

GRAPHICAL MODEL

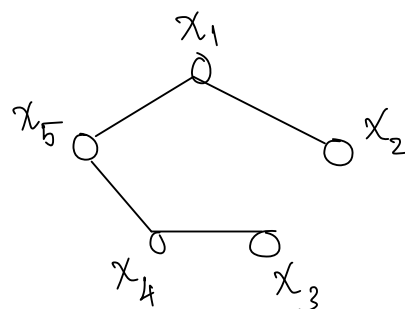
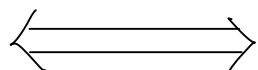
◦ Prerequisites: Multivariate Normal, Precision Matrix

Main idea:

- Recall that Precision Matrix measure conditional independence
- We can actually represent the Precision Matrix using a graph.

Given this **sparse** precision matrix:

$$\begin{matrix} & x_1 & \dots & & x_5 \\ \begin{matrix} x_1 \\ \vdots \\ x_5 \end{matrix} & \begin{bmatrix} 2 & 1 & & & 1 \\ 1 & 2 & & & 1 \\ & & 2 & 1 & \\ & & 1 & 2 & 1 \\ 1 & 1 & & 1 & 2 \end{bmatrix} \end{matrix}$$



We can read **Markov** (conditional independence) from the graph, like:

$$i) \quad x_1 \perp (x_3, x_4) \mid (x_2, x_5)$$

Markov blanket

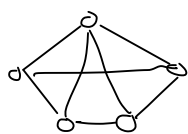
Condition on (x_2, x_5) will make x_1 independent (x_3, x_4)

$$ii) \quad i, j \text{ disconnected} \Rightarrow x_i \perp x_j \mid x_{-ij}$$

If 2 nodes are disconnected, then they are independent conditioned on any path between them (example: x_2 and x_3)

Why not use Covariance Matrix:

- Recall that the Covariance Matrix measure the marginal independence between variables (features), it is pairwise
- If we were to graph out the Covariance Matrix, we would get a fully connected graph (if all variables are correlated)



This is not very meaningful.

How to find (estimate) the graph?

- Use a technique called **Graphical Lasso**. The main idea is to use **maximum likelihood** estimation with some **penalty** to encourage sparsity
- Mathematically:

$$\hat{Q} = \underset{Q}{\operatorname{argmax}} \log P(D \mid Q) - \lambda \phi(Q)$$

$$\text{where } D = \{x_i\}_{i=1}^n \sim N(0, \Sigma), \quad Q = \Sigma^{-1}$$

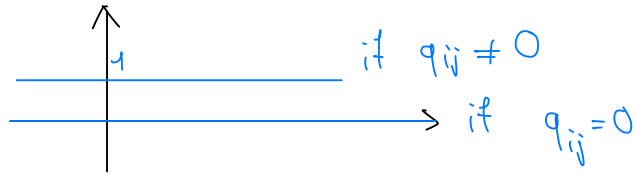
• On the penalty:

Its "strict" definition is the number of edges, called L_0 norm

$$\phi(Q) = \|Q\|_0 = \sum_{i \neq j} I(q_{ij} \neq 0) = \# \text{ of edges}$$

$$= \sum_{i \neq j} q_{ij}^0 = \begin{cases} 0 & \text{if } q_{ij} = 0 \\ 1 & \text{otherwise} \end{cases}$$

\Rightarrow This function is not convex, so its hard to maximize



So we relax the definition and use L_1 norm instead:

$$\phi(Q) = \|Q\|_1 = \sum_{i \neq j} |q_{ij}|$$

$$= \begin{cases} 0 & \text{if } q_{ij} = 0 \\ |q_{ij}| & \text{otherwise} \end{cases}$$

\Rightarrow This function is convex, and can be maximized

