

ROB311 Quiz 3

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One-Shot Multi-Agent Decision Problems

1 Multi-Agent Problems

Summary: In a **Multi-Agent problem**, we assume that:

- Set of states for environment is \mathcal{S}
- P agents within environment.
- For each state $s \in \mathcal{S}$:
 - possible actions for agent i is $\mathcal{A}_i(s)$
 - set of action profiles is $\mathcal{A}(s) = \prod_{i=1}^P \mathcal{A}_i(s)$
- possible state-action pairs are $\mathcal{T} = \{(s, a) \text{ s.t. } s \in \mathcal{S}, a \in \mathcal{A}(s)\}$
- environment in some origin state, s_0
- environment destroyed after N transitions
- agent j wants to find policy $\pi_j(a_j | s)$ so that $\mathbb{E}[r_j(p)]$ is maximized
- agents act independently given the environmen

Name	Function:
State transition given state-action pair defined by $\text{tr} : \mathcal{T} \rightarrow \mathcal{S}$	$\text{tr}(s, a) = \text{state transition from } s \text{ under } a$
Reward to each agent, i defined by $r_i : \mathcal{Q} \times \mathcal{S} \rightarrow \mathbb{R}_+$	$r_i(s, a, \text{tr}(s, a)) = \text{rwd to agent } i \text{ for } (s, a, \text{tr}(s, a))$
State evolution of environment after N transitions	$p = \langle (s_0, a^{(1)}, s_1), \dots, (s_{N-1}, a^{(N)}, s_N) \rangle$
<ul style="list-style-type: none"> • Given sequence of actions: $p.a = \langle a^{(1)}, \dots, a^{(n)} \rangle$ • $s_N = \tau(s_{n-1}, a^{(n)})$ 	
reward to agent i	$r_i(p) = \sum_{n=1}^N r_i(s_{n-1}, a^{(n)}, s_n)$
expected-reward (value) of playing a from s for agent j	$p(s' s) := \mathbb{P}[S_{t+1} = s' S_t = s]$
Prob. that state of the env. after T transitions is s	$p_T(s) := \mathbb{P}[S_T = s]$ $= \sum_{s'} p_{T-1}(s') p(s s')$
<ul style="list-style-type: none"> • $p_{T-1}(s')$: Prob. s' at $T-1$ (given) <ul style="list-style-type: none"> – $p_0(s)$: Base case • $p(s s')$: Prob. s given s' (from graph) 	

1.1 Action Equilibria

1.1.1 Finding Action Equilibria

1.2 Strategy Equilibria

1.2.1 Finding Strategy Equilibria

1.2.2 Existence of Strategy Equilibria

1.2.3 Convergence of Strategy Equilibria

1.3 Examples

1.3.1 Optimal Action Profiles