ROB311 Quiz 3

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April 3, 2025

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Turn-Taking Multi-Agent Decision Algorithms

1 Monte-Carlo Tree Search (MCTS)

Algorithm:

1. Selection: Traverse using an alternate policy until a node has unexplored children.

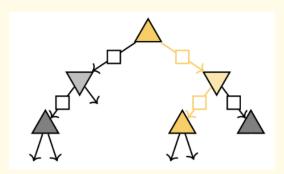


Figure 1

- Our Agent (Upper Triangle): Uses UCB to choose the next node to explore
- Other Agent (Down Triangle): Can't control their actions, so this agent picks w/ their own heuristic.
- Square Boxes: Estimated values (i.e. n and \hat{q})
- Ends when there is at least one action that hasn't been explored yet. In this case, two actions ahven't been explored.
- Can skip expansion and simulation if the most recently expanded node is a terminal state.
- 2. Expansion: Expand an unexplored child; initialize n(a) and $\hat{q}(s,a)$.

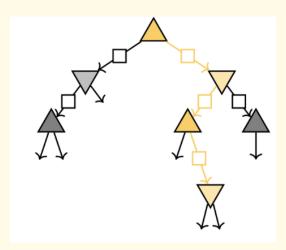


Figure 2

- $\hat{q}(s,a)$ is initialized to 0 and n(a) is initialized to 1 b/c we've visited this node once.
- Randomly pick an unexplored action unless there is only one action left.
- Can skip similuation if the most recently expanded node is a terminal state.
- 3. Simulation: Traverse using the random policy until a terminal node is reached.

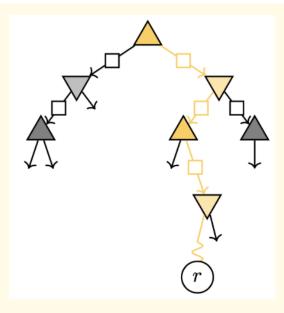


Figure 3

• Using random policy to simulate the game until a terminal state is reached (i.e. reward is obtained)
4. Back-propogation: Get the reward and reverse; update n(a) and $\hat{q}(s, a)$.

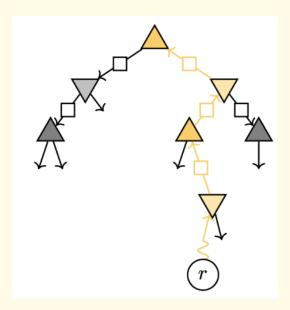


Figure 4

• Go up the path in yellow and update the values of n(a) and $\hat{q}(s,a)$ for OUR agent only (i.e. the upper triangle)

Warning:

- Works for more than 2 agents.
- Don't need to know anyone else's reward function.
- Has to be turn taking but can be not alternating (i.e. immediate switch between agents)
- Can augment simultaneous actions
- Communication
- Works fo rnon-zero sum games.

1.1 1 Player vs. 2 Player Turn-Taking Game Tree

Notes:

- 1 Player:
- $\bullet \ 2$ Player:

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1.2 Examples

1.2.1 1 Player Turn-Taking Game Tree

1.2.2 2 Player Turn-Taking Game Tree

Example:

1. **Given:** Consider a simplified two-player turn-based game tree. You are currently at the root node S_0 , which has three possible actions a_1, a_2, a_3 . The current statistics of its children are as follows:

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Action	$N(s_0,a)$	$\bar{X}(s_0,a)$
a_1	10	0.6
a_2	5	0.8
a_3	0	_

• $N(s_0, a)$: Number of times action a has been selected at state s_0

• $\bar{X}(s_0, a)$: Average reward obtained from action a at state s_0

• UCB =
$$\bar{X}(s_0, a) + \sqrt{\frac{\ln(t)}{N(s_0, a)}}$$

- t: Total number of actions taken at s_0

2. Problems:

• If we were to use the UCB algorithm, which nodes get selected during the selection phase? Which node gets expanded during the expansion phase?

• Suppose from the expanded node, simulation is performed until termination. A reward of +1 is obtained. Update the statistics at s_0 accordingly.

• Then, repeat the question, assuming a reward of -1 is attained after the simulation phase.

3. Solution:

(a) **Selection 1:** s_0 since we traverse until a node has unexplored children (i.e. s_3 is unexplored)

(b) **Expansion 1:** s_3 is automatically expanded since it is the only unexplored child of s_0 w/ $N(s_0, a_3) = 1$ and $\bar{X}(s_0, a_3) = 0$

(c) Simulation 1: Get a reward of +1

(d) **Back Propogation 1:** For this edge from s_0 to s_3 , we update the statistics as follows:

• $N(s_0, a_3) = 1$

•
$$\bar{X}(s_0, a_3) = \frac{1}{1} = 1$$

(e) **Selection 2:** s_0 and choose the action with the highest UCB value for s_1 , s_2 , and s_3 :

• $UCB(s_0, a_1) = 0.6 + \sqrt{\frac{\ln(16)}{10}} = 1.13$

• $UCB(s_0, a_2) = 0.8 + \sqrt{\frac{\ln(16)}{5}} = 1.54$

• $UCB(s_0, a_3) = 1 + \sqrt{\frac{\ln(16)}{1}} = 2.67$. Therefore, choose s_3 as part of the selection phase and assume it has unexplored children.

(f) Expansion 2: Not enough info but assume we expand an unexplored child.

(g) Simulation 2: Get a reward of -1

(h) **Back Propogation 2:** For this edge from s_0 to s_3 , we update the statistics as follows:

• $N(s_0, a_3) = 2$

• $\bar{X}(s_0, a_3) = \frac{1 + (-1)}{2} = 0$

Example:

1. Given: Consider (partial) 2-player turn-taking game-tree in which 21 iterations of MCTS have already been performed:

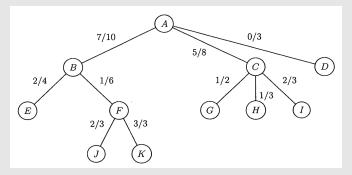


Figure 5

- Total reward: Numerator
- \bullet Total number of times action a has been selected at state s: Denominator
- 2. Problem: If we use UCB to rank order state-action pairs, which of the following states will be chosen during the 22nd selection phase.
- 3. Solution:

• UCB(AB) =
$$7/10 + \sqrt{\frac{\ln(21)}{10}} = 1.25$$

- UCB(BE) = $2/4 + \sqrt{\frac{\ln(10)}{4}} = 1.26$
- UCB(BF) = $1/6 + \sqrt{\frac{\ln(10)}{6}} = 0.79$

• UCB(AC) =
$$5/8 + \sqrt{\frac{\ln(21)}{8}} = 1.24$$

Example:

1. **Given:** Consider (partial) 2-player turn-taking game-tree in which 9 iterations of MCTS have already been performed:

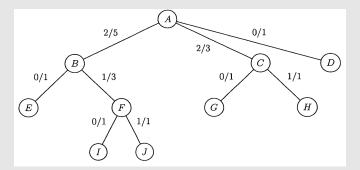


Figure 6

- Fix: CG has 0/2 not 0/1 and CH has 0/1 not 1/1
- 2. **Problem:** Suppose path chosen during the 10th selection phase had the state sequence $\langle A, C, H \rangle$ (i.e. H is the state expanded during the 10th expansion phase)
 - The simulation phase lasts for 12 transitions, after which a terminal state is reached.
 - The reward to the last turn-taker was +4.
 - Find $q(A, \langle A, B \rangle)$, $q(A, \langle A, C \rangle)$, $q(C, \langle C, H \rangle)$
- 3. Solution:
 - Assuming P1 starts at A, then P2 goes at C, then P1 goes at H, that means after 12 transitions (**even number**), P1 is the last turn-taker, therefore, P1 gets the reward of +4.
 - Backpropogation:
 - $-N(C,\langle C,H\rangle)=1, X(C,\langle C,H\rangle)=4 \text{ so } 4/1$
 - $-N(A, \langle A, C \rangle) = 4, X(A, \langle A, C \rangle) = 2 + 4 = 6 \text{ so } 6/4$
 - $-q(A, \langle A, B \rangle) = 2/5 = 0.4$
 - $-q(A, \langle A, C \rangle) = 6/4 = 1.5$
 - $-q(C,\langle C,H\rangle)=4/1=4$