

Chan gyo, Lee

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Education Mar 2010-	Seoul National University of Science and Technology	Seoul, Korea	
Feb 2018	■ Graduate B.A in Mechanical Engineering (GPA 3.5/4.5)		
	<u>Relevant Coursework</u> : Computer Programming(Matlab, Labview, C++), MEM Electrical & Electronical Engineering, Engineering Mathematics, CAD, Engineering Mathematics, Manufacturing progress, Internal Combustion Engin Analysis	leat Transfer, Fluid Mechanics,	
Jan 2015 Jan 2015	 Huazhong University of Science and Technology Exchange Student (Winter Semester) <u>Relevant Coursework</u>: Learning Chinese and Culture 	Wuhan, China	
Mar 2016	Harbin Far East Institute of Technology	Harbin, China	
Dec 2016	 Exchange Student (1 Year) <u>Relevant Coursework</u>: Chinese, Hydraulic Transmission, Precision Design, Mechanical Drive and Control 		
Sep 2018 ~ Now	Shanghai Jiaotong University Graduate engineer program in Mechanical Engineering, (GPA 2.98/4), Expected Graduation date: Mar 2021 **Relevant Coursework*: Digital Signal Processing, Mechanical System Dynamics, Performance Simulation and Control of Robot, Optimization Methods, Machine Vision, Linear Algebra, Mechatronics, Elastic & Plastic Mechanics		
Work Exp	erience		
May 2011- Feb 2013	Republic of Korea Army • Position: Army	Seoul, Korea	
	 Task/Responsibility: Operating M39 155mm Towed artillery Defense Korean Territory 		
Feb 2017- Dec 2017	 Micro Interfacial Flow and Visualization Laboratory Position: Undergraduate-level researcher <u>Task/Responsibility</u>: Assisted Senior researcher CFD Experiment Project: Research on Optimization of HVAC using CFD 	Seoul, Korea	
Jan 2018- Jun 2018	Kohyoung Technology Position: Technical Support <u>Task/Responsibility:</u> HW/SW Issue Trouble Shooting	Seoul, Korea	
Jan 2020-	上海月波广告有限公司(shanghai Edu advertisement) •Position: Data Engineer <u>Task/Responsibility:</u> • Web Crawling using Beatifulsoup in python.	Shanghai, China	
Sep 2018- Mar 2021	Robot Control and Machine Vision Laboratory • Position: graduate-level researcher Track/Page page in this in the control of	Shanghai, China	

Develop Slam (Semantic SLAM based on ORB-SLAM2 SLAM system and Yolov3)

Task/Responsibility:

- Develop Frontier-based Exploration in an unknown environment and navigation
 - https://youtu.be/rUtJTubiweA
- Control Dual-arm manipulator in ros (https://youtu.be/IS2WA1j4Uro)
- Develop Object recognition and detection (https://youtu.be/oHN6IxD7TDc)
- Develop Hybrid motion planning algorithm(RRTs and Artificial potential field)

Project: Pick and Place, Object Detection, Slam, Exploration, Navigation

Award	and	Honors
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Apr 2008-	Seoul City Technical skill Competition Silver prize on CNC lathe	Seoul, Korea
Sep 2008-	Seoul City High School Technical Skill Competition Silver prize on CNC lathe	Seoul, Korea
Jul 2016-	Ecovacs Robotics Competition The Excellent Robot Design award More detail: http://robot.ecovacs.cn/thread-99539-1-sortid-1.html	Harbin, China
Sep 2018- Mar 2021	China Scholarship Council ScholarShip A Grade	Shanghai, China
Skills		
Languages	Korean (Native Speaker)	
	English (TOEIC 865/ OPIC Intermediate High Level at 2018)	
т.	Chinese (HSK 6 205 score at 2018)	
License	Certification of CNC Lathe Engineer Certification of Commutan application (Eyest, Word, Poycer Point)	
	Certification of Computer application (Excel, Word, PowerPoint)	
	Certification of Air-Conditioning and Refrigerating System Engineer	
Duo onomonio -	Certification of Korean history proficiency test for 1st grade	
Programming	Python, C++, ROS, SOLIDWORK, MASTERCAM	

Social Activities Sep 2014- Inte

International Students Club

Dec 2015	 Position: President <u>Relevant Activities</u>: Assisted international students to adjust to living in Korea 	
Sep 2008-	International Students Union Position: Member	Shanghai, China

Seoul, Korea

Relevant Activities: Assisted international students to adjust to living in china