



Changyo LEE

Student

lcgyo@naver.com

Shanghai, China

+86 18818221052

[linkedin.com/in/chan-gyo-lee-480b1a1852](https://www.linkedin.com/in/chan-gyo-lee-480b1a1852)

“Innovative, teamwork-oriented, Provide the best solution to the customers” it is my attitude I have always had since I majored in engineering. I studied Mechanical Engineering in the bachelor's and master's program, and have experience in providing new value by participating in many projects such as ROS Programming, Data Fusion, SLAM, Machine Vision, Troubleshooting simple/complex issues of Robot, and Implementing new features based on user feedback. In addition, Native Korean, with professional working proficiency in Chinese and English.

EDUCATION

❑ Master's Degree In Mechanical Engineering

*Shanghai Jiao Tong University
Shanghai, China (2018-2021)*

Courses:

Digital Signal Processing, Machine Vision, Mechanical system Dynamics, Mechatronics, Performance Simulation and Control of Robot, Optimization methods, Matrix Theory, Elastic & plastic Mechanics

Project:

- Library Assistant mobile Robot

Thesis:

- Fast-Frontier-based Exploration and Navigation using Semantic Applications

❑ Bachelor's Degree In Mechanical Engineering

*Seoul National University of Science and Technology
Seoul, Korea (2010-2018)*

Courses:

Computer Language, MEMS, Statics, CAD, Thermodynamics, Dynamics, Electric, Electronic, Engineering Mathematics, Numerical Analysis, Fluid Mechanics, etc.

Project:

- Smart stick for blinds using Arduino kit

Thesis:

- Optimization method of HVAC System

❑ 1 Year Exchange Student

*Harbin Far East Institute of Technology
Harbin, China (2016 — 1 year)*

Project:

- Autonomous wall painting robot

❑ Winter Semester Exchange Student

*Huazhong University of Science and Technology
Wuhan, China (2015 — 2 months)*

WORK EXPERIENCE

❑ Graduate Student Researcher

*Robot Control and Machine Vision LAB
Shanghai Jiao tong university
(2018 — 2021, Full-time)*

Task/Responsibility

- Design Semantic SLAM Based on ORB-SLAM2 with yolov3
- Design Fast Frontier-based Exploration and navigation system
- Design Robots in ROS

❑ Journalist

*Shanghai Edu News
Shanghai, china (2020 — 5 months, Part-time)*

Task/Responsibility

- Translate(Chinese-Korean)
- Web Crawling in python

❑ Interpreter

*2018 Weplay Game Expo
Shanghai China (2018— 3 days, Part-time)*

Task/Responsibility

- B2C Translation(Korean-English-Chinese)

❑ Technical Support Engineer

*Kohyoung Technology
Seoul, Korea (2018— 6 months, Full-time)*

Task/Responsibility

- Trouble shooting HW/SW of semi conductor inspection equipment(AOI, SPI)
- SW/HW Test

❑ Research Assistant

*Micro Interfacial Flow and Visualization LAB
Seoul National University of science and technology
(2017 — 1 year, Full-time)*

Task/Responsibility

- Assist Graduate-level student's research
- Project: Optimization of HVAC system

❑ Towed artillery Maintenance Soldier

*Republic of Korea Army
Gangwon-do, Korea (2011-2013, Full-time)*

Task/Responsibility

- Defence Republic of Korea

PUBLICATIONS

❑ Asynchronous Fusion of Visual and Wheel Odometer for SLAM applications

*Changyo lee, jichao peng
IEEE/ASME International Conference on Advance Intelligent Mechatronics, pp. 1990-1995, IEEE(2020)*

Award and Honors

❑ Scholarship A

- China Scholarship Council(2018-2021)*
- Support Full tuition, insurance
- Every months 3000RMB scholarship and 1200RMB living subsidy, etc.
- During Master Program

❑ Win a Dreamer Award

- Ecovacs Robotics 3rd Robot Design Competition Harbin, China(2016)*
- [Link \(http://robot.ecovacs.cn/thread-99539-1-sortid-1.html\)](http://robot.ecovacs.cn/thread-99539-1-sortid-1.html)

❑ Win a Silver Medal in CNC Lathe

*Seoul Skill Competition(2-times)
Seoul, Korea(2008)*

Language

Korean(Native)



Chinese(新HSK6 205)



English(Toeic 865)



Programming

C++



Python



Tensor Flow



Matlab



TOOL

ROS



Solidwork



Master CAM



Blender



Certification

Robotics issued by
edX Columbia
University

ROS for Beginners path
issued by Robot ignite
Academy