

# ECE368 Cheatsheet

Hanhee Lee

January 22, 2025

## Contents

<b>1</b>	<b>L1: Probability Review</b>	<b>2</b>
1.1	Sample Space	2
1.2	Probability Definitions	2
1.3	Axioms of Probability	3
1.4	Conditional Probability	3
1.4.1	Consequences of Conditional Probability	3
1.4.2	Independence	3
1.4.3	Importance of Labelling	3
<b>2</b>	<b>L2: Probability Review</b>	<b>4</b>
2.1	Total Probability	4
2.2	Bayes' Rule	4
2.2.1	Posteriori Probability, Priori Probability (Prior), Likelihood	4
2.2.2	Interpretation of Bayes' Rule	4
2.3	Random Variables	5
2.4	Distribution of RV	5
2.4.1	Cumulative Distribution Function (CDF) of RV	5
2.4.2	Discrete RV Probability Mass Function (PMF)	5
2.4.3	Continuous RV Probability Density Function (PDF)	5
2.4.4	Conditional PMF/PDF	6
2.5	Expected Values	6
<b>3</b>	<b>L3: Probability Review</b>	<b>8</b>
3.1	2 RVs	8
3.2	Joint PMF/PDF	8
3.3	Expectations	8
3.3.1	Correlation	8
3.3.2	Covariance	9
3.3.3	Correlation Coefficient	9
3.4	Marginal PMF/PDF	9
3.5	Conditional PMF/PDF	9
3.6	Bayes' Rule	10
3.7	Independent vs. Uncorrelated vs. Orthogonal	10
3.8	Conditional Expectation	10
<b>4</b>	<b>L4: Estimation of Sample Mean</b>	<b>13</b>
4.1	Parameter Estimation:	13
4.2	Estimator:	13
4.2.1	Estimation Error:	13
4.2.2	Unbiased	13
4.2.3	Consistent	13
4.3	Sample Mean & Law of Large Numbers	14
4.3.1	Digression for Sum of RVs (not necessarily independent or identically distributed)	14
4.3.2	Unbiased (i.i.d.)	14
4.3.3	Consistent (i.i.d.)	15

4.3.4	Weak Law of Large Numbers	15
4.3.5	Confidence Interval: Finding $n$	16
<b>5</b>	<b>L5: Sample Mean and Maximum Likelihood Estimation</b>	<b>17</b>
5.1	Maximum Likelihood Estimation	17
5.1.1	Log-Likelihood	17
<b>6</b>	<b>L6: Maximum Likelihood and Laplace</b>	<b>20</b>
6.1	MLE for Categorical Random Variables	20
6.2	MLE for Gaussian Random Variables	21
6.3	Will the Sun Rise Tomorrow? (Laplace's Problem)	21
6.3.1	Frequentist Approach	22
6.3.2	Bayesian Approach	22

**Summary:** On second thoughts, the lecture notes he posts are good, so I think I'll just do the cheatsheet.

## W1 (LG-IPPR 1.1, 1.2; Murphy 2.1 – 2.3)

### 1 L1: Probability Review

**Summary:**

**FAQ:**

- How to study? Practice, practice.
- What textbooks? Use 2024 version of Murphy, Leon Garcia as main reference, Bishop, 4th textbook is intro.
- How is HW graded? Effort, and tutorials are used to explain soln.

#### 1.1 Sample Space

**Motivation:** If you have 4 sheep and a flea, the probability that starting from sheep 1, the flea will jump to sheep 4 in 10 steps is 0.2.

- Ambiguous as there are 2 different interpretations for the sample space (i.e. space of probability is not clear):
  - Set of sheep
  - Set of number of steps

#### 1.2 Probability Definitions

**Definition:**

- **Random Experiment:** An outcome (realization) for each run.
- **Sample Space  $\Omega$ :** Set of all possible outcomes.
- **Events:** (measurable) subsets of  $\Omega$ .
- **Probability of Event  $A$ :**  $P[A] \equiv P[\text{'outcome is in } A\text{'}]$ .

**Example: Roll Fair Die**

- $\Omega = \{1, 2, 3, 4, 5, 6\}$ .
- $P[\text{'even number'}] = \frac{1}{2}$ .

### 1.3 Axioms of Probability

**Definition:**

1.  $P[A] \geq 0$  for all  $A \in \Omega$ .
2.  $P[\Omega] = 1$ .
3. If  $A \cap B = \emptyset$ , then  $P[A \cup B] = P[A] + P[B]$  for all  $A, B \in \Omega$ .



Figure 1: 3rd Axiom

### 1.4 Conditional Probability

**Definition:**

$$P[A|B] = \frac{P[A \cap B]}{P[B]} \quad (1)$$

- $|\cdot$ : Given event (data/obs.).

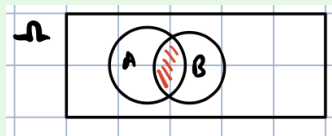


Figure 2: Conditional Probability

**Notes:**

- Changing sample space to  $B$ .
- Conditional probability satisfy the 3 axioms (i.e. are probabilities), can be viewed as probability measure on new sample space  $B$ .

#### 1.4.1 Consequences of Conditional Probability

**Definition:**

$$P[A \cap B] = P[A|B]P[B] = P[B|A]P[A] \quad (2)$$

#### 1.4.2 Independence

**Definition:**  $A$  and  $B$  are independent iff

$$P[A \cap B] = P[A]P[B] \iff P[A|B] = P[A] \iff P[B|A] = P[B] \quad (3)$$

#### 1.4.3 Importance of Labelling

**Example: Toss 2 Fair Coins**

1. **Given:** Given that one of the coins is heads, what is the probability that the other coin is tails?
2. **Wrong Solution:**  $\frac{1}{2}$  since  $\{HH, HT, TH, TT\}$ , so  $P[T|H] = \frac{1}{2}$ , which assumes that the coins are distinguishable (i.e. coin #1 is heads)
3. **Correct Solution:**  $\frac{2}{3}$  since  $\{HH, HT, TH\}$  as we didn't specify which coin was heads, so  $P[T|H] = \frac{2}{3}$ , which assumes that the coins are indistinguishable.

## 2 L2: Probability Review

### 2.1 Total Probability

**Definition:** If  $H_1, \dots, H_n$  form a partition of  $\Omega$ , then

$$P[A] = \sum_{i=1}^n P[A|H_i]P[H_i] \quad (4)$$

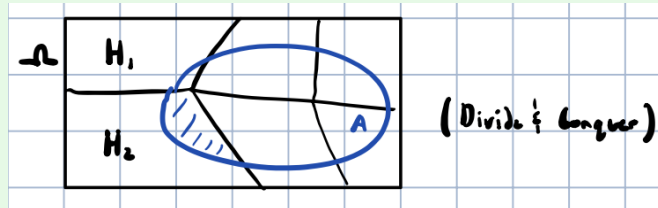


Figure 3: Total Probability

### 2.2 Bayes' Rule

**Definition:**

$$P[H_k|A] = \frac{P[H_k \cap A]}{P[A]} = \frac{P[A|H_k]P[H_k]}{\sum_{i=1}^n P[A|H_i]P[H_i]} \quad (5)$$

#### 2.2.1 Posteriori Probability, Priori Probability (Prior), Likelihood

**Definition:**

- **Posteriori:**  $P[H_k|A]$ .
- **Priori:**  $P[H_k]$ .
- **Likelihood:**  $P[A|H_k]$ .

**Example:** Suppose a lie detector is 95% accurate, i.e.  $P[\text{'out=truth'}|\text{'in=truth'}] = 0.95$  and  $P[\text{'out=lie'}|\text{'in=lie'}] = 0.95$ . It says that Mr. Ernst is lying. What is the probability Mr. Ernst is actually lying.

- **Observation:**  $A = \text{'out=lie'}$ .
- **Hypothesis:**  $H_0 = \text{'in=lie'}$  and  $H_1 = \text{'in=truth'}$ .
- **Solution:** 
$$P[H_0|A] = \frac{P[A|H_0]P[H_0]}{P[A|H_0]P[H_0] + P[A|H_1]P[H_1]} = \frac{0.95 \times P[H_0]}{0.95 \times P[H_0] + 0.05 \times (1 - P[H_0])}.$$
- $H_0 = 0.01$ : i.e. 1% of the population are liars, then 
$$P[H_0|A] = \frac{0.95 \times 0.01}{0.95 \times 0.01 + 0.05 \times 0.99} = 0.16.$$

**Warning:** Need to know priori probability.

#### 2.2.2 Interpretation of Bayes' Rule

**Notes:** Taking one component of the total probability and normalizing it by the sum of all components.

## 2.3 Random Variables

**Motivation: Coin Toss** Mapping of each outcome to a real number

- $w \in \Omega$  is the outcome of a coin toss, and  $X$  is the RV, so  $H \rightarrow 0$  and  $T \rightarrow 1$ .



Figure 4: Random Variables

- Mapping is deterministic function. RV is not random or variable.

**Definition:** Mapping from  $\Omega$  to  $\mathbb{R}$ .

## 2.4 Distribution of RV

### 2.4.1 Cumulative Distribution Function (CDF) of RV

**Definition:**

$$F_X(x) \equiv P[X \leq x] \quad (6)$$

### 2.4.2 Discrete RV Probability Mass Function (PMF)

**Definition:**

$$P_X(x_j) \equiv P[X = x_j] \quad j = 1, 2, 3, \dots \quad (7)$$

**Example: Binomial RV w/  $(n, p)$**

$$P_X(k) = \binom{n}{k} p^k (1-p)^{n-k} \quad (8)$$

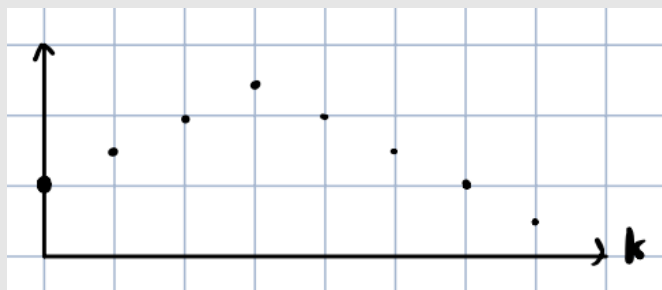


Figure 5: Binomial RV

### 2.4.3 Continuous RV Probability Density Function (PDF)

**Definition:**

$$f_X(x) \equiv \frac{d}{dx} F_X(x) \quad (9)$$

$$P[x < X < x + dx] = f_X(x)dx \quad (10)$$

**Example: Gaussian RV w/  $(\mu, \sigma^2)$**

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \quad (11)$$

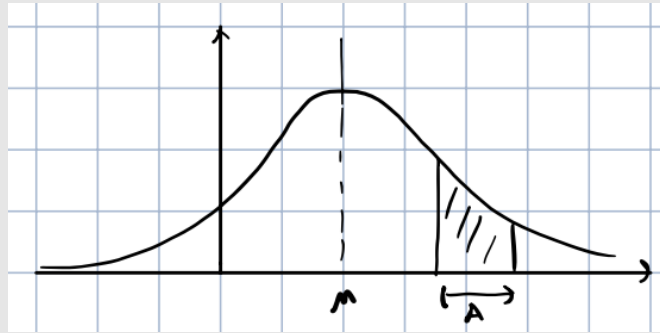


Figure 6: Gaussian RV

- $P[X \in A] = \int_A f_X(x) dx.$

**Notes:** Discrete RV has pdf w/  $\delta$  functions.

#### 2.4.4 Conditional PMF/PDF

**Definition:**

$$P_X(x|A) \quad (12)$$

$$f_X(x|A) \quad (13)$$

**Example: Continuous**

$$f(x|X > a) = \begin{cases} \frac{f_X(x)}{P[X > a]} & \text{if } x > a \\ 0 & \text{otherwise} \end{cases} \quad (14)$$

**Example: Geometric RV** Geometric RV  $X$  w/ success probability  $p$

$$P_X(k) = (1-p)^{k-1}p \quad (15)$$

- **Memoryless Property:**  $P_X[k|X > m] = \frac{p(1-p)^{k-1}}{(1-p)^m} = p(1-p)^{k-m-1}.$ 
  - So it only cares about the additional trials (i.e. same as resetting after  $m$  trials).

## 2.5 Expected Values

**Definition:**

$$E[X] = \int_{-\infty}^{\infty} x f_X(x) dx \quad \text{If int. values} \quad \sum_{k=-\infty}^{\infty} k f_X(k) \quad (16)$$

$$E[h(X)] = \int_{-\infty}^{\infty} h(x) f_X(x) dx \quad \text{If int. values} \quad \sum_{k=-\infty}^{\infty} h(k) f_X(k) \quad (17)$$

$$\text{Var}[X] = E[(X - E[X])^2] = E[X^2] - E[X]^2 \quad (18)$$

$$E[X|A] = \int_{-\infty}^{\infty} x f_X(x|A) dx \quad (19)$$

**Example: Lottery Ticket (Geometric RV)**

1. **Given:** Buying one lottery ticket per week
  - Each ticket has  $10^{-7} = p$  chance of winning the jackpot.
  - $X$  = '# of weeks to win jackpot'.
2. **Problem:** What is the expected number of weeks to win the jackpot?
3. **Solution:**  $E[X] = \sum_{k=1}^{\infty} k(1-p)^{k-1}p = \dots = \frac{1}{p} = 10^7$  weeks.
4. **Extension (Memoryless Property):** If I have already played for 999999 weeks, what is the expected number of weeks to win the jackpot?  $E[X - 999999 | X > 999999] = E[X] = 10^7$  weeks.

### 3 L3: Probability Review

#### 3.1 2 RVs

**Notes:** RVs are neither random nor a variable.

$$\underline{Z} = (X, Y)$$

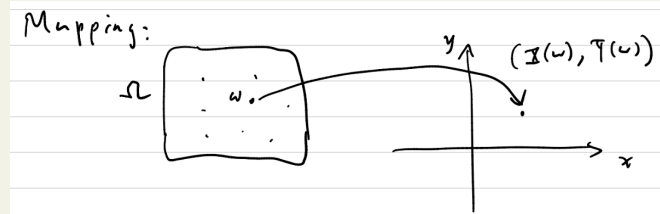


Figure 7: Mapping of RVs

#### 3.2 Joint PMF/PDF

**Definition:**

$$P_{X,Y}(x, y) = P[X = x, Y = y] \quad (20)$$

$$f_{X,Y}(x, y) = \frac{\partial^2}{\partial x \partial y} F_{X,Y}(x, y) \quad (21)$$

$$P[(X, Y) \in A] = \int \int_{(x,y) \in A} f_{X,Y}(x, y) dx dy \quad (22)$$

**Example:** Jointly Gaussian RVs  $X$  and  $Y$  with  $(\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \rho)$

$$f_{X,Y}(x, y) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}} \exp \left\{ -\frac{1}{2(1-\rho^2)} \left[ \left( \frac{x-\mu_1}{\sigma_1} \right)^2 - 2\rho \left( \frac{x-\mu_1}{\sigma_1} \right) \left( \frac{y-\mu_2}{\sigma_2} \right) + \left( \frac{y-\mu_2}{\sigma_2} \right)^2 \right] \right\}$$

#### 3.3 Expectations

**Definition:**

$$E[g(X, Y)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y) f_{X,Y}(x, y) dx dy$$

**Notes:**

- $g(X, Y)$  is also an RV, but inside the integral or sum, you use  $x$  and  $y$  as dummy variables to vary through the values of the RVs.

##### 3.3.1 Correlation

**Definition:**

$$E[XY] \quad (23)$$



### 3.3.2 Covariance

**Definition:**

$$\text{Cov}[X, Y] = E[(X - \mu_X)(Y - \mu_Y)] = E[XY] - \mu_X \mu_Y = E[XY] - E[X]E[Y] \quad (24)$$

**Notes:**

- Mean shifted to 0.

### 3.3.3 Correlation Coefficient

**Definition:**

$$\rho_{X,Y} = E \left[ \left( \frac{X - \mu_X}{\sigma_X} \right) \left( \frac{Y - \mu_Y}{\sigma_Y} \right) \right] = \frac{\text{Cov}[X, Y]}{\sigma_X \sigma_Y} \quad (25)$$

- $|\rho_{X,Y}| \leq 1$

**Notes:**

- Mean shifted to 0 and normalized by the standard deviation.

## 3.4 Marginal PMF/PDF

**Definition:**

$$P_X(x) = \sum_{j=1}^{\infty} P_{X,Y}(x, y_j), \quad P_Y(y) = \sum_{j=1}^{\infty} P_{X,Y}(x_j, y) \quad (26)$$

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dy, \quad f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x, y) dx \quad (27)$$

**Notes:**

- Total probability theorem is being used here.

**Example:** Jointly Gaussian  $X$  and  $Y$ :

$$\begin{aligned} f_X(x) &= \int_{-\infty}^{\infty} f_{X,Y}(x, y) dy \\ &= \dots \quad (\text{completing the square}) \\ &= \frac{1}{\sqrt{2\pi}\sigma_1} e^{-\frac{(x-\mu_1)^2}{2\sigma_1^2}}, \quad \text{marginally Gaussian} \end{aligned}$$

- Gaussian RVs has a property that the PDF of a single variable is equal to the marginal Gaussian of two variables.

## 3.5 Conditional PMF/PDF

**Definition:**

$$P_{X|Y}(x|y) \triangleq P[X = x|Y = y] = \frac{P_{X,Y}(x, y)}{P_Y(y)} \quad (28)$$

$$f_{X|Y}(x|y) \triangleq \frac{f_{X,Y}(x, y)}{f_Y(y)} \quad (29)$$

### 3.6 Bayes' Rule

**Definition:**

$$P_{Y|X}(x|y) = \frac{P_{X,Y}(x,y)}{P_X(x)} = \frac{P_{X|Y}(x|y)P_Y(y)}{\sum_{j=1}^{\infty} P_{X,Y}(x,y_j)P_Y(y_j)} \quad (30)$$

$$f_{Y|X}(y|x) = \frac{f_{X,Y}(x,y)}{f_X(x)} = \frac{f_{X|Y}(x|y)f_Y(y)}{\int_{-\infty}^{\infty} f_{X|Y}(x|y')f_Y(y') dy'} \quad (31)$$

### 3.7 Independent vs. Uncorrelated vs. Orthogonal

**Definition:**

1. Independent:

$$f_{X|Y}(x|y) = f_X(x) \quad \forall y \Leftrightarrow f_{X,Y}(x,y) = f_X(x)f_Y(y) \quad (32)$$

2. Uncorrelated:

$$\text{Cov}[X,Y] = 0 \quad \Leftrightarrow \quad \rho_{X,Y} = 0 \quad (33)$$

3. Orthogonal:

$$E[XY] = 0 \quad (34)$$

**Theorem:** If independent, then uncorrelated.

**Derivation:**

$$\begin{aligned} \text{Independent} &\implies E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_{X,Y}(x,y) dx dy \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_X(x) f_Y(y) dx dy \\ &= \left( \int_{-\infty}^{\infty} x f_X(x) dx \right) \left( \int_{-\infty}^{\infty} y f_Y(y) dy \right) \\ &\implies E[XY] = E[X]E[Y] \\ &\implies \text{Cov}[X,Y] = 0, \quad \text{uncorrelated} \\ &\neq \text{in general.} \end{aligned}$$

**Example:** Jointly Gaussian RVs  $X$  and  $Y$ : If uncorrelated, i.e.  $\rho_{X,Y} = 0$ , then  $X$  and  $Y$  are independent.

$$\begin{aligned} f_{X,Y}(x,y) &= \frac{1}{2\pi\sigma_1\sigma_2} \exp \left\{ -\frac{1}{2} \left[ \left( \frac{x-\mu_1}{\sigma_1} \right)^2 + \left( \frac{y-\mu_2}{\sigma_2} \right)^2 \right] \right\} \\ &= \frac{1}{\sqrt{2\pi}\sigma_1} e^{-\frac{(x-\mu_1)^2}{2\sigma_1^2}} \cdot \frac{1}{\sqrt{2\pi}\sigma_2} e^{-\frac{(y-\mu_2)^2}{2\sigma_2^2}} \\ &= f_X(x)f_Y(y) \quad \text{independent} \end{aligned}$$

### 3.8 Conditional Expectation

**Definition:**

$$E[Y] = E[E[Y|X]] \quad (35)$$

$$E[h(Y)] = E[E[h(Y)|X]] \quad (36)$$

**Notes:**

- $E[E[Y|X]]$  is w.r.t.  $X$ .
- $E[Y|X]$  is w.r.t.  $Y$ .

**Derivation:**

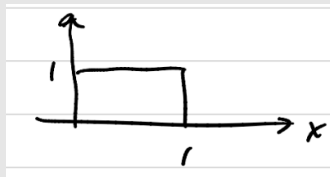
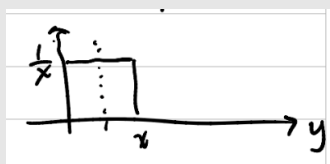
$$\begin{aligned}
 E[Y] &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y f_{X,Y}(x,y) dx dy \\
 &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y f_{Y|X}(y|x) f_X(x) dx dy \\
 &= \int_{-\infty}^{\infty} \left( \int_{-\infty}^{\infty} y f_{Y|X}(y|x) dy \right) f_X(x) dx \\
 &= \int_{-\infty}^{\infty} E[Y|X=x] f_X(x) dx \quad (\text{using the total probability theorem}) \\
 &= \int_{-\infty}^{\infty} g(x) f_X(x) dx \\
 &= E[g(X)] \\
 &= E[E[Y|X]].
 \end{aligned}$$

**Example:**

1. **Given:** An unknown voltage.  $X \sim \text{Uniform}(0, 1)$ . Measurement from a (bad) voltmeter:  $Y \sim \text{Uniform}(0, X)$ .

$$\begin{aligned}
 f_X(x) &= \begin{cases} 1, & 0 < x < 1 \\ 0, & \text{otherwise} \end{cases} \\
 f_{Y|X}(y|x) &= \begin{cases} \frac{1}{x}, & 0 < y < x \\ 0, & \text{otherwise} \end{cases}
 \end{aligned}$$

- **Note:** Area under PDF is 1.

Figure 8: Uniform Distribution of  $X$ Figure 9: Uniform Distribution of  $Y$

## 2. Expected Value (Average Reading of Bad Voltmeter):

$$\begin{aligned}
 E[Y] &= E[E[Y|X]] \\
 &= E\left[\frac{X}{2}\right] \quad \text{Since in the middle of 0 and x} \\
 &= \frac{1}{2} \cdot E[X] \\
 &= \frac{1}{2} \cdot \frac{1}{2} = \frac{1}{4} \quad \text{Since } E[X] \text{ (i.e. mean) is 0.5}
 \end{aligned}$$

## 3. The Long Way:

$$\begin{aligned}
 f_Y(y) &= \int_{-\infty}^{\infty} f_{Y|X}(y|x) f_X(x) dx \\
 &= \int_y^1 f_{Y|X}(y|x) f_X(x) dx \\
 &= \int_y^1 \frac{1}{x} \cdot 1 dx \\
 &= -\ln y. \\
 E[Y] &= \int_0^1 y \cdot (-\ln y) dy = \dots = \frac{1}{4}
 \end{aligned}$$

4. **Question:** Suppose  $Y = \frac{1}{8}$ . What is "best" given  $X$ ? This will be the question for the rest of the course.

## 4 L4: Estimation of Sample Mean

### 4.1 Parameter Estimation:

**Motivation:** The readout of a sensor is  $X = \theta + N$  volts

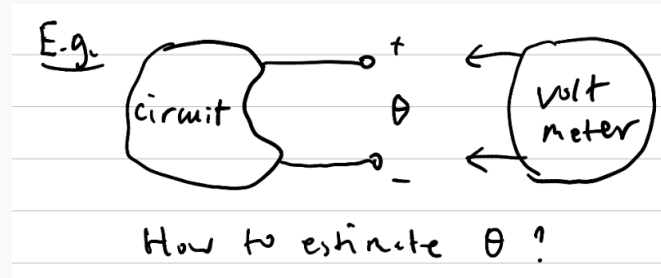


Figure 10:

- There is some noise  $N$  in the sensor, so we want to estimate the true value of  $\theta$  (unknown parameter to be estimated)
  - e.g. Mean and/or variance of  $X$ .

### 4.2 Estimator:

**Definition:** Perform  $n$  independent and identically distributed (i.i.d.) measurements/observations of  $X$ :  $X_1, X_2, \dots, X_n$ .

$$\hat{\Theta} = \hat{\Theta}(\underline{X}) = g(X_1, X_2, \dots, X_n) \quad (37)$$

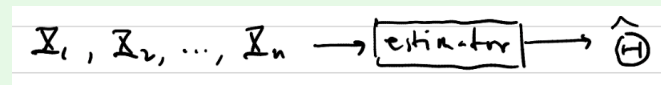


Figure 11:

#### 4.2.1 Estimation Error:

**Definition:**

$$\hat{\Theta}(\underline{X}) - \theta \quad (38)$$

#### 4.2.2 Unbiased

**Definition:** The estimator  $\hat{\Theta}$  is unbiased if

$$\mathbb{E}[\hat{\Theta}(\underline{X})] = \theta \quad (39)$$

- **Asymptotically Unbiased:**  $\lim_{n \rightarrow \infty} \mathbb{E}[\hat{\Theta}(\underline{X})] = \theta$  (big data)

#### 4.2.3 Consistent

**Definition:** The estimator  $\hat{\Theta}$  is consistent if  $\hat{\Theta}(\underline{X}) \rightarrow \theta$  as  $n \rightarrow \infty$ , in probability, i.e.,  $\forall \epsilon > 0$ ,

$$\lim_{n \rightarrow \infty} P(|\hat{\Theta}(\underline{X}) - \theta| < \epsilon) \rightarrow 1 \quad (40)$$

as  $n \rightarrow \infty$ .

### 4.3 Sample Mean & Law of Large Numbers

**Definition:** Given a sequence of i.i.d. random variables (RVs),  $X_1, X_2, \dots, X_n$ , w/ unknown mean  $\mu$ , estimate  $\mu$ . Let  $S_n = X_1 + X_2 + \dots + X_n$ . The *sample mean* is

$$M_n = \frac{1}{n} S_n$$

- How good is  $M_n$  as an estimator of  $\mu$ ?
  - Use unbiased and consistent to evaluate  $M_n$ .

**Example:** Previous voltage measurement, e.g.,

$$X_i = \mu + N_i$$

where  $\mu$  is the true value and  $N_i$  is the noise.

If we assume  $N_i$  are i.i.d. with zero mean,

$$E[X_i] = E[\mu + N_i] = E[\mu] + E[N_i] = \mu + 0 = \mu, \quad \forall i$$

#### 4.3.1 Digression for Sum of RVs (not necessarily independent or identically distributed)

**Derivation:**

$$\begin{aligned} E[S_n] &= E[X_1 + \dots + X_n] \\ &= E[X_1] + \dots + E[X_n] \end{aligned}$$

**Derivation:**

$$\begin{aligned} \text{Var}[S_n] &= E[(S_n - E[S_n])^2] \\ &= E\left[\left(\sum_{i=1}^n X_i - E[X_i]\right)^2\right] \\ &= E\left[\sum_{i=1}^n \sum_{j=1}^n (X_i - E[X_i])(X_j - E[X_j])\right] \\ &= \sum_{i=1}^n \sum_{j=1}^n E[(X_i - E[X_i])(X_j - E[X_j])] \\ &= \sum_{i=1}^n \sum_{j=1}^n \text{Cov}[X_i, X_j] \\ &= \sum_{i=1}^n \text{Var}[X_i] + \sum_{i \neq j} \sum_{j=1}^n \text{Cov}[X_i, X_j] \end{aligned}$$

#### 4.3.2 Unbiased (i.i.d.)

**Derivation:**

$$\begin{aligned}
E[M_n] &= E\left[\frac{1}{n}S_n\right] \\
&= \frac{1}{n}(E[X_1] + \dots + E[X_n]) \\
&= \frac{1}{n}(n\mu) \quad \text{since } X_i \text{ are i.i.d. so same expectation} \\
&= \mu \Rightarrow \text{Unbiased!}
\end{aligned}$$

**4.3.3 Consistent (i.i.d.)****Derivation:**

$$\begin{aligned}
\text{Var}[M_n] &= \text{Var}\left[\frac{1}{n}S_n\right] \\
&= \frac{1}{n^2}\text{Var}[S_n] \quad \text{taking out constant requires squaring} \\
&= \frac{1}{n^2}\left(\sum_{i=1}^n \text{Var}[X_i] + \sum_{i \neq j} \text{Cov}[X_i, X_j]\right) \\
&= \frac{1}{n^2}(n\sigma^2) \quad \sigma^2 \triangleq \text{Var}[X_i] \text{ and } X_i \text{ are i.i.d. so covariance is 0} \\
&= \frac{\sigma^2}{n} \rightarrow 0 \text{ as } n \rightarrow \infty.
\end{aligned}$$

- This means that there is no variance in the sample mean as  $n$  approaches infinity, so it converges to the true mean.

Recall the Chebyshev Inequality:

$$P[|X - E[X]| \geq \epsilon] \leq \frac{\text{Var}[X]}{\epsilon^2}, \quad \forall \epsilon > 0.$$

Substitute in  $M_n$ :

$$\begin{aligned}
P[|M_n - E[M_n]| \geq \epsilon] &\leq \frac{\text{Var}[M_n]}{\epsilon^2} \\
P[|M_n - \mu| \geq \epsilon] &\leq \frac{\sigma^2}{n\epsilon^2} \\
\Rightarrow P[|M_n - \mu| < \epsilon] &\geq 1 - \frac{\sigma^2}{n\epsilon^2} \rightarrow 1 \text{ as } n \rightarrow \infty \text{ then it is consistent}
\end{aligned}$$

**Warning:** Cov = 0 because independence implies uncorrelated.

**4.3.4 Weak Law of Large Numbers**

**Definition:** Even if  $\sigma$  is infinite, then  $\forall \epsilon > 0$ ,

$$\lim_{n \rightarrow \infty} P[|M_n - \mu| < \epsilon] = 1$$

### 4.3.5 Confidence Interval: Finding $n$

**Example:** Measure an unknown voltage  $\theta$  for  $n$  times and obtain independent measurements:

$$X_i = \theta + N_i,$$

where  $N_i$  are i.i.d. random variables with mean 0 and variance 1.

- We want to determine how many measurements  $n$  are sufficient so that

$$P(|M_n - \theta| < 0.1) \geq 0.95,$$

where 0.1 is the desired precision and 0.95 is the confidence level.

- The sample mean is given by:

$$M_n = \frac{1}{n} \sum_{i=1}^n X_i = \theta + \frac{1}{n} \sum_{i=1}^n N_i.$$

- The variance of  $X_i$  is:

$$\sigma^2 = \text{Var}[X_i] = \text{Var}[\theta + N_i] = \text{Var}[N_i] = 1.$$

–  $\text{Var}[aX + b] = a^2 \text{Var}[X]$ , where  $a = 1$  and  $b = \theta$ .

- Using Chebyshev's inequality:

$$1 - \frac{\sigma^2}{n\epsilon^2} \geq 0.95,$$

where  $\epsilon = 0.1$  (precision).

- Solving for  $n$ :

$$\begin{aligned} 1 - \frac{1}{n(0.1)^2} &\geq 0.95, \\ \frac{1}{n(0.1)^2} &\leq 0.05, \\ n &\geq 2000. \end{aligned}$$

Thus, at least 2000 measurements are needed to achieve the desired precision and confidence level.



## 5 L5: Sample Mean and Maximum Likelihood Estimation

### FAQ:

- Why can we say that it is consistent for the last example?

### 5.1 Maximum Likelihood Estimation

**Motivation:** Choose parameter  $\theta$  that is most likely to generate the observation  $x_1, x_2, \dots, x_n$ .

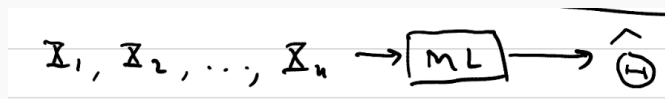


Figure 12:

#### Definition:

$$\hat{\Theta} = \arg \max_{\theta} P_{\underline{X}}(\underline{x}|\theta), \text{ discrete } X. \quad (41)$$

$$\hat{\Theta} = \arg \max_{\theta} f_{\underline{X}}(\underline{x}|\theta), \text{ continuous } X. \quad (42)$$

#### 5.1.1 Log-Likelihood

#### Definition:

$$\hat{\theta} = \arg \max_{\theta} \sum_{i=1}^n \log P_X(x_i|\theta) \quad (43)$$

$$\hat{\theta} = \arg \max_{\theta} \sum_{i=1}^n \log f_X(x_i|\theta). \quad (44)$$

**Warning:** Can only go from argmax of fcn to argmax of log fcn, if it is i.i.d.

#### Derivation:

$$\begin{aligned}
 \text{i.i.d. } X_1, X_2, \dots, X_n &\implies \\
 p_{\underline{X}}(\underline{x}|\theta) &= \prod_{i=1}^n p_{X_i}(x_i|\theta) \\
 &= \prod_{i=1}^n p_X(x_i|\theta) \quad \text{drop the i due to i.i.d. assumption} \\
 \log p_{\underline{X}}(\underline{x}|\theta) &= \sum_{i=1}^n \log p_X(x_i|\theta).
 \end{aligned}$$

#### Example:

##### 1. Model and Observations:

- Assume a biased coin with probability  $\theta$  of showing heads. Find ML estimator for  $\theta$ .
- Toss the coin  $n$  times and obtain Bernoulli random variables  $X_1, \dots, X_n$  such that:

$$\text{"heads"} \rightarrow 1, \quad \text{"tails"} \rightarrow 0.$$

- Total number of heads is:

$$k = \sum_{i=1}^n X_i.$$

For example:

$$\underline{x} = (1, 0, 0, 0, 1, 1, 0, 1, 1, 1), \quad k = 6.$$

- Probability of observations  $x_1, \dots, x_n$  corresponding to parameter  $\theta$  is:

$$p_{\underline{X}}(\underline{x}|\theta) = \theta^k (1 - \theta)^{n-k}.$$

- It is sufficient to know only  $k$ .
- Note: Don't need the  $\binom{n}{k}$  term because we are given the specific sequence of heads and tails.

## 2. Log-Likelihood and Maximization:

- The log-likelihood function is:

$$\log p_{\underline{X}}(\underline{x}|\theta) = k \log(\theta) + (n - k) \log(1 - \theta).$$

- To maximize the log-likelihood over  $\theta$ , set:

$$\begin{aligned} 0 &= \frac{\partial}{\partial \theta} \log p_{\underline{X}}(\underline{x}|\theta), \\ 0 &= \frac{k}{\theta} - \frac{n - k}{1 - \theta}, \\ \theta &= \frac{k}{n}. \end{aligned}$$

- Thus, the Maximum Likelihood Estimator (MLE) is:

$$\hat{\Theta} = \frac{k}{n}, \quad \text{where } k = \sum_{i=1}^n X_i.$$

This corresponds to the observed frequency of heads, which is intuitive b/c the more heads we see, the more likely the coin is biased towards heads.

## 3. Examples:

- For  $\underline{x} = (1, 0, 0, 0, 1, 1, 0, 1, 1, 1)$ :

$$\begin{aligned} p_X(\underline{x}|\theta) &= \theta^6 (1 - \theta)^4, \\ \hat{\theta} &= \frac{6}{10} = 0.6. \end{aligned}$$

- For  $\underline{x} = (0, 1, 1, 1, 0, 0, 1, 0, 1, 0)$ :

$$\begin{aligned} p_X(\underline{x}|\theta) &= \theta^5 (1 - \theta)^5, \\ \hat{\theta} &= \frac{5}{10} = 0.5. \end{aligned}$$

## Notes:

1.  $k$  is a sufficient statistic for this Maximum Likelihood (ML) estimator.

2. The expectation of the estimator  $\hat{\theta}$  is:

$$\begin{aligned} E[\hat{\Theta}] &= E\left[\frac{1}{n} \sum_{i=1}^n X_i\right] \\ &= \frac{1}{n} \sum_{i=1}^n E[X_i] \\ &= \frac{1}{n}(n\theta) \\ &= \theta \quad (\text{Unbiased}). \end{aligned}$$

$$- E[X_i] = (1)\theta + (0)(1 - \theta) = \theta$$

3. In fact,  $\hat{\Theta} = \frac{1}{n} \sum_{i=1}^n X_i$  is the sample mean, and  $\theta$  is the true mean. Therefore,  $\hat{\theta} \rightarrow \theta$  in probability, which implies that  $\hat{\theta}$  is *consistent*.

## 6 L6: Maximum Likelihood and Laplace

### 6.1 MLE for Categorical Random Variables

**Example:**

1. We say that  $X \sim \text{Cat}(\underline{\theta})$  if

$$P[X = m] = \theta_m, \quad m = 1, 2, \dots, M.$$

- Going from 2 to  $M$  categories is a generalization of the Bernoulli distribution.

The parameter  $\underline{\theta}$  is a vector:

$$\underline{\theta} = \begin{bmatrix} \theta_1 \\ \theta_2 \\ \vdots \\ \theta_M \end{bmatrix},$$

such that  $\theta_m \geq 0$  and  $\sum_{m=1}^M \theta_m = 1$ .

2. Given  $n$  i.i.d. observations  $X_1, \dots, X_n$ , we aim to find the maximum likelihood estimator (MLE) of  $\underline{\theta}$ .
3. Define  $n_m$  as the number of observations that equal  $m$ :

$$n_m = \sum_{i=1}^n 1(x_i = m),$$

where  $1(x_i = m)$  is the indicator function. Note that  $\sum_{m=1}^M n_m = n$ .

4. The likelihood function is:

$$p_{\underline{X}}(\underline{x} | \underline{\theta}) = \prod_{m=1}^M \theta_m^{n_m}.$$

- Similar to the Bernoulli distribution, but with  $M$  categories.

Taking the log, we get:

$$\log p_{\underline{X}}(\underline{x} | \underline{\theta}) = \sum_{m=1}^M n_m \log \theta_m.$$

5. To find the optimal  $\underline{\theta}$ , we minimize the negative log-likelihood:

$$\min_{\underline{\theta}} - \sum_{m=1}^M n_m \log \theta_m,$$

subject to the constraints  $\theta_m \geq 0$  for  $1 \leq m \leq M$  and  $\sum_{m=1}^M \theta_m = 1$ .

6. Solving this optimization problem, the MLE is:

$$\hat{\theta}_m = \frac{N_m}{n} = \frac{\sum_{i=1}^n 1(X_i = m)}{n}, \quad \hat{\underline{\theta}} = \begin{bmatrix} \frac{N_1}{n} \\ \vdots \\ \frac{N_M}{n} \end{bmatrix}.$$

## 6.2 MLE for Gaussian Random Variables

### Example:

1. Given  $n$  i.i.d. observations  $X_1, \dots, X_n$  of a Gaussian random variable with parameters  $(\mu, \sigma^2)$ , we aim to find the maximum likelihood estimators (MLEs) of  $\mu$  and  $\sigma^2$ .

$$f_{\underline{X}}(\underline{x}|\mu, \sigma^2) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x_i - \mu)^2}{2\sigma^2}\right),$$

$$\log f_{\underline{X}}(\underline{x}|\mu, \sigma^2) = \sum_{i=1}^n \left(-\frac{(x_i - \mu)^2}{2\sigma^2} - \log \sigma - \log \sqrt{2\pi}\right).$$

2. To find  $\mu$ , take the derivative of the log-likelihood with respect to  $\mu$  and set it to zero:

$$0 = \frac{\partial}{\partial \mu} \sum_{i=1}^n \left(-\frac{(x_i - \mu)^2}{2\sigma^2}\right),$$

$$0 = \frac{1}{n} \sum_{i=1}^n x_i - \mu,$$

$$\mu = \frac{1}{n} \sum_{i=1}^n x_i.$$

3. To find  $\sigma^2$ , take the derivative of the log-likelihood with respect to  $\sigma^2$  and set it to zero:

$$0 = \frac{\partial}{\partial \sigma^2} \sum_{i=1}^n \left(-\frac{(x_i - \mu)^2}{2\sigma^2} - \frac{1}{2} \log \sigma^2\right),$$

$$0 = -\frac{1}{2} \sum_{i=1}^n \left(\frac{(x_i - \mu)^2}{\sigma^4}\right) + \frac{1}{2\sigma^2},$$

$$\sigma^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2.$$

4. Thus, the MLEs are:

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^n X_i, \quad (\text{sample mean})$$

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \hat{\mu})^2. \quad (\text{sample variance})$$

- Note: The sample variance is biased, so we often use  $\frac{1}{n-1}$  instead of  $\frac{1}{n}$  to make it unbiased.
- Note: The sample mean is unbiased.

## 6.3 Will the Sun Rise Tomorrow? (Laplace's Problem)

### Example:

- Observation: The Sun has risen for  $n$  consecutive days. Estimate the probability that it will rise tomorrow.
- Model: Assume  $n$  i.i.d. Bernoulli random variables  $X_1, \dots, X_n$  with  $P[X_i = 1] = \theta$ .

### 6.3.1 Frequentist Approach

**Example:**

1. The Maximum Likelihood Estimator (MLE) is:

$$\hat{\theta} = \frac{K}{n} = \frac{\sum_{i=1}^n X_i}{n}.$$

2. If  $K = n$  (i.e., the Sun has risen every day so far), then:

$$\hat{\theta} = \frac{n}{n} = 1.$$

3. Conclusion: The Sun will rise tomorrow with probability 1, regardless of what  $n$  is, based on the Frequentist approach.
  - This doesn't make sense b/c if  $n = 1$  then we are assuming 100% it will rise based on one observation.

### 6.3.2 Bayesian Approach

**Example:**

1. Assume that  $\theta$  is not fixed but drawn from a uniform distribution in  $[0, 1]$ . This means that the probability of the Sun rising is based on a uniform distribution.
2. We want to find the probability that the sun will rise tomorrow given that it has risen for  $n$  consecutive days:

$$P[X_{n+1} = 1 | X_1 = 1, \dots, X_n = 1].$$

Using Bayes' Theorem:

$$P[X_{n+1} = 1 | X_1 = 1, \dots, X_n = 1] = \frac{P[X_1 = 1, \dots, X_{n+1} = 1]}{P[X_1 = 1, \dots, X_n = 1]}.$$

3. Compute  $P[X_1 = 1, \dots, X_n = 1]$ :

$$P[X_1 = 1, \dots, X_n = 1] = \int_0^1 P[X_1 = 1, \dots, X_n = 1 | \Theta = \theta] f_{\Theta}(\theta) d\theta.$$

Since  $f_{\Theta}(\theta) = 1$  (uniform prior) and  $P[X_1 = 1, \dots, X_n = 1 | \Theta = \theta] = \theta^n$ , we have:

$$P[X_1 = 1, \dots, X_n = 1] = \int_0^1 \theta^n d\theta = \frac{1}{n+1}.$$

4. Compute  $P[X_1 = 1, \dots, X_{n+1} = 1]$  similarly:

$$P[X_1 = 1, \dots, X_{n+1} = 1] = \int_0^1 \theta^{n+1} d\theta = \frac{1}{n+2}.$$

5. Combine results:

$$P[X_{n+1} = 1 | X_1 = 1, \dots, X_n = 1] = \frac{\frac{1}{n+2}}{\frac{1}{n+1}} = \frac{n+1}{n+2}.$$

6. Conclusion: As  $n$  increases, the probability approaches 1, providing more certainty with more data.