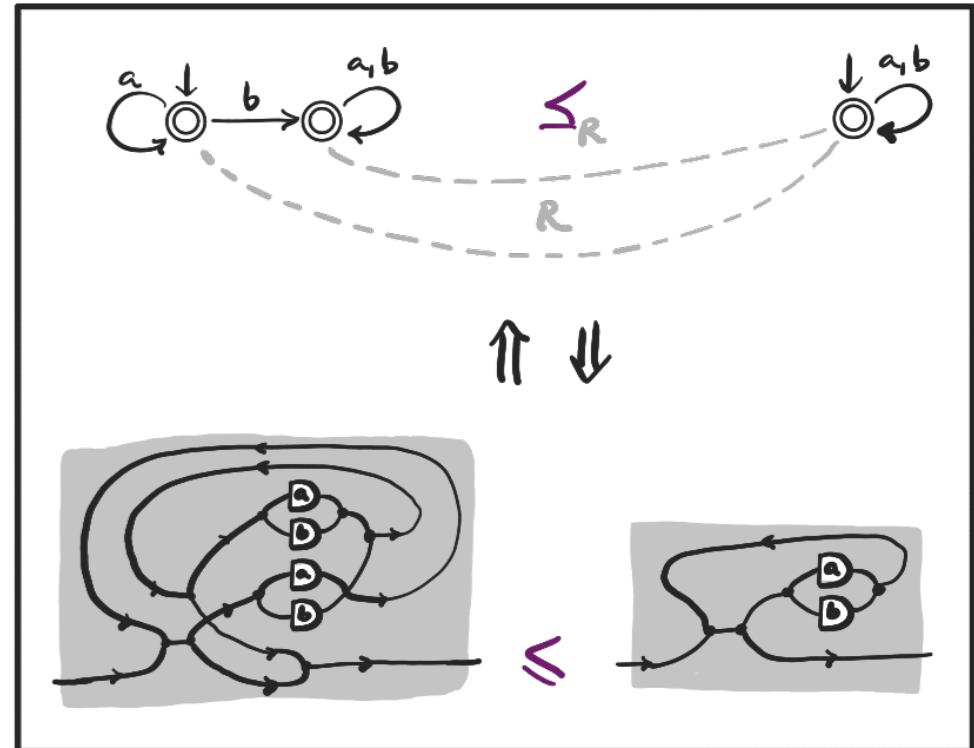


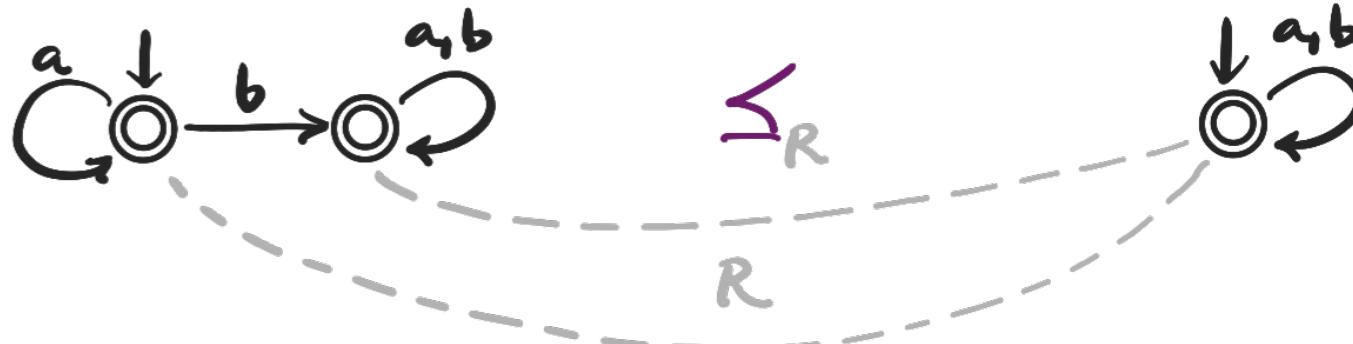
# A COMPLETE DIAGRAMMATIC CALCULUS for AUTOMATA SIMULATION



Thibaut Antoine<sup>1</sup>, Robin Piedeleu<sup>2</sup>,  
Alexandra Silva<sup>2</sup>, Fabio Zanasi<sup>2</sup>

<sup>1</sup>ENS Rennes <sup>2</sup>UCL

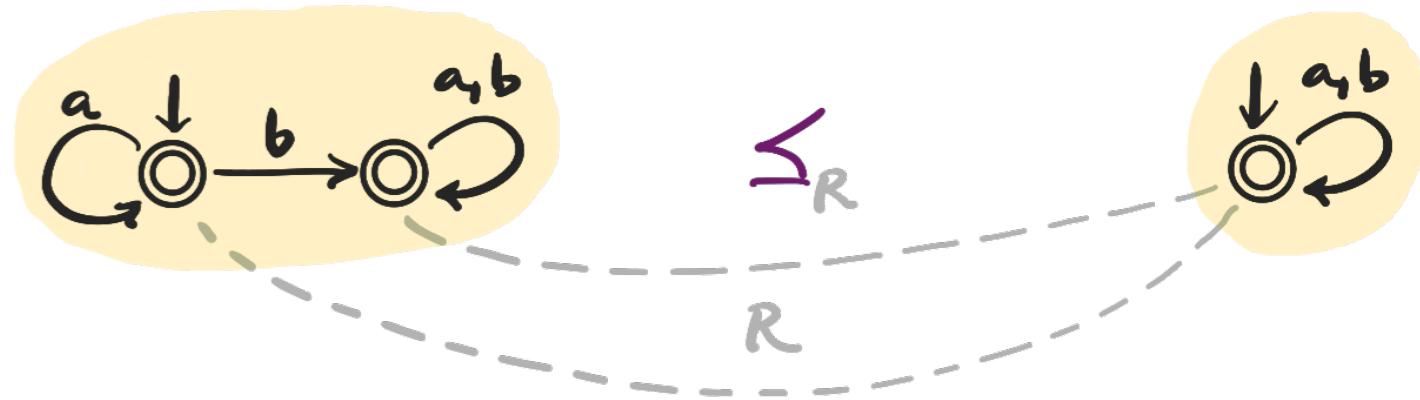
# ONE-SLIDE SYNOPSIS



SOUNDNESS  $\uparrow\downarrow$  COMPLETENESS



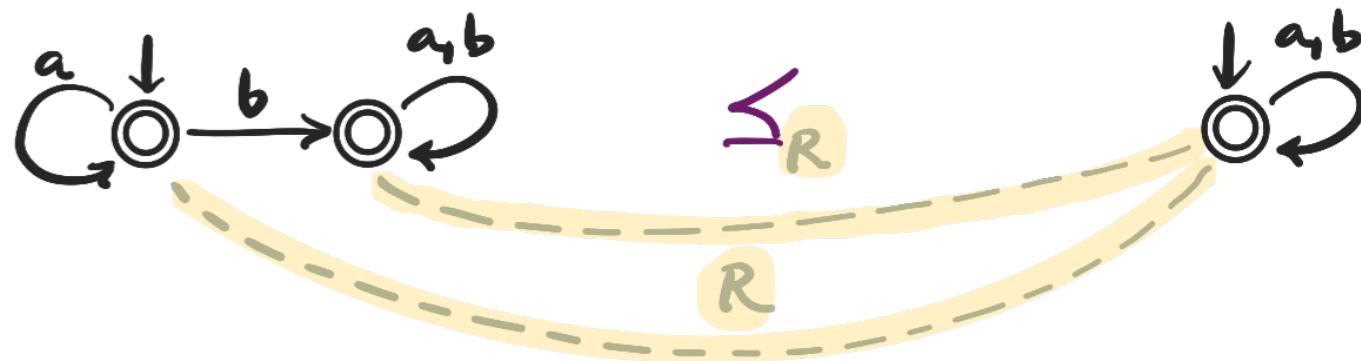
# ONE-SLIDE SYNOPSIS



SOUNDNESS  $\uparrow \downarrow$  COMPLETENESS



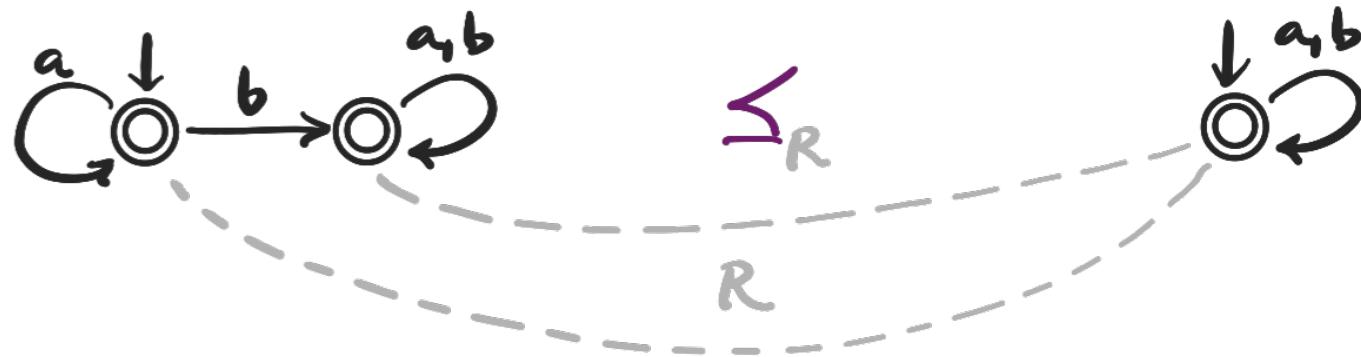
# ONE-SLIDE SYNOPSIS



SOUNDNESS  $\uparrow \downarrow$  COMPLETENESS



# ONE-SLIDE SYNOPSIS



SOUNDNESS  $\uparrow \downarrow$  COMPLETENESS

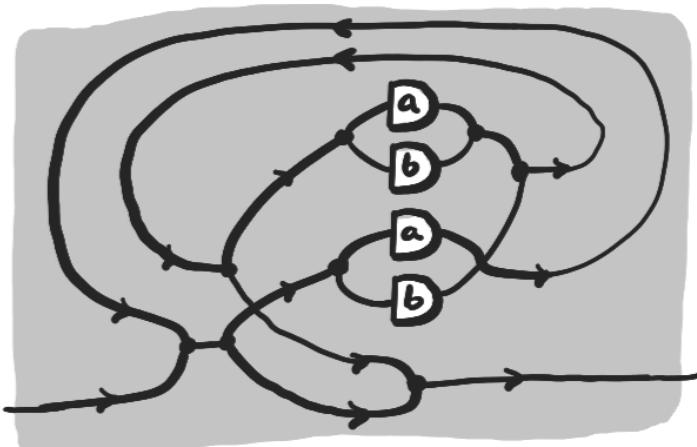
$$a^*(b(a+b)^* + 1) \leq (a+b)^*$$

# PREVIOUSLY...

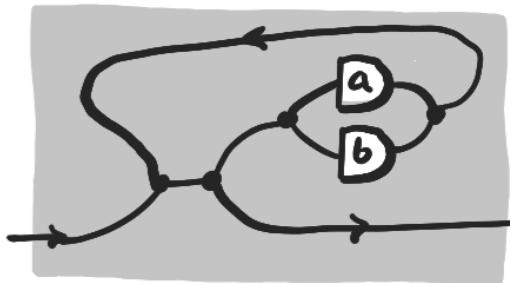
$$\mathcal{L} \left( \begin{array}{c} a \\ \downarrow \\ \textcircled{G} \\ \xrightarrow{b} \end{array} \right) \subseteq \mathcal{L} \left( \begin{array}{c} a,b \\ \downarrow \\ \textcircled{G} \end{array} \right)$$

$\nwarrow$  recognised Language

SOUNDNESS       $\uparrow$        $\downarrow$  COMPLETENESS



$\leqslant$



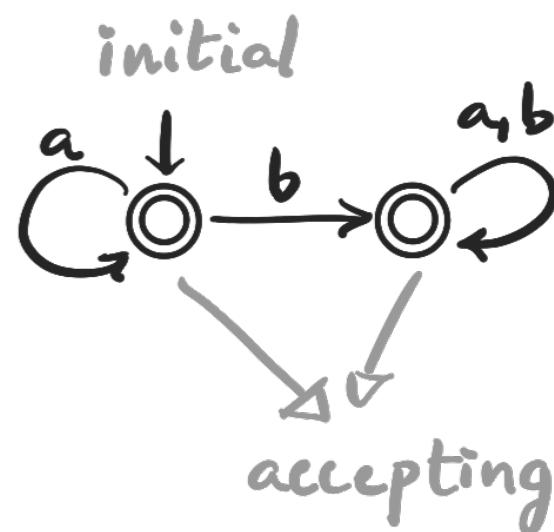
P. & Zanasi, A finite axiomatisation of finite-state automata using string diagrams, LMCS, 2023

# NFA

$$(\Sigma, Q, \delta \subseteq Q \times \Sigma \times Q, q_0 \in Q, F \subseteq Q)$$

↑  
alphabet      ↑  
finite set  
of states      ↑  
transition  
relation      ↑  
initial  
state      ↑  
accepting  
states

E.g.



$$\Sigma = \{a, b\}$$

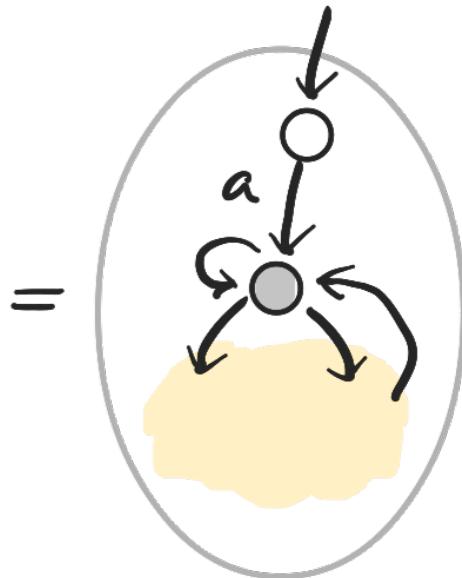
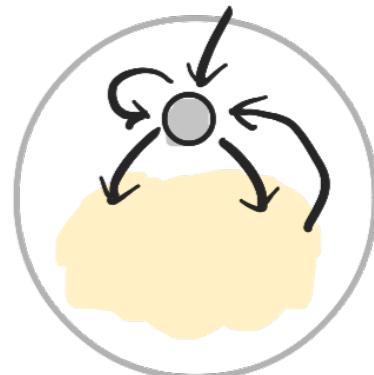
# OPERATIONS ON NFA

- Product:  $(q, s) \xrightarrow{a} (q', s')$  in  $A \times B$  iff  $q \xrightarrow{a} q'$  in  $A$  and  $s \xrightarrow{a} s'$  in  $B$ .

- Prefixing:

$a \in \Sigma$

a.



# SIMULATION

A simulation from A to B is a relation

$$R \subseteq Q^A \times Q^B \text{ s.t.}$$

- ① if  $(q, s) \in R$  and  $q \in F^A$  then  $s \in F^B$
- ② if  $(q, s) \in R$  and  $q \xrightarrow{a} q'$  then there exists  $s' \in Q^B$  s.t.  $s \xrightarrow{a} s'$  and  $(q', s') \in R$ .
- ③  $(q_0^A, q_0^B) \in R$

$\Rightarrow$  We write  $A \leq_R B$  or  $A \leq B$

# SIMILARITY

A and B are (two-way) similar, written  $A \simeq B$ ,  
if  $A \leq_R B$  and  $B \leq_S A$

behaviours

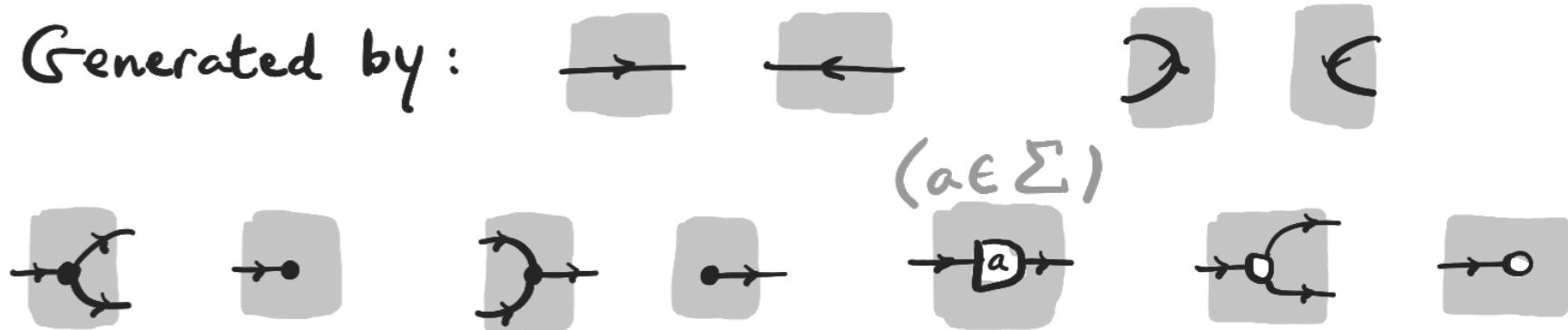
Theorem. The set  $\Omega$  of NFA modulo  $\simeq$  form  
a semi-lattice with:

- $A \times B$  as meet
- $\downarrow \circlearrowleft_{a \in \Sigma}$  as top

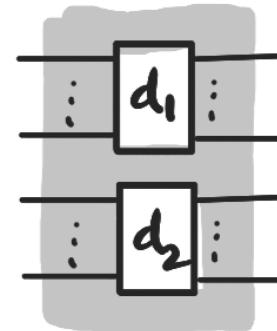
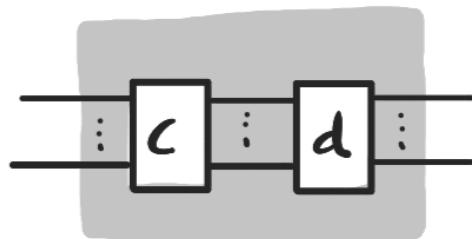
And prefixing is monotone.

# 2D SYNTAX FOR NFA

Generated by :



using two forms of composition :



and wire crossings, e.g.

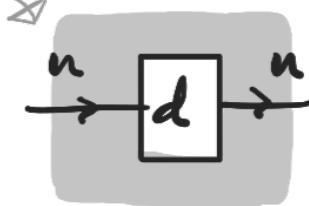


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# ENCODING NFA

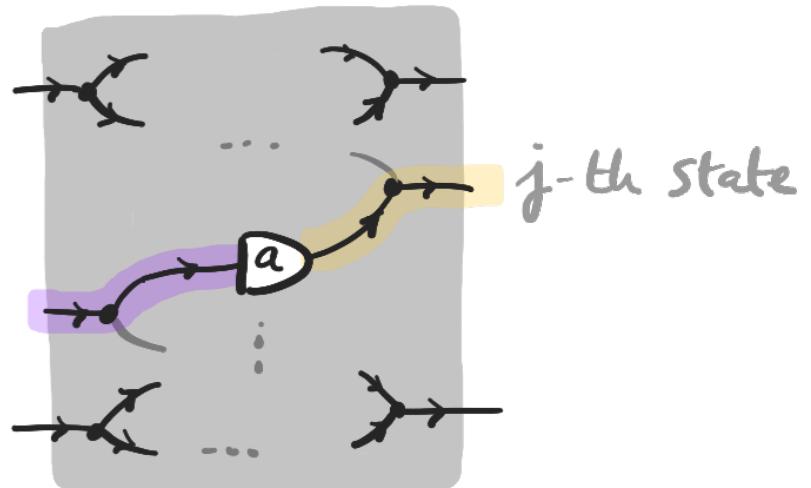
- Transition relation  $\delta$ :

number  
of states  
 $n = |Q|$



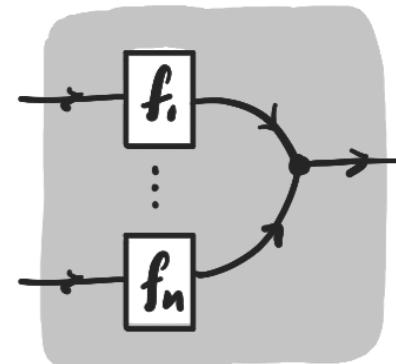
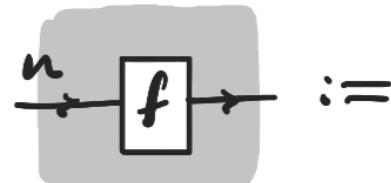
$:=$  i-th state

initial state



iff  $(q_i, a, q_j) \in \delta$

- Final states:

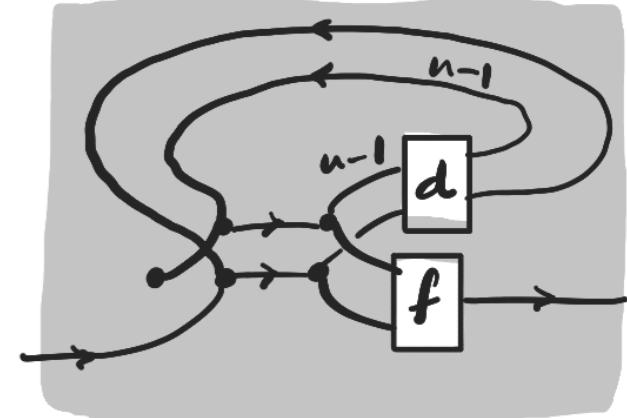


where

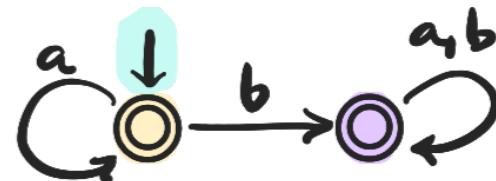
$$\xrightarrow{f_i} = \begin{cases} \xrightarrow{\quad} & \text{if } q_i \in F, \\ \xrightarrow{\quad} \xrightarrow{\quad} & \text{otherwise.} \end{cases}$$

# ENCODING NFA

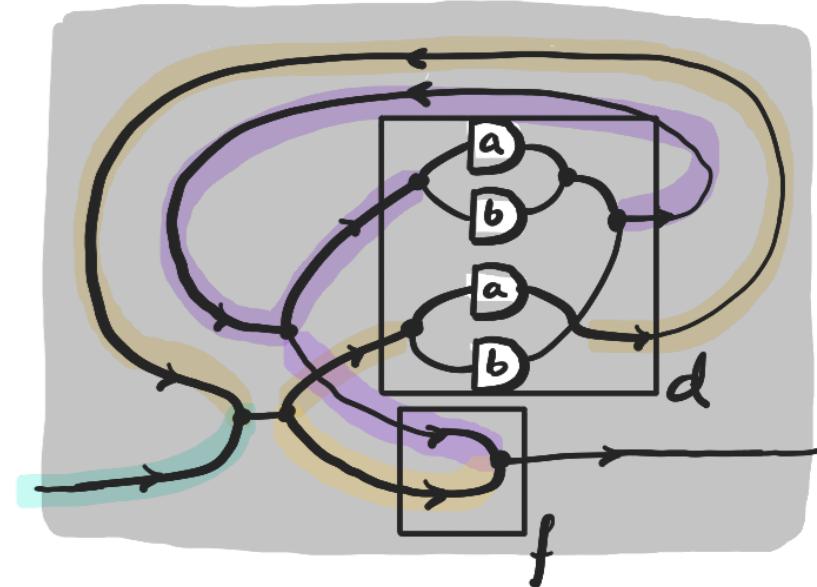
$(\Sigma, \{q_0, \dots, q_{n-1}\}, \delta, q_0, F) \rightsquigarrow$



For example :



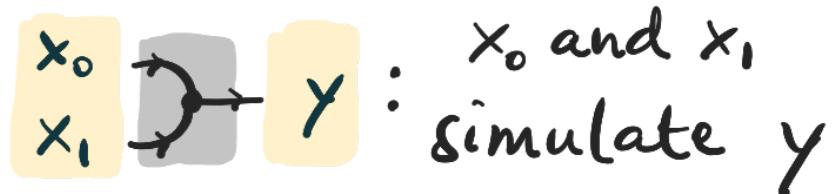
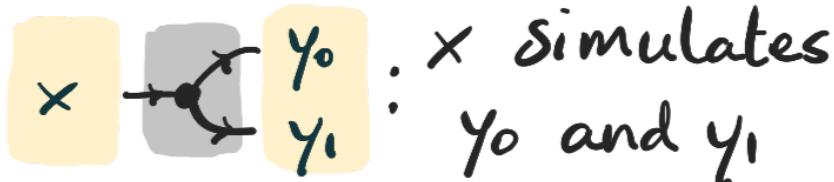
$\rightsquigarrow$



# SEMANTICS

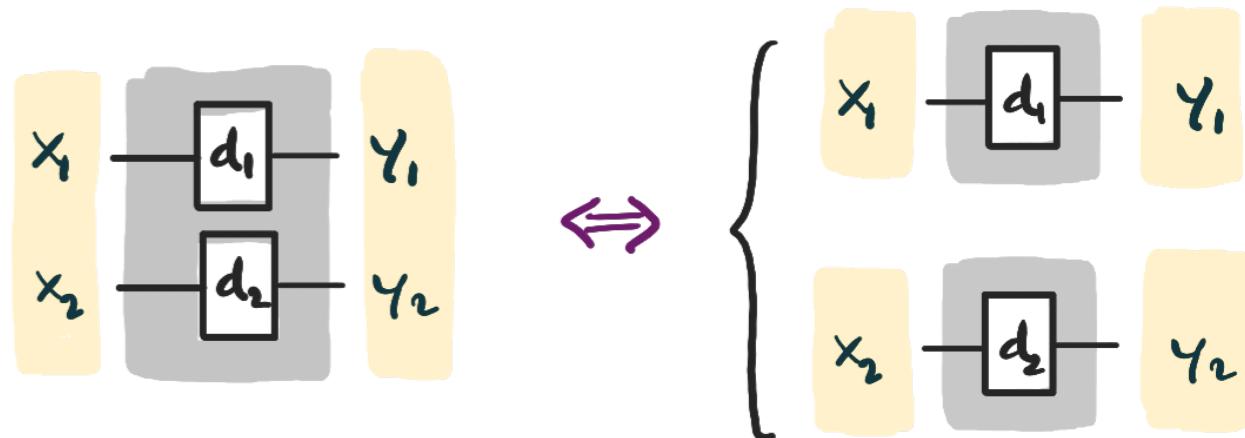
"Behaviours"

$x, y, x_i, y_i \in \Sigma$  ↪ = NFA up to  $\sim$



"plumbing"  
(cf. paper)

# SEMANTICS

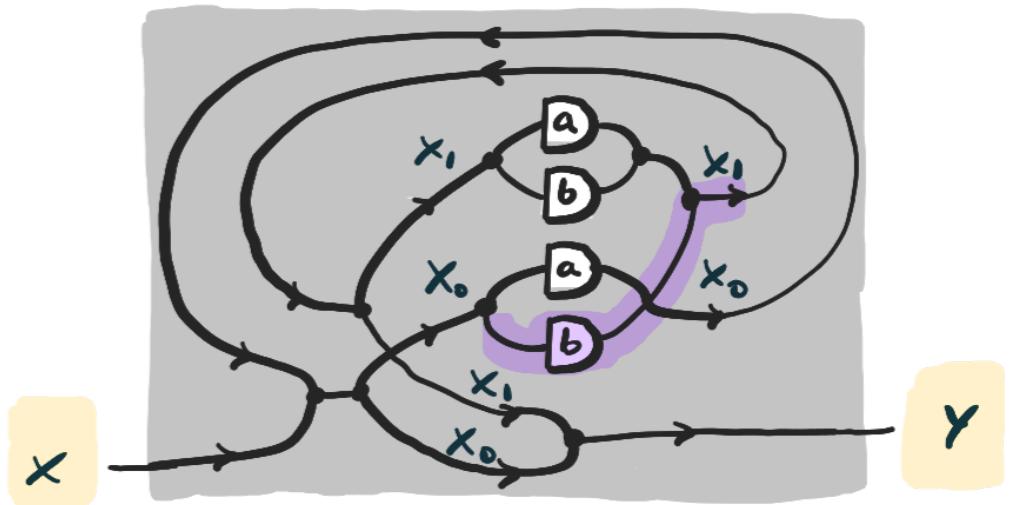


## COMPOSITIONALITY

The behaviour of a composite diagram  
can be computed from the behaviour of its parts.

# SEMANTICS

Diagram  $\mapsto$  Solution set of system  
of linear inequalities

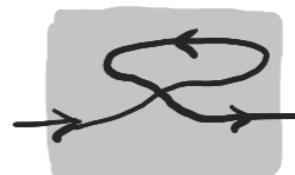


$\exists x_0, x_1 \left( x_0 \leq x, \text{internal vars} \right)$

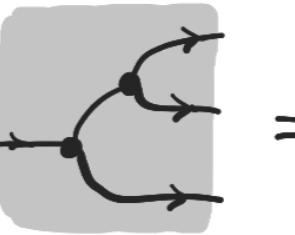
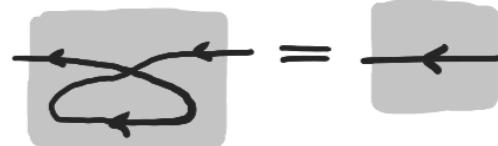
$\iff$

$\begin{aligned} & a \cdot x_0 \leq x_0, \\ & b \cdot x_1 \leq x_0, \\ & a \cdot x_1 \leq x_1, \\ & b \cdot x_1 \leq x_1, \\ & y \leq x_0, x_1 \end{aligned}$

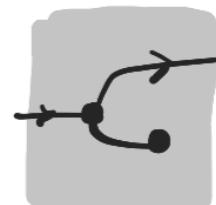
# EQUATIONAL THEORY



$$= \quad \rightarrow$$



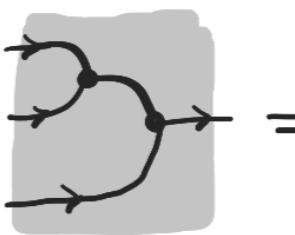
$$= \quad \rightarrow$$



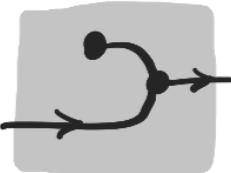
$$= \quad \rightarrow$$



$$=$$



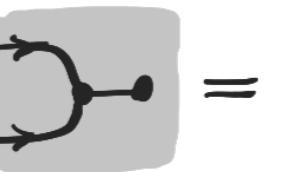
$$= \quad \rightarrow$$



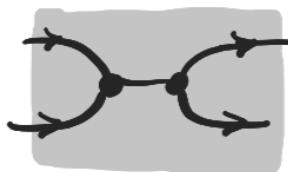
$$= \quad \rightarrow$$



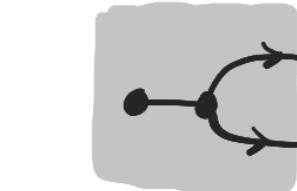
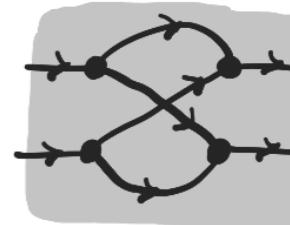
$$= \quad \rightarrow$$



$$= \quad \bullet$$



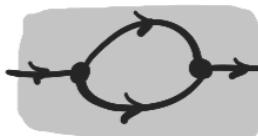
$$=$$



$$= \quad \bullet$$



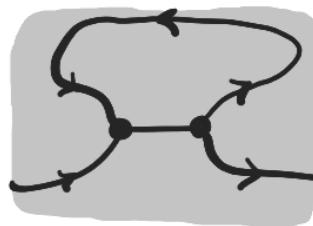
$$= \quad \bullet$$



$$=$$

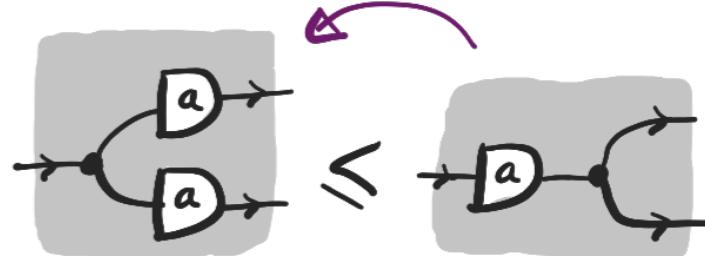


$$=$$



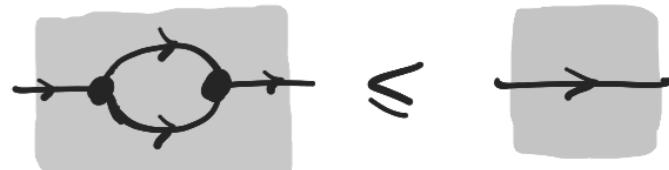
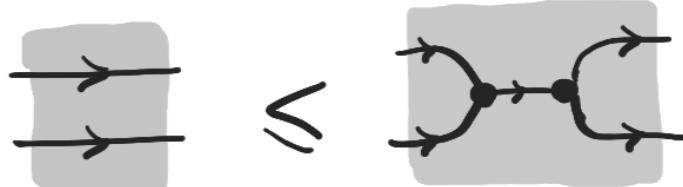
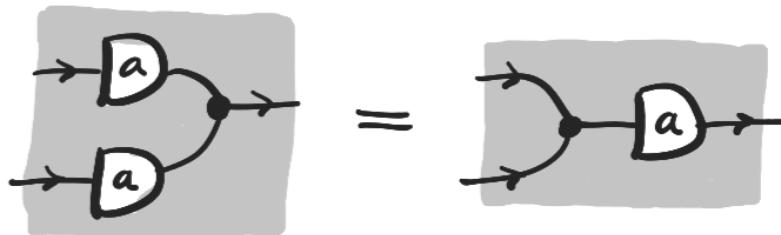
# EQUATIONAL THEORY

Simulates



$$a.b + a.c \leq a.(b+c)$$

---



# SOUNDNESS

Theorem. If  $\boxed{c_A}$  and  $\boxed{c_B}$  encode NFA A and B respectively, then

$$\boxed{c_A} \leq \boxed{c_B} \Rightarrow A \leq B$$

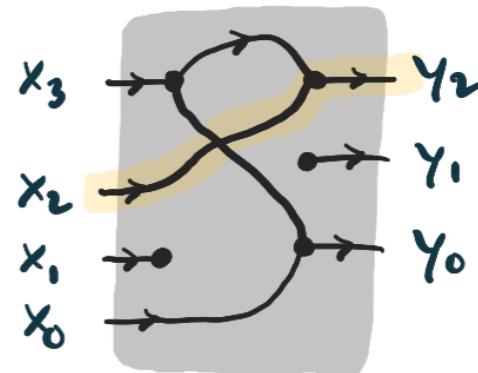
Proof. Using the semantics: we just need to check the validity of all axioms.

# SIMULATIONS AS DIAGRAMS

A simulation is just a relation and relations correspond to diagrams in the fragment generated by



E.g.

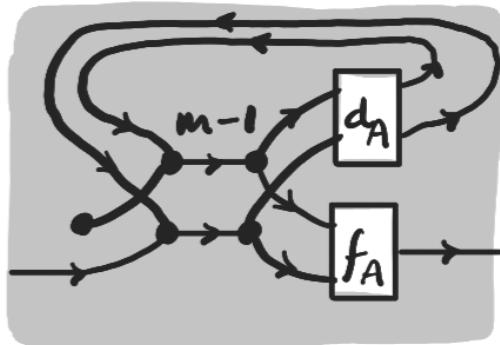


$$\{ (x_3, y_2), (x_3, y_0), (x_2, y_2), (x_0, y_0) \}$$

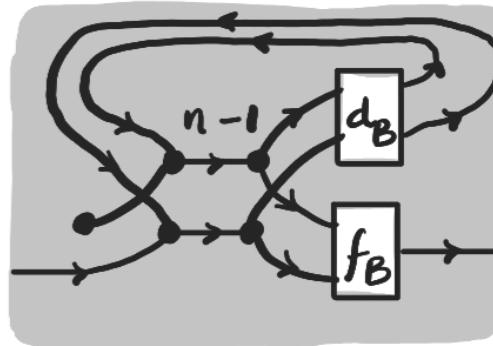
( $x_1, y_1$  do not belong to the relation)

# SIMULATIONS AS DIAGRAMS

If

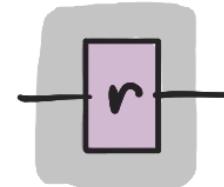


and

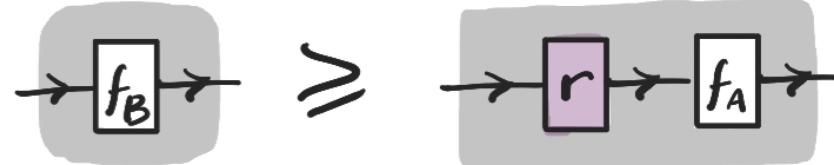


encode NFA A

and B, and  $A \leq_R B$ , then there exists



①



s.t.

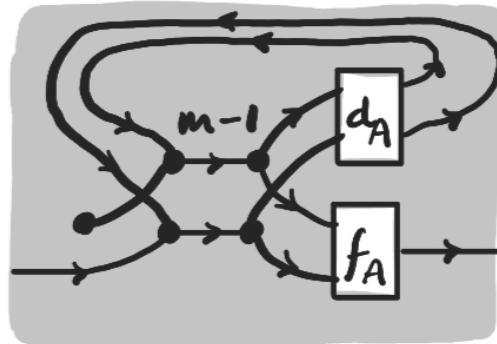
②



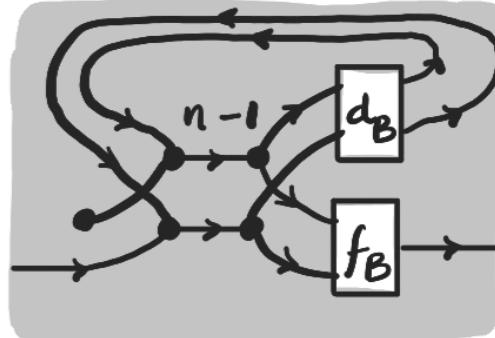
i.e. internalise properties of simulations.

# SIMULATIONS AS DIAGRAMS

If

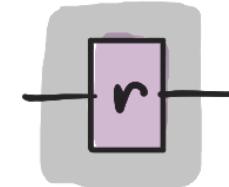


and



encode NFA A

and B, and  $A \leq_R B$ , then there exists



①



s.t.

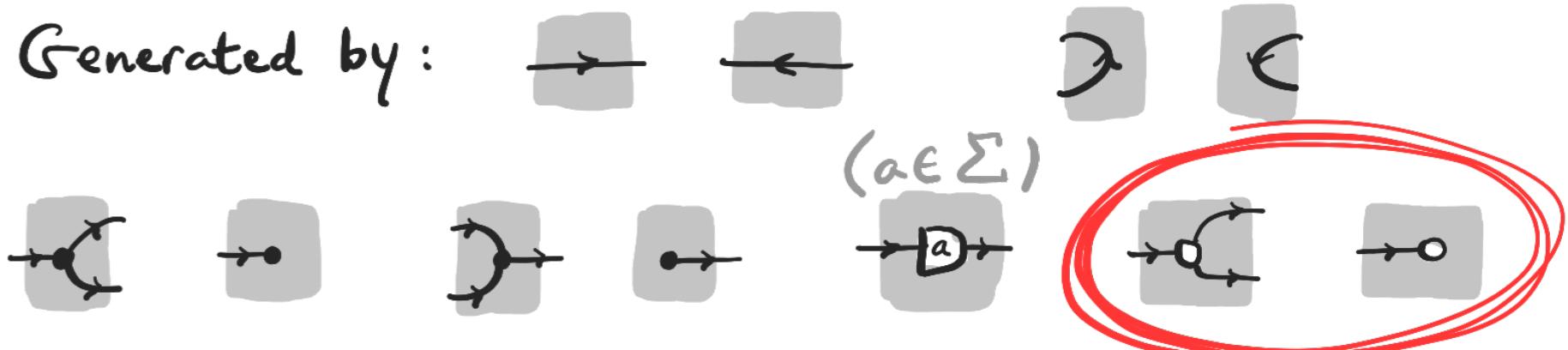
②



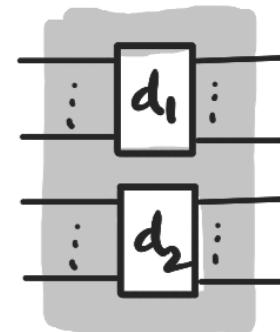
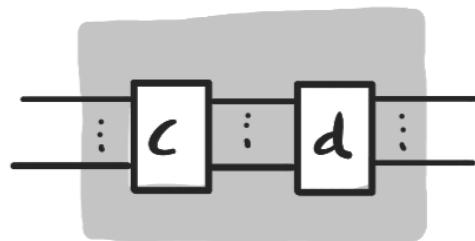
BUT NOT ENOUGH...

# 2D SYNTAX FOR NFA

Generated by :



using two forms of composition :



What about these ?

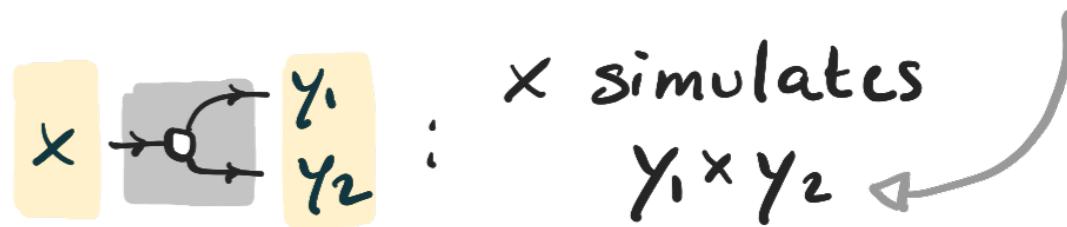
and wire crossings, e.g. 



P. & Zanasi, A finite axiomatisation of finite-state automata using string diagrams, LMCS, 2023

## SEMANTICS, CONTINUED

product of NFA/meet  
of lattice



top of  
lattice

# EQUATIONAL THEORY, CONTINUED

$$\begin{array}{c} \text{Diagram: } \text{A grey box containing a directed graph with two nodes. The left node has an incoming arrow from the left and an outgoing arrow pointing right. The right node has an incoming arrow from the right and an outgoing arrow pointing left. There is a curved arrow from the right side of the left node to the left side of the right node.} \\ = \\ \text{Diagram: } \text{A grey box containing a directed graph with two nodes. The left node has an incoming arrow from the left and an outgoing arrow pointing right. The right node has an incoming arrow from the right and an outgoing arrow pointing left. There is a curved arrow from the top of the left node to the bottom of the right node.} \end{array}$$

$$\begin{array}{c} \text{Diagram: } \text{A grey box containing a directed graph with two nodes. The left node has an incoming arrow from the left and an outgoing arrow pointing right. The right node has an incoming arrow from the right and an outgoing arrow pointing left. There is a curved arrow from the top of the left node to the bottom of the right node.} \\ = \\ \text{Diagram: } \text{A grey box containing a single horizontal directed edge from left to right.} \end{array}$$

$$\begin{array}{c} \text{Diagram: } \text{A grey box containing a directed graph with two nodes. The left node has an incoming arrow from the left and an outgoing arrow pointing right. The right node has an incoming arrow from the right and an outgoing arrow pointing left. There is a curved arrow from the top of the left node to the bottom of the right node.} \\ = \\ \text{Diagram: } \text{A grey box containing a directed graph with two nodes. The left node has an incoming arrow from the left and an outgoing arrow pointing right. The right node has an incoming arrow from the right and an outgoing arrow pointing left. There is a curved arrow from the bottom of the left node to the top of the right node.} \end{array}$$

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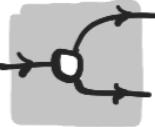
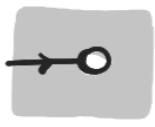
$$\begin{array}{c} \text{Diagram: } \text{A grey box containing a directed graph with three nodes. The left node has an incoming arrow from the left and an outgoing arrow pointing right. The middle node has an incoming arrow from the left and an outgoing arrow pointing right. The right node has an incoming arrow from the right and an outgoing arrow pointing left. There is a curved arrow from the right side of the left node to the left side of the right node.} \\ \leq \\ \text{Diagram: } \text{A grey box containing a single horizontal directed edge from left to right.} \end{array}$$

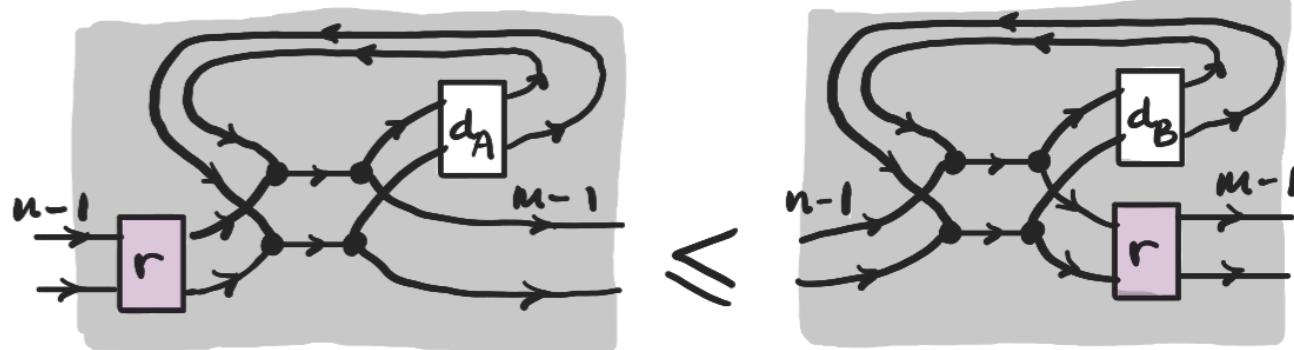
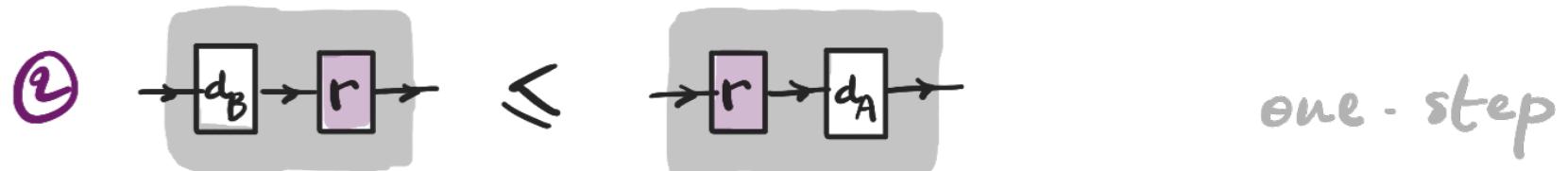
$$\begin{array}{c} \text{Diagram: } \text{A grey box containing a single horizontal directed edge from left to right.} \\ \leq \\ \text{Diagram: } \text{A grey box containing a directed graph with two nodes. The left node has an incoming arrow from the left and an outgoing arrow pointing right. The right node has an incoming arrow from the right and an outgoing arrow pointing left. There is a curved arrow from the top of the left node to the bottom of the right node.} \end{array}$$

$$\begin{array}{c} \text{Diagram: } \text{A grey box containing a directed graph with two nodes. The left node has an incoming arrow from the left and an outgoing arrow pointing right. The right node has an incoming arrow from the right and an outgoing arrow pointing left. There is a curved arrow from the top of the left node to the bottom of the right node.} \\ \leq \\ \text{Diagram: } \text{An empty grey box.} \end{array}$$

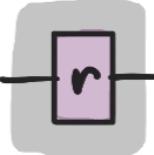
$$\begin{array}{c} \text{Diagram: } \text{A grey box containing a single horizontal directed edge from left to right.} \\ \leq \\ \text{Diagram: } \text{A grey box containing a directed graph with two nodes. The left node has an incoming arrow from the left and an outgoing arrow pointing right. The right node has an incoming arrow from the right and an outgoing arrow pointing left. There is a curved arrow from the bottom of the left node to the top of the right node.} \end{array}$$

# SIMULATIONS AS DIAGRAMS, CONTINUED

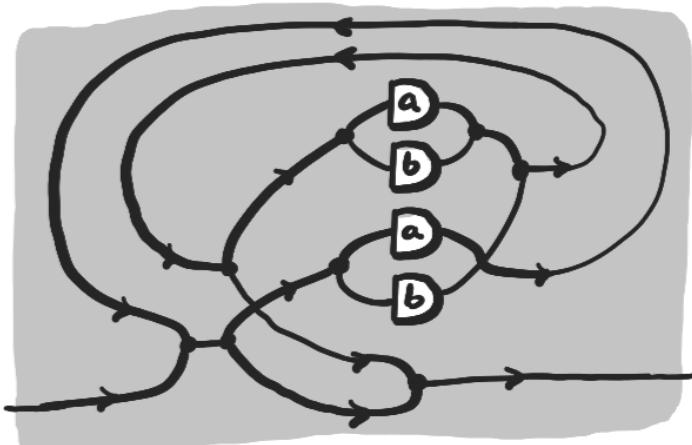
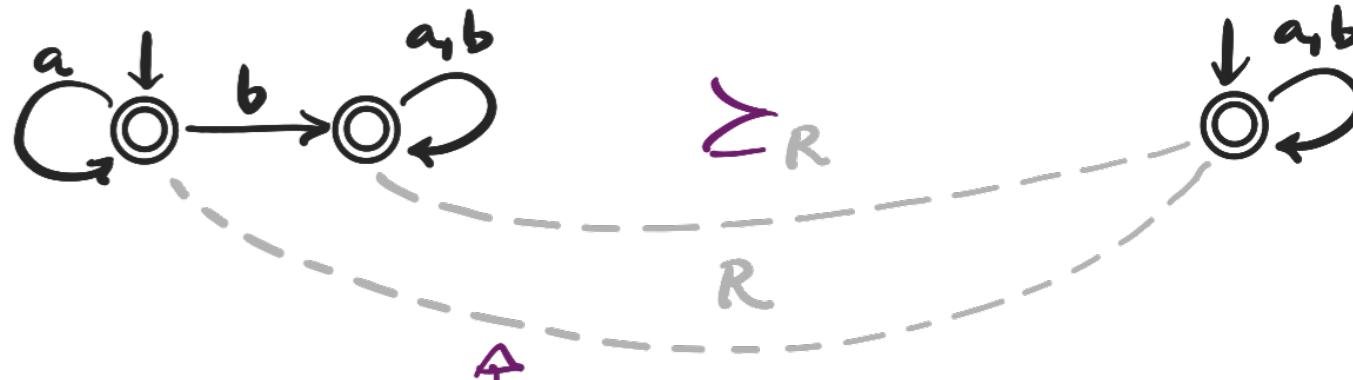
Using   with the axioms above, we can show



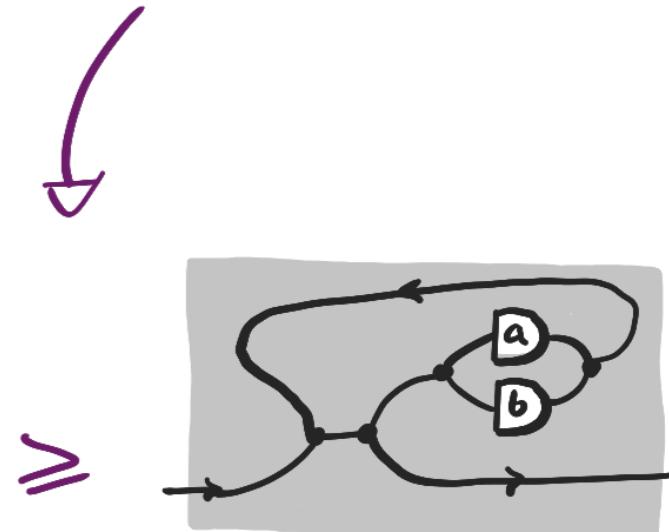
arbitrarily  
many steps

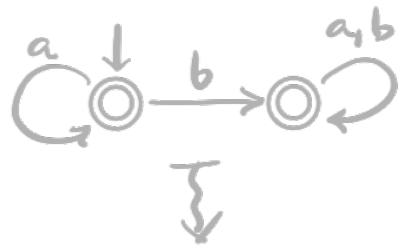
for  encoding a simulation  $A \leq_R B$

# WORKED EXAMPLE

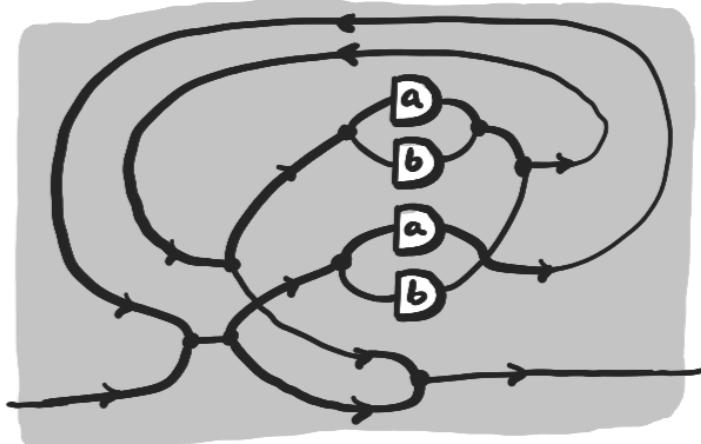


We want to show

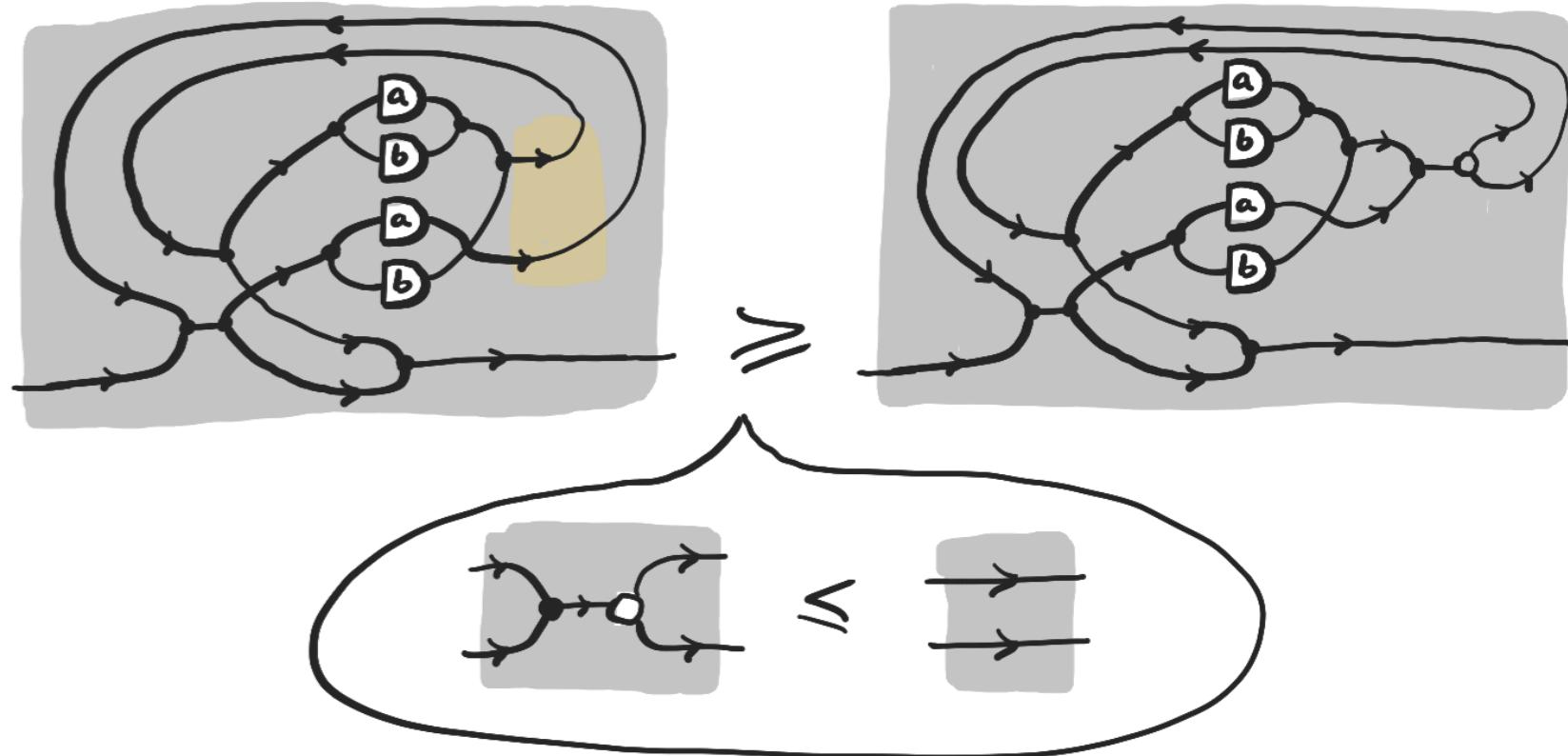




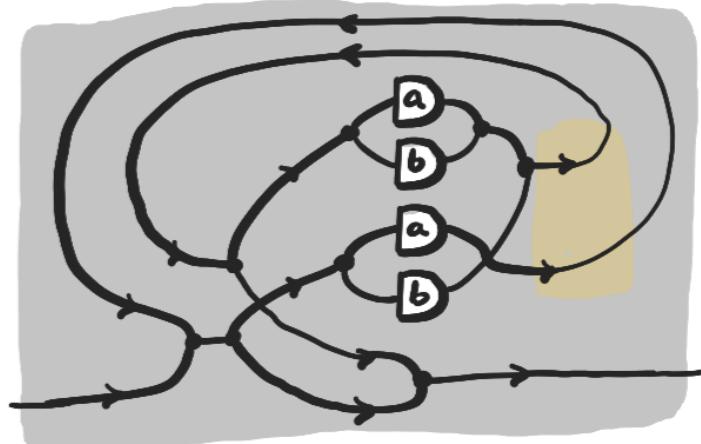
## WORKED EXAMPLE



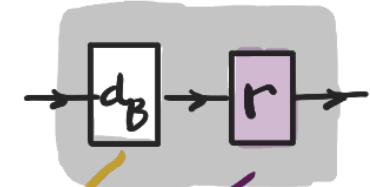
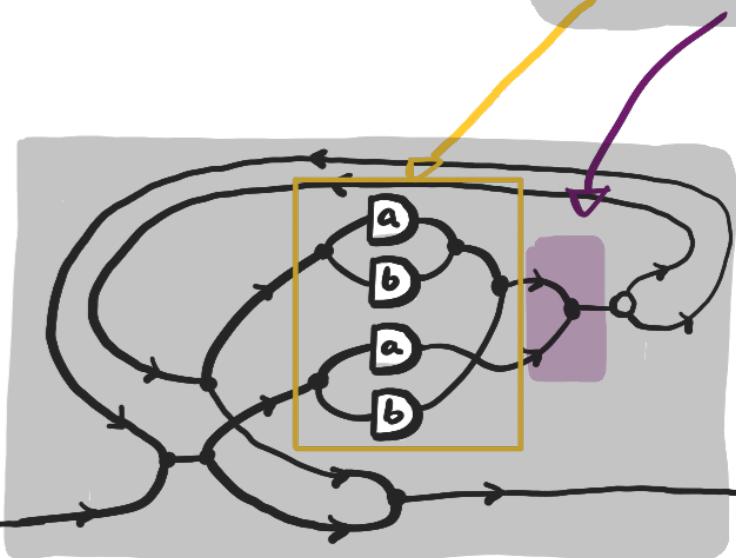
# WORKED EXAMPLE



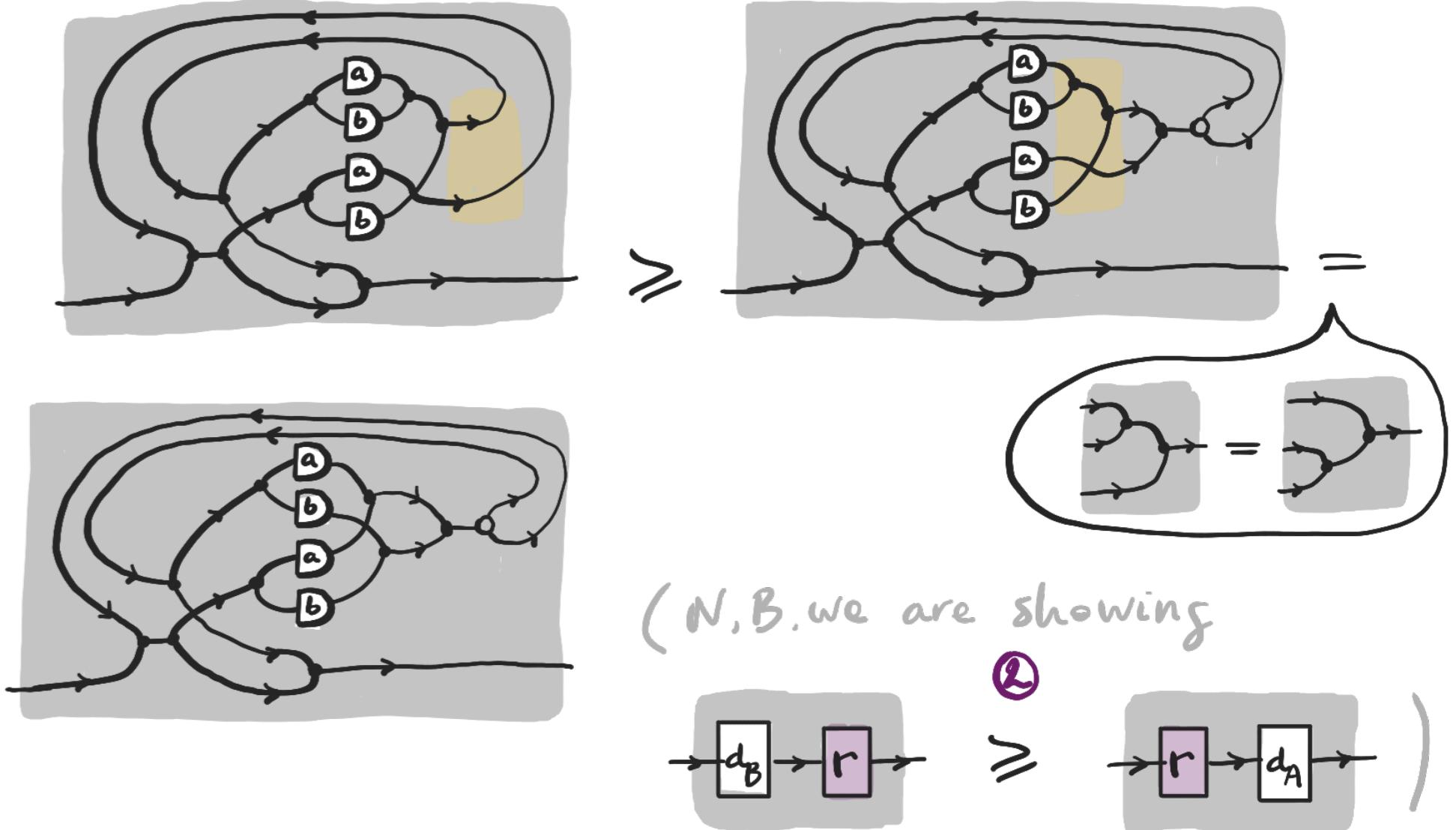
# WORKED EXAMPLE



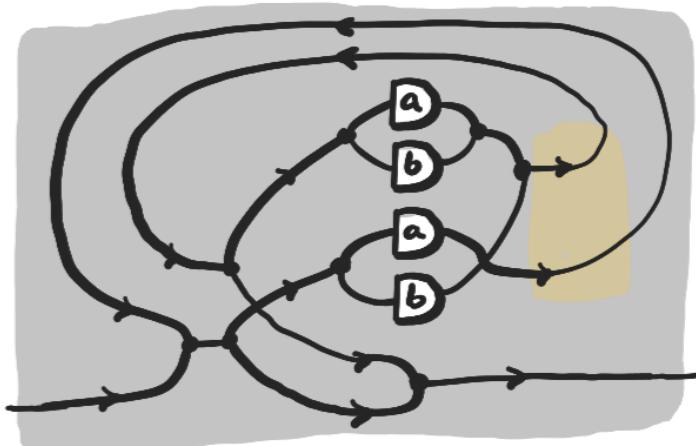
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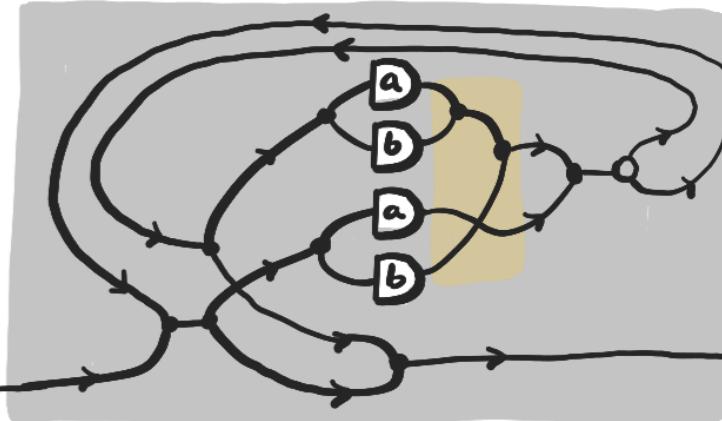
# WORKED EXAMPLE



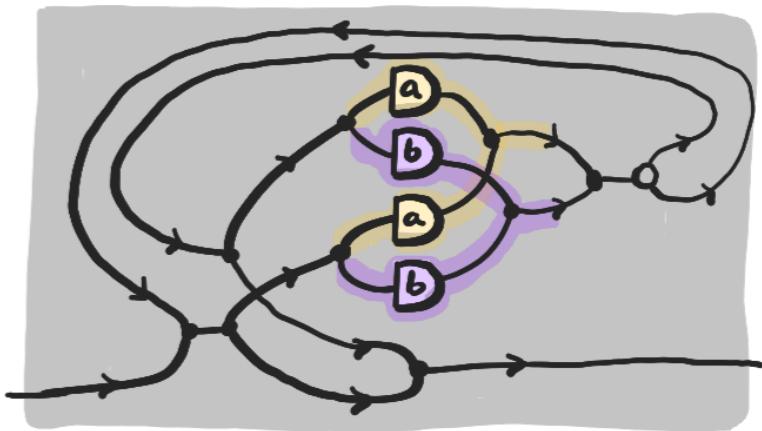
# WORKED EXAMPLE



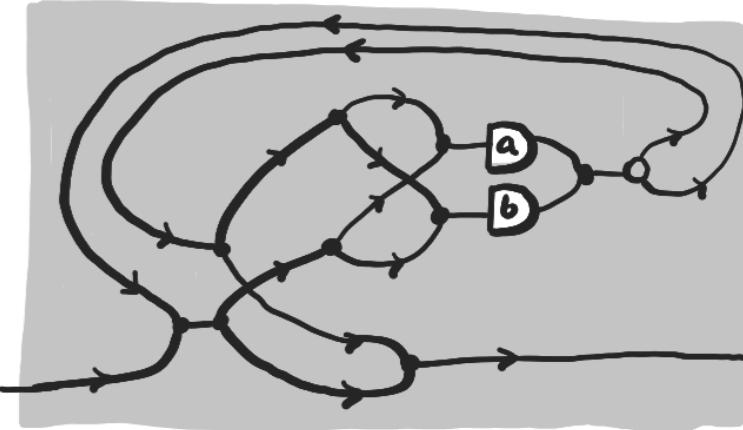
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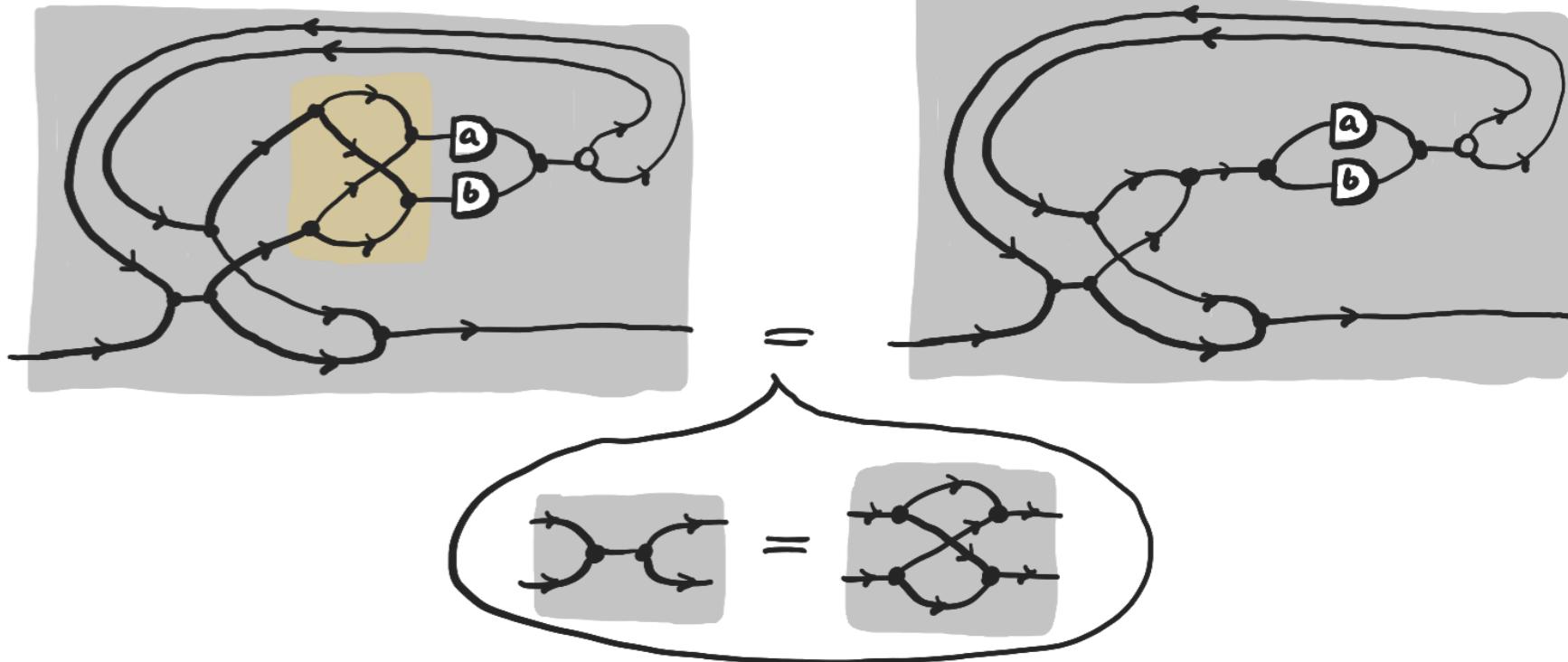
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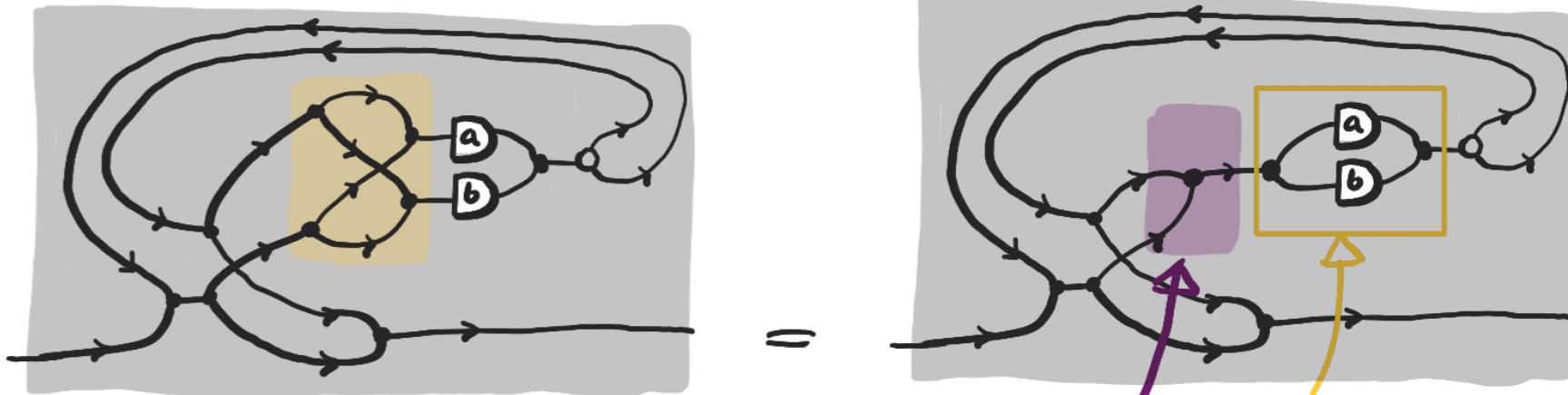
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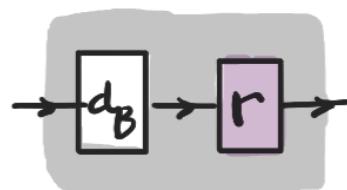
# WORKED EXAMPLE



# WORKED EXAMPLE

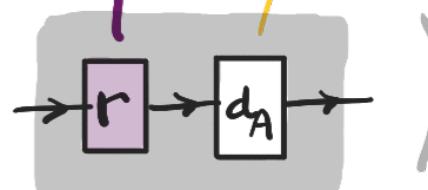


(we have shown

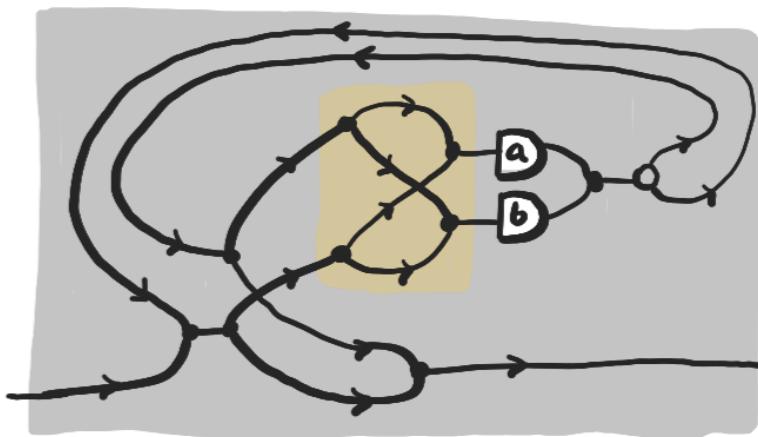


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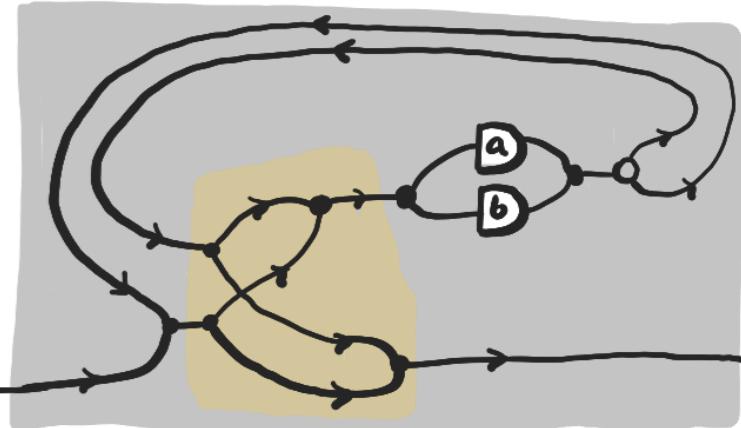
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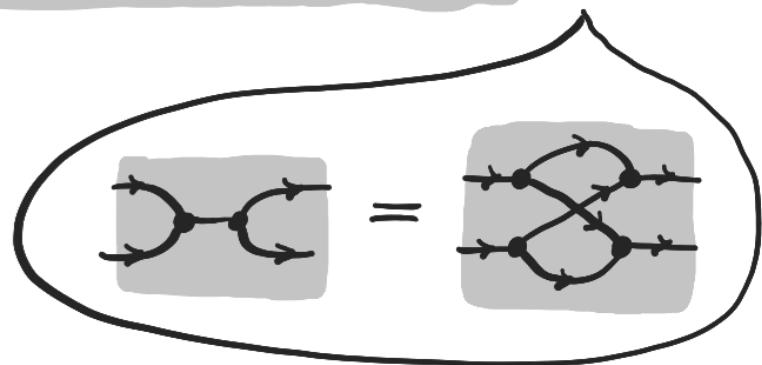
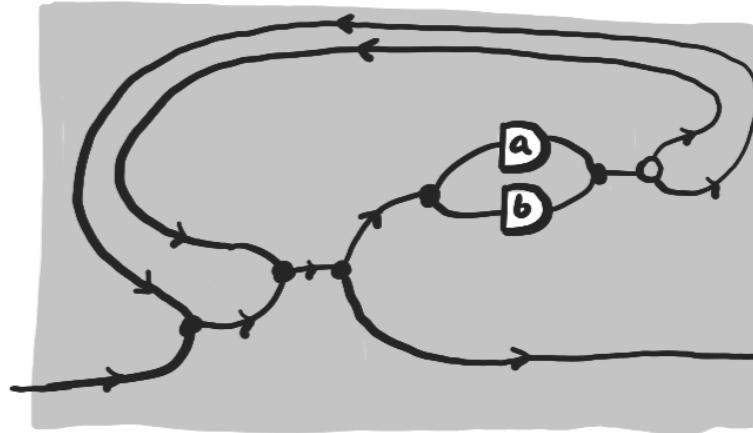
# WORKED EXAMPLE



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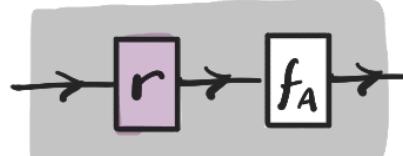
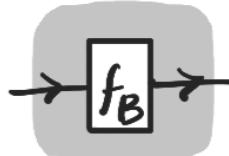
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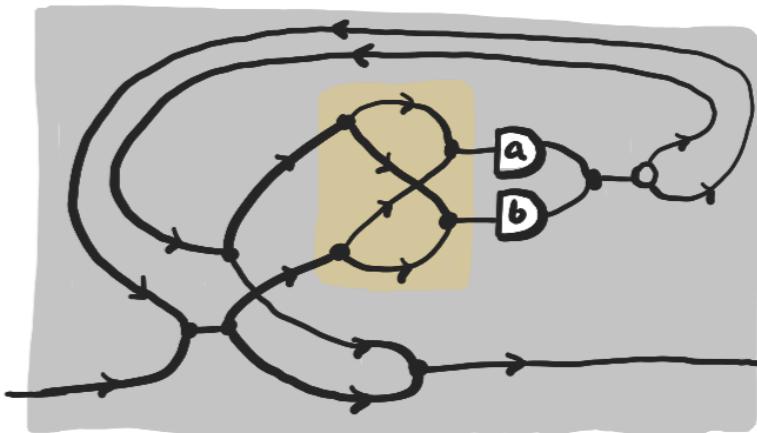
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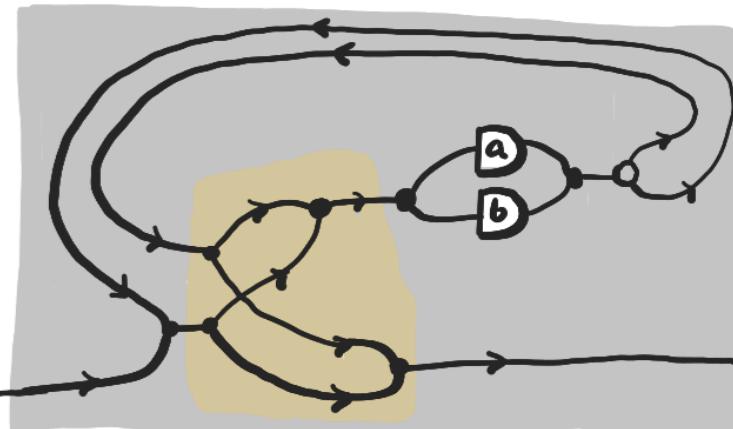


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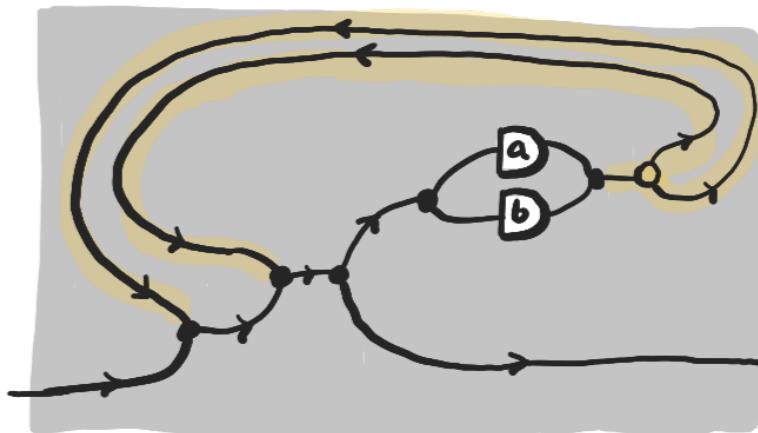
# WORKED EXAMPLE



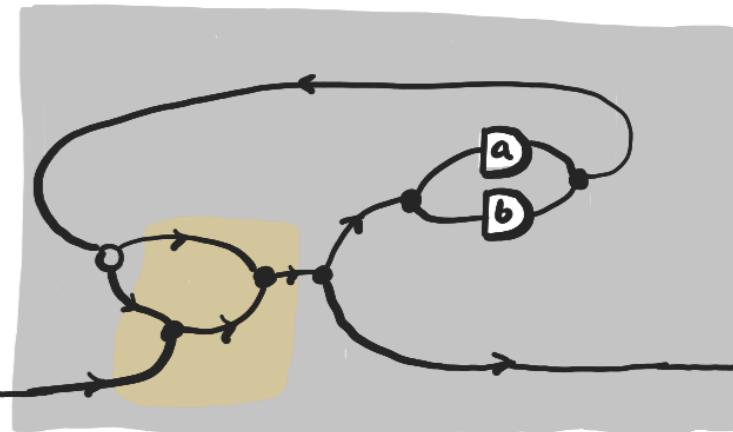
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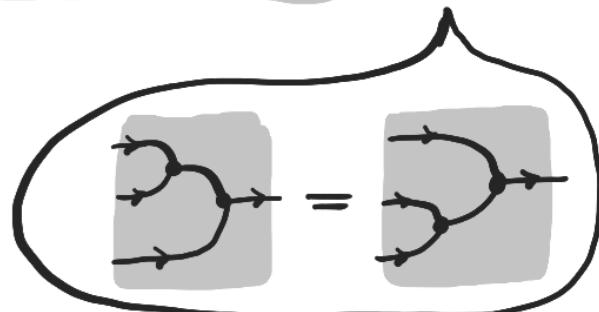
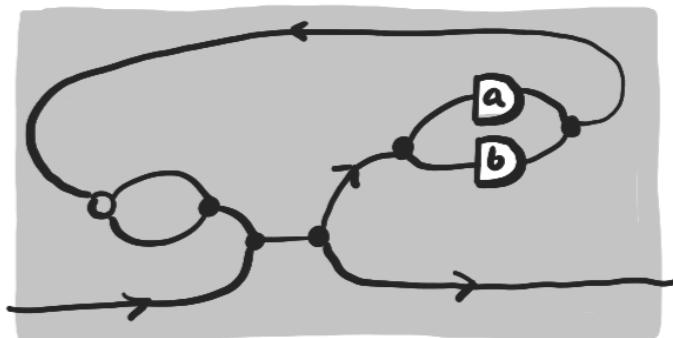
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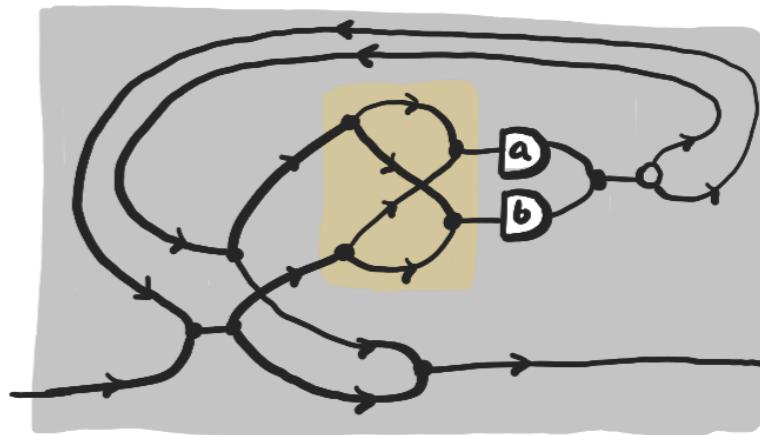
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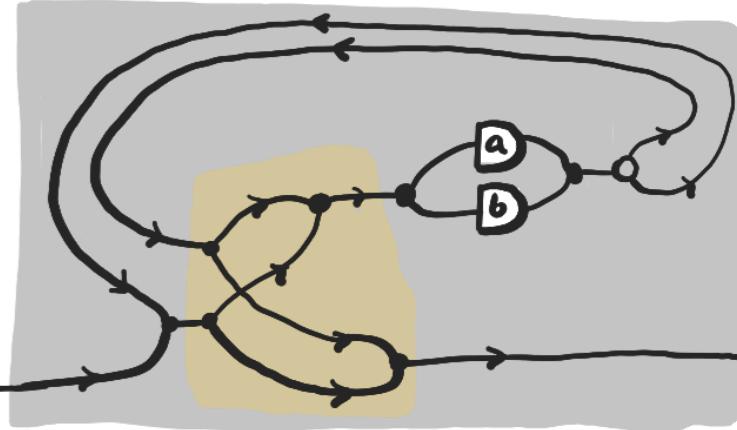
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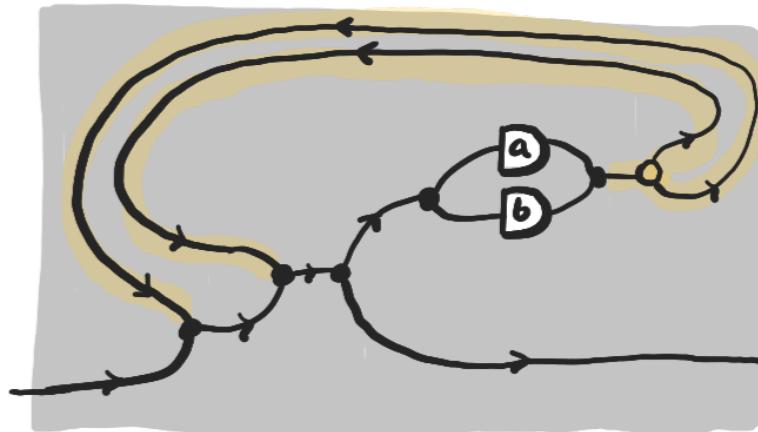
# WORKED EXAMPLE



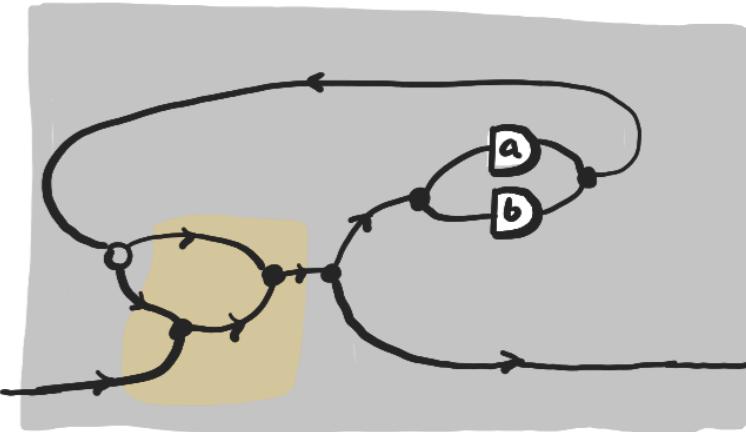
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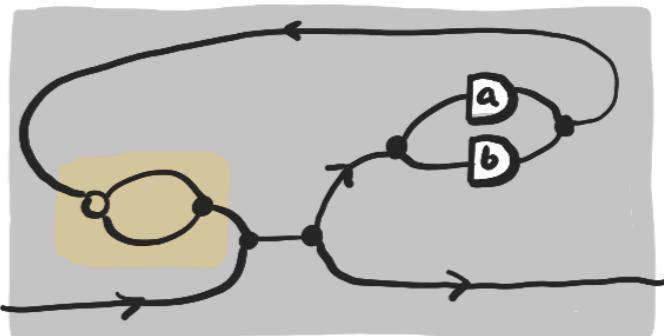
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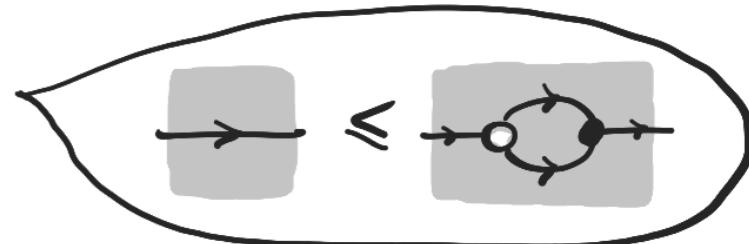
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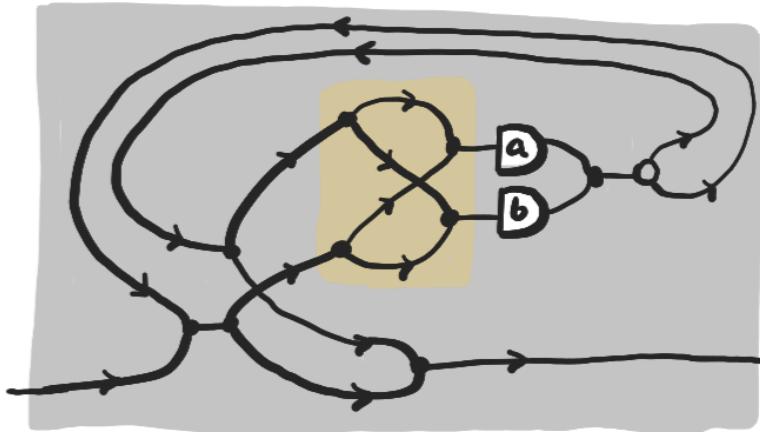
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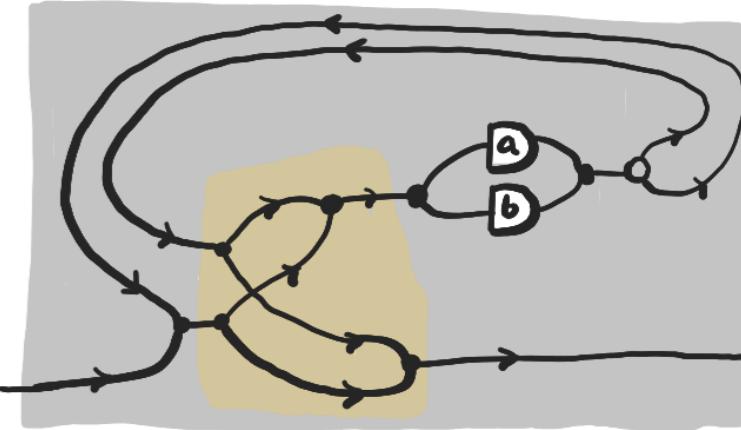
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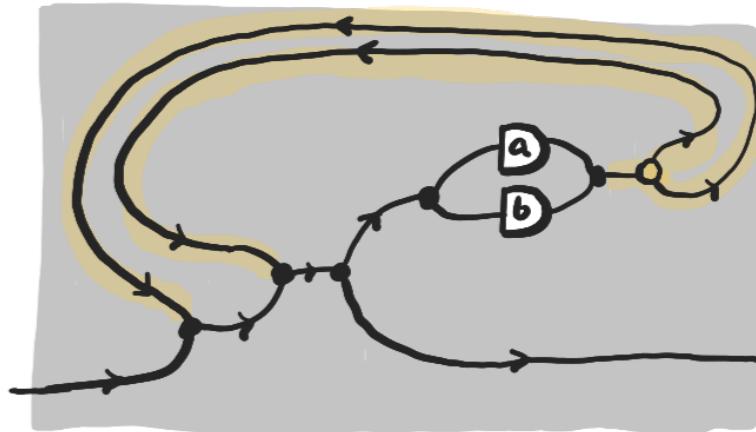
# WORKED EXAMPLE



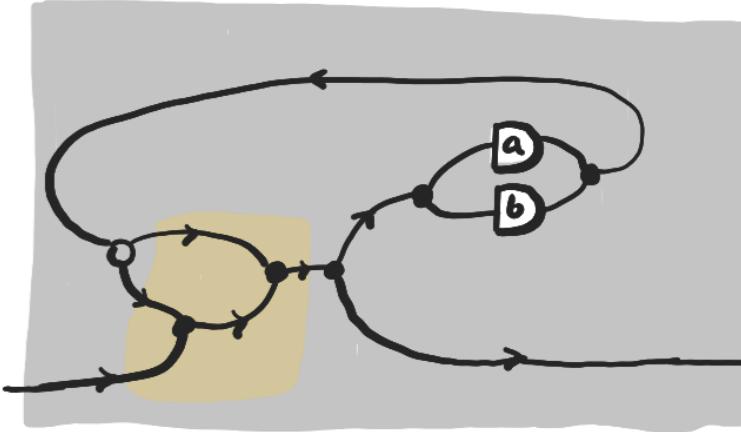
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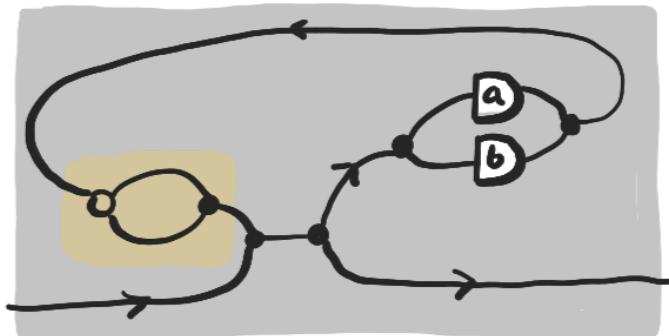
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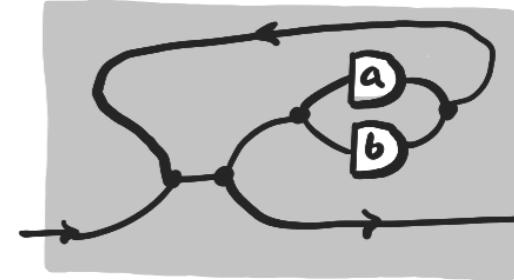
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↪ ↴  $a, b$

# COMPLETENESS

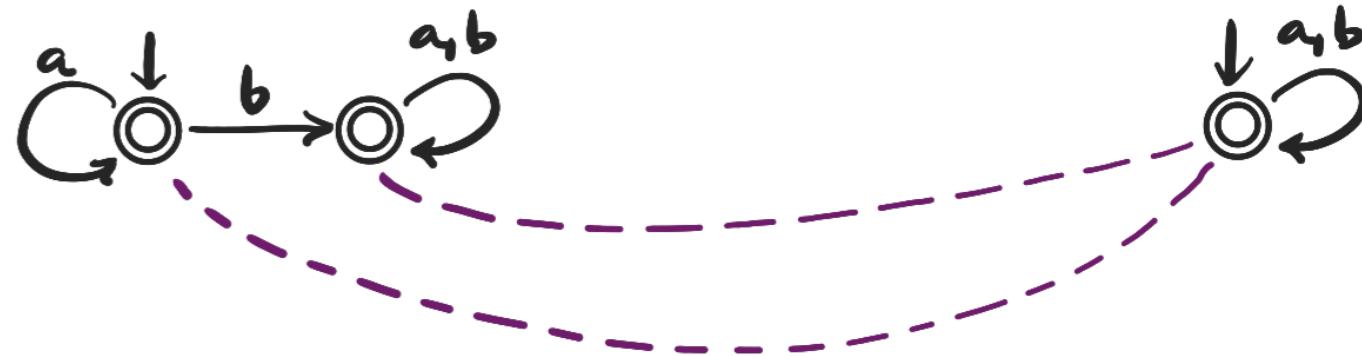
Theorem. If  $\boxed{c_A}$  and  $\boxed{c_B}$  encode NFA A and B respectively, then

$$A \leq B \Rightarrow \boxed{c_A} \leq \boxed{c_B}$$

Proof idea : Via encoding simulations as diagrams and using the axioms above to show that they indeed behave as simulations syntactically.

## FUTURE WORK

- Using an extended syntax to internalise proofs of simulation, equivalence, etc. in other models : KAT, GKAT, CKA, ...
- Bisimulation in a 2-categorical setting (i.e. with "proof-relevant inequalities"  $\leq_R$ )
- Formulate axioms as hypergraph-rewriting system (DPO) .



THANK YOU!  $\downarrow \uparrow$  QUESTIONS ?



# (1D) SYNTAX FOR NFA

- Regular expressions

$$e ::= e + e \mid e \cdot e \mid e^* \mid 0 \mid 1 \mid a \in \Sigma$$

- Milner's algebra of regular behaviours

$$e ::= e + e \mid \mu x. e \mid a. e \mid 0 \mid z$$

fragment  
of CCS

↳ has an axiomatization 



Frendrup & Jensen, A complete axiomatisation of simulation for regular CCS expressions, 2001