

# Modified ResNet for CIFAR Mini-project 7123

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the link to the code base is <https://github.com/leeexi/7123-mini-project-resnet-sp24>

## Abstract

The mini-project requires to design, and train modified residual network architecture with CIFAR-10 image and do the image classification on a custom test dataset like CIFAR-10 image. The architecture should have less than 5 million parameters. To design an efficient and accurate model, some experiments have been conducted. In this paper, there is a brief introduction to the architecture of the model, the data preprocessing techniques and the experiments on activation and optimizers to finally train an accurate model.

## Introduction

A residual neural network is a type of deep learning model where the weight layers learn residual functions based the layer inputs. It operates similarly to a highway network with gates that are opened through strongly positive bias weights. This characteristic allows deep learning models with numerous layers to train more effectively and achieve higher accuracy as they become deeper. In this project, the goal is to modify the classic residual neural network to design a lighter model with lower than 5 million parameters and then do image classification on a custom test. The basic architecture is ResNet 18 Figure 1 which consists 18 layers, including convolutional layers, pooling layers, fully connected layers and identity shortcuts. Some data augmentation techniques and optimizers are also listed in the project

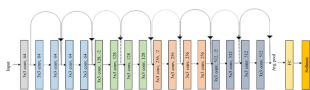


Figure 1: Original model of ResNet-18

## Methodology

The dataset consists 60000 32x32 image in which 50000 are for training and 10000 are for testing. Data augmentation is the process of applying a range of transformations to the current dataset to generate additional images. This technique aims to improve the model's resilience to noise and enhance

its ability to generalize by introducing variations in the input data. Some data augmentation techniques are defined in this project including: including resized crop, vertical flip, horizontal flip, color jitter, rotation, and Gaussianblur.

### Random resized crop

The input image is first resized to a random size within a certain range, which helps the model learn to recognize objects at different scales. After resizing, a random crop of the specified size is taken from the resized image. This random cropping helps the model learn to focus on different parts of the image, enhancing its ability to generalize. By applying Random Resize Crop, the model is exposed to variations in the input data, making it more robust to different image sizes and compositions.

### Random vertical flip

For each image during training, a random decision is made whether to perform a vertical flip or not. If the random decision is to flip the image vertically, the image is flipped along the vertical axis, effectively reversing the top-to-bottom orientation of the image. By applying Random Vertical Flip, the model is exposed to variations in the orientation of the input images, which can help improve its robustness and generalization performance.

### Color jitter

For each image during training, random adjustments are made to its color channels. The magnitude of the color adjustments is controlled by predefined parameters such as the range of possible changes for each color channel.

### Cutout

Since the images in the dataset are smaller in size, another technique named cutout is also applied. Cut out is a simple regularization method which involves randomly masking out sections of input images during the training process. In this way, Cutout mimics occluded examples and encourages the model to focus on smaller details when making predictions, rather than solely relying on a few prominent features. In this way, more detailed feature in smaller images can be used

## Architecture

The model in Figure 2 and Figure 3 shows the summary of the architecture of the model. In its core part, the beginning of the model is an initial convolutional layer, followed by batch normalization. The kernel size is set to 3x3. In order to make the model fix complex pattern of train and test dataset, GELU activation is chosen as the activation layer. With GELU, the model becomes smoother and better at handling complex pattern. With the number of residual blocks as [3,2,4,3], the model performs well and the number of parameters is near 5 mil-lion. As shown in figure 2, the total number of layers in this model is 69. This model is a variant of ResNet 18 architecture with shortcut connections with shortcuts and a global average pooling layer. With this model, the total number of parameters is about 4.5 million and the best test accuracy is 92%.

Layer (type)	Output shape	Param #
Conv2d-1	[-1, 32, 32, 32]	864
BatchNorm2d-2	[-1, 32, 32, 32]	64
Conv2d-3	[-1, 32, 32, 32]	9,216
BatchNorm2d-4	[-1, 32, 32, 32]	64
Conv2d-5	[-1, 32, 32, 32]	9,216
BatchNorm2d-6	[-1, 32, 32, 32]	64
BasicBlock-7	[-1, 32, 32, 32]	0
Conv2d-8	[-1, 32, 32, 32]	9,216
BatchNorm2d-9	[-1, 32, 32, 32]	64
Conv2d-10	[-1, 32, 32, 32]	9,216
BatchNorm2d-11	[-1, 32, 32, 32]	64
BasicBlock-12	[-1, 32, 32, 32]	0
Conv2d-13	[-1, 32, 32, 32]	9,216
BatchNorm2d-14	[-1, 32, 32, 32]	64
Conv2d-15	[-1, 32, 32, 32]	9,216
BatchNorm2d-16	[-1, 32, 32, 32]	64
BasicBlock-17	[-1, 32, 32, 32]	0
Conv2d-18	[-1, 64, 16, 16]	18,432
BatchNorm2d-19	[-1, 64, 16, 16]	128
Conv2d-20	[-1, 64, 16, 16]	36,864
BatchNorm2d-21	[-1, 64, 16, 16]	128
Conv2d-22	[-1, 64, 16, 16]	2,448
BatchNorm2d-23	[-1, 64, 16, 16]	128
BasicBlock-24	[-1, 64, 16, 16]	0
Conv2d-25	[-1, 64, 16, 16]	36,864
BatchNorm2d-26	[-1, 64, 16, 16]	128
Conv2d-27	[-1, 64, 16, 16]	36,864
BatchNorm2d-28	[-1, 64, 16, 16]	128
BasicBlock-29	[-1, 64, 16, 16]	0
Conv2d-30	[-1, 128, 8, 8]	73,728
BatchNorm2d-31	[-1, 128, 8, 8]	256
Conv2d-32	[-1, 128, 8, 8]	147,456
BatchNorm2d-33	[-1, 128, 8, 8]	256
Conv2d-34	[-1, 128, 8, 8]	8,192
BatchNorm2d-35	[-1, 128, 8, 8]	256
BasicBlock-36	[-1, 128, 8, 8]	0
Conv2d-37	[-1, 128, 8, 8]	147,456
BatchNorm2d-38	[-1, 128, 8, 8]	256
Conv2d-39	[-1, 128, 8, 8]	147,456
BatchNorm2d-40	[-1, 128, 8, 8]	256
BasicBlock-41	[-1, 128, 8, 8]	0
Conv2d-42	[-1, 128, 8, 8]	147,456
BatchNorm2d-43	[-1, 128, 8, 8]	256
Conv2d-44	[-1, 128, 8, 8]	147,456
BatchNorm2d-45	[-1, 128, 8, 8]	256
BasicBlock-46	[-1, 128, 8, 8]	0
Conv2d-47	[-1, 128, 8, 8]	147,456
BatchNorm2d-48	[-1, 128, 8, 8]	256

Figure 2: model summary-1

Conv2d-49	[-1, 128, 8, 8]	147,456
BatchNorm2d-50	[-1, 128, 8, 8]	256
BasicBlock-51	[-1, 128, 8, 8]	0
Conv2d-52	[-1, 256, 4, 4]	704,912
BatchNorm2d-53	[-1, 256, 4, 4]	512
Conv2d-54	[-1, 256, 4, 4]	589,824
BatchNorm2d-55	[-1, 256, 4, 4]	512
Conv2d-56	[-1, 256, 4, 4]	32,768
BatchNorm2d-57	[-1, 256, 4, 4]	512
BasicBlock-58	[-1, 256, 4, 4]	0
Conv2d-59	[-1, 256, 4, 4]	589,824
BatchNorm2d-60	[-1, 256, 4, 4]	512
Conv2d-61	[-1, 256, 4, 4]	589,824
BatchNorm2d-62	[-1, 256, 4, 4]	512
BasicBlock-63	[-1, 256, 4, 4]	0
Conv2d-64	[-1, 256, 4, 4]	589,824
BatchNorm2d-65	[-1, 256, 4, 4]	512
Conv2d-66	[-1, 256, 4, 4]	589,824
BatchNorm2d-67	[-1, 256, 4, 4]	512
BasicBlock-68	[-1, 256, 4, 4]	0
Linear-69	[-1, 1, 1]	2,576

Total params: 4,587,680  
Trainable params: 4,587,680  
Non-trainable params: 0  
Input size (MB): 0.41  
Forward/backward pass size (MB): 7.66  
Params size (MB): 17.56  
Estimated total size (MB): 25.17  
None

Figure 3: model summary-2

## Result

The model is trained with 50000 CIFAR images. The combinations of different activation and opti-mizer are also examined. The activation method includes Relu and GELU, and the optimizer in-cludes Adam and SGD. The combination that produces best result is GELU and Adam with learning rate of 0.01. The highest test accuracy is 92.36%. Figure 4,5,6,7 are the result from the different experiments.

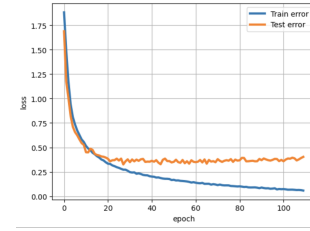


Figure 4: Result of SGD and Relu

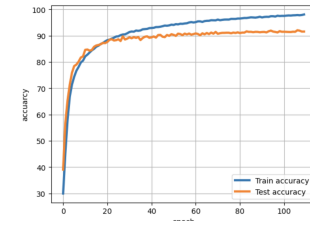


Figure 5: Result of SGD and Relu

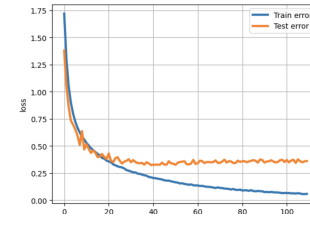


Figure 6: Result of Adam and GELU

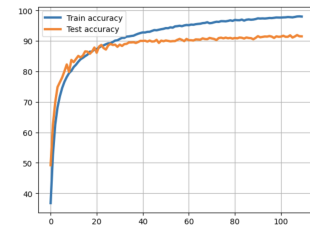


Figure 7: Result of Adam and GELU

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