REPRESENTING POLYNOMIALS

2 ways to represent polynomials

There are 2 ways: coefficient form and point-value form

· Coefficient form-

For a polynomial $A(x) = \sum_{j=0}^{n-1} a_j x^j$. The coefficient representation is vector $\alpha = (a_0, a_1, \dots, a_{n-1})$

· Point - value form:

For a polynomial $A(x) = \sum_{j=0}^{n-1} a_j x^j$. The point-value representation is a set of n point-value pairs: $\binom{j}{x_0, y_0}, (x_1, y_1), \ldots, (x_{n-1}, y_{n-1})$ such that $y_j = A(x_0)$

Convert from Coefficient Form to Point-value Form, and vice versos:

· From Coefficient Form to Point-value Form

Problem: Given vector $\alpha = (\alpha_0, \alpha_1, \dots, \alpha_{n-1})$ represents a polynomial $A(x) = \sum_{j=0}^{n-1} a_j x^j$. Find a set of n distinct points such that $y_j = A(x_0)$.

- =) This is actually the process of evaluating A(x) at a diotinct points.
- => Using Horner's Method, this takes O(n2)
- =) Using Fast Fourier Transform, this takes O(nlogn)

 -> discussed in Discrete Fourier Transform"

. From Point-talue Form to Coefficient Form

Problem: Crisen a set of n distinct point-value points: $\frac{d(x_0, y_0)}{d(x_0, y_0)}, (x_1, y_1), \dots, (x_{n-1}, y_{n-1})$

Find the vector $a = (a_0, a_1, \dots, a_{n-1})$ represent the coefficients of polynomial $A(x) = \sum_{j=0}^{n-1} a_j x^j$

=> This is actually the process of interpolation A(x) given n distints pairs.

=> There are 3 ways to interpolation:

Note that I ways to interpolation:

or Inverse Vander-monde matrix:

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$$a = V^{-1}y$$
, where $V = \begin{bmatrix} 1 & x_0 & x_0^2 & \dots & x_0^{-1} \\ 1 & x_1 & x_1^2 & \dots & x_{n-1}^{-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n-1} & x_{n-1}^2 & \vdots & \vdots \\ 1 & x_{n-1} & x_{n-1}$

o <u>lagrange</u>'s formula:

$$A(x) = \sum_{k=0}^{n-1} y_k \frac{T_{j+k}(x-y_j)}{T_{j+k}(x_{k-j})}$$

This cost $O(n^2)$

This cost O(n logn)

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