

FIT 3181/5215 Deep Learning

Quiz for: Practical Skills in Deep Learning

Tutor Team

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What should be if the gradient norm $||g||_2$ (i.e., gradient of the loss w.r.t. all model parameters) of a deep learning model is decreasing to 0?

- ■A. The training arrives at local minima
- ☐ B. The training arrives at local maximal
- □C. The training arrives at saddle point
- D. One of A, B, C
- ■E. None of A, B, C

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Which activation function that Xavier initialization is good for? (MC if needed)

- ☐A. Sigmoid
- □B. Tanh
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What is gradient vanishing problem?

- ■A. Too big gradient at the higher layers of model
- □B. Too big gradient at the lower layers of model
- □C. Too small gradient at any layer of model
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Which layer can help to reduce gradient vanishing problem? (MC)

- ■A. Convolutional layer
- ■B. Pooling layer
- C. Fully Connected layer
- ■D. Dropout layer
- ■E. Batch normalization layer
- □ F. Skip connection layer
- G. ReLU Activation

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why does pooling not help?

Which is the phenomenon of overfitting problem (given a small dataset such as MNIST and a baseline model can achieve more than 90% training accuracy)?

- □ A. Training accuracy: 99%, Testing accuracy: 50%
- □B. Training accuracy: 99%, Testing accuracy: 90%
- □C. Training accuracy: 70%, Testing accuracy: 40%
- □D. Training accuracy: 30%, Testing accuracy: 40%

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In fact, there is no a gold threshold to say which case occurs overfitting. But for a small dataset like MNIST, baseline models such as baseline CNNs easily achieve more than 90% training accuracy. So A should be the correct answer.

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In fact, there is no a gold threshold to say which case occurs underfitting or overfitting. But for a small dataset like MNIST, baseline models such as baseline CNNs easily achieve more than 90% training accuracy. So C, D should be correct answers.

Which likely to be overfitting?

- ■A. Very big model with few images
- □B. Very small model with many images

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Which helps to reduce the overfitting problem? (MC)

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- ■B. Early stopping
- C. Adding more data
- □D. Weight decay
- ■E. Adding more layer
- ☐F. Using Dropout
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In batch-normalization algorithm (in training time), which are trainable parameters? (MC)

- \square A. Minibatch mean μ_B .
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- \square C. Scaling parameter γ .
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1.
$$\mu_B = \frac{1}{m_B} \sum_{i=1}^{m_B} \mathbf{x}^{(i)}$$

2.
$$\sigma_B^2 = \frac{1}{m_B} \sum_{i=1}^{m_B} (\mathbf{x}^{(i)} - \boldsymbol{\mu}_B)^2$$

3.
$$\widehat{\mathbf{x}}^{(i)} = \frac{\mathbf{x}^{(i)} - \mathbf{\mu}_B}{\sqrt{{\sigma_B}^2 + \varepsilon}}$$

4.
$$\mathbf{z}^{(i)} = \mathbf{\gamma} \otimes \widehat{\mathbf{x}}^{(i)} + \mathbf{\beta}$$

Given training and testing sets as showing. Which data augmentations should be used?







Ford





Ford



Training set consists of blue Ford (left) and Chevrolet (right) cars

The two classes in our hypothetical dataset. The one in the left represents Brand A (Ford), and the one in the right represents Brand B (Chevrolet).

Chevrolet



Chevrolet

Typical examples in testing sets

- ■A. Horizontally flipping and center crop
- ■B. Vertically flipping and center crop
- □C. Horizontally flipping and color shift
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