

## LINEAR PROGRAMMING

Motivation example:

	Book	Calculator
Sales	\$ 20	\$ 18
Cost	\$ 5	\$ 4
Time	5 minutes	15 minutes

- Monthly cost must not exceed \$ 27 000
- How many books and calculators should the company make to maximize profit? Determine max profit in 30 day period?

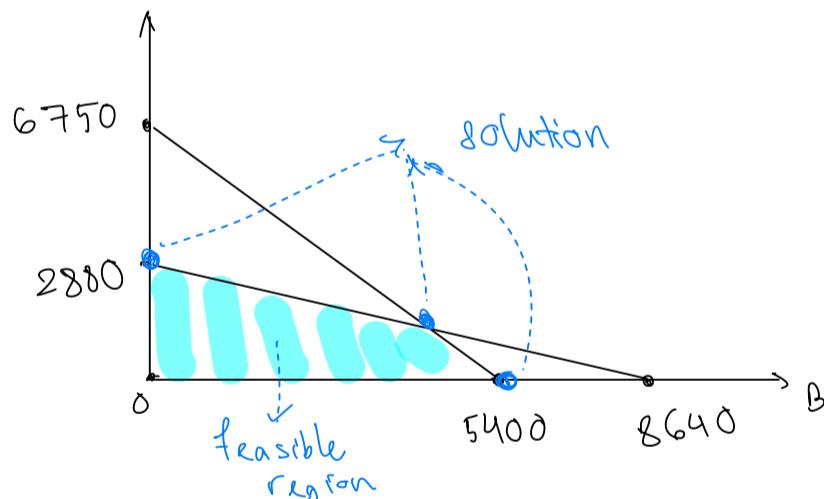
Let  
 $B = \begin{cases} \text{books in a month} \\ \text{calculators in a month} \\ \text{profits in a month} \end{cases}$

Constraints:  $\begin{cases} 5B + 4C \leq 27000 & (1) \\ 5B + 15C \leq 43200 & (2) \end{cases}$

Objective:  $\max P = 15B + 14C \quad (3)$

Solution:

1. Find intersects (1) and (2) on the axis



$$\begin{aligned} \text{. } B=0 \text{ in (1)} &\Rightarrow C=6750 \\ \text{. } C=0 \text{ in (1)} &\Rightarrow B=5400 \\ \text{. } B=0 \text{ in (2)} &\Rightarrow C=2880 \\ \text{. } C=0 \text{ in (2)} &\Rightarrow B=8640 \end{aligned}$$

2. Find intersection of (1) and (2):

$$\begin{aligned} \text{Solve } \begin{cases} 5B + 4C = 27000 \\ 5B + 15C = 43200 \end{cases} \\ \Rightarrow \begin{cases} B = 4221 \\ C = 1473 \end{cases} \end{aligned}$$

3. Find solution to objective

$$P = \underset{B,C}{\operatorname{argmax}} (15B + 14C) : (B,C) = \begin{cases} (0, 2880) \\ (4221, 1473) \\ (5400, 0) \end{cases}$$

$$\Rightarrow P = 83937 \text{ with } (B,C) = (4221, 1473)$$

## Linear Program Components

### 1. Decision Variables

$$x_1, x_2, \dots, x_n \in \mathbb{R}$$

### 2. Linear Constraints

$$\sum_{j=1}^d a_{ij} x_j \leq b_i \quad \text{where } a_{ij}, b_i \text{ are constants}$$

(part of the input)

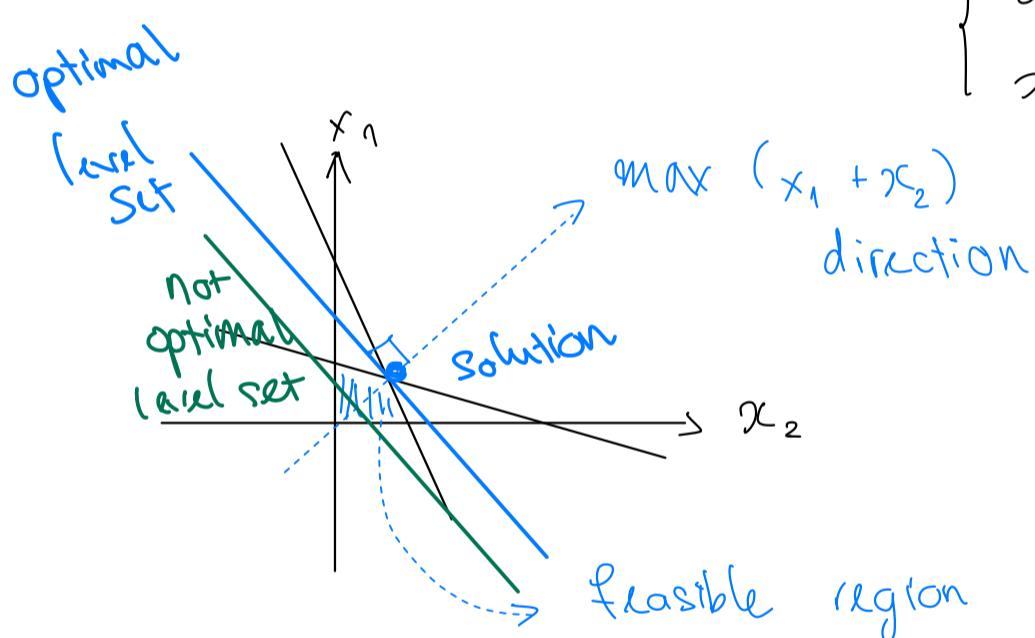
### 3. Objective function

$$\max / \min \sum_{j=1}^n c_j x_j$$

$\Rightarrow$  If you have these 3 components defined, then you have a linear program

Example 1: Consider this LP :  $\max (x_1 + x_2)$

$$\begin{cases} 2x_1 + x_2 \leq 1 \\ x_1 + 2x_2 \leq 1 \end{cases}$$



$\Rightarrow$  Optimal at the "level set" that is "furthest out" in the feasible region

In general:

- feasible region = intersection of half spaces

Recall: in  $\mathbb{R}^n$  problem space, solution is a line / plane of dimension  $(n-1)$ . If we talk ab inequalities, then we have a half space divided by that solution line / plane

- level sets = parallel hyperplanes

- Optimal solution = furthest point in feasible region in direction  $c$

## Edge cases

### 1. Infeasible linear programming

Constraints:  $x_1 \leq -5$

$$x_1 \geq 0$$

Objective: Maximize  $x_1$

### 2. Unbounded linear programming (opt value = $\pm \infty$ )

Constraint:  $x_1 > 0$

Objective: Maximize  $x_1$

"Feasible:" means satisfying all the constraints

## Slack variable:

These statements are similar:

Constraint:  $x_1 + x_2 \leq 7$   
 $\forall x_1, x_2 \geq 0$

Constraint:  $x_1 + x_2 + x_3 = 7$   
 $\forall x_1, x_2, x_3 \geq 0$

## Linear Programming Problem

Maximise / Minimise a linear function subject to linear constraints

For example: Maximise  $c^T x$  subject to:  $\begin{cases} Ax \leq b \\ x \geq 0 \end{cases}$

where:  $\begin{cases} x \in \mathbb{R}^n : n \times 1 \text{ vector} \\ c \in \mathbb{R}^n : n \times 1 \text{ vector} \\ A \in \mathbb{R}^{m \times n} : m \times n \text{ matrix} \\ b \in \mathbb{R}^m : m \times 1 \text{ matrix} \end{cases}$

## Purpose:

Linear Programming is a tool we used to answer the question  
 "How do we know we are done" when designing an algorithm

## Other examples

- Inequalities
- Max-flow min-cut with constraints (capacities)

## Applications

### 1. Max-flow

- Decision variables:  $f_e : e \in E$  (flows)
- Constraints:
  - flow in = flow out for any vertices not  $\circled{S}$  or  $\circled{T}$
$$\sum_{e \in \delta^-(v)} f_e = \sum_{e \in \delta^+(v)} f_e$$
- capacity constraint

$$0 \leq f_e$$

$$f_e \leq c_e$$

#### Objective function:

Maximize flow going out of the source

$$\max \sum_{e \in \delta^+(s)} f_e$$

### 2. Min-cost flow

- Decision variables:  $f_e : e \in E$

#### Constraints:

- At each vertex, inflow - outflow equals the supply / demand at that vertex:

$$\sum_{\text{in}(v)} f_e - \sum_{\text{out}(v)} f_e = b_v$$

where

$$\begin{cases} b_v > 0 & : \text{vertex } v \text{ is "supply" vertex} \\ b_v < 0 & : \text{vertex } v \text{ is "demand" vertex} \\ b_v = 0 & : \text{vertex } v \text{ is "intermediate" vertex} \end{cases}$$

- Capacity constraints
- Objective func:

$$\min \sum c_e f_e$$

## Duality of Linear Program

Any linear program has a dual.

For example: Given this linear program

$$\begin{array}{l} \text{"Maximize } c^T x \text{ subject to } \\ \quad \left\{ \begin{array}{l} Ax \leq b \\ x \geq 0 \end{array} \right. \end{array}$$

Its "dual" is:

$$\begin{array}{l} \text{"Minimize } y^T b \text{ subject to } \\ \quad \left\{ \begin{array}{l} A^T y \geq c \\ y \geq 0 \end{array} \right. \end{array}$$

$$\text{where } \left\{ \begin{array}{l} y \in \mathbb{R}^m \\ c \in \mathbb{R}^n \\ A \in \mathbb{R}^{m \times n} \\ b \in \mathbb{R}^m \end{array} \right.$$

→ Dual of dual is Primal

$$\begin{array}{ll} \begin{array}{l} \text{"Max } c^T x, \text{ constraints } \\ \quad \left\{ \begin{array}{l} Ax \leq b \\ x \geq 0 \end{array} \right. \end{array} & \equiv \begin{array}{l} \text{"Min } -c^T x, \text{ constraints } \\ \quad \left\{ \begin{array}{l} -Ax \geq -b \\ x \geq 0 \end{array} \right. \end{array} \\ \text{primal-dual} & \text{primal-dual} \end{array}$$

$$\begin{array}{ll} \begin{array}{l} \text{"Min } y^T b, \text{ constraints } \\ \quad \left\{ \begin{array}{l} A^T y \geq c \\ y \geq 0 \end{array} \right. \end{array} & \equiv \begin{array}{l} \text{"Max } -y^T b, \text{ constraints } \\ \quad \left\{ \begin{array}{l} -A^T y \leq -c \\ y \geq 0 \end{array} \right. \end{array} \end{array}$$

## Weak Duality Theorem

Given Primal: "Maximize  $c^T x$  subject to  $Ax \leq b$  and  $x \geq 0$ "

Dual: "Minimize  $y^T b$  subject to  $A^T y \geq c$  and  $y \geq 0$ "

If  $x$  is feasible in Primal,  $y$  is feasible in Dual

$$\Rightarrow c^T x \leq y^T b$$

→ Proof:

$$\begin{aligned} & A^T y \geq c \\ \Leftrightarrow & y^T A \geq c^T \\ \Leftrightarrow & y^T A x \geq c^T x \quad \langle x \geq 0 \rangle \\ \text{Since } & b \geq A x \Leftrightarrow y^T b \geq y^T A x \\ \Rightarrow & y^T b \geq c^T x \end{aligned}$$

### Corollary 1: Weak Duality

If  $x$  is feasible in Primal,  $y$  is feasible in Dual,  
and  $c^T x = y^T b$   
 $\Rightarrow x$  is optimal for Primal,  $y$  is optimal for Dual

Proof: (by contradiction)

Assume  $\exists y'$  that is "more optimal" in Dual

$$\begin{aligned} \Rightarrow y'^T b &< y^T b \\ &= c^T x \end{aligned}$$

$\Rightarrow$  Contradicts the condition  $y^T b = c^T x$

### Corollary 2: Weak Duality

If the Primal is **feasible** and **unbounded**, then Dual is **infeasible**

### Strong Duality Theorem

Given Primal: "Maximize  $c^T x$  subject to  $Ax \leq b$  and  $x \geq 0$ "

Dual: "Minimize  $y^T b$  subject to  $A^T y \geq c$  and  $y \geq 0$ "

If either (1) Both Primal and Dual are feasible

[2] Only Primal is feasible and bounded

Then: } Both Primal and Dual are feasible and bounded

} Primal and Dual have the same objective function

## Combinations of Primal - Dual Pairs

There are 3 possible categories for any LP

- Feasible and bounded
- Feasible and unbounded
- Infeasible

The possible combinations of Primal - Dual are:

1. Primal is feasible and bounded  $\Rightarrow$  Dual is feasible and bounded
2. Primal is feasible and unbounded  $\Rightarrow$  Dual is infeasible
3. Primal is infeasible  $\Rightarrow$ 
  - Dual is feasible and unbounded
  - Dual is infeasible

## Upper bound

### Case 1 - Concrete numbers

Given this LP:  $\max (x_1 + x_2)$

$$\text{s.t. } \begin{cases} 4x_1 + x_2 \leq 2 \\ x_1 + 2x_2 \leq 1 \end{cases}$$

We can have these upper bounds:

$$\begin{aligned} - x_1 + x_2 &\leq 4x_1 + x_2 \leq 2 & \text{because } (1,1) \leq (4,1) \\ - x_1 + x_2 &\leq x_1 + 2x_2 \leq 1 & (1,1) \leq (1,2) \\ - x_1 + x_2 &\leq \frac{1}{7}(4x_1 + x_2) + \frac{3}{7}(x_1 + 2x_2) \\ &\leq \frac{1}{7} \cdot 2 + \frac{3}{7} \cdot 1 \\ &= \frac{5}{7} \Rightarrow \text{tightest bound} \end{aligned}$$

### Case 2: No-concrete numbers

Consider this LP:  $\max \sum_{j=1}^n c_j x_j \rightarrow c^T x$

s.t.  $\sum_{j=1}^n a_{ij} x_j \leq b_i \quad \forall 1 \leq i \leq m$

$\downarrow \quad A\mathbf{x} \leq \mathbf{b}$

Similar to case 1, we can deduce the upper bound as follows.

Suppose  $\exists y_1, y_2, \dots, y_m \geq 0$  that satisfy:

$$\sum_{i=1}^m y_i a_{ij} \geq c_j \quad \forall 1 \leq j \leq n \rightarrow A^T y \geq c$$

$$\begin{aligned} \text{Then: } \sum_{j=1}^n c_j x_j &\leq \sum_{j=1}^n \left( \sum_{i=1}^m y_i a_{ij} \right) x_j \\ &= \sum_{i=1}^m y_i \left( \sum_{j=1}^n a_{ij} x_j \right) \\ &\leq \sum_{i=1}^m y_i b_i \rightarrow y^T b \end{aligned}$$

Conclusion: If  $y \geq 0$  s.t. (\*): the mentioned LP problem holds  
the optimal solution is upper-bounded by  $y^T b$ .

$\rightarrow$  We try to get the "tightest" bound, so objective func =  $\min(y^T b)$

So:  $\max(c^T x) \text{ s.t. } A\mathbf{x} \leq \mathbf{b} \Leftrightarrow \min(y^T b) \text{ s.t. } A^T y \geq c$

$\Rightarrow$  Proof for duality of Linear Program

$$\text{Denote } \begin{cases} P = LP \max(c^T x) \text{ s.t. } Ax \leq b & \text{Primal} \\ D = LP \min(y^T b) \text{ s.t. } A^T y \geq c & \text{Dual} \end{cases}$$

Then by construction (the green highlight particularly)

$$\begin{matrix} \text{Optimal}(P) & \leq & \text{Optimal}(D) \\ \text{Primal} & \leq & \text{Dual} \end{matrix}$$

### Sanity check Case 1:

<u>Primal</u>	<u>Dual</u>
$P = \max(x_1 + x_2)$ s.t. $\begin{cases} 4x_1 + x_2 \leq 2 \\ x_1 + 2x_2 \leq 1 \end{cases}$ $\Rightarrow$ Tightest upper-bound: $x_1 + x_2 \leq \frac{5}{7}$	$D = \min(2y_1 + y_2)$ s.t. $\begin{cases} 4y_1 + y_2 \leq 1 \\ y_1 + y_2 \leq 1 \end{cases}$ $\Rightarrow$ Tightest lower-bound: $2y_1 + y_2 \geq \frac{5}{7}$

Since:  $\begin{cases} \text{Optimal}(P) \leq \text{Optimal}(D) \\ P \leq \frac{5}{7} \leq D \end{cases}$

$\Rightarrow$  Optimal solution for both  $P$  and  $D$  is  $\frac{5}{7}$

### Duality in Max Flow

Alternative LP: Maximize Paths instead of edges

. Decision variables:  $f_e \quad \forall e \in E$

. Constraints:

. Capacity constraint: "for all path  $p$  s.t. edge  $e$  belongs to, the total flow should not exceed the capacity"

$$\sum_{e \in p} f_e \leq c_e \quad \forall e \in E$$

. Flow conservations constraint is automatically satisfied by formulation of the Alternative LP

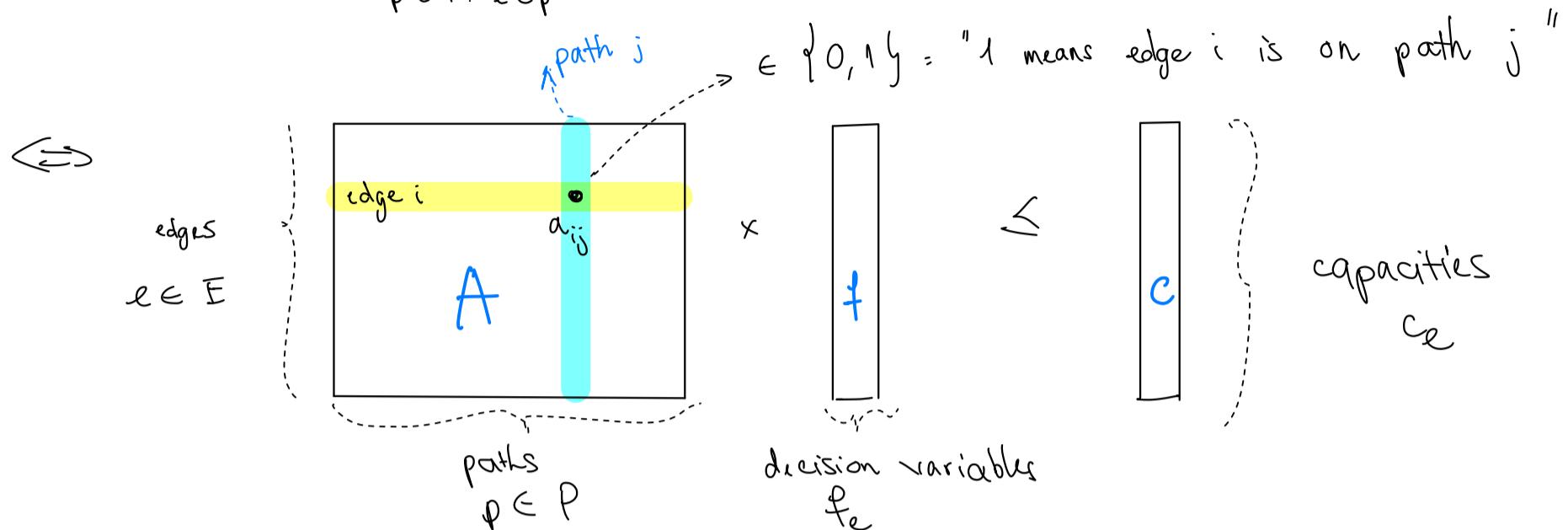
. Objective: Maximize flows of all s-t paths

$$\max \sum_{p \in P: e \in p} f_e$$

Think of this Alternative LP in terms of matrix:

Let's think of the constraint:

$$\sum_{p \in P: e \in p} f_e \leq c_e \quad \forall e \in E$$



We try to maximize:  $1^T f$  where  $\begin{cases} 1^T : \text{vector size } (1 \times P) \\ f : \text{vector size } (1 \times P) \end{cases}$

### Dual of Alternative LP

Let variable  $l_e$  correspond to every  $f_e$  s.t.  $l_e \geq 0$

Then in theory, the dual is:

$$\text{"Min } l^T c \text{ s.t. } A^T l \geq 1"$$

$$\sum_{e \in E} c_e \cdot l_e \quad \forall e \in E$$

$$\sum_{e \in p} l_e \geq 1 \quad \forall p \in P$$

$\Leftrightarrow$  This inequality holds for every path

$\Rightarrow$  Also holds for the "shortest path"

Interpretation of the Dual: Compute nonnegative lengths on the edges so that if you compute the shortest path, it has length at least 1.

$\Rightarrow$  Objective function meaning:  $\min l^T c$  - minimizing the "volume" of "a pipe" of length  $\geq 1$  and width = capacity

### Observations

. Dual's constraints ~ Primal's decision variables

$$l_e \quad \forall e \in E$$

$$f_e \quad \forall e \in E$$

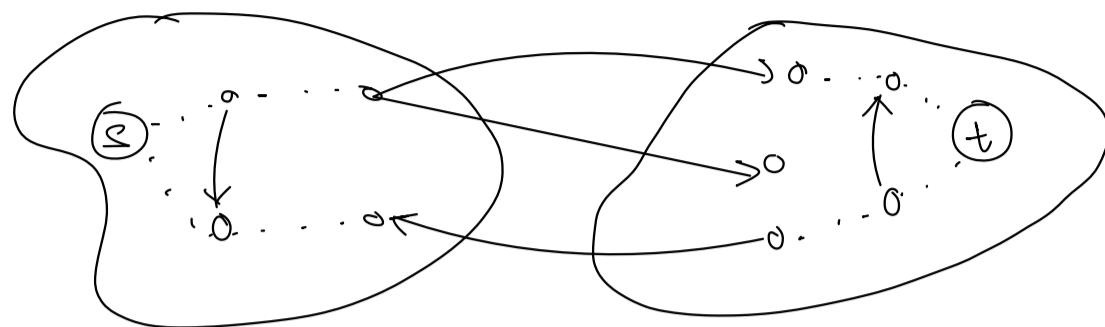
. Dual's decision variables ~ Primal's constraints

$$l_e \quad \forall e \in E$$

$$f_e \quad \forall e \in E$$

## Connection Min-Capacity Cut and the Dual

Fix your favorite s-t cut  $(A, B)$ , there are 3 kind of edges - internal, forward, backward



$$\text{S.t.: } l_e = \begin{cases} 1 & : \text{edge "sticking out" of } A \\ 0 & : \text{otherwise} \end{cases}$$

Claim:  $\forall$  possible cuts, the result is "feasible" solution of Dual  
In other words: Any s-t path in any cut will have length of at least 1

$$\sum_{e \in p} l_e \geq 1 \quad \forall p \in P$$

Proof Claim: Since  $l_e = 1$  for edge "stick out" of A  
 $\Rightarrow$  That edge must belong to some s-t path ( $p \in P$ )  
 $\Rightarrow$  Any s-t path created by the cut  $(A, B)$  have length at least 1 (you cannot have a path of all 0-length edges)

Active function: Instead of minimizing the "volume" in the Dual, we minimizing only the capacity of the cut

$$\begin{aligned} & \text{Min } \sum_{e \in P} c_e l_e \quad (\text{Dual Obj}) \\ &= \text{Min } \sum_{e \in S^+(A)} c_e \quad \left( \begin{array}{l} \text{Replace } \begin{cases} l_e = 1 & : e \in S^+(A) \\ l_e = 0 & : e \notin S^+(A) \end{cases} \end{array} \right) \\ &= \text{Min Capacity of cut } (A, B) \end{aligned}$$

Conclusion: • For every s-t cut, we can extract a feasible solution to the Dual (minimizing "volume") with the same objective function (minimizing capacity)  
 $\Rightarrow$  Min Cut Capacity is a "special case" of the Dual  
 $\Rightarrow$  Optimal (Dual)  $\leq$  Min cut capacity

Main Takeaways : Max flow Min Cut as LP

$$\text{Max flow} = \text{Optimal (Primal)} \leq \text{Optimal (Dual)} = \text{Min Volume (1)}$$
$$\leq \text{Min Cut Capacity} \quad (2)$$

(1) : By construction

(2) : Explained in previous page

Weak Duality

Stronger takeaway : Using Maxflow MinCut theorem

We know that in Maxflow MinCut theorem

$$\text{Maxflow} = \text{MinCut Capacity}$$

So, we can strengthen our conclusion above to say that:

$$\begin{aligned}\text{Maxflow} &= \text{Optimal (Primal)} = \text{Optimal (Dual)} \\ &= \text{Min Cut Capacity}\end{aligned}$$

Strong Duality