

MULTIVARIATE NORMAL

Univariate Normal (distribution of a random variable)

- Each data point is a **scalar**
- Formally, given some data $\{x_i\}_{i=1}^n \in \mathbb{R}$

random variable $\leftarrow x \sim N(\mu, \sigma^2)$

Mean

$$\begin{aligned} \mu &= E(x) \\ &= \begin{cases} \frac{1}{n} \sum_{i=1}^n x_i & \text{discrete} \\ \int x_i \cdot p(x_i) dx & \text{continuous} \end{cases} \end{aligned}$$

Variance

$$\begin{aligned} \sigma^2 &= E(x - \mu)^2 \\ &= \begin{cases} \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2 & \text{discrete} \\ \int (x_i - \mu)^2 p(x_i) dx & \text{continuous} \end{cases} \end{aligned}$$

Multivariate Normal (joint distribution of many random variables)

- Each data point is a **vector**
- Formally, given some data $\{x_i\}_{i=1}^n \in \mathbb{R}^d$

vector of random variables $\leftarrow x \sim N(\mu, \Sigma)$

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_d \end{bmatrix}$$

Mean

$$\mu = E(x) = \begin{bmatrix} E(x_1) \\ \vdots \\ E(x_d) \end{bmatrix} = \begin{cases} \begin{bmatrix} \frac{1}{n} \sum x_1 \\ \vdots \\ \frac{1}{n} \sum x_d \end{bmatrix} & \text{discrete} \\ \begin{bmatrix} \int x_1^{(i)} p(x_1^{(i)}) dx_1 \\ \vdots \\ \int x_d^{(i)} p(x_d^{(i)}) dx_d \end{bmatrix} & \text{continuous} \end{cases}$$

Covariance matrix

$$\Sigma = E((x - \mu)(x - \mu)^T) = \begin{bmatrix} \lambda_{11} & \dots & \lambda_{1d} \\ \vdots & & \vdots \\ \lambda_{d1} & \dots & \lambda_{dd} \end{bmatrix}$$

$\text{cov}(x_1, x_d) = E[(x_1 - \mu_1)(x_d - \mu_d)]$
 variance of $x_i = E(x_i - \mu_i)^2$

PROPERTIES OF MULTIVARIATE NORMAL

1. Independent Normal Distributions

- The covariance matrix is diagonal

- Formally, given some data $\{x_i\}_{i=1}^n \in \mathbb{R}^d$, where $x_i \perp x_j \quad \forall i \neq j$ (independent)

$$x \sim N(\mu, \Sigma)$$

Proof $\text{Cov}(X, Y) = 0$

if X independent Y :

$$\begin{aligned} \text{Cov}(X, Y) &= E(XY) - E(X)E(Y) \\ &= E(X)E(Y) - E(X)E(Y) \end{aligned}$$

Diagonal Covariance Matrix

$$\begin{aligned} \Sigma &= E[(x - \mu)(x - \mu)^T] \\ &= \begin{bmatrix} \lambda_{11} & 0 \\ & \ddots \\ 0 & \lambda_{dd} \end{bmatrix} \end{aligned}$$

2. Marginal Distributions

- The marginal distributions that are components of multivariate normal distribution is also normal.

- Formally, we can partition vector and matrix of:

$$x \sim N(\mu, \Sigma)$$

vector $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ $\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}$ $\begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}$ matrix

x_1 is also Gaussian

$$x_1 \sim N(\mu_1, \Sigma_{11})$$

3. Conditional Distributions

- The conditional distributions of any components of multivariate normal distribution is also normal

- Formally, conditional on first component of vector $x \sim N(\mu, \Sigma)$:

$$x_1 | x_2 = a \sim N(\mu_{1/2}, \Sigma_{1/2})$$

Conditional Mean

$$\begin{aligned} \mu_{1/2} &= E(x_1 | x_2 = a) \\ &= \mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (a - \mu_2) \end{aligned}$$

Conditional Covariance matrix

$$\begin{aligned} \Sigma_{1/2} &= \text{cov}(x_1 | x_2 = a) \\ &= \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21} \end{aligned}$$

$\Sigma_{1/2}$ is Schur complement of Σ_{22} in Σ

4. Linear Transform

- Linear transform multivariate normal distribution give a **another multivariate normal**

- Formally, given some data $\{x_i\}_{i=1}^n \in \mathbb{R}^d$:

$$x \sim N(\mu, \Sigma)$$

$$a^T (x - \mu) (x - \mu)^T a$$

and: $z = Ax + b$

then: $z \sim N(\mu_z, \Sigma_z)$

Transformed Mean

$$\begin{aligned} \mu_z &= E(z) \\ &= E(Ax + b) \\ &= A \cdot E(x) + b \\ &= A\mu + b \end{aligned}$$

Transformed Covariance Matrix

$$\begin{aligned} \Sigma_z &= E[(z - \mu_z)(z - \mu_z)^T] \\ &= E[A(x - \mu_z)[A(x - \mu_z)]^T] \\ &= E[A(x - \mu_z)(x - \mu_z)^T A^T] \\ &= A \Sigma A^T \end{aligned}$$

5. PCA under the lense of multivariate normal distributions

- Recall in PCA, we try to find principal components with maximum variance.

- Given some data $\{x_i\}_{i=1}^n \in \mathbb{R}^d$, assume the data is normally distributed and centralized:

$$x \sim N(0, \Sigma)$$

- Eigendecompose covariance matrix Σ :

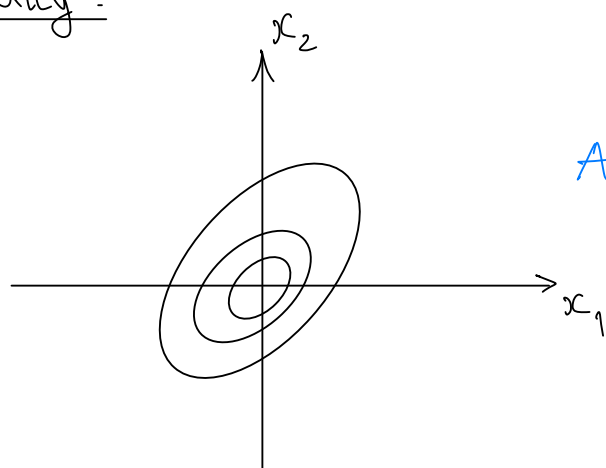
$$\Sigma = Q D Q^T$$

- Let say $A = Q^T$ and $z = Ax + b$, then:

$$z \sim N(0, D)$$

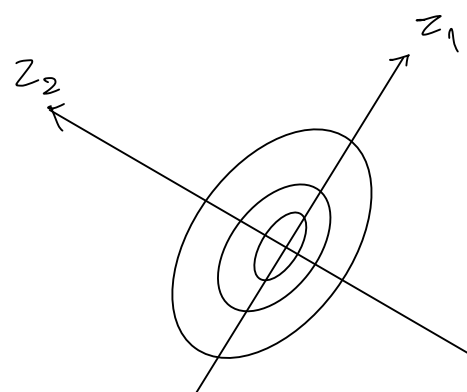
new coordinate system

- Visually:



$$A \Sigma A^T = D$$

PCA



MULTIVARIATE NORMAL (NATURAL FORM)

Standard form: $x \sim N(\mu, \Sigma)$

$$p(x) = \frac{1}{Z} \exp\left(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu)\right)$$

Natural form:

$$x \sim \bar{N}(b, Q)$$

$$p(x) = \frac{1}{C} \exp\left(-\frac{1}{2} x^T Q x + b^T x\right)$$

$$\propto \exp\left(-\frac{1}{2} x^T Q x + b^T x\right)$$

$$Q = \Sigma^{-1}$$

(precision matrix)

$$b = \Sigma^{-1} \mu$$

$$C = \exp\left(-\frac{1}{2} b^T Q^{-1} b\right) / Z$$

(normalization constant)

Proof Standard form equals Natural form

$$\begin{aligned} p(x) &= \frac{1}{Z} \exp\left(-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu)\right) \\ &\propto \exp\left(-\frac{1}{2} \left(x^T \Sigma^{-1} x - 2x^T \Sigma^{-1} \mu + \mu^T \Sigma^{-1} \mu\right)\right) \\ &\propto \exp\left(-\frac{1}{2} x^T \underbrace{\Sigma^{-1}}_Q x + x^T \underbrace{\Sigma^{-1} \mu}_b\right) \end{aligned}$$

Why use natural form?

- Easier to derive conditional distributions
- For example, given some data $\{x_i\}_{i=1}^n \sim N(\mu, \Sigma)$.

Then the **marginal distribution** is given by:

i) In Standard Form:

$$x_1 \sim N(\mu_1, \underbrace{\Sigma_{11}}_{\text{Cov}(x_1)})$$

And the **conditional distribution** is given by:

i) In Standard Form:

$$x_{1|2=a} \sim N(\mu_{1|2}, \underbrace{\Sigma_{1|2}}_{\text{Cov}(x_1 | x_2)})$$

$$\mu_{1|2} = \mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (x_2 - \mu_2)$$

$$\Sigma_{1|2} = \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}$$

$$\begin{aligned} &\text{Cov}(x_1 | x_2) \\ &= Q_{11}^{-1} \end{aligned}$$

ii) In Natural Form:

$$x_{1|2=a} \sim \bar{N}(b_1 - \underbrace{Q_{12} x_2}_{\text{Cov}(x_1 | x_2)}, Q_{11})$$

Proof that $x_1 | x_2 = a \sim \bar{N}(b_1 - Q_{12}x_2, Q_{11})$

Let $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

Then in Natural Form:

$$\begin{aligned} p(x) &\propto \exp \left[-\frac{1}{2} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}^T \begin{bmatrix} Q_{11} & Q_{12} \\ Q_{21} & Q_{22} \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}^T \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \right] \\ &\propto \exp \left[-\frac{1}{2} \left(x_1^T Q_{11} x_1 + \underbrace{x_1^T Q_{12} x_2 + x_2^T Q_{21} x_1}_{Q_{12} = Q_{21}} + x_2^T Q_{22} x_2 \right) + (b_1^T x_1 + b_2^T x_2) \right] \\ &\propto \exp \left[-\frac{1}{2} \left(x_1^T Q_{11} x_1 + 2 x_1^T Q_{12} x_2 + x_2^T Q_{22} x_2 \right) + (b_1^T x_1 + b_2^T x_2) \right] \end{aligned}$$

Conditioned on x_2 (remove x_2 out of the equation)

$$\begin{aligned} p(x_1 | x_2) &\propto \exp \left[-\frac{1}{2} (x_1^T Q_{11} x_1 + 2 x_1^T Q_{12} x_2) + b_1^T x_1 \right] \\ &\propto \exp \left[-\frac{1}{2} x_1^T Q_{11} x_1 + x_1^T (b_1 - Q_{12} x_2) \right] \end{aligned}$$

Therefore, $x_1 | x_2 = a \sim \bar{N}(b_1 - Q_{12}x_2, Q_{11})$

What do Standard Form and Natural Form tell us about the relationship between different features

• **Covariance** matrix $\Sigma = [\sigma_{ij}]_{ij}$ measures **marginal independence**
 $\sigma_{ij} = 0$ if $x_i \perp x_j$

• **Precision** matrix $Q = \Sigma^{-1} = [q_{ij}]_{ij}$ measures **conditional independence**
 $q_{ij} = 0$ if $x_i \perp x_j | x_{-ij}$ (not i and j)

What this means in term of probability?

• Marginal Independence: $x_1 \perp x_2 \Leftrightarrow P(x_1, x_2) = P(x_1) \cdot P(x_2)$

• Conditional Independence: $x_1 \perp x_2 | x_3 \Leftrightarrow P(x_1, x_2 | x_3) = P(x_1 | x_3) \cdot P(x_2 | x_3)$

Proof $x_1 \perp x_2 | x_3 \Leftrightarrow P([x_1, x_2] | x_3) = P(x_1 | x_3) \cdot P(x_2 | x_3)$

• Partition $Q = \begin{bmatrix} Q_{11} & Q_{12} & Q_{13} \\ \vdots & \ddots & \vdots \\ Q_{31} & \dots & Q_{33} \end{bmatrix}$ $b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$

- Using previous work, we can prove that:

$$[x_1, x_2] \mid x_3 \sim \mathcal{N}(\underbrace{b_{1:2} - Q_{1:2,3} x_3}_{\tilde{b}}, \underbrace{Q_{1:2,1:2}}_{\tilde{Q}})$$

- Now we analyze $p([x_1, x_2] \mid x_3)$:

$$\begin{aligned} p([x_1, x_2] \mid x_3) &\propto \exp \left[-\frac{1}{2} (x_1^T Q_{11} x_1 + 2 x_1^T Q_{12} x_2 + x_2^T Q_{22} x_2) \right. \\ &\quad \left. + (\tilde{b}_1^T x_1 + \tilde{b}_2^T x_2) \right] \\ &\propto \underbrace{\exp \left(-\frac{1}{2} x_1^T Q_{11} x_1 + \tilde{b}_1^T x_1 \right)}_{p(x_1 \mid x_3)} \cdot \underbrace{\exp \left(-\frac{1}{2} x_2^T Q_{22} x_2 + \tilde{b}_2^T x_2 \right)}_{p(x_2 \mid x_3)} \end{aligned}$$

So $x_1 \perp x_2 \mid x_3$