# ECE368 Cheatsheet

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Summary: On second thoughts, the lecture notes he posts are good, so I think I'll just do the cheatsheet.

## W1 (LG-IPPR 1.1, 1.2; Murphy 2.1 – 2.3)

## 1 L1: Probability Review

#### Summary:

#### FAQ:

- How to study? Practice, practice.
- What textbooks? Use 2024 version of Murphy, Leon Garcia as main reference, Bishop, 4th textbook is intro.
- How is HW graded? Effort, and tutorials are used to explain soln.

## 1.1 Sample Space

Motivation: If you have 4 sheeps and a flea, the probability that starting from sheep 1, the flea will jump to sheep 4 in 10 steps is 0.2.

- Ambigious as there are 2 different interpretations for the sample space (i.e. space of probability is not clear):
  - Set of sheeps
  - Set of number of steps

## 1.2 Probability Definitions

#### **Definition:**

- Random Experiment: An outcome (realization) for each run.
- Sample Space  $\Omega$ : Set of all possible outcomes.
- Events: (measurable) subsets of  $\Omega$ .
- Probability of Event A:  $P[A] \equiv P[\text{'outcome is in A'}].$

#### Example: Roll Fair Die

•  $\Omega = \{1, 2, 3, 4, 5, 6\}.$ 

•  $P[\text{'even number'}] = \frac{1}{2}$ .

## 1.3 Axioms of Probability

### **Definition**:

- 1.  $P[A] \geq 0$  for all  $A \in \Omega$ .
- 2.  $P[\Omega] = 1$ .
- 3. If  $A \cap B = \emptyset$ , then  $P[A \cup B] = P[A] + P[B]$  for all  $A, B \in \Omega$ .



Figure 1: 3rd Axiom

## 1.4 Conditional Probability

#### Definition:

$$P[A|B] = \frac{P[A \cap B]}{P[B]} \tag{1}$$

• |: Given event (data/obs.).

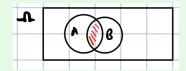


Figure 2: Conditional Probability

#### Notes:

- Changing sample space to B.
- Conditional probability satisfy the 3 axioms (i.e. are probabilities), can be viewed as probability measure on new sample space B.

#### 1.4.1 Consequences of Conditional Probability

$$P[A \cap B] = P[A|B]P[B] = P[B|A]P[A] \tag{2}$$

## 1.4.2 Independence

**Definition**: A and B are independent iff

$$P[A \cap B] = P[A]P[B] \iff P[A|B] = P[A] \iff P[B|A] = P[B] \tag{3}$$

### Importance of Labelling

### Example: Toss 2 Fair Coins

- 1. Given: Given that one of the coins is heads, what is the probability that the other coin is tails?
- Given: Given that one of the coins is heads, what is the probability that the other coin is tails?
   Wrong Solution: <sup>1</sup>/<sub>2</sub> since {HH, HT, TH, TT}, so P[T|H] = <sup>1</sup>/<sub>2</sub>, which assumes that the coins are distinguishable (i.e. coin #1 is heads)
   Correct Solution: <sup>2</sup>/<sub>3</sub> since {HH, HT, TH} as we didn't specify which coin was heads, so P[T|H] = <sup>2</sup>/<sub>3</sub>, which assumes that the coins are indistinguishable.

#### 2 L2: Probability Review

#### 2.1 Total Probability

**Definition**: If  $H_1, \ldots, H_n$  form a partition of  $\Omega$ , then

$$P[A] = \sum_{i=1}^{n} P[A|H_i]P[H_i]$$
(4)

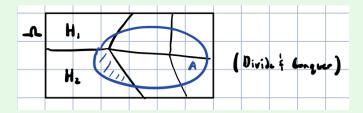


Figure 3: Total Probability

#### 2.2Bayes' Rule

Definition:

$$P[H_k|A] = \frac{P[H_k \cap A]}{P[A]} = \frac{P[A|H_k]P[H_k]}{\sum_{i=1}^n P[A|H_i]P[H_i]}$$
(5)

#### Posteriori Probability, Priori Probability (Prior), Likelihood

**Definition:** 

• Posteriori:  $P[H_k|A]$ .

• Priori:  $P[H_k]$ .

• Likelihood:  $P[A|H_k]$ .

**Example:** Suppose a lie detector is 95% accurate, i.e.  $P[\text{'out=truth'}|\text{'in=truth'}] = 0.95 \text{ and } P[\text{'out=lie'}|\text{'in=lie'}] = 0.95 \text{ and } P[\text{$ 0.95. It says that Mr. Ernst is lying. What is the probability Mr. Ernst is actually lying.

• Observation: A = 'out=lie'.

• Hypothesis:  $H_0 = \text{in} = \text{lie}$ : and  $H_1 = \text{in} = \text{truth}$ . • Solution:  $P[H_0|A] = \frac{P[A|H_0]P[H_0]}{P[A|H_0]P[H_0] + P[A|H_1]P[H_1]} = \frac{0.95 \times P[H_0]}{0.95 \times P[H_0] + 0.05 \times (1 - P[H_0])}$ . •  $H_0 = 0.01$ : i.e. 1% of the population are liars, then  $P[H_0|A] = \frac{0.95 \times 0.01}{0.95 \times 0.01 + 0.05 \times 0.99} = 0.16$ .

Warning: Need to know priori probability.

#### Interpretation of Bayes' Rule

Notes: Taking one component of the total probability and normalizing it by the sum of all components.

#### 2.3 Random Variables

Motivation: Coin Toss Mapping of each outcome to a real number

•  $w \in \Omega$  is the outcome of a coin toss, and X is the RV, so  $H \to 0$  and  $T \to 1$ .



Figure 4: Random Variables

• Mapping is deterministic function. RV is not random or variable.

**Definition**: Mapping from  $\Omega$  to  $\mathbb{R}$ .

#### 2.4 Distribution of RV

## 2.4.1 Cumulative Distribution Function (CDF) of RV

**Definition**:

$$F_X(x) \equiv P[X \le x] \tag{6}$$

#### 2.4.2 Discrete RV Probability Mass Function (PMF)

**Definition**:

$$P_X(x_j) \equiv P[X = x_j] \quad j = 1, 2, 3, \dots$$
 (7)

Example: Binonmial RV w/ (n, p)

$$P_X(k) = \binom{n}{k} p^k (1-p)^{n-k} \tag{8}$$

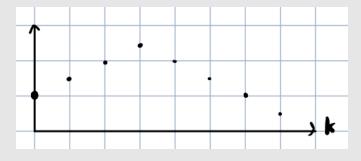


Figure 5: Binomial RV

## 2.4.3 Continuous RV Probability Density Function (PDF)

$$f_X(x) \equiv \frac{d}{dx} F_X(x) \tag{9}$$

$$P[x < X < x + dx] = f_X(x)dx \tag{10}$$

Example: Gaussian RV w/  $(\mu, \sigma^2)$ 

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$
 (11)

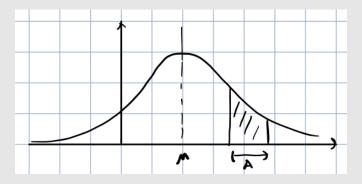


Figure 6: Gaussian RV

•  $P[X \in A] = \int_A f_X(x) dx$ .

**Notes**: Discrete RV has pdf w/  $\delta$  functions.

### 2.4.4 Conditional PMF/PDF

**Definition**:

$$P_X(x|A) \tag{12}$$

$$f_X(x|A) (13)$$

**Example: Continuous** 

$$f(x|X>a) = \begin{cases} \frac{f_X(x)}{P[X>a]} & \text{if } x>a\\ 0 & \text{otherwise} \end{cases}$$
 (14)

**Example: Geometric RV** Geometric RV X w/ success probability p

$$P_X(k) = (1-p)^{k-1}p (15)$$

- Memoryless Property:  $P_X[k|X > m] = \frac{p(1-p)^{k-1}}{(1-p)^m} = p(1-p)^{k-m-1}$ .
  - So it only cares about the additional trials (i.e. same as resetting after m trials).

## 2.5 Expected Values

$$E[X] = \int_{-\infty}^{\infty} x f_X(x) dx \stackrel{\text{If int. values}}{=} \sum_{k=-\infty}^{\infty} k f_X(k)$$
 (16)

$$E[h(X)] = \int_{-\infty}^{\infty} h(x) f_X(x) dx \stackrel{\text{If int. values}}{=} \sum_{k=-\infty}^{\infty} h(k) f_X(k)$$
(17)

$$Var[X] = E[(X - E[X])^{2}] = E[X^{2}] - E[X]^{2}$$
(18)

$$E[X|A] = \int_{-\infty}^{\infty} x f_X(x|A) dx \tag{19}$$

## Example: Lottery Ticket (Geometric RV)

- 1. Given: Buying one lottery ticket per week
  - Each ticket has  $10^{-7} = p$  chance of winning the jackpot.
- X = '# of weeks to win jackpot'.
  2. Problem: What is the expected number of weeks to win the jackpot?
- Solution: E[X] = ∑<sub>k=1</sub><sup>∞</sup> k(1-p)<sup>k-1</sup>p = ... = 1/p = 10<sup>7</sup> weeks.
   Extension (Memoryless Property): If I have already played for 999999 weeks, what is the expected number of weeks to win the jackpot? E[X − 999999|X > 999999] = E[X] = 10<sup>7</sup> weeks.

## 3 L3: Probability Review

#### 3.1 2 RVs

Notes: RVs are neither random nor a variable.

$$\underline{Z} = (X, Y)$$

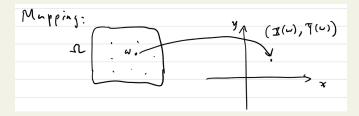


Figure 7: Mapping of RVs

## 3.2 Joint PMF/PDF

**Definition:** 

$$P_{X,Y}(x,y) = P[X = x, Y = y]$$
(20)

$$f_{X,Y}(x,y) = \frac{\partial^2}{\partial x \partial y} F_{X,Y}(x,y)$$
 (21)

$$P[(X,Y) \in A] = \int \int_{(x,y)\in A} f_{X,Y}(x,y) \, dx \, dy \tag{22}$$

**Example**: Jointly Gaussian RVs X and Y with  $(\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \rho)$ 

$$f_{X,Y}(x,y) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}} \exp\left\{-\frac{1}{2(1-\rho^2)} \left[ \left(\frac{x-\mu_1}{\sigma_1}\right)^2 - 2\rho\left(\frac{x-\mu_1}{\sigma_1}\right) \left(\frac{y-\mu_2}{\sigma_2}\right) + \left(\frac{y-\mu_2}{\sigma_2}\right)^2 \right] \right\}$$

## 3.3 Expectations

**Definition:** 

$$E[g(X,Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x,y) f_{X,Y}(x,y) \, dx \, dy$$

Notes

• g(X,Y) is also an RV, but inside the integral or sum, you use x and y as dummy variables to vary through the values of the RVs.

#### 3.3.1 Correlation

$$E[XY] \tag{23}$$

#### 3.3.2 Covariance

**Definition:** 

$$Cov[X,Y] = E[(X - \mu_X)(Y - \mu_Y)] = E[XY] - \mu_X \mu_Y = E[XY] - E[X]E[Y]$$
(24)

Notes:

• Mean shifted to 0.

#### 3.3.3 Correlation Coefficient

**Definition:** 

$$\rho_{X,Y} = E\left[\left(\frac{X - \mu_X}{\sigma_X}\right)\left(\frac{Y - \mu_Y}{\sigma_Y}\right)\right] = \frac{\text{Cov}[X, Y]}{\sigma_X \sigma_Y}$$
(25)

•  $|\rho_{X,Y}| \leq 1$ 

Notes:

• Mean shifted to 0 and normalized by the standard deviation.

## 3.4 Marginal PMF/PDF

Definition:

$$P_X(x) = \sum_{j=1}^{\infty} P_{X,Y}(x, y_j), \quad P_Y(y) = \sum_{j=1}^{\infty} P_{X,Y}(x_j, y)$$
 (26)

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) \, dy, \quad f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) \, dx$$
 (27)

Notes:

• Total probability theorem is being used here.

**Example:** Jointly Gaussian X and Y:

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) \, dy$$

$$= \dots \quad \text{(completing the square)}$$

$$= \frac{1}{\sqrt{2\pi}\sigma_1} e^{-\frac{(x-\mu_1)^2}{2\sigma_1^2}}, \quad \text{marginally Gaussian}$$

• Gaussian RVs has a property that the PDF of a single variable is equal to the marginal Gaussian of two variables.

## 3.5 Conditional PMF/PDF

$$P_{X|Y}(x|y) \triangleq P[X = x|Y = y] = \frac{P_{X,Y}(x,y)}{P_{Y}(y)}$$
 (28)

$$f_{X|Y}(x|y) \triangleq \frac{f_{X,Y}(x,y)}{f_Y(y)} \tag{29}$$

## 3.6 Bayes' Rule

**Definition**:

$$P_{Y|X}(x|y) = \frac{P_{X,Y}(x,y)}{P_X(x)} = \frac{P_{X|Y}(x|y)P_Y(y)}{\sum_{j=1}^{\infty} P_{X,Y}(x,y_j)P_Y(y_j)}$$
(30)

$$f_{Y|X}(y|x) = \frac{f_{X,Y}(x,y)}{f_X(x)} = \frac{f_{X|Y}(x|y)f_Y(y)}{\int_{-\infty}^{\infty} f_{X|Y}(x|y')f_Y(y') \, dy'}$$
(31)

## 3.7 Independent vs. Uncorrelated vs. Orthogonal

**Definition:** 

1. Independent:

$$f_{X|Y}(x|y) = f_X(x) \ \forall y \Leftrightarrow f_{X,Y}(x,y) = f_X(x)f_Y(y) \tag{32}$$

2. Uncorrelated:

$$Cov[X,Y] = 0 \quad \Leftrightarrow \quad \rho_{X,Y} = 0 \tag{33}$$

3. Orthogonal:

$$E[XY] = 0 (34)$$

**Theorem**: If independent, then uncorrelated.

**Derivation**:

$$\begin{split} \text{Independent} &\implies E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_{X,Y}(x,y) \, dx \, dy \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_X(x) f_Y(y) \, dx \, dy \\ &= \left( \int_{-\infty}^{\infty} x f_X(x) \, dx \right) \left( \int_{-\infty}^{\infty} y f_Y(y) \, dy \right) \\ &\implies E[XY] = E[X] E[Y] \\ &\implies \operatorname{Cov}[X,Y] = 0, \quad \text{uncorrelated} \\ &\not= \text{in general.} \end{split}$$

**Example**: Jointly Gaussian RVs X and Y: If uncorrelated, i.e.  $\rho_{X,Y} = 0$ , then X and Y are independent.

$$f_{X,Y}(x,y) = \frac{1}{2\pi\sigma_1\sigma_2} \exp\left\{-\frac{1}{2} \left[ \left(\frac{x-\mu_1}{\sigma_1}\right)^2 + \left(\frac{y-\mu_2}{\sigma_2}\right)^2 \right] \right\}$$
$$= \frac{1}{\sqrt{2\pi}\sigma_1} e^{-\frac{(x-\mu_1)^2}{2\sigma_1^2}} \cdot \frac{1}{\sqrt{2\pi}\sigma_2} e^{-\frac{(y-\mu_2)^2}{2\sigma_2^2}}$$
$$= f_X(x) f_Y(y) \quad \text{independent}$$

## 3.8 Conditional Expectation

$$E[Y] = E[E[Y|X]] \tag{35}$$

$$E[h(Y)] = E[E[h(Y)|X]] \tag{36}$$

#### Notes:

- E[E[Y|X]] is w.r.t. X.
- E[Y|X] is w.r.t. Y.

## Derivation:

$$\begin{split} E[Y] &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y f_{X,Y}(x,y) \, dx \, dy \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y f_{Y|X}(y|x) f_X(x) \, dx \, dy \\ &= \int_{-\infty}^{\infty} \left( \int_{-\infty}^{\infty} y f_{Y|X}(y|x) \, dy \right) f_X(x) \, dx \\ &= \int_{-\infty}^{\infty} E[Y|X=x] f_X(x) \, dx \quad \text{(using the total probability theorem)} \\ &= \int_{-\infty}^{\infty} g(x) f_X(x) \, dx \\ &= E[g(X)] \\ &= E[E[Y|X]]. \end{split}$$

### Example:

1. **Given:** An unknown voltage.  $X \sim \text{Uniform}(0,1)$ . Measurement from a (bad) voltmeter:  $Y \sim \text{Uniform}(0,X)$ .

$$f_X(x) = \begin{cases} 1, & 0 < x < 1 \\ 0, & \text{otherwise} \end{cases}$$

$$f_{Y|X}(y|x) = \begin{cases} \frac{1}{x}, & 0 < y < x \\ 0, & \text{otherwise} \end{cases}$$

• Note: Area under PDF is 1.

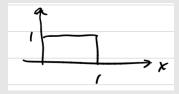


Figure 8: Uniform Distribution of X

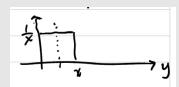


Figure 9: Uniform Distribution of Y

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2. Expected Value (Average Reading of Bad Voltmeter):

$$\begin{split} E[Y] &= E[E[Y|X]] \\ &= E\left[\frac{X}{2}\right] \quad \text{Since in the middle of 0 and x} \\ &= \frac{1}{2} \cdot E[X] \\ &= \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4} \quad \text{Since } E[X] \text{ (i.e. mean) is 0.5} \end{split}$$

3. The Long Way:

$$f_Y(y) = \int_{-\infty}^{\infty} f_{Y|X}(y|x) f_X(x) dx$$

$$= \int_y^1 f_{Y|X}(y|x) f_X(x) dx$$

$$= \int_y^1 \frac{1}{x} \cdot 1 dx$$

$$= -\ln y.$$

$$E[Y] = \int_0^1 y \cdot (-\ln y) dy = \dots = \frac{1}{4}$$

4. Question: Suppose  $Y = \frac{1}{8}$ . What is "best" given X? This will be the quesiton for the rest of the course.

## 4 L4: Estimation of Sample Mean

## 4.1 Parameter Estimation:

Motivation: The readout of a sensor is  $X = \theta + N$  volts

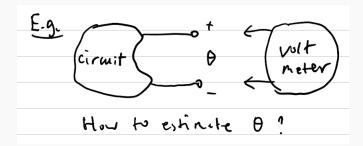


Figure 10:

- There is some noise N in the sensor, so we want to estimate the true value of  $\theta$  (unknown parameter to be estimated)
  - e.g. Mean and/or variance of X.

#### 4.2 Estimator:

**Definition**: Perform n independent and identically distributed (i.i.d.) measurements/observations of X:  $X_1, X_2, \ldots, X_n$ .

$$\hat{\Theta} = \hat{\Theta}(\underline{X}) = g(X_1, X_2, \dots, X_n) \tag{37}$$

$$X_i$$
,  $X_2$ , ...,  $X_n \longrightarrow e_i + i \cdot k \cdot k \cdot k \longrightarrow \widehat{\Theta}$ 

Figure 11:

#### 4.2.1 Estimation Error:

Definition:  $\hat{\Theta}(\underline{X}) - \theta \tag{38}$ 

## 4.2.2 Unbiased

**Definition**: The estimator  $\hat{\Theta}$  is unbiased if  $\mathbb{E}[\hat{\Theta}(\underline{X})] = \theta \tag{39}$ 

• Asymptotically Unbiased:  $\lim_{n\to\infty} \mathbb{E}[\hat{\Theta}(\underline{X})] = \theta$  (big data)

## 4.2.3 Consistent

**Definition**: The estimator  $\hat{\Theta}$  is consistent if  $\hat{\Theta}(\underline{X}) \to \theta$  as  $n \to \infty$ , in probability, i.e.,  $\forall \epsilon > 0$ ,

$$\lim_{n \to \infty} P(|\hat{\Theta}(\underline{X}) - \theta| < \epsilon) \to 1 \tag{40}$$

as  $n \to \infty$ .

## 4.3 Sample Mean & Law of Large Numbers

**Definition**: Given a sequence of i.i.d. random variables (RVs),  $X_1, X_2, \ldots, X_n$ , w/ unknown mean  $\mu$ , estimate  $\mu$ . Let  $S_n = X_1 + X_2 + \cdots + X_n$ . The sample mean is

$$M_n = \frac{1}{n} S_n$$

- How good is  $M_n$  as an estimator of  $\mu$ ?
  - Use unbiased and consistent to evaluate  $M_n$ .

Example: Previous voltage measurement, e.g.,

$$X_i = \mu + N_i$$

where  $\mu$  is the true value and  $N_i$  is the noise.

If we assume  $N_i$  are i.i.d. with zero mean,

$$E[X_i] = E[\mu + N_i] = E[\mu] + E[N_i] = \mu + 0 = \mu, \quad \forall i$$

## 4.3.1 Digression for Sum of RVs (not necessarily independent or identically distributed)

**Derivation**:

$$E[S_n] = E[X_1 + \dots + X_n]$$
  
=  $E[X_1] + \dots + E[X_n]$ 

**Derivation**:

$$Var[S_n] = E \left[ (S_n - E[S_n])^2 \right]$$

$$= E \left[ \left( \sum_{i=1}^n X_i - E[X_i] \right)^2 \right]$$

$$= E \left[ \sum_{i=1}^n \sum_{j=1}^n (X_i - E[X_i])(X_j - E[X_j]) \right]$$

$$= \sum_{i=1}^n \sum_{j=1}^n E \left[ (X_i - E[X_i])(X_j - E[X_j]) \right]$$

$$= \sum_{i=1}^n \sum_{j=1}^n Cov[X_i, X_j]$$

$$= \sum_{i=1}^n Var[X_i] + \sum_{i \neq j} Cov[X_i, X_j]$$

#### 4.3.2 Unbiased (i.i.d.)

**Derivation**:

$$E[M_n] = E\left[\frac{1}{n}S_n\right]$$

$$= \frac{1}{n} \left(E[X_1] + \dots + E[X_n]\right)$$

$$= \frac{1}{n} (n\mu) \quad \text{since } X_i \text{ are i.i.d. so same expectation}$$

$$= \mu \Rightarrow \text{Unbiased!}$$

## 4.3.3 Consistent (i.i.d.)

**Derivation**:

$$\begin{split} \operatorname{Var}[M_n] &= \operatorname{Var}\left[\frac{1}{n}S_n\right] \\ &= \frac{1}{n^2}\operatorname{Var}[S_n] \quad \text{taking out constant requires squaring} \\ &= \frac{1}{n^2}\left(\sum_{i=1}^n \operatorname{Var}[X_i] + \sum_{i \neq j} \operatorname{Cov}[X_i, X_j]\right) \\ &= \frac{1}{n^2}(n\sigma^2) \quad \sigma^2 \triangleq \operatorname{Var}[X_i] \text{ and } X_i \text{ are i.i.d. so covariance is } 0 \\ &= \frac{\sigma^2}{n} \to 0 \text{ as } n \to \infty. \end{split}$$

• This means that there is no variance in the sample mean as n approaches infinity, so it converges to the true mean

Recall the Chebyshev Inequality:

$$P[|X - E[X]| \ge \epsilon] \le \frac{\operatorname{Var}[X]}{\epsilon^2}, \quad \forall \epsilon > 0.$$

Substitute in  $M_n$ :

$$\begin{split} P\left[|M_n - E[M_n]| \geq \epsilon\right] &\leq \frac{\mathrm{Var}[M_n]}{\epsilon^2} \\ P\left[|M_n - \mu| \geq \epsilon\right] &\leq \frac{\sigma^2}{n\epsilon^2} \\ \Rightarrow P\left[|M_n - \mu| < \epsilon\right] \geq 1 - \frac{\sigma^2}{n\epsilon^2} \to 1 \text{ as } n \to \infty \text{ then it is consistent} \end{split}$$

Warning: Cov = 0 because independence implies uncorrelated.

#### 4.3.4 Weak Law of Large Numbers

**Definition**: Even if  $\sigma$  is infinite, then  $\forall \epsilon > 0$ ,

$$\lim_{n \to \infty} P\left[|M_n - \mu| < \epsilon\right] = 1$$

#### 4.3.5 Confidence Interval: Finding n

**Example**: Measure an unknown voltage  $\theta$  for n times and obtain independent measurements:

$$X_i = \theta + N_i,$$

where  $N_i$  are i.i.d. random variables with mean 0 and variance 1.

 $\bullet$  We want to determine how many measurements n are sufficient so that

$$P(|M_n - \theta| < 0.1) \ge 0.95,$$

where 0.1 is the desired precision and 0.95 is the confidence level.

• The sample mean is given by:

$$M_n = \frac{1}{n} \sum_{i=1}^n X_i = \theta + \frac{1}{n} \sum_{i=1}^n N_i.$$

• The variance of  $X_i$  is:

$$\sigma^2 = \operatorname{Var}[X_i] = \operatorname{Var}[\theta + N_i] = \operatorname{Var}[N_i] = 1.$$

-  $Var[aX + b] = a^2 Var[X]$ , where a = 1 and  $b = \theta$ .

• Using Chebyshev's inequality:

$$1 - \frac{\sigma^2}{n\epsilon^2} \ge 0.95,$$

where  $\epsilon = 0.1$  (precision).

• Solving for n:

$$1 - \frac{1}{n(0.1)^2} \ge 0.95,$$
$$\frac{1}{n(0.1)^2} \le 0.05,$$
$$n > 2000$$

Thus, at least 2000 measurements are needed to achieve the desired precision and confidence level.

## 5 L5: Sample Mean and Maximum Likelihood Estimation

#### FAQ:

• Why can we say that it is consistent for the last example?

#### 5.1 Maximum Likelihood Estimation

Motivation: Choose parameter  $\theta$  that is most likely to generate the observation  $x_1, x_2, \ldots, x_n$ .

Figure 12:

**Definition:** 

$$\hat{\Theta} = \arg \max_{\underline{a}} P_{\underline{X}}(\underline{x}|\theta), \text{ discrete } X.$$
(41)

$$\hat{\Theta} = \arg \max_{\theta} f_{\underline{X}}(\underline{x}|\theta), \text{ continuous } X.$$
 (42)

#### 5.1.1 Log-Likelihood

Definition:

$$\hat{\theta} = \arg\max_{\theta} \sum_{i=1}^{n} \log P_X(x_i|\theta) \tag{43}$$

$$\hat{\theta} = \arg\max_{\theta} \sum_{i=1}^{n} \log f_X(x_i|\theta). \tag{44}$$

Warning: Can only go from argmax of fcn to argmax of log fcn, if it is i.i.d.

#### **Derivation**:

i.i.d. 
$$X_1, X_2, \dots, X_n \implies$$
 
$$p_{\underline{X}}(\underline{x}|\theta) = \prod_{i=1}^n p_{X_i}(x_i|\theta)$$
 
$$= \prod_{i=1}^n p_X(x_i|\theta) \quad \text{drop the i due to i.i.d. assumption}$$
 
$$\log p_{\underline{X}}(\underline{x}|\theta) = \sum_{i=1}^n \log p_X(x_i|\theta).$$

### Example:

- 1. Model and Observations:
  - Assume a biased coin with probability  $\theta$  of showing heads. Find ML estimator for  $\theta$ .
  - Toss the coin n times and obtain Bernoulli random variables  $X_1, \ldots, X_n$  such that:

"heads" 
$$\to 1$$
, "tails"  $\to 0$ .

• Total number of heads is:

$$k = \sum_{i=1}^{n} X_i.$$

For example:

$$\underline{x} = (1, 0, 0, 0, 1, 1, 0, 1, 1, 1), \quad k = 6.$$

• Probability of observations  $x_1, \ldots, x_n$  corresponding to parameter  $\theta$  is:

$$p_X(\underline{x}|\theta) = \theta^k (1-\theta)^{n-k}.$$

- It is sufficient to know only k.
- Note: Don't need the  $\binom{n}{k}$  term because we are given the specific sequence of heads and tails.

### 2. Log-Likelihood and Maximization:

• The log-likelihood function is:

$$\log p_X(\underline{x}|\theta) = k \log(\theta) + (n-k) \log(1-\theta).$$

• To maximize the log-likelihood over  $\theta$ , set:

$$0 = \frac{\partial}{\partial \theta} \log p_{\underline{X}}(\underline{x}|\theta),$$

$$0 = \frac{k}{\theta} - \frac{n-k}{1-\theta},$$

$$\theta = \frac{k}{n}.$$

• Thus, the Maximum Likelihood Estimator (MLE) is:

$$\hat{\Theta} = \frac{k}{n}$$
, where  $k = \sum_{i=1}^{n} X_i$ .

This corresponds to the observed frequency of heads, which is intuitive b/c the more heads we see, the more likely the coin is biased towards heads.

#### 3. Examples:

• For  $\underline{x} = (1, 0, 0, 0, 1, 1, 0, 1, 1, 1)$ :

$$p_X(\underline{x}|\theta) = \theta^6 (1 - \theta)^4,$$
  
 $\hat{\theta} = \frac{6}{10} = 0.6.$ 

• For  $\underline{x} = (0, 1, 1, 1, 0, 0, 1, 0, 1, 0)$ :

$$p_X(\underline{x}|\theta) = \theta^5 (1 - \theta)^5,$$
  
 $\hat{\theta} = \frac{5}{10} = 0.5.$ 

#### Notes:

1. k is a sufficient statistic for this Maximum Likelihood (ML) estimator.

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2. The expectation of the estimator  $\hat{\theta}$  is:

$$E[\hat{\Theta}] = E\left[\frac{1}{n}\sum_{i=1}^{n}X_{i}\right]$$

$$= \frac{1}{n}\sum_{i=1}^{n}E[X_{i}]$$

$$= \frac{1}{n}(n\theta)$$

$$= \theta \quad \text{(Unbiased)}.$$

- $E[X_i] = (1)\theta + (0)(1 \theta) = \theta$
- 3. In fact,  $\hat{\Theta} = \frac{1}{n} \sum_{i=1}^{n} X_i$  is the sample mean, and  $\theta$  is the true mean. Therefore,  $\hat{\theta} \to \theta$  in probability, which implies that  $\hat{\theta}$  is *consistent*.

## L6: Maximum Likelihood and Laplace

## MLE for Categorical Random Variables

#### Example:

1. We say that  $X \sim \operatorname{Cat}(\underline{\theta})$  if

$$P[X = m] = \theta_m, \quad m = 1, 2, \dots, M.$$

 $\bullet$  Going from 2 to M categories is a generalization of the Bernoulli distribution.

The parameter  $\theta$  is a vector:

$$\underline{\theta} = \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_M \end{bmatrix},$$

such that  $\theta_m \geq 0$  and  $\sum_{m=1}^{M} \theta_m = 1$ .

- 2. Given n i.i.d. observations  $X_1, \ldots, X_n$ , we aim to find the maximum likelihood estimator (MLE) of  $\underline{\theta}$ .
- 3. Define  $n_m$  as the number of observations that equal m:

$$n_m = \sum_{i=1}^n 1(x_i = m),$$

where  $1(x_i = m)$  is the indicator function. Note that  $\sum_{m=1}^{M} n_m = n$ .

4. The likelihood function is:

$$p_{\underline{X}}(\underline{x} \mid \underline{\theta}) = \prod_{m=1}^{M} \theta_m^{n_m}.$$

 $\bullet$  Similar to the Bernoulli distribution, but with M categories. Taking the log, we get:

$$\log p_{\underline{X}}(\underline{x} \mid \underline{\theta}) = \sum_{m=1}^{M} n_m \log \theta_m.$$

5. To find the optimal  $\theta$ , we minimize the negative log-likelihood:

$$\min_{\underline{\theta}} - \sum_{m=1}^{M} n_m \log \theta_m,$$

subject to the constraints  $\theta_m \geq 0$  for  $1 \leq m \leq M$  and  $\sum_{m=1}^{M} \theta_m = 1$ .

6. Solving this optimization problem, the MLE is:

$$\hat{\Theta}_m = \frac{N_m}{n} = \frac{\sum_{i=1}^n 1(X_i = n)}{n}, \quad \hat{\underline{\Theta}} = \begin{bmatrix} \frac{N_1}{n} \\ \vdots \\ \frac{N_m}{n} \end{bmatrix}.$$

#### 6.2 MLE for Gaussian Random Variables

#### Example:

1. Given n i.i.d. observations  $X_1, \ldots, X_n$  of a Gaussian random variable with parameters  $(\mu, \sigma^2)$ , we aim to find the maximum likelihood estimators (MLEs) of  $\mu$  and  $\sigma^2$ .

$$\begin{split} f_{\underline{X}}(\underline{x}|\mu,\sigma^2) &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x_i-\mu)^2}{2\sigma^2}\right), \\ &\log f_{\underline{X}}(\underline{x}|\mu,\sigma^2) = \sum_{i=1}^n \left(-\frac{(x_i-\mu)^2}{2\sigma^2} - \log \sigma - \log \sqrt{2\pi}\right). \end{split}$$

2. To find  $\mu$ , take the derivative of the log-likelihood with respect to  $\mu$  and set it to zero:

$$0 = \frac{\partial}{\partial \mu} \sum_{i=1}^{n} \left( -\frac{(x_i - \mu)^2}{2\sigma^2} \right),$$

$$0 = \frac{1}{n} \sum_{i=1}^{n} x_i - \mu,$$

$$\mu = \frac{1}{n} \sum_{i=1}^{n} x_i.$$

3. To find  $\sigma^2$ , take the derivative of the log-likelihood with respect to  $\sigma^2$  and set it to zero:

$$0 = \frac{\partial}{\partial \sigma^2} \sum_{i=1}^n \left( -\frac{(x_i - \mu)^2}{2\sigma^2} - \frac{1}{2} \log \sigma^2 \right),$$

$$0 = -\frac{1}{2} \sum_{i=1}^n \left( \frac{(x_i - \mu)^2}{\sigma^4} \right) + \frac{1}{2\sigma^2},$$

$$\sigma^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2.$$

4. Thus, the MLEs are:

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} X_i, \quad \text{(sample mean)}$$

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^{n} (X_i - \hat{\mu})^2. \quad \text{(sample variance)}$$

- Note: The sample variance is biased, so we often use  $\frac{1}{n-1}$  instead of  $\frac{1}{n}$  to make it unbiased.
- Note: The sample mean is unbiased.

## 6.3 Will the Sun Rise Tomorrow? (Laplace's Problem)

#### ${f Example}$ :

- Observation: The Sun has risen for n consecutive days. Estimate the probability that it will rise tomorrow.
- Model: Assume n i.i.d. Bernoulli random variables  $X_1, \ldots, X_n$  with  $P[X_i = 1] = \theta$ .

#### 6.3.1 Frequentist Approach

#### Example:

1. The Maximum Likelihood Estimator (MLE) is:

$$\hat{\theta} = \frac{K}{n} = \frac{\sum_{i=1}^{n} X_i}{n}.$$

2. If K = n (i.e., the Sun has risen every day so far), then:

$$\hat{\theta} = \frac{n}{n} = 1.$$

- 3. Conclusion: The Sun will rise tomorrow with probability 1, regardless of what n is, based on the Frequentist approach.
  - This doesn't make sense b/c if n=1 then we are assuming 100% it will rise based on one observation.

#### 6.3.2 Bayesian Approach

#### Example:

- 1. Assume that  $\theta$  is not fixed but drawn from a uniform distribution in [0, 1]. This means that the probability of the Sun rising is based on a uniform distribution.
- 2. We want to find the probability that the sun will rise tomorrow given that it has risen for n consecutive days:

$$P[X_{n+1} = 1 | X_1 = 1, \dots, X_n = 1].$$

Using Bayes' Theorem:

$$P[X_{n+1} = 1 | X_1 = 1, \dots, X_n = 1] = \frac{P[X_1 = 1, \dots, X_{n+1} = 1]}{P[X_1 = 1, \dots, X_n = 1]}.$$

3. Compute  $P[X_1 = 1, ..., X_n = 1]$ :

$$P[X_1 = 1, \dots, X_n = 1] = \int_0^1 P[X_1 = 1, \dots, X_n = 1 | \Theta = \theta] f_{\Theta}(\theta) d\theta.$$

- The joint probability is calculated by integrating the product of the likelihood and the prior (i.e. marginalizing over  $\theta$ ).
- The likilihood becomes  $\theta^n$  because the observations are i.i.d.
- The prior is uniform, so  $f_{\Theta}(\theta) = 1$ .

Since  $f_{\Theta}(\theta) = 1$  (uniform prior) and  $P[X_1 = 1, ..., X_n = 1 | \Theta = \theta] = \theta^n$ , we have:

$$P[X_1 = 1, \dots, X_n = 1] = \int_0^1 \theta^n d\theta = \frac{1}{n+1}.$$

4. Compute  $P[X_1 = 1, ..., X_{n+1} = 1]$  similarly:

$$P[X_1 = 1, \dots, X_{n+1} = 1] = \int_0^1 \theta^{n+1} d\theta = \frac{1}{n+2}.$$

5. Combine results:

$$P[X_{n+1} = 1 | X_1 = 1, \dots, X_n = 1] = \frac{\frac{1}{n+2}}{\frac{1}{n+1}} = \frac{n+1}{n+2}.$$

6. Conclusion: As n increases, the probability approaches 1, providing more certainty with more data.

## 6.4 Sample Mean is Not Always an ML Estimator

**Example**: Given an unknown voltage x, we measure it using a voltmeter that outputs a random reading Y that is uniform in [0, x]. Suppose we make n i.i.d. measurements  $Y_1, \ldots, Y_n$  and wish to estimate  $\mu = \frac{x}{2} = \mathbb{E}[Y]$ .

1. Sample Mean:

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} Y_i \quad \cdots (1)$$

2. To Find the ML Estimator:

$$f_{\mathbf{Y}}(\mathbf{y} \mid \mu) = \prod_{i=1}^{n} f_{Y}(y_{i} \mid \mu)$$

$$= \prod_{i=1}^{n} \frac{1}{2\mu} \cdot 1(0 \le y_{i} \le 2\mu)$$

$$= \frac{1}{(2\mu)^{n}} \prod_{i=1}^{n} 1(0 \le y_{i} \le 2\mu).$$

The likelihood is maximized for:

$$\arg\max_{\mu} f_{\mathbf{Y}}(\mathbf{y} \mid \mu) = \max_{1 \le i \le n} \frac{1}{2} Y_i.$$

Therefore:

$$\hat{\mu} = \max_{1 \le i \le n} \frac{1}{2} Y_i \quad \cdots (2)$$

3. Clearly,  $(1) \neq (2)$ .

# L7: Maximum A Posteriori (MAP) Estimation

# 8 L8: MAP Conjugate Prior

## 9 L9: Least Mean Squares (LMS) Estimation

1. Assume prior:

$$p_{\Theta}(\theta)$$
 or  $f_{\Theta}(\theta)$  (Bayesian)

Observations:  $\bar{X} = x$ .

2. LMS Estimator:

$$\hat{\theta} = g(x) = \mathbb{E}[\Theta \mid \bar{X} = x]$$
 or  $\hat{\Theta} = g(\bar{X}) = \mathbb{E}[\Theta \mid \bar{X}].$ 

Note:

- MAP: Use the most probable  $\theta$  given x.
- LMS: Use the expected value (conditional on  $\bar{X} = x$ ) of  $\Theta$ , i.e., the "Conditional Expectation Estimator."
- 3. Unbiasedness of LMS Estimator:

$$\begin{split} \mathbb{E}[\hat{\Theta}] &= \mathbb{E}[\mathbb{E}[\Theta \mid \bar{X}]] = \mathbb{E}[\Theta], \\ \Longrightarrow \mathbb{E}[\hat{\Theta} - \Theta] &= 0. \end{split}$$

4. LMS Estimator Minimizes Conditional MSE:

$$\mathbb{E}\big[(\Theta - \hat{\Theta})^2 \mid \bar{X} = x\big].$$

**Proof:** 

(a) First, suppose no observations:  $\hat{\Theta}$  is a constant.

$$\hat{\Theta} = \arg\min_{c} \mathbb{E}[(\Theta - c)^{2}],$$

$$0 = \frac{d}{dc} [-2\mathbb{E}[\Theta] + 2c],$$

$$c = \mathbb{E}[\Theta].$$

(b) Alternate view:

$$\mathbb{E}[(\Theta - c)^2] = \operatorname{Var}[\Theta] + (\mathbb{E}[\Theta] - c)^2.$$

To minimize: Set bias  $\mathbb{E}[\Theta] - c$  to zero.

(c) Now, with observations  $\bar{X} = x$ :

$$\mathbb{E}\big[(\Theta - g(x))^2 \mid \bar{X} = x\big] = \operatorname{Var}[\Theta \mid \bar{X} = x] + (\mathbb{E}[\Theta \mid \bar{X} = x] - g(x))^2.$$

To minimize: Set  $g(x) = \mathbb{E}[\Theta \mid \bar{X} = x]$ .

5. Conclusion:

$$\hat{\Theta} = g(x) = \mathbb{E}[\Theta \mid \bar{X} = x].$$

1. Example: Prior Coin Toss Problem

$$\hat{\theta}_{\text{LMS}} = \mathbb{E}[\Theta \mid X = k]$$
$$= \frac{k + \alpha}{n + \alpha + \beta}.$$

- 2. Example: Prior Voltage Problem
  - (a) Setup:
    - Unknown voltage  $\Theta$ .
    - Prior:  $\Theta \sim \text{Uniform}[0, 1]$ .

- Volt meter reading Y given  $\Theta$ :  $Y \sim \text{Uniform}[0, \Theta]$ .
- Independent measurements:  $Y_1, \ldots, Y_n$  given  $\Theta$ .
- (b) Likelihood:

$$f_{Y|\Theta}(\mathbf{y} \mid \theta) = \prod_{i=1}^{n} f_{Y}(y_{i} \mid \theta)$$
$$= \frac{1}{\theta^{n}} \cdot 1(\theta \ge \max_{i} y_{i}).$$

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(c) Posterior:

$$f_{\Theta|Y}(\theta \mid \mathbf{y}) = \frac{\frac{1}{\theta^n} \cdot 1(\theta \ge \max_i y_i)}{f_Y(\mathbf{y})}.$$

- (d) Estimators:
  - Maximum Likelihood (ML):

$$\hat{\theta} = \max_{1 \le i \le n} y_i.$$

• LMS:

$$\hat{\theta} = \mathbb{E}[\Theta \mid Y = y] = \int_0^\infty \theta f_{\Theta \mid Y}(\theta \mid y) d\theta.$$

- (e) Derivation for LMS:
  - i. Compute  $f_Y(y)$  for n=1:

$$f_Y(y) = \int_y^1 \frac{1}{\theta} d\theta$$
$$= \ln(\theta) \Big|_y^1$$
$$= -\ln(y).$$

ii. Compute  $\hat{\theta}$  for n=1:

$$\hat{\theta} = \int_{y}^{1} \frac{\theta \cdot 1(\theta \ge y)}{-\ln(y)} d\theta$$
$$= \frac{1}{-\ln(y)} \int_{y}^{1} \theta d\theta$$
$$= \frac{1}{-\ln(y)} \cdot \frac{y^{2} - 1}{2}.$$

- $(f) \ \ \textbf{Graphical Interpretation:}$ 
  - $f_{\Theta|Y}(\theta \mid y) = \frac{1}{-\ln(y)} \cdot 1(\theta \ge y) \cdot 1(0 \le \theta \le 1).$
  - The MAP estimator corresponds to the most probable  $\theta$ .
  - The LMS estimator minimizes the mean squared error, representing the "safest" choice.