

APPLICATIONS MAX-FLOW MIN-CUT

- First, recalls some facts

Relationship between Max-flow and Min-cut Capacity

The minimum s - t cut problem reduces in linear time to the maximum flow problem

Proof: Assume a residual graph G_f , and we know the max flow.

- Then we can just perform a DFS/BFS, which takes linear time from s to t .

- Since no path $s \rightarrow t$, the DFS/BFS will stop before reaching t

Let (A, B) be the cut s.t. $v \in A : v$ is visited during DFS/BFS

$w \in B : w$ is not visited during DFS/BFS

\Rightarrow The cut (A, B) is the minimum-cut that is derived from a given max-flow in $O(n)$ time

Image Segmentation Problem as Min-Cut Capacity Problem

Problem:

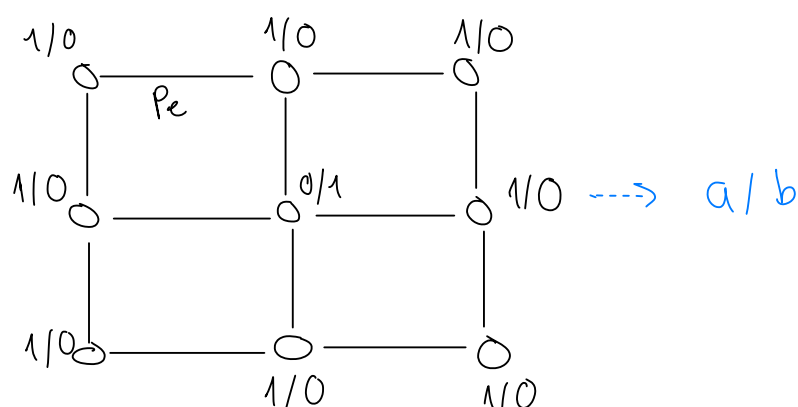
Input: A image

Goal: Segment the image into "foreground" and "background"

The setup:

Think of the image as an undirected graph G , each pixel is a vertex with 2 values $\left\{ \begin{array}{l} a_v : v \in X : \text{foreground set} \\ b_v : v \in Y : \text{background set} \end{array} \right.$

each edge has a value p_e



Let's try to maximize this objective function:

$$f = \sum_{v \in X} a_v + \sum_{v \in Y} b_v - \sum_{e \in \delta(X)} p_e$$

where $\left\{ \begin{array}{l} X: \text{foreground set} \\ Y: \text{background set} \\ \delta(X): \text{set of edges cut by } (X, Y) \end{array} \right.$

Observations:

- Function f is the maximum likelihood function
 - Vertex v "earns" a prize a_v if $v \in X$, similarly "earns" a prize b_v if $v \in Y$
 - An optimal set X and $Y \Leftrightarrow$ Minimum penalty term $\sum_{e \in \delta(X)} p_e$
- \Rightarrow By the last observation, we can "kinda" see that "If we partition X and Y in a way that minimize the penalty term, then the Image Segmentation problem is solved"
- \Rightarrow Very similar to min-cut capacity problem

But there is a problem: How to cast this problem as a Min-cut capacity problem

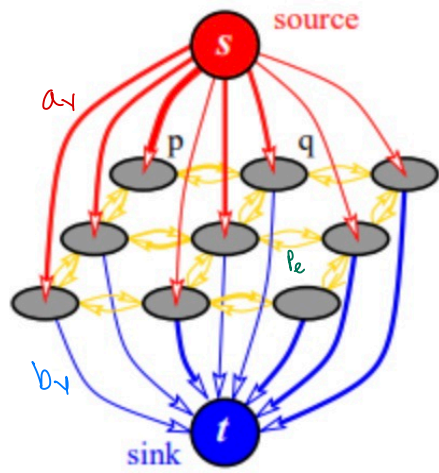
Some differences we can see in Image Segmentation problem and Min-Cut Capacity problem are:

1. No source (s) and sink (t) , undirected edge
2. Each vertex in Image Segmentation problem has 2 values, compare to 1 value in Min-Cut Capacity problem.
3. Maximize problem vs Minimizing problem

Let's address this one by one:

1. No source (s) and sink (t) , undirected edge
 \Rightarrow Add source (s) and sink (t) , convert undirected edge to two directed edges
2. Each vertex in Image Segmentation problem has 2 values, compare to 1 value in Min-Cut Capacity problem.
 $\Rightarrow \left\{ \begin{array}{l} \text{edge } (s, v) \text{ has capacity } c(s, v) = a_v \\ \text{edge } (v, t) \text{ has capacity } c(v, t) = b_v \end{array} \right.$

Base on those description, we can construct a graph G' as follows:



3. Maximize objective function in G vs Minimize cut capacity in G'

We know: Objective function f in G

$$f = \sum_{v \in X} a_v + \sum_{v \in Y} b_v - \sum_{e \in \delta(X)} p_e$$

And: $\operatorname{argmax}(f) = \operatorname{argmin}(-f)$

So, the corresponding objective function in G' has the form

$$\begin{aligned} f' &= -f \\ &= -\sum_{v \in X} a_v - \sum_{v \in Y} b_v + \sum_{e \in \delta(X)} p_e \end{aligned}$$

We can get rid of the negative values by using this fact:

$$\operatorname{argmin}(f) = \operatorname{argmin}(f' + C)$$

$$\text{Let } C = \sum_{v \in X} a_v + \sum_{v \in Y} b_v$$

Then: $f' + C = \sum_{v \in Y} a_v + \sum_{v \in X} b_v + \sum_{e \in \delta(X)} p_e$

↪ objective function of G'

Claim: \exists bijection (one-to-one) between

Partition (X, Y) of $G \longleftrightarrow (S, T)$ cut of G'

such that Objective function f is preserved

We prove 2 things: $\left\{ \begin{array}{l} (X, Y) \longleftrightarrow (S, T) \text{ , Uniqueness , one-to-one} \\ \text{Cut capacity} = \text{objective function } f' \text{ , Preservation} \end{array} \right.$

• First: $(X, Y) \longleftrightarrow (S, T)$

By construction of G' : $\left\{ \begin{array}{l} S = X + \textcircled{2} \\ T = Y + \textcircled{4} \end{array} \right.$

\Rightarrow Proven

• Second: Cut capacity = objective function f'

For a cut $(X + \textcircled{S}, Y + \textcircled{T})$, there are 3 cases:

$$\cdot (s, v) \quad \forall v \in Y \quad \Leftrightarrow c(s, v) = a_v$$

$$\cdot (v, t) \quad \forall v \in X \quad \Leftrightarrow c(v, t) = b_v$$

$$\cdot (u, v) \quad \forall \begin{cases} u \in X \\ v \in Y \end{cases} \quad \Leftrightarrow c(u, v) = p_e$$

Easy to see that the Cut capacity for any cut $(X + \textcircled{S}, Y + \textcircled{T})$

$$\text{is: } \sum_{v \in Y} a_v + \sum_{v \in X} b_v + \sum_{e \in \delta(X)} p_e$$

\Rightarrow which is the same as objective function f' in G'

$$\text{Since: } \operatorname{argmax}_{(X, Y)} f \text{ in } G \quad \longleftrightarrow \quad \operatorname{argmin}_{(S, T)} f' \text{ in } G'$$

Conclude that: \exists bijection between 2 sets G and G'

$$\text{such that: } \operatorname{argmax}_{(X, Y)} f \text{ in } G \quad \longleftrightarrow \quad \operatorname{argmin}_{(S, T)} f' \text{ in } G'$$

\Rightarrow Proven Claim

Bipartite Matching as Max-flow

The problem:

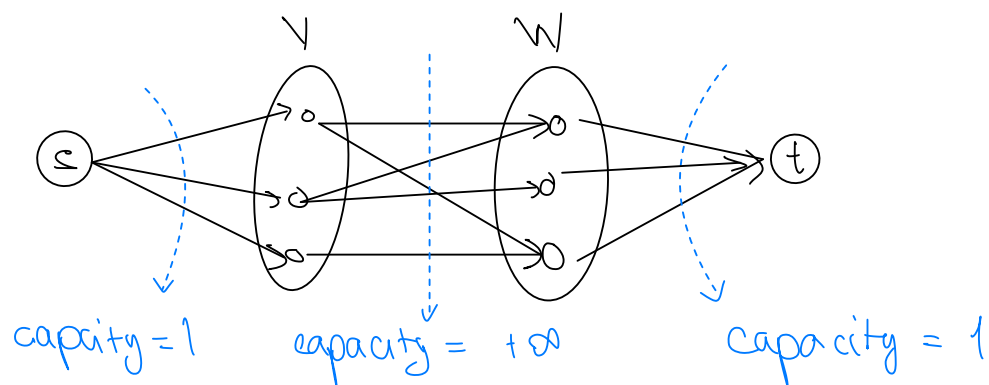
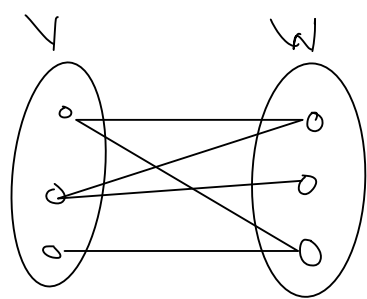
Input : Bipartite graph $G = (V, W, E)$

Matching = Subset of edges $M \subseteq E$ with no shared endpoints

Goal : Find max-cardinality subset M

Claim : Bipartite Matching Problem reduces to Max-flow problem in $O(n)$

Convert bipartite graph G to flow network G'



Prove the claim by proving: \exists bijection between
Matchings in $G \iff$ Integral flows in G'
(such that preserves Objective function)

Proof:

- \forall edge (v, w) s.t. $v \in V, w \in W$ that is a match in $G \iff 0 < f(v, w) < c(v, w)$
 \Rightarrow edges $\begin{cases} (s, v) = 1 \\ (w, t) = 1 \end{cases}$
 \Rightarrow create a flow in G' : $s \rightarrow v \rightarrow w \rightarrow t$ ①
 - \forall vertex v of a matching edge (v, w) cannot belongs to another matching edge ②
 - \forall vertex v belongs to a flow $s \rightarrow v \rightarrow w \rightarrow t$ cannot appear in an augmenting path again ③
- ①, ② and ③ \Rightarrow matchings in $G \iff$ flows in G'

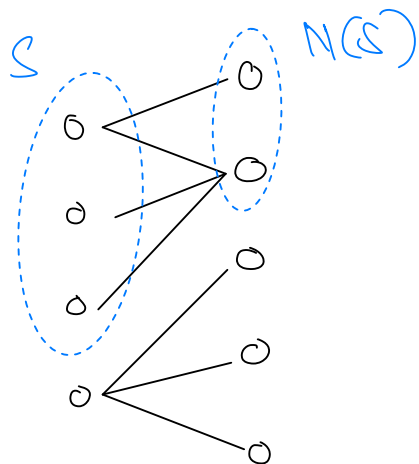
Hall's theorem

Assume V is the LHS set, and $|LHS| < |RHS|$:

\exists perfect matching $\Leftrightarrow \forall S \subseteq V, |S| \leq |N(S)|$

In words:

If you can find a "restricting subset" in your bipartite graph, meaning a set S in the LHS (assume $|LHS| < |RHS|$) such that $|S| > |N(S)|$, then there are some vertices in S without a match



\Rightarrow Cant match all of S
 \Rightarrow No perfect-matching

Proof: Hall's theorem

• Case 1: Perfect matching (ie all V matches all W)

\Rightarrow Trivially true

• Case 2: Non-perfect matching (Given 100 edges between V and W , and 40 matchings - How do we know we have the max-cardinality matching?)