

Data Structures and Algorithms

Part 10: Binary Heap

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Horton D4.12

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- 1 What is a Binary Heap
- 2 What is it used for?
- 3 Insertion
- 4 Removal
- 5 Heap Build
- 6 Heap Sort
- 7 Array-based Implementation

What is a Binary Heap

A Binary Heap is

- 1 a complete binary tree. . .
- 2 where the nodes contain objects with keys. . .
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 - all leaves are at depth h or depth $h - 1$; and
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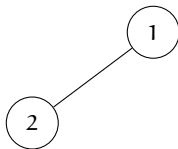
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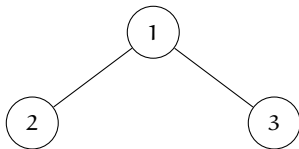
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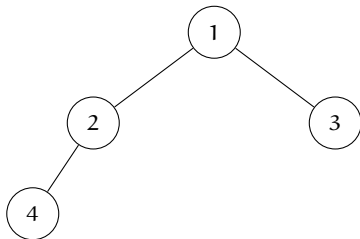
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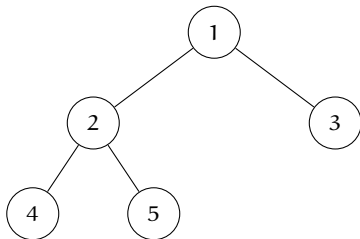
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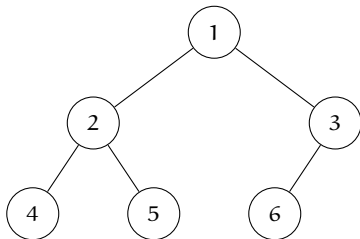
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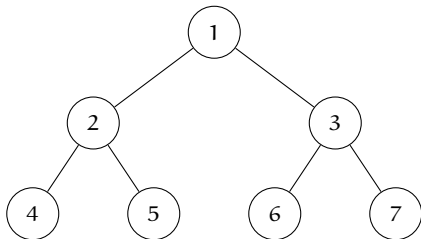
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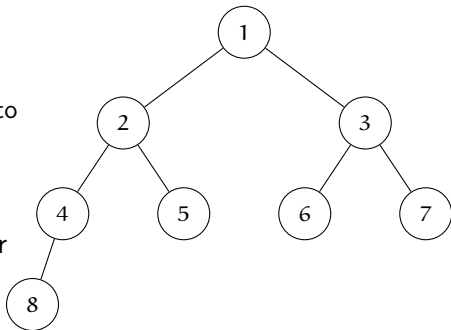
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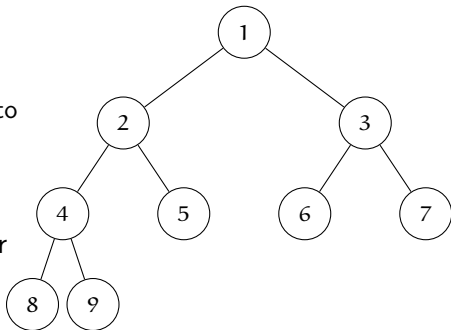
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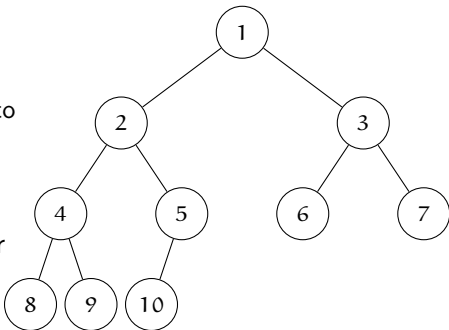
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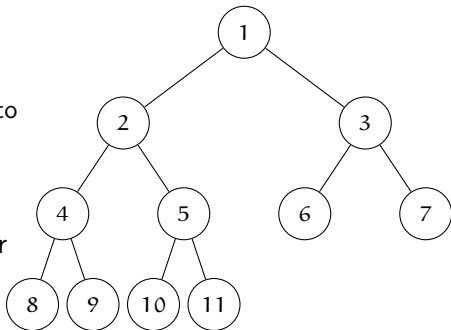
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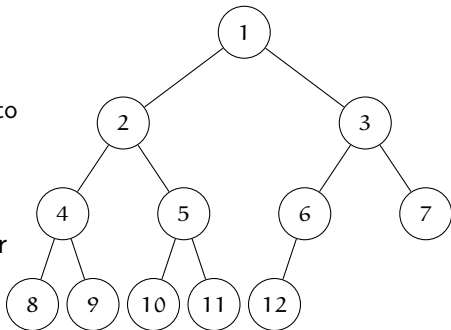
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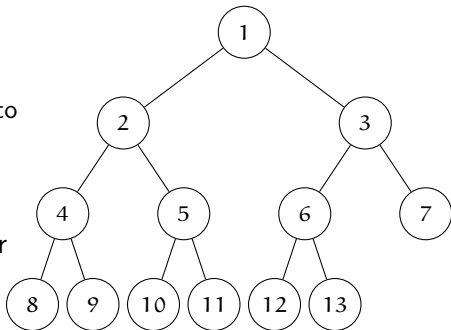
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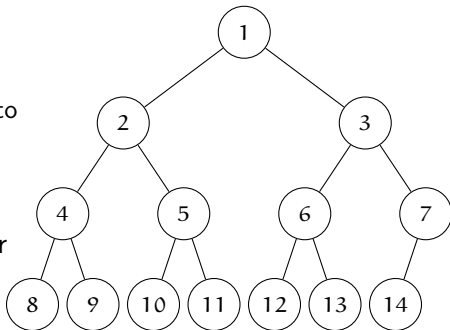
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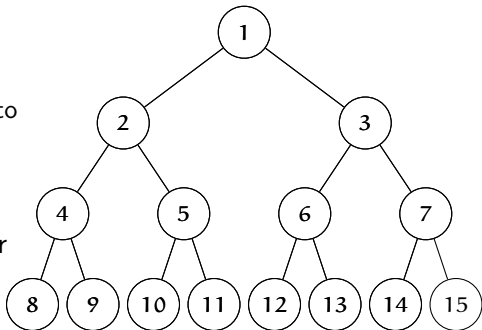
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Heap-Order Property

min-heap For every node, the key is greater than or equal to the key in the node's parent

- The **smallest** key is at the root

max-heap For every node, the key is less than or equal to the key in the node's parent

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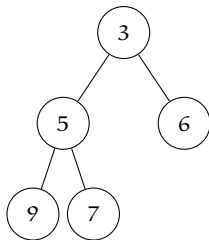
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Insertion – add an object to the heap

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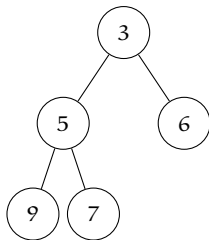
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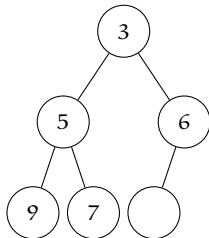
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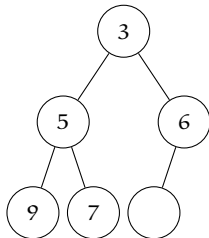
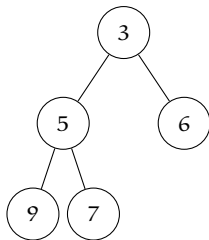


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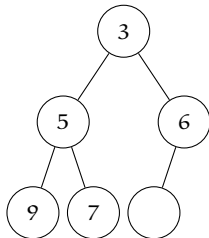
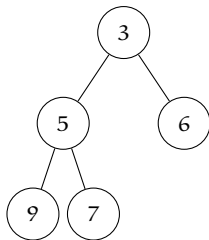
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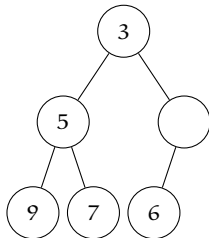
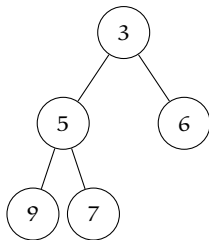
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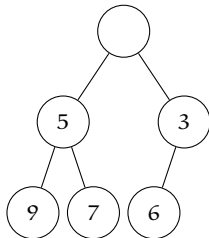
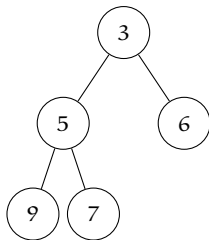
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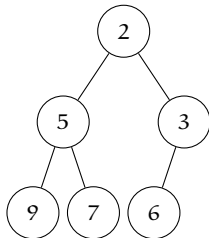
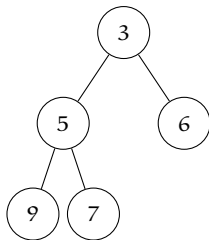
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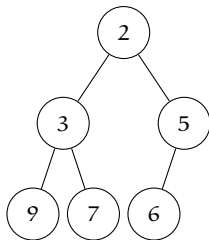
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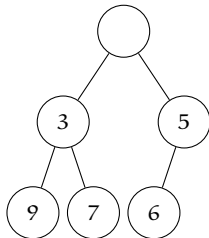
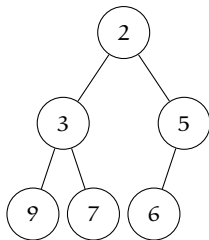
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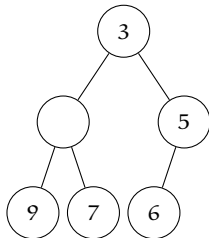
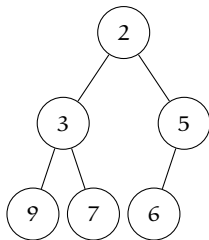
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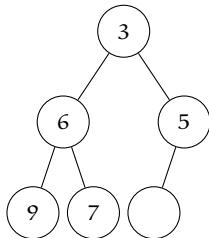
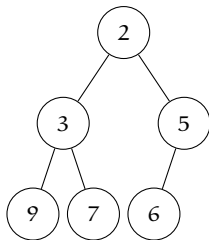
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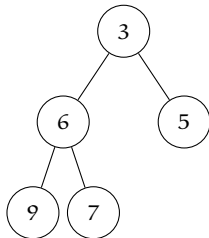
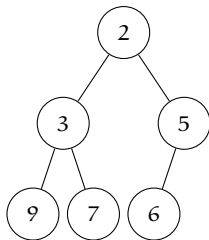
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Run Times for insertion and removal

In the worst cases:

Inserting one item involves the “hole” being moved from the lowest leaf to the root

In both cases the run time is (asymptotically) proportional to the height of the tree

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If the heap contains n items, the times are $\mathcal{O}(\log_2 n)$

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- The Heap ADT includes a method for bulk loading of many objects into the heap at one time
- The method is (usually) called `heapBuild`
- Its run time is $\mathcal{O}(n)$, where n is the number of objects in the heap (after all the new ones have been loaded)
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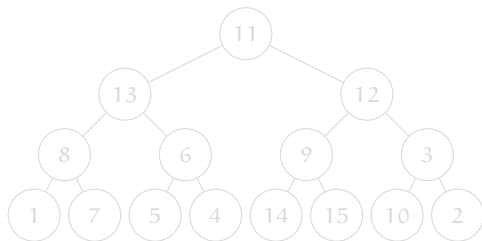
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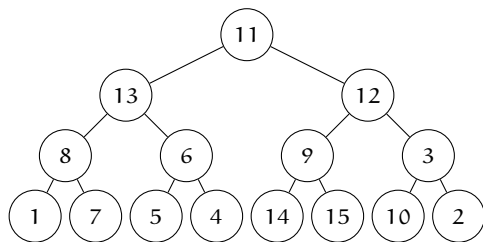


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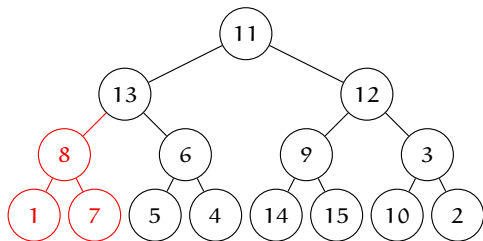


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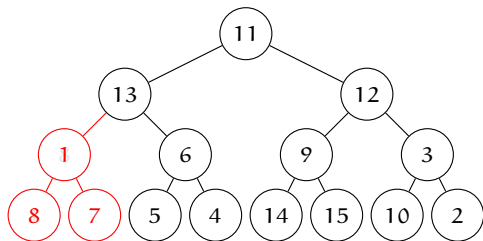


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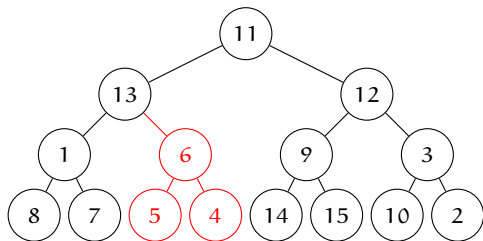


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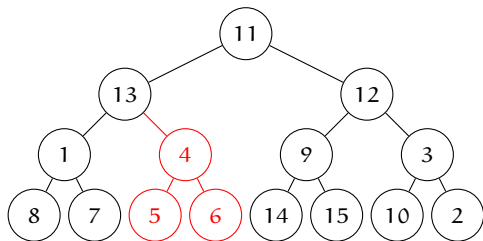


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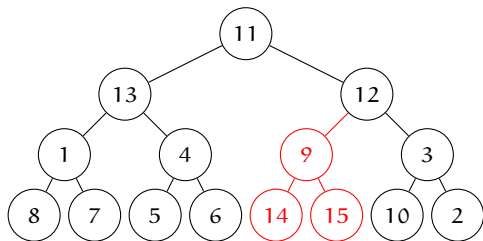


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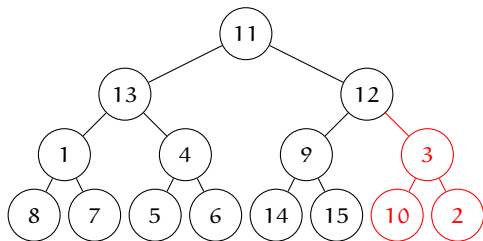


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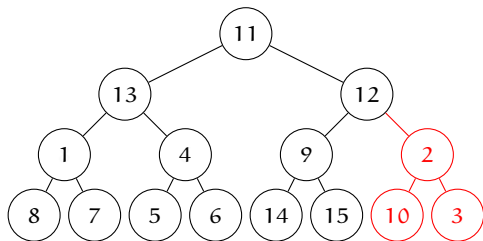


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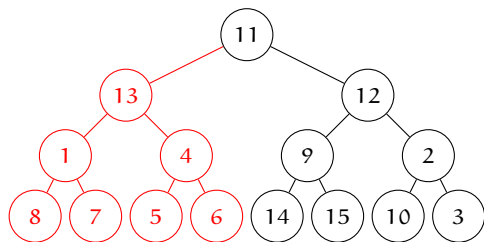


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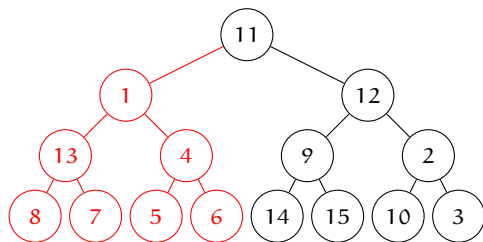


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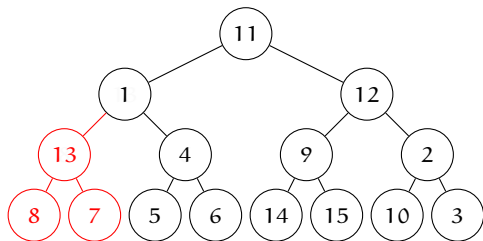


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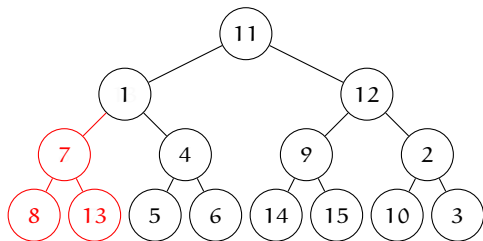


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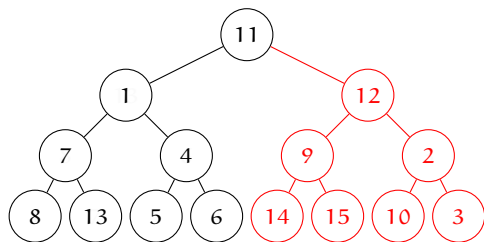


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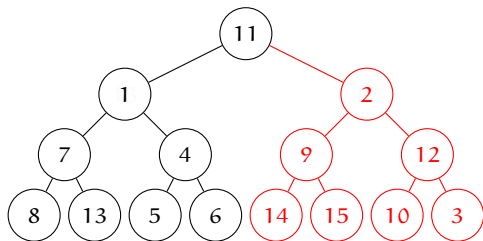


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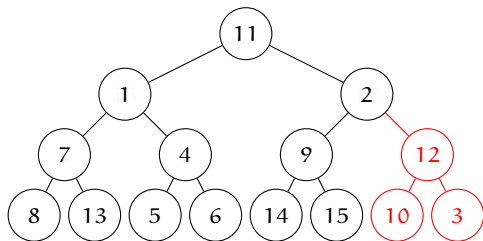


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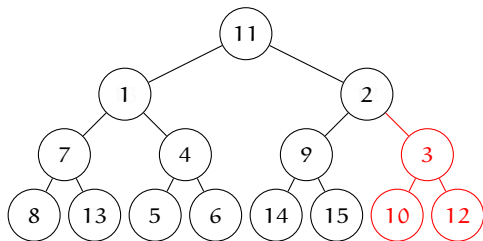


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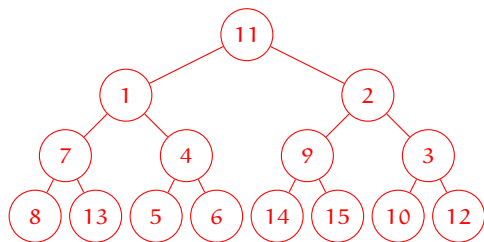


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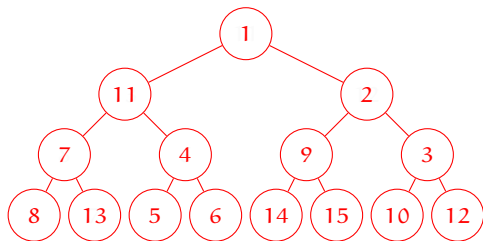


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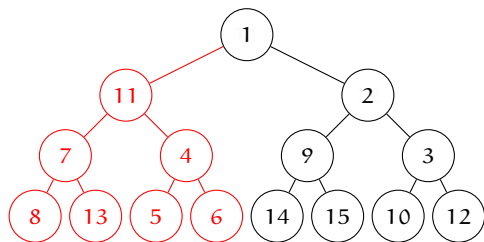


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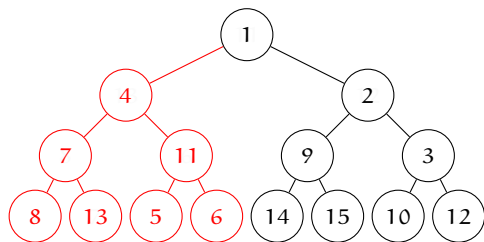


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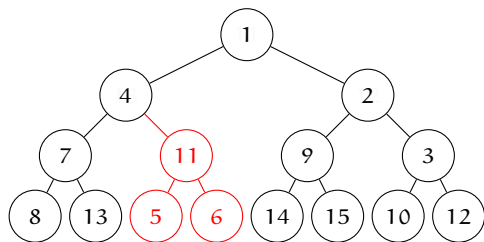


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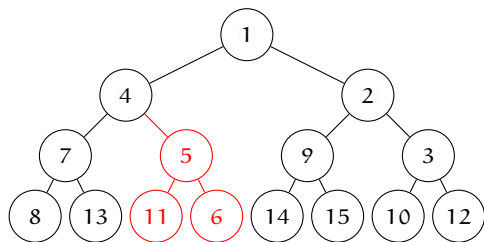


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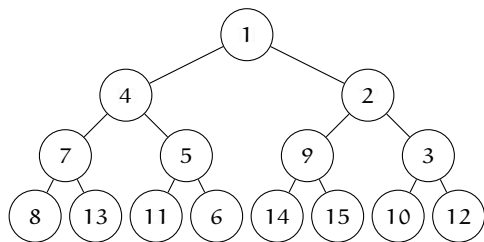


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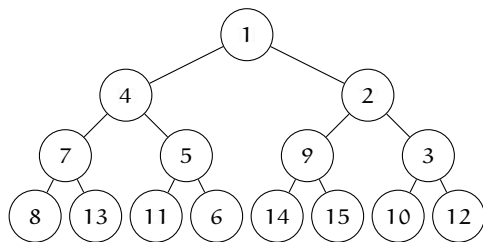


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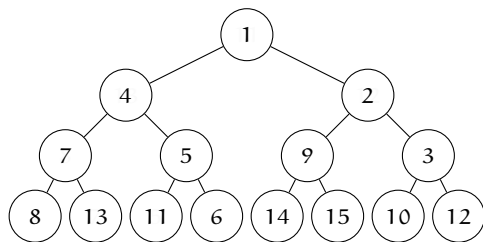


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 - run time $\mathcal{O}(n)$
- 2 Output objects in order, one-by-one using `removeFirst`
 - run time $\mathcal{O}(n \log_2 n)$
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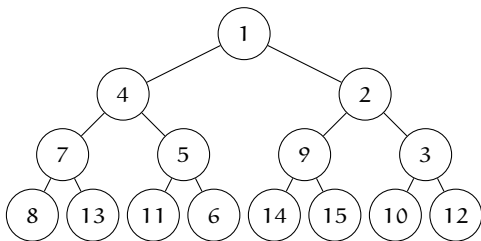
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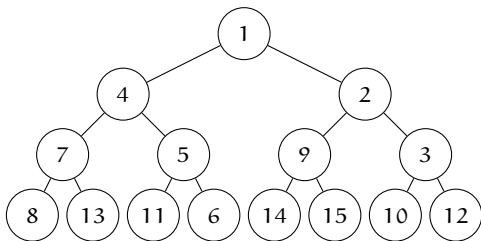
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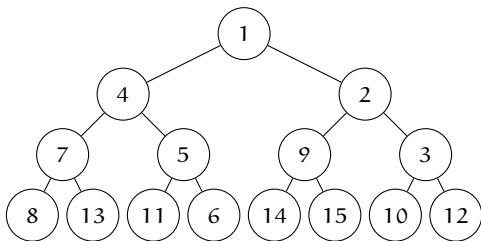
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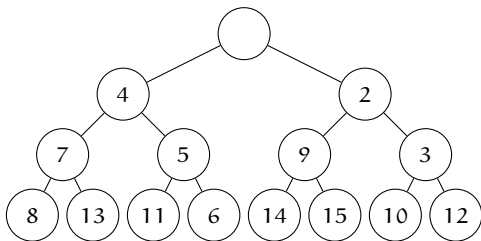
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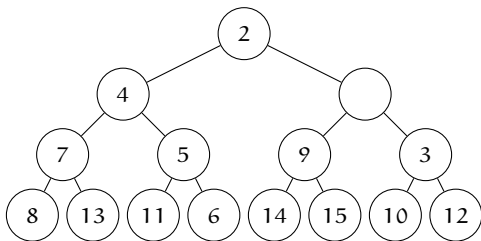
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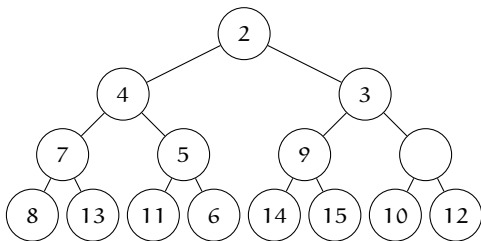
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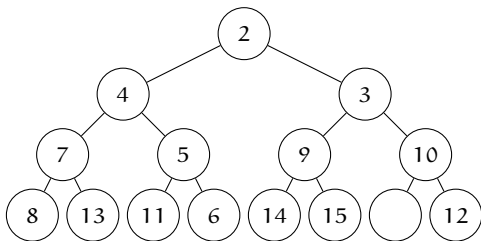
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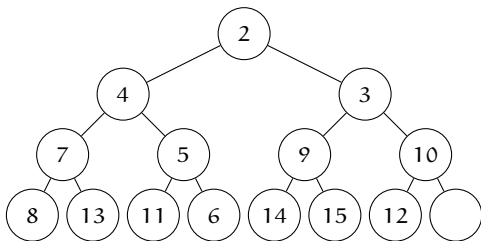
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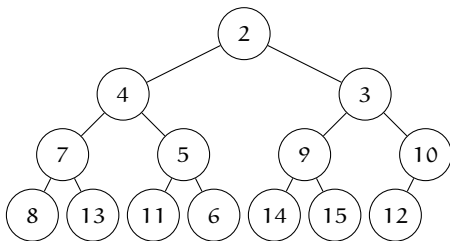
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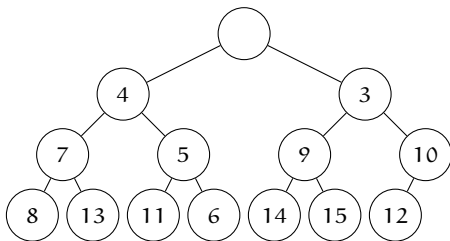
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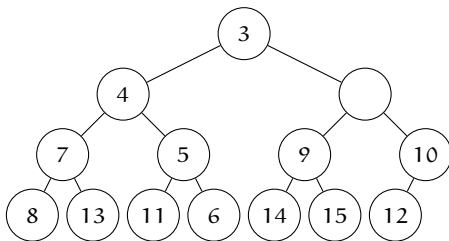
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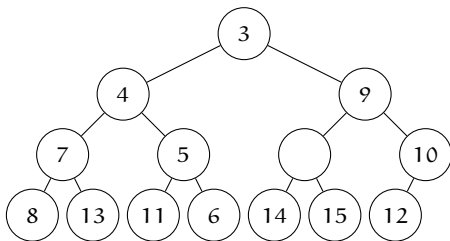
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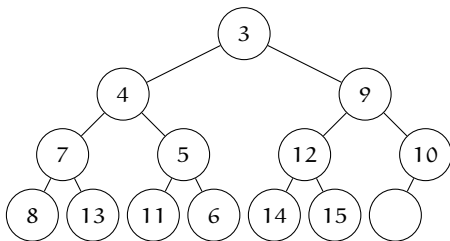
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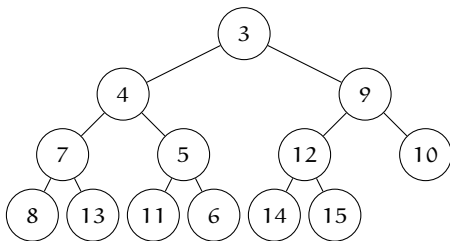
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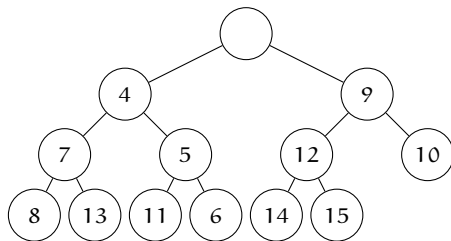
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Binary Heap ADT Interface

- ❶ Constructors – may accept
 - indicator for min-heap or max-heap
 - Comparator
- ❷ insert or add
- ❸ remove or removeFirst or removeMin
- ❹ heapBuild
- ❺ size
- ❻ isEmpty

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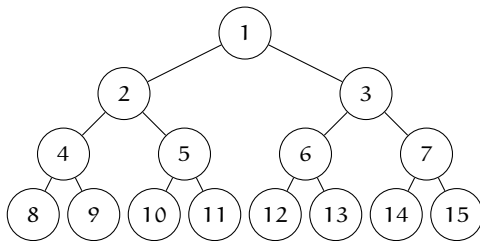
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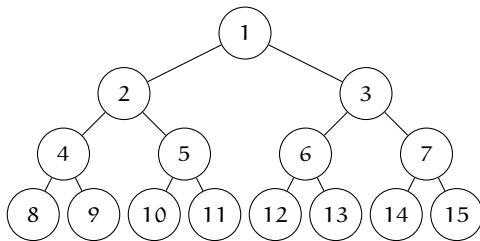
Binary Heap Implementation

- 1 The heap is not implemented as a tree but as an array
- 2 The root is at index 1
- 3 In general, if a node is at index k
 - 4 its parent is at $\lfloor k/2 \rfloor$
 - 5 its left child is $2k$
 - 6 its right child is $2k+1$
- 7 Position index 0 is kept empty



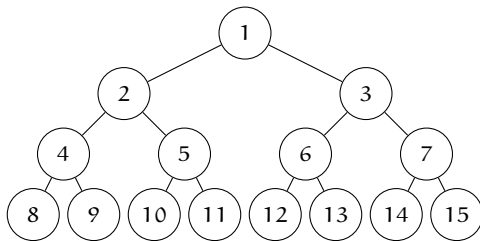
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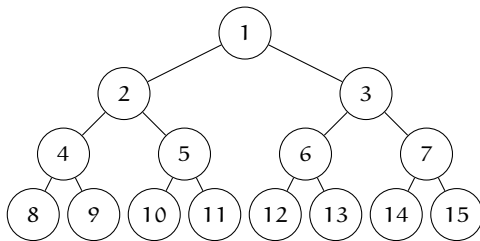
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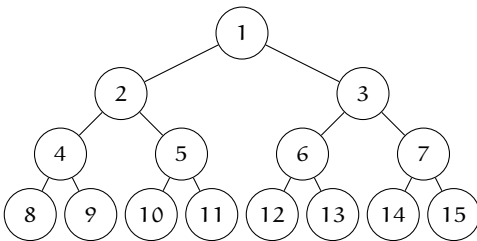
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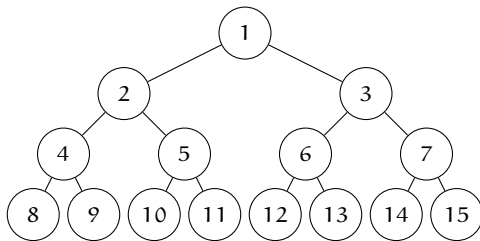
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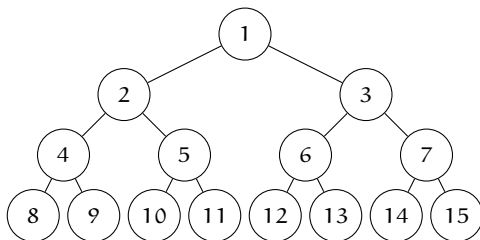
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