# Medici MAT185: Cheat Sheet

# **Chapter 4: A Postcard from Vector Space**

## **Vector Space:**

A vector space V over a field  $\Gamma$  of elements  $\{\alpha, \beta, \gamma...\}$  called scalars, is a **set** of elements  $\{u, v, w...\}$  called vectors, such that the following **axioms are satisfied**.

These axioms involve two operations:

1. **Vector Addition**, denoted as u + w, such that for all  $u, v, w \in V$ 

Ai. Closure:  $u + v \in V$ 

Aii. Associativity: (u + v) + w = u + (v + w)

Aiii. Zero:  $\exists$  a zero or null vector  $0 \in V$  such that u + 0 = u

Aiv. Negative:  $\exists$  a negative  $-u \in V$  such that u + (-u) = 0

2. **Scalar Multiplication**, denoted as  $\alpha u$ , such that for all  $u, v \in V$  and all  $\alpha, \beta \in \Gamma$ 

Mi. Closure:  $\alpha u \in V$ 

Mii. Associativity:  $\alpha(\beta u) = (\alpha \beta)u$ 

Miii. Distributivity:

a) 
$$(\alpha + \beta)u = \alpha u + \beta u$$

b) 
$$\alpha(u + v) = \alpha u + \alpha v$$

Be careful: One is the rule of adding real numbers and the other is adding vectors.

Miv. Unitary: For the identity element  $1 \in \Gamma$ , 1u = u

## **Proposition I:**

For every u,  $-u \in V$ , -u + u = 0

## **Proposition II:**

For every,  $u \in V$ , 0 + u = u

#### **Theorem I: Cancellation Theorem**

If u + w = v + w then u = v for any  $u, v, w \in V$ 

## **Proposition III:**

Let  $u \in V$ , then...

- 1. The zero vector  $0 \in V$  is unique.
- 2. The negative -u of u is unique.
- 3. -(-u) = u

#### **Definition of Subtraction:**

If  $u, v \in V$ , then the subtraction of v from u, denoted by u - v, is

## **Proposition IV (Commutative Property):**

For  $u, v \in V$ , u + v = v + u

## Proposition V (Properties of Zero):

 $\forall v \in V \text{ and all } \alpha \in \Gamma$ ,

- 1. 0v = 0
- 2.  $\alpha 0 = 0$
- 3. If  $\alpha v = 0$ , then either  $\alpha = 0$  or v = 0

## **Proposition VI:**

 $\forall v \in V \text{ and } \alpha \in \Gamma, (-\alpha)v = -(\alpha v) = \alpha(-v)$ 

# **Chapter 5: The Subspace Homesick Blues**

#### **Definition of Subset:**

A subset U of a vector space V is a subspace of V iff U is itself a vector space over the same field  $\Gamma$  with the same vector addition and scalar multiplication of V

## **Theorem I: Subspace Test**

Let *U* be a subset of a vector space *V*. Then *U* is a subspace of *V*, over the same field  $\Gamma$  with the same vector addition and scalar multiplication as *V*, iff for all  $u, v \in V$  and all  $\alpha \in \Gamma$ ,

S1. Zero:  $\exists$  a zero or null vector  $0 \in U$ 

S2. Closure under VA:  $u + v \in U$ 

S3. Closure under SM:  $\alpha u \in U$ 

#### **Definition of Linear Combination:**

A vector  $v \in V$  is linear combination of  $\{v_1, v_2 \dots v_n\} \subset V$  iff it can be written as

$$v = \sum_{j=1}^{n} \lambda_{j} v_{j} = \lambda_{1} v_{1} ... + \lambda_{n} v_{n}$$
 for some  $\lambda_{j} \in \Gamma$ 

## **Definition of Span:**

The span of  $\{v_1, v_2 \dots v_n\} \subset V$ , denoted  $span\{v_1, v_2 \dots v_n\}$ , is

$$span\{v_1, v_2 \dots v_n\} = \{v | v = \sum_{j=1}^n \lambda_j v_j, \forall \lambda_j \in \Gamma\}$$

## **Proposition I:**

The span of  $\{v_1, v_2 \dots v_n\} \subset V$  is a subspace of the vector space V

#### **Proposition II:**

Let  $U = span\{v_1, v_2 \dots v_n\} \sqsubseteq V$ . If W is subspace of V containing the vectors  $\{v_1, v_2 \dots v_n\}$ , then  $U \sqsubseteq W$ .

# **Chapter 6: Covering All the Bases**

## **Definition of Linear Independence:**

A set of vectors  $\{v_1, v_2 \dots v_n\} \subset V$  is linearly independent iff

$$\sum_{j=1}^{n} \lambda_{j} v_{j} = \lambda_{1} v_{1} + \dots + \lambda_{n} v_{n} = 0$$

implies that all  $\lambda_i = 0$ 

## **Proposition I:**

If  $\{v_1, v_2 \dots v_n\} \subset V$  is linearly independent and  $v = \sum_{j=1}^n \lambda_j v_j$  for all  $v \in V$ , then  $\lambda_j$  are uniquely determined.

#### Theorem I:

Let  $\{v_1, v_2 \dots v_n\} \subset V$ , a vector space. For every  $v_k (k = 1 \dots n)$ ,  $span\{v_1 \dots v_{k-1}, v_{k+1} \dots v_n\} \subsetneq span\{v_1 \dots v_n\} \text{ iff } \{v_1, v_2 \dots v_n\} \text{ is linearly independent.}$ 

## **Corollary:**

$$\begin{split} & \text{Let } \{v_1^{}, v_2^{} ... v_n^{}\} \subset V \text{, a vector space. For at least one } v_k^{} (1 \leq k \leq n), \\ & span\{v_1^{} ... v_{k-1}^{}, v_{k+1}^{} ... v_n^{}\} = span\{v_1^{} ... v_n^{}\} \text{ iff } \{v_1^{}, v_2^{} ... v_n^{}\} \text{ is linearly dependent.} \end{split}$$

## Theorem II Fundamental Theorem of Algebra:

Let V be a vector space spanned by n vectors. If a set of m vectors from V is linearly independent, then  $m \le n$ .

#### **Definition of Bases:**

A set of vectors  $\{e_1, e_2 \dots e_n\} \in V$  is a basis for the vector space V iff

- 1.  $\{e_1, e_2 \dots e_n\}$  is linearly independent
- 2.  $\{e_1, e_2 \dots e_n\}$  spans V.

#### Theorem III:

Every basis for a given vector space contains the same number of vectors.

#### **Definition of Dimensions:**

The dimension of a vector space *V*, denoted *dim V*, is the number of vectors in any of its bases.

#### **Proposition II:**

Let V be a finite-dimensional vector space w / dim V = n. Then,

- 1. A linearly independent set of vectors in V can at most contain n vectors.
- 2. A spanning set for V must at least contain n vectors.

#### Theorem IV:

Let  $\{v_1, v_2 \dots v_n\} \subset V$  be linearly independent. Then for a vector  $v \in V$ ,  $\{v, v_1, v_2 \dots v_n\}$  is linearly independent iff  $v \notin span\{v_1, v_2 \dots v_n\}$ 

#### **Theorem V Existence of Bases:**

Let *V* be a vector space spanned by a finite set of vectors. Then every linearly independent set of vectors in *V* can be extended to a basis for V.

#### Theorem VI:

Let U & W be subspaces of a finite-dimensional vector space V. It follows that

- 1. U is finite-dimensional and  $\dim U \leq \dim V$
- 2. If  $U \subseteq W$ , then  $\dim U \leq \dim W$
- 3. If  $U \subseteq W$  and  $\dim U = \dim W$ , then U = W

#### Theorem VII:

Any spanning set for a vector space V contains a basis for V.

#### Theorem VIII:

Let V be a vector space and dim V = n. Then,

- 1. Any set  $\{v_1...v_n\} \subset V$  that's linearly independent is a basis for V; and
- 2. Any set  $\{v_1 \dots v_n\} \subset V$  that spans V is a basis for V.

# Chapter 7: Rank and File

#### **Definition of Row Space:**

The row space of  $A \in {}^m R^n$ , denoted row A, is  $row A \triangleq span\{r_1, r_2 \dots r_m\}$  where  $r_i \in R^n$  are the rows of A.

## **Definition of Column Space:**

The column space of  $A \in {}^m R^n$ , denoted col A, is  $col A \triangleq span\{c_1, c_2 \dots c_n\}$  where  $c_i \in {}^m R$  are the columns of A.

## **Proposition I:**

Let  $A \in {}^m R^n$ ,  $U \in {}^m R^m$  and  $V \in {}^n R^n$ . Then  $row \ UA \le row \ A$  with equality holding if U is invertible. Furthermore,  $col \ AV \subseteq col \ A$  with equality holding if V is invertible.

## **Proposition II:**

Let  $\{x_1, x_2 \dots x_r\} \subset^m R$  and let  $U \in^m R^m$  be invertible. Then  $\{x_1, x_2 \dots x_r\}$  is linearly independent iff  $\{U_{x_1}, U_{x_2} \dots U_{x_r}\}$  is linearly independent.

#### Lemma I:

Let  $A \in {}^m R^n$ . Then  $row \tilde{A} = row A$ , where  $\tilde{A}$  is the RREF of A, and hence  $dim row \tilde{A} = dim row A$ . Moreover, the non-zero rows of  $\tilde{A}$  constitute a basis for row A.

#### Lemma II:

Let  $A \in {}^{m}R^{n}$ . Then

- 1. The set of columns with leading "1"s  $\{\varsigma_{j_1}, \varsigma_{j_2}...\varsigma_{j_r}\}$  of  $\tilde{A}$ , the RREF of A, constitutes a basis for *col*  $\tilde{A}$ .
- 2. The set of corresponding columns  $\{c_{j_1}, c_{j_2} \dots c_{j_r}\}$  of A constitutes a basis for col A.

As such  $\dim \operatorname{col} \tilde{A} = \dim \operatorname{col} A$ 

#### Theorem I:

Let  $A \in {}^{m}R^{n}$ . Then  $\dim row A = \dim col A$ 

#### **Definition of Rank:**

Let  $A \in {}^{m}R^{n}$ . The rank of A, denoted rank A, is the common dimension of row A and col A.

## **Properties of Rank:**

Property I: If  $A \in {}^{m}R^{n}$ , then  $rank A = rank \tilde{A}$ 

Property II: If  $A \in {}^{m}R^{n}$ , then  $rank A = rank A^{T}$ 

Property III: If  $A \in {}^m R^n$ ,  $U \in {}^m R^m$  and  $V \in {}^n R^n$ , then  $rank \ UA \le rank \ A$  and

 $rank \ AV \le rank \ A$  with equality holding if U and V are, respectively, invertible.

#### Theorem II Dimension Formula:

Let  $A \in {}^{m}R^{n}$ . Then  $\dim null A = n - rank A$ 

## **Theorem III: (Square Matrices)**

Let  $A \in {}^{n}R^{n}$ . Then the following statements are equivalent.

- 1. A is invertible
- 2. A has full rank n
- 3. The rows of A are linearly independent.
- 4. The columns of A are linearly independent.
- 5. For  $x \in {}^{n}R$ , Ax = 0 implies x = 0
- 6. For  $z \in {}^{n}R$ ,  $z^{T}A = 0$  implies z = 0

## Theorem IV: (Column Version)

Let  $A \in {}^{m}R^{n}$ . Then the following statements are equivalent.

- 1. rank A = n
- 2. The columns of A are linearly independent.
- 3. For  $x \in {}^n R$ , Ax = 0 implies x = 0.
- 4.  $A^{T}A$  is invertible.
- 5. A has a left inverse, i.e. BA = I for some  $B \in {}^{n}R^{m}$

#### Lemma III:

Let  $s \in {}^{n}R$ . Then, if  $s^{T}s = 0$ , s = 0

## Theorem V: (Row Version)

Let  $A \in {}^{m}R^{n}$ . Then the following statements are equivalent.

- 1. rank A = m
- 2. The rows of A are linearly independent.
- 3. For  $z \in {}^m R$ ,  $z^T A = 0$  implies z = 0.
- 4.  $AA^{T}$  is invertible.
- 5. A has a right inverse, i.e. AB = I for some  $B \in {}^{n}R^{m}$

# **Chapter 8: Coordination Plans**

**Definition of Linear Transformation:** 

**Proposition I:** 

**Definition of Image:** 

**Definition of Kernel** 

**Proposition II:** 

Theorem I Dimension Formula:

**Definition of** 

# **Chapter 9: Great Determinations** Determinant of a 2x2 Matrix: Sarrus's Rule: **Definition of Determinant Function:** Theorem I Properties of a Determinant Function: **Proposition I: Proposition II:** Lemma I: Theorem II: **Definition of Determinant: Definition of Minor Matrix: Definition of Laplace Expansion:** Theorem III: **Determinants of Elementary Matrices: Theorem IV Cauchy-Binet Product Theorem:** Theorem V Transpose Theorem: Theorem VI Invertibility Theorem:

Corollary:
Theorem VII Maclaurin-Cramer Rule:
<b>Definition of Cofactor:</b>
Definition of Adjoint:
Theorem VIII: