



Concurrent Data Structures

Lock-based Concurrent Data Structures

- Adding locks to a data structure makes the structure thread safe
 - How locks are added determine both the **correctness** and **performance** of the data structure

Example: Concurrent Counters without Locks

- Incorrect version

```
1      typedef struct __counter_t {
2          int value;
3      } counter_t;
4
5      void init(counter_t *c) {
6          c->value = 0;
7      }
8
9      void increment(counter_t *c) {
10         c->value++;
11     }
12
13     void decrement(counter_t *c) {
14         c->value--;
15     }
16
17     int get(counter_t *c) {
18         return c->value;
19     }
```

Example: Concurrent Counters with Locks

- Add a **single lock**
 - The lock is acquired when calling a routine that manipulates the data structure

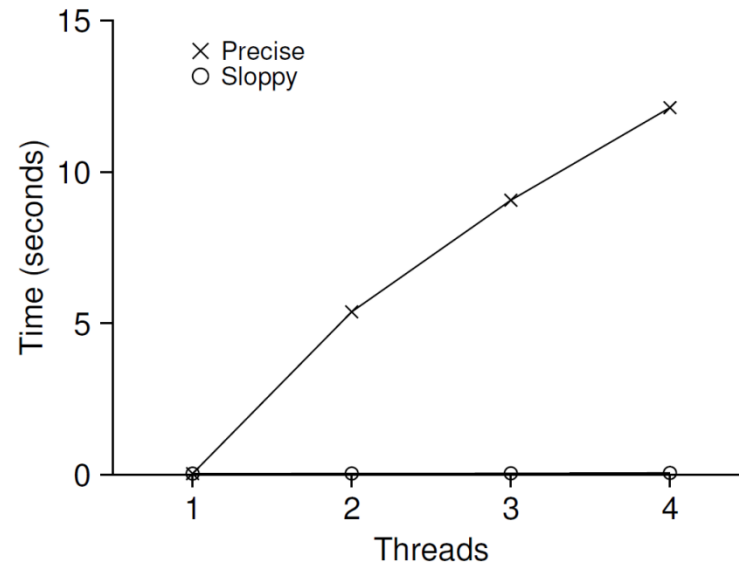
```
1      typedef struct __counter_t {
2          int value;
3          pthread_lock_t lock;
4      } counter_t;
5
6      void init(counter_t *c) {
7          c->value = 0;
8          Pthread_mutex_init(&c->lock, NULL);
9      }
10
11     void increment(counter_t *c) {
12         Pthread_mutex_lock(&c->lock);
13         c->value++;
14         Pthread_mutex_unlock(&c->lock);
15     }
16
```

Example: Concurrent Counters with Locks

```
(Cont.)
17     void decrement(counter_t *c) {
18         pthread_mutex_lock(&c->lock);
19         c->value--;
20         pthread_mutex_unlock(&c->lock);
21     }
22
23     int get(counter_t *c) {
24         pthread_mutex_lock(&c->lock);
25         int rc = c->value;
26         pthread_mutex_unlock(&c->lock);
27         return rc;
28     }
```

Overhead of Simple Approach

- Each thread updates a single shared counter
 - Each thread updates the counter one million times
 - iMac with four Intel 2.7GHz i5 CPUs



**Performance of
Traditional vs. Sloppy Counters**
(Threshold of Sloppy, s_i , is set to 1024)

Synchronized counter scales poorly

Perfect Scaling

- Even though more work is done, it is **done in parallel**
- The time taken to complete the task is *not increased*

Sloppy counter

- The sloppy counter works by representing ...
 - A single **logical counter** via numerous local physical counters, on per CPU core
 - A single **global counter**
 - There is only one lock for the global counter
- Example: on a machine with four CPUs
 - Four local counters
 - One global counter

Basic Ideas of Sloppy Counting

- When a thread running on a core wishes to increment the counter
 - It increment its local counter
 - Each CPU has its own local counter
 - Threads across CPUs can update local counters *without contention*
 - Thus counter updates are **scalable**
 - The local values are periodically transferred to the global counter
 - Acquire the global lock
 - Increment it by the local counter's value
 - Local counter is then reset to zero

The basic idea of sloppy counting

- How often the local-to-global transfer occurs is determined by a threshold, S (sloppiness)
 - The smaller S :
 - The more the counter behaves like the *non-scalable counter*
 - The bigger S :
 - The more scalable the counter
 - The further off the global value might be from the *actual count*

Sloppy Counter Example

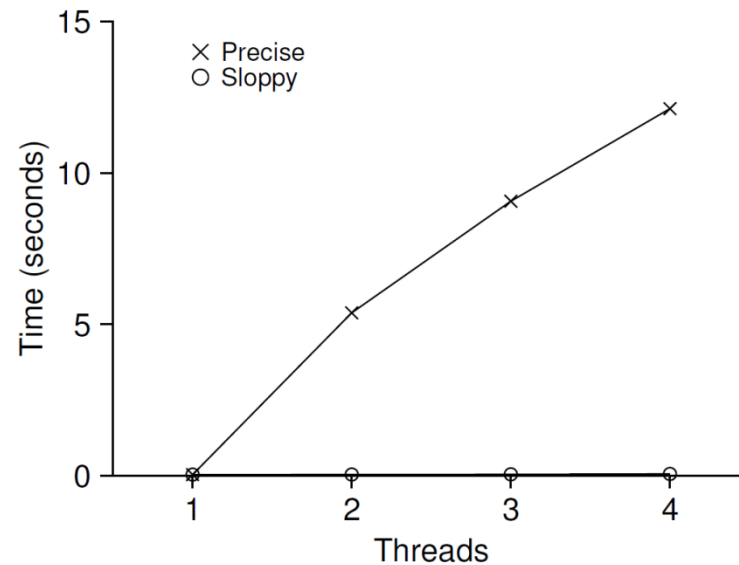
■ Tracing the Sloppy Counters

- The threshold S is set to 5
- There are threads on each of four CPUs
- Each thread updates their local counters $L_1 \dots L_4$

Time	L_1	L_2	L_3	L_4	G
0	0	0	0	0	0
1	0	0	1	1	0
2	1	0	2	1	0
3	2	0	3	1	0
4	3	0	3	2	0
5	4	1	3	3	0
6	5 \rightarrow 0	1	3	4	5 (from L_1)
7	0	2	4	5 \rightarrow 0	10 (from L_4)

Sloppy Counter Performance

- Each thread updates a single shared counter
 - Each thread updates the counter one million times
 - iMac with four Intel 2.7GHz i5 CPUs

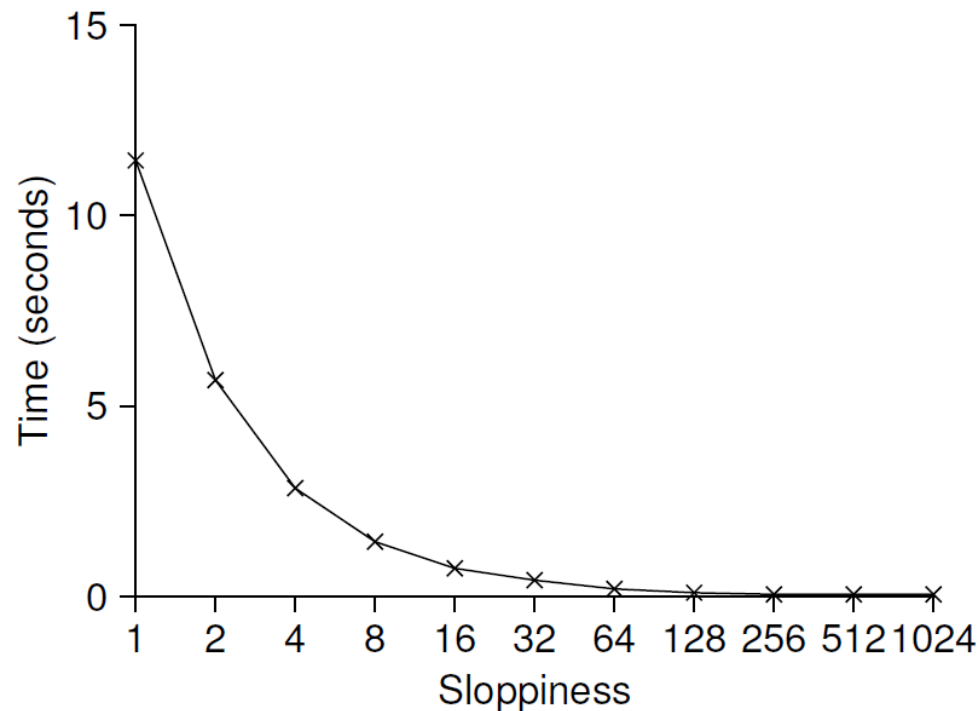


**Performance of
Traditional vs. Sloppy Counters**
(Threshold of Sloppy, s_i , is set to 1024)

Sloppy counter scales well

Importance of Threshold Value s

- Each four threads increments counter 1 million times, respectively
 - Low $S \rightarrow$ **poor** performance, accurate global counter
 - High $S \rightarrow$ Performance is **excellent**, The global count **lags**.



Scaling Sloppy Counters

Sloppy Counter Implementation

```
1  typedef struct __counter_t {
2      int global;           // global count
3      pthread_mutex_t glock; // global lock
4      int local[NUMCPUS];   // local count (per cpu)
5      pthread_mutex_t llock[NUMCPUS]; // ... and locks
6      int threshold;        // update frequency
7  } counter_t;
8
9  // init: record threshold, init locks, init values
10 //      of all local counts and global count
11 void init(counter_t *c, int threshold) {
12     c->threshold = threshold;
13
14     c->global = 0;
15     pthread_mutex_init(&c->glock, NULL);
16
17     int i;
18     for (i = 0; i < NUMCPUS; i++) {
19         c->local[i] = 0;
20         pthread_mutex_init(&c->llock[i], NULL);
21     }
22 }
23
```

Sloppy Counter Implementation

```
(Cont.)
24 // update: usually, just grab local lock and update local amount
25 //           once local count has risen by 'threshold', grab global
26 //           lock and transfer local values to it
27 void update(counter_t *c, int threadID, int amt) {
28     pthread_mutex_lock(&c->llock[threadID]);
29     c->local[threadID] += amt; // assumes amt > 0
30     if (c->local[threadID] >= c->threshold) { // transfer to global
31         pthread_mutex_lock(&c->glock);
32         c->global += c->local[threadID];
33         pthread_mutex_unlock(&c->glock);
34         c->local[threadID] = 0;
35     }
36     pthread_mutex_unlock(&c->llock[threadID]);
37 }
38
39 // get: just return global amount (which may not be perfect)
40 int get(counter_t *c) {
41     pthread_mutex_lock(&c->glock);
42     int val = c->global;
43     pthread_mutex_unlock(&c->glock);
44     return val; // only approximate!
45 }
```

Concurrent Linked Lists

```
1      // basic node structure
2      typedef struct __node_t {
3          int key;
4          struct __node_t *next;
5      } node_t;
6
7      // basic list structure (one used per list)
8      typedef struct __list_t {
9          node_t *head;
10         pthread_mutex_t lock;
11     } list_t;
12
13     void List_Init(list_t *L) {
14         L->head = NULL;
15         pthread_mutex_init(&L->lock, NULL);
16     }
17
18     (Cont.)
```


Concurrent Linked Lists

```
(Cont.)
18     int List_Insert(list_t *L, int key) {
19         pthread_mutex_lock(&L->lock);
20         node_t *new = malloc(sizeof(node_t));
21         if (new == NULL) {
22             perror("malloc");
23             pthread_mutex_unlock(&L->lock);
24             return -1; } // fail
26         new->key = key;
27         new->next = L->head;
28         L->head = new;
29         pthread_mutex_unlock(&L->lock);
30         return 0; // success
31     }
(Cont.)
```

Concurrent Linked Lists

```
(Cont.)
32
32     int List_Lookup(list_t *L, int key) {
33         pthread_mutex_lock(&L->lock);
34         node_t *curr = L->head;
35         while (curr) {
36             if (curr->key == key) {
37                 pthread_mutex_unlock(&L->lock);
38                 return 0; // success
39             }
40             curr = curr->next;
41         }
42         pthread_mutex_unlock(&L->lock);
43         return -1; // failure
44     }
```

Concurrent Linked Lists

- The code **acquires** a lock in the insert routine upon entry
- The code **releases** the lock upon exit
 - If `malloc()` happens to *fail*, the code must also release the lock before failing the insert
 - This kind of exceptional control flow has been shown to be quite error prone
 - **Solution:** The lock and release *only surround* the actual critical section in the insert code

Concurrent Linked List: Rewritten

```
1      void List_Init(list_t *L) {
2          L->head = NULL;
3          pthread_mutex_init(&L->lock, NULL);
4      }
5
6      void List_Insert(list_t *L, int key) {
7          // synchronization not needed
8          node_t *new = malloc(sizeof(node_t));
9          if (new == NULL) {
10              perror("malloc");
11              return;
12          }
13          new->key = key;
14
15          // just lock critical section
16          pthread_mutex_lock(&L->lock);
17          new->next = L->head;
18          L->head = new;
19          pthread_mutex_unlock(&L->lock);
20      }
21
```

Concurrent Linked List: Rewritten

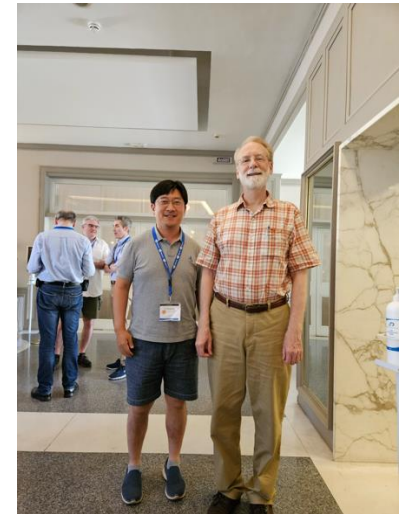
```
(Cont.)
22     int List_Lookup(list_t *L, int key) {
23         int rv = -1;
24         pthread_mutex_lock(&L->lock);
25         node_t *curr = L->head;
26         while (curr) {
27             if (curr->key == key) {
28                 rv = 0;
29                 break;
30             }
31             curr = curr->next;
32         }
33         pthread_mutex_unlock(&L->lock);
34         return rv; // now both success and failure
35     }
```

Scaling Linked List

- Hand-over-hand locking (lock coupling)
 - Add a **lock per node** of the list instead of having a single lock for the entire list
 - When traversing the list
 - First grabs the next node's lock
 - And then releases the current node's lock
 - Enable a high degree of concurrency in list operations
 - However, in practice, the overheads of acquiring and releasing locks for each node of a list traversal is *prohibitive*

Michael and Scott Concurrent Queues

- There are two locks
 - One for the **head** of the queue
 - One for the **tail**
 - The goal of these two locks is to enable concurrency of *enqueue* and *dequeue* operations
- Add a dummy node
 - Allocated in the queue initialization code
 - Enable the separation of head and tail operations



Me with Prof. Scott in 2024

Concurrent Queues

```
1     typedef struct __node_t {
2         int value;
3         struct __node_t *next;
4     } node_t;
5
6     typedef struct __queue_t {
7         node_t *head;
8         node_t *tail;
9         pthread_mutex_t headLock;
10        pthread_mutex_t tailLock;
11    } queue_t;
12
13    void Queue_Init(queue_t *q) {
14        node_t *tmp = malloc(sizeof(node_t));
15        tmp->next = NULL;
16        q->head = q->tail = tmp;
17        pthread_mutex_init(&q->headLock, NULL);
18        pthread_mutex_init(&q->tailLock, NULL);
19    }
20
21    (Cont.)
```


Concurrent Queues

```
(Cont.)
21     void Queue_Enqueue(queue_t *q, int value) {
22         node_t *tmp = malloc(sizeof(node_t));
23         assert(tmp != NULL);
24
25         tmp->value = value;
26         tmp->next = NULL;
27
28         pthread_mutex_lock(&q->tailLock);
29         q->tail->next = tmp;
30         q->tail = tmp;
31         pthread_mutex_unlock(&q->tailLock);
32     }
(Cont.)
```

Concurrent Queues

(Cont.)

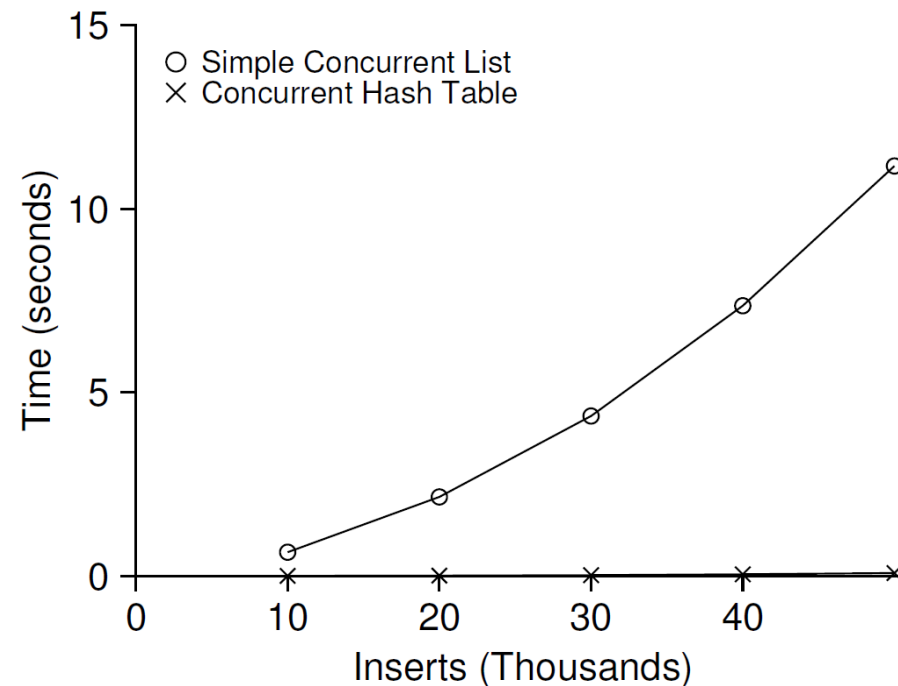
```
33     int Queue_Dequeue(queue_t *q, int *value) {
34         pthread_mutex_lock(&q->headLock);
35         node_t *tmp = q->head;
36         node_t *newHead = tmp->next;
37         if (newHead == NULL) {
38             pthread_mutex_unlock(&q->headLock);
39             return -1; // queue was empty
40         }
41         *value = newHead->value;
42         q->head = newHead;
43         pthread_mutex_unlock(&q->headLock);
44         free(tmp);
45         return 0;
46     }
```

Concurrent Hash Table

- Focus on a simple hash table
 - The hash table does not resize
 - Built using the concurrent lists
 - It uses a **lock per hash bucket** each of which is represented by *a list*

Performance of Concurrent Hash Table

- From 10,000 to 50,000 concurrent updates from each of four threads
 - iMac with four Intel 2.7GHz i5 CPUs



**The simple concurrent hash table
scales magnificently**

Concurrent Hash Table

```
1      #define BUCKETS (101)
2
3      typedef struct __hash_t {
4          list_t lists[BUCKETS];
5      } hash_t;
6
7      void Hash_Init(hash_t *H) {
8          int i;
9          for (i = 0; i < BUCKETS; i++) {
10             List_Init(&H->lists[i]);
11          }
12      }
13
14      int Hash_Insert(hash_t *H, int key) {
15          int bucket = key % BUCKETS;
16          return List_Insert(&H->lists[bucket], key);
17      }
18
19      int Hash_Lookup(hash_t *H, int key) {
20          int bucket = key % BUCKETS;
21          return List_Lookup(&H->lists[bucket], key);
22      }
```