

Robust Optimization: Static Case

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 - How to add uncertainty in an optimization problem
 - Why shall you do Robust Optimization ?
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 - Ellipsoidal uncertainty set
 - Polyhedral uncertainty set
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An optimization problem

A generic optimization problem can be written

$$\begin{array}{ll} \min_x & L(x) \\ \text{s.t.} & g(x) \leq 0 \end{array}$$

where

- x is the decision variable
- L is the objective function
- g is the constraint function

An optimization problem with uncertainty

Adding uncertainty ξ in the mix

$$\begin{aligned} \min_x \quad & L(x, \tilde{\xi}) \\ \text{s.t.} \quad & g(x, \tilde{\xi}) \leq 0 \end{aligned}$$

Remarks:

- $\tilde{\xi}$ is unknown. Two main way of modelling it:
 - $\tilde{\xi} \in R$ with a known uncertainty set R , and a pessimistic approach. This is the **robust optimization** approach (RO).
 - $\tilde{\xi}$ is a random variable with known probability law. This is the **Stochastic Programming** approach (SP).
- Cost is not well defined.
 - RO: $\max_{\xi \in R} L(x, \xi)$.
 - SP: $\mathbb{E}[L(x, \xi)]$.
- Constraints are not well defined.
 - RO: $g(x, \xi) \leq 0, \quad \forall \xi \in R$.
 - SP: $g(x, \xi) \leq 0, \quad \mathbb{P} - a.s.$

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Requirements and limits

- Stochastic optimization:
 - requires a law of the uncertainty ξ
 - can be hard to solve (generally require discretizing the support and blowing up the dimension of the problem)
 - there exists specific methods (like Bender's decomposition)
- Robust optimization:
 - requires an uncertainty set R
 - can be overly conservative, even for reasonable R
 - complexity strongly depend on the choice of R
- Distributionally robust optimization:
 - is a mix between robust and stochastic optimization
 - consists in solving a stochastic optimization problem where the law is chosen in a robust way
 - is a fast growing fields with multiple recent results
 - but is still hard to implement than other approaches

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Some numerical tests on real-life LPs

From Ben-Tal and Nemirovski

- take LP from Netlib library
- look at non-integer coefficients, assuming that they are not known with perfect certainty
- What happens if you change them by 0.1% ?
 - constraints can be violated by up to 450%
 - $\mathbb{P}(\text{violation} > 0) = 0.5$
 - $\mathbb{P}(\text{violation} > 150\%) = 0.18$
 - $\mathbb{E}[\text{violation}] = 125\%$

What do you want from robust optimization ?

- finding a solution that is less sensible to modified data, without a great increase of price
- choosing an uncertainty set R that:
 - offer robustness guarantee
 - yield an easily solved optimization problem

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Solving a robust optimization problem

The robust optimization problem we want to solve is¹

$$\begin{array}{ll} \min_x & L(x) \\ \text{s.t.} & g(x, \xi) \leq 0 \quad \forall \xi \in R \end{array}$$

Two main approaches are possible:

Constraint generation: replace R by a finite set of ξ , that is we replace an "infinite number of constraints" by a finite number of them.

Reformulation: replace $g(x, \xi) \leq 0 \quad \forall \xi \in R$,
by $\sup_{\xi \in R} g(x, \xi) \leq 0$,
then explicit the sup.

¹For simplicity reason we dropped w.l.o.g. the uncertainty in the objective.

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Constraint generation algorithm

Data: Problem parameters, reference uncertainty ξ_0

Result: approximate value with gap;

for $k \in \mathbb{N}$ **do**

 solve $\tilde{v} = \min_x \{L(x) \mid g(x, \xi_k) \forall k \leq k\} \rightsquigarrow x_k$;

 solve $s = \max_{\xi \in R} g(x_k, \xi) \rightsquigarrow \xi_{k+1}$;

if $s \leq 0$ **then**

 Robust optimization problem solved,
 with value \tilde{v} and optimal solution x_k

Algorithm 1: Constraint Generation Algorithm

Note that we are solving a problem similar to the deterministic problem with an increasing number of constraints.

This is easy to implement and can be numerically efficient.

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Reformulation principle

We can write the robust optimization problem as

$$\begin{array}{ll} \min_x & L(x) \\ \text{s.t.} & \sup_{\xi \in R} g(x, \xi) \leq 0 \end{array}$$

Now, there are two ways of simplifying this problem:

- we can explicitly compute $\bar{g}(x) = \sup_{\xi \in R} g(x, \xi)$;
 - by duality we can write $\sup_{\xi \in R} g(x, \xi) = \min_{\eta \in Q} h(x, \eta)$
- ➡ $\min_{\eta \in Q} h(x, \eta) \leq 0$ is equivalent to $\exists \eta$ such that $h(x, \eta) \leq 0$, i.e. just add η as a variable in your optimization problem

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Canonization of the problem

We consider

$$\begin{aligned} \min_{x \geq 0} \quad & \max_{(A,b,c) \in R} \quad c^\top x \\ \text{s.t.} \quad & Ax \leq b \end{aligned}$$

Without loss of generality we can consider a deterministic cost:

$$\begin{aligned} \min_{x \geq 0, \theta} \quad & \theta \\ \text{s.t.} \quad & Ax \leq b & \forall (A, b, c) \in R \\ & c^\top x \leq \theta & \forall (A, b, c) \in R \end{aligned}$$

That can be written as

$$\begin{aligned} \min_{x \geq 0, \theta} \quad & \theta \\ \text{s.t.} \quad & a_i^\top x - b_i \leq 0 & \forall (A, b, c) \in R, \forall i \in [m] \end{aligned}$$

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Canonization of the problem

II

We now consider

$$\begin{array}{ll} \min_{x \geq 0} & c^\top x \\ \text{s.t.} & a_i^\top x - b_i \leq 0 \quad \forall (A, b) \in R, \forall i \in [m] \end{array}$$

Let R_i be the projection of R onto coordinate i .

We have in particular $R \subset R_1 \times \cdots \times R_m$.

But note that, in the robust constraint, R can be replaced by $R_1 \times \cdots \times R_m$, indeed,

$$\begin{aligned} f_i(x, \xi_i) \leq 0, \quad \forall i \in [m], \quad \forall \xi \in R \\ \iff f_i(x, \xi_i) \leq 0, \quad \forall i \in [m], \forall \xi \in R_1 \times \cdots \times R_m \\ \iff f_i(x, \xi_i) \leq 0, \quad \forall \xi_i \in R_i \quad \forall i \in [m] \end{aligned}$$

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Canonization of the problem



We now consider

$$\min_{x \geq 0} \quad c^\top x$$

$$s.t. \quad a_i^\top x - b_i \leq 0$$

$$\forall (a_i, b_i) \in R_i, \forall i \in [m]$$

Canonization of the problem



We now consider

$$\min_{x \geq 0} \quad c^T x$$

$$s.t. \quad a^T x - b \leq 0$$

$$\forall (a, b) \in R,$$

Canonization of the problem



We now consider

$$\begin{array}{ll} \min_{x \geq 0} & c^\top x \\ \text{s.t.} & a^\top x - b \leq 0 \end{array} \quad \forall (a, b) \in R,$$

To model correlation we set

$$a = \bar{a} + P\zeta \quad b = \bar{b} + p^\top \zeta$$

where (\bar{a}, \bar{b}) are the nominal value, and ζ is the primitive/residual uncertainty.

Canonization of the problem



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The robust constraint now reads

$$(\bar{a}^\top x - \bar{b}) + (P^\top x - p)^\top \zeta \leq 0 \quad \forall \zeta \in \mathcal{Z}$$

Canonization of the problem

IV

Example: assume that a is a random variable with mean \bar{a} and covariance Σ . Then, a natural reformulation would be

$$a = \bar{a} + \Sigma^{1/2} \zeta,$$

so that ζ is centered with uncorrelated coordinates.

Finally, w.l.o.g. we assume that b is deterministic (can be obtained by adding a variable x_{n+1} constrained to be equal to 1).

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An explicit worst case value

- We consider an ellipsoidal uncertainty set

$$R = \left\{ \xi = \{\bar{a} + P\zeta\}_i \mid \|\zeta\|_2 \leq \rho \right\}$$

- Here we can, for a given x , explicitly compute

$$\begin{aligned} \sup_{\xi \in R} \xi^\top x &= \bar{a}^\top x + \sup_{\|\zeta\|_2 \leq \rho} (P\zeta)^\top x \\ &= \bar{a}^\top x + \rho \|P^\top x\|_2 \end{aligned}$$

- Hence, constraint

$$\sup_{\xi \in R} \xi^\top x \leq b$$

can be written

$$\bar{a}^\top x + \rho \|P^\top x\|_2 \leq b$$

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SOCp problem

- An Second Order Cone Programming constraint is a constraint of the form

$$\|Ax + b\|_2 \leq c^T x + d$$

- An SOCP problem is a (continuous) optimization problem with linear cost and linear and SOCP constraints
- There exists powerful software to solve SOCP (e.g. CPLEX, Gurobi, MOSEK...) with dedicated interior points methods
- There exist a duality theory akin to the LP duality theory
- If a robust optimization problem can be cast as an SOCP the formulation is deemed efficient

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Linear duality: recalls

- Recall that, if finite,

$$\begin{aligned} \max_{\xi} \quad & \xi^\top x \\ \text{s.t.} \quad & D\xi \leq d \end{aligned}$$

as the same value as

$$\begin{aligned} \min_{\eta} \quad & \eta^\top d \\ \text{s.t.} \quad & \eta^\top D = x \\ & \eta \geq 0 \end{aligned}$$

- Thus,

$$\begin{aligned} \sup_{\xi: D\xi \leq d} \xi^\top x \leq b & \iff \min_{\eta \geq 0: \eta^\top D = x} \eta^\top d \leq b \\ & \iff \exists \eta \geq 0, \quad \eta^\top D = x, \quad \eta^\top d \leq b \end{aligned}$$

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Polyhedral uncertainty

- We consider a polyhedral uncertainty set

$$R = \left\{ \xi \mid D\xi \leq d \right\}$$

- Then the robust optimization problem

$$\begin{aligned} \min_{x \geq 0} \quad & c^\top x \\ \text{s.t.} \quad & \sup_{\xi \in R} \xi^\top x \leq h \end{aligned}$$

reads

$$\begin{aligned} \min_{x \geq 0, \eta \geq 0} \quad & c^\top x \\ \text{s.t.} \quad & \eta^\top d \leq h \\ & \eta^\top d = x \end{aligned}$$

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Soyster model

The problem

$$\min_{\mathbf{x}} \mathbf{c}^T \mathbf{x}$$

$$\tilde{\mathbf{A}} \mathbf{x} \leq \mathbf{b}$$

$$\forall \tilde{\mathbf{A}} \in \mathcal{R}$$

$$\underline{\mathbf{x}} \leq \mathbf{x} \leq \bar{\mathbf{x}}$$

where each coefficient $\tilde{a}_{ij} \in [\bar{a}_{ij} - \delta_{ij}, \bar{a}_{ij} + \delta_{ij}]$

Soyster model

The problem

$$\begin{aligned} \min_{\mathbf{x}} \quad & \mathbf{c}^T \mathbf{x} \\ & \sup_{\tilde{\mathbf{A}} \in R} \tilde{\mathbf{A}} \mathbf{x} \leq \mathbf{b} \\ & \underline{\mathbf{x}} \leq \mathbf{x} \leq \bar{\mathbf{x}} \end{aligned}$$

where each coefficient $\tilde{a}_{ij} \in [\bar{a}_{ij} - \delta_{ij}, \bar{a}_{ij} + \delta_{ij}]$

Soyster model

The problem

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where each coefficient $\tilde{a}_{ij} \in [\bar{a}_{ij} - \delta_{ij}, \bar{a}_{ij} + \delta_{ij}]$
can be written

$$\begin{aligned} \min_{\mathbf{x}} \quad & \mathbf{c}^\top \mathbf{x} \\ & \sum_j \bar{a}_{ij} x_j + \sum_j \delta_{ij} |x_j| \leq b_i \quad \forall i \\ & \underline{\mathbf{x}} \leq \mathbf{x} \leq \bar{\mathbf{x}} \end{aligned}$$

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$$\begin{aligned} \min_{\mathbf{x}} \quad & \mathbf{c}^T \mathbf{x} \\ & \sum_j \bar{a}_{ij} x_j + \sum_j \delta_{ij} y_j \leq b_i \quad \forall i \\ & \underline{\mathbf{x}} \leq \mathbf{x} \leq \bar{\mathbf{x}} \\ & y_j \geq x_j, \quad y_j \geq -x_j \end{aligned}$$

Cardinality constrained LP

Soyster's model is over conservative, we want to consider a model where only Γ_i coefficient per line have non-zero errors, leading to

$$\min_{x,y} c^T x$$

$$\sum_j \bar{a}_{ij} x_j + \max_{S_i: |S_i|=\Gamma_i} \sum_{j \in S_i} \delta_{ij} y_j \leq b_i \quad \forall i$$

$$\underline{x} \leq x \leq \bar{x}$$

$$y_j \geq x_j, \quad y_j \geq -x_j$$

Cardinality constrained LP

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$$\begin{aligned}
 & \min_{x,y} c^T x \\
 & \sum_j \bar{a}_{ij} x_j + \beta_i \leq b_i \quad \forall i \\
 & \max_{S_i: |S_i|=\Gamma_i} \sum_{j \in S_i} \delta_{ij} y_j \leq \beta_i \\
 & \underline{x} \leq x \leq \bar{x} \\
 & y_j \geq x_j, \quad y_j \geq -x_j
 \end{aligned}$$

Cardinality constrained LP

II

This means that, for line i we take a margin of

$$\beta_i(x, \Gamma_i) := \max_{S_i: |S_i|=\Gamma_i} \sum_{j \in S_i} \delta_{ij} |x_j|$$

which can be obtained as

$$\begin{aligned} \beta_i(x, \Gamma_i) = \max_{z \geq 0} \quad & \sum_j \delta_{ij} |x_j| z_{ij} \\ & \sum_j z_{ij} \leq \Gamma_i & [\lambda_i] \\ & z_{ij} \leq 1 & [\mu_{ij}] \end{aligned}$$

This LP can be then dualized to be integrated in the original LP.

Cardinality constrained LP



$$\begin{aligned}\beta_i(x, \Gamma_i) = \max_{z \geq 0} \quad & \sum_j \delta_{ij} |x_j| z_{ij} \\ & \sum_j z_{ij} \leq \Gamma_i \quad [\lambda_i] \\ & z_{ij} \leq 1 \quad [\mu_{ij}]\end{aligned}$$

Cardinality constrained LP



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$$\beta_i(x, \Gamma_i) = \max_{z \geq 0} \min_{\lambda, \mu \geq 0} \sum_j \delta_{ij} |x_j| z_{ij} + \lambda_i \left(\Gamma_i - \sum_j z_{ij} \right) \sum_j \mu_{ij} (1 - z_{ij})$$

Cardinality constrained LP



$$\begin{aligned}
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 &= \min_{\lambda, \mu \geq 0} \max_{z \geq 0} \lambda_i \Gamma_i + \sum_j \mu_{ij} \quad + \sum_j z_{ij} \left(\delta_{ij} |x_j| - \lambda_i - \mu_{ij} \right)
 \end{aligned}$$

Cardinality constrained LP



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 &= \min_{\lambda, \mu \geq 0} \lambda_i \Gamma_i + \sum_j \mu_{ij} \\
 \text{s.t.} \quad & \delta_{ij} |x_j| \leq \lambda_i + \mu_{ij}
 \end{aligned}$$

Cardinality constrained LP

IV

In the end we obtain

$$\begin{aligned}
 & \min_{\mathbf{x}, \beta, \lambda, \mu} \mathbf{c}^\top \mathbf{x} \\
 & \sum_j \bar{a}_{ij} x_j + \beta_i \leq b_i \quad \forall i \\
 & \lambda_i \Gamma_i + \sum_j \mu_{ij} \leq \beta_i \quad \forall i \\
 & \delta_{ij} x_j \leq \lambda_i + \mu_{ij} \quad \forall i, j \\
 & -\delta_{ij} x_j \leq \lambda_i + \mu_{ij} \quad \forall i, j \\
 & \lambda \geq 0, \quad \mu \geq 0 \\
 & \underline{\mathbf{x}} \leq \mathbf{x} \leq \bar{\mathbf{x}}
 \end{aligned}$$

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Robust constraint implying a probabilistic guarantee

Definition

We say that, for a given set of probability measures $\mathbb{P} \in \mathcal{P}$, the constraint

$$g(x, \xi) \leq 0, \quad \forall \xi \in R,$$

implies a probabilistic guarantee of level ε if, for all $\mathbb{P} \in \mathcal{P}$,

$$\mathbb{P}\left(g(x, \xi) \leq 0\right) \geq 1 - \varepsilon.$$

Probability guarantee for ellipsoidal uncertainty

- We consider a linear constraint

$$\sum_j \tilde{a}_{ij} x_j \leq b_i, \quad \forall i \in [m]$$

- We assume that $\tilde{a}_{ij} = \bar{a}_{ij}(1 + \varepsilon \xi_{ij})$ where ξ_{ij} is a random variable with mean 0, contained in $[-1, 1]$, and independent in j .
- Then the robust constraint

$$\sum_j \bar{a}_{ij} x_j + \varepsilon \Omega \sqrt{\sum_j \bar{a}_{ij}^2 x_j^2} \leq b_i^+, \quad \forall i \in [m]$$

implies a probabilistic guarantee of level $1 - e^{-\Omega^2/2}$.

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A combinatorial optimization problem with cardinality constraint

We consider a combinatorial optimization problem:

$$\begin{aligned} \min_{x \in \{0,1\}^N} \quad & \max_{\tilde{c} \in R} \tilde{c}^T x \\ \text{s.t.} \quad & x \in X \end{aligned}$$

where R is such that each $\tilde{c}_i \in [\bar{c}_i, \bar{c}_i + \delta_i]$, with at most Γ coefficient deviating from \bar{c}_i .
Thus, the problem reads

$$\begin{aligned} (P) \quad \min_{x \in \{0,1\}^N} \quad & \bar{c}^T x + \max_{|S| \leq \Gamma} \sum_{i \in S} \delta_i x_i \\ \text{s.t.} \quad & x \in X \end{aligned}$$

wlog we assume that the i are ordered by decreasing cost uncertainty span:
 $\delta_1 \geq \delta_2 \geq \dots \geq \delta_n$.

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wlog we assume that the i are ordered by decreasing cost uncertainty span:
 $\delta_1 \geq \delta_2 \geq \dots \geq \delta_n$.

Solving the robust combinatorial problem

We can write (P) as

$$\begin{aligned} \min_{x \in \{0,1\}^N} \quad & \max_{\zeta \in [0,1]^n} \quad \bar{c}^\top x + \sum_{i=1}^n \delta_i x_i \zeta \\ \text{s.t.} \quad & x \in X \\ & \sum_{i=1}^n \zeta \leq \Gamma \end{aligned}$$

For a given $x \in X$ we dualize the inner maximization LP problem

Solving the robust combinatorial problem

II

Thus we can write (P) as

$$\begin{aligned} \min_{x, y, \theta} \quad & \bar{c}^\top x + \Gamma \theta + \sum_{j=1}^n y_j \\ \text{s.t.} \quad & x \in X \\ & y_j + \theta \geq \delta_j x_j \\ & y_j, \theta \geq 0 \end{aligned}$$

Note that an optimal solution satisfies

$$y_j = (\delta_j x_j - \theta)^+ = (\delta_j - \theta)^+ x_j$$

as $x_j \in \{0, 1\}$, and $\theta \geq 0$.

Solving the robust combinatorial problem

II

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Thus we can write (P) as

$$\begin{aligned} \min_{\theta \geq 0} \min_{\mathbf{x}} \quad & \bar{\mathbf{c}}^\top \mathbf{x} + \Gamma \theta + \sum_{j=1}^n x_j (\delta_j - \theta)^+ \\ \text{s.t.} \quad & \mathbf{x} \in X \end{aligned}$$

We can now decompose the problem for $\theta \in [\delta_\ell, \delta_{\ell-1}]$ where $\delta_{n+1} = 0$ and $\delta_0 = +\infty$. Therefore, we have

$$\text{val}(P) = \min_{\ell \in [n]} Z^\ell$$

where

$$Z^\ell = \min_{\mathbf{x} \in X, \theta \in [\delta_\ell, \delta_{\ell-1}]} \bar{\mathbf{c}}^\top \mathbf{x} + \Gamma \theta + \sum_{j=1}^{\ell-1} x_j (\delta_j - \theta)$$

Solving the robust combinatorial problem



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Solving the robust combinatorial problem

IV

As the problem is linear in θ we have that

$$Z^\ell = \min_{\mathbf{x} \in X, \theta \in [\delta_\ell, \delta_{\ell-1}]} \bar{\mathbf{c}}^\top \mathbf{x} + \Gamma \theta + \sum_{j=1}^{\ell-1} x_j (\delta_j - \theta)$$

is attained for $\theta = \delta_\ell$ or $\theta = \delta_{\ell-1}$.

So in the end, we have

$$\text{val}(P) = \min_{\ell \in [n]} G^\ell$$

where

$$G^\ell = \Gamma \delta_\ell + \min_{\mathbf{x} \in X} \left\{ \bar{\mathbf{c}}^\top \mathbf{x} + \sum_{j=1}^{\ell} \underbrace{(\delta_j - \delta_\ell)}_{\geq 0} x_j \right\}$$

Algorithm for the robust problem

- ① For $\ell \in [n]$, solve

$$G^\ell = \Gamma \delta_\ell + \min_{x \in X} \left\{ \bar{c}^\top x + \sum_{i=1}^{\ell} (\delta_i - \delta_\ell) x_j \right\}$$

with optimal solution x_ℓ

- ② Set $\ell^* \in \arg \min_{\ell \in [n]} G^\ell$
- ③ Return $val(P) = G^{\ell^*}$ and $x^* = x_\ell$

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Why do robust optimization ?

- Because you want to account for some uncertainty
- Because you want to have a solution that resists to changes in data
- Because your data is unprecise and robustness yield better out-of-sample result
- Because you do not have the law of the uncertainty
- Because you can control the robustness level
- Because your problem is "one-shot"

Which uncertainty set to choose ?


- An uncertainty set that is computationally tractable
- An uncertainty set that yields good results
- An uncertainty set that have some theoretical soundness
- An uncertainty set that take available data into account
- Select uncertainty set / level through cross-validation


Is there some theoretical results ?


- Yes: with some assumption over the randomness (e.g. bounded and symmetric around \bar{a}) some uncertainty set (e.g. ellipsoidal) have a probabilistic guarantee:


$$\forall \xi \in R_\varepsilon, \quad g(x, \xi) \leq 0 \quad \implies \quad \mathbb{P}(g(x, \xi) \leq 0) \geq 1 - \varepsilon$$


- Yes: in some cases approximation scheme for nominal problem can be extended to robust problem (e.g. cardinal uncertainty in combinatorial problem)
- Yes: using relevant data we can use statistical tools to construct a robust set R that imply a probabilistic guarantee

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