```
Intro: Random Experiment: An outcome for each run. Sample Space Ω: Set of all possible outcomes. Event: Subsets of Ω.
Event: Subsets of \Omega.

Prob. of Event A: P(A) = \frac{\text{Number of outcomes in A}}{\text{Number of outcomes in }\Omega}

Axioms: P(A) \ge 0 \ \forall A \in \Omega, P(A) = 1,

If A \cap B = \emptyset, then P(A \cup B) = P(A) + P(B) \ \forall A, B \in \Omega

Cond. Prob. P(A|B) = \frac{P(A \cap B)}{P(B)}

* P(A \cap B) = P(A|B)P(B) = P(B|A)P(A)

Independence: P(A|B) = P(A|B)P(A) = P(A|B)P(A)

Total Prob. Thm: If H_1, H_2, \dots, H_n form a partition of \Omega, then P(A) = \sum_{i=1}^n P(A|H_i)P(H_i).

Bayes' Rule: P(H_i \mid A) = P(H_i \cap A) = P(A|H_i)P(H_i)
 Bayes' Rule: P(H_k|A) = \frac{P(H_k \cap A)}{P(A)} = \frac{P(A|H_k)P(H_k)}{\sum_{i=1}^n P(A|H_i)P(H_i)}
*Posteriori: P(H_k|A), Likelihood: P(A|H_k), Prior: P(H_k)
1 RV: CDF: F_X(x) = P[X \le x]
PMF: P_X(x_j) = P[X = x_j] \ j = 1, 2, \dots
   PDF: f_X(x) = \frac{d}{dx} F_X(x)
    *P[a \le X \le b] = \int_a^b f_X(x) dx IS THIS CORRECT?
   Cond. PMF: P_X(x|A) = P[X = x|A] = \frac{P[X=x,A]}{P[A]} IS THIS
  Variance: \sigma_X^2 = \operatorname{Var}[X] = E[(X - E[X])^2] = E[X^2] - E[X]^2

Cond. Exp.: E[X|A] = \int_{-\infty}^{\infty} x f_X(x|A) dx

2 RVs: Joint PMF: P_{X,Y}(x,y) = P[X = x, Y = y]

Joint PDF: f_{X,Y}(x,y) = \frac{\partial^2}{\partial x \partial y} F_{X,Y}(x,y)
 Joint PDF: f_{X,Y}(x,y) = \frac{1}{\partial x}\partial y F_{X,Y}(x,y)

*P[(X,Y) \in A] = \int \int_{(x,y) \in A} f_{X,Y}(x,y) dx dy

Exp.: E[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y)f_{X,Y}(x,y) dx dy

Correlation (Corr.): E[XY]

Covar.: Cov[X,Y] = E[(X - \mu_X)(Y - \mu_Y)] = E[XY] - E[X]E[Y]

Corr. Coeff.: \rho_{X,Y} = E\left[\left(\frac{X - \mu_X}{\sigma_X}\right)\left(\frac{Y - \mu_Y}{\sigma_Y}\right)\right] = \frac{Cov[X,Y]}{\sigma_X\sigma_Y}

Marginal PMF: P_X(x) = \sum_{j=1}^{\infty} P_{X,Y}(x,y)j

Marginal PDF: f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy
  Cond. PDF: f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_{Y}(y)}
  f_{Y|X}(y|x) = \frac{f_{X,Y}(x,y)}{f_{X}(x)} = \frac{f_{X|Y}(x|y)f_{Y}(y)}{\int_{-\infty}^{\infty} f_{X|Y}(x|y')f_{Y}(y') dy'}
*P_{X|Y}(y|x) = \frac{P_{X,Y}(x,y)}{P_{X}(y)} = \frac{P_{X|Y}(x|y)P_{Y}(y)}{P_{X}(y)}
  \begin{split} ^*P_{Y\mid X}(y\mid x) &= \frac{P_{X,Y}(x,y)}{P_{X}(x)} = \frac{P_{X\mid Y}(x\mid y)P_{Y}(y)}{\sum_{j=1}^{\infty}P_{X\mid Y}(x\mid y_{j})P_{Y}(y_{j})}\\ \mathbf{Ind.:}\ \ f_{X\mid Y}(x\mid y) &= f_{X}(x)\ \forall y \Leftrightarrow f_{X,Y}(x,y) = f_{X}(x)f_{Y}(y) \end{split}
   *If independent, then uncorrelated: Uncorrelated: Cov[X,Y] = 0 \Leftrightarrow \rho_{X,Y} = 0
Uncorrelated: \operatorname{Cov}[X,Y] = 0 \Leftrightarrow \rho_{X,Y} = 0
Orthogonal: E[XY] = 0
Cond. \operatorname{Exp.}: E[Y] = E[E[Y|X]] \text{ or } E[E[h(Y)|X]]
*E[E[Y|X]] \text{ w.r.t. } X \mid E[Y|X] \text{ w.r.t. } Y.
Estimation: Estimate unknown parameter \theta from n i.i.d. measurements X_1, X_2, \ldots, X_n, \hat{\Theta}(X) = g(X_1, X_2, \ldots, X_n)
Estimation Error: \hat{\Theta}(X) - \theta.
Unbiased: \hat{\Theta}(X) is unbiased if E[\hat{\Theta}(X)] = \theta.
*Asymptotically unbiased: \lim_{n \to \infty} E[\hat{\Theta}(X)] = \theta.
Consistent: \hat{\Theta}(X) is consistent if \hat{\Theta}(X) \to \theta as n \to \infty or \forall \epsilon > 0, \lim_{n \to \infty} P[|\hat{\Theta}(X) - \theta] < \epsilon] \to 1.
Sample Mean: M_n = \frac{1}{n}S_n = \frac{1}{n}\sum_{i=1}^n X_i.
*Given a sequence of i.i.d. RVs, X_1, X_2, \ldots, X_n, M_n is unbiased and consistent.
Chebychev's Inequality: P[|X - E[X]| > \epsilon] < \frac{\operatorname{Var}[X]}{\epsilon}
   Chebychev's Inequality: P[|X - E[X]| \ge \epsilon] \le \frac{\operatorname{Var}[X]}{2}
    Weak Law of Large #s: \lim_{n\to\infty} P[|M_n - \mu| < \epsilon] = 1 \ \forall \epsilon > 0
  0. ML Estimation: Choose parameter \theta that is most likely to generate the obs. x_1, x_2, \ldots, x_n.
  *Disc: \hat{\Theta} = \arg\max_{\theta} P_{\underline{X}}(\underline{x}|\theta) \stackrel{\log}{\to} \hat{\theta} = \arg\max_{\theta} \sum_{i=1}^{n} \log P_{X}(x_{i}|\theta)
  *Cont: \hat{\Theta} = \arg \max_{\theta} f_{\underline{X}}(\underline{x}|\theta) \xrightarrow{\log \theta} \hat{\theta} = \arg \max_{\theta} \sum_{i=1}^{n} \log f_{X}(x_{i}|\theta)

Maximum A Posteriori (MAP) Estimation:
    *Disc: \hat{\theta} = \arg \max_{\theta} P_{\Theta|\underline{X}}(\theta|\underline{x}) = \arg \max_{\theta} P_{\underline{X}|\Theta}(\underline{x}|\theta)P_{\Theta}(\theta)
   *Cont: \hat{\theta} = \arg \max_{\theta} f_{\Theta|X}(\theta|\underline{x}) = \arg \max_{\theta} f_{X|\Theta}(x|\theta) f_{\Theta}(\theta)
*f_{\Theta|X}(\theta|\underline{x}): Posteriori, f_{X|\Theta}(\underline{x}|\theta): Likelihood, f_{\Theta}(\theta): Prior
\begin{split} \text{Bayes' Rule: } P_{\Theta|X}(\theta|\underline{x}) &= \begin{cases} \frac{P_X|\Theta(\underline{x}|\theta)P_{\Theta}(\theta)}{P_X(\underline{x})} \\ \frac{f_X|\Theta(\underline{x}|\theta)P_{\Theta}(\theta)}{f_X(\underline{x})} \end{cases} \\ f_{\Theta|X}(\theta|\underline{x}) &= \begin{cases} \frac{P_X|\Theta(\underline{x}|\theta)P_{\Theta}(\theta)}{f_X(\underline{x})} \\ \frac{f_X|\Theta(\underline{x}|\theta)f_{\Theta}(\theta)}{f_X(\underline{x})} \\ \frac{f_X|\Theta(\underline{x}|\theta)f_{\Theta}(\theta)}{f_X(\underline{x})} \\ \frac{f_X|\Theta(\underline{x}|\theta)f_{\Theta}(\theta)}{f_X(\underline{x})} \end{aligned} \quad \text{if $\underline{X}$ cont.} \\ * \text{Independent of $\theta$: } f_X(\underline{x}) &= f^{\infty} \end{cases}
                                                                                                                                                                                                 if X disc.
                                                                                                                                                                                                   if X cont.
    *Independent of \theta: f_{\underline{X}}(\underline{x}) = \int_{-\infty}^{\infty} f_{\underline{X}|\Theta}(\underline{x}|\theta) f_{\Theta}(\theta) d\theta
  \begin{array}{l} \textbf{Beta Prior } \Theta \text{ is a Beta R.V. } \text{w/ } \alpha, \beta > 0 \\ f_{\Theta}(\theta) = \begin{cases} \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} \theta^{\alpha - 1} (1 - \theta)^{\beta - 1} & \text{if } 0 < \theta < 1 \\ 0 & \text{otherwise} \end{cases} \end{array}
                                                                                                                                                    otherwise
 \begin{cases} 0 & \text{for } x = 1 \\ 0 & \text{for } t^{x-1} e^{-t} \ dt \end{cases}
Prop.: 1. \Gamma(x+1) = x\Gamma(x). For m \in \mathbb{Z}^+, \Gamma(m+1) = m!.
2. \beta(\alpha,\beta) = \frac{(\alpha+\beta-1)!}{(\alpha-1)!(\beta-1)!} = \beta \binom{\alpha+\beta-1}{\alpha-1}
3. Expected Value: E[\Theta] = \frac{\alpha}{\alpha+\beta} \text{ for } \alpha, \beta > 0
   4. Mode (max of PDF): \frac{\alpha-1}{\alpha+\beta-2} for \alpha, \beta > 1
   Drawing Beta Dist. 1. Label x-axis from 0 to 1. 2. Identify
  mode.
3. Determine shape based on \alpha and \beta: \alpha = \beta = 1 (uniform), \alpha = \beta > 1 (bell-shaped, peak at 0.5), \alpha = \beta < 1 (U-shaped w/ high density near 0 and 1), \alpha > \beta (left-skewed), \alpha < \beta
  w/ mgi density field \phi and \Gamma), \alpha > \beta (fete-skewed), \alpha < \beta (right-skewed). Least Mean Squares (LMS) Estimation: Assume prior P_{\Theta}(\theta) or f_{\Theta}(\theta) w/ obs. X = \underline{x}. *\hat{\theta} = g(\underline{x}) = \mathbb{E}[\Theta|\underline{X} = \underline{x}] \mid \hat{\Theta} = g(\underline{X}) = \mathbb{E}[\Theta|\underline{X}]
  *E[X] = \frac{a+b}{2}, Var[X] = \frac{(b-a)^2}{12}
Conditional Exp. E[X|Y] = \int_{-\infty}^{\infty} x f_{X|Y}(x|y) dx
```

```
Binary Hyp. Testing: H_0: Null Hyp., H_1: Alt. Hyp.
  TI Err. (False Rejection): Reject H_0 when H_0 is true. *\alpha(R) = P[\underline{X} \in R \mid H_0] TII Err. (False Accept.): Accept H_0 when H_1 is true. *\beta(R) = P[\underline{X} \in R^c \mid H_1]
  ^*L(\underline{x}) = \frac{P_{\underline{X}}(\underline{x}|H_1)}{P_{\underline{X}}(\underline{x}|H_0)} \mathop{\gtrless}_{H_0}^{H_1} 1 \text{ or } \xi
   *MLT: 1, LRT: \xi
Neyman-Pearson Lemma: Given a false rejection prob. (\alpha), the LRT offers the smallest possible false accept. prob. (\beta),
    and vice versa. *LRT produces (\alpha, \beta)
                                                                                                                                   no that lie on the efficient frontier.
 Bayesian Hyp. Testing: MAP Rule: L(\underline{x}) = \frac{p_{\underline{X}}(\underline{x}|H_1)}{p_{\underline{X}}(\underline{x}|H_0)} \overset{H_1}{\gtrless} \frac{P[H_0]}{P[H_1]}
  Min. Cost Bayes' Dec. Rule: C_{ij} is cost of choosing H_j when H_i is true. Given obs. \underline{X} = \underline{x}, the exp. cost of choosing H_j is A_j(\underline{x}) = \sum_{i=0}^l C_{ij} P[H_i|\underline{X} = \underline{x}].
\begin{aligned} & \text{Min. Cost Dec. Rule: } L(\underline{x}) = \frac{P_{\underline{X}}(\underline{x}|H_1)}{P_{\underline{X}}(\underline{x}|H_0)} \begin{tabular}{l} $H_1$ & $(C_{01}-C_{00})P[H_0]$ \\ & & & \\ \hline 
   Notation: P_{\underline{X}|\Theta}(\underline{x}|\theta), only put RVs in subscript, not values.
   P_X(\underline{x}|H_i), didn't put H in subscript b/c it's not a RV.
   Binomial # of successes in n trials, each w/ prob. p
   b(x \mid n, p) = {n \choose x} p^x (1-p)^{n-x}, x = 0, 1, 2, \dots
\begin{array}{l} b(x\mid n,p) = \binom{n}{x} p^x (1-p)^{n-x}, x=0,1,2,\dots \\ *E[X] = \mu = np \mid Var(X) = \sigma^2 = np(1-p) \\ \text{Multinomial} \# \text{ of } x_i \text{ successes in } n \text{ trials, each w/ prob. } p_i \\ f(x_i\mid p_i \forall i,n) = \frac{n!}{x_1!\dots x_m!} p_1^{x_1} \dots p_m^{x_m} \\ *\sum_i x_i = n, \text{ and } \sum_{i=1}^m p_i = 1 \\ *E[X_i] = \mu_i = np_i \mid Var(X_i) = \sigma_i^2 = np_i (1-p_i) \\ \text{Hypergeometric} \# \text{ of successes in } n \text{ draws from } N \text{ items, } k \text{ of which are successes} \\ h(x\mid N,n,k) = \frac{\binom{k}{x}\binom{N-k}{n-x}}{\binom{N}{n}} \\ *\max\{0,n-(N-k)\} \leq x \leq \min\{n,k\} \\ *E[X] = \mu = \frac{nk}{N} \mid Var(X) = \sigma^2 = \frac{N-n}{N-1} \cdot n \cdot \frac{k}{N} \cdot \left(1-\frac{k}{N}\right) \\ \text{Negative Binomial} \# \text{ of trials until } k \text{ successes, each w/ prob.} \end{array}
   b^*(x \mid k, p) = {x-1 \choose k-1} p^k (1-p)^{x-k}
  \begin{array}{l} (k-1)^p \\ *x \geq k, x = k, k+1, \dots \\ *E[X] = \mu = \frac{k}{p} \mid Var(X) = \sigma^2 = \frac{k(1-p)}{p^2} \\ \textbf{Geometric} \ \# \ \text{of trials until 1st success, each w/ prob.} \ p \end{array}
  g(x \mid p) = p(1-p)^{x-1} 
*x \ge 1, x = 1, 2, 3, \dots
  *E[X] = \mu = \frac{1}{p} \mid Var(X) = \sigma^2 = \frac{1-p}{p^2}
Poisson # of events in a fixed interval w/ rate \lambda
  p(x \mid \lambda t) = \frac{e^{-\lambda t} (\lambda t)^x}{x!}
*x \ge 0, x = 0, 1, 2, \dots
   {^*E[X]} = \mu = \lambda t \mid Var(X) = \sigma^2 = \lambda t
  Gaussian to Q Fcn: 1. Find Q(x) = \frac{1}{\sqrt{2\pi}} \int_x^{\infty} e^{-t^2/2} dt.
   2. Use table to find Q(x) for x \geq 0.
   Random Vector: \underline{X} = [X_1, \dots, X_n]^T
   Mean Vector: \underline{m}_{\underline{X}} = E[\underline{X}] = [\mu_1, \dots, \mu_n]^T
                                                                                                         \begin{bmatrix} E[X_1^2] & E[X_1X_2] & \cdots \\ E[X_2X_1] & E[X_2^2] & \cdots \\ & & & & \end{bmatrix}
                                                                                                                                                                                                                                                                                 E[X_1X_n]
                                                                                                                                                                                                                                                                                 E[X_2X_n]
   Corr. Mat.: R_{\underline{X}} =
                                                                                                            \begin{bmatrix} E[X_n X_1] & E[X_n X_2] \end{bmatrix}
    *R is real, symmetric, and PSD (\forall \underline{a}, \underline{a}^T R \underline{a} \geq 0).
                                                                                                                  \begin{bmatrix} \operatorname{Var}[X_1] & \cdots \\ \operatorname{Cov}[X_2, X_1] & \cdots \end{bmatrix}
                                                                                                                                                                                                                                       Cov[X_1, X_n]

Cov[X_2, X_n]
   Covar. Mat.: K_{\underline{X}} =
  \begin{bmatrix} \operatorname{Cov}[X_n,X_1] & \cdots & \operatorname{Var}[X_n] \end{bmatrix}
*K\underline{X} = R\underline{X} - \underline{m}\underline{X} = R\underline{X} - \underline{m}\underline{m}^T
*Diagonal K\underline{X} \iff X_1,\dots,X_n are (mutually) uncorrelated.

Lin. Trans. \underline{Y} = A\underline{X} (A rotates and stretches \underline{X})
Mean: E[\underline{Y}] = A\underline{m}\underline{X}
   Covar. Mat.: K_{\underline{Y}} = AK_{\underline{X}}A^T
 Diag. Covar. Mat.: For any \underline{X}, if \underline{Y} = P^T \underline{X}, then K\underline{Y} = P^T K\underline{X}P = \Lambda (i.e. \underline{Y} is uncorrelated) *K\underline{X} = P\Lambda P^T Find eigenvalues, norm. eigenvectors of K\underline{X}.
  2. Set \underline{Y} = P^T \underline{X}, K\underline{Y} = \Lambda.

PDF of L.T. If \underline{Y} = \underline{A}\underline{X} w/ A not singular, then
  f_{\underline{Y}}(\underline{y}) = \frac{f_{\underline{X}}(\underline{x})}{|\det A|} \Big|_{\underline{x} = A^{-1} \underline{y}}
  Find f_{\underline{Y}}(\underline{y}) 1. Given f_{\underline{X}}(\underline{x}), define transformation A 2. Determine |\det A|, A^{-1}, then f_{\underline{Y}}(\underline{y}).

Gaussian RVs: Analytic Tractability: PDF of jointly Gaussian X_1, \ldots, X_n is Guassian vector.
  \begin{split} ^*f_{\underline{X}}(\underline{x}) &= \frac{1}{(2\pi)^{n/2} |\det \Sigma|^{1/2}} e^{-\frac{1}{2} (\underline{x} - \underline{\mu})^T \Sigma^{-1} (\underline{x} - \underline{\mu})} \\ ^*\underline{\mu} &= \underline{m}_{\underline{X}}, \ \Sigma = K_{\underline{X}} \ \text{(if } \Sigma \text{ is not singular)} \end{split}
```

```
Properties of Guassian Vector: \underline{X} \sim \mathcal{N}(\underline{\mu}, \Sigma) 1. PDF is completely determined by \underline{\mu}, \Sigma. 2. \underline{X} uncorrelated \Longrightarrow \underline{X} independent. 3. Any L.T. \underline{Y} = A\underline{X} + \underline{b} is Gaussian vector \mathbf{w}/\underline{\mu}_{\underline{Y}} = A\underline{\mu}_{\underline{X}}, \Sigma_{\underline{Y}} = A\Sigma_{\underline{X}}A^T. 4. Any subset of \{X_i\} are jointly Gaussian. 5. Any cond. PDF of a subset of \{X_i\} given the other elements is Gaussian.

Diag. of Guassian Covar. Eigen decomp. of \Sigma_{\underline{X}}: \{\lambda_i\}, \{e_i\} A = [\underline{e}_1, \ldots, \underline{e}_n]^T, then \underline{Y} = A\underline{X} has \Sigma_{\underline{Y}} = \Lambda.

*Y: Vector of indep. Gaussian RVs.

Guassian Discriminant Analysis: Obs: \underline{X} = \underline{x} = (x_1, \ldots, x_D) Hyp: \underline{x} is gen. by \mathcal{N}(\underline{\mu}_{\underline{C}}, \Sigma_c), c \in C
Dec: Which "Guassian bump" generated \underline{x}? Prior: P[C = c] = \pi_c (Gaussian Mixture Model)

MAP Rule: \hat{c} = \arg\max_c P_C[c|\underline{X} = \underline{x}] \hat{c} = \arg\max_c f_{\underline{X}|C}(\underline{x} \mid c)\pi_c

LGD: \Sigma_c = \Sigma \forall c, find c \mathbf{w}/ best \underline{\mu}_c \hat{c} = \arg\max_c \frac{\beta^T_c}{2} = \frac{1}{r} \gamma_c = \log\pi_c - \frac{1}{2}\underline{\mu}_c^T \Sigma^{-1}\underline{\mu}_c
*Bin. hyp. dec. boundary: \underline{\beta}_0^T \underline{x} + \gamma_0 = \underline{\beta}_1^T \underline{x} + \gamma_1 (lin. in space of \underline{x})

QGD: \Sigma_c are diff., find c \mathbf{w}/ best \underline{\mu}_c, \Sigma_c
*Bin. hyp. dec. boundary: Quadratic in space of \underline{x}
How to find \underline{x}_c,\underline{\mu}_c,\Sigma_c: Given n points gen. by GMM, then n_c points \{\underline{x}_1^C,\ldots,\underline{x}_{n_c}^C\} come from \mathcal{N}(\underline{\mu}_c,\Sigma_c)
\hat{\pi}_c = \frac{n_c}{n_c},\hat{\mu}_c \in \frac{1}{n_c}\sum_{i=1}^n \underline{x}_i^C, \Sigma_c
= \frac{1}{n_c}\sum_{i=1}^{n_c} (x_i^c - \hat{\mu}_c)(x_i^c - \hat{\mu}_c)^T
```