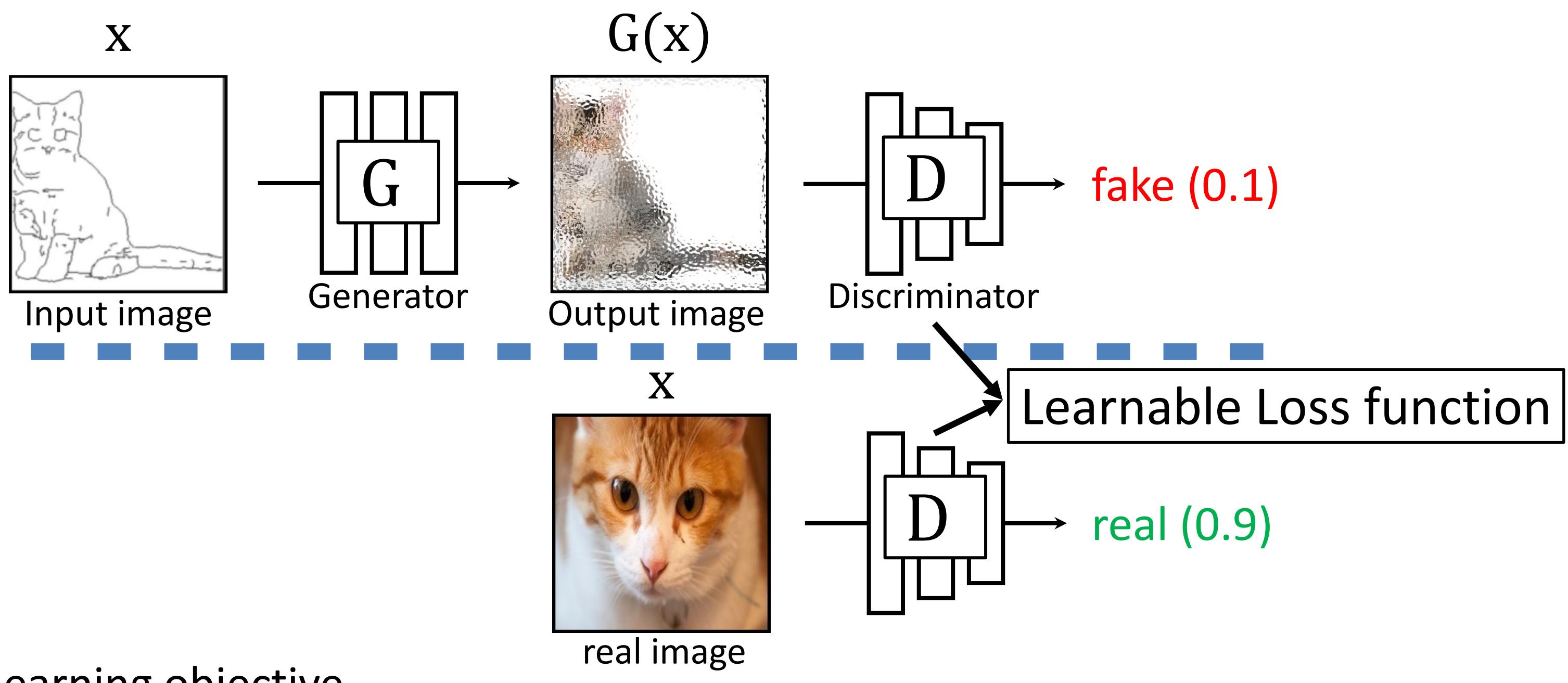


fake (0.1)

## Learning objective

$$\min_G \max_D \mathbb{E}_x [\log(1 - D(G(x)))] + \mathbb{E}_y [\log D(y)]$$

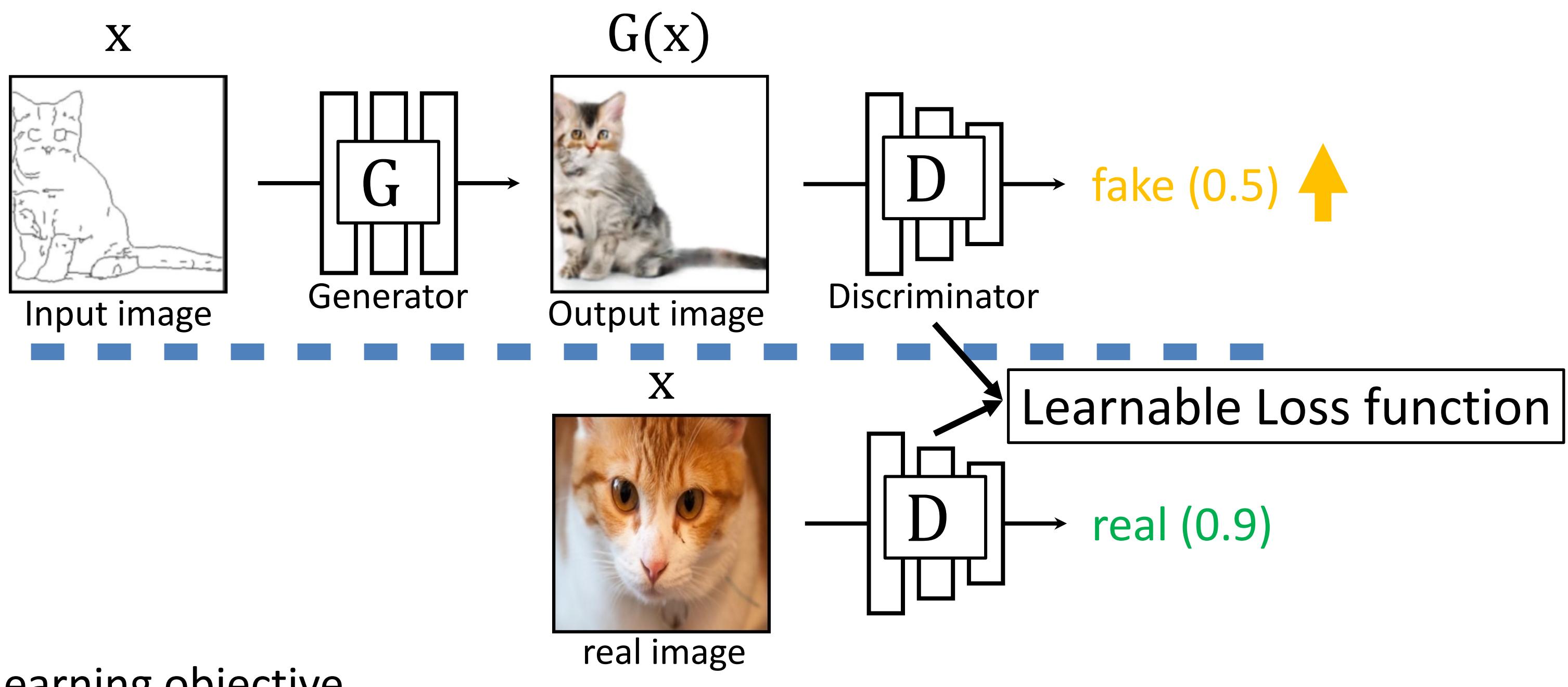
[Goodfellow et al. 2014]



Learning objective

$$\min_G \max_D \mathbb{E}_x [\log(1 - D(G(x)))] + \mathbb{E}_y [\log D(y)]$$

[Goodfellow et al. 2014]

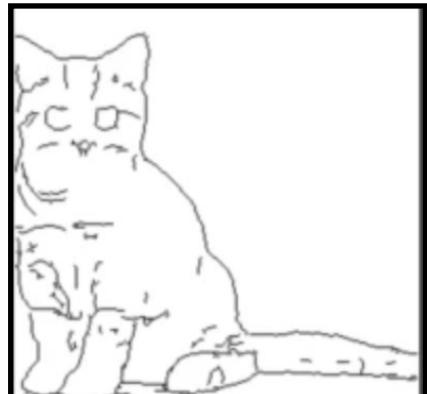


Learning objective

$$\min_G \max_D \mathbb{E}_x[\log(1 - D(G(x)))] + \mathbb{E}_y[\log D(y)]$$

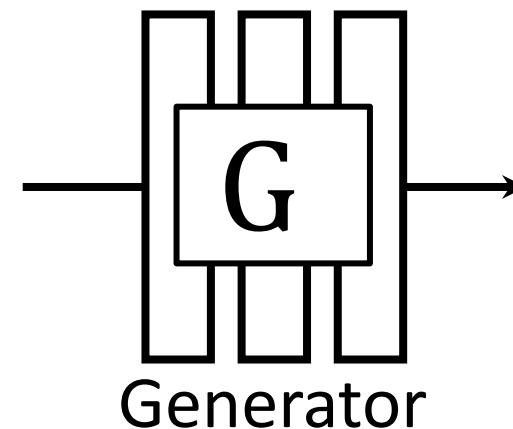
[Goodfellow et al. 2014]

$x$

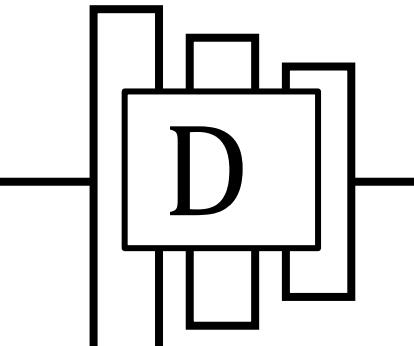


Input image

$G(x)$



Output image



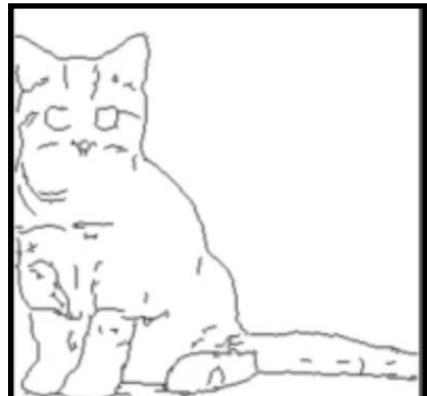
Discriminator

Real✓

## Learning objective

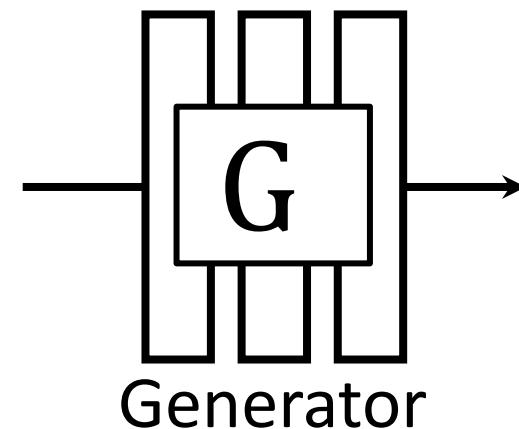
$$\min_G \max_D \mathbb{E}_x[\log(1 - D(G(x)))] + \mathbb{E}_y[\log D(y)]$$

X

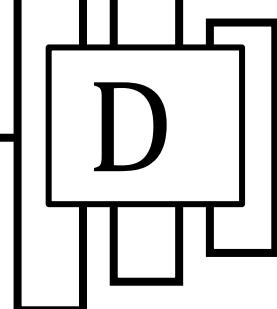


Input image

G(x)



Output image

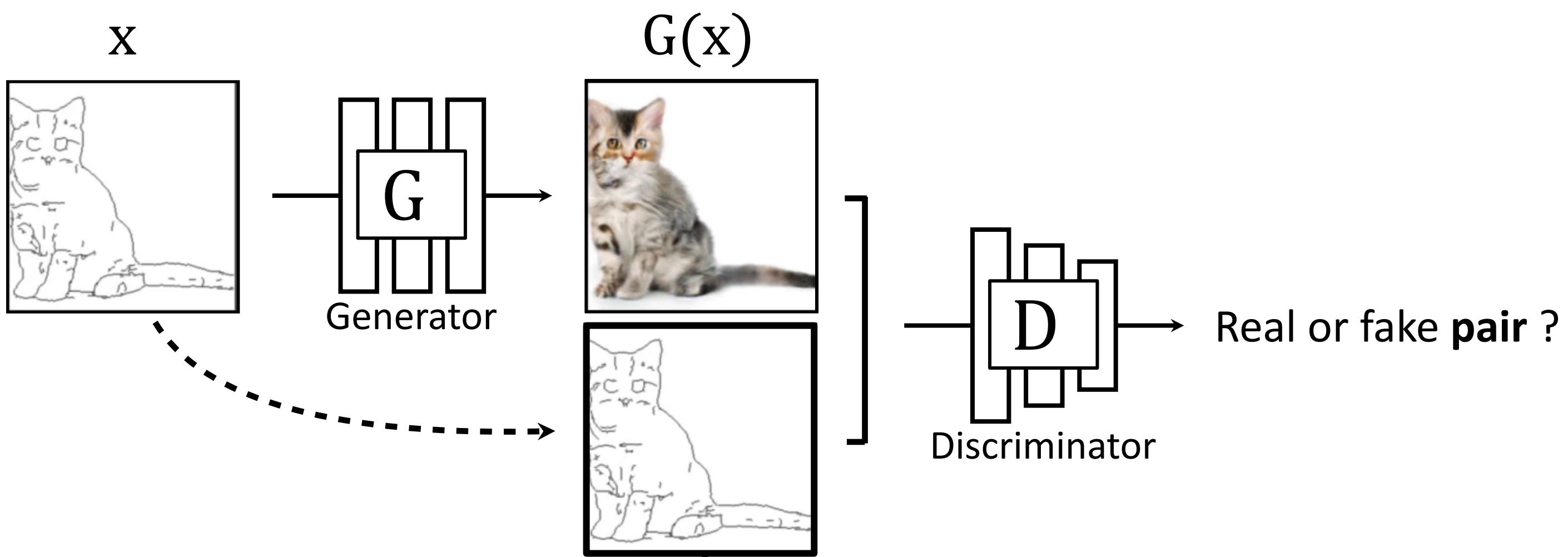


Discriminator

Real too ✓

## Learning objective

$$\min_G \max_D \mathbb{E}_x[\log(1 - D(G(x)))] + \mathbb{E}_y[\log D(y)]$$

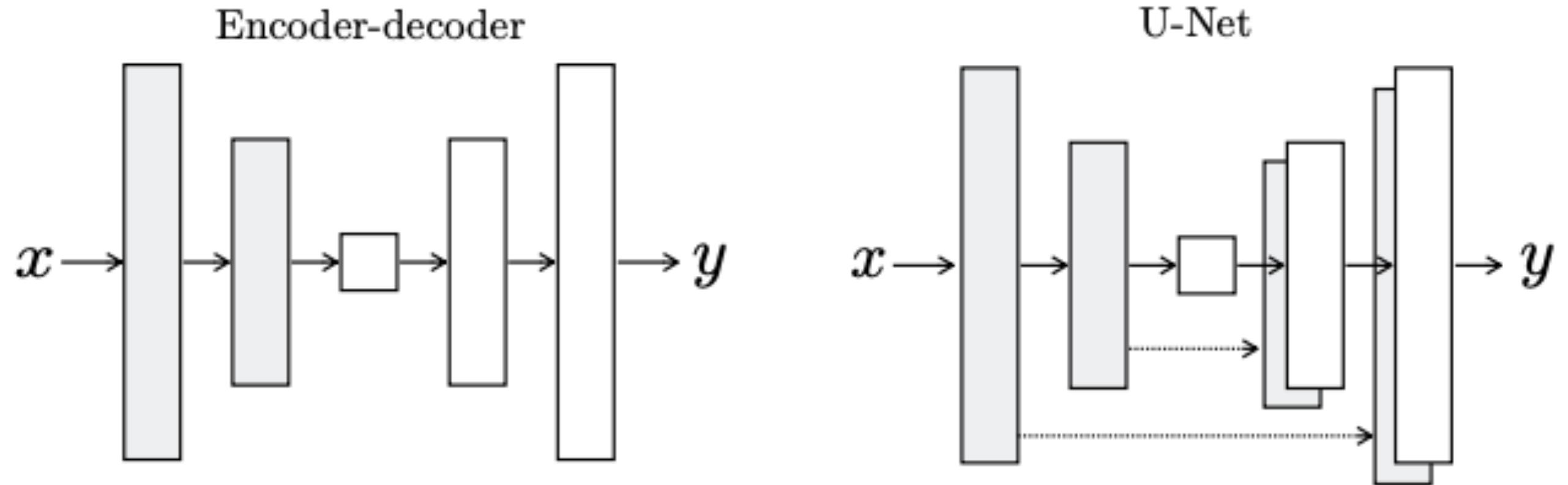


Learning objective

$$\min_G \max_D \mathbb{E}_x [\log(1 - D(\boxed{x}, G(x)))] + \mathbb{E}_{x,y} [\log D(\boxed{x}, y)]$$

Pix2pix [Isola et al., 2016]

# pix2pix Generator (U-Net)



U-Net [Ronneberger et al.]: popular CNN backbone for biomedical image segmentation

U-Net: preserve high-frequency information (e.g., edge) of the input image.

Encoder-decoder: lose high-frequency details due to the information bottleneck

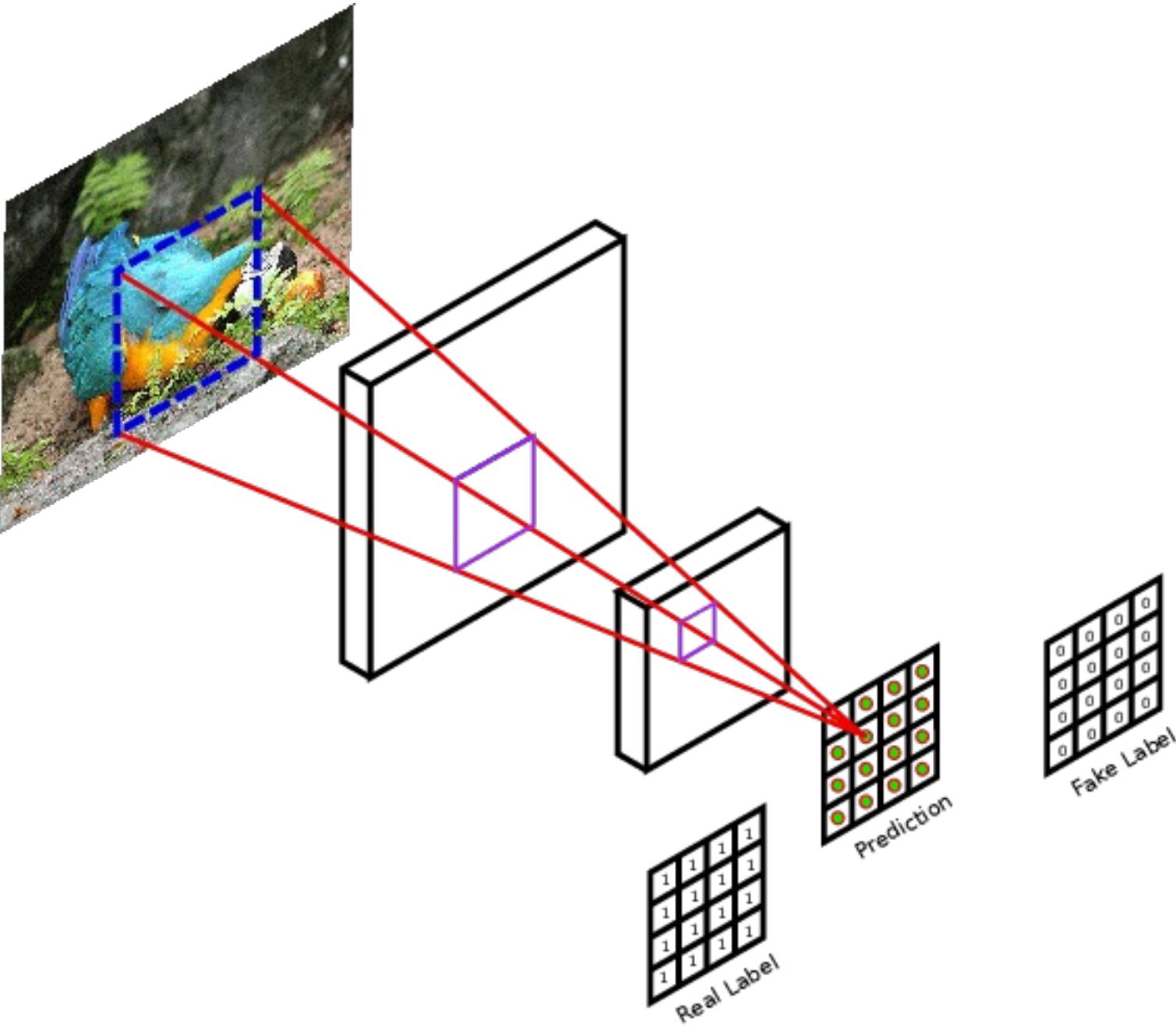
# pix2pix Generator (U-Net)



Generator design is critical for image quality.

cGAN (conditional GANs) loss: capture realism. L1 loss stabilizes training (faster convergence)

# pix2pix Discriminator (PatchGAN)



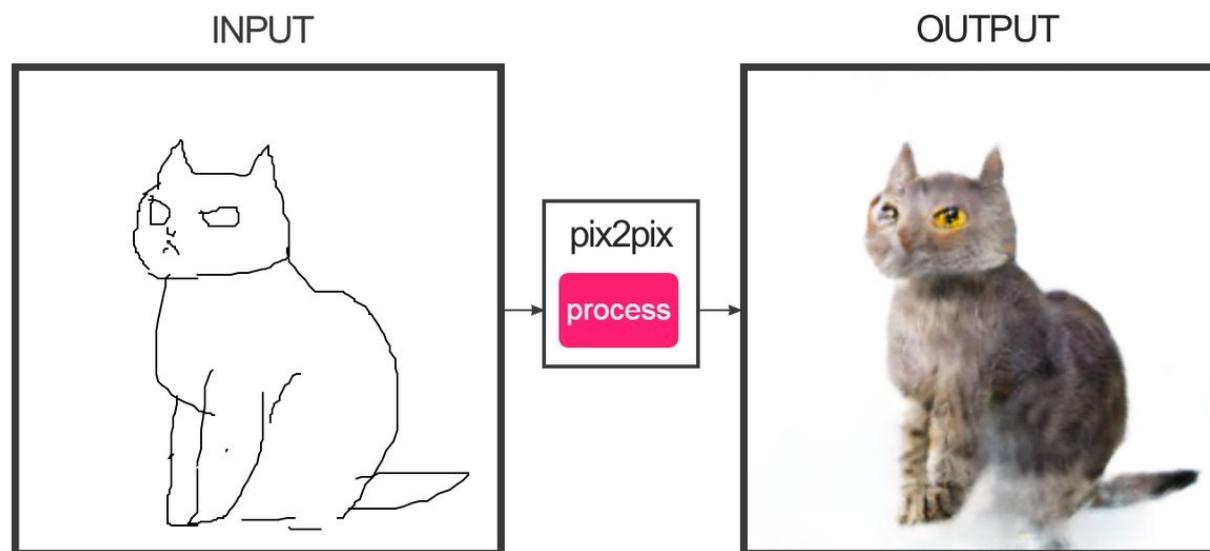
- Rather than penalizing if output *image* looks fake, penalize if each overlapping *patches* looks fake
- Focus on local visual cues (color, textures).
- Global structure: the input image has already encoded global structure. L1 loss can help as well.

## Advantages

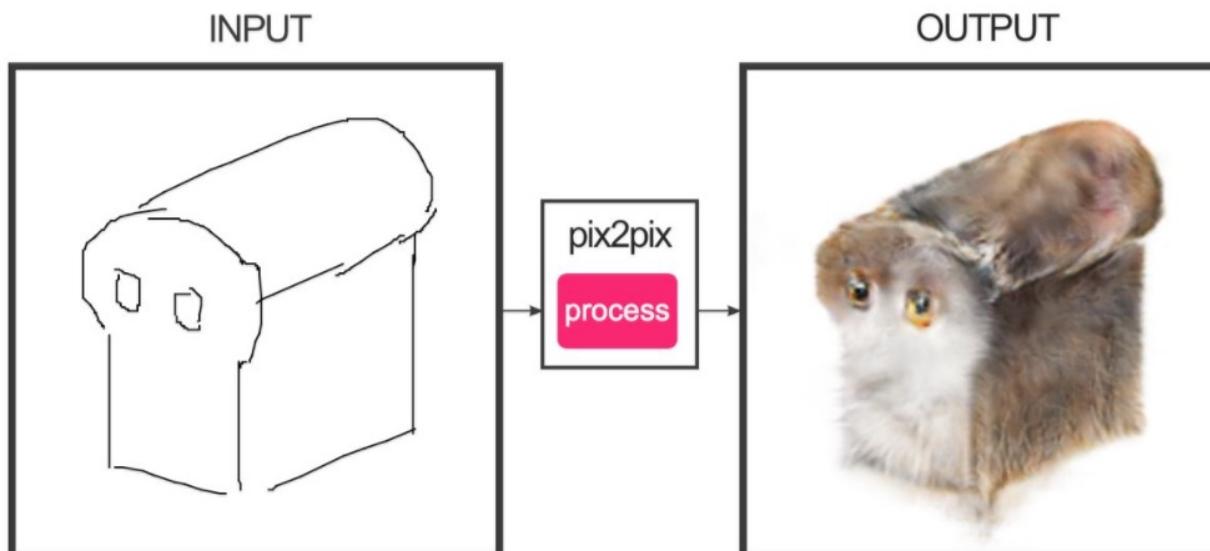
- Faster, fewer parameters
- More supervised observations
- Applies to arbitrarily large images

#edges2cats

[Christopher Hesse]



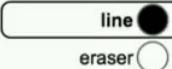
@gods\_tail



Ivy Tasi @ivymyt

edges2cats

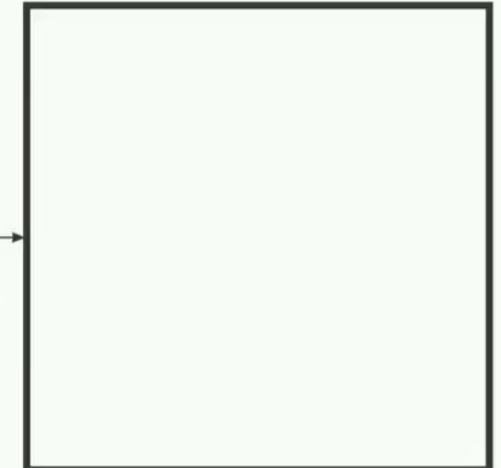
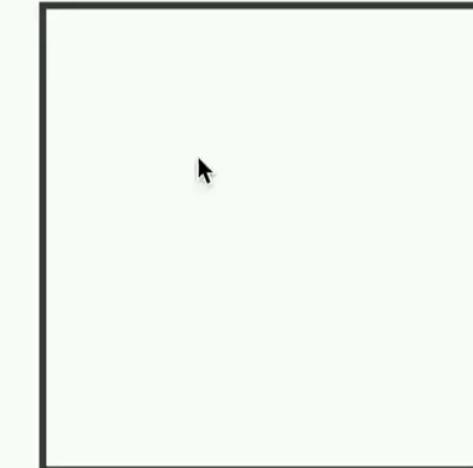
TOOL



line

eraser

INPUT



undo

clear

random

save

@matthematician



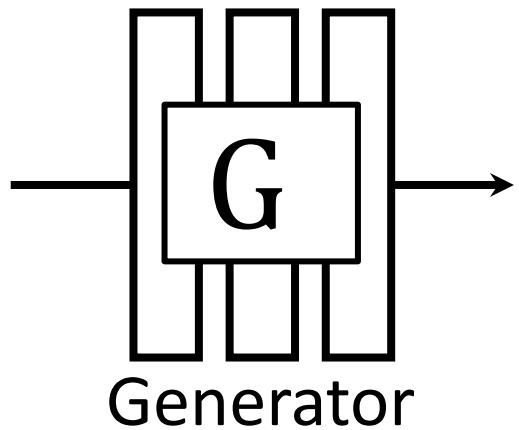
Vitaly Vidmirov @vvid

<https://affinelayer.com/pixsrv/>

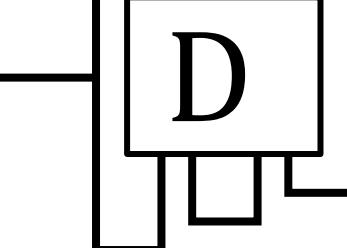
X



G(x)



Generator



Discriminator

Real or fake pair ?

Input: ~~Skatyskate~~ Output ~~Photo~~ Photo Color

# Automatic Colorization with pix2pix

Input



Output



Input



Output



Input



Output



Data from [Russakovsky et al. 2015]

# Automatic Colorization with pix2pix

Input



Output



Input



Output



Input



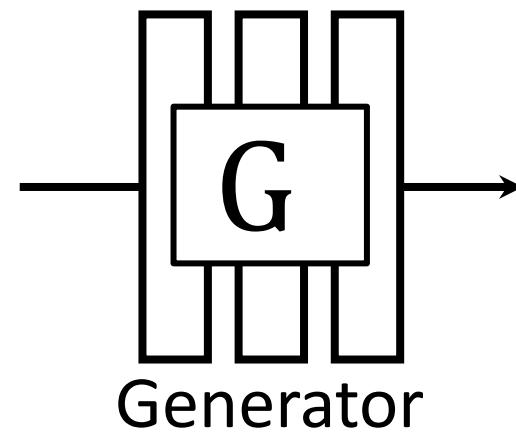
Output



Data from [Russakovsky et al. 2015]

$X$

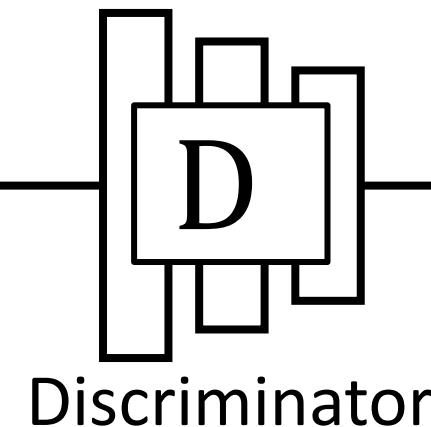
this bird is  
red with  
white and  
has a very  
short beak



$G(X)$



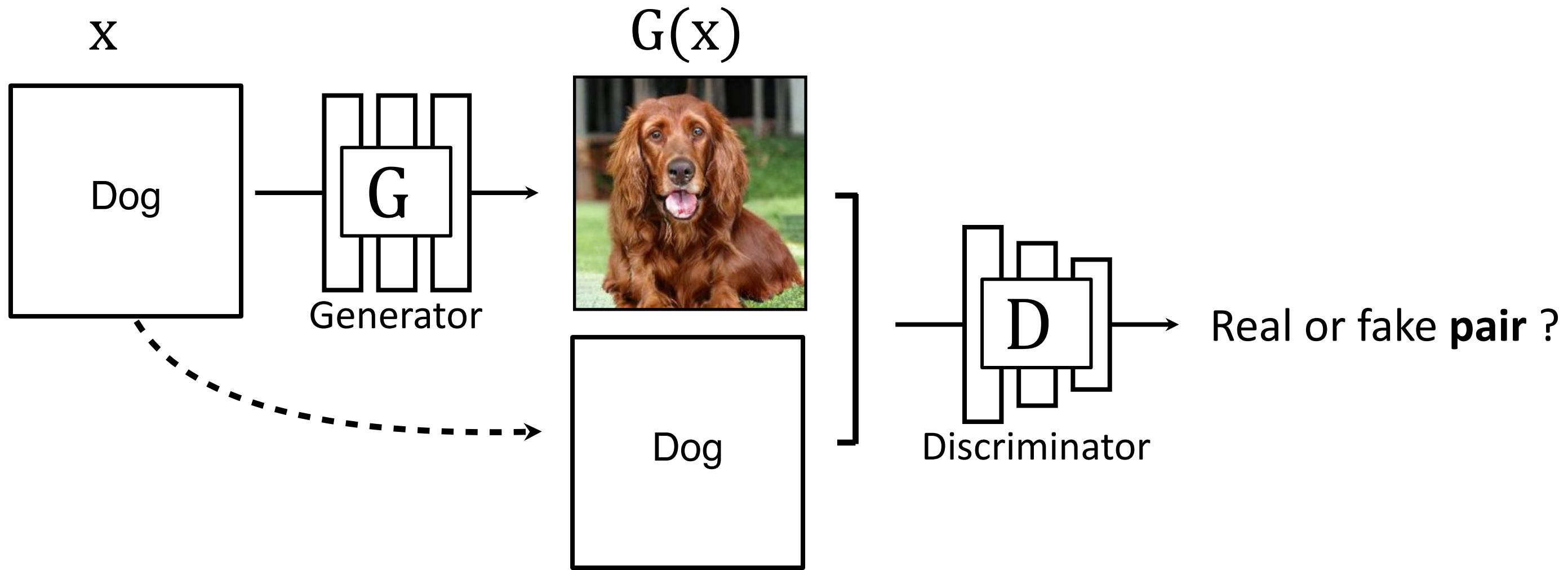
]



Real or fake pair ?

Input: **Text** → Output: **Photo**

Text-to-Image Synthesis



Input: **Class** → Output: **Photo**

## Class-conditional GANs

cGANs [Mirza and Osindero. 2014], SAGAN [Zhang et al., 2018], BigGAN [Brock et al., 2019]

StyleGAN-XL [Sauer et al., 2022]

# BigGAN

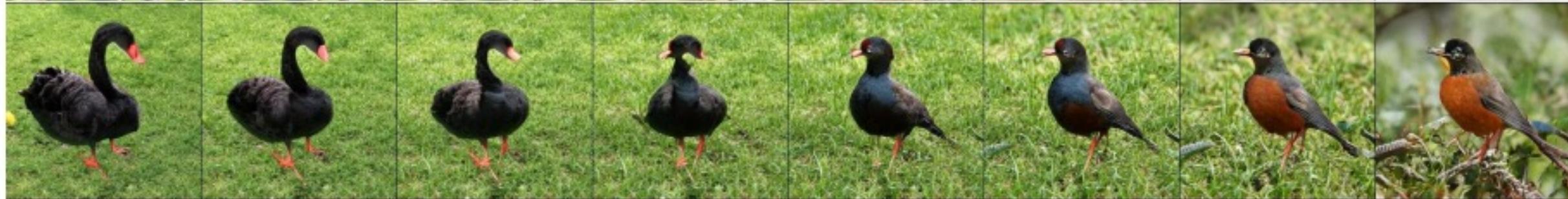


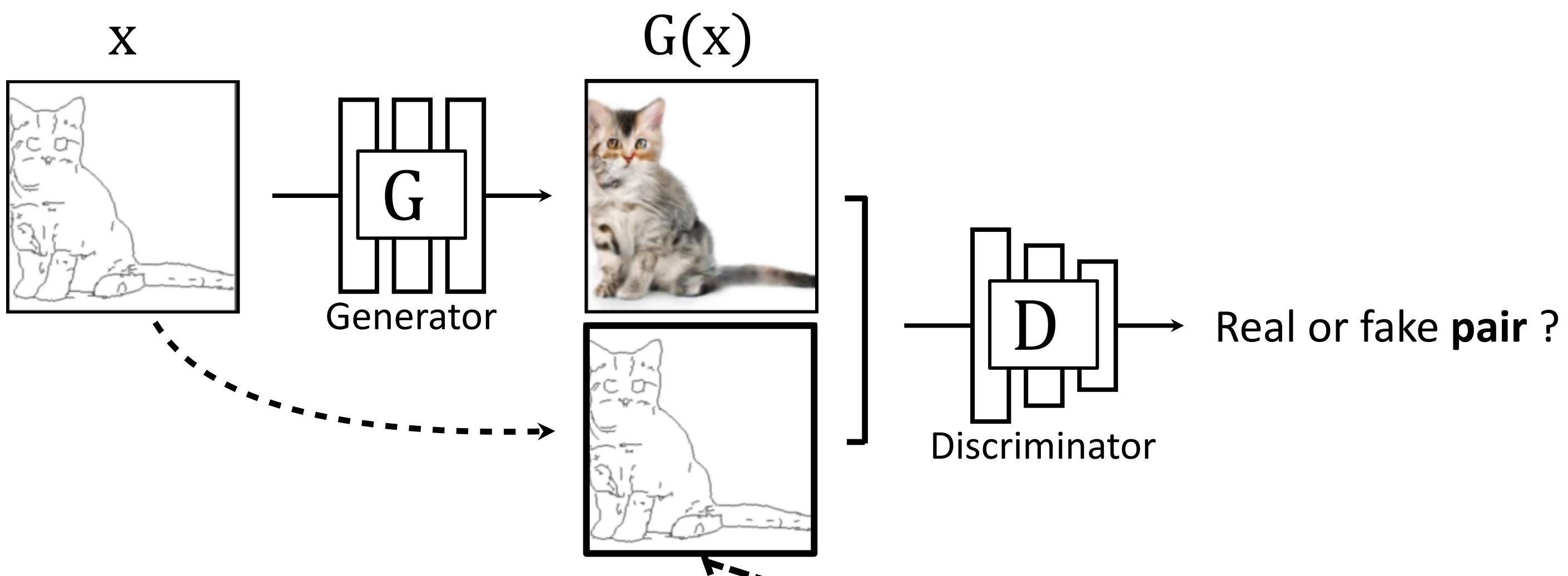
(a)  $128 \times 128$

(b)  $256 \times 256$

(c)  $512 \times 512$

(d)





Learning objective

$$\min_G \max_D \mathbb{E}_x[\log(1 - D(\boxed{x}, G(x)))] + \mathbb{E}_{x,y}[\log D(\boxed{x}, y)]$$

Pix2pix [Isola et al., 2016]

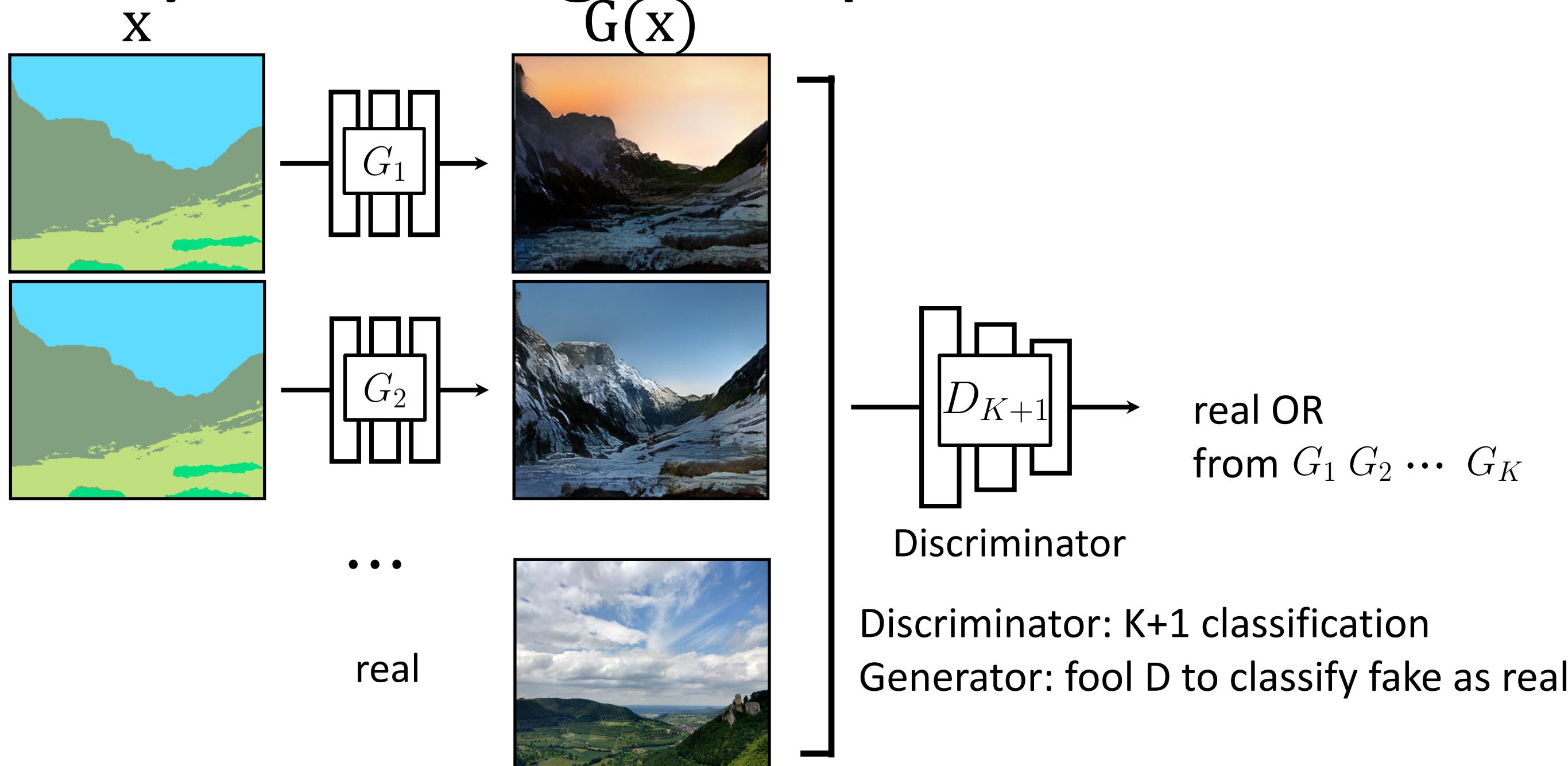
# Limitations

- One-to-one mapping.
- Low-resolution output.
- Requires paired training data

# Improving Conditional GANs

- Multimodal synthesis.
- High-resolution synthesis.
- Model training without pairs (next lecture)

# Synthesizing Multiple Results



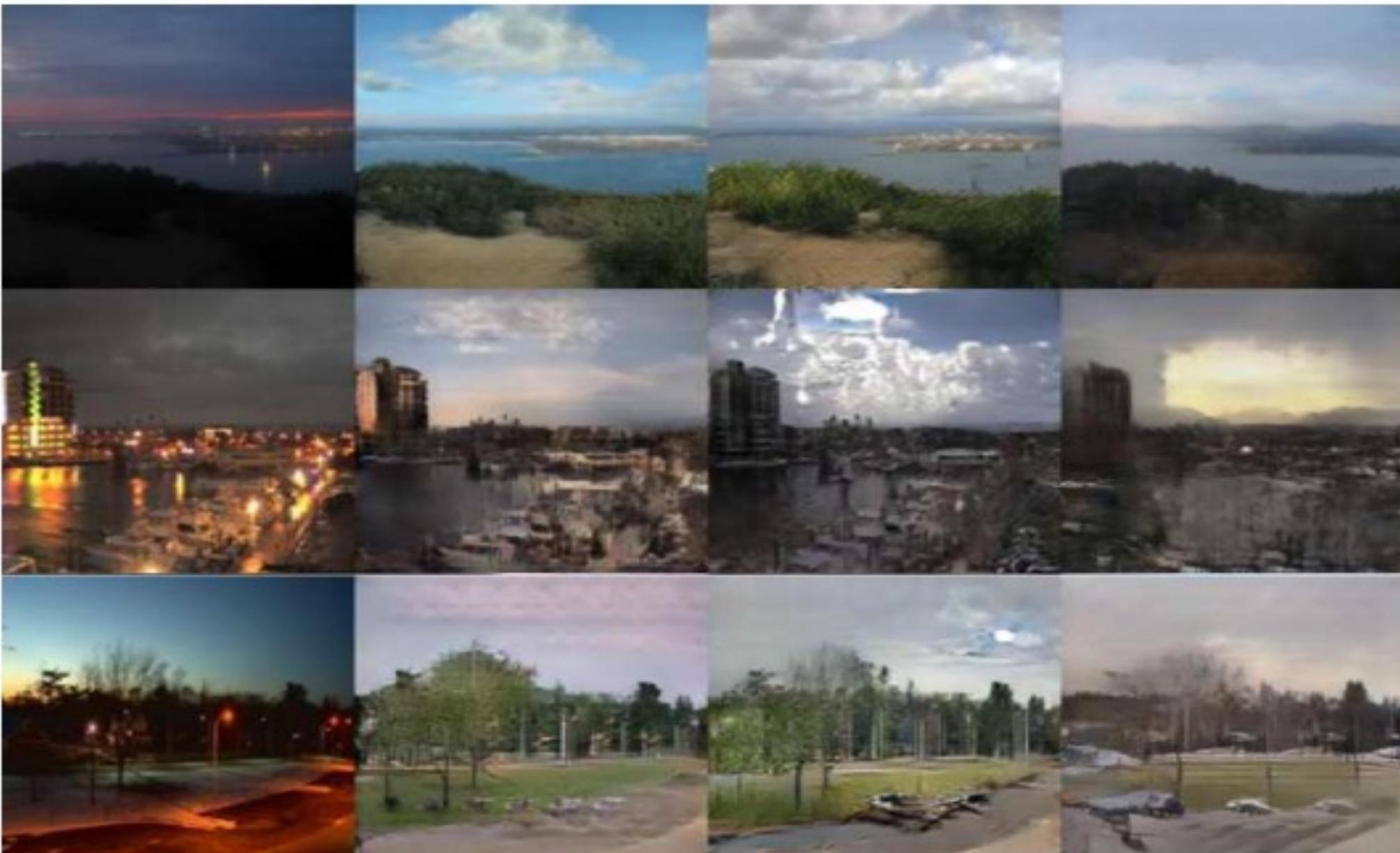
# Synthesizing Multiple Results

Night input

Day output 1

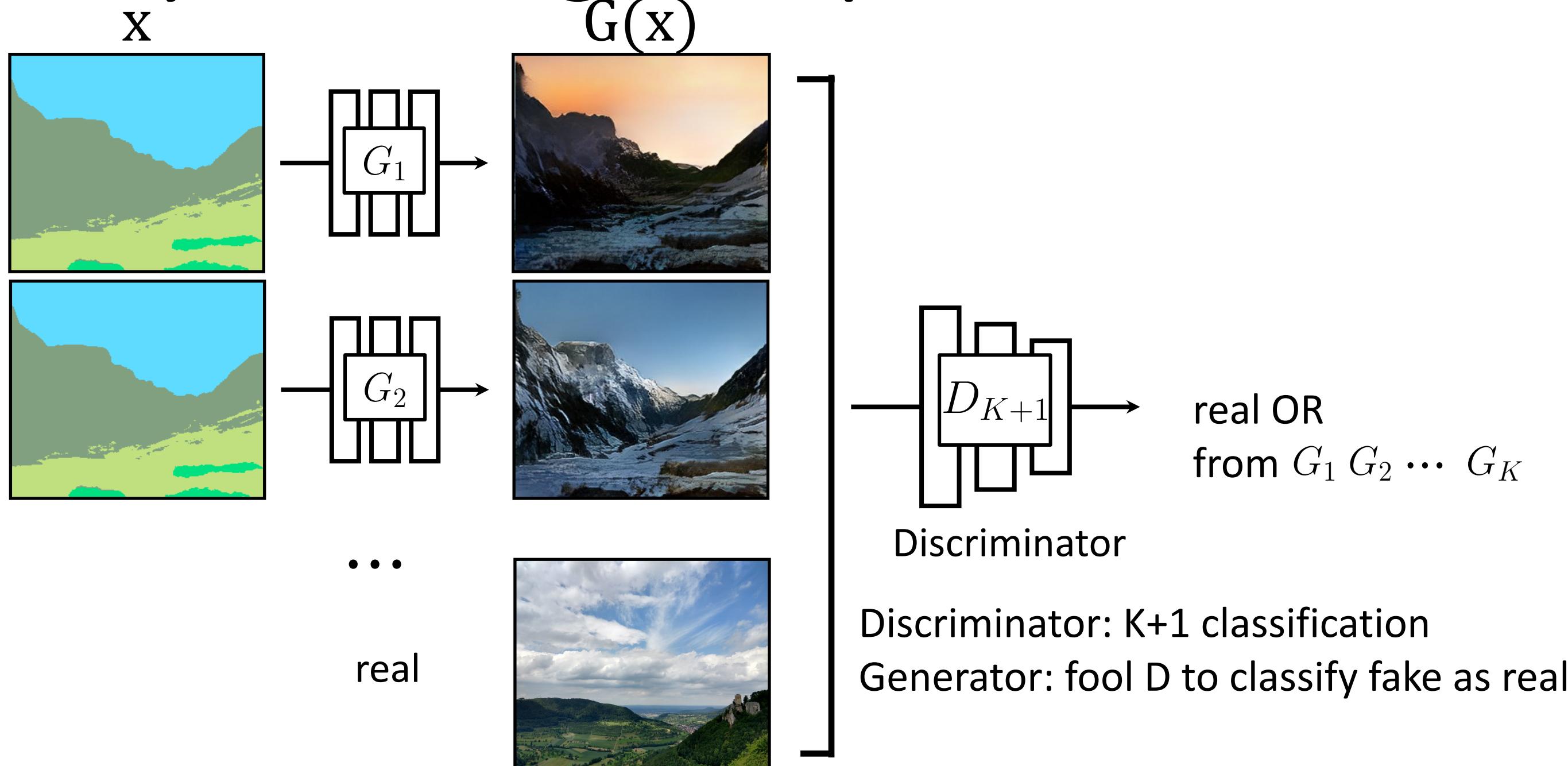
Day output 2

Day output 3



Multi-agent Diverse GANs [Ghosh et al., CVPR 2018]

# Synthesizing Multiple Results



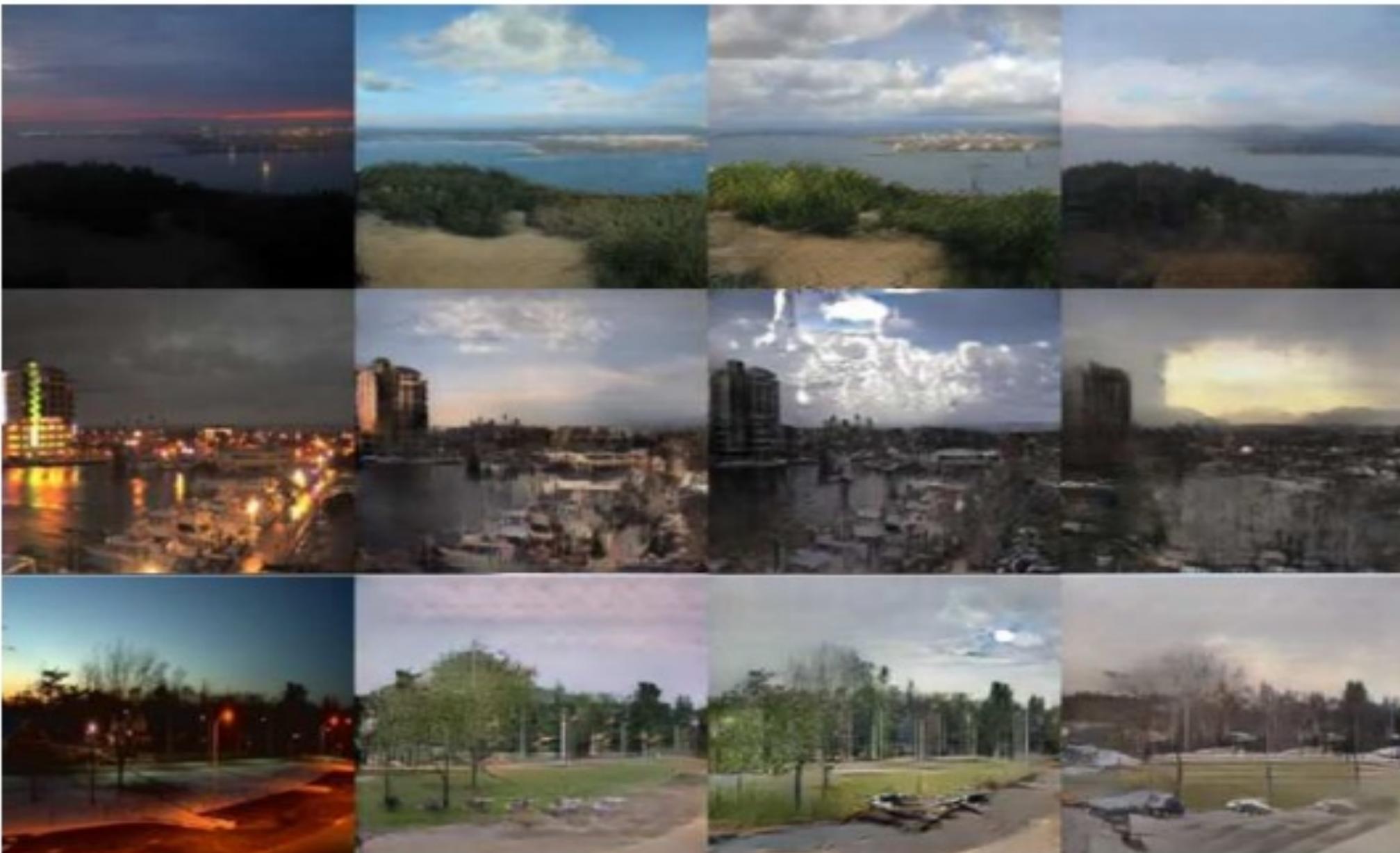
# Synthesizing Multiple Results

Night input

Day output 1

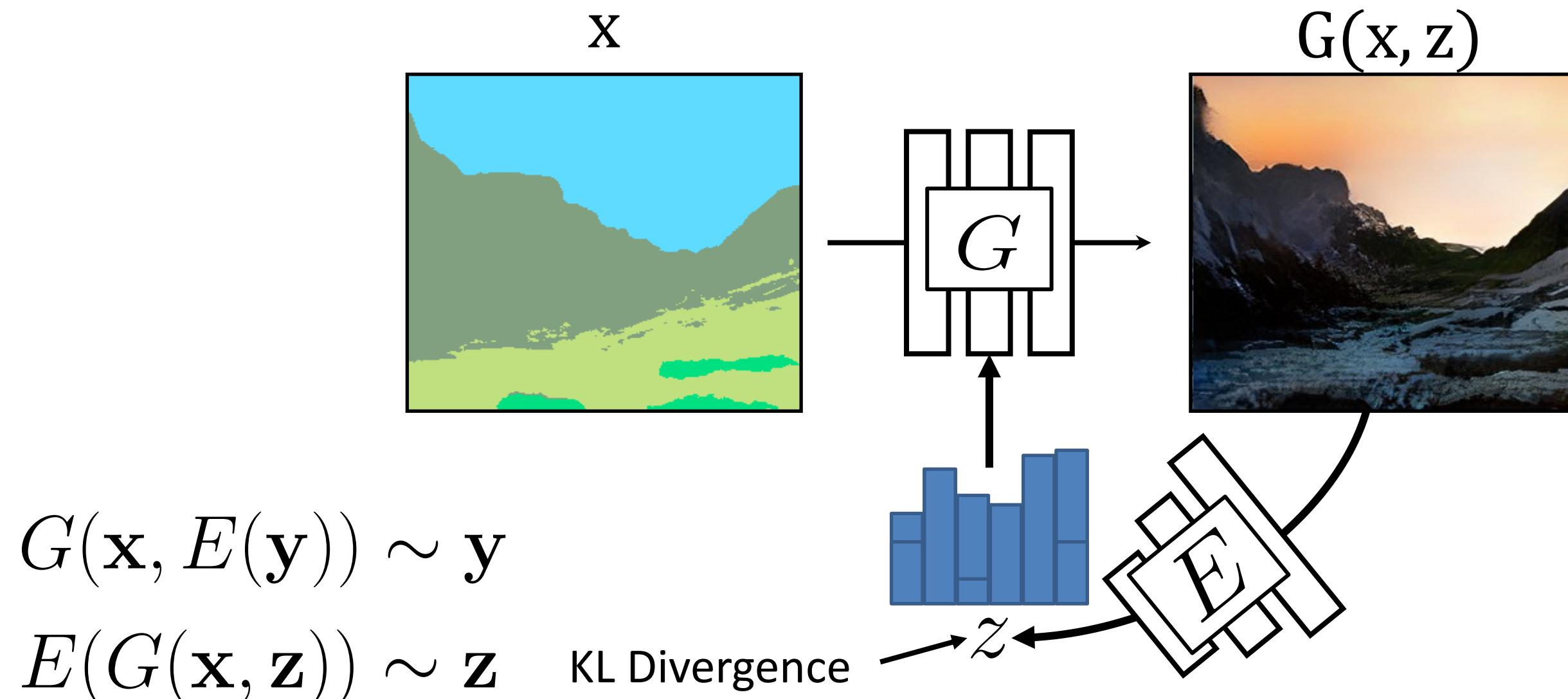
Day output 2

Day output 3



Multi-agent Diverse GANs [Ghosh et al., CVPR 2018]

# Synthesizing Multiple Results



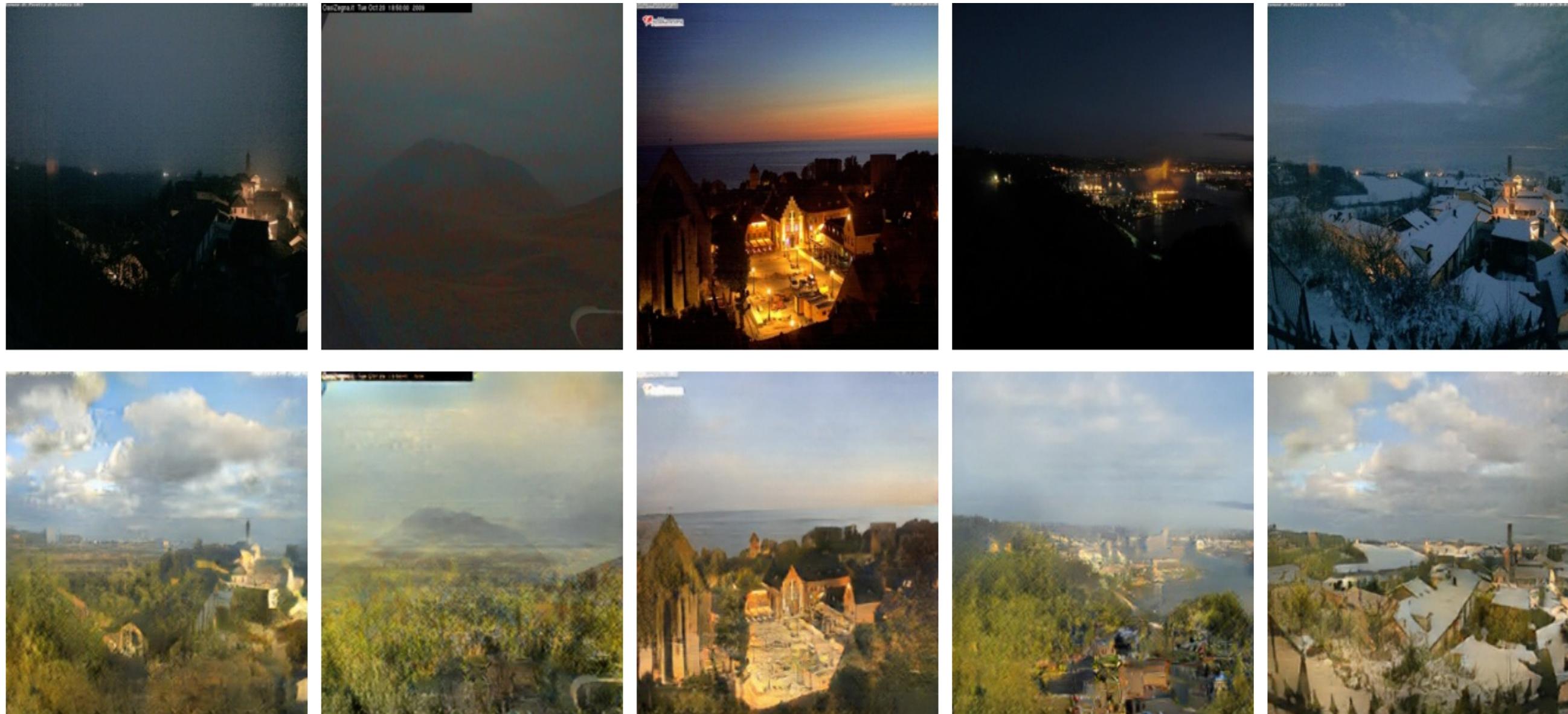
VAE-GAN [Larsen et al., 2016], BicycleGAN [Zhu et al., 2017]

# Synthesizing Multiple Results



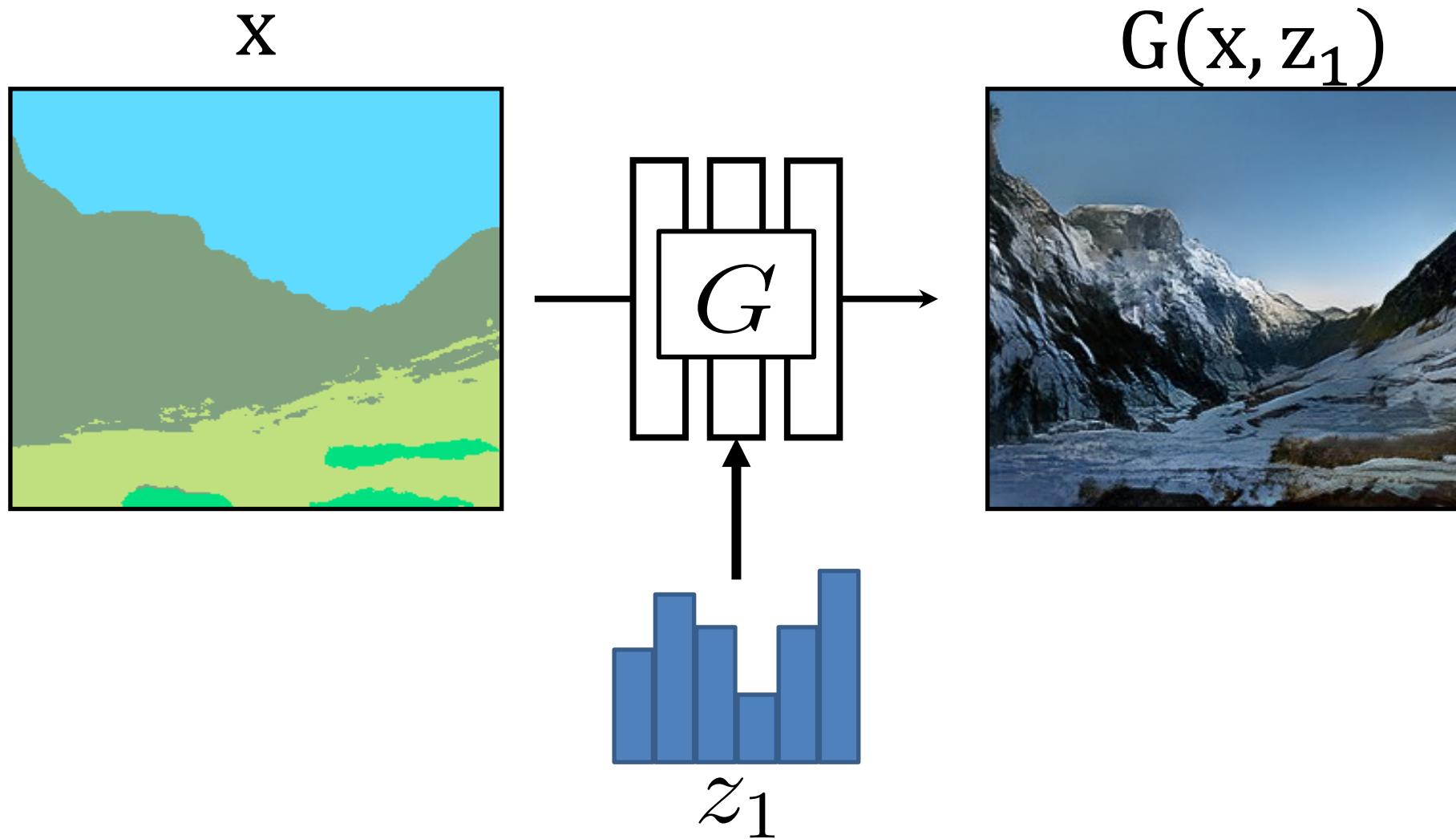
BicycleGAN [Zhu et al., 2017]

# Synthesizing Multiple Results



BicycleGAN [Zhu et al., 2017]

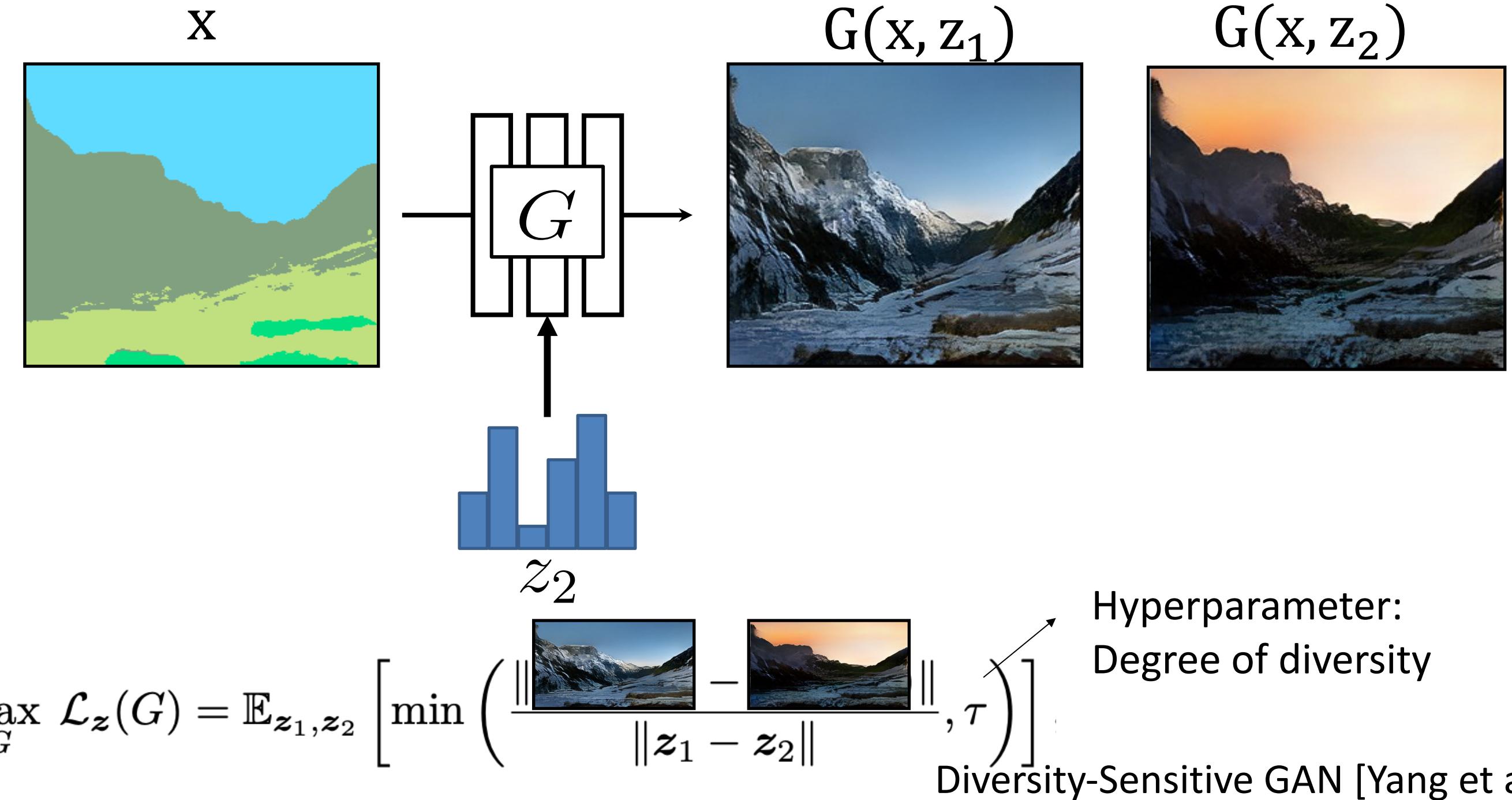
# Synthesizing Multiple Results



$$\max_G \mathcal{L}_z(G) = \mathbb{E}_{z_1, z_2} \left[ \min \left( \frac{\|G(\mathbf{x}, z_1) - G(\mathbf{x}, z_2)\|}{\|z_1 - z_2\|}, \tau \right) \right],$$

Hyperparameter:  
Degree of diversity  
Diversity-Sensitive GAN [Yang et al., 2019]

# Synthesizing Multiple Results



# Synthesizing Multiple Results



$$\max_G \mathcal{L}_z(G) = \mathbb{E}_{z_1, z_2} \left[ \min \left( \frac{\|G(\mathbf{x}, z_1) - G(\mathbf{x}, z_2)\|}{\|z_1 - z_2\|}, \tau \right) \right]$$

Hyperparameter:  
Degree of diversity

Diversity-Sensitive GAN [Yang et al., 2019]